## On Compositional safety verification with Max-SMT

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### Overview

- Introduction
- 2 Program graphs
- Algorithm overview
- 4 Example execution
- Conclusion

#### **Terms**

## Safety verification

Prove that an assertion is always true at a location

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### Non-compositional safety verification

Safety verification where the whole program is analyzed in one step

### Compositional safety verification

Safety verification where program parts are analyzed semi-independently and composed

### Motivation

Scalability ← Loss in precision

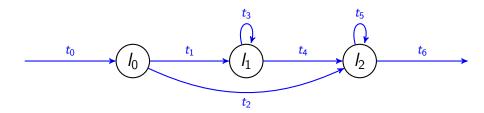
$$\mathcal{L} = \{\ell_0, \ell_1, \ell_2\}$$



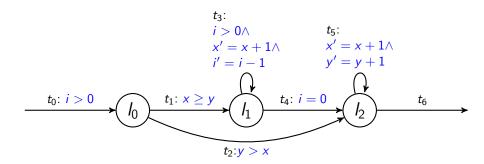


$$I_2$$

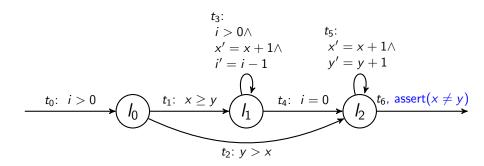
$$\mathcal{L} = \{\ell_0, \ell_1, \ell_2\}$$
 ,  $\mathcal{T} = \{t_i \mid i \in \{1, \dots, 6\}\}$ 



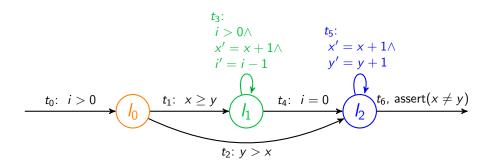
$$\mathcal{L}=\{\ell_0,\ell_1,\ell_2\}$$
 ,  $\mathcal{T}=\{t_i\mid i\in\{1,\dots,6\}\}$  ,  $\mathcal{V}=\{x,y,i\},~\mathcal{V}'=\{x',y',i'\}$ 



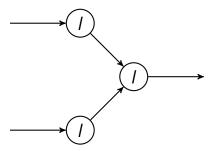
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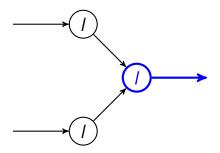
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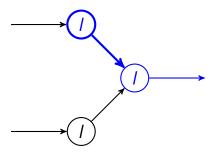
#### Idea



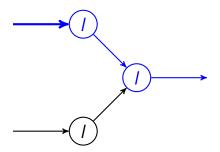
#### Idea



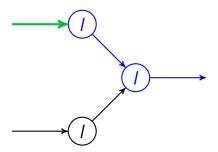
### Idea



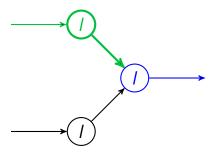
#### Idea



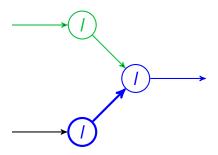
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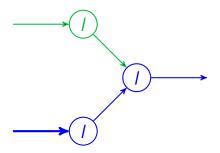
### Idea



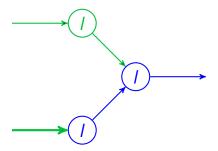
### Idea



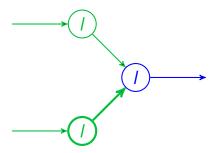
#### Idea



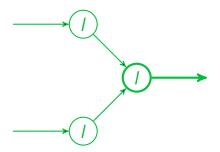
#### Idea



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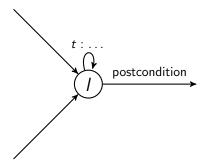
#### Idea



### CondSafe

#### Idea

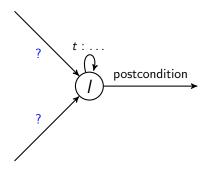
Find a precondition for a component such that all runs satisfying the precondition always imply the postcondition



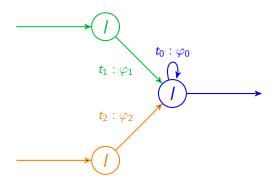
### CondSafe

#### Idea

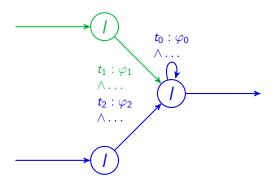
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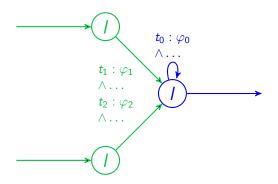
#### Idea



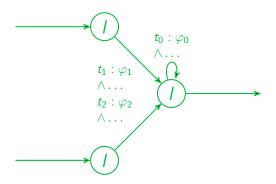
#### Idea



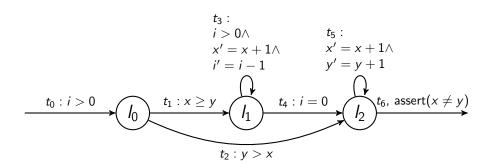
#### Idea

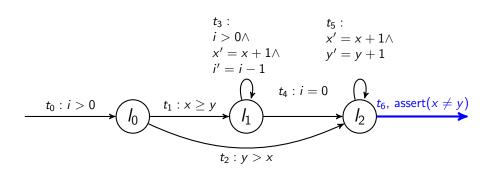


#### Idea



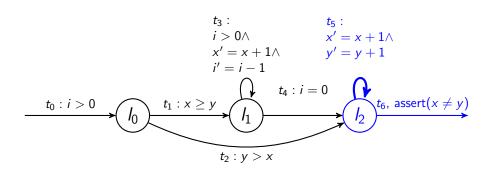
## Example program





#### Task

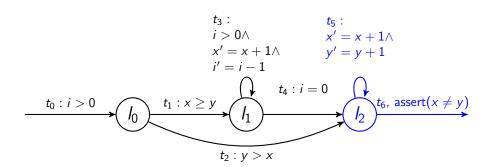
Prove that the program is safe for  $x \neq y$  at  $t_6$ 



## CheckSafe on $\{\ell_2\}$ for $x \neq y$

 $t_6$  does not already imply  $x \neq y$   $t_6$  is not an initial transition Call CondSafe

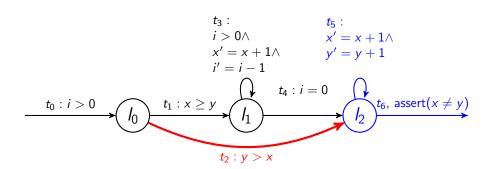
40 > 40 > 42 > 42 > 2 90



## Max-SMT on $\{\ell_2\}$ for $x \neq y$

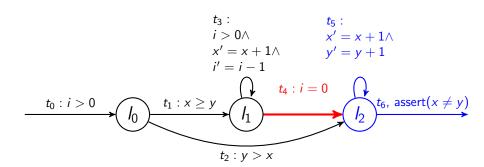
$$I_{\ell_2,1}(\{x,y,i\}) \equiv i_{\ell_2,1} + i_{\ell_2,1,x} * \mathsf{x} + i_{\ell_2,1,y} * \mathsf{y} + i_{\ell_2,1,i} * \mathsf{i} \leq 0$$

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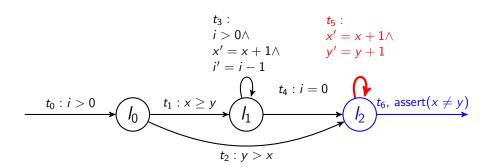


$$\mathbb{I}_{t_2,1,1} \equiv y > x \wedge i' = i \wedge x' = x \wedge y' = y \Rightarrow l'_{\ell_2,1,1}$$



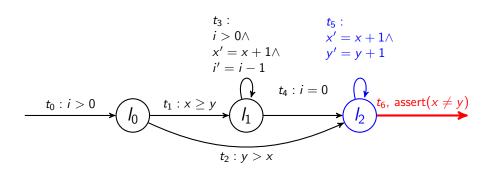


$$\mathbb{I}_{t_4,1,1} \equiv i = 0 \wedge i' = i \wedge x' = x \wedge y' = y \Rightarrow I'_{\ell_2,1,1}$$



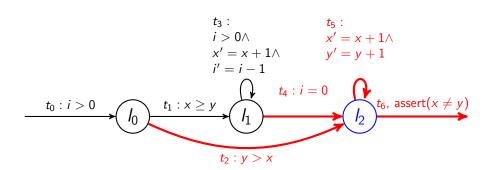
$$\mathbb{C}_{t_5,1} \equiv \mathit{I}_{\ell_2,1} \land x' = x + 1 \land y' = y + 1 \land \mathit{i}' = \mathit{i} \Rightarrow \mathit{I}'_{\ell_2,1}$$





$$\mathbb{S}_1 \equiv I_{\ell_2,1} \wedge i' = i \wedge x' = x \wedge y' = y \Rightarrow x' \neq y'$$

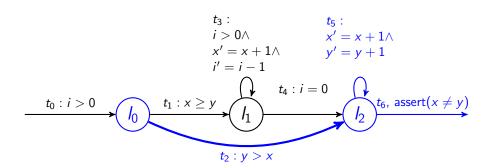




## Max-SMT on $\{\ell_2\}$ for $x \neq y$

 $\mathbb{F}_1 \equiv \mathbb{C}_{t_5,1} \wedge \mathbb{S}_1 \wedge (\mathbb{I}_{t_2,1,1} \vee \neg p_{t_2}) \wedge (\mathbb{I}_{t_4,1,1} \vee \neg p_{t_4}) \wedge [p_{t_2},1] \wedge [p_{t_4},1]$  Assume x > y does satisfy  $\mathbb{F}_1$ 

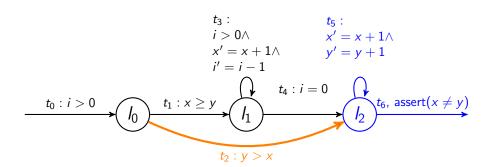
40 > 40 > 42 > 42 > 2 90



# CheckSafe on $\{\ell_0\}$ for x > y

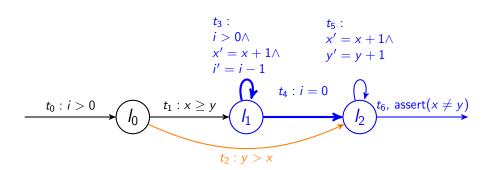
 $t_2$  does not already imply x > y $t_2$  is not an initial transition

Call CondSafe



## CheckSafe on $\{\ell_0\}$ for x > y

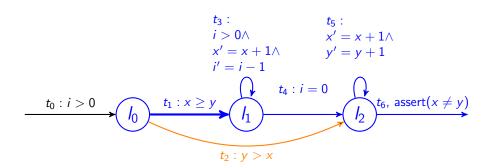
No precondition, since y > x contradicts x > yPath is maybe safe, but not for x > y



# CheckSafe on $\{\ell_1\}$ for x>y

 $t_4$  does not already imply x > y $t_4$  is not an initial transition

Call CondSafe, get  $i > 0 \land x \ge y$  as precondition

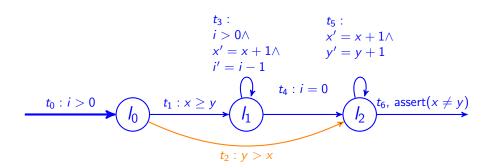


# CheckSafe on $\{\ell_0\}$ for i > 0

 $t_1$  does not already imply i > 0

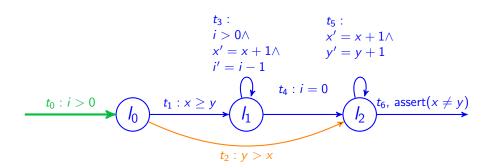
 $t_1$  is not an initial transition

Call CondSafe, get i > 0 as precondition



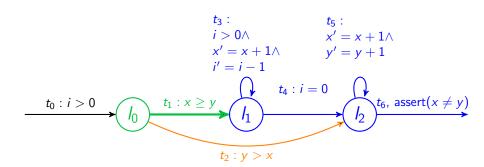
#### CheckSafe on initial SCC for i > 0

 $t_0$  does already imply i > 0



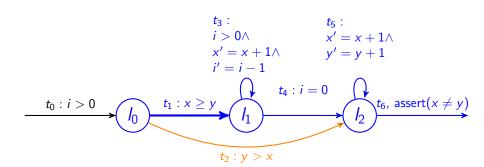
#### CheckSafe on initial SCC for i > 0

Path is safe for i > 0



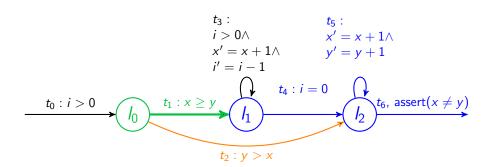
#### CheckSafe on $\{\ell_0\}$ for i > 0

Path is safe for i > 0



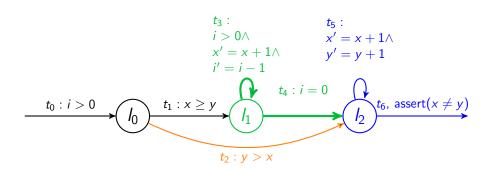
## CheckSafe on $\{\ell_0\}$ for $x \ge y$

 $t_1$  does already imply  $x \ge y$ 



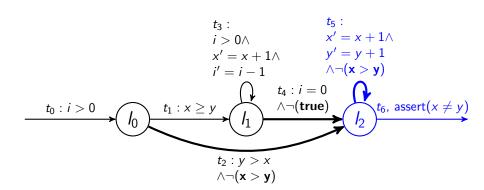
### CheckSafe on $\{\ell_0\}$ for $x \ge y$

Path is safe for  $x \ge y$ 



## CheckSafe on $\{\ell_1\}$ for x > y

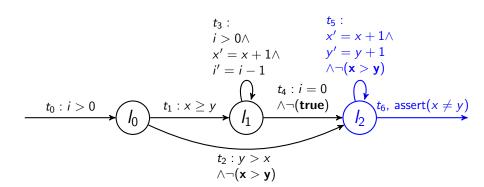
Path is safe for x > y



# Narrow on $\{\ell_2\}$

Add  $\neg(x > y)$  to  $t_2$ 

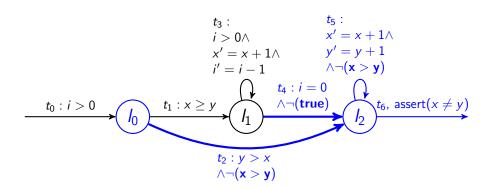
Add  $\neg(x > y)$  to  $t_5$ 



# CheckSafe on $\{\ell_2\}$ for $x \neq y$

Call CondSafe, get y > x instead of x > y as precondition

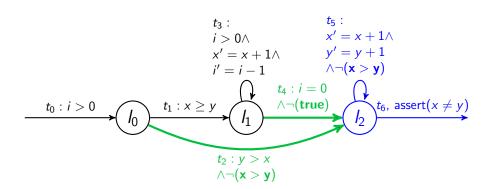
101401212121212121



### CheckSafe on $\{\ell_0\}$ for y > x

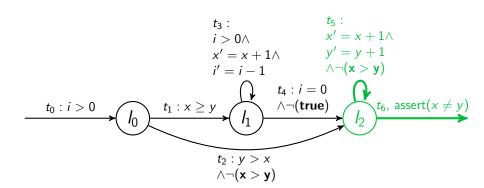
 $t_2$  does already imply y > x  $t_4$  does already imply y > x

4 D F 4 D F 4 D F 9 0 C



### CheckSafe on $\{\ell_0\}$ for y > x

Paths are safe for y > x



### CheckSafe on $\{\ell_0\}$ for y > x

Program is safe for  $x \neq y$ 

#### Conclusion

#### We saw:

- The exploration of multiple entry SCCs by CheckSafe
- The effect of narrowing if a path to the SCC is proved safe and another could not be proved safe
- The behavior of CheckSafe if a precondition with multiple conjunctions is found

#### We didn't saw:

 SCCs with multiple transitions (effects consecution conditions in Max-SMT and entry locations in Narrowing)