

# Stationary and weakly stationary time series

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# Outline

- 1 Stationary Time series
  - The statistical approach
  - Classical steps of statistical inference
  - Random processes in a nutshell
  - Examples
  - Stationary time series
- 2 Weakly stationary time series
  - $L^2$  processes
  - Weak stationarity
  - Spectral measure
  - Empirical estimation

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# Basic (important) definitions

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## Definition : Statistic

A **statistic** is any value which can be computed from the data.

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  - ▶ In the case of **multivariate time series**, each variable usually corresponds to a column (so each row corresponds to a date).

## Example : US GNP data set

```
# Title:           Gross National Product
# Source:          U.S. Department of Commerce
# Frequency:       Quarterly
```

```
DATE,VALUE
```

```
1947-01-01,238.1
```

```
1947-04-01,241.5
```

```
1947-07-01,245.6
```

```
1947-10-01,255.6
```

```
1948-01-01,261.7
```

```
1948-04-01,268.7
```

```
1948-07-01,275.3
```

```
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- ▶ Or applying a well chosen filter  $F_\psi$ , such that  $F_\psi(D) = 0$  and thus

$$F_\psi(X) = F_\psi(Y) .$$



# R code example: Johnson and Johnson trend adjustment

[trend-adjustment.html](#)

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### Example

$Y_1, \dots, Y_n$  is the sample of a Gaussian ARMA( $p, q$ ) model with (unknown) **parameter**  $\vartheta = (\theta_1, \dots, \theta_q, \phi_1, \dots, \phi_p, \sigma^2)$ .

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$Y_1, \dots, Y_n$  is the sample of a centered stationary Gaussian process with (unknown) autocovariance  $\gamma$  (or spectral density  $f$ ).

## Third step : estimate parameters, test hypotheses

Once a model is fixed for  $Y_1, \dots, Y_n$ , it can be used to

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→ Define a **statistical test**, say

$$\delta = \begin{cases} 1 & \text{if } T_n > t_n, \\ 0 & \text{otherwise,} \end{cases}$$

where  $T_n$  is a **statistic** based on the sample  $Y_1, \dots, Y_n$  and  $t_n$  is a **threshold**.

# Stationary and ergodic models

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  - ▶ A Markov chain on a finite state space can be made stationary by choosing the initial state adequately. If it is **irreducible**, then it is ergodic.

# R code example: dependent data

[non-iid-data.html](#)

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# Random processes

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  - ▶ A **collection of random variables**  $(X_t)_{t \in T}$  such that each  $X_t$  is defined on  $(\Omega, \mathcal{F}, \mathbb{P})$  and valued in  $(E, \mathcal{E})$ .

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- ▶ A **random path**  $X$  valued in the **trajectory space**  $(E^T, \mathcal{E}^{\otimes T})$  defined on  $(\Omega, \mathcal{F}, \mathbb{P})$ .

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- ▶ A **random path**  $X$  valued in the **trajectory space**  $(E^T, \mathcal{E}^{\otimes T})$  defined on  $(\Omega, \mathcal{F}, \mathbb{P})$ .
- ▶ We can go back and forth from one definition to another
  - ▶ Define  $X : \Omega \rightarrow E^T$  by  $X(\omega) = (X_t(\omega))_{t \in T}$ .
  - ▶ Define for all  $t \in T$ ,  $X_t : \Omega \rightarrow E$  by  $X_t(\omega) = \xi_t(X(\omega))$ , where  $\xi_t : (x_s)_{s \in T} \mapsto x_t$  denotes the **canonical projection** from  $E^T$  to  $E$ .

# Law of $X$

- ▷ Exactly as usual random variables, the random path  $X$  admits a distribution defined by

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- ▷ Alternatively, one can consider **finite-dimensional** distributions: for all finite subset  $I = \{t_1, \dots, t_n\} \subset T$  of indices,
- ▷ denote by  $\Pi_I$  is the canonical projection  $(x_t)_{t \in T} \mapsto (x_t)_{t \in I}$ ,
  - ▷ denote by  $X_I$  the random vector  $(X_t)_{t \in I} = \Pi_I \circ X$ ,
  - ▷ denote by  $\mathbb{P}^{X_I}$  the distribution of  $X_I$ , which is defined by

$$\mathbb{P}^{X_I}(A_{t_1} \times \dots \times A_{t_n}) = \mathbb{P}(X_t \in A_t, t \in I),$$

where  $A_{t_1} \dots A_{t_n}$  are subset of  $E$  (in  $\mathcal{E}$ ).

- ▷ The collection  $(\mathbb{P}^{X_I})_{I \in \mathcal{I}(T)}$  are called the **fidi distributions**.
- ▷  $\mathbb{P}^X$  can be constructed from  $(\mathbb{P}^{X_I})_{I \in \mathcal{I}(T)}$  (Kolmogorov theorem).

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$$\mathbb{P}(X_t \in A_t \text{ for all } t \in I) = \prod_{t \in I} \mathbb{P}(X_t \in A_t) = \prod_{t \in I} \nu_t(A_t) .$$

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- ▶ If  $\nu_t = \nu$  for all  $t \in T$  we say that  $(X_t)_{t \in T}$  is a independent and identically distributed (IID) with marginal  $\nu$ .

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- ▷ Then there exists a process  $(X_t)_{t \in T}$  on a probability space  $(\Omega, \mathcal{F}, \mathbb{P})$  such that, for all  $I \in \mathcal{I}(T)$

$$\mathbb{P}^{X_I} = \mathcal{N}((\mu_t)_{t \in I}, \Gamma_I) ,$$

which is equivalent to have for all  $(x_s)_{s \in I} \in E^I$

$$\mathbb{E} \left[ e^{i \sum_{s \in I} x_s X_s} \right] = \exp \left( i \sum_{s \in I} x_s \mu_s - \frac{1}{2} \sum_{s \in I} \sum_{t \in I} x_s \gamma_{s,t} x_t \right) .$$



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- ▷ We denote  $X \sim \mathcal{N}(\mu, \gamma)$  and say that  $X$  is a Gaussian process with mean  $\mu$  and covariance function  $\gamma$ .

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- Random processes in a nutshell
- Examples
- Stationary time series

## 2 Weakly stationary time series

# Shift and backshift operators

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$$S(x) = (x_{t+1})_{t \in T} \quad \text{for all } x = (x_t)_{t \in T} \in E^T.$$

For all  $\tau \in T$ , we define  $S^\tau$  by

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- ▷ The operator  $S^{-1}$  is called the **backshift operator**, denoted by  $B$ .

# Strict stationarity

## Definition : Strict stationarity

Let  $X = (X_t)_{t \in T}$  be a random process defined on  $(\Omega, \mathcal{F}, \xi)$  with  $T = \mathbb{Z}$  or  $T = \mathbb{N}$ . We say that  $X$  is **stationary (in the strict sense)** if

$$X \stackrel{\text{fidi}}{=} S \circ X ,$$

which is equivalent to

$$\mathbb{P}^X = \mathbb{P}^{S \circ X} .$$

# Examples based on finite distributions

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- ▷ **Gaussian processes** :  $X \sim \mathcal{N}(\mu, \Gamma)$  is stationary if and only if  $\mu_t = \mu_0$  and  $\gamma_{s,t} = \gamma_{s-t,0}$  for all  $s, t \in T$ .

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- ▶ Many stationary and ergodic models can be defined as a **Causal** “Bernoulli” shift:

$$X_t = \phi(\epsilon_t, \epsilon_{t-1}, \epsilon_{t-2}, \dots)$$

for a convenient mapping  $\phi$ .

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# $L^2$ space

We set  $E = \mathbb{C}^d$ . We denote

$$L^2(\Omega, \mathcal{F}, \mathbb{P}) = \left\{ X \text{ } \mathbb{C}^d\text{-valued r.v. such that } \mathbb{E} [|X|^2] < \infty \right\} .$$

$(L^2, \langle, \rangle)$  is a Hilbert space with

$$\langle X, Y \rangle = \mathbb{E} [X^T \overline{Y}] .$$

## Definition : $L^2$ Processes

The process  $\mathbf{X} = (\mathbf{X}_t)_{t \in T}$  defined on  $(\Omega, \mathcal{F}, \mathbb{P})$  with values in  $\mathbb{C}^d$  is an  $L^2$  process if  $\mathbf{X}_t \in L^2(\Omega, \mathcal{F}, \mathbb{P})$  for all  $t \in T$ .

# Mean and covariance functions

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- ▷ Its **covariance function** is defined by

$$\Gamma(s, t) = \text{cov}(\mathbf{X}_s, \mathbf{X}_t) = \mathbb{E} [\mathbf{X}_s \mathbf{X}_t^H] - \mathbb{E} [\mathbf{X}_s] \mathbb{E} [\mathbf{X}_t]^H .$$

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## Linear combinations $\rightarrow$ scalar case

Let  $\mathbf{X} = (\mathbf{X}_t)_{t \in T}$  be an  $L^2$  process with mean function  $\mu$  and covariance function  $\Gamma$ . This is equivalent to say that for all  $\mathbf{u} \in \mathbb{C}^d$ ,  $\mathbf{u}^H \mathbf{X}$  is a scalar  $L^2$  process with mean function  $\mathbf{u}^H \mu$  and covariance function  $\mathbf{u}^H \Gamma \mathbf{u}$ .



## Scalar case $E = \mathbb{C}$ , examples

- ▶ If  $E = \mathbb{C}$ , then the auto-covariance function is  $\mathbb{C}$ -valued, and denoted by  $\gamma$ .

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### Hermitian symmetry, non-negative definiteness

For all  $I \in \mathcal{I}(T)$ ,  $\Gamma_I = \text{Cov}([X(t)]_{t \in I}) = [\gamma(s, t)]_{s, t \in I}$  is a hermitian non-negative definite matrix.

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### Examples

- ▶  $L^2$  independent random variables  $(X_t)_{t \in \mathbb{Z}}$  have mean  $\mu(t) = \mathbb{E}(X_t)$  and covariance

$$\gamma(s, t) = \begin{cases} \text{var}(X_t) & \text{if } s = t, \\ 0 & \text{otherwise.} \end{cases}$$

- ▶ A Gaussian process is an  $L^2$  process whose law is entirely determined by its mean and covariance functions.

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## Definition : Weak stationarity

We say that a random process  $X$  is **weakly stationary** with **mean**  $\mu \in \mathbb{C}$  and **autocovariance function**  $\gamma : \mathbb{Z} \rightarrow \mathbb{C}$  if it is  $L^2$  with mean function  $t \mapsto \mu$  and covariance function  $(s, t) \mapsto \gamma(s - t)$ .

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- ▶ The **autocorrelation function** is then defined (when  $\gamma(0) > 0$ ) by

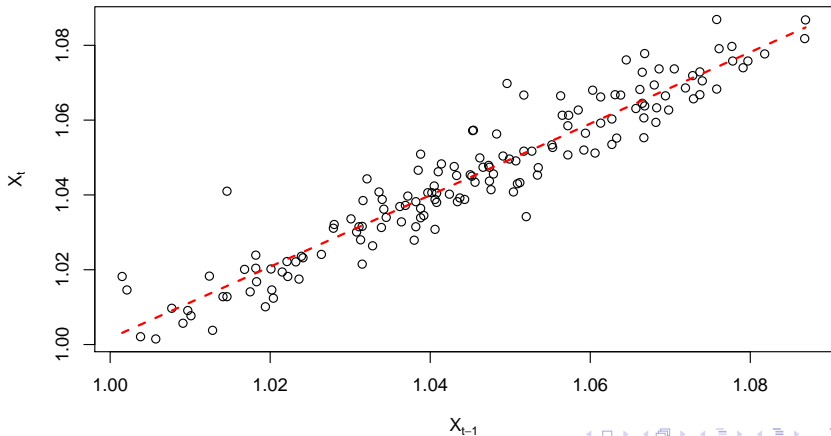
$$\rho(h) = \frac{\gamma(h)}{\gamma(0)} \in [-1, 1] .$$



# Autocorrelation=slope of regression line

We have, for all  $t \in \mathbb{Z}$  and  $h = 1, 2, \dots$ ,

$$X_{t+h} = \text{Constant} + \rho(h)X_t + \epsilon_{t,h} \quad \text{with} \quad \epsilon_{t,h} \perp \text{Span}(1, X_t) .$$



# Partial Autocorrelation

▷ We can also write, for all  $t \in \mathbb{Z}$  and  $h = 1, 2, \dots$ ,

$$X_t = \text{Constant} + \sum_{k=1}^{h-1} \phi_k X_{t-k} + \kappa(h) X_{t-h} + \epsilon_{t,h}$$

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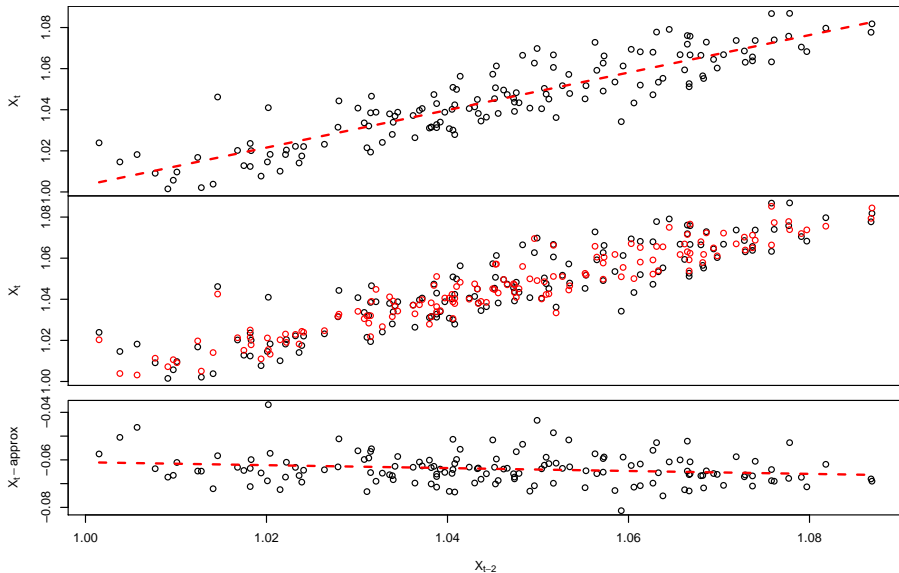
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- ▷  $X_t - \left( \text{Constant} + \sum_{k=1}^{h-1} \phi_k X_{t-k} \right)$  as a function of  $X_{t-h}$ ,  
compared to the regression line  $X_{t-h} \mapsto \kappa(h) X_{t-h}$ .

# Partial Autocorrelation=slope of partial regression



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- ▶ An  $L^2$  process  $X$  with constant mean  $\mu$  and **constant diagonal covariance function** equal to  $\sigma^2$  is called a **weak white noise**. It is denoted by  $X \sim \text{WN}(\mu, \sigma^2)$ . (It does not have to be i.i.d.)

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- ▷ Let  $g = \sum_k \psi_k B^k$ :  $Y_t = \sum_k \psi_k X_{t-k}$  with  $\psi \in \ell^1$ . Then

$$\begin{aligned} \mu' &= \mu \sum_k \psi_k \\ \gamma'(\tau) &= \sum_{\ell, k} \psi_k \bar{\psi}_\ell \gamma(\tau + \ell - k) \end{aligned} \tag{1}$$

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## Herglotz Theorem

Let  $\gamma : \mathbb{Z} \rightarrow \mathbb{C}$ . Then the two following assertions are equivalent:

- (i)  $\gamma$  is hermitian symmetric and non-negative definite.
- (ii) There exists a finite non-negative measure  $\nu$  on  $\mathbb{T} = \mathbb{R}/2\pi\mathbb{Z}$  such that,

$$\text{for all } t \in \mathbb{Z}, \quad \gamma(t) = \int_{\mathbb{T}} e^{i\lambda t} \nu(d\lambda). \quad (2)$$

When these two assertions hold,  $\nu$  is uniquely defined by (2).

# Spectral density

If moreover  $\gamma \in \ell^1(\mathbb{Z})$ , these assertions are equivalent to

$$f(\lambda) := \frac{1}{2\pi} \sum_{t \in \mathbb{Z}} e^{-i\lambda t} \gamma(t) \geq 0 \text{ for all } \lambda \in \mathbb{R},$$

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## Definition : spectral measure and spectral density

If  $\gamma$  is the autocovariance of a weakly stationary process  $X$ , the corresponding measure  $\nu$  is called the **spectral measure** of  $X$ . Whenever the spectral measure  $\nu$  admits a density  $f$ , it is called the **spectral density function**.

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- ▶ Then  $Y$  is a weakly stationary process with spectral measure  $\nu'$  having density  $\lambda \mapsto \left| \sum_k \psi_k e^{-i\lambda k} \right|^2$  with respect to  $\nu$ ,

$$\nu'(d\lambda) = \left| \sum_k \psi_k e^{-i\lambda k} \right|^2 \nu(d\lambda) .$$



## A special one : the harmonic process

Let  $(A_k)_{1 \leq k \leq N}$  be  $N$  real valued  $L^2$  random variables. Denote  $\sigma_k^2 = \mathbb{E}[A_k^2]$ . Let  $(\Phi_k)_{1 \leq k \leq N}$  be  $N$  i.i.d. random variables with a uniform distribution on  $[0, 2\pi]$ , and independent of  $(A_k)_{1 \leq k \leq N}$ . Define

$$X_t = \sum_{k=1}^N A_k \cos(\lambda_k t + \Phi_k), \quad (3)$$

where  $(\lambda_k)_{1 \leq k \leq N} \in [-\pi, \pi]$  are  $N$  frequencies. The process  $(X_t)$  is called a **harmonic process**. It satisfies  $\mathbb{E}[X_t] = 0$  and, for all  $s, t \in \mathbb{Z}$ ,

$$\mathbb{E}[X_s X_t] = \frac{1}{2} \sum_{k=1}^N \sigma_k^2 \cos(\lambda_k(s - t)).$$

Hence  $X$  is weakly stationary with autocovariance

$$\gamma(t) = \frac{1}{2} \sum_{k=1}^N \sigma_k^2 \cos(\lambda_k t) = \int_{\mathbb{T}} e^{i\lambda t} \left( \frac{1}{4} \sum_{k=1}^N \sigma_k^2 (\delta_{-\lambda_k}(d\lambda) + \delta_{\lambda_k}(d\lambda)) \right).$$

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- ▷ Define the **empirical autocovariance** and **autocorrelation** functions as

$$\hat{\gamma}_n(h) = \frac{1}{n} \sum_{k=1}^{n-|h|} (X_k - \hat{\mu}_n)(X_{k+|h|} - \hat{\mu}_n) \quad \text{and}$$
$$\hat{\rho}_n(h) = \frac{\hat{\gamma}_n(h)}{\hat{\gamma}_n(0)} .$$

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- ▶ Now  $\hat{\gamma}_n$  is defined on  $\mathbb{Z}$  and satisfies

$$\hat{\gamma}_n(h) = \int_{-\pi}^{\pi} e^{i\lambda h} I_n(\lambda) d\lambda ,$$

where  $I_n$  is called the (raw) **periodogram** and is defined by

$$I_n(\lambda) = \frac{1}{2\pi n} \left| \sum_{k=1}^n (X_k - \hat{\mu}_n) e^{-i\lambda k} \right|^2 .$$



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- ▶  $I_n(\lambda)$  can be seen as a (bad) estimator of the spectral density  $f(\lambda)$ .