

Color Image Processing - Summary Notes

1. Color Models

- RGB: (R, G, B) $\in [0, 255]$.
- HSI: Hue (H), Saturation (S), Intensity (I).
- $I = (R+G+B)/3$

2. Power-Law Transformation (Gamma Correction)

$$f_{\text{out}} = 255 * (f_{\text{in}} / 255)^{\gamma}$$

3. Filters

- Averaging filter (smoothing): $g(x,y) = (1/mn) \sum f(x+i, y+j)$
- Gaussian filter: $g(x,y) = \sum f(x+i,y+j) * \exp(-(i^2+j^2)/(2\sigma^2))$

4. Laplacian (Sharpening)

$$\nabla^2 f(x,y) = \partial^2 f / \partial x^2 + \partial^2 f / \partial y^2$$
$$\text{Sharpened} = f(x,y) - \lambda \nabla^2 f(x,y)$$

5. Segmentation in HSI

- Use Hue for color detection.
- Mask from Saturation > threshold.
- Product: Hue \times Mask \rightarrow Threshold \rightarrow Binary segmentation.

6. Segmentation in RGB

- Mean vector $a = (aR, aG, aB)$
- Box limits = $a \pm 1.25\sigma$ (σ = std deviation per channel).
- Pixel \in box \rightarrow foreground.

7. Edge Detection in RGB

- Vector gradient magnitude:
- $$|\nabla f| = \sqrt{[(\partial R / \partial x)^2 + (\partial R / \partial y)^2 + (\partial G / \partial x)^2 + (\partial G / \partial y)^2 + (\partial B / \partial x)^2 + (\partial B / \partial y)^2]}$$

8. Noise in Color Images

- Additive Gaussian noise: $n(x,y) \sim N(0, \sigma^2)$.
- Noise spreads in HSI due to nonlinear conversion.

9. Color Image Compression

- Image size = width \times height \times bits/pixel.
- RGB (24-bit): 8 bits per channel.
- Compression ratio = Original size / Compressed size.
- Lossy compression may blur, lossless keeps exact data.