# Mobilenet | ibean (Al-Lab-Makerere)

**Pigasin Dmitry** 

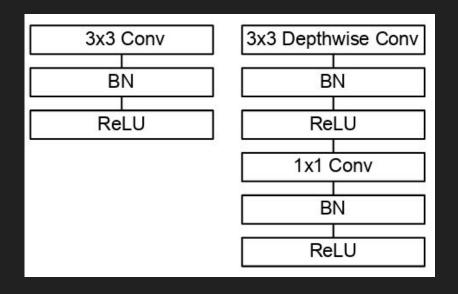
## Dataset

Class	Examples
Healthy class	428
Angular Leaf Spot	432
Bean Rust	436
Total:	1,296



	Input size   Output size	Type / Stride	Filter Shape	Input Size
	0 conv2d (None, 500, 500, 3) (None, 250, 250, 8)	Conv / s2	$3 \times 3 \times 3 \times 32$	$224 \times 224 \times 3$
Structure	3 depthwise conv2d	Conv dw / s1	$3 \times 3 \times 32 \text{ dw}$	$112 \times 112 \times 32$
	(None, 250, 250, 8) (None, 250, 250, 8)	Conv / s1	$1 \times 1 \times 32 \times 64$	$112\times112\times32$
	6 conv2d_1	Conv dw / s2	$3 \times 3 \times 64 \text{ dw}$	$112 \times 112 \times 64$
	(None, 250, 250, 8) (None, 250, 250, 16)	Conv / s1	$1\times1\times64\times128$	$56 \times 56 \times 64$
	9 depthwise_conv2d_1 (None, 250, 250, 16) (None, 125, 125, 16)	Conv dw / s1	$3 \times 3 \times 128 \text{ dw}$	$56 \times 56 \times 128$
		Conv / s1	$1\times1\times128\times128$	$56 \times 56 \times 128$
	12 conv2d_2 (None, 125, 125, 16) (None, 125, 125, 32)	Conv dw / s2	$3 \times 3 \times 128 \mathrm{dw}$	$56 \times 56 \times 128$
31 layers	15 depthwise conv2d 2	Conv / s1	$1\times1\times128\times256$	$28 \times 28 \times 128$
Total params: 10,275	(None, 125, 125, 32) (None, 125, 125, 32)	Conv dw / s1	$3 \times 3 \times 256 \text{ dw}$	$28 \times 28 \times 256$
Trainable params: 9,795 Non-trainable params: 480	18 conv2d_3	Conv / s1	$1\times1\times256\times256$	$28 \times 28 \times 256$
Non-trainable params. 400	(None, 125, 125, 32) (None, 125, 125, 32)	Conv dw / s2	$3 \times 3 \times 256 \text{ dw}$	$28 \times 28 \times 256$
	21 depthwise_conv2d_3 (None, 125, 125, 32) (None, 63, 63, 32)	Conv / s1	$1\times1\times256\times512$	$14 \times 14 \times 256$
	24 conv2d 4	$5 \times \frac{\text{Conv dw / s1}}{5}$	$3 \times 3 \times 512 \mathrm{dw}$	$14\times14\times512$
	(None, 63, 63, 32) (None, 63, 63, 64)	Conv/s1	$1 \times 1 \times 512 \times 512$	$14 \times 14 \times 512$
	27 global_average_pooling2d (None, 63, 63, 64) (None, 64)	Conv dw / s2	$3 \times 3 \times 512 \text{ dw}$	$14 \times 14 \times 512$
		Conv / s1	$1 \times 1 \times 512 \times 1024$	$7 \times 7 \times 512$
	28 dense (None, 64) (None, 64)	Conv dw / s2	$3 \times 3 \times 1024 \mathrm{dw}$	$7 \times 7 \times 1024$
		Conv / s1	$1\times1\times1024\times1024$	$7 \times 7 \times 1024$
	29 dense_1 (None, 64) (None, 3)	Avg Pool / s1	Pool $7 \times 7$	$7 \times 7 \times 1024$
	30 activation 9	FC/s1	$1024 \times 1000$	$1 \times 1 \times 1024$
	(None, 3) (None, 3)	Softmax / s1	Classifier	$1 \times 1 \times 1000$

#### Structure



```
def add conv(filters):
        Conv2D(
            filters=filters,
            kernel size=(1, 1),
            strides=(1, 1),
            padding='same'
        BatchNormalization(),
        Activation('relu'),
def add dw(strides):
        DepthwiseConv2D(
            kernel size=(3, 3),
            strides=strides,
            padding='same'
        BatchNormalization(),
        Activation('relu'),
```

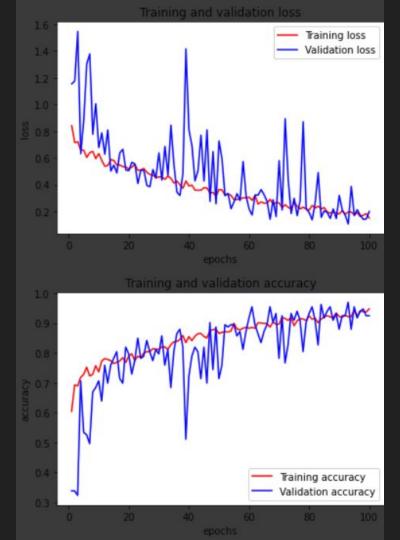
```
def qet my model(min filter count=8, max filter count=64, fc layer count=1):
    conv layers = [
        Conv2D(filters=min filter count, kernel size=(3, 3), strides=(2, 2),
               padding='same', input shape=(img width, img height, 3)),
        BatchNormalization(),
        Activation('relu'),
    cur filter count = min filter count * 2
   while cur filter count < max filter count:</pre>
        conv layers.extend([
            *add dw(strides=1),
            *add conv(filters=cur filter count),
        ])
        cur filter count *= 2
        conv layers.extend([
            *add dw(strides=2),
            *add conv(filters=cur filter count),
        ])
   model = Sequential([
        *conv layers,
        GlobalAveragePooling2D(),
        *[Dense(max filter count // (2 ** i), activation='relu') for i in range(fc layer count)],
        Dense(3),
        Activation('softmax'),
    1)
   model.compile(
        loss='categorical crossentropy',
        optimizer='rmsprop',
        metrics=['accuracy'],
   return model
```

#### Keras Tuner

```
|-Default search space size: 3
def build model(hp):
    min filter count = hp.Choice('min filter count',
                                    values=[4, 8, 16, 32, 64])
                                                                                       min_filter_count (Choice)
    max filter count = hp.Choice('max filter count',
                                    <u>values=[32, 64, 128, 256, 512, 1024])</u>
                                                                                       I-default: 4
    fc layer count = hp.Choice('fc layer count',
                                  values=[1, 2, 3, 4])
                                                                                       |-values: [4, 8, 16, 32, 64]
    return get my model (min filter count, max filter count, fc layer count)
                                                                                       max_filter_count (Choice)
tuner = Hyperband(
                                                                                       |-default: 32
    build model,
    objective='val accuracy',
                                                                                       |-values: [32, 64, 128, 256, 512, 1024]
    directory='models',
    project name='lab2',
                                                                                      fc_layer_count (Choice)
                                                                                       |-default: 1
                                                                                       |-values: [1, 2, 3, 4]
```

## Model training

```
checkpoint = ModelCheckpoint(
    os.path.join(lab2 root, 'best epoch.h5'),
    save best only=True,
    monitor='val accuracy',
    mode='max',
    verbose=2,
fit history = model.fit(
    train generator,
    epochs=100,
    validation data=validation generator,
    verbose=2,
    callbacks=[checkpoint],
100 epochs - loss: 0.2237 - accuracy: 0.9141
Best epoch - loss: 0.3018 - accuracy: 0.8906
```

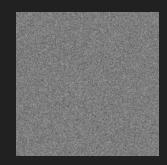


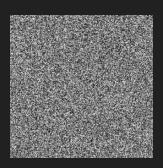
#### **Test**

```
def preprocess image(image):
    return np.expand dims(img to array(image), axis=0) / 255.
image paths = [os.path.join(dir, random.choice(os.listdir(dir))) for dir in image dirs * 3]
classes = ['angular leaf spot', 'bean rust', 'healthy']
for path in image paths:
    out = model.predict(preprocess image(load img(path)))[0]
   print(dict(zip(classes, [round(x, 2) for x in out])), path.split('/')[-1])
{'angular leaf spot': 0.98, 'bean rust': 0.02, 'healthy': 0.0} angular leaf spot train.259.jpg
{'angular leaf spot': 0.01, 'bean rust': 0.99, 'healthy': 0.0} bean rust train.80.jpg
{'angular leaf spot': 0.0, 'bean rust': 0.03, 'healthy': 0.97} healthy train.41.jpg
{'angular leaf spot': 0.99, 'bean rust': 0.0, 'healthy': 0.01} angular leaf spot train.17.jpg
{'angular leaf spot': 0.0, 'bean rust': 1.0, 'healthy': 0.0} bean rust train.41.jpg
{'angular leaf spot': 0.0, 'bean rust': 0.0, 'healthy': 1.0} healthy train.231.jpg
{'angular leaf spot': 0.82, 'bean rust': 0.18, 'healthy': 0.0} angular leaf spot train.214.jpg
{'angular leaf spot': 0.0, 'bean rust': 1.0, 'healthy': 0.0} bean rust train.75.jpg
{'angular leaf spot': 0.0, 'bean rust': 0.0, 'healthy': 1.0} healthy train.230.jpg
```

#### Test with noise

```
def get normal noise(image):
   noise = np.random.normal(128, 20, (image.shape[0], image.shape[1]))
   return np.dstack((noise, noise, noise)).astype(np.uint8)
def add normal noise(image):
   noise = get normal noise(image) * S
   noise image = cv2.add(image.astype(np.float64), noise.astype(np.float64))
   cv2.normalize(noise image, noise image, 0, 255, cv2.NORM MINMAX)
   return noise image
def get uniform noise(image):
   noise = np.random.uniform(0, 255, (image.shape[0], image.shape[1]))
   return np.dstack((noise, noise, noise)).astype(np.uint8)
def add uniform noise(image):
   noise = get uniform noise(image) * S
   noise image = cv2.add(image.astype(np.float64), noise.astype(np.float64))
   cv2.normalize(noise image, noise image, 0, 255, cv2.NORM MINMAX)
   return noise image
```





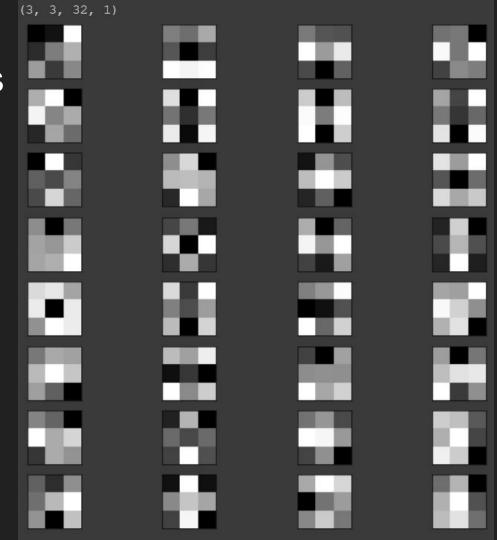
### Test with noise



loss: 1.1743 - accuracy: 0.5703

loss: 2.5685 - accuracy: 0.4844

## Conv filters



# Feature maps

