Supplementary Material (B) - Testing the Circumplex Structure of the Soundscape Survey

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1. Finishing the SEM analysis

This analysis continues from the previous document Supplementary Material (A) - Testing the Circumplex Structure of the Soundscape Survey. In that stage, we used CircE to test the circumplex structure of the soundscape survey based on a Structural Equation Modelling (SEM) approach and produced a suite of fit indices. First, we will compile and analyse these fit indices results and determine whether each translation has passed the SEM fit criteria.

We will then use the Structural Summary Method (SSM) to analyse the circumplex structure of the soundscape survey.

As in step one, we load the data and predefine the scales and the set of equally-spaced angles to be used in the analysis.

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1.1. Angles of the scales

i Intro to standalone paper

As expected, the soundscape circumplex does not conform to a strict circumplex. However, some of the translations are shown to conform with a quasi-circumplex structure. This can present an issue when data from a quasi-circumplex instrument is analysed as if it were a strict circumplex (i.e. with equally spaced angles and equal communalities). This is because the quasi-circumplex structure may result in the data being rotated and displaced, locating some particular analysis at the wrong coordainte within the space.

This error may be considered acceptable if one were only working and comparing results within one instrument (within-instrument analysis), such that the errors from the quasi-circumplexity are consistent. However, when working with translations of the same circumplex instrument, the quasi-circumplexity may result in the data being rotated and displaced differently for each translation. This would result in the data from each translation being located at different coordinates within the space, making direct comparison between translations difficult.

For instrument translations, it is apparent that between-instrument comparisons are equally as important as within-instrument comparisons. As such, a method which would allow the correction or normalisation of data from each translation to a common circumplex structure would be useful.

DRAFT: Explain the equal vs corrected angles and how we propose to use the corrected angles.

DRAFT: Explain inverse angles, reference? / CircE docs and their discussion of why we can just reverse them. Maybe in a footnote in those papers?

1.2. Acoustic Data

In addition to the survey responses, we also have acoustic data for each recording. This data includes the L_{eq} , L_{Aeq} , N, and L_{A90} values for each recording. These values are used to calculate the acoustic indices for each recording, which can then be correlated with the survey responses. This will be used later, in the validation of the survey instrument.

2. Calculate the SEM fit score

The SEM fit score is calculated by counting the number of fit indices that pass the pre-defined threshold. The thresholds are defined in the first part of the code. The thresholds are based on the thresholds used by ?.

The first part of the code defines a dictionary named thresholds which contains the thresholds for different fit criteria used in SEM. These criteria include p-value (p), Comparative Fit Index (CFI), Goodness of Fit Index (GFI), Adjusted Goodness of Fit Index (AGFI), Standardized Root Mean Square Residual (SRMR), and others.

The incl_in_score list is used to select which criteria will be included in the final score calculation. The pass_thresh and tent_thresh variables define the thresholds for passing and tentative passing scores, respectively.

The next part of the code calculates whether each SEM result passes the defined thresholds for each criterion. This is done by comparing the SEM result for each criterion to its respective threshold. The results of these comparisons are stored as boolean values in new columns in the sem_res DataFrame.

The final score for each SEM result is then calculated by summing the number of criteria each result passes. This score is stored as an integer in a new column in the sem_res DataFrame. The passing column categorizes each SEM result as 'Fail', 'Tentative', or 'Pass' based on its final score.

Finally, the results are saved to an Excel file and a subset of the results is displayed. The subset includes only the results for the "Equal comm." model type and is sorted by score in descending order.

	Language	Model Type	Score	passing
33	ita	Equal comm.	4	Pass
5	arb	Equal comm.	4	Pass
45	nld	Equal comm.	4	Pass
41	kor	Equal comm.	4	Pass
65	vie	Equal comm.	4	Pass
17	ell	Equal comm.	4	Pass
9	cmn	Equal comm.	4	Pass
25	hrv	Equal comm.	3	Tentative
29	ind	Equal comm.	3	Tentative
13	deu	Equal comm.	3	Tentative
53	spa	Equal comm.	3	Tentative
57	swe	Equal comm.	3	Tentative
61	tur	Equal comm.	3	Tentative
1	eng	Equal comm.	3	Tentative
21	fra	Equal comm.	2	Fail
49	por	Equal comm.	2	Fail
37	$_{ m jpn}$	Equal comm.	1	Fail

3. Structural Summary Method Analysis

To begin the SSM analysis, we first filter the languages to examine by whether or not they passed Step one, the SEM analysis.

3.1. Step two: Locating external variables in the circumplex

As described in ?, Step Two involves testing whether external variables can be located within the circumplex. This is done by correlating the external variables with the circumplex scales.

For this, we use a consistent external variable across all language datasets - psychoacoustic loudness, max_N. For each recording, we have measured the psychoacoustic loudness to which the participants were exposed, for both channels. To get a single level for each recording, we select the maximum loudness level from the two channels, as suggested in ?.

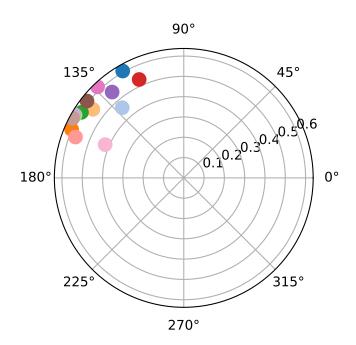
This max_N is then correlated with each circumplex scale across each of the passing language, and the SSM parameters are calculated. Because we have derived new angles in the SEM step, we use these 'corrected' angles for calculating the SSM parameters.

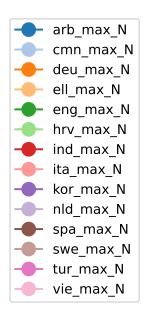
In order to determine whether the language circumplexes can adequately allow an external variable to be located, we use the following criteria:

- $R^2 > 0.8$
- amplitude > .15

These indices are based on the criteria used by ?, however we use an increased criterion of $R^2 > 0.8$ since we have a prior expectation that loudness is a highly significant correlate with soundscape perception. As such, any successful circumplex instrument should show a very good fit when locating loudness.

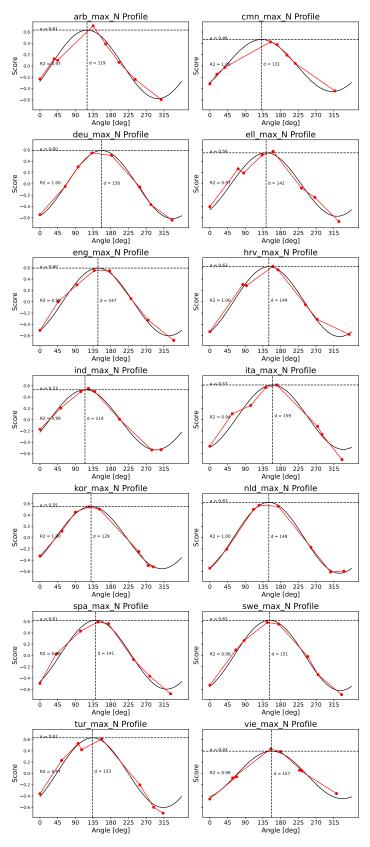
For this analysis, we use a custom Python package developed for this paper, called circumplex which can be installed from PyPI.





	group	measure	elevation	xval	yval	amplitude	displacement	r2	PAQ1	P
arb_max_N	arb	max_N	0.028652	-0.300776	0.526289	0.606173	119.748102	0.973883	0.0	36
cmn_max_N	cmn	$\max_{}$ N	0.008257	-0.302994	0.345729	0.459710	131.231028	0.997280	0.0	18
deu_max_N	deu	$\max_{}$ N	-0.012336	-0.552609	0.239104	0.602119	156.602687	0.997791	0.0	64
ell_max_N	ell	$\max_{}$ N	-0.012408	-0.447707	0.337784	0.560838	142.966368	0.965840	0.0	72
eng_max_N	eng	$\max_{}$ N	-0.002989	-0.503990	0.322928	0.598572	147.350541	0.980108	0.0	46
hrv_max_N	hrv	$\max_{}$ N	0.001776	-0.535124	0.309361	0.618112	149.967353	0.995544	0.0	84
ind_max_N	ind	\max_{N}	-0.003039	-0.219705	0.484667	0.532140	114.385256	0.994985	0.0	53
ita_max_N	ita	$\max_{}$ N	0.043825	-0.533336	0.201253	0.570044	159.326103	0.944581	0.0	57
kor_max_N	kor	$\max_{}$ N	-0.001199	-0.352948	0.422768	0.550731	129.856771	0.995467	0.0	56
nld_max_N	nld	\max_{N}	-0.004002	-0.542282	0.314914	0.627089	149.855424	0.998637	0.0	43
spa_max_N	spa	\max_{N}	0.013359	-0.476590	0.378525	0.608621	141.542150	0.979561	0.0	41
swe_max_N	swe	\max_{N}	0.001115	-0.547474	0.293851	0.621350	151.775732	0.991721	0.0	66
tur_max_N	tur	$\max_{}$ N	0.012860	-0.424515	0.448116	0.617269	133.450768	0.971465	0.0	55
vie_max_N	vie	max_N	-0.027039	-0.387283	0.163897	0.420536	157.062077	0.978702	0.0	68

R2 > 0.8 : 14 / 14 amp > 0.15: 14 / 14



All of the investigated languages are able to adequately locate an external variable using SSM. We can further investigate the SSM profile of each of these:

3.2. Step 3: Accurately locating circumplex items within each language

The final step of ? 's three step procedure is to test the congruence between the empirical locations and theoretical expectations within the circumplex structure. In the case of the soundscape circumplex and our SATP data, we don't have an external variable with a defined theoretical location within the circumplex - for instance loudness does not have a defined location within the circumplex where it is expected to be

Taking inspiration from ?, we propose to use the circumplex structure of the soundscape survey itself as the theoretical expectation. ? proposes that one circumplex can be located within another by calculating the SSM correlation between each of the scales of the reference circumplex and the test circumplex. In this way, each scale of the reference circumplex can be located within the test circumplex, and we can test whether these empirical locations meet our expectations.

The process to do this is as follows:

- 1. For both the reference and test circumplex, calculate the mean value of each scale for each recording.
- 2. Calculate the SSM correlation between each scale of the reference circumplex and the test circumplex, in our case using the corrected angles.
- 3. Test the congruence betwen the empirical locations and theoretical expectations using the Procrustes congruence test (?).

We will be using the full dataset as the reference set and the data from each translation as the test set. This effectively means that we are testing whether each translation is able to locate the circumplex structure of the soundscape survey, consistently across all languages.

This aligns with the overall goal of our process of allowing data (i.e. the circumplex coordinate) from different languages to be directly compared, by correcting for the differences in the circumplex structure between languages.

to minimize $M^2=\sum (data1-data2)^2$, or the sum of the squares of the pointwise differences between the two input datasets.

3.2.1. Congruence

What ? (and Orthosim) refer to as Tucker's Congruence Coefficient is also commonly referred to as the cosine similarity (see the Tensorly documentation). We therefore use the sklearn implementation of cosine similarity to calculate the congruence between the empirical locations and theoretical expectations. This produces a matrix of cosine similarity values, which we then use to calculate the mean congruence, to match the model congruence from ?.

We can confirm the equivalence of this method by comparing with the results from ? 's Orthosim analysis:

```
Model Congruence == 0.984: True
Vulnerability Congruence == 0.99: True
Antagonism Congruence == 1.0: True
Grandiosity Congruence == 0.97: True
```

3.2.2. Procrustes

However, it appears that, despite? 's description, this method is not actually based on a Procrustes analysis. The equivalent distance metric from a Procrustes method would be the rotational-based Procrustes distance, i.e. the squared Froebenius norm of the difference between the two orthogonal matrices. See ?:

Instead, the second distance exploits the orthogonal matrix parameters solution of the Procrustes problem. The rotational-based distance computes the squared Frobenius distance between these estimated orthogonal matrices. As we will see, this metric measures the level of dissimilarity/similarity in orientation between matrices/subjects before functional alignment.

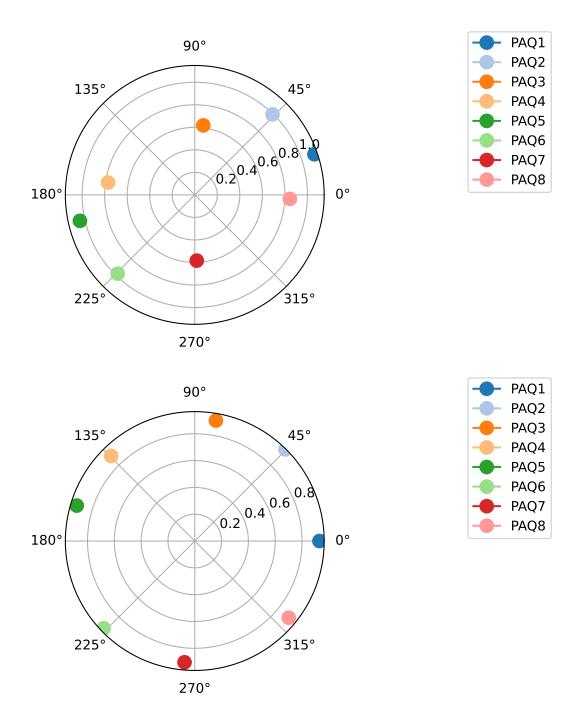
As such, we can also calculate this distance using the procrustes package:

Based on the proof given in ?, given that the input matrices are scaled (i.e. rotational(scale=True)), then the Procrustes distance is a true distance measure which obeys 0 < p(X,Y) < 1 (?, 322). Therefore we can convert the Procrustes distance to a similarity measure by subtracting it from 1.

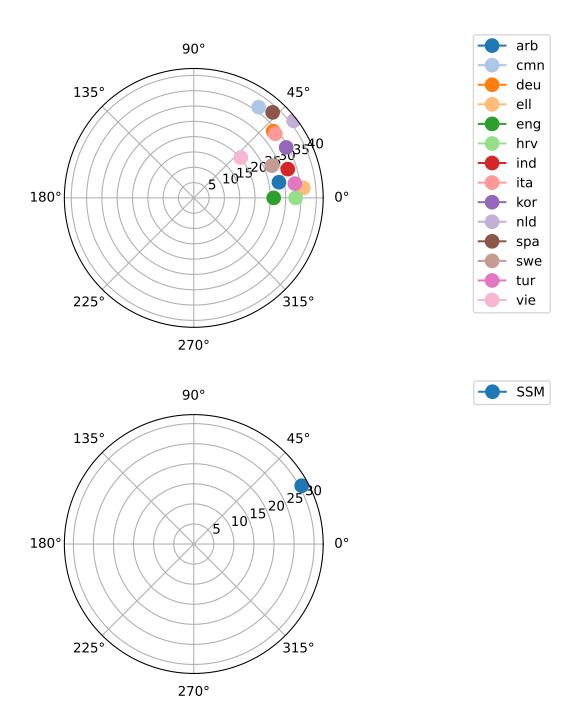
	Language	Eq Ang Model	Corr Ang Model	Eq Ang Procrustes	Corr Ang Procrustes
0	arb	0.990	0.940	0.980	0.983
1	cmn	0.931	0.992	0.881	0.990
2	deu	0.986	0.960	0.974	0.983
3	ell	0.986	0.990	0.972	0.980
4	eng	0.989	0.979	0.983	0.983
5	hrv	0.990	0.971	0.982	0.985
6	ind	0.965	0.948	0.937	0.982
7	ita	0.985	0.954	0.975	0.974
8	kor	0.958	0.976	0.924	0.976
9	nld	0.979	0.974	0.941	0.979
10	spa	0.987	0.983	0.968	0.978
11	swe	0.987	0.975	0.973	0.977
12	tur	0.957	0.985	0.924	0.981
13	vie	0.935	0.938	0.926	0.945

We can see from the above table that the congruence between the empirical locations and theoretical expectations is quite high for all languages. In addition, by using the corrected angles, we can see that the procrustes similarity is improved for nearly all languages (slight decrease for 'ita').

Below, we can show that this looks like in practice. The first plot shows the empirical locations of the scales for the Mandarin translation, using the equal angles. The second plot shows the empirical locations of the scales for the Mandarin translation, using the corrected angles.



While the relative locations of the scales around the circumplex are not perfect, it can be clearly seen that when the correction is applied, the scales are much more closely located to the theoretical expectations. Since this is true across all of the languages, we can now have the expectation that we are working within a consistent circumplex space. This means that we can directly compare the circumplex coordinates between languages, and that any differences in the circumplex coordinates are due to differences in the soundscape perception, rather than differences in the circumplex structure of the translation.



4. Using the corrected angles for ISO 12913-3 and ? style analysis $\frac{1}{2}$

Making use of these corrected angles in line with either the analysis recommended in ? or ? is quite straightforward. Simply replace the $\cos 45$ in the ISO projection equation with $\cos \theta$ and $\sin \theta$, where θ is the corrected angle for each scale.

For example, the ISO projection equation for ISOPleasant and ISOEventful in Swedish are now:

```
P = p + \cos(66) * v + \cos(87) * e + \cos(146) * ch + \cos(175) * a + \cos(249) * m + \cos(275) * u + \cos(335) * ca
```

```
E = \sin(66) * v + \sin(87) * e + \sin(146) * ch + \sin(175) * a + \sin(249) * m + \sin(275) * u + \sin(335) * ca
```

For each language, simply replace the θ values with the corrected angles for that language.

In more SEM-like terms, we are multiplying each scale by its respective loading expressed in terms of its angle around the circumplex, and then summing the results. Some may argue that we should just directly treat this system as an SEM, however by expressing this projection in terms of the angles, we can directly see how this is related to the circumplex and the projected coordinate point, and more easily compare the results with the results from the SSM analysis.

In that vein, we would actually recommend performing the ISOPleasant & ISOEventful calculations via the Structural Summary Method, rather than the projection method. This provides a more flexible and informative framework for the analysis, and allows for the correlation of the scales with external variables, calculation of model fit, and other useful analyses.