

Mishal Assif P K | Resume

CSL 164, 1308 W Main St – Urbana, IL 61801

📧 [mishalassif.github.io](https://github.com/mishalassif)

✉ mishal2@illinois.edu

EDUCATION

University of Illinois Urbana-Champaign

Ph.D in Electrical Engineering, CPI: 4.00/4.00

Urbana-Champaign, USA

Present

Indian Institute of Technology Bombay

B.Tech + M.Tech in Mechanical Engineering, CPI: 8.63/10.00

Bombay, India

August 2019

PUBLICATIONS

Scenario approach for minmax optimization in the nonconvex setting: positive results and caveats

M. Assif P K, D. Chatterjee, R. Banavar

2020

SIAM Journal on Optimization, Vol.30(2), 2020. [\[doi\]](#), [\[arXiv preprint\]](#)

A simple proof of the discrete time geometric Pontryagin maximum principle

M. Assif P K, D. Chatterjee, R. Banavar

2020

Automatica, Vol.114, 2020. [\[doi\]](#), [\[arXiv preprint\]](#)

Measure of quality of finite-dimensional linear systems: A frame-theoretic view

M. Assif P K, M. R. Sheriff, D. Chatterjee

2019

Submitted. [\[arXiv preprint\]](#)

Variational collision avoidance on Riemannian manifolds

M. Assif, R. Banavar, A. M. Bloch, M. Camarinha, L. Colombo

2018

Proceedings of the IEEE Conference on Decision and Control, 2018. [\[doi\]](#), [\[arXiv preprint\]](#)

TEACHING EXPERIENCE

Microprocessors and Automatic Control (Theory + Lab)

Teaching Assistant

2019

Differential Geometric Methods in Control

Teaching Assistant

2018

TECHNICAL EXPERIENCE

Autonomous Underwater Vehicle Team (AUV-IITB)

Software developer, Controls subsystem

2015 - 2016

- Worked as part of a team in the development of algorithms to enable an AUV to autonomously localise itself and perform realistic missions based on feedback from visual, inertial and acoustic sensors.
- Secured second place at the International AUVSI Robosub competition 2016.
- Maintained a very modular software stack written in C++ and Python, using ROS for integrations of various subsystems.
- Implemented a finite state machine for planning the execution flow of the AUV.
- Developed and tuned a PID controller for controlling the 5 degrees of freedom of the AUV.
- Created various ancilliary tools such as drivers for sensors, simulators and runtime debug interfaces.

SOFTWARE SKILLS

Programming Languages: C++, Python, Matlab. **Other tools:** \LaTeX , ROS, Gazebo, OpenCV.