

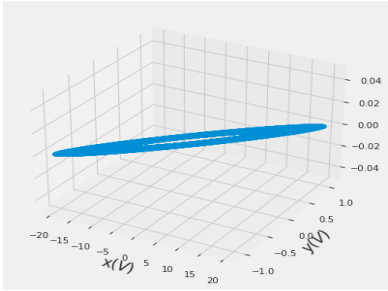
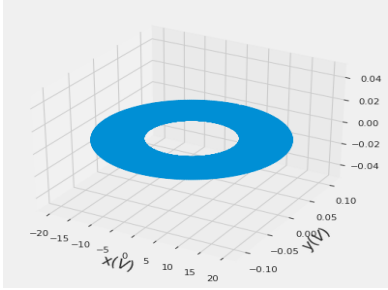
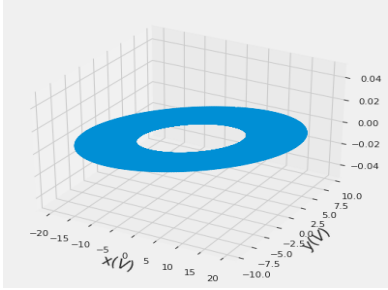
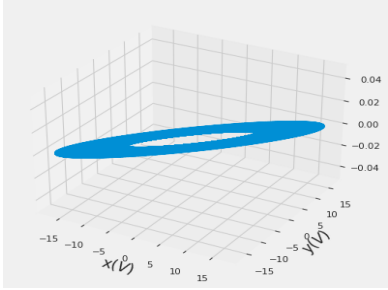
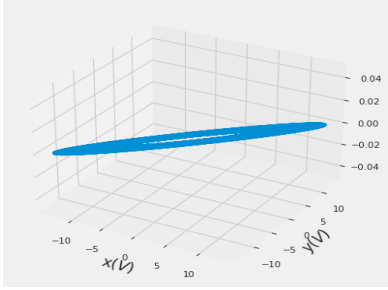
$R(\Omega)$	$A_x (V)$	$A_y (V)$	$T_d(\text{ms})$	$T_p(\text{ms})$	$\theta(\text{rad})$	Lissajous Figures
0.1	19.97	1.093	9.6875	10	6.08375	
10	19.97	0.1093	2.5	10	1.57	
1000	19.97	9.56	1.875	10	1.1775	
100000	17.005	16.865	0.625	10	0.3925	
1000000	13.54	13.555	0.3125	10	0.19625	

Table 1: A few basic circuit blocks and their frequency response for servo design.