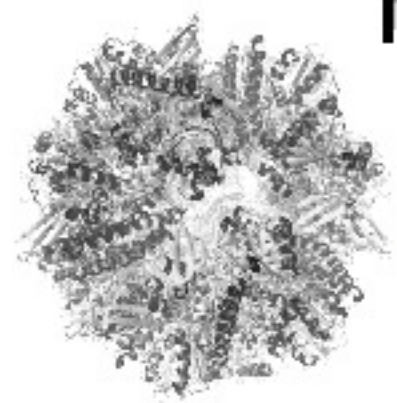
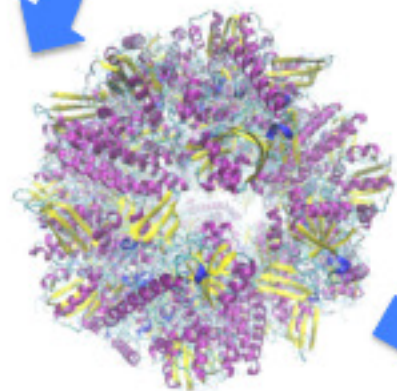


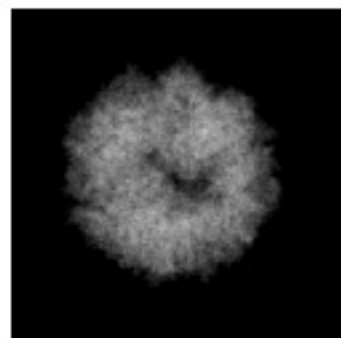
Model



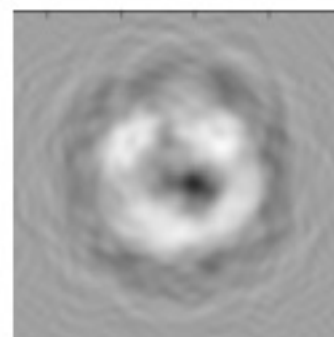
Rotation



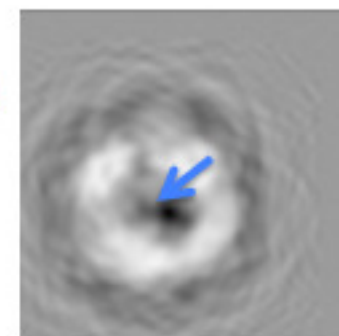
Projection



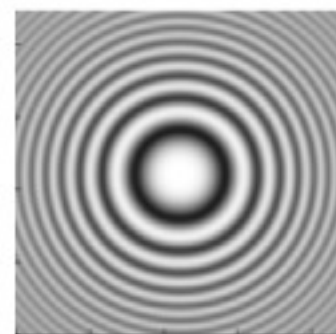
Convolution



Center displacement



Point spread Function (PSF)



Likelihood?

Calculated



Observed

Normalization
+ Offset
+ **Noise**

