$R(\Omega)$	$A_{\mathbf{x}}$ (V)	$A_{\mathbf{y}}(V)$	$T_{\rm d}({\rm ms})$	$T_{\rm p}({\rm ms})$	$\theta(\mathrm{rad})$	Lissajous Figures
0.1	19.97	1.093	9.6875	10	6.08375	-20_15_10_5 10_15_20 -1.0
10	19.97	0.1093	2.5	10	1.57	0.04 0.02 0.00 -0.02 -0.04 0.10 0.05 0.05 0.05 0.05 0.05 0.05 0.05
1000	19.97	9.56	1.875	10	1.1775	-20_15_10_5 10_15_2010.0
100000	17.005	16.865	0.625	10	0.3925	-15 _10 _5 _10 _1515
1000000) 13.54	13.555	0.3125 1	10	0.19625	0.04 0.02 0.00 -0.02 -0.04

Table 1: A few basic circuit blocks and their frequency response for servo design.