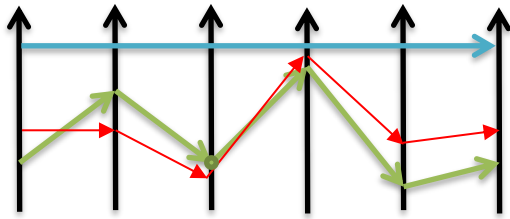
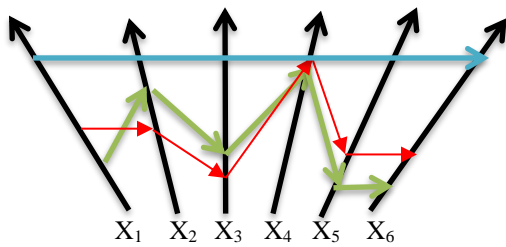


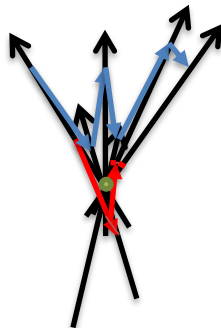
HW 3  
Part 1



(a) Use HW1 to draw this picture

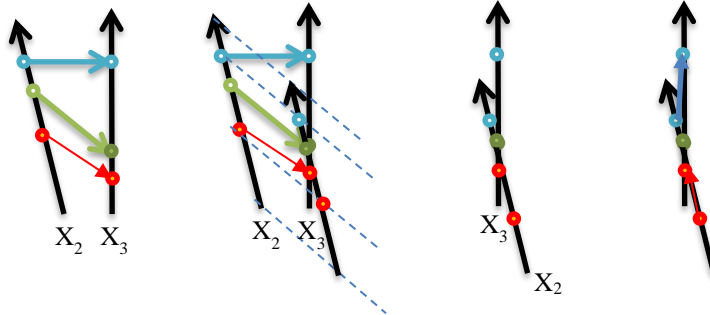


(b) Modify HW1 code to make this picture



(c) Make this picture by shifting  $X_1, X_2, X_4, X_5, X_6$  to  $X_3$ . The green line from (b) is collapsed to a single green dot (small circle).

Algorithm for (c) is illustrated for  $X_2$  and  $X_3$  where  $X_2$  is shifted to  $X_3$  in a way such that the green point on  $X_2$  is moving to the green point on  $X_3$ . Blue and red points also are moved parallel to the green point. Next the moved blue point on  $X_2$  is connected by the arrow to the blue point on  $X_3$ . Next the moved red point on  $X_2$  is connected by the arrow to the red point on  $X_3$ . The same process is applied when other  $X_i$  are moved to  $X_3$ .



Part 2. Generalize code above for three classes of and 100 6-D points read from the file

Part 3. Conduct computational experiments with 3 datasets on 100 cases each of 3 classes similarly to experiment in HW1. You can increase the angles of other axis  $X_i$  relative to  $X_3$  to make the picture less occluded.