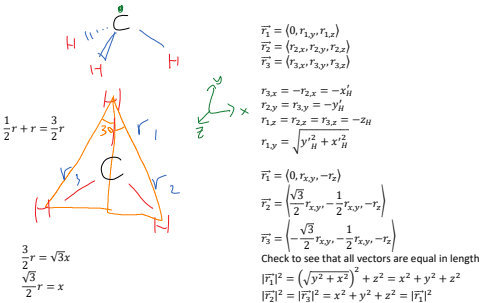


Methyl

Saturday, April 16, 2016 3:23 PM



The origin is at the Carbon atom
Now that we have the relative positions of the atoms in CH_3 radical, we can now determine the total momentum, total angular momentum and center of mass

$$M = \sum_i^4 m_i = m_c + 3m_h$$
$$R_{CM} = \frac{1}{M} \sum_i^4 m_i r_i = \frac{1}{M} (m_c \vec{r}_c + m_h (\vec{r}_1 + \vec{r}_2 + \vec{r}_3))$$
$$\vec{r}_c = 0$$
$$\vec{R}_{CM} = \frac{1}{M} \sum_i^4 m_i r_i = \frac{m_H}{m_c + 3m_H} (\vec{r}_1 + \vec{r}_2 + \vec{r}_3) = \frac{m_H}{m_c + 3m_H} \left((0, r_{x,y}, -r_z) + \left(\frac{\sqrt{3}}{2} r_{x,y}, -\frac{1}{2} r_{x,y}, -r_z \right) + \left(-\frac{\sqrt{3}}{2} r_{x,y}, -\frac{1}{2} r_{x,y}, -r_z \right) \right)$$
$$= \frac{m_H}{m_c + 3m_H} (0, 0, -3r_z)$$
$$\vec{R}_{CM} = \frac{m_H}{m_c + 3m_H} (0, 0, -3r_z) = \alpha (0, 0, -3r_z)$$
$$\alpha = \frac{m_H}{m_c + 3m_H}$$

$$m_H = 1.008u$$
$$m_C = 12.000u$$
$$\vec{R}_{cm} = \frac{1.008u}{12.000u + 3 \cdot 1.008u} (0, 0, -3r_z) = (0, 0, -3\alpha r_z)$$

$$\vec{P} = \sum_i^4 m_i \vec{v}_i$$

define new coordinate system S' shifted to the the center of mass

$$\vec{L} = \sum_i^4 r_i \times m_i \vec{v}_i = \vec{R} \times \vec{P} + \sum_i^4 \vec{r}'_i \times m_i \vec{v}'_i$$
$$\vec{r}' = \vec{r} - R_{cm}$$

$$L = \vec{R} \times \vec{P} + \sum_i^4 m_i (\vec{r}'_i \times \vec{v}'_i)$$

$$m_i (\vec{r}_i - \vec{R}_{cm}) \times (\vec{v}_i - \vec{V}_{cm})$$
$$\vec{r}'_1 = (0, r_{x,y}, -r_z) \Rightarrow \vec{v}'_1 = (0, r_{x,y}, -r_z + 3\alpha r_z) = (0, r_{x,y}, r_z(3\alpha - 1))$$
$$\vec{r}'_2 = \left(\frac{\sqrt{3}}{2} r_{x,y}, -\frac{1}{2} r_{x,y}, -r_z \right) \Rightarrow \vec{v}'_2 = \left(\frac{\sqrt{3}}{2} r_{x,y}, -\frac{1}{2} r_{x,y}, r_z(3\alpha - 1) \right)$$
$$\vec{r}'_3 = \left(-\frac{\sqrt{3}}{2} r_{x,y}, -\frac{1}{2} r_{x,y}, -r_z \right) \Rightarrow \vec{v}'_3 = \left(-\frac{\sqrt{3}}{2} r_{x,y}, -\frac{1}{2} r_{x,y}, r_z(3\alpha - 1) \right)$$
$$\vec{r}'_c = \vec{r}_c = 0 \Rightarrow \vec{v}'_4 = (0, 0, 3\alpha r_z)$$

$$L = \vec{R} \times \vec{P} + \sum_i^4 m_i (\vec{r}'_i \times \vec{v}'_i)$$

$$\vec{r}'_i \times \vec{v}'_i = \vec{r}'_i \times \vec{\omega}_i \times \vec{r}'_i = \vec{r}'_i \times \begin{vmatrix} i & j & k \\ \omega_x^i & \omega_y^i & \omega_z^i \\ r_x^i & r_y^i & r_z^i \end{vmatrix}$$

$$\begin{vmatrix} i & j & k \\ \omega_x^i & \omega_y^i & \omega_z^i \\ r_x^i & r_y^i & r_z^i \end{vmatrix} = \left(\omega_x^i r_z^i - \omega_z^i r_x^i, -(\omega_x^i r_y^i - \omega_y^i r_x^i), \omega_x^i r_y^i - \omega_y^i r_z^i \right) = \left(\omega_x^i r_z^i - \omega_z^i r_x^i, \omega_z^i r_z^i - \omega_x^i r_z^i, \omega_x^i r_y^i - \omega_y^i r_z^i \right)$$

$$\begin{vmatrix} i & j & k \\ r_x^i & r_y^i & r_z^i \end{vmatrix} = \begin{pmatrix} \omega_x^i r_y^i r_z^i - \omega_y^i r_x^i r_z^i - \omega_z^i r_x^i r_y^i + \omega_x^i r_z^i r_x^i \\ \omega_x^i r_z^i r_z^i - \omega_z^i r_y^i r_z^i - \omega_x^i r_y^i r_x^i + \omega_y^i r_x^i r_x^i \\ \omega_x^i r_x^i r_z^i - \omega_z^i r_x^i r_z^i - \omega_x^i r_z^i r_y^i + \omega_y^i r_y^i r_z^i \end{pmatrix} = \begin{pmatrix} \omega_x^i \left[(r_y^i)^2 + (r_z^i)^2 \right] - \omega_z^i r_x^i r_z^i - \omega_x^i r_z^i r_z^i \\ \omega_y^i \left[r_z^i r_z^i + r_x^i r_x^i \right] - \omega_z^i r_x^i r_z^i - \omega_x^i r_y^i r_x^i \\ \omega_z^i \left[r_x^i r_x^i + r_y^i r_y^i \right] - \omega_x^i r_z^i r_x^i - \omega_y^i r_z^i r_y^i \end{pmatrix} = m \begin{pmatrix} \left[(r_y^i)^2 + (r_z^i)^2 \right] & -r_x^i r_y^i & -r_x^i r_z^i \\ -r_x^i r_y^i & [(r_z^i)^2 + (r_x^i)^2] & -r_y^i r_z^i \\ -r_x^i r_z^i & -r_y^i r_z^i & [(r_z^i)^2 + (r_y^i)^2] \end{pmatrix} \begin{pmatrix} \omega_x \\ \omega_y \\ \omega_z \end{pmatrix}$$

$$L = \vec{R} \times \vec{P} + \sum_i^4 m_i \begin{pmatrix} \left[(r_y^i)^2 + (r_z^i)^2 \right] & -r_x^i r_y^i & -r_x^i r_z^i \\ -r_x^i r_y^i & [(r_z^i)^2 + (r_x^i)^2] & -r_y^i r_z^i \\ -r_x^i r_z^i & -r_y^i r_z^i & [(r_z^i)^2 + (r_y^i)^2] \end{pmatrix}_i \begin{pmatrix} \omega_x \\ \omega_y \\ \omega_z \end{pmatrix}_i$$

$$L_{xx} = \sum_i^4 m_i (r_y^2 + r_z^2)_i, \quad L_{xy} = L_{yx} = -\sum_i m_i (xy)_i$$

$$L_{yy} = \sum_i^4 m_i (r_x^2 + r_z^2)_i, \quad L_{yz} = L_{zy} = -\sum_i m_i (yz)_i$$

$$L_{zz} = \sum_i^4 m_i (r_x^2 + r_y^2)_i, \quad L_{zx} = L_{xz} = -\sum_i m_i (zx)_i$$

Diagonal Elements

$$L_{xx} = \sum_i^4 m_i (r_y^2 + r_z^2)_i = m_c (3ar_z)^2 + m_H \left[(r_{x,y}^2 + r_z^2(3\alpha - 1)^2) + 2 \left(\frac{r_{x,y}^2}{4} + r_z^2(3\alpha - 1)^2 \right) \right] = m_c (3\alpha r_z)^2 + m_H \left[\left(\frac{3r_{x,y}^2}{2} \right) + 3r_z^2(3\alpha - 1) \right]$$

$$L_{yy} = \sum_i^4 m_i (r_x^2 + r_z^2)_i = m_c (3\alpha r_z)^2 + m_H \left[r_z^2(3\alpha - 1)^2 + 2 \left(\frac{3}{4} r_{x,y}^2 + r_z^2(3\alpha - 1)^2 \right) \right] = m_c (3\alpha r_z)^2 + m_H \left[3r_z^2(3\alpha - 1)^2 + \frac{3}{2} r_{x,y}^2 \right]$$

$$L_{zz} = \sum_i^4 m_i (r_x^2 + r_y^2)_i = m_c \cdot 0 + m_H \left[0^2 + r_{x,y}^2 + 2 \left(\frac{3}{4} r_{x,y}^2 + \frac{1}{4} r_{x,y}^2 \right) \right] = 3m_H [r_{x,y}^2]$$

$$L_{xx} = L_{yy} = m_c (3\alpha r_z)^2 + m_H \left[3r_z^2(3\alpha - 1)^2 + \frac{3}{2} r_{x,y}^2 \right], \quad L_{zz} = 3m_H [r_{x,y}^2]$$

Off Diagonal Elements

$$L_{xy} = L_{yx} = -\sum_i m_i (xy)_i = -\left[m_c \cdot 0 \cdot 0 + m_H \left(r_{x,y} \cdot 0 + \frac{\sqrt{3}}{2} r_{x,y} \cdot \left(-\frac{1}{2} r_{x,y} \right) + \frac{\sqrt{3}}{2} r_{x,y} \cdot \left(\frac{1}{2} r_{x,y} \right) \right) \right] = 0$$

$$L_{xx} = L_{xx} = -\sum_i m_i (xz)_i = -\left[m_c (0 \cdot 3\alpha r_z) + m_H \left[(0)r_z(3\alpha - 1) + \frac{\sqrt{3}}{2} r_{x,y} r_z(3\alpha - 1) - \frac{\sqrt{3}}{2} r_{x,y} r_z(3\alpha - 1) \right] \right] = 0$$

$$L_{yz} = L_{zy} = -\sum_i m_i (yz)_i = -\left[m_c (0)(3\alpha r_z) + m_H \left[r_{x,y} r_z(3\alpha - 1) - \frac{1}{2} r_{x,y} r_z(3\alpha - 1) - \frac{1}{2} r_{x,y} r_z(3\alpha - 1) \right] \right] = 0$$

$$L_{ij} = \begin{bmatrix} m_c (3\alpha r_z)^2 + m_H \left[\left(\frac{3r_{x,y}^2}{2} \right) + 3r_z^2(3\alpha - 1) \right] & 0 & 0 \\ 0 & m_c (3\alpha r_z)^2 + m_H \left[3r_z^2(3\alpha - 1)^2 + \frac{3}{2} r_{x,y}^2 \right] & 0 \\ 0 & 0 & 3m_H [r_{x,y}^2] \end{bmatrix}$$

$$I_a = I_b = m_c (3\alpha r_z)^2 + m_H \left[3r_z^2(3\alpha - 1)^2 + \frac{3}{2} r_{x,y}^2 \right], \quad I_c = 3m_H [r_{x,y}^2]$$

$$I_{ij} = \begin{bmatrix} I_a & 0 & 0 \\ 0 & I_b & 0 \\ 0 & 0 & I_c \end{bmatrix}, \text{ this is a Oblate Symmetric Top}$$

$$L_i = I_i \omega_i$$

$$L_{ij} = \begin{bmatrix} I_a & 0 & 0 \\ 0 & I_b & 0 \\ 0 & 0 & I_c \end{bmatrix} \begin{pmatrix} \omega_x \\ \omega_y \\ \omega_z \end{pmatrix}$$

$$L^2 = L_x^2 + L_y^2 + L_z^2 = I_a^2 \omega_x^2 + I_b^2 \omega_y^2 + I_c^2 \omega_z^2 \Rightarrow L^2 - L_x^2 = L_y^2 + L_z^2$$

Feedback Signal: $u(t)$

Error Signal: $e(t)$

$$u(t) = K_{pro} e(t) + K_{int} \int e(t) dt$$

$$\bar{n}_{rot} = \frac{L_2^2}{2l_a} + \frac{L_2^2}{2l_b} + \frac{L_2^2}{2l_c} + \frac{L_2^2}{2l_a} + \frac{L_2^2}{2l_b} + \frac{L_2^2}{2l_c} = \frac{1}{2l_a} (L_2^2 + L_2^2) + \frac{L_2^2}{2l_c}$$

$$\bar{H}_{rot} = \frac{L^2 - L_2^2}{2l_a} + \frac{L_2^2}{2l_c} \Rightarrow \left\{ \begin{array}{l} switch \\ to \\ operators \end{array} \right\} \bar{n}_{rot} = \frac{L^2 - L_2^2}{2l_a} + \frac{L_2^2}{2l_c}$$

$$L^2|J, K\rangle = \hbar^2(J(J+1))|J, K\rangle$$

$$L_2^2|J, K\rangle = \hbar^2 K^2|J, K\rangle$$

$$\bar{n}_{rot}|J, K\rangle = E|J, K\rangle = \left(\frac{L^2 - L_2^2}{2l_a} + \frac{L_2^2}{2l_c}\right)|J, K\rangle = \left(\frac{\hbar^2 J(J+1) - K^2}{2l_a} + \frac{\hbar^2 K^2}{2l_c}\right)|J, K\rangle$$

$$E(J, K) = \frac{\hbar^2 J(J+1) - K^2}{2l_a} + \frac{\hbar^2 K^2}{2l_c} = \frac{\hbar^2}{2l_a} J(J+1) + \frac{\hbar^2 K^2}{2} \left(\frac{1}{l_c} - \frac{1}{l_a}\right) = \frac{\hbar^2}{2l_a} J(J+1) + \frac{\hbar^2 K^2}{2} \left(\frac{l_a - l_c}{l_a l_c}\right)$$

$$E(J, K) = \frac{\hbar^2}{2l_a} J(J+1) + \frac{\hbar^2 K^2}{2} \left(\frac{l_a - l_c}{l_a l_c}\right)$$

$$E(J = J' + 1, K'') - E(J = J', K') = \Delta E(\Delta J = 1, \Delta K)$$

$$E(J = J' + 1, K'') = \frac{\hbar^2}{2l_a} \left((J' + 1)(J' + 1 + 1) \right) + \frac{\hbar^2 K''^2}{2} \left(\frac{l_a - l_c}{l_a l_c} \right) = \frac{\hbar^2}{2l_a} \left((J' + 1)(J' + 2) \right) + \frac{\hbar^2 K''^2}{2} \left(\frac{l_a - l_c}{l_a l_c} \right)$$

$$= \frac{\hbar^2}{2l_a} (J'^2 + 3J' + 2) + \frac{\hbar^2 K''^2}{2} \left(\frac{l_a - l_c}{l_a l_c} \right)$$

$$E(J = J' + 1, K'') - E(J = J', K') = \Delta E(\Delta J = 1, \Delta K)$$

$$E(J', K') = \frac{\hbar^2}{2l_a} (J'(J' + 1)) + \frac{\hbar^2 K'^2}{2} \left(\frac{l_a - l_c}{l_a l_c} \right) = \frac{\hbar^2}{2l_a} (J'^2 + J') + \frac{\hbar^2 K'^2}{2} \left(\frac{l_a - l_c}{l_a l_c} \right)$$

$$\Delta E_{rot}(\Delta J = 1, \Delta K) = \frac{\hbar^2}{2l_a} (J'^2 + 3J' + 2) + \frac{\hbar^2 K''^2}{2} \left(\frac{l_a - l_c}{l_a l_c} \right) - \frac{\hbar^2}{2l_a} (J'^2 + J') - \frac{\hbar^2 K'^2}{2} \left(\frac{l_a - l_c}{l_a l_c} \right)$$

$$= \frac{\hbar^2}{2l_a} (J'^2 + 3J' + 2 - J'^2 - J') + \frac{\hbar^2}{2} \left(\frac{l_a - l_c}{l_a l_c} \right) (K''^2 - K'^2)$$

$$\Delta E_{rot}(\Delta J = 1, \Delta K) = \frac{\hbar^2}{l_a} (J' + 1) + \frac{\hbar^2}{2} \left(\frac{l_a - l_c}{l_a l_c} \right) (K''^2 - K'^2)$$

$$\Delta E_{rot}(\Delta J = 0, \Delta K) = \frac{\hbar^2}{2} \left(\frac{l_a - l_c}{l_a l_c} \right) (K''^2 - K'^2)$$

$$\Delta E_{rot}(\Delta J = -1, \Delta K) = E(J = J' - 1, K'') - E(J = J', K')$$

$$E(J = J' - 1, K'') = \frac{\hbar^2}{2l_a} \left((J' - 1)(J' - 1 + 1) \right) + \frac{\hbar^2 K''^2}{2} \left(\frac{l_a - l_c}{l_a l_c} \right) = \frac{\hbar^2}{2l_a} \left((J' - 1)(J') \right) + \frac{\hbar^2 K''^2}{2} \left(\frac{l_a - l_c}{l_a l_c} \right) = \frac{\hbar^2}{2l_a} (J'^2 - J') + \frac{\hbar^2 K''^2}{2} \left(\frac{l_a - l_c}{l_a l_c} \right)$$

$$E(J', K') = \frac{\hbar^2}{2l_a} (J'(J' + 1)) + \frac{\hbar^2 K'^2}{2} \left(\frac{l_a - l_c}{l_a l_c} \right) = \frac{\hbar^2}{2l_a} (J'^2 + J') + \frac{\hbar^2 K'^2}{2} \left(\frac{l_a - l_c}{l_a l_c} \right)$$

$$\Delta E_{rot}(\Delta J = -1, \Delta K) = \frac{\hbar^2}{2l_a} (J'^2 - J') + \frac{\hbar^2 K''^2}{2} \left(\frac{l_a - l_c}{l_a l_c} \right) - \frac{\hbar^2}{2l_a} (J'^2 + J') - \frac{\hbar^2 K'^2}{2} \left(\frac{l_a - l_c}{l_a l_c} \right)$$

$$= \frac{\hbar^2}{2l_a} (J'^2 - J' - J'^2 - J') + \frac{\hbar^2}{2} \left(\frac{l_a - l_c}{l_a l_c} \right) (K''^2 - K'^2)$$

$$= \frac{\hbar^2}{2l_a} (-2J') + \frac{\hbar^2}{2} \left(\frac{l_a - l_c}{l_a l_c} \right) (K''^2 - K'^2)$$

$$= \frac{\hbar^2}{l_a} (J') + \frac{\hbar^2}{2} \left(\frac{l_a - l_c}{l_a l_c} \right) (K''^2 - K'^2)$$

$$\begin{bmatrix} 2 & 6 & 10 & 14 & 18 \\ 2 & 6 & 10 & 14 & 18 \\ 1 & 3 & 5 & 7 & 9 \\ 2 & 6 & 10 & 14 & 18 \\ 2 & 6 & 10 & 14 & 18 \end{bmatrix}$$