Michael Goforth CAAM 550 HW 4 9/22/2021

Problem 1 part a

$$\boldsymbol{G^TG} = \begin{bmatrix} g_1^T \\ g_2^T \\ \vdots \\ g_m^T \end{bmatrix} \begin{bmatrix} g_1 & g_2 & \dots & g_m \end{bmatrix}$$

where  $g_1, g_2, \ldots, g_m$  are the columns of  $\boldsymbol{G}$ . Then

$$\boldsymbol{G^TG} = \begin{bmatrix} g_1^T g_1 & g_1^T g_2 & \dots & g_1^T g_m \\ g_2^T g_1 & g_2^T g_2 & \dots & g_2^T g_m \\ \dots & \dots & \dots & \dots \\ g_m^T g_1 & g_m^T g_2 & \dots & g_m^T g_m \end{bmatrix}$$

and for a given element  $q_a, b \in \mathbf{G}^T \mathbf{G}$ , for any  $a, b \neq j, k$ ,

$$q_{a,b} = \begin{cases} 1, & a = b \\ 0, & a \neq b \end{cases}$$

Also for any element  $a \neq j, k, q_{a,j} = 0, q_{a,k} = 0$  and any element  $b \neq j, k, q_{j,b} = 0, q_{k,b} = 0$ . Finally,

$$q_{i,j} = q_{k,k} = \cos^2(\theta) + \sin^2(\theta) = 1$$

$$q_{j,k} = q_{k,j} = cos(\theta)sin(\theta) - cos(\theta)sin(\theta) = 0$$

Combining all of this together gives

$$q_{a,b} = \left\{ egin{array}{ll} 1, & a=b \ 0, & a 
eq b \end{array} 
ight. = {m I}$$

 $G^TG = I$  so a Givens rotation is orthogonal.

#### part b

Consider a matrix  $A \in \mathbb{R}^{2x^2}$  where

$$\boldsymbol{A} = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$$

and Givens rotation matrix

$$\boldsymbol{G} = \begin{bmatrix} \cos(\theta) & \sin(\theta) \\ -\sin(\theta) & \cos(\theta) \end{bmatrix}$$

If we want to use a Givens rotation to make A upper triangular, then we want

$$(GA)_{1,2} = -a \sin(\theta) + c \cos(\theta) = 0$$

$$a \sin(\theta) = c \cos(\theta)$$
  
 $\theta = \arctan(c/a)$ 

In a similar way, we can use Givens rotations to zero out all the lower elements of a generic matrix  $A \in \mathbb{R}^{nxn}$ . For every element in  $a_i$  below the diagonal of A, a matrix  $G_j$  can be formed such that  $A_j = G_j A$  and  $(A_j)_i = 0$ . Repeat this for every subdiagonal element and then combine the G matrices such that

$$G = \prod_{i=1}^{n} G_i$$

where each  $G_i$  is a Givens rotation that zeros out one of the n subdiagonal elements of A. Then

$$GA = (G_n \dots G_2 G_1)A = R$$

which is upper triangular. Also, as shown in part a, Givens rotations are orthogonal so

$$G^TGA = G^TR$$

and finally

$$A = G^T R = QR$$

One Givens rotation will be needed for each subdiagonal element. When  $n \leq m$ , this will be the (n-1)th triangular number, which can be found as  $\frac{1}{2}(n^2-n)$ . When m > n, we will have require the same number as in the previous case plus an additional (m-n) rows of length n. Combining these yields the number of Givens rotations, i, as

$$i = \left\{ \begin{array}{cc} \frac{n}{2}(n-1), & n \leq m \\ \frac{n}{2}(n-1) + (m-n)n, & m > n \end{array} \right.$$

As shown above,

$$A = G^T R = QR$$

so

$$Q = G^T$$

## part c

See Jupyter notebook for implementation and output.

### Problem 2

x + (y + z) = (x + y) + z does not hold in floating point arithmetic due to the rounding that takes place at each step. For example, if

 $\bar{x} = 5.112$ 

 $\bar{y} = 5.112$ 

 $\bar{z} = 5.113$ 

$$fl(fl(\bar{x} + \bar{y}) + \bar{z}) = fl(fl(10.224) + 5.113) = fl(1.022 * 10^{1} + 5.113) = fl(15.333) = 1.533 * 10^{1} + 10^{1$$

# Problem 3 part i

$$\sigma = \left[\frac{1}{n-1} \sum_{i=1}^{n} (x_i - \bar{x})^2\right]^{1/2}$$

$$= \left[\frac{1}{n-1} \sum_{i=1}^{n} (x_i^2 - 2\bar{x}x_i + \bar{x}^2)\right]^{1/2}$$

$$= \left[\frac{1}{n-1} \left(\sum_{i=1}^{n} x_i^2 - \sum_{i=1}^{n} 2\bar{x}x_i + \sum_{i=1}^{n} \bar{x}^2\right)\right]^{1/2}$$

$$= \left[\frac{1}{n-1} \left(\sum_{i=1}^{n} x_i^2 - 2\bar{x}\frac{n}{n} \sum_{i=1}^{n} x_i + n\bar{x}^2\right)\right]^{1/2}$$

$$= \left[\frac{1}{n-1} \left(\sum_{i=1}^{n} x_i^2 - 2\bar{x}n\bar{x} + n\bar{x}^2\right)\right]^{1/2}$$

$$= \left[\frac{1}{n-1} \left(\sum_{i=1}^{n} x_i^2 - n\bar{x}^2\right)\right]^{1/2}$$

part ii See Jupyter notebook for code and results.

# Problem 4 part i

$$A1 = \text{fl}(4 * \text{fl}(\text{fl}(\pi) * \text{fl}(\text{fl}(r) * \text{fl}(r))))$$

$$= \text{fl}(4 * \text{fl}(\text{fl}(3.142) * \text{fl}(\text{fl}(6370) * \text{fl}(6370))))$$

$$= \text{fl}(4 * \text{fl}(3.142 * \text{fl}(6.370 * 10^3 * 6.370 * 10^3)))$$

$$= \text{fl}(4 * \text{fl}(3.142 * \text{fl}(40, 576, 900)))$$

$$= \text{fl}(4 * \text{fl}(3.142 * 4.058 * 10^7))$$

$$= \text{fl}(4 * \text{fl}(127, 502, 360))$$

$$= \text{fl}(4 * 1.275 * 10^8)$$

$$= \text{fl}(510, 000, 000)$$

$$= 5.100 * 10^8$$

### part ii

$$\begin{split} A2 &= \text{fl}(4*\text{fl}(\text{fl}(\pi)*\text{fl}(\text{fl}(r)*\text{fl}(r)))) \\ &= \text{fl}(4*\text{fl}(\text{fl}(3.142)*\text{fl}(\text{fl}(6371)*\text{fl}(6371)))) \\ &= \text{fl}(4*\text{fl}(3.142*\text{fl}(6.371*10^3*6.371*10^3))) \\ &= \text{fl}(4*\text{fl}(3.142*\text{fl}(40,589,641))) \\ &= \text{fl}(4*\text{fl}(3.142*4.059*10^7)) \\ &= \text{fl}(4*\text{fl}(127,533,780)) \\ &= \text{fl}(4*\text{fl}(127,533,780)) \\ &= \text{fl}(4*1.275*10^8) \\ &= \text{fl}(510,000,000) \\ &= 5.100*10^8 \end{split}$$

#### part iii

$$\begin{split} \frac{d}{dr}A &= \text{fl}(8\text{fl}(\pi r)) \\ &= \text{fl}(8\text{fl}(3.142*6.370*10^3)) \\ &= \text{fl}(8\text{fl}(20,014.54)) \\ &= \text{fl}(8*2.001*10^4)) \\ &= \text{fl}(160,080)) \\ &= 1.601*10^5 \end{split}$$

## part iv

Part iii is more accurate.

### part v

Part iii is more accurate because it is computing the difference directly. Part i and ii are the same in floating point arithmetic because the magnitude of the areas is much greater than the difference between them, so when the result of part i is subtracted from the result of part ii, catastrophic cancellation occurs. If floating point arithmetic with a longer mantissa is used, the difference between parts i and ii will be more accurate.