On Compositional safety verification with Max-SMT

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Overview

- Introduction
- 2 Program graphs
- Algorithm overview
- 4 Example execution
- Conclusion

Terms

Safety verification

Prove that an assertion is always true at a location

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Safety verification where the whole program is analyzed in one step

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Non-compositional safety verification

Safety verification where the whole program is analyzed in one step

Compositional safety verification

Safety verification where program parts are analyzed semi-independently and composed

Motivation

Scalability ← Loss in precision

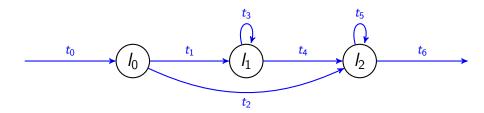
$$\mathcal{L} = \{\ell_0, \ell_1, \ell_2\}$$



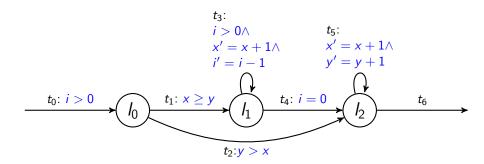


$$I_2$$

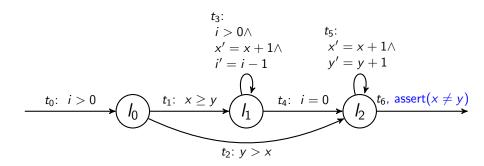
$$\mathcal{L} = \{\ell_0, \ell_1, \ell_2\}$$
 , $\mathcal{T} = \{t_i \mid i \in \{1, \dots, 6\}\}$



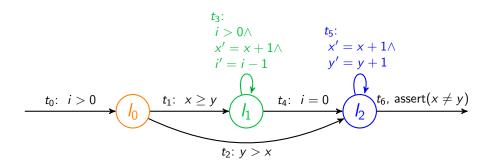
$$\mathcal{L}=\{\ell_0,\ell_1,\ell_2\}$$
 , $\mathcal{T}=\{t_i\mid i\in\{1,\dots,6\}\}$, $\mathcal{V}=\{x,y,i\},~\mathcal{V}'=\{x',y',i'\}$



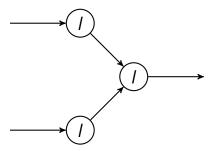
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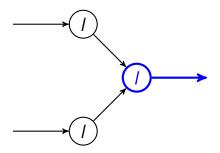
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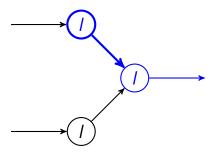
Idea



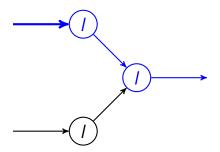
Idea



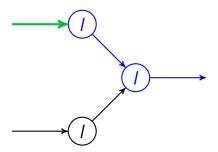
Idea



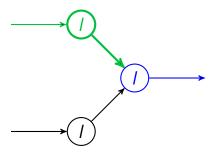
Idea



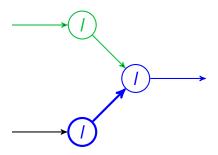
Idea



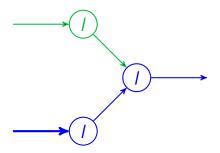
Idea



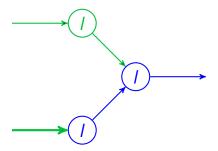
Idea



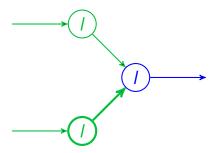
Idea



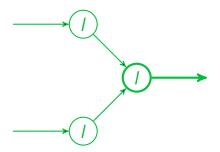
Idea



Idea



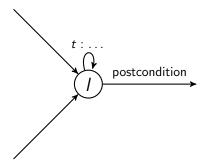
Idea



CondSafe

Idea

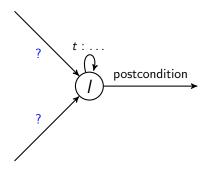
Find a precondition for a component such that all runs satisfying the precondition always imply the postcondition



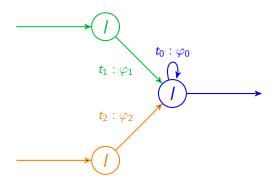
CondSafe

Idea

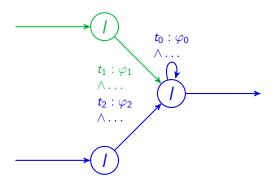
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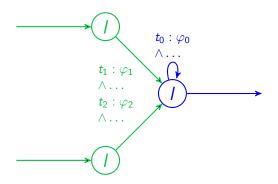
Idea



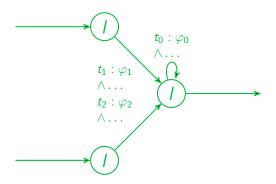
Idea



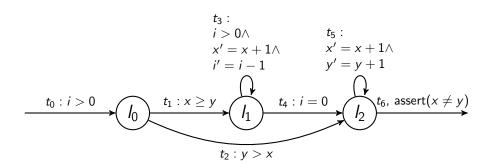
Idea

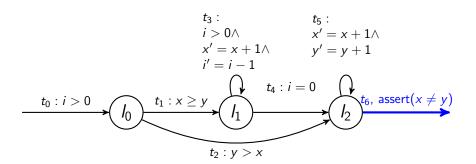


Idea



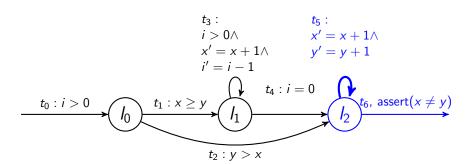
Example program





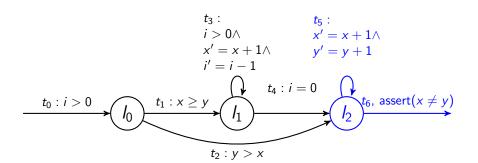
Task

Prove that the program is safe for $x \neq y$ at t_6

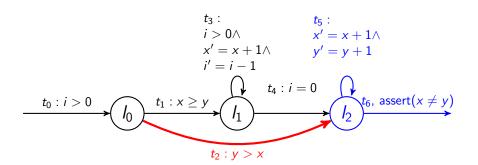


CheckSafe on $\{\ell_2\}$ for $x \neq y$

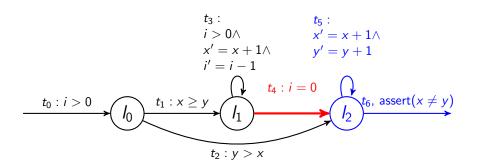
 t_6 does not already imply $x \neq y$ t_6 is not an initial transition Call CondSafe



$$I_{\ell_2,1}(\{x,y,i\}) \equiv i_{\ell_2,1} + i_{\ell_2,1,x} * \mathbf{x} + i_{\ell_2,1,y} * \mathbf{y} + i_{\ell_2,1,i} * \mathbf{i} \leq 0$$

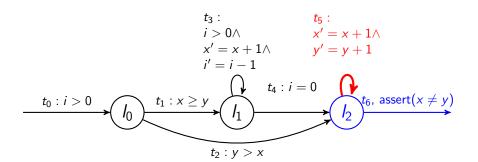


$$\mathbb{I}_{t_2,1,1} \equiv y > x \wedge i' = i \wedge x' = x \wedge y' = y \Rightarrow I'_{\ell_2,1,1}$$



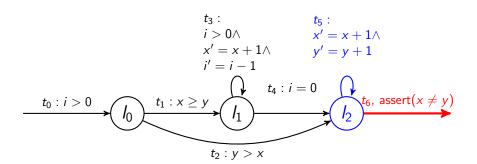
$$\mathbb{I}_{t_4,1,1} \equiv i = 0 \wedge i' = i \wedge x' = x \wedge y' = y \Rightarrow I'_{\ell_2,1,1}$$



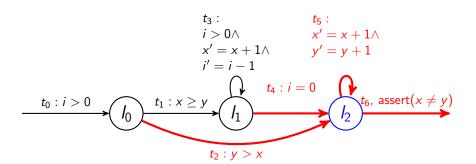


$$\mathbb{C}_{t_5,1} \equiv \mathit{I}_{\ell_2,1} \land \, x' = x + 1 \land y' = y + 1 \land \mathit{i}' = \mathit{i} \, \Rightarrow \mathit{I}'_{\ell_2,1}$$



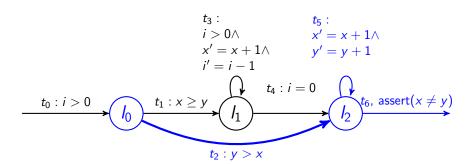


$$\mathbb{S}_1 \equiv \textit{I}_{\ell_2,1} \land \textit{i'} = \textit{i} \land \textit{x'} = \textit{x} \land \textit{y'} = \textit{y} \Rightarrow \textit{x'} \neq \textit{y'}$$



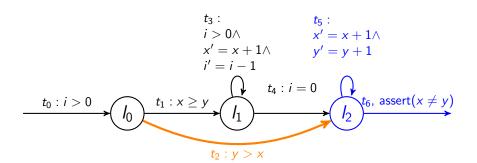
Max-SMT on $\{\ell_2\}$ for $x \neq y$

$$\begin{split} \mathbb{F}_1 &\equiv \mathbb{C}_{t_5,1} \wedge \mathbb{S}_1 \wedge (\mathbb{I}_{t_2,1,1} \vee \neg \rho_{t_2}) \wedge (\mathbb{I}_{t_4,1,1} \vee \neg \rho_{t_4}) \wedge [\rho_{t_2},1] \wedge [\rho_{t_4},1] \\ \text{Assume } x > y \text{ does satisfy } \mathbb{F}_1 \end{split}$$



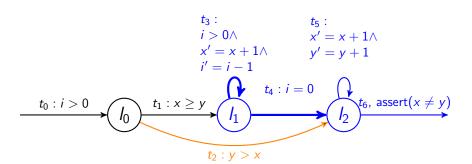
CheckSafe on $\{\ell_0\}$ for x > y

 t_2 does not already imply x > y t_2 is not an initial transition Call CondSafe



CheckSafe on $\{\ell_0\}$ for x > y

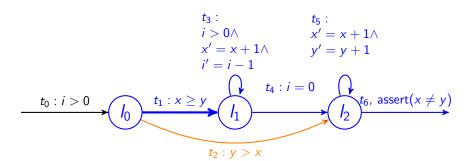
No precondition, since y > x contradicts x > yPath is maybe safe, but not for x > y



CheckSafe on $\{\ell_1\}$ for x > y

 t_4 does not already imply x > y t_4 is not an initial transition Call CondSafe, get $i > 0 \land x \ge y$ as precondition



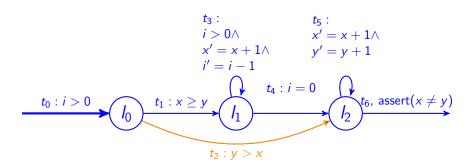


CheckSafe on $\{\ell_0\}$ for i > 0

 t_1 does not already imply i > 0 t_1 is not an initial transition Call CondSafe, get i > 0 as precondition

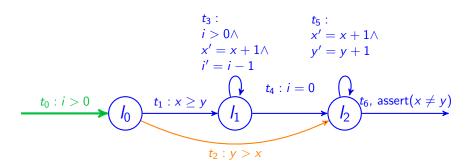
Fabian Böller with David Korzeniewski (i2)

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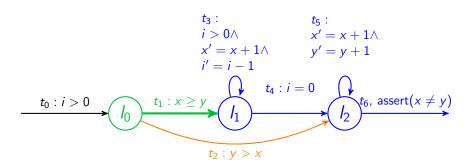
CheckSafe on initial SCC for i > 0

 t_0 does already imply i > 0



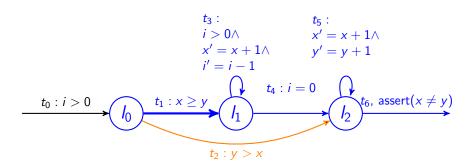
CheckSafe on initial SCC for i > 0

Path is safe for i > 0



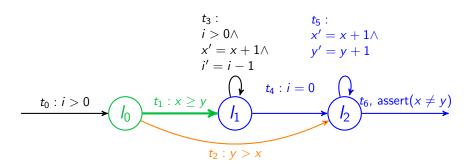
CheckSafe on $\{\ell_0\}$ for i > 0

Path is safe for i > 0



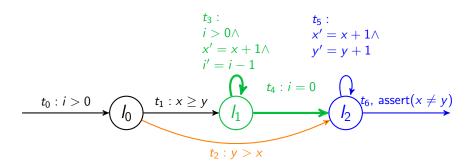
CheckSafe on $\{\ell_0\}$ for $x \geq y$

 t_1 does already imply $x \ge y$



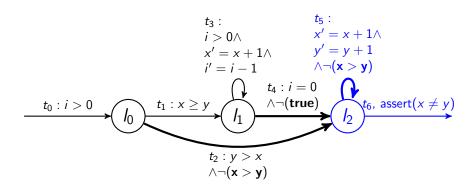
CheckSafe on $\{\ell_0\}$ for $x \geq y$

Path is safe for $x \ge y$



CheckSafe on $\{\ell_1\}$ for x > y

Path is safe for x > y

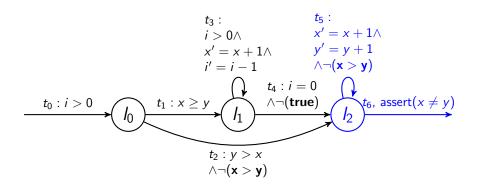


Narrow on $\{\ell_2\}$

Add $\neg(x > y)$ to t_2

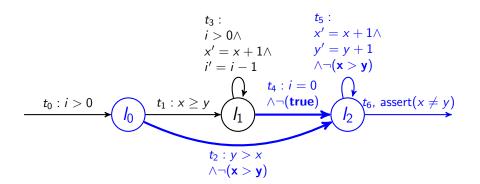
Add $\neg(x > y)$ to t_5

Remove t₄



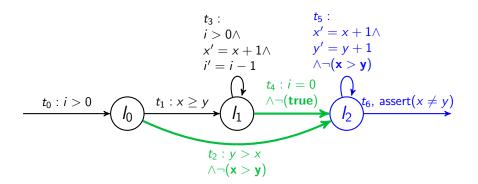
CheckSafe on $\{\ell_2\}$ for $x \neq y$

Call CondSafe, get y > x instead of x > y as precondition



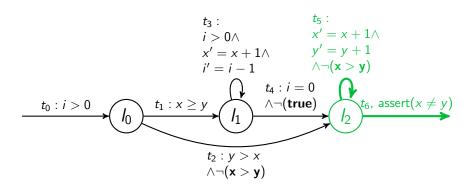
CheckSafe on $\{\ell_0\}$ for y > x

 t_2 does already imply y > x t_4 does already imply y > x



CheckSafe on $\{\ell_0\}$ for y > x

Paths are safe for y > x



CheckSafe on $\{\ell_0\}$ for y > x

Program is safe for $x \neq y$

Conclusion

We saw:

- The exploration of multiple entry SCCs by CheckSafe
- The effect of narrowing if a path to the SCC is proved safe and another could not be proved safe
- The behavior of CheckSafe if a precondition with multiple conjunctions is found

We didn't saw:

 SCCs with multiple transitions (effects consecution conditions in Max-SMT and entry locations in Narrowing)