

Table 1: Models and failures shown by each model. Each row represents an trained model with a specific architecture and set of training parameters.

	Architecture	Data Aug. & Balancing	Inputs	Dataset Size	Normalization	Epochs	Loss Function
M1	DAVE2	✓	1	11K	×	100	MSE
M2	DAVE2	✓	1	11K	×	100	L1
M3	DAVE2	×	1	11K	ImageNet Norm	100	MSE
M4	DAVE2	×	1	11K	BatchNorm	100	MSE
M5	DAVE2	✓	1	11K	×	convergence	L1
M6	MiniTransformer1	✓	1	11K	×	100	MSE
M7	MiniTransformer1	✓	1	11K	×	convergence	MSE
M8	MiniTransformer1	✓	1	11K	BatchNorm	100	MSE
M9	MiniTransformer1	✓	1	11K	ImageNet Norm	100	MSE
M10	MiniTransformer1	×	1	11K	×	convergence	MSE
M11	MiniTransformer2	✓	1	11K	×	100	MSE
M12	MiniTransformer2	✓	1	11K	×	convergence	MSE
M13	MiniTransformer2	✓	1	11K	BatchNorm	100	MSE
M14	MiniTransformer2	✓	1	11K	ImageNet Norm	100	MSE
M15	MiniTransformer2	×	1	11K	×	100	MSE
M16	MiniTransformer2	×	1	11K	×	convergence	MSE
M17	MiniRecurrent	✓	1 + 4	11K	×	100	MSE
M18	MiniRecurrent	✓	1 + 4	11K	×	convergence	L1
M19	MiniRecurrent	×	1 + 4	11K	×	convergence	MSE
M20	DAVE2	✓	1	11K	BatchNorm	100	L1
M21	DAVE2	✓	1	11K	BatchNorm	convergence	MSE
M22	DAVE2	×	1	11K	BatchNorm	convergence	MSE
M23	DAVE2	×	1	11K	ImageNet Norm	100	L1
M24	DAVE2	✓	1	11K	ImageNet Norm	100	MSE
M25	DAVE2	✓	1	97K	×	convergence	MSE
M26	Chauffeur	✓	1	11K	×	100	MSE
M27	Chauffeur	✓	1	11K	BatchNorm	convergence	MSE
M28	Chauffeur	✓	1	11K	ImageNet Norm	convergence	L1
M29	Chauffeur	✓	1	11K	ImageNet Norm	100	MSE
M30	Chauffeur	×	1	11K	BatchNorm	convergence	MSE
M31	Chauffeur	×	1	11K	ImageNet Norm	convergence	MSE
M32	Chauffeur	×	1	11K	×	convergence	L1
M33	Chauffeur	×	1	11K	×	convergence	MSE
M34	DroNet	✓	1	11K	×	100	L1
M35	DroNet	✓	1	11K	×	convergence	L1
M36	DroNet	✓	1	11K	×	100	MSE
M37	DroNet	✓	1	11K	×	convergence	MSE
M38	DroNet	×	1	11K	BatchNorm	100	MSE
M39	DroNet	×	1	11K	ImageNet Norm	100	MSE
M40	DroNet	×	1	11K	BatchNorm	convergence	MSE
M41	DroNet	×	1	97K	×	100	MSE