

## **Robotics Competition**

2019-20

### **Testing Instructions**

This file contains testing instructions for Buzzer, Standard Servo, Motor Driver, Motor Encoder and LCD along with ATmega2560 Development board.

Make sure you have followed instructions given in Assembly of Hardware.pdf.

#### Steps to follow in the testing instructions:

- 1. Assemble the circuits which is as shown in the **Assembly of Hardware.pdf** provided to you.
- 2. Follow the instruction given in **NEX AVR USB ISP STK500V2.pdf** to burn the hex file.
- 3. Burn the appropriate hex files provide in **HEX** folder to test the following components.
  - Buzzei
    - a) Check the connection of buzzer with the Atmega 2560 Development Board.
    - b) Burn buzzer test.hex File
    - c) Beep sound from buzzer indicate the successful testing of buzzer.
  - LCD
    - a) Check the connection of LCD with the Atmega 2560 Development Board in **Assembly of Hardware.pdf**.
    - b) Burn LCD test.hex File
    - c) Displaying "Testing Done" on LCD indicate LCD test is complete.
  - Servo
    - d) Check the connection of Servo with the Atmega 2560 Development Board in **Assembly of Hardware.pdf**.
    - a) Burn servo test.hex file
    - b) Servo moving at different angle with some delay indicate servo test is complete.

Note: Similarly, You can check the other provided servo motor

- DC Motor
  - a) Check the connection of Servo with the Atmega 2560 Development Board in **Assembly of Hardware.pdf**.
  - b) Burn motor test.hex File.
  - c) Motor moving in forward and backward direction indicates the Motor test is complete
- Encoder
  - a) Check the connection of Servo with the Atmega 2560 Development Board in **Assembly of Hardware.pdf**.
  - b) Burn encoder test.hex File
  - c) Value of encoder will be printing on serial port. To check the value on serial port follow the following procedure
  - d) Monitoring Output on Serial Terminal
    - ❖ Use Tera Term to view the encoder values.
    - ❖ Install Tera Term from the link given.
    - ❖ Go to Setup->Serial Port.
    - Set the Speed (Baud Rate) to 57600.
    - \* Rotate the motor forward and backward direction by hand
    - ❖ You will be able to view the encoder values on Tera Term





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Refer this video link on: How to do the hardware testing and record a video and submit.

#### **Submission Instruction:**

After successful testing of the hex file provided to you, make a video of the whole testing process and submit the you tube link of video on portal.

All The Best!!

