```
PROGRAM Euler_Cromer
! *****************************
! Se resuelve el pendulo no-lineal, amortiguado y con forzamiento
REAL*8, DIMENSION(:), ALLOCATABLE :: theta, omega, t
REAL*8 :: length,dt
 !print*, "numero de pasos"
 !read*, n
n = 10000
ALLOCATE (theta(0:n),omega(0:n),t(0:n))
call inicializa(theta, omega, t, n, length, dt)
call calcula (theta, omega, t, n, length, dt)
call despliega (theta, omega, t, n, length, dt)
END PROGRAM Euler_Cromer
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SUBROUTINE inicializa(theta, omega, t, n ,length, dt)
INTEGER, INTENT (IN) :: n
REAL*8, DIMENSION(0:n) :: theta, omega, t
REAL*8 :: length,dt
 !print*,'Angulo inicial del pendulo (en radianes)'
 !read*, theta(0)
theta(0) = 0.2d0
 !print*, 'Velocidad angular inicial del pendulo (en radianes/s)'
 !read*, omega(0)
omega(0) = 0.d0
t(0)=0.d0
 !print*,'Longitud del pendulo (in m)'
 !read*, length
length = 9.80d0
 !print*, 'Tamaño de paso (en segundos)'
 !read*, dt
dt = 0.001
END SUBROUTINE inicializa
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SUBROUTINE calcula(theta, omega, t, n, length, dt)
 INTEGER, INTENT (IN) :: n
REAL*8, DIMENSION(0:n) :: theta, omega, t
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REAL*8 :: length,dt,g,periodo,k1,k2,l1,l2
  INTEGER :: i
  PI = 4.*ATAN(1.)
  i = 0
  g = 9.80d0
  q=1/2.0d0
   !print*," Amplitud de la fuerza"
   !read*, df
  df = 0.d0
  !df=0.0d0, 0.5d0, 1.20d0
  dfr=2/3.d0
  DO
  t(i+1) = t(i) + dt
  k1 = (-1)*(g/length) *sin(theta(i)) * dt + q * omega(i)*dt+df*sin(dfr*t(i))*dt
  11 = omega(i) * dt
  k2 = (-1)*(g/length) *sin(theta(i)+l1) * dt + q * (omega(i)+k1)*dt+df*sin(dfr*t(i+1))
  12 = (omega(i)+k1) * dt
  omega(i+1) = omega(i) + (0.5d0)*(k1+k2)
  theta(i+1) = theta(i) + (0.5d0)*(11+12)
   !omega(i+1) = omega(i) - (g/length) *sin(theta(i)) * dt + q * omega(i)*dt+df*sin(dframe) * dframe (frame) 
   !theta(i+1) = theta(i) + omega(i+1) * dt ! Metodo de Cromer
  if (theta(i+1) > PI) theta(i+1)=theta(i+1)-2.*PI
  if (theta(i+1) < -PI) theta(i+1)=theta(i+1)+2.*PI
  IF (i \ge n-1) EXIT
  i=i+1
  ENDDO
END SUBROUTINE calcula
SUBROUTINE despliega(theta, omega, t, n, length, dt)
  INTEGER, INTENT (IN) :: n
  REAL*8, DIMENSION(0:n) :: theta,omega,t
  REAL*8 :: length,dt
  INTEGER :: i
  CHARACTER(LEN=10), PARAMETER :: f1 = '(3ES16.6)'
  CHARACTER(10) :: archivo
   !print*," archivo de datos"
   !read*, archivo
  archivo = "pen.dat"
  OPEN (UNIT=1,FILE=archivo,STATUS='UNKNOWN')
  WRITE(1,f1)(theta(i),omega(i),t(i), i=0,n)
  CLOSE(1)
END SUBROUTINE despliega
```

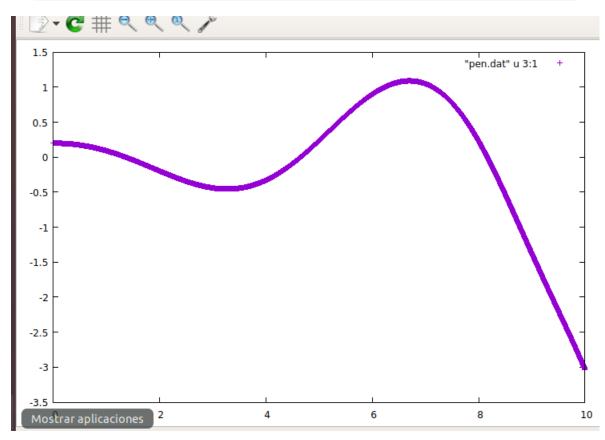
```
misael@misael-VirtualBox:~/Descargas$ gfortran penduloRKII.f90
misael@misael-VirtualBox:~/Descargas$ ./a.out
misael@misael-VirtualBox:~/Descargas$ gnuplot

G N U P L O T
Version 5.2 patchlevel 2 last modified 2017-11-01

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gnuplot home: http://www.gnuplot.info
faq, bugs, etc: type "help FAQ"
immediate help: type "help" (plot window: hit 'h')

Terminal type is now 'qt'
gnuplot> p "pen.dat" u 3:1
gnuplot>
```



```
!print*, "numero de pasos"
 !read*, n
 n = 10000
 ALLOCATE (theta(0:n),omega(0:n),t(0:n))
!
 call inicializa(theta, omega, t, n, length, dt)
 call calcula (theta, omega, t, n, length, dt)
 call despliega (theta, omega, t, n, length, dt)
END PROGRAM Euler_Cromer
SUBROUTINE inicializa(theta, omega, t, n ,length, dt)
 INTEGER, INTENT (IN) :: n
 REAL*8, DIMENSION(0:n) :: theta, omega, t
 REAL*8 :: length,dt
 !print*,'Angulo inicial del pendulo (en radianes)'
 !read*, theta(0)
 theta(0) = 0.2d0
 !print*,'Velocidad angular inicial del pendulo (en radianes/s)'
 !read*, omega(0)
 omega(0) = 0.d0
 t(0)=0.d0
 !print*,'Longitud del pendulo (in m)'
 !read*, length
 length = 9.80d0
 !print*, 'Tamaño de paso (en segundos)'
 !read*, dt
 dt = 0.001
END SUBROUTINE inicializa
SUBROUTINE calcula(theta, omega, t, n, length, dt)
 INTEGER, INTENT (IN) :: n
 REAL*8, DIMENSION(0:n) :: theta, omega, t
 REAL*8 :: length,dt,g,periodo,k1,k2,k3,k4,l1,l2,l3,l4
 INTEGER :: i
 PI = 4.*ATAN(1.)
 i = 0
 g = 9.80d0
 q=1/2.0d0
 !print*," Amplitud de la fuerza"
 !read*, df
 df = 0.d0
 !df=0.0d0, 0.5d0, 1.20d0
```

```
dfr=2/3.d0
  DO
  t(i+1) = t(i) + dt
  k1 = (-1)*(g/length) *sin(theta(i)) * dt + q * omega(i)*dt+df*sin(dfr*t(i))*dt
  11 = omega(i) * dt
  k2 = (-1)*(g/length) *sin(theta(i)+(l1*(0.5d0))) * dt + q * (omega(i)+(k1*(0.5d0)))*
  12 = (\text{omega}(i) + (k1*(0.5d0))) * dt
  k3 = (-1)*(g/length) *sin(theta(i)+(12*(0.5d0))) * dt + q * (omega(i)+(k2*(0.5d0)))*
  13 = (\text{omega}(i) + (k2*(0.5d0))) * dt
  k4 = (-1)*(g/length) *sin(theta(i)+(13*(0.5d0))) * dt + q * (omega(i)+(k3*(0.5d0)))*
  14 = (\text{omega}(i) + (k3*(0.5d0))) * dt
  omega(i+1) = omega(i) + (1/6d0)*(k1+2*k2+2*k3+k4)
  theta(i+1) = theta(i) + (1/6d0)*(11+2*12+2*13+14)
   !omega(i+1) = omega(i) - (g/length) *sin(theta(i)) * dt + q * omega(i)*dt+df*sin(dframe) * dframe (g/length) * dframe (g/len
   !theta(i+1) = theta(i) + omega(i+1) * dt ! Metodo de Cromer
  if (theta(i+1) > PI) theta(i+1)=theta(i+1)-2.*PI
  if (theta(i+1) < -PI) theta(i+1)=theta(i+1)+2.*PI
  IF (i \ge n-1) EXIT
  i=i+1
  ENDDO
END SUBROUTINE calcula
SUBROUTINE despliega(theta, omega, t, n, length, dt)
  INTEGER, INTENT (IN) :: n
  REAL*8, DIMENSION(0:n) :: theta, omega, t
  REAL*8 :: length,dt
  INTEGER :: i
  CHARACTER(LEN=10), PARAMETER :: f1 = '(3ES16.6)'
  CHARACTER(10) :: archivo
   !print*," archivo de datos"
  !read*, archivo
  archivo = "pen.dat"
  OPEN (UNIT=1,FILE=archivo,STATUS='UNKNOWN')
  WRITE(1,f1) (theta(i),omega(i),t(i), i=0,n)
  CLOSE(1)
END SUBROUTINE despliega
```

```
misael@misael-VirtualBox:~/Descargas$ gfortran penduloRKIV.f90
misael@misael-VirtualBox:~/Descargas$ ./a.out
misael@misael-VirtualBox:~/Descargas$ gnuplot

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Terminal type is now 'qt'
gnuplot> p "pen.dat" u 3:1
gnuplot> exit
```

