Causal Machine Learning - Fall 2023

Week 6: Deep Nets & Two Step Semiparametrics

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Topics to cover

- 1. Derive the influence function for the ATE
- 2. Two step semiparametric inference
 - Solving the problem from last time using influence functions and sample splitting
- 3. More general influence functions

Remember in week 3 we did **parametric** two step estimation:

$$\widehat{\mathbb{E}[Y(1)]} = \frac{1}{n} \sum_{i=1}^{n} x_i' \hat{\beta}_1$$

The big conclusion was to show that the first stage *estimation* had an impact on the second-stage *inference*.

$$\begin{split} \sqrt{n} \left(\widehat{\mathbb{E}[Y(1)]} - \mathbb{E}[Y(1)]\right) \\ &= \frac{1}{\sqrt{n}} \sum_{i=1}^n \left\{ \underbrace{x_i' \beta_1 - \mathbb{E}[X\beta_1]}_{\text{Plug in part}} + \underbrace{\mathbb{E}[X'] \mathbb{E}[TXX']^{-1} t_i x_i \varepsilon_i}_{\text{First step correction}} \right\} + o_p(1) \\ &\to_d \mathcal{N} \left(0, \mathbb{V}[\phi(z_i)]\right) \end{split}$$

Last week we did the same thing, but with ML/nonparametrics in the first stage:

$$\widehat{\mathbb{E}[Y(1)]} = \frac{1}{n} \sum_{i=1}^{n} \hat{\mu}_1(x_i)$$

The big conclusion was that first stage *estimation* had an such a big impact on the second stage that we couldn't get inference

$$\sqrt{n}\left(\widehat{\mathbb{E}[Y(1)]} - \mathbb{E}[Y(1)]\right) \to \infty$$

So we need a two-step estimator that is less sensitive to the first stage.

- 1. Influence function gives us exactly this
- 2. Sample splitting helps even more

Prove that the influence function for $\mathbb{E}[Y(1)]$ is

$$\psi(z_i) = \mu_1(x_i) - \mathbb{E}[Y(1)] + \frac{t_i(y_i - \mu_1(x_i))}{p(x_i)}$$

Remember that we got influence functions by taking the derivative of the parameter with respect to a perturbation in the DGP.

$$\mu(F) = \mathbb{E}[Y(1)] = \mathbb{E}\big[\mathbb{E}[Y \mid T=1, X]\big] = \mathbb{E}\big[\theta(X)\big], \ \theta(X) = \mathbb{E}[Y \mid T=1, X].$$

So we need to find

$$\left. \frac{d}{d\varepsilon} \mu(F_{\varepsilon}) \right|_{\varepsilon=0} = \left. \frac{d}{d\varepsilon} \mathbb{E}_{\varepsilon} \left[\mathbb{E}_{\varepsilon} [Y \mid T=1, X] \right] \right|_{\varepsilon=0} = \left. \frac{d}{d\varepsilon} \int \theta_{\varepsilon}(x) f_{\varepsilon}(x) dx \right|_{\varepsilon=0}$$

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Instead of

$$\widehat{\mathbb{E}[Y(1)]} = \frac{1}{n} \sum_{i=1}^{n} \hat{\mu}_1(x_i)$$

We will use

$$\widehat{\mathbb{E}[Y(1)]} = \frac{1}{n} \sum_{i=1}^{n} \hat{\mu}_1(x_i) + \frac{t_i(y_i - \hat{\mu}_1(x_i))}{\hat{p}(x_i)}$$

for nonparametric $\hat{\mu}_1(x_i)$ and $\hat{p}(x_i)$.

Show that this works...

More generally:

$$\mu(F) = \mu = \mathbb{E}[H(X, \theta(X))], \qquad \theta_0(x) = \arg\max \sum_{i=1}^n \ell(y_i, t_i, \theta(x))$$

Has influence function

$$H(x_i, \theta(x_i)) - \mu + (\nabla_{\theta} H) \mathbb{E}[\ell_{\theta\theta} \mid x_i]^{-1} \ell_{\theta}(y_i, t_i, \theta(x_i))$$