

Relativistic Electrodynamics

The Brief Summary

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Syllabus

The Syllabus and Learning Outcomes

https:

[//www.dur.ac.uk/faculty.handbook/module_description/?year=2017&module_code=PHYS3661](https://www.dur.ac.uk/faculty.handbook/module_description/?year=2017&module_code=PHYS3661)

Content

- The syllabus contains:
- Relativistic Electrodynamics: Einstein's postulates, the geometry of relativity, Lorentz transformations, structure of space-time, proper time and proper velocity, relativistic energy and momentum, relativistic kinematics, relativistic dynamics, magnetism as a relativistic phenomenon, how the fields transform, the field tensor, electrodynamics in tensor notation, relativistic potentials, scalar and vector potentials, gauge transformations, Coulomb gauge, retarded potentials, fields of a moving point charge, dipole radiation, radiation from point charges.

Learning Outcomes

Subject-specific Knowledge:

- Having studied this module, students will have developed a working knowledge of tensor calculus, and be able to apply their understanding to relativistic electromagnetism.

Reading List

<http://www.dur.ac.uk/physics/modules/2017/phys3661/>
Sections in “Introduction to Electrodynamics”, D. J. Griffiths.

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|----|--|----|---|
| 1 | Einstein's postulates [12.1] | 11 | The Field Tensor [12.3] |
| 2 | The geometry of relativity [12.1] | 12 | Electrodynamics in Tensor notation [12.3] |
| 3 | Lorentz transformations [12.1] | 13 | Relativistic potentials [12.3] |
| 4 | Structure of space-time [12.1] | 14 | Scalar and Vector potentials [10.1] |
| 5 | Proper time and proper velocity [12.2] | 15 | Gauge transformations [10.1] |
| 6 | Relativistic energy and momentum [12.2] | 16 | Coulomb gauge [10.1] |
| 7 | Relativistic Kinematics [12.2] | 17 | Retarded potentials [10.2] |
| 8 | Relativistic Dynamics [12.2] | 18 | Fields of a moving point charge [10.3] |
| 9 | Magnetism as a relativistic phenomena [12.3] | 19 | Dipole radiation [11.1] |
| 10 | How the Fields transform [12.3] | 20 | Radiation from point charges [11.2] |

Einstein's Postulates

Inertial frames (IF)

A Euclidean frame in which a body not acted upon by external forces moves with constant velocity.

Relativity principle

The laws of physics have the same form in all IF.

Invariance of c

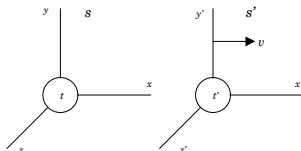
The speed of light in vacuum, c , is independent of the motion of its source.

Lorentz transformation (LT)

Assume the IF's S and S' are in the standard configuration

For $t = t' = 0$

S and S' coincide



$$ct' = \gamma ct - \gamma\beta x$$

$$x' = \gamma x - \gamma\beta ct$$

$$y' = y$$

$$z' = z$$

$$ct = \gamma ct' + \gamma\beta x'$$

$$x = \gamma x' + \gamma\beta ct'$$

$$y = y'$$

$$z = z'$$

$$\gamma \equiv \frac{1}{\sqrt{1 - \frac{v^2}{c^2}}}$$

$$\beta \equiv \frac{v}{c}$$

Lorentz invariant: $(ct)^2 - x^2 - y^2 - z^2 = (ct')^2 - x'^2 - y'^2 - z'^2$

One-dimensional addition of velocities: $v_{AC} = \frac{v_{AB} + v_{BC}}{1 + v_{AB}v_{BC}/c^2}$

Basics of Relativity

Lorentz invariant classification of 4-vectors

consider a 4-vector $s^\mu = (s^0, \vec{s})$ and it's (Minkowski) square
 $s^2 \equiv s^\mu s_\mu$.

$s^2 = 0$ lightlike

$s^2 < 0$ spacelike there is an IF S' s.t. $s'^0 = 0$

$s^2 > 0$ timelike there is an IF S'' s.t. $\vec{s}'' = \vec{0}$

- The distance of any two points on the worldline of a particle is **timelike** (or **lightlike** if the particle travels at the speed of light).
- The worldline is globally and locally within the lightcone
- Spacelike separated events cannot be causally connected

Basics of Relativity

Time dilation

- τ : The **proper time** of the object, i.e. the time as measured in the rest frame of the object
- t : The time as measured in an IF moving with velocity v with respect to the object

$$d\tau = \frac{dt}{\gamma(v)}$$

Length contraction

- l_0 : The **proper length** of the object, i.e. the length as measured in the rest frame of the object
- l' : The length as measured in an IF moving with velocity v with respect to the object

$$l_0 = \gamma(v) l'$$

Tensor Calculus

scalar: A single quantity that is the same in all IF

4-vector: Any quantity that transforms like

$$x^\mu = (x^0, x^1, x^2, x^3) \stackrel{\text{old not}}{=} (ct, x, y, z) = (ct, \vec{x})$$

Transformation of x^μ

$$x'^\mu = \sum_{\nu=0}^3 \Lambda^\mu_{\nu} x^\nu \stackrel{\Sigma_{\text{conv}}}{=} \Lambda^\mu_{\nu} x^\nu = \frac{\partial x'^\mu}{\partial x^\nu} x^\nu$$

or written explicitly for the standard configuration of frames

$$\begin{pmatrix} ct' \\ x' \\ y' \\ z' \end{pmatrix} = \begin{pmatrix} \gamma & -\gamma\beta & 0 & 0 \\ -\gamma\beta & \gamma & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} ct \\ x \\ y \\ z \end{pmatrix}$$

x^μ is a **contravariant** 4-vector.

Tensor Calculus

The corresponding **covariant** 4-vector is defined by

$$x_{\mu} = g_{\mu\nu} x^{\nu} \stackrel{\text{old}}{=} \stackrel{\text{not}}{=} (ct, -\vec{x})$$

where $g_{\mu\nu} = \text{diag}(1, -1, -1, -1)$ is the **metric**. It transforms as

$$x'_{\mu} = \Lambda_{\mu}^{\nu} x_{\nu} = \frac{\partial x^{\nu}}{\partial x'^{\mu}} x_{\nu} \quad \text{with} \quad \Lambda^{\mu}_{\rho} \Lambda_{\mu}^{\nu} = g_{\rho}^{\nu} = \delta_{\rho}^{\nu}$$

The Minkowski scalar product of two 4-vectors

$$x^{\mu} y_{\mu} = x_{\mu} y^{\mu} = x_{\mu} y_{\nu} g^{\mu\nu} = x^0 y^0 - \vec{x} \cdot \vec{y} = \dots$$

is invariant under LT

Tensor of rank 2: Any quantity $F^{\mu\nu}$ that transforms as follows:

$$F'^{\mu\nu} = \Lambda^{\mu}_{\rho} \Lambda^{\nu}_{\sigma} F^{\rho\sigma}$$

Important 4-vectors

4-velocity: $u^\mu \equiv \frac{dx^\mu}{d\tau} = \gamma(v) (c, \vec{v})$ Note: $u^\mu u_\mu = c^2$

4-momentum: $p^\mu \equiv m_0 u^\mu = m_0 \gamma(v) (c, \vec{v}) \equiv m_\gamma (c, \vec{v})$

m_0 : The rest mass of the object, i.e. the mass as measured in its rest frame.

m_γ : The inertial mass. This mass is not Lorentz invariant and is hardly ever used: $m_\gamma \equiv m_0 \gamma(v)$

E_0 : The rest energy of the object: $E_0 = m_0 c^2$

E : The total relativistic energy of the object:
 $E = E_0 + E_{\text{kin}}$

\vec{p} : The relativistic momentum: $\vec{p} = \gamma m_0 \vec{v}$

$$p^\mu = \left(\frac{E}{c}, \vec{p} \right) \quad \text{and} \quad p^2 \equiv p^\mu p_\mu = \frac{E^2}{c^2} - \vec{p}^2 = m_0^2 c^2$$

Important 4-vectors

4-acceleration:

$$a^\mu \equiv \frac{d^2 x^\mu}{d\tau^2} = \frac{du^\mu}{d\tau}$$

- **proper acceleration:** the acceleration as measured in the rest frame
- **uniformly accelerated:** acceleration with constant proper acceleration

Note: $a^\mu = \gamma (\dot{\gamma} c, \dot{\gamma} \vec{v} + \gamma \vec{a})$ where $\dot{\gamma} \equiv d\gamma/dt$. Also, $a^\mu u_\mu = 0$.

4-force: $f^\mu \equiv \frac{dp^\mu}{d\tau}$ $f^\mu = \left(\frac{\gamma}{c} \frac{dE}{dt}, \gamma \vec{F} \right)$ where \vec{F} is normal 3-force.

$$\vec{F} = \gamma m_0 \left(\vec{a} + \frac{\vec{v}(\vec{v} \cdot \vec{a})}{c^2 - \vec{v}^2} \right) \quad \text{Only if } \vec{v} \cdot \vec{a} = 0 (\dot{\gamma} = 0) \text{ is } \vec{F} = \gamma m_0 \vec{a}.$$

Electromagnetism

$$\vec{\nabla} \cdot \vec{E} = \frac{\rho}{\epsilon_0}$$

$$\vec{\nabla} \cdot \vec{B} = 0$$

$$\vec{\nabla} \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$$

$$\vec{\nabla} \times \vec{B} = \mu_0 \vec{j} + \frac{1}{c^2} \frac{\partial \vec{E}}{\partial t}$$

$$\vec{F} = q(\vec{E} + \vec{v} \times \vec{B})$$

$$c = \frac{1}{\sqrt{\epsilon_0 \mu_0}}$$

Electromagnetic 4-Vectors

4-current density:

$$j^\mu \equiv \rho_0 \gamma(\mathbf{c}, \vec{v}) = \rho(\mathbf{c}, \vec{v}) = (\rho c, \vec{j})$$

ρ_0 : charge density in rest frame;

ρ : charge density;

Continuity equation:

$$\partial_\mu j^\mu = 0$$

$$\partial_\mu = \frac{\partial}{\partial x^\mu} = \left(\frac{1}{c} \frac{\partial}{\partial t}, \vec{\nabla} \right)$$

$$\partial^\mu = \frac{\partial}{\partial x_\mu} = \left(\frac{1}{c} \frac{\partial}{\partial t}, -\vec{\nabla} \right)$$

4-potential:

$$A^\mu \equiv (\Phi, c\vec{A})$$

Φ : scalar potential, \vec{A} : vector potential

The relation of the potential to the \vec{E} and \vec{B} field is as follows:

$$\vec{E} = -\vec{\nabla}\Phi - \frac{\partial \vec{A}}{\partial t}; \quad \vec{B} = \vec{\nabla} \times \vec{A};$$

These relations entail $\vec{\nabla} \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$ and $\vec{\nabla} \cdot \vec{B} = 0$

The 4-Potential

Gauge transformation: For any “reasonable” function $\Psi(t, \vec{x})$, the transformation

$$\Phi \rightarrow \Phi - \frac{\partial \Psi}{\partial t}; \quad \vec{A} \rightarrow \vec{A} + \vec{\nabla} \Psi \quad \therefore \quad A^\mu \rightarrow A^\mu - c \partial^\mu \Psi$$

leaves \vec{E} and \vec{B} **unchanged**. This allows fixing $\vec{\nabla} \cdot \vec{A}$ (choosing a gauge). The **Lorenz gauge** is convenient in electrodynamics:

$$\vec{\nabla} \cdot \vec{A} = -\frac{1}{c^2} \frac{\partial \Phi}{\partial t} \quad \text{or} \quad \partial_\mu A^\mu = 0$$

Wave equation:

The two remaining Maxwell equations $\vec{\nabla} \cdot \vec{E} = \frac{\rho}{\epsilon_0}$ and $\vec{\nabla} \times \vec{B} = \mu_0 \vec{j} + \frac{1}{c^2} \frac{\partial \vec{E}}{\partial t}$ lead to (using Lorenz Gauge):

$$\partial_\mu \partial^\mu A^\nu = \frac{1}{c \epsilon_0} j^\nu \quad \text{wave equation}$$

In vacuum, $\partial_\mu \partial^\mu A^\nu = 0$ and the solutions are **plane waves**: $e^{-ik^\nu x_\nu} = e^{-i\omega t + i\vec{k} \cdot \vec{x}}$ where $k^\nu = (\frac{\omega}{c}, \vec{k})$ is the wave 4-vector.

The Field Strength Tensor

The Electromagnetic Field Strength Tensor is defined from the potential as

$$\boxed{F^{\mu\nu} \equiv \partial^\mu A^\nu - \partial^\nu A^\mu} \quad \text{dual:} \quad \boxed{\tilde{F}^{\mu\nu} \equiv \frac{1}{2} \epsilon^{\mu\nu\rho\sigma} F_{\rho\sigma}}$$

with $\epsilon^{\mu\nu\rho\sigma}$ the totally antisymmetric 4-dimensional **Levi-Civita tensor**: $\epsilon^{\mu\nu\rho\sigma} = -\epsilon_{\mu\nu\rho\sigma}$ and $\epsilon_{0123} = +1$

The explicit form of $F^{\mu\nu}$ in terms of the fields is

$$F^{\mu\nu} = \begin{pmatrix} 0 & -E_x & -E_y & -E_z \\ E_x & 0 & -cB_z & cB_y \\ E_y & cB_z & 0 & -cB_x \\ E_z & -cB_y & cB_x & 0 \end{pmatrix} \quad \tilde{F}^{\mu\nu} = \begin{pmatrix} 0 & cB_x & cB_y & cB_z \\ -cB_x & 0 & -E_z & E_y \\ -cB_y & E_z & 0 & -E_x \\ -cB_z & -E_y & E_x & 0 \end{pmatrix}$$

Maxwell Equations and Transformation of the Fields

Maxwells equations in covariant form ($\mu_0\epsilon_0 = c^{-1/2}$)

$$\left. \begin{aligned} \vec{\nabla} \cdot \vec{E} &= \frac{\rho}{\epsilon_0} \\ \vec{\nabla} \times \vec{B} &= \mu_0 \vec{j} + \frac{1}{c^2} \frac{\partial \vec{E}}{\partial t} \end{aligned} \right\} \rightarrow \boxed{\partial_\mu F^{\mu\nu} = \frac{1}{c\epsilon_0} j^\nu}$$

$$\left. \begin{aligned} \vec{\nabla} \times \vec{E} &= -\frac{\partial \vec{B}}{\partial t} \\ \vec{\nabla} \cdot \vec{B} &= 0 \end{aligned} \right\} \rightarrow \boxed{\partial_\mu \tilde{F}^{\mu\nu} = 0}$$

Assume S and S' are in **standard configuration**:

$$\begin{aligned} E'_x &= E_x & B'_x &= B_x \\ E'_y &= \gamma(E_y - vB_z) & B'_y &= \gamma\left(\frac{v}{c^2}E_z + B_y\right) \\ E'_z &= \gamma(E_z + vB_y) & B'_z &= \gamma\left(-\frac{v}{c^2}E_y + B_z\right) \end{aligned}$$

Lorentz Invariants

$$\left. \begin{aligned} \vec{E} \cdot \vec{B} &= \frac{1}{4c} F_{\mu\nu} \tilde{F}^{\mu\nu} \\ \vec{E}^2 - c^2 \vec{B}^2 &= -\frac{1}{2} F_{\mu\nu} F^{\mu\nu} \end{aligned} \right\} \text{Invariant under LT}$$

Fields of a moving point charge

The **4-potential** (Lorenz gauge) at the point \vec{r} at time t of a **point charge** in **arbitrary motion**

$$A^\mu(\vec{r}, t) = \frac{q}{4\pi\epsilon_0} \frac{u^\mu}{u_\nu R^\nu}$$

(u^μ is the 4-velocity of the particle at the retarded time t_r).

The corresponding **electromagnetic fields** are given by

$$\vec{E}(\vec{r}, t) = \frac{q}{4\pi\epsilon_0} \frac{R}{(\vec{R} \cdot \vec{u})^3} \left[\overbrace{[(c^2 - v^2)\vec{u}]}^{\text{velocity field}} + \overbrace{\vec{R} \times (\vec{u} \times \vec{a})}^{\text{acceleration field}} \right]$$

$$\vec{B}(\vec{r}, t) = \frac{1}{c} \hat{\vec{R}} \times \vec{E}(\vec{r}, t)$$

where \vec{R} is the vector between the point charge and the observer, \vec{v} is the velocity of the point charge, $\vec{u} = c\hat{\vec{R}} - \vec{v}$, and \vec{a} is the acceleration of the point charge. \vec{R} , \vec{u} , \vec{v} , and \vec{a} must be evaluated at the **retarded time** $t_r = t - R/c$.

Power radiated

The Poynting vector is

$$\vec{S} = \frac{1}{\mu_0} \vec{E} \times \vec{B}$$

The **Power radiated** by an **accelerated point charge**

$$\begin{aligned} P &= \int \left(\frac{\vec{R} \cdot \vec{u}}{Rc} \right) |\vec{S}| R^2 d\Omega = -\frac{\mu_0 q^2}{6\pi c} \frac{1}{(mc)^2} \frac{dp^\mu}{d\tau} \frac{dp_\mu}{d\tau} \\ &= \frac{\mu_0 q^2 \gamma^2}{6\pi m^2 c} \left[\left| \frac{dp}{dt} \right|^2 - \beta^2 \left(\frac{dp}{dt} \right)^2 \right] \\ &= \frac{\mu_0 q^2 \gamma^6}{6\pi c} \left(\vec{a}^2 - \left| \frac{\vec{v} \times \vec{a}}{c} \right|^2 \right) \end{aligned}$$