

# Metodo Diferencia progresiva y regresiva

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$$\frac{\partial u}{\partial t} = \frac{\partial^2 u}{\partial x^2} - \frac{\partial u}{\partial x} + u \quad 0 \leq x \leq 1$$

$$\frac{\partial u}{\partial x}(0, t) = 2t \quad u(1, t) = \frac{t^2}{2} \quad t > 0$$

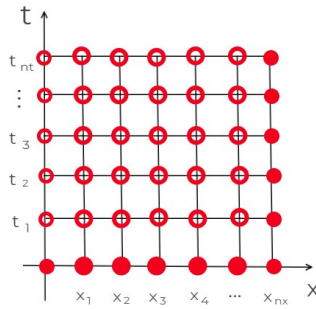
$$u(x, 0) = \sin(x) + \cos(x)$$

Limitamos  $0 \leq t \leq T_{max}$  Discretizamos los intervalos mediante una serie de nodos equiespaciados:

$$nx = ih, \quad i = 0, 1, 2, \dots, nx$$

$$nt = jk \quad j = 0, 1, 2, \dots, nt$$

donde  $h = \frac{1-0}{nx}$ ,  $k = \frac{T_{max}}{nt}$ . Generando asi la discretizacion.



# 1 Método Explícito

Utilizamos formulas de aproximacion en diferencias para  $u_{xx}$ ,  $u_t$  y  $u_x$ .

$$u_t = \frac{u_{i,j+1} - u_{i,j}}{k}$$

$$u_x = \frac{u_{i+1,j} - u_{i,j}}{h}$$

$$u_{xx} = \frac{u_{i+1,j} - 2u_{i,j} + u_{i-1,j}}{h^2}$$

reemplazando en la ecuación original tenemos:

$$\frac{u_{i,j+1} - u_{i,j}}{k} = \frac{u_{i+1,j} - 2u_{i,j} + u_{i-1,j}}{h^2} - \frac{u_{i+1,j} - u_{i,j}}{h} + u_{i,j}$$

despejamos la variable con el tiempo mayor

$$u_{i,j+1} = \frac{k}{h^2}(u_{i+1,j} - 2u_{i,j} + u_{i-1,j}) - \frac{k}{h}(u_{i+1,j} - u_{i,j}) + (1+k)u_{i,j}$$

$$u_{i,j+1} = (\frac{k}{h^2} - \frac{k}{h})u_{i+1,j} + (1+k + \frac{k}{h} - 2\frac{k}{h^2})u_{i,j} + \frac{k}{h^2}u_{i-1,j}$$

para  $i = 0$  tenemos

$$u_{0,j+1} = (\frac{k}{h^2} - \frac{k}{h})u_{1,j} + (1+k + \frac{k}{h} - 2\frac{k}{h^2})u_{0,j} + \frac{k}{h^2}u_{-1,j} \quad (*)$$

$$\forall j = 1, 2, \dots, nt - 1$$

para  $u_{-1,j}$  hacemos diferencia regresiva para  $u_x$

$$u_x(0, t) = \frac{u_{0,j} - u_{-1,j}}{h} = 2t_j$$

$$u_{-1,j} = u_{0,j} - 2ht_j$$

reemplazando  $u_{-1,j}$  en  $(*)$  obtenemos la siguiente ecuacion para  $i = 0$

$$u_{0,j+1} = (\frac{k}{h^2} - \frac{k}{h})u_{1,j} + (1+k + \frac{k}{h} - 2\frac{k}{h^2})u_{0,j} + \frac{k}{h^2}(u_{0,j} - 2ht_j)$$

$$u_{0,j+1} = (\frac{k}{h^2} - \frac{k}{h})u_{1,j} + (1 + k + \frac{k}{h} - \frac{k}{h^2})u_{0,j} - \frac{k}{h^2}2ht_j$$

para  $i = nx$  tenemos

$$u_{nx,j+1} = \frac{t^2}{2} \quad \forall j = 0, 1, 2, \dots, nt - 1$$

para todo  $j = 0, 1, 2, \dots, nt - 1$  tenemos

$$\left\{ \begin{array}{l} u_{0,j+1} = (\frac{k}{h^2} - \frac{k}{h})u_{1,j} + (1 + k + \frac{k}{h} - \frac{k}{h^2})u_{0,j} - \frac{k}{h^2}2ht_j \\ u_{i,j+1} = (\frac{k}{h^2} - \frac{k}{h})u_{i+1,j} + (1 + k + \frac{k}{h} - 2\frac{k}{h^2})u_{i,j} + \frac{k}{h^2}u_{i-1,j} \\ u_{nx,j+1} = \frac{t^2}{2} \end{array} \right.$$

Por condicion inicial tenemos

$$u(x, 0) = \sin(x) + \cos(x) = f(x)$$

$$u_{i,0} = f(ih) \quad \forall i = 0, 1, 2, \dots, nx$$

para  $j = 0$

$$\begin{aligned} u_{0,1} &= (\frac{k}{h^2} - \frac{k}{h})u_{1,0} + (1 + k + \frac{k}{h} - \frac{k}{h^2})u_{0,0} - \frac{k}{h^2}2ht_0 \\ u_{1,1} &= (\frac{k}{h^2} - \frac{k}{h})u_{2,0} + (1 + k + \frac{k}{h} - 2\frac{k}{h^2})u_{1,0} + \frac{k}{h^2}u_{0,0} \\ u_{2,1} &= (\frac{k}{h^2} - \frac{k}{h})u_{3,0} + (1 + k + \frac{k}{h} - 2\frac{k}{h^2})u_{2,0} + \frac{k}{h^2}u_{1,0} \\ &\vdots \\ u_{nx-1,1} &= (\frac{k}{h^2} - \frac{k}{h})u_{nx,0} + (1 + k + \frac{k}{h} - 2\frac{k}{h^2})u_{nx-1,0} + \frac{k}{h^2}u_{nx-2,0} \\ u_{nx,1} &= \frac{t_0^2}{2} \end{aligned}$$

la forma matricial seria:

$$\lambda = \frac{k}{h^2}$$

$$\begin{pmatrix} u_{0,1} \\ u_{1,1} \\ u_{2,1} \\ u_{3,1} \\ \vdots \\ u_{nx-1,1} \end{pmatrix} = A \begin{pmatrix} u_{0,0} \\ u_{1,0} \\ u_{2,0} \\ u_{3,0} \\ \vdots \\ u_{nx-1,0} \end{pmatrix} + \begin{pmatrix} -\lambda 2ht_0 \\ 0 \\ 0 \\ \vdots \\ (\frac{k}{h^2} - \frac{k}{h})u_{nx,0} \end{pmatrix} \quad (1)$$

$$A = \begin{pmatrix} 1 + k + \frac{k}{h} - \lambda & \lambda - \frac{k}{h} & 0 & 0 & \cdots & 0 & 0 \\ \lambda & 1 + k + \frac{k}{h} - 2\lambda & \lambda - \frac{k}{h} & 0 & \cdots & 0 & 0 \\ 0 & \lambda & 1 + k + \frac{k}{h} - 2\lambda & \lambda - \frac{k}{h} & \cdots & 0 & 0 \\ \vdots & \vdots & & \ddots & & & \vdots \\ 0 & 0 & 0 & 0 & \cdots & \lambda & 1 + k + \frac{k}{h} - 2\lambda \end{pmatrix}$$

la forma matricial general:

$$\forall j = 0, 1, 2, \dots, nt - 1$$

$$\begin{pmatrix} u_{0,j+1} \\ u_{1,j+1} \\ u_{2,j+1} \\ \vdots \\ u_{nx-1,j+1} \end{pmatrix} = A \begin{pmatrix} u_{0,j} \\ u_{1,j} \\ u_{2,j} \\ \vdots \\ u_{nx-1,j} \end{pmatrix} + \begin{pmatrix} -\lambda 2ht_j \\ 0 \\ 0 \\ \vdots \\ (\frac{k}{h^2} - \frac{k}{h})u_{nx,j} \end{pmatrix} \quad (2)$$

## 2 Método Implícito

Utilizamos formulas de aproximacion en diferencias para  $u_{xx}$ ,  $u_t$  y  $u_x$ .

$$\begin{aligned}u_t &= \frac{u_{i,j} - u_{i,j-1}}{k} \\u_x &= \frac{u_{i,j} - u_{i-1,j}}{h} \\u_{xx} &= \frac{u_{i+1,j} - 2u_{i,j} + u_{i-1,j}}{h^2}\end{aligned}$$

reemplazando en la ecuación original tenemos:

$$\frac{u_{i,j} - u_{i,j-1}}{k} = \frac{u_{i+1,j} - 2u_{i,j} + u_{i-1,j}}{h^2} - \frac{u_{i,j} - u_{i-1,j}}{h} + u_{i,j}$$

despejamos la variable con el tiempo menor

$$\begin{aligned}u_{i,j} - u_{i,j-1} &= \frac{k}{h^2}(u_{i+1,j} - 2u_{i,j} + u_{i-1,j})h^2 - \frac{k}{h}(u_{i,j} - u_{i-1,j}) + ku_{i,j} \\(1 - k + 2\frac{k}{h^2} + \frac{k}{h})u_{i,j} - (\frac{k}{h^2} + \frac{k}{h})u_{i-1,j} - \frac{k}{h^2}u_{i+1,j} &= u_{i,j-1}\end{aligned}$$

Para  $i = 0$  tenemos

$$\begin{aligned}(1 - k + 2\frac{k}{h^2} + \frac{k}{h})u_{0,j} - (\frac{k}{h^2} + \frac{k}{h})u_{-1,j} - \frac{k}{h^2}u_{1,j} &= u_{0,j-1} \quad (*) \\ \forall j = 1, 2, \dots, nt\end{aligned}$$

para  $u_{-1,j}$  hacemos diferencia regresiva en  $u_x$

$$\begin{aligned}u_x(0, t) &= \frac{u_{0,j} - u_{-1,j}}{h} = 2t_j \\u_{-1,j} &= u_{0,j} - 2ht_j\end{aligned}$$

reemplazando  $u_{-1,j}$  en (\*) obtenemos la siguiente ecuacion para  $i = 0$

$$\begin{aligned}(1 - k + 2\frac{k}{h^2} + \frac{k}{h})u_{0,j} - (\frac{k}{h^2} + \frac{k}{h})(u_{0,j} - 2ht_j) - \frac{k}{h^2}u_{1,j} &= u_{0,j-1} \\(1 - k + \frac{k}{h^2})u_{0,j} + (\frac{k}{h^2} + \frac{k}{h})2ht_j - \frac{k}{h^2}u_{1,j} &= u_{0,j-1}\end{aligned}$$

para todo  $j = 1, 2, \dots, nt$  tenemos

$$\left\{ \begin{array}{l} (1 - k + \frac{k}{h^2})u_{0,j} + (\frac{k}{h^2} + \frac{k}{h})2ht_j - \frac{k}{h^2}u_{1,j} = u_{0,j-1} \\ (1 - k + 2\frac{k}{h^2} + \frac{k}{h})u_{i,j} - (\frac{k}{h^2} + \frac{k}{h})u_{i-1,j} - \frac{k}{h^2}u_{i+1,j} = u_{i,j-1} \\ u_{nx,j} = \frac{t_j^2}{2} \end{array} \right.$$

Por condicion inicial tenemos

$$u(x, 0) = \sin(x) + \cos(x) = f(x)$$

$$u_{i,0} = f(ih) \quad \forall i = 0, 1, 2, \dots, nx$$

para  $j = 1$

$$\begin{aligned} (1 - k + \frac{k}{h^2})u_{0,1} + (\frac{k}{h^2} + \frac{k}{h})2ht_1 - \frac{k}{h^2}u_{1,1} &= u_{0,0} \\ (1 - k + 2\frac{k}{h^2} + \frac{k}{h})u_{1,1} - (\frac{k}{h^2} + \frac{k}{h})u_{0,1} - \frac{k}{h^2}u_{2,1} &= u_{1,0} \\ (1 - k + 2\frac{k}{h^2} + \frac{k}{h})u_{2,1} - (\frac{k}{h^2} + \frac{k}{h})u_{1,1} - \frac{k}{h^2}u_{3,1} &= u_{2,0} \\ &\vdots \\ (1 - k + 2\frac{k}{h^2} + \frac{k}{h})u_{nx-1,1} - (\frac{k}{h^2} + \frac{k}{h})u_{nx-2,1} - \frac{k}{h^2}u_{nx,1} &= u_{nx-1,0} \end{aligned}$$

El sistema de arriba puede escribirse en forma de matriz

$$A \begin{pmatrix} u_{0,1} \\ u_{1,1} \\ u_{2,1} \\ \vdots \\ u_{nx-1,1} \end{pmatrix} = \begin{pmatrix} u_{0,0} \\ u_{1,0} \\ u_{2,0} \\ \vdots \\ u_{nx-1,0} \end{pmatrix} + \begin{pmatrix} -(\frac{k}{h^2} + \frac{k}{h})2ht_1 \\ 0 \\ 0 \\ \vdots \\ -\frac{k}{h^2}u_{nx,1} \end{pmatrix} \quad (3)$$

$$A = \begin{pmatrix} 1 - k + \frac{k}{h^2} & \frac{k}{h^2} + \frac{k}{h} & 0 & 0 & \cdots & 0 & 0 \\ -(\frac{k}{h^2} + \frac{k}{h}) & 1 - k + 2\frac{k}{h^2} + \frac{k}{h} & -\frac{k}{h^2} & 0 & \cdots & 0 & 0 \\ 0 & -(\frac{k}{h^2} + \frac{k}{h}) & 1 - k + 2\frac{k}{h^2} + \frac{k}{h} & -\frac{k}{h^2} & \cdots & 0 & 0 \\ \vdots & \vdots & & \ddots & & & \vdots \\ 0 & 0 & 0 & 0 & \cdots & -(\frac{k}{h^2} + \frac{k}{h}) & 1 - k + 2\frac{k}{h^2} + \frac{k}{h} \end{pmatrix}$$