

Multitasking Autotuning PID Controller in Heat Transfer Application

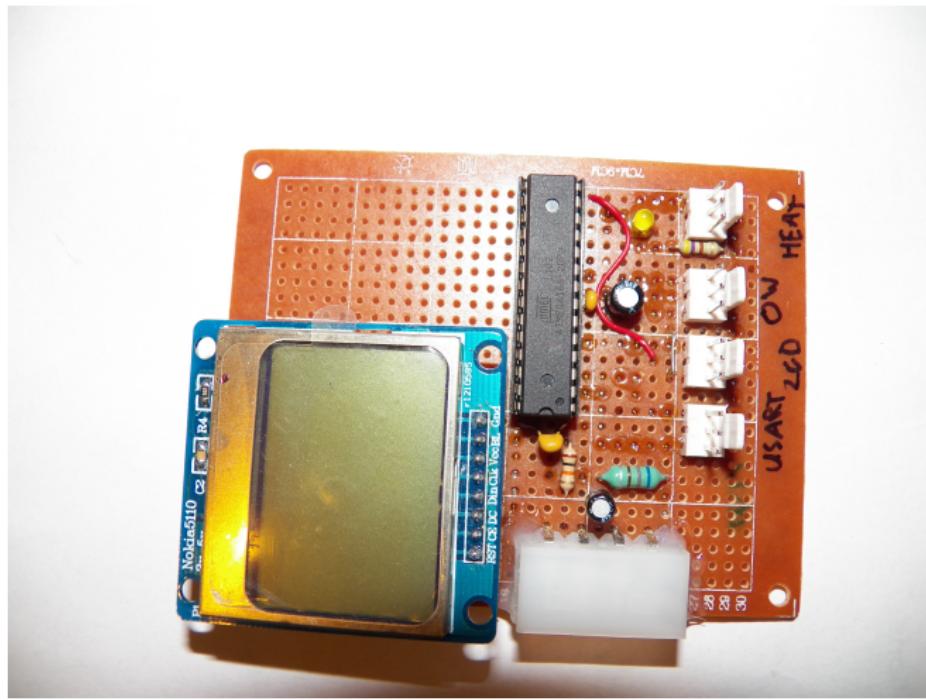
or how to build a 30 BGN universal vectorized regulator

Miroslav Vitkov

ELDE, Technical University-Sofia

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The device



Peak detector algorithm

```
pid_state_t pid_wait_to_settle(pid_inout_t proc_val, pid_inout_t critical, pid_inout_t threshold, clock_seconds_t now)
{
    extremum_t *min = &g_pid.tune.min;
    extremum_t *max = &g_pid.tune.max;
    extremum_t **curr = &g_pid.tune.curr;
    extremum_t **prev_ = &g_pid.tune.prev;

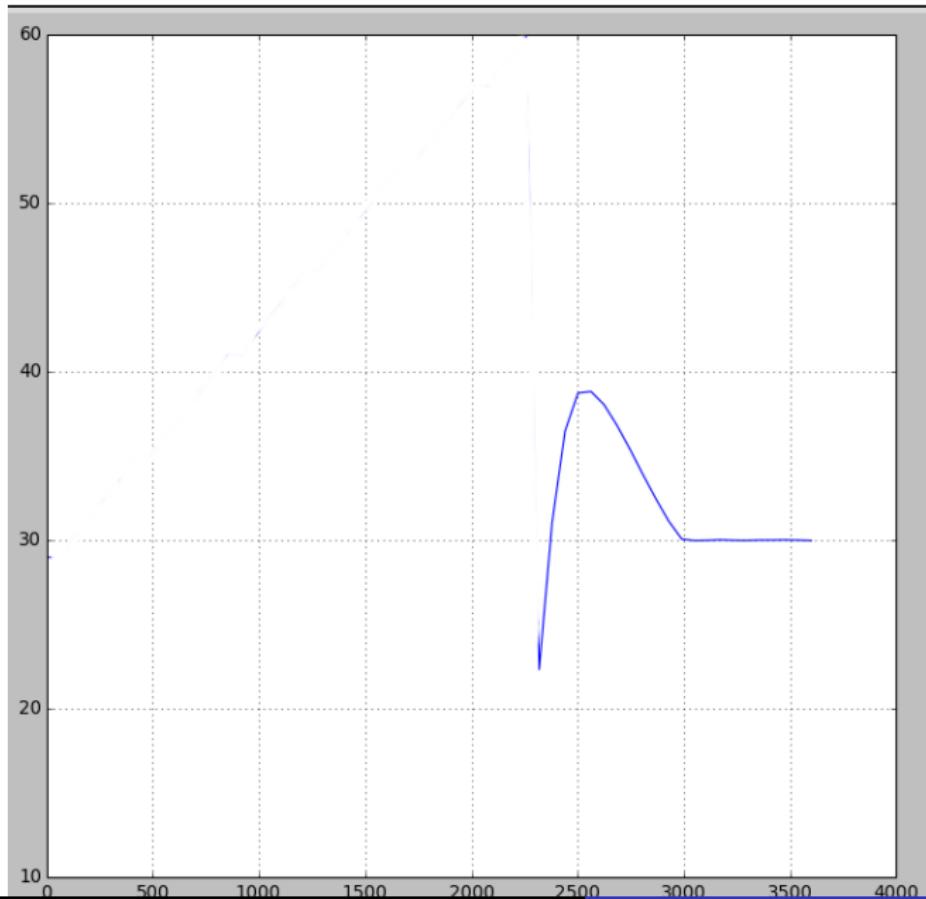
    static pid_inout_t prev, prevprev;

    if(*curr == min)
    {
        // Look for a local maximum.
        if(prevprev <= prev && prev > proc_val)
        {
            (*max).val = proc_val;
            (*max).when = now;
            *curr = max;
            *prev_ = min;
        }
    }
    else
    {
        if(prevprev >= prev && prev < proc_val)
        {
            (*min).val = proc_val;
            (*min).when = now;
            *curr = min;
            *prev_ = max;
        }
    }

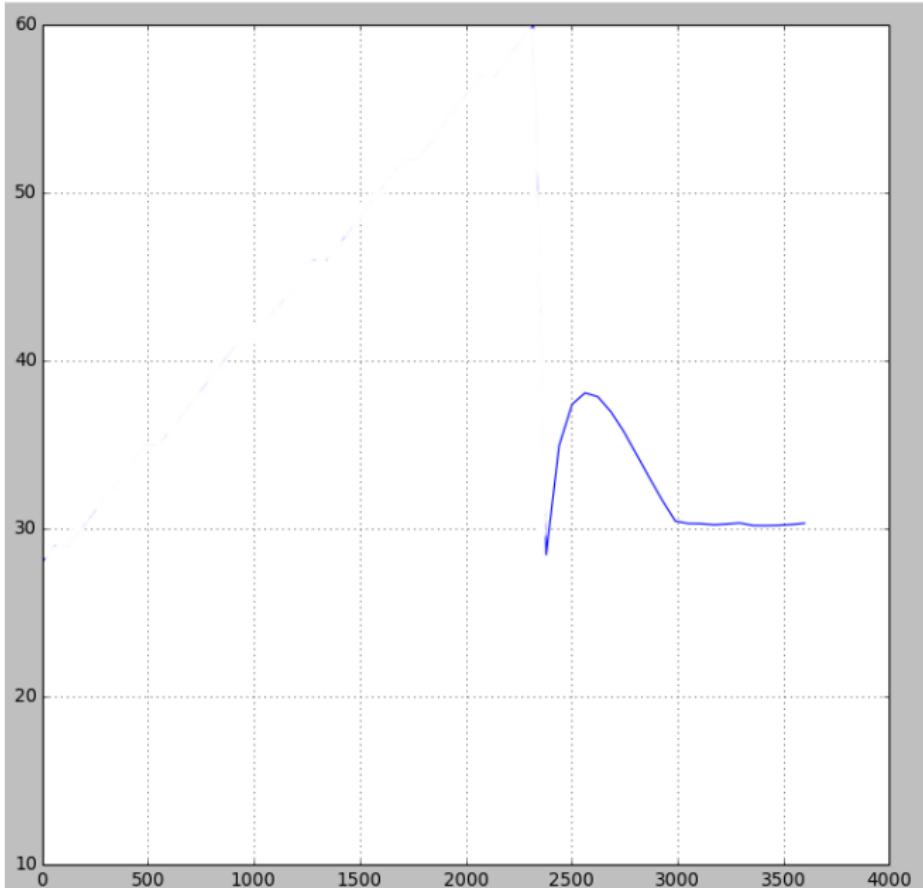
    prevprev = prev;
    prev = proc_val;

    if(proc_val >= critical) return UNSTABLE;
    else if((*min).val + threshold < (*max).val)
return SETTLED;
    else return OSCILLATING;
}
```

Ziegler-Nichols sustained oscillation mode



Astrom-Hagglund sustained oscillation mode



The sampling frequency

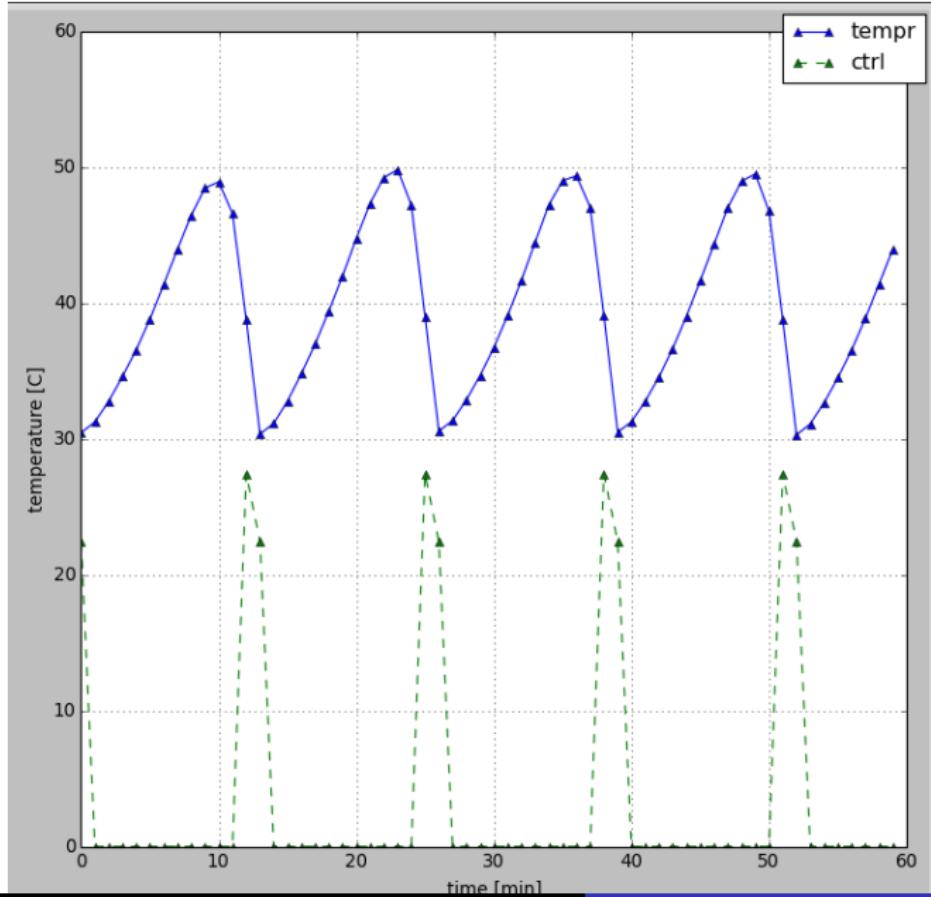


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