# hw3 code

### September 17, 2021

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```
[3]: import math import numpy as np import matplotlib.pyplot as plt
```

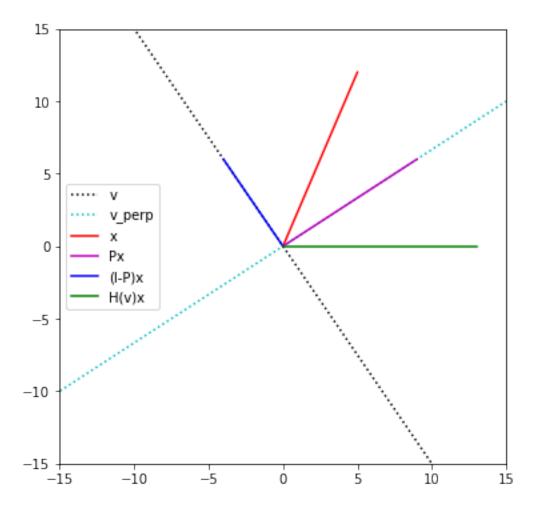
#### 0.0.1 Problem 2c

```
[36]: fig, ax = plt.subplots()
      fig.set_size_inches(6, 6)
      # plot span(v)
      v = np.array([-8, 12])
      vx = [v[0] * i for i in np.linspace(-10, 10)]
      vy = [v[1] * i for i in np.linspace(-10, 10)]
      plt.plot(vx, vy, 'k:', label='v')
      # plot span(v_perp)
      v_p = np.array([12, 8])
      vx_p = [v_p[0] * i for i in np.linspace(-10, 10)]
      vy_p = [v_p[1] * i for i in np.linspace(-10, 10)]
      plt.plot(vx_p, vy_p, 'c:', label='v_perp')
      # plot x vector
      x = np.array([5, 12])
      plt.plot([0, x[0]], [0, x[1]], 'r', label='x')
      # plot Px
      P = np.array([[9/13, 6/13], [6/13, 4/13]])
      px = P @ x
      plt.plot([0, px[0]], [0, px[1]], 'm', label='Px')
      # plot (I - P)x
      IPx = (np.identity(2) - P) @ x
      plt.plot([0, IPx[0]], [0, IPx[1]], 'b', label='(I-P)x')
      # plot H(v)x
      H = np.array([[5/13, 12/13], [12/13, -5/13]])
```

```
Hx = H @ x
plt.plot([0, Hx[0]], [0, Hx[1]], 'g', label='H(v)x')

plt.xlim([-15, 15])
plt.ylim([-15, 15])
plt.legend()
```

[36]: <matplotlib.legend.Legend at 0x1c63cca4b20>



## 0.0.2 Problem 3b

```
[1]: A = np.array([[1, 2, 3], [-1, 2, 1], [0, 1, 1]])
Q, R = np.linalg.qr(A)
print("Q = " + str(Q))
print("R = " + str(R))
```

```
Q = [[-0.70710678 -0.66666667 -0.23570226][ 0.70710678 -0.66666667 -0.23570226]
```

```
[-0. -0.33333333 0.94280904]]

R = [[-1.41421356e+00 6.66133815e-16 -1.41421356e+00]

[ 0.00000000e+00 -3.00000000e+00 -3.00000000e+00]

[ 0.00000000e+00 0.00000000e+00 -1.14863726e-16]]
```

#### 0.0.3 Problem 4

```
[2]: def multiQR(A, j=10):
         '''Function as described in problem 4 of HW3.
         Parameters
         A : np.array
            matrix to be decomposed
         j : value (optional, default = 10)
             number of iterations of QR decomposition
         Returns
         _____
         A_j: np.array
               resulting matrix. A_j = (Q_0 Q_1 \dots Q_{j-1})^T A_0 (Q_0 Q_1 \dots Q_{j-1})
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         for i in range(j):
             Q, R = np.linalg.qr(A)
             A = R @ Q
         return A
```

```
[54]: # Matrix trial 1
A = np.array([[3, -5], [-5, 3]])
A10 = multiQR(A, 10)
A11 = multiQR(A, 11)

print('Matrix A:')
print(str(A))
print('Eigenvalues: ' + str(np.linalg.eig(A)[0]))
print('A after 10 iterations: ')
print(str(A10))
print('A after 11 iterations: ')
print(str(A11))
```

Matrix A: [[ 3 -5]

```
[-5 3]]
     Eigenvalues: [8. -2.]
     A after 10 iterations:
     [[ 8.00000000e+00 -9.53674316e-06]
      [-9.53674316e-06 -2.00000000e+00]]
     A after 11 iterations:
     [[ 8.00000000e+00 -2.38418579e-06]
      [-2.38418579e-06 -2.00000000e+00]]
[72]: # Matrix trial 2
      B = np.array([[2, -5], [1, 3]])
      B10 = multiQR(B, 10000)
      B11 = multiQR(B, 10001)
      print('Matrix B:')
      print(str(B))
      print('Eigenvalues: ' + str(np.linalg.eig(B)[0]))
      print('B after 100 iterations: ')
      print(str(B10))
      print('B after 101 iterations: ')
      print(str(B11))
     Matrix B:
     [[ 2 -5]
      [ 1 3]]
     Eigenvalues: [2.5+2.17944947j 2.5-2.17944947j]
     B after 100 iterations:
     [[ 0.44712643 -2.81102877]
      [ 3.18897123 4.55287357]]
     B after 101 iterations:
     [[ 4.52568494  2.61711554]
      [-3.38288446 0.47431506]]
[59]: # Matrix trial 3
      C = np.array([[3, 2], [7, 3]])
      C10 = multiQR(C, 10)
      C11 = multiQR(C, 11)
      print('Matrix C:')
      print(str(C))
      print('Eigenvalues: ' + str(np.linalg.eig(C)[0]))
      print('A after 10 iterations: ')
      print(str(C10))
      print('A after 11 iterations: ')
      print(str(C11))
     Matrix C:
     [[3 2]
      [7 3]]
```

Eigenvalues: [ 6.74165739 -0.74165739]

A after 10 iterations:

[[ 6.74165739e+00 -5.00000000e+00]

[ 1.61551876e-09 -7.41657388e-01]]

A after 11 iterations:

[[ 6.74165739e+00 5.00000000e+00]

[ 1.77725054e-10 -7.41657387e-01]]