




# Miroslav Vitkov

## Curriculum Vitae

### TECHNICAL SKILLS

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- MAJOR
- \* **C++14** under procedural, object oriented or functional paradigm
  - \* **C11** for  $\mu$ C or ARM applications
  - \* tools such as git, gitolite, cmake, teamcity, valgrind, clang-tidy, objdump
- MINOR
- \* **python** for ML applications
  - \* **bash**, the LFHS, standard utilities, security configuration and evaluation, unix sockets
  - \* **L<sup>A</sup>T<sub>E</sub>X**
  - \* basic electrical engineering - read a schematic, reason about it, use an oscilloscope, design a filter
- MISC
- \* **haskell** - below junior level
  - \* **regex** - for capture groups
  - \* Autodesk **inventor** - design a simple gearbox and simulate it
  - \* **matlab** - programming, SimuLink modelling
  - \* **R** - for ggplot2
  - \* avr-**asm**

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### EDUCATION

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- 2017 – 2019 **Machine Learning Scientist - dropped**  
COGNITIVE SYSTEMS: LANGUAGE, LEARNING AND REASONING  
*University of Potsdam, Germany*
- 2007 – 2016 **Industrial Engineer**  
BACHELOR THESIS:  
MULTITASKING AUTOTUNING PID CONTROLLER IN HEAT TRANSFER APPLICATION  
*Technical University of Sofia*
- 2008 – 2010 **Physicist - dropped**  
*Sofia University Kliment Ohridski*
- 2003 – 2007 **Communications technician**  
HIGH SCHOOL DIPLOMA  
*Technical School of Communications, Sofia*

### COMMUNICATION SKILLS

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- BULGARIAN C2: Native speaker
- ENGLISH C2: Fluent (Cambridge CPE)
- GERMAN A1: Basic

## PROJECTS ON GITHUB

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C++	<b>face</b> <i>Use OpenCV Haar cascades to identify persons.</i>
C++	<b>rocks</b> <i>Multiclass classification. Uses dlib.</i>
C++	<b>silhouette</b> <i>Human silhouette extraction using HOG descriptor, SVM classifier and adaptive background thresholding.</i>
C	<b>micli</b> <i>Micro CLimate controller, an autotuning PID regulator.</i>
C	<b>megaboot</b> <i>Simple atmega168 bootloader.</i>
C	<b>cgetset</b> <i>Generate getter/setter methods. Self-contained.</i>
PYTHON	<b>rat</b> <i>Encrypted chat infrastructure.</i>
PYTHON	<b>rtplot</b> <i>Realtime temperature plotting utility.</i>
PYTHON	<b>gender</b> <i>Guess the gender of the author of a short paragraph.</i>
BASH	<b>scripts</b> <i>Utilities for everyday use.</i>
HASKELL	<b>voiceid</b> <i>Identify different persons via speech.</i>
LATEX	<b>rpg</b> <i>A role-playing game.</i>
INVENTOR	<b>gearbox</b> <i>Gearbox calculation and technical drawings.</i>

## WORK EXPERIENCE

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FEB 2020 - JUL 2020

Smule

### *C++ Android algorithms*

- Revive a legacy codebase (2000 line functions, zero documentation, no authors) but of significant business and engineering importance.
- Segment words from audio stream.
- Remain productive despite endless meetings.
- Write simple tools in python to parse logs and source code.
- Investigate crashes on Android devices.

JAN 2016 - SEP 2017

Euro Games Technology

### *C++ embedded linux*

- Maintain the layer just below Business Logic. Essentially encapsulate SDL2, OpenGL, linux files, IPC, devices and network as to provide an API to internal clients.
- Bill accepting device user-space driver implementation from scratch.
- Script Gitolite hooks and communicate their purpose to the other teams.
- Animate custom fonts, draw values based on network updates.

20 MAY 2013 - 21 MAR 2015

Antelope Audio

### *C++ ARM bare metal*

- Implement a reverb in C++ on bare metal ARM.
- Design a GUI communicating with the device using pyQt.
- Implement dynamic biquad filter coefficient update as to respond to the user turning a knob.
- The filter representations in z-domain are combined to yield a frequency response graph.
- Develop UAB2 Audio mode firmware for bare metal ARM.
- JTAG-and-scope debugging.

FEB 2013 - MAY 2013

Johnson Controls

### *C embedded*

Boolean algebra, concurrency, unit tests and documentation.

22 AUG 2011 - 15 JAN 2013

MM Solutions

## *C++ Android algorithms*

Developed and implemented image stabilization for Android videos. The use of the on-board gyroscope in the feedback loop was novel at the time, allowing unparalleled performance in real-time video capture. Additionally SIFT features were used for training and for drift correction. All rotations were expressed in quaternions.