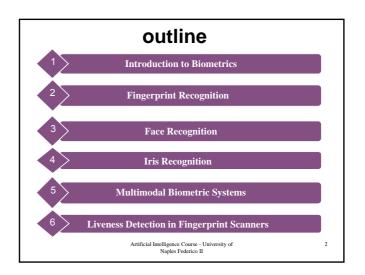
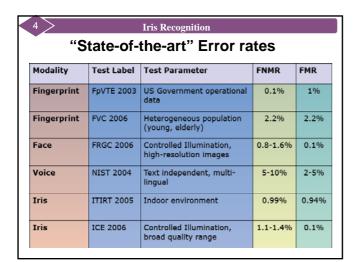


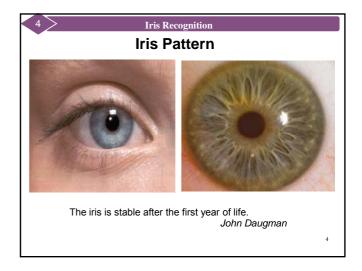


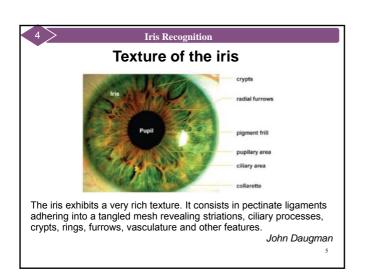
# BIOMETRIC SYSTEMS

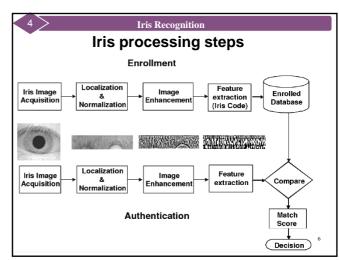
"Artificial Intelligence" Course University of Naples Federico II May 13, 2010





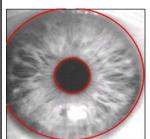






### Iris Recognition

## **Localizing Iris**



- · Localize precisely the inner and outer boundaries of the iris.
- · Detect and exclude eyelids if they intrude.
- · These detection operations are accomplished by an integrodifferential operator, which behaves as a circular edge detector:

I(x,y)<sub>ds</sub>  $\max(_{r,x0,y0})\,|\,G_{\sigma}\big(r\big)*$  $\partial r \int_{r,x_0,y_0}^{y} 2\pi r$ 

 $\bullet$  The operator searches for a circular boundary with radius r and center  $(x_0,\,y_0)$  such that the change in radial pixel intensity across the boundary is maximum.

## Iris Recognition

## Iris Encoding

The output of the segmentation process is a binary mask that indicates the Iris and non-iris pixels in the image.

Normalization scheme: each point in the (x,y) domain is mapped to a pair of Polar coordinates  $(r, \Theta)$ . This results in a fixed size rectangular iris image.



### Iris Recognition

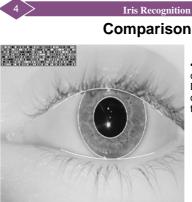
### **IrisCode**

Gabor filters are then used to extract the textural information from the iris encoding

 $G(x,y) = e^{-\pi[(x-x_0)^2/\alpha^2 + (y-y_0)^2/\beta^2]} e^{-2\pi i[u_0(x-x_0) + \nu_0(y-y_0)]}$ 

Since the prominence of iris texture changes as one moves away from the pupil, three different Gabor filters are applied to different regions of the normilized iris.





• Two IrisCodes of eyes are compared by using Hamming Distance (HD) in order to detect the fraction of their bits that disagree.

 $HD = \frac{\|(I_1 \bigotimes I_2) \bigcap M_1 \bigcap M_2\|}{\|I_1 \bigotimes I_2 \bigcap M_1 \bigcap M_2\|}$  $||M_1 \cap M_2||$ 

## **Multimodal Biometric Systems**

## **Fusion in Biometrics**

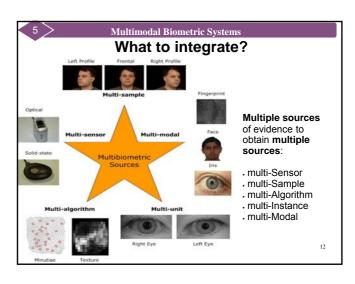
A combination of multiple pieces of the evidence

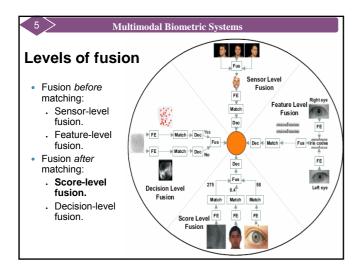


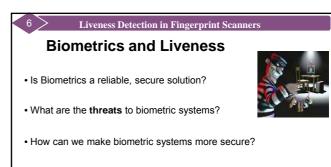
## Why Multi-Biometrics?

- · Performance Improvement, error rates are not zero
- Noisy Data, e.g., low quality images Intra-class Variations, e.g., different samples of the same person
- Distinctiveness: Inter-class Similarity
- Non-Universality
- · Spoof Attacks, e.g., artificial fingers



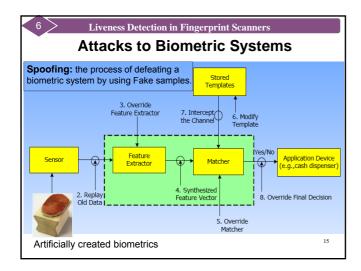


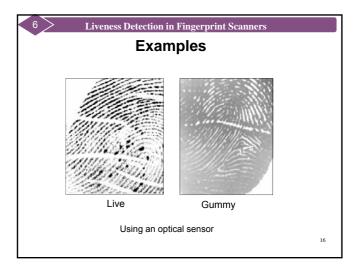


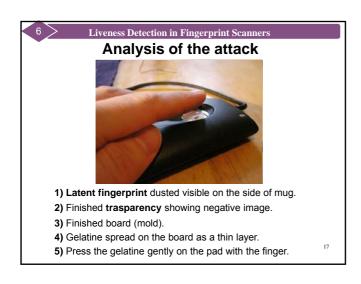


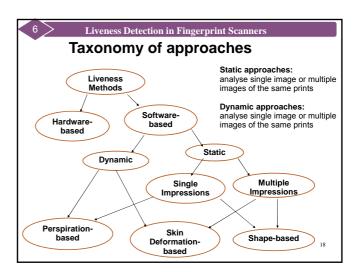
- Since intruders will introduce a large number of spoofed biometrics, Liveness will enhance performance of a biometric system.
- Liveness detection reads claimant's physiological signs of life.

14









## Liveness Detection in Fingerprint Scanners

## Static Algorithm

- The fingerprint image is tranformed into a ridge signal.
- The algorithm is based on statical features derived from a single fingerprint image.
  - Pore spacing.
  - Residual noise of the fingerprint image.
  - Intensity-based features.
  - Texture analysis

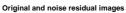


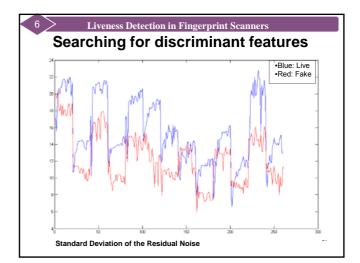


1000 dpi sensor









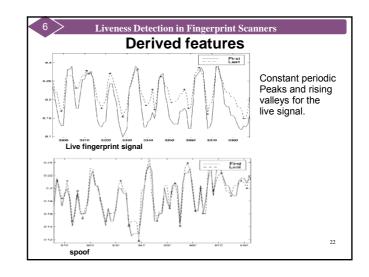
### **Liveness Detection in Fingerprint Scanners**

## **Dynamic Algorithm**

## West Virginia Perspiration Method:

- The algorithm analyse the perspiration over time as sign of life.
- Fingerprint images are processed and ridge signals are obtained.
- Signal amplitude is proportional to the moisture along the traversed ridges.
- Peaks relate to the moistest and valleyss to driest regions.
- In live fingers, perspiration starts around the pores and spread along the ridges creating a distinct signature of the process.

21



### **Liveness Detection in Fingerprint Scanners**

### References

- K. Choi H. Choi, R. Kang and J. Kim, "Aliveness detection of fingerprint using multiple static features", World Academy of Science, Engineering and Technology, 28: 157-162, 2007.
- S. Schuckers, "Spoofing and Anti-spoofing measures", Information Security Technical Report, 7(4): 56-62, 2002.

23