TEXAS INSTRUMENTS

TMS320C1x/C2x/C2xx/C5x Assembly Language Tools

User's Guide

User's
Guide

TMS320C1x/C2x/C2xx/C5x

Assembly Language Tools

1995

TMS320C1x/C2x/C2xx/C5x
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Read This First

What Is This Book About?

The *TMS320C1x/C2x/C2xx/C5x Assembly Language Tools User's Guide* tells you how to use these assembly language tools:

❏ Assembler
❏ Archiver
❏ Linker
❏ Absolute lister
❏ Cross-reference lister
❏ Hex conversion utility

Before you can use this book, you should read the *TMS320C1x/C2x/ C2xx/ C5x Code Generation Tools Getting Started* to install the assembly language tools.

How to Use This Manual

The goal of this book is to help you learn how to use the Texas Instruments assembly language tools specifically designed for the TMS320 fixed-point DSPs. This book is divided into four distinct parts:

❏ **Part I: Introductory Information** gives you an overview of the assembly language development tools and also discusses common object file format (COFF) which helps you to use the TMS320C1x/C2x/C2xx/C5x tools more efficiently. *Read Chapter 2 before using the assembler and linker.*

❏ **Part II: Assembler Description** contains detailed information about using the assembler. This section explains how to invoke the assembler and discusses source statement format, valid constants and expressions, assembler output, and assembler directives. It also summarizes the TMS320C1x, TMS320C2x, TMS320C2xx, and TMS320C5x instruction sets alphabetically and describes macro elements.

❑ **Part III: Additional Assembly Language Tools** describes in detail each of the tools provided with the assembler to help you create assembly language source files. For example, Chapter 8 explains how to invoke the linker, how the linker operates, and how to use linker directives. Chapter 11 explains how to use the hex conversion utility.

❑ **Part IV: Reference Material** provides supplementary information. This section contains technical data about the internal format and structure of COFF object files. It discusses symbolic debugging directives that the TMS320C2x/C5x C compiler uses. Finally, it includes sample linker command files, assembler and linker error messages, and a glossary.

Notational Conventions

This document uses the following conventions.

❑ Program listings, program examples, and interactive displays are shown in a special font. Examples use a bold version of the special font for emphasis. Here is a sample program listing:

```
11  0005  0001          .field   1, 2
12  0005  0003          .field   3, 4
13  0005  0006          .field   6, 3
14  0006                .even
```

❑ In syntax descriptions, the instruction, command, or directive is in a **bold face** font and parameters are in an *italics*. Portions of a syntax that are in **bold face** should be entered as shown; portions of a syntax that are in *italics* describe the type of information that should be entered. Syntax that will be entered on a command line is centered in a bounded box. Syntax that will be used in a text file is left-justified in an unbounded box. Here is an example of command line syntax:

dspabs   *filename*

dspabs is a command. The command invokes the absolute lister and has one parameter, indicated by *filename*. When you invoke the absolute lister, you supply the name of the file that the absolute lister uses as input.

❑ Square brackets (**[** and **]**) identify an optional parameter. If you use an optional parameter, you specify the information within the brackets; you don't enter the brackets themselves. Here's an example of an instruction that has an optional parameter:

dsphex   [*–options*]   *filename*

The **dsphex** command has two parameters. The first parameter, *–options*, is optional. Since *options* is plural, you may select several options. The second parameter, *filename*, is required.

Square brackets are also used as part of the pathname specification for VMS pathnames; in this case, the brackets are actually part of the pathname (they are not optional).

❏ In assembler syntax statements, column one is reserved for the first character of a label or symbol. If the label or symbol is **optional**, it is usually not shown. If it is a **required** parameter, then it will be shown starting against the left margin of the shaded box, as in the example below. No instruction, command, directive, or parameter, other than a symbol or label, should begin in column one.

symbol **.usect "***section name***",** *size in bytes*

The *symbol* is **required** for the .usect directive and must begin in **column one**. The *section name* must be enclosed in quotes, and the section *size in bytes* must be separated from the *section name* by a comma.

❏ Some directives can have a varying number of parameters. For example, the .byte directive can have up to 100 parameters. The syntax for this directive is:

Note that **.byte** does not begin in column one.

.byte   *value$_1$* [, ... , *value$_n$*]

This syntax shows that .byte must have at least one value parameter, but you have the option of supplying additional value parameters, separated by commas.

❏ Braces ({ and }) indicate a list. The symbol **|** (read as *or*) separates items within the list. Here's an example of a list:

{ * | *+ | *− }

This provides three choices: *, *+, or *−.

Unless the list is enclosed in square brackets, you must choose one item from the list.

Related Documentation From Texas Instruments

The following books describe the TMS320C1x, 'C2x, 'C2xx, and 'C5x devices and related support tools. To obtain a copy of any of these TI documents, call the Texas Instruments Literature Response Center at (800) 477–8924. When ordering, please identify the book by its title and literature number.

TMS320C1x User's Guide (literature number SPRU013) discusses the hardware aspects of the 'C1x generation of CMOS fixed-point digital signal processors. It describes pin assignments, architecture, instruction set, and software and hardware applications. This book also features a section with analog interface peripherals and applications for the 'C1x DSPs, and includes a consolidated data sheet with electrical specifications and package information for all 'C1x devices.

TMS320C2x User's Guide (literature number SPRU014) discusses the hardware aspects of the 'C2x fixed-point digital signal processors. It describes pin assignments, architecture, instruction set, and software and hardware applications. It also includes electrical specifications and package mechanical data for all 'C2x devices. The book features a section with a 'C1x-to-'C2x DSP system migration.

TMS320C2xx User's Guide (literature number SPRU127) discusses the hardware aspects of the 'C2xx fixed-point digital signal processors. It describes pin assignments, architecture, instruction set, and software and hardware applications. It also includes electrical specifications and package mechanical data for all 'C2xx devices. The book features a section comparing instructions from 'C2x to 'C2xx.

TMS320C5x User's Guide (literature number SPRU056) describes the TMS320C5x 16-bit, fixed-point, general-purpose digital signal processors. Covered are its architecture, internal register structure, instruction set, pipeline, specifications, DMA, and I/O ports. Software applications are covered in a dedicated chapter.

TMS320C2x/C2xx/C5x Optimizing C Compiler User's Guide (literature number SPRU024) describes the 'C2x/'C2xx/C5x C compiler. This C compiler accepts ANSI standard C source code and produces TMS320 assembly language source code for the 'C2x, 'C2xx, and 'C5x generations of devices.

TMS320 Family Development Support Reference Guide (literature number SPRU011) describes the '320 family of digital signal processors and covers the various products that support this product line. This includes code-generation tools (compilers, assemblers, linkers, etc.) and system integration and debug tools (simulators, emulators, evaluation modules, etc.). Also covered are available documentation, seminars, the university program, and factory repair and exchange.

TMS320 Third-Party Support Reference Guide (literature number SPRU052) alphabetically lists over 100 third parties that provided various products that serve the family of '320 digital signal processors. A myriad of products and applications are offered—software and hardware development tools, speech recognition, image processing, noise cancellation, modems, etc.

***Digital Signal Processing Applications with the TMS320 Family,* Volumes 1, 2, and 3** (literature numbers SPRA012, SPRA016, SPRA017) Volumes 1 and 2 cover applications using the 'C10 and 'C20 families of fixed-point processors. Volume 3 documents applications using both fixed-point processors as well as the 'C30 floating-point processor.

TMS320C2x C Source Debugger User's Guide (literature number SPRU070) tells how to invoke the debugger with the TMS320C2x simulator version of the C source debugger interface. This book discusses various aspects of the debugger interface, including window management, command entry, code execution, data management, and breakpoints, and includes a tutorial that introduces basic debugger functionality.

TMS320C5x C Source Debugger User's Guide (literature number SPRU055) tells you how to invoke the 'C5x emulator, EVM, and simulator versions of the C source debugger interface. This book discusses various aspects of the debugger interface, including window management, command entry, code execution, data management, and breakpoints, and includes a tutorial that introduces basic debugger functionality.

If You Need Assistance. . .

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Introduction

The TMS320C1x/C2x/C2xx/C5x fixed-point DSPs are supported by the following assembly language tools:

❏ Assembler
❏ Archiver
❏ Linker
❏ Absolute lister
❏ Cross-reference lister
❏ Hex conversion utility

This chapter shows how these tools fit into the general software tools development flow and gives a brief description of each tool. For convenience, it also summarizes the C compiler and debugging tools; however, the compiler and debugger are not shipped with the assembly language tools. For detailed information on the compiler and debugger and for complete descriptions of the TMS320C1x/C2x/C2xx/C5x devices, refer to books listed in *Related Documentation From Texas Instruments* on page vi.

The assembly language tools create and use object files in common object file format (COFF) to facilitate modular programming. Object files contain separate blocks (called sections) of code and data that you can load into TMS320 memory spaces. You can program the TMS320 devices more efficiently if you have a basic understanding of COFF. Chapter 2, *Introduction to Common Object File Format*, discusses this object format in detail.

1.1 Tools Overview and Development Flow

Figure 1–1 shows the assembly language development flow. The shaded portion highlights the most common development path; the other portions are optional.

Figure 1–1. TMS320C1x/C2x/C2xx/C5x Assembly Language Development Flow
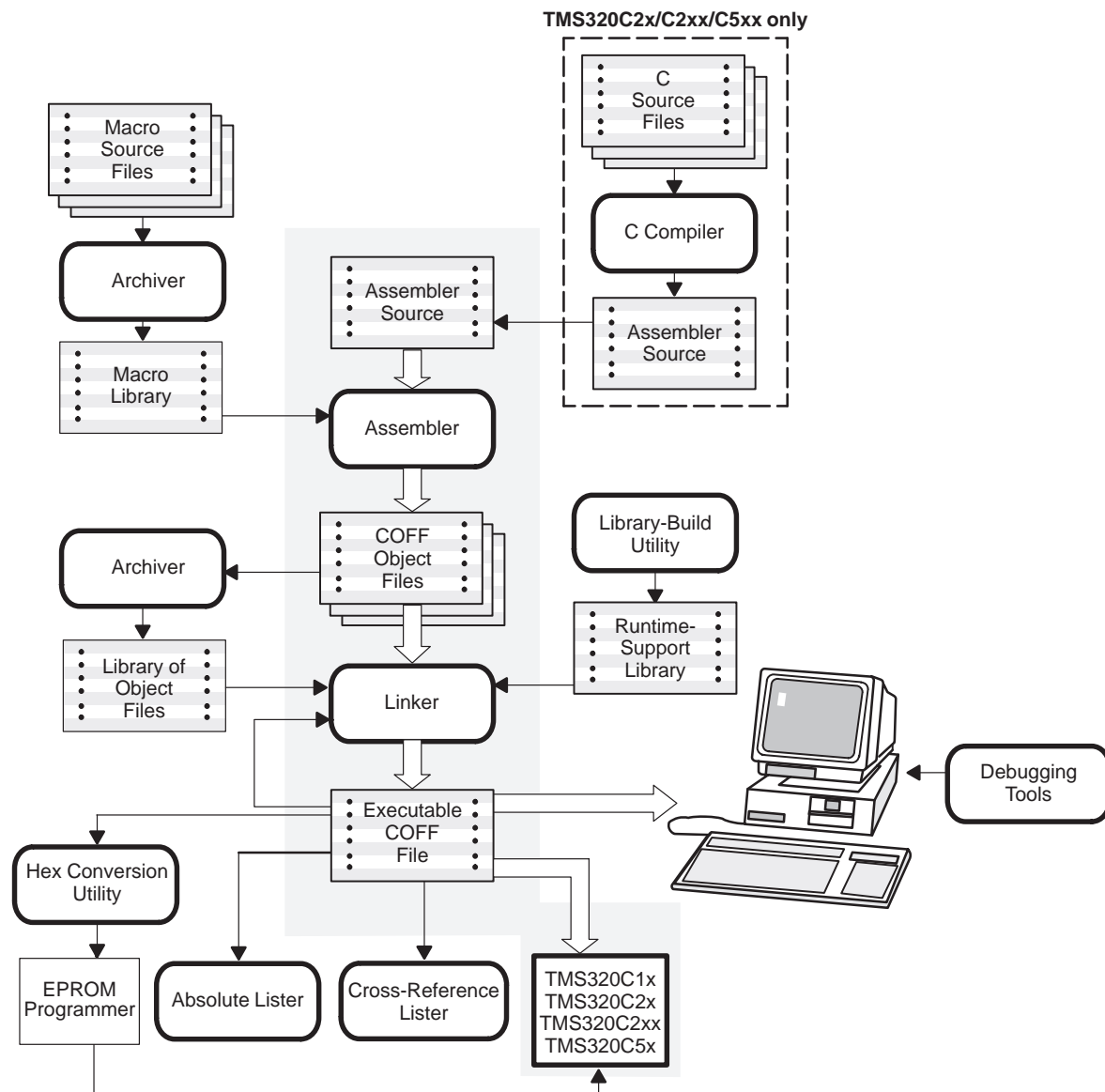
1.2 Tools Descriptions

❏ The **TMS320C2x/C2xx/C5x C compiler** translates C source code into TMS320C2x/C2xx/C5x assembly language source code. The C compiler is not shipped with the assembly language tools package.

❏ The **assembler** translates assembly language source files into machine language COFF object files. Source files can contain instructions, assembler directives, and macro directives. You can use assembler directives to control various aspects of the assembly process, such as the source listing format, data alignment, and section content.

❏ The **archiver** allows you to collect a group of files into a single archive file. For example, you can collect several macros into a macro library. The assembler will search the library and use the members that are called as macros by the source file. You can also use the archiver to collect a group of object files into an object library. The linker will include in the library the members that resolve external references during the link.

❏ The **linker** combines object files into a single executable COFF object module. As it creates the executable module, it performs relocation and resolves external references. The linker accepts relocatable COFF object files (created by the assembler) as input. It also accepts archiver library members and output modules created by a previous linker run. Linker directives allow you to combine object file sections, bind sections or symbols to addresses or within memory ranges, and define or redefine global symbols.

❏ The **absolute lister** generates a file that can be reassembled to produce a listing of the absolute addresses of an object file.

❏ The **cross-reference lister** uses object files to produce a cross-reference listing showing symbols, their definition, and their references in the linked source files.

❏ The TMS320C1x/C2x/C2xx/C5x debugging tools accept COFF files as input, but most EPROM programmers do not. The **hex conversion utility** converts a COFF object file into TI-Tagged, Intel, Motorola, or Tektronix object format. The converted file can be downloaded to an EPROM programmer.

❏ Table 1–1 lists debugging tools that you can use on various systems to refine and correct your code before you download it.

Table 1–1. Fixed-Point Debugging Support on Various Systems

Debugging Tools	'C1x	'C2x	'C2xx	'C5x
Simulator	PC	PC	PC	PC
		SPARC	SPARC	SPARC
Evaluation Module	PC	PC	PC	PC
		SPARC	SPARC	SPARC
Emulator	PC	PC	PC	PC
			SPARC	SPARC

Note: PC running under MS-DOS or OS/2.
SPARC running under UNIX.

Introduction to
Common Object File Format

The assembler and linker create object files that can be executed by a TMS320C1x/C2x/C2xx/C5x The format of these object files is called common object file format, or COFF.

COFF makes modular programming easier because it encourages you to think in terms of blocks of code and data when you write an assembly language program. These blocks are known as sections. Both the assembler and the linker provide directives that allow you to create and manipulate sections.

This chapter provides an overview of COFF sections and includes the following topics:

For additional information, see Appendix A, which details COFF object file structure.

2.1 Sections

The smallest unit of an object file is called a **section**. A section is a block of code or data that will ultimately occupy contiguous space in the memory map. Each section of an object file is separate and distinct. COFF object files always contain three default sections:

.text section	usually contains executable code.
.data section	usually contains initialized data.
.bss section	usually reserves space for uninitialized variables.

In addition, the assembler and linker allow you to create, name, and link **named** sections that are used like the .data, .text, and .bss sections.

There are two basic types of sections:

Initialized sections   contain data or code. The .text and .data sections are initialized; named sections created with the .sect assembler directive are also initialized.

Uninitialized sections   reserve space in the memory map for uninitialized data. The .bss section is uninitialized; named sections created with the .usect assembler directive are also uninitialized.

Several assembler directives allow you to associate various portions of code and data with the appropriate sections. The assembler builds these sections during the assembly process, creating an object file organized as shown in Figure 2–1.

One of the linker's functions is to relocate sections into the target memory map; this function is called **allocation**. Because most systems contain several types of memory, using sections can help you use target memory more efficiently. All sections are independently relocatable; you can place any section into any allocated block of target memory. For example, you can define a section that contains an initialization routine and then allocate the routine into a portion of the memory map that contains EPROM.

Figure 2–1 shows the relationship between sections in an object file and a hypothetical target memory.

Figure 2–1. Partitioning Memory Into Logical Blocks

Initialized Program Memory   **Object File**   **Uninitialized Data Memory**

on-chip ROM	.data
on-chip ROM	.text
	.bss

on-chip RAM
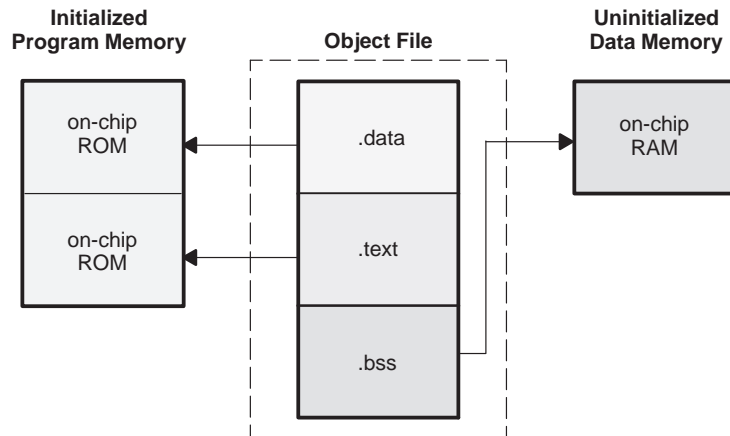
2.2 How the Assembler Handles Sections

The assembler identifies the portions of an assembly language program that belong in a section. The assembler has six directives that support this function:

- ❑ **.bss**
- ❑ **.usect**
- ❑ **.text**
- ❑ **.data**
- ❑ **.sect**
- ❑ **.asect**

The .bss and .usect directives create *uninitialized sections*; the .text, .data, .sect, and .asect directives create *initialized* sections.

Note: Default Section Directive

If you don't use any of the sections directives, the assembler assembles everything into the .text section.

2.2.1 Uninitialized Sections

Uninitialized sections reserve space in TMS320 memory; they are usually allocated into RAM. These sections have no actual contents in the object file; they simply reserve memory. A program can use this space at runtime for creating and storing variables.

Uninitialized data areas are built by using the .bss and .usect assembler directives. The .bss directive reserves space in the .bss section. The .usect directive reserves space in a specific uninitialized named section. Each time you invoke the .bss directive, the assembler reserves more space in the .bss section. Each time you invoke the .usect directive, the assembler reserves more space in the specified named section.

The syntax for these directives is:

> **.bss** *symbol, size in words* [*blocking flag*]
>
> *symbol* **.usect** "*section name", size in words,* [*blocking flag*]

symbol   points to the first byte reserved by this invocation of the .bss or .usect directive. The *symbol* corresponds to the name of the variable that you're reserving space for. It can be referenced by any other section and can also be declared as a global symbol (with the .global assembler directive).

size in words   is an absolute expression. The .bss directive reserves *size* words in the .bss section; the .usect directive reserves *size* words in *section name*.

blocking flag   is an optional parameter. If you specify a value greater than 0 for this parameter, the assembler associates size words contiguously; the allocated space will not cross a page boundary, unless size is greater than a page, in which case the object will start on a page boundary.

section name   tells the assembler which named section to reserve space in. For more information about named sections, refer to subsection 2.2.3.

The .text, .data, .sect, and .asect directives tell the assembler to stop assembling into the current section and begin assembling into the indicated section. The .bss and .usect directives, however, *do not* end the current section and begin a new one; they simply "escape" from the current section temporarily. The .bss and .usect directives can appear anywhere in an initialized section without affecting its contents.

2.2.2 Initialized Sections

Initialized sections contain executable code or initialized data. The contents of these sections are stored in the object file and placed in TMS320 memory when the program is loaded. Each initialized section is separately relocatable and may reference symbols that are defined in other sections. The linker automatically resolves these section-relative references.

Four directives tell the assembler to place code or data into a section. The syntaxes for these directives are:

> **.text**
>
> **.data**
>
> **.sect** *"section name"*
>
> **.asect** *"section name"* , *address*

When the assembler encounters one of these directives, it stops assembling into the current section (acting as an implied "end current section" command). It then assembles subsequent code into the designated section until it encounters another .text, .data, .sect, or .asect directive.

Sections are built through an iterative process. For example, when the assembler first encounters a .data directive, the .data section is empty. The statements following this first .data directive are assembled into the .data section (until the assembler encounters a .text, .sect, or .asect directive). If the assembler encounters subsequent .data directives, it adds the statements following these .data directives to the statements already in the .data section. This creates a single .data section that can be allocated contiguously into memory.

2.2.3 Named Sections

Named sections are sections that *you* create. You can use them like the default .text, .data, and .bss sections, but they are assembled separately.

For example, repeated use of the .text directive builds up a single .text section in the object file. When linked, this .text section is allocated into memory as a single unit. Suppose there is a portion of executable code (perhaps an initialization routine) that you don't want allocated with .text. If you assemble this segment of code into a named section, it will be assembled separately from .text, and you will be able to allocate it into memory separately. You can also assemble initialized data that is separate from the .data section, and you can reserve space for uninitialized variables that is separate from the .bss section.

Three directives let you create named sections:

❑ The **.usect** directive creates sections that are used like the .bss section. These sections reserve space in RAM for variables.

❑ The **.sect** and **.asect** directives create sections, like the default .text and .data sections, that can contain code or data. The .sect directive creates named sections with relocatable addresses; the .asect directive creates named sections with absolute addresses.

The syntaxes for these directives are:

symbol **.usect** *"section name", size in words,* [*blocking flag*]

       .sect *"section name"*

       .asect *"section name" , address*

The *section name* parameter is the name of the section. Section names are significant to 8 characters. You can create up to 32,767 separate named sections.

Each time you invoke one of these directives with a new name, you create a new named section. Each time you invoke one of these directives with a name that was already used, the assembler assembles code or data (or reserves space) into the section with that name. *You cannot use the same names with different directives.* That is, you cannot create a section with the .usect directive and then try to use the same section with .sect.

The .asect *address* identifies the section's absolute starting address in target memory. This address is required the first time that you assemble into a specific absolute section. If you use .asect to continue assembling into an absolute section that already contains code, you *cannot* use the address parameter.

2.2.4 Section Program Counters

The assembler maintains a separate program counter for each section. These program counters are known as *section program counters*, or **SPC**s.

An SPC represents the current address within a section of code or data. Initially, the assembler sets each SPC to 0. As the assembler fills a section with code or data, it increments the appropriate SPC. If you resume assembling into a section, the assembler remembers the appropriate SPC's previous value and continues incrementing the SPC at that point.

The assembler treats each section as if it began at address 0. The linker relocates each section according to its final location in the memory map.

2.2.5 Absolute Sections

The .asect directive defines a named section whose addresses are absolute with respect to a specified address. Absolute sections are useful for loading code from off-chip memory into faster on-chip memory.

Note: The .asect Directive Is Obsolete

The .asect directive is obsolete because the linker's SECTIONS directive now allows separate load and run addresses for any section; however, the .asect directive is fully functional to allow compatibility with previous versions of the assembler. For more information, refer to Section 8.7, page 8-24.

2.2.6 An Example That Uses Sections Directives

Figure 2–1 shows how you can build COFF sections incrementally, using the sections directives to swap back and forth between the different sections. You can use sections directives to begin assembling into a section for the first time, or to continue assembling into a section that already contains code. In the latter case, the assembler simply appends the new code to the code that is already in the section.

The format in Example 2–1 is a listing file. Example 2–1 shows how the SPCs are modified during assembly. A line in a listing file has four fields:

Field 1   contains the source code line counter.
Field 2   contains the section program counter.
Field 3   contains the object code.
Field 4   contains the original source statement.

Example 2–1.Using Sections Directives

```
   1
   2           ************************************************
   3           **  assemble an initialized table into .data  **
   4           ************************************************
   5 0000               .data
   6 0000 0011  coeff   .word   011h, 022h, 033h
     0001 0022
     0002 0033
   7           ************************************************
   8           ** reserve space in .bss for two variables    **
   9           ************************************************
  10 0000               .bss    var1, 1
  11 0001               .bss    buffer, 10
  12           ************************************************
  13           **   still in data                            **
  14           ************************************************
  15 0003 0123  ptr     .word   0123h
  16           ************************************************
  17           ** assemble code into .text section           **
  18           ************************************************
  19 0000               .text
  20 0000 200f  add:    LAC     0Fh
  21 0001 d003  aloop:  SBLK    1
     0002 0001
  22 0003 f280          BLEZ    aloop
     0004 0001'
  23 0005 6000–         SACL    var1, 0
  24           ************************************************
  25           **  assemble another initialized table into   **
  26           **  the .data section                         **
  27           ************************************************
  28 0004               .data
  29 0004 00aa  ivals   .word   0AAh, 0BBh
     0005 00bb
  30           ************************************************
  31           **  define the named section ''newvars''      **
  32           ************************************************
  33 0000      var2    .usect  "newvars", 1
  34 0001      inbuf   .usect  "newvars", 7
  35           ************************************************
  36           **  assemble more code into .text             **
  37           ************************************************
  38 0006               .text
  39 0006 ccff          ADD #0FFh
```

Field 1 Field 2 Field 3   Field 4

As Figure 2–2 shows, the file in Example 2–1 creates four sections:

.text	contains 7 words of object code.
.data	contains 5 words of object code.
.bss	reserves 11 words in memory.
newvars	is a named section created with the .usect directive; it reserves 8 words in memory.

The second column shows the object code that is assembled into these sections; the third column shows the source statements that generated the object code.

Figure 2–2. Object Code Generated by the Listing in Example 2–1

Line Numbers	Object Code	Section
20	200F	.text
21	D003	
21	0001	
22	F280	
22	0001	
23	6000	
39	CCFF	
6	0011	.data
6	0022	
6	0033	
29	00AA	
29	00BB	
10	No data—	.bss
11	11 words reserved	
33	No data—	newvars
34	8 words reserved	

2.3 How the Linker Handles Sections

The linker has two main functions in regard to sections. First, the linker uses the sections in COFF object files as building blocks; it combines input sections (when more than one file is being linked) to create output sections in an executable COFF output module. Second, the linker chooses memory addresses for the output sections.

Two linker directives support these functions:

❑ The **MEMORY directive** allows you to define the memory map of a target system. You can name portions of memory and specify their starting addresses and their lengths.

❑ The **SECTIONS directive** tells the linker how to combine input sections and where to place the output sections in memory.

It is not always necessary to use linker directives. If you don't use them, the linker uses the target processor's default allocation algorithm described in subsection 2.3.1. When you *do* use linker directives, you must specify them in a linker command file.

Refer to the following sections for more information about linker command files and linker directives:

Section   **Page**

Note that the linker refers to program memory as PAGE 0 and to data memory as PAGE 1; these pages are separate from and should not be confused with the data page memory format of the TMS320C1x/C2x/C2xx/C5x devices.

Note: Examples in This Section Are for the TMS320C25

Section allocation is based on the configuration of target memory. The examples in this section illustrate this concept using the TMS320C25 as the target processor. Each processor has its own programmable memory configuration.

2.3.1 Default Memory Allocation

You can link files without specifying a MEMORY or SECTIONS directive. The linker uses a default model to combine sections (if necessary) and allocate them into memory. When using the default model, the linker:

1) Reads the object file to determine the correct target processor.

2) Assuming the target processor is the TMS320C25, the following memory locations are available:

   ❏ Program memory

     External locations   1000h–0FEFFh

   ❏ Data memory

     On-chip locations   300h–3FFh   (on-chip block B1)

     External locations   400h–0FFFFh

3) Allocates .text into program memory, beginning at address 1000h.

4) Allocates .data into program memory, immediately following .text.

5) Allocates any *initialized* named sections into program memory, immediately following .data. Named sections are allocated in the order that the linker encounters them in the input files.

6) Allocates .bss into data memory, beginning at address 300h.

7) Allocates any *uninitialized* named sections into data memory, immediately following .bss. Named sections are allocated in the order that the linker encounters them in the input files.

Figure 2–3 shows how a single file would be allocated into memory using default allocation for the TMS320C25. Note that the linker does not actually place object code into memory; it assigns addresses to sections so that a loader can place the code in memory.

For information about the default allocation for the TMS320C1x, TMS320C2x, TMS320C2xx, and TMS320C5x, refer to Section 8.11, page 8-45.

Figure 2–3. Default Allocation for the Object Code in Figure 2–2
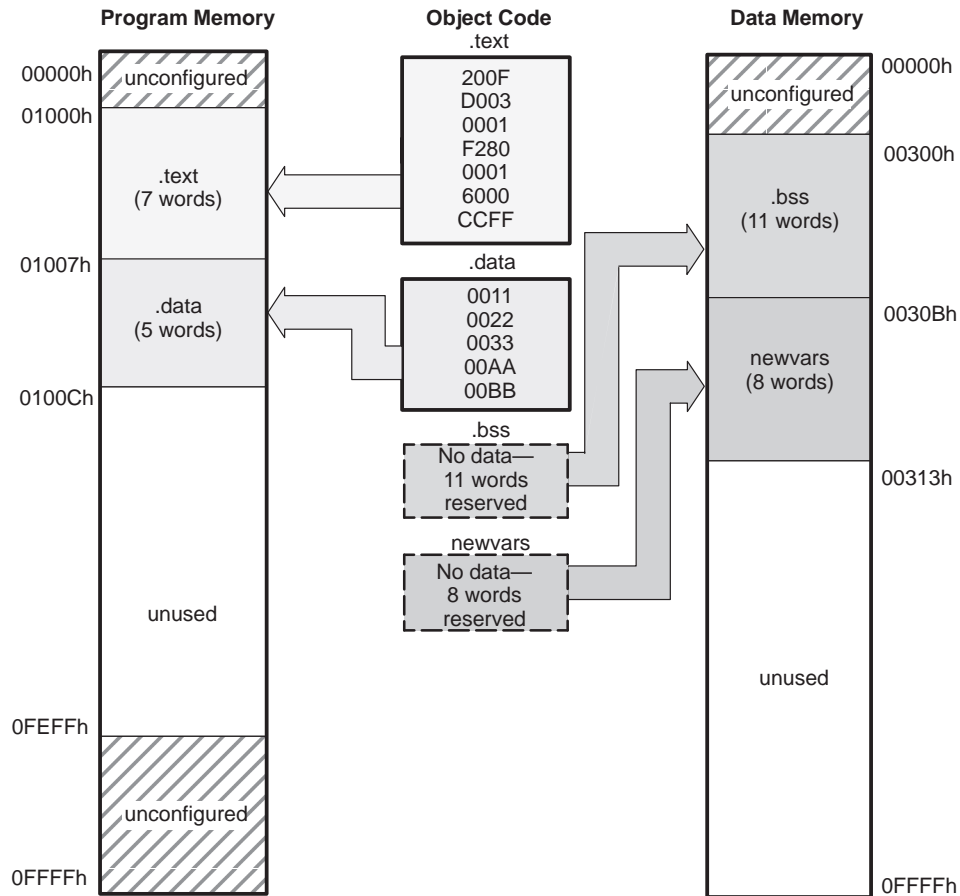
As Figure 2–3 shows, the linker:

1) Allocates the .text section first, beginning at address 1000h in program memory. The .text section contains 7 words of object code.

2) Allocates the .data section next, beginning at address 1007h in program memory The .data section contains 5 words of object code.

3) Allocates the .bss section, beginning at address 300h in data memory. The .bss section reserves 11 words in memory.

4) Allocates the uninitialized named section newvars at address 30Bh in data memory. The newvars section reserves 8 words in memory.

Note that the space in address range 0100Ch–0FFFFh in program memory and 0313h–0FFFFh in data memory is not used.

Figure 2–4 shows a simple example of how two files would be linked together. When you link several files by using the default algorithm, the linker combines all input sections that have the same name into one output section that has this same name. For example, the linker combines the .text sections from two input files to create one .text output section.

Figure 2–4. Combining Input Sections From Two Files (Default Allocation)
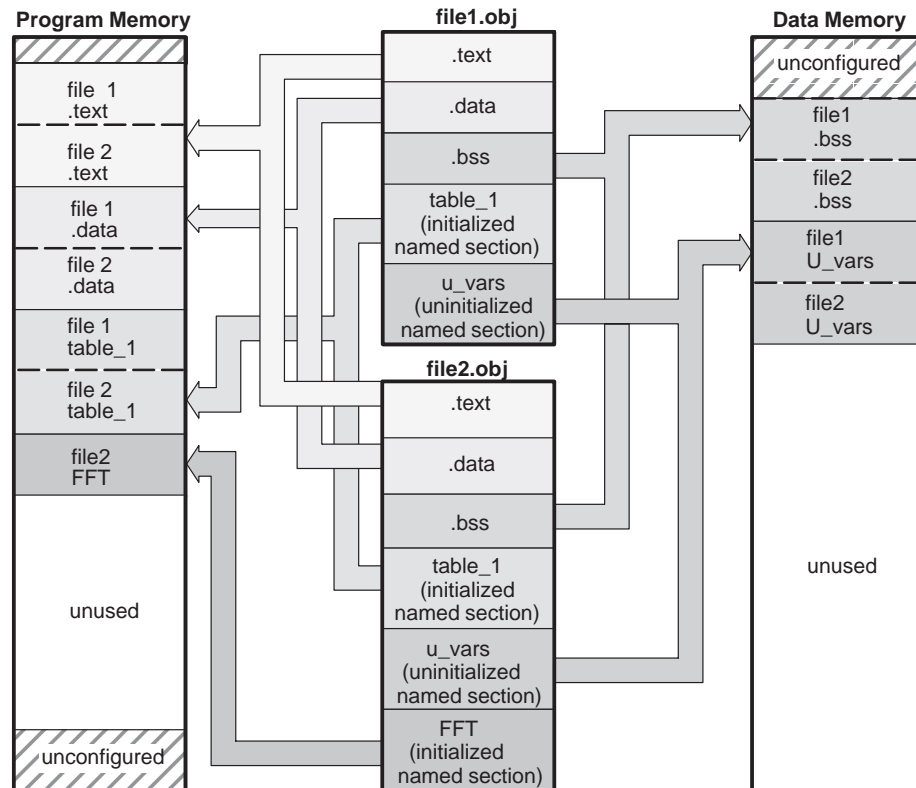
In Figure 2–4, file1.obj and file2.obj each contain the .text, .data, and .bss default sections; an initialized named section called Table_1; and an uninitialized named section called U_vars. file2.obj also contains an initialized named section called FFT. As Figure 2–4 shows, the linker:

1) Combines file1 .text with file2 .text to form one .text output section. The .text output section is allocated at address 1000h in program memory.

2) Combines file1 .data with file2 .data to form the .data output section. The .data output section is allocated into program memory following the .text output section.

3) Combines file1 table_1 with file2 table_1 to form the table_1 output sec-
    tion. The table_1 section is the first initialized named section that the linker
    encounters, so it is allocated before the second initialized named section,
    FFT. The table_1 output section is allocated into program memory follow-
    ing the .data output section.

4) Allocates the FFT section from file2 after the table_1 section.

5) Combines file1 .bss with file2 .bss to form the .bss output section. The .bss
    output section is allocated at address 300h in data memory.

6) Combines file1 U_vars with file2 U_vars to form the U_vars output section.
    The U_vars output section is allocated into data memory following the .bss
    output section.

For more information about default allocation algorithms, refer to Section
8.11, page 8-45.

2.3.2 Placing Sections in the Memory Map

Figure 2–3 and Figure 2–4 illustrate the linker's default methods for combining
sections and allocating them into memory. Sometimes you may not want to
use the default setup. For example, you may not want to combine all of the
.data sections into a single .data output section. Or, you might want to place
a named section instead of the .text section at program memory address
1000h. Most memory maps contain various types of memories (DRAM, ROM,
EPROM, etc.) in varying amounts; you may want to place a section in a type
of memory.

The next illustrations show another possible combination of the sections from
Figure 2–3. Assume that a CNFD instruction defined block B0 as data memory
and that microcomputer mode is selected (MP/$\overline{MC}$=0).

Example 2–2 contains TMS320C25 MEMORY and SECTIONS definitions.
Figure 2–5 shows how the ranges defined in Example 2–2 fit into the
TMS320C25 memory map, and
Figure 2–6 shows how the sections from Figure 2–3 are allocated into the
memory map.

For examples of linker command files for the TMS320C10, TMS320C25, and
TMS320C50 in other modes, refer to Appendix C.

Example 2–2.TMS320C25 MEMORY and SECTIONS Directives

```
MEMORY
{                                       /* Program Memory */
   PAGE 0 : VECS:  origin =   0h,  length = 020h
            CODE:  origin = 020h,  length = 0F90h
                                        /* Data Memory    */
   PAGE 1 : RAMB2: origin = 060h,  length = 020h
            RAMB0: origin = 200h,  length = 100h
            RAMB1: origin = 300h,  length = 100h
}

SECTIONS
{
   vectors:               >   000000h
   .text:                 >   CODE

   .data:                 >   RAMB2
   .bss:                  >   RAMB0
   newvars:               >   RAMB1
}
```

❑   The MEMORY directive in Example 2–2 defines five memory ranges:

VECS	CODE
RAMB2	RAMB0
RAMB1	

The PAGE option identifies the type of memory that the range occupies. PAGE 0 identifies program memory, and PAGE 1 identifies data memory. The origin for each of these ranges identifies the range's starting address in memory. The length specifies the length of the range.

For example, memory range RAMB0 on PAGE 1 has a starting address of 200h and a length of 100h; it defines the addresses 0200h through 02FFh in data memory.

Note that this MEMORY definition does not define the following ranges:

■   0FB0h–0FFFFh in program memory
■   0h–05Fh in data memory
■   080h–01FFh in data memory
■   0400h–0FFFFh in data memory

These undefined ranges are **unconfigured**. As far as the linker is concerned, these areas do not exist, and no code or data can be loaded into them. Whenever you use the MEMORY directive, only the memory ranges that the directive defines can contain code or data.

❑ The SECTIONS directive in Example 2–2 defines the order in which the sections are allocated into memory. The vectors section must begin at address 0 in program memory; .text is allocated into the CODE range in program memory. The .data section is allocated into the RAMB2 range in data memory, .bss is allocated into RAMB0 in data memory, and newvars is allocated into RAMB1 in data memory.

Figure 2–5. Memory Map Defined by Example 2–2
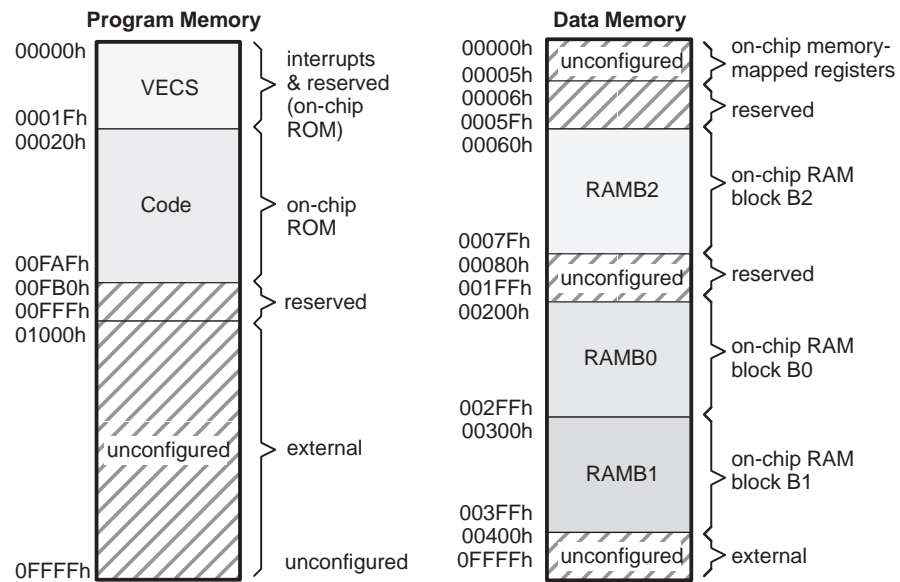
Figure 2–5 shows how the ranges defined by the MEMORY directive in Example 2–2 fit into the memory map.

❑ In program memory, the VECS range occupies the addresses that are usually used for interrupts. The CODE range occupies the on-chip ROM area. The reserved and external memory locations are unconfigured.

❑ In data memory, the RAMB2 range occupies the addresses used by on-chip RAM block B2, RAMB0 occupies block B0, and RAMB1 occupies block B1. The on-chip memory-mapped registers and the reserved and external memory locations are unconfigured.

Figure 2–6. Allocating the Sections With the Linker
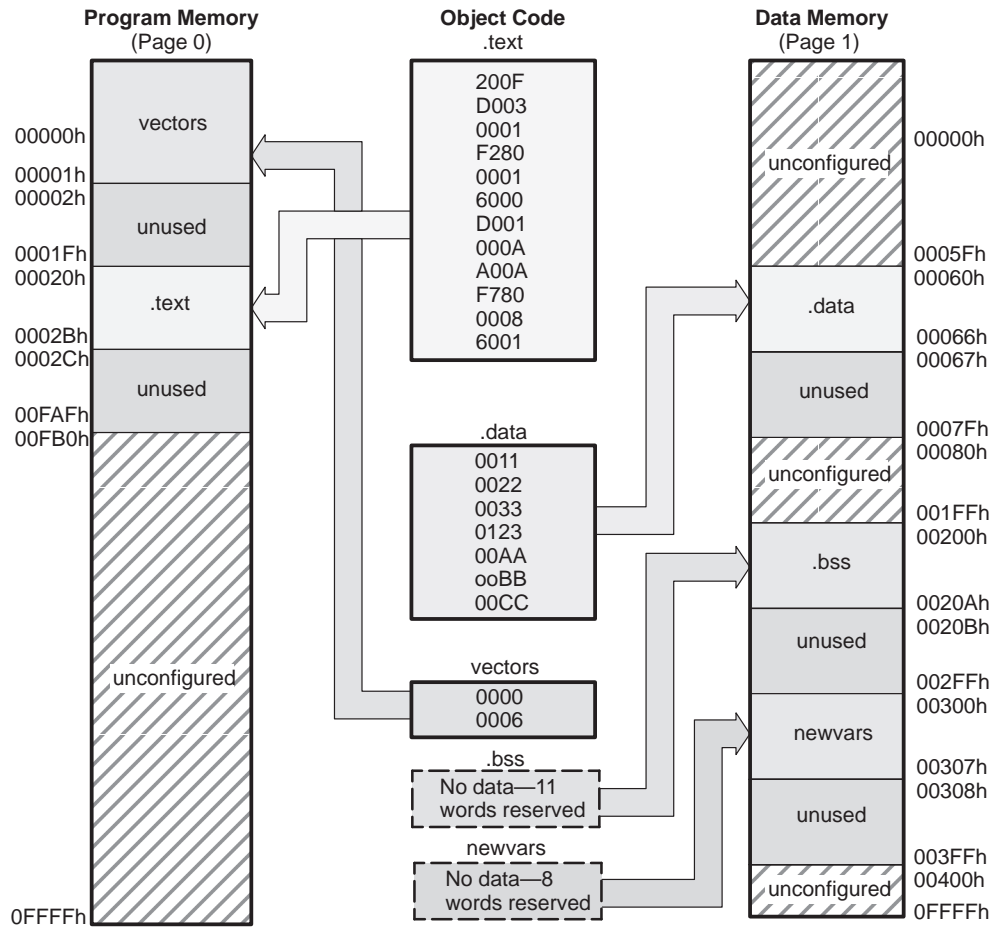
Figure 2–6 shows how the sections are allocated into the memory ranges defined in Example 2–2. Note that some of the memory is configured but unused. For example, the .text section is allocated into the CODE area. The length of the CODE range is 0F90h words; however, the .text section contains only 12 words. Thus, locations 02Ch–0FAFh are unused.

2.4   Relocation

The assembler treats each section as if it began at address 0. All relocatable symbols (labels) are relative to address 0 in their sections. Of course, all sections can't actually begin at address 0 in memory, so the linker **relocates** sections by:

❑   Allocating them into the memory map so that they begin at the appropriate address

❑   Adjusting symbol values to correspond to the new section addresses

❑   Adjusting references to relocated symbols to reflect the adjusted symbol values

The linker uses *relocation entries* to adjust references to symbol values. The assembler creates a relocation entry each time a relocatable symbol is referenced. The linker then uses these entries to patch the references after the symbols are relocated. Example 2–3 contains a code segment for the TMS320C25 that generates relocation entries.

Example 2–3. Code That Generates Relocation Entries

```
1                     .ref    X
2    0000             .text
3    0000  FF80       B       X  ; Generates a relocation entry
     0001  0000!
4    0002  D001       LALK    Y  ; Generates a relocation entry
     0003  0004′
5    0004  CE1F   Y:  IDLE
```

In Example 2–3, both symbols X and Y are relocatable. Y is defined in the .text section of this module; X is defined in another module. When the code is assembled, X has a value of 0 (the assembler assumes all undefined external symbols have values of 0), and Y has a value of 4 (relative to address 0 in the .text section). The assembler generates two relocation entries, one for X and one for Y. The reference to X is an external reference (indicated by the ! character in the listing). The reference to Y is to an internally defined relocatable symbol (indicated by the ′ character in the listing).

After the code is linked, suppose that X is relocated to address 0x0100. Suppose also that the .text section is relocated to begin at address 0x0200; Y now has a relocated value of 0x0204. The linker uses the two relocation entries to patch the two references in the object code:

```
FF80    B    X     becomes    FF80
0000                           0100
D001    LALK Y     becomes    D001
0004                           0204
```

Each section in a COFF object file has a table of relocation entries. The table contains one relocation entry for each relocatable reference in the section. The linker usually removes relocation entries after it uses them. This prevents the output file from being relocated again (if it is relinked or when it is loaded). A file that contains no relocation entries is an *absolute file* (all its addresses are absolute addresses). If you want the linker to retain relocation entries, invoke the linker with the –r option.

2.5   Runtime Relocation

At times you may want to load code into one area of memory and run it in another. For example, you may have performance-critical code in a ROM-based system. The code must be loaded into ROM but would run faster in RAM.

The linker provides a simple way to specify this. Using the SECTIONS directive, you can optionally direct the linker to allocate a section twice: once to set its load address, and again to set its run address. Use the *load* keyword for the load address and the *run* keyword for the run address.

The load address determines where a loader will place the raw data for the section. Any references to the section (such as labels in it) refer to its run address. The application must copy the section from its load address to its run address; this does *not* happen automatically simply because you specify a separate run address. For an example that illustrates how to move a block of code at runtime, see Example 8–7, page 8-35.

If you provide only one allocation (either load or run) for a section, the section is allocated only once and will load and run at the same address. If you provide both allocations, the section is actually allocated as if it were two separate sections of the same size.

Uninitialized sections (such as .bss) are not loaded, so the only significant address is the run address. The linker allocates uninitialized sections only once: if you specify both run and load addresses, the linker warns you and ignores the load address.

For a complete description of runtime relocation, see Section 8.8, page 8-33.

2.6 Loading a Program

The linker produces executable COFF object modules. An executable object file has the same COFF format as object files that are used as linker input; the sections in an executable object file, however, are combined and relocated into target memory.

To run a program, the data in the executable object module must be transferred, or *loaded*, into target system memory. Several methods can be used for loading a program, depending on the execution environment. Three common methods are described below.

❏ The TMS320C1x/C2x/C2xx/C5x debugging tools, including the software simulator, XDS emulator, and software development system, have built-in loaders. Each of these tools has a LOAD command that invokes a loader; the loader reads the executable file and copies the program into target memory.

❏ You can use the hex conversion utility (the dsphex, which is shipped as part of the assembly language package) to convert the executable COFF object module into one of several object file formats. You can then use the converted file with an EPROM programmer to burn the program into an EPROM.

❏ Some TMS320C1x/C2x/C2xx/C5x programs are loaded under the control of an operating system or monitor software running directly on the target system. In this type of application, the target system usually has an interface to the file system on which the executable module is stored. You must write a custom loader for this type of system. Refer to Appendix A for supplementary information about the internal format of COFF object files. The loader must comprehend the file system (in order to access the file) and the memory organization of the target system (to load the program into memory).

2.7 Symbols in a COFF File

A COFF file contains a symbol table that stores information about symbols in the program. The linker uses this table when it performs relocation. Debugging tools can also use the symbol table to provide symbolic debugging.

2.7.1 External Symbols

External symbols are symbols that are defined in one module and referenced in another module. You can use the **.def, .ref**, or **.global** directives to identify symbols as external:

Defined (.def)   Defined in the current module and used in another module

Referenced (.ref)   Referenced in the current module, but defined in another module

Global (.global)   May be either of the above

The following code segment illustrates these definitions.

```
x:      ADD       056h     ;  Define x
        MPY       y        ;  Reference y
        .global   x        ;  DEF of x
        .global   y        ;  REF of y
```

The .global definition of x says that it is an external symbol defined in this module and that other modules can reference x. The .global definition of y says that it is an undefined symbol that is defined in another module.

The assembler places both x and y in the object file's symbol table. When the file is linked with other object files, the entry for x defines unresolved references to x from other files. The entry for y causes the linker to look through the symbol tables of other files for y's definition.

The linker must match all references with corresponding definitions. If the linker cannot find a symbol's definition, it prints an error message about the unresolved reference. This type of error prevents the linker from creating an executable object module.

2.7.2 The Symbol Table

The assembler always generates an entry in the symbol table when it encounters an external symbol (both definitions and references). The assembler also creates special symbols that point to the beginning of each section; the linker uses these symbols to relocate references to other symbols in a section.

The assembler does not usually create symbol table entries for any symbol other than those described above, because the linker does not use them. For example, labels are not included in the symbol table unless they are declared with .global. For symbolic debugging purposes, it is sometimes useful to have entries in the symbol table for each symbol in a program. To accomplish this, invoke the assembler with the –s option.

Assembler Description

The assembler translates assembly language source files into machine language object files. These files are in common object file format (COFF), which is discussed in Chapter 2 and Appendix A. Source files can contain the following assembly language elements:

Assembler directives   described in Chapter 4

Assembly language instructions   described in Chapter 5

Macro directives   described in Chapter 6

3.1 Assembler Overview

The two-pass assembler does the following:

❏ Processes the source statements in a text file to produce a relocatable object file

❏ Produces a source listing (if requested) and provides you with control over this listing

❏ Allows you to segment your code into sections and maintain an SPC (section program counter) for each section of object code

❏ Defines and references global symbols and appends a cross-reference listing to the source listing (if requested)

❏ Assembles conditional blocks

❏ Supports macros, allowing you to define macros inline or in a library

❏ Allows you to assemble TMS320C1x, TMS320C2x, TMS320C2xx, or TMS320C5x code

3.2 Assembler Development Flow

Figure 3–1 illustrates the assembler's role in the assembly language development flow. The assembler accepts assembly language source files as input. The TMS320C1x/C2x/C2xx/C5x assembler also accepts assembly language files created by the TMS320C2x/C2xx/C5x C compiler.

Figure 3–1. Assembler Development Flow
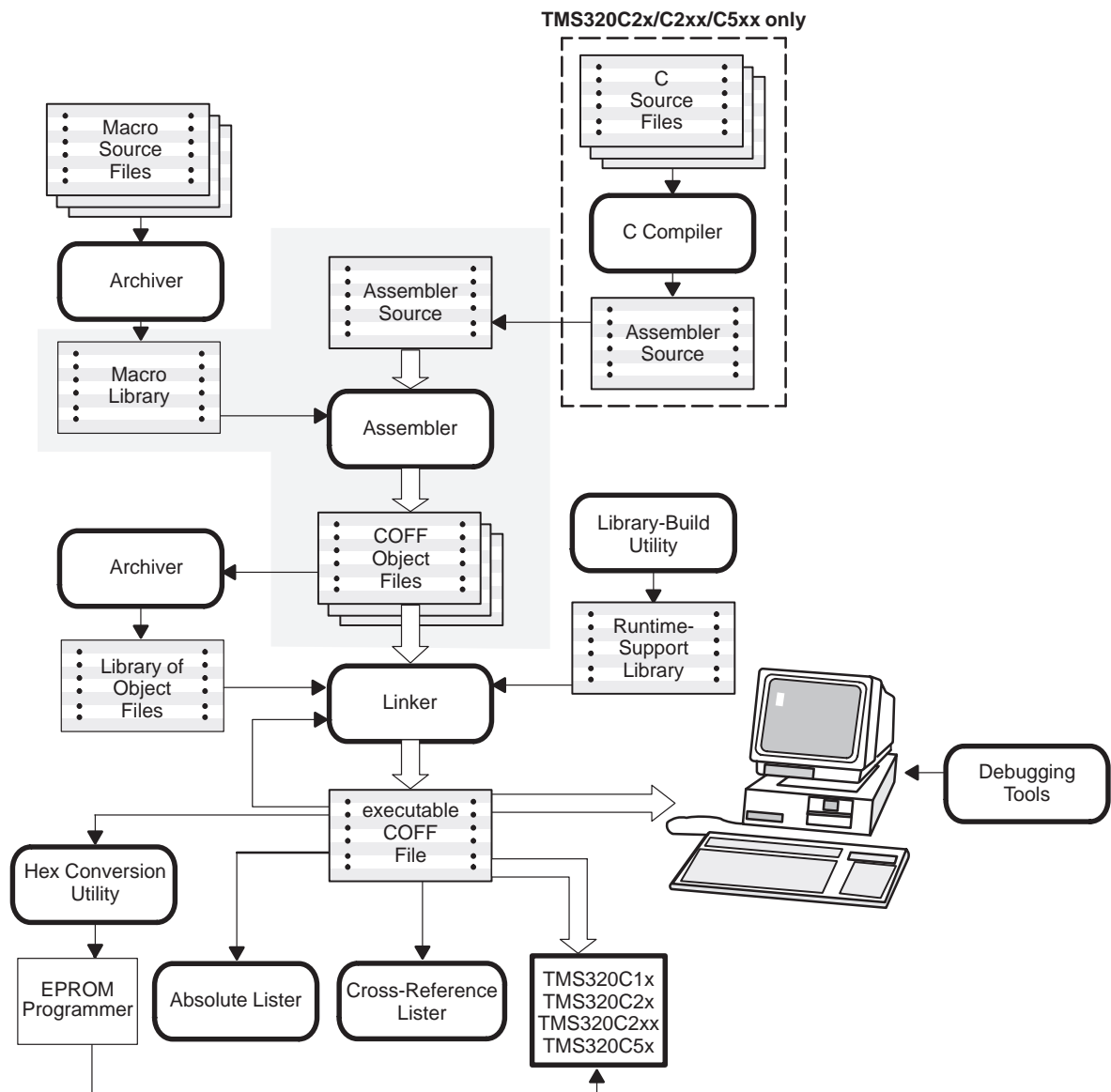
3.3   Invoking the Assembler

To invoke the assembler, enter the following:

dspa   [*input file*   [*object file*   [*listing file*]]]   [*–options*]

dspa   is the command that invokes the assembler.

input file   names the assembly language source file. If you do not supply
                  an extension, the assembler uses the default extension *.asm*. If
                  you do not supply an input filename, the assembler will prompt
                  you for one.

object file   names the object file that the assembler creates. If you do not
                  supply an extension, the assembler uses *.obj* as a default. If you
                  do not supply an object file, the assembler creates a file that uses
                  the input filename with the *.obj* extension.

listing file   names the optional listing file that the assembler can create. If
                  you do not supply a listing filename, *the assembler does not cre-*
                  ate one unless you use the –l (lowercase L) option. In this case,
                  the assembler uses the input filename. If you do not supply an
                  extension, the assembler uses *.lst* as a default.

options   identifies the assembler options that you want to use. Options
                  are not case-sensitive and can appear anywhere on the
                  command line, following the command. Precede each option
                  with a hyphen. Single-letter options without parameters can be
                  combined: for example, –lc is equivalent to –l –c. Options that
                  have parameters, such as –i, must be specified separately.

    –a   creates an absolute listing. When you use –a, the assem-
                  bler does not produce an object file. The –a option is used
                  in conjunction with the absolute lister.

    –c   makes case insignificant in the assembly language files.
                  For example, –c will make the symbols ABC and abc
                  equivalent. *If you do not use this option, case is significant*
                  (default).

    –d   **–d**name [=value] sets the *name* symbol. This is equiva-
                  lent to inserting *name* **.set** [value] at the beginning of the
                  assembly file. If *value* is omitted, the symbol is set to 1. For
                  more information, see subsection 3.9.3, page 3-21.

    –i   specifies a directory where the assembler can find files
                  named by the .copy, .include, or .mlib directives. The for-
                  mat of the –i option is –i*pathname*. You can specify up to
                  10 directories in this manner; each pathname must be
                  preceded by the –i option. For more information, see
                  subsection 3.5.1, page 3-12.

–l   (lowercase L) produces a listing file.

–p   enables the   porting of TMS320C2x code to the TMS320C5x or the TMS320C2xx (see subsection 3.4.1, page 3-6).

–pp   lets you port TMS320C2x code to the TMS320C2xx and defines the .TMS32025 and .TMS3202xx symbols. The –pp option can be used with code that was written using the .TMS32025 and .TMS32050 symbols so that the code compiles for either processor (see subsection 3.4.2, page 3-8).

–q   (quiet) suppresses the banner and all progress infor- mation.

–s   puts all defined symbols in the object file's symbol table. The assembler usually puts only global symbols into the symbol table. When you use –s, symbols defined as la- bels or as assembly-time constants are also placed in the table.

–v   specifies a version. The version tells the assembler which of the following TMS320 devices it should produce code for (the default is –v25):

  –v10 selects the TMS320C1x

  –v16 selects the TMS320C16

  –v20 selects the TMS320C20

  –v25 selects the TMS320C2x

  –v2xx selects the TMS320C2xx

  –v50 selects the TMS320C5x

–w   detects pipeline conflicts in TMS320C5x code. This is ba- sically a warning switch. This option is valid for the TMS320C5x only. For more information, see subsection 3.4.3.

–x   produces a cross-reference table and appends it to the end of the listing file; also adds cross-reference informa- tion to the object file for use by the cross-reference utility. If you do not request a listing file, the assembler creates one anyway.

3.4   Upward Compatibility Within the TMS320C1x/C2x/C2xx/C5x Processors

The TMS320C1x/C2x/C2xx/C5x fixed-point processors are upwardly source code compatible. For example, code originally written for the TMS320C10 can be assembled for the TMS320C25 with –v25 assembler option. The –v option is explained in detail on page 3-5.

All of the processors are capable of handling upwardly ported code as long as the target processor's number is the same as or greater than the original target processor. Porting code downward, however, produces undefined results; in most cases, the code will fail to assemble.

This section explains how to use the –p and –w options to ease porting.

3.4.1   Porting Inconsistencies (–p Option)

The TMS320C5x's and TMS320C2xx's hardware enhancements have resulted in several code porting inconsistencies. The following three cases are either not supported on the TMS320C5x or TMS320C2xx or might indirectly alter the original algorithm.

❏ The TMS320C5x and TMS320C2xx do not support conditional branches with ARP or AR update. For example:

```
bgz label, *+, ar6
```

❏ The NORM instruction modifies the AR on the fourth phase of the instruction pipe and therefore might cause a pipeline conflict.

❏ These TMS320C2x serial port commands are not valid for the TMS320C5x or TMS320C2xx: RFSM, SFSM, RTXM, STXM, and FORT.

You should be aware of these porting inconsistencies so that you can find and fix them. To enable you to port code quickly, however, the –p assembler option is available. The –p option handles two of the cases and produces a flag in the third case. Use the –p option with the appropriate version option (–v50 or –v2xx). Specifically, the –p option performs these actions:

❏ Translates conditional branches with ARP updates into a branch-on-condition delayed-MAR-NOP instruction sequence. For example:

TMS320C5x

```
bgz label, *+, ar6  translates to  bcndd label, GT
                                    mar *+, ar6
                                    nop
```

TMS320C2xx

```
bgz label, *+, ar6  translates to  mar *+, ar6
                                    BCND gt
```

❑ Inserts two NOP instructions after a NORM instruction to protect the pipeline.

❑ Flags the serial port control register instructions as invalid opcodes, because the instructions cannot be translated directly by the assembler into valid TMS320C5x instructions.

Example 3–1 shows how TMS320C25 code is affected when –p is used with –v50.

Example 3–1. –p Option and –v50 Option Effect on Ported Code

```
 1  *-p option branch with ARP update
 2
 3 0000   b90a      LACK   10
 4 0001   7c01   L1 SBRK   1
 5 0002   90aa      SACL   *+,AR2
 6 0003   90a0      SACL   *+
 7 0004   f304      BGZ L1, AR1   ; arp update not supported on 'C5x
   0005   001'   ; *** DELAYED BRANCH REPLACES PREVIOUS INSTRUCTION ***
   0006   8b09      MAR ; *** UPDATE ARx AS IN PREVIOUS BRANCH ***
   0007   8b00      NOP ; *** INSERTED FOR PIPELINE ALIGNMENT ***
 8
 9 0008   2080   L2 ADD *
10 0009   f100      BBNZ   L2,AR1
   000a   0008   ; *** DELAYED BRANCH REPLACES PREVIOUS INSTRUCTION ***
   000b   8b09      MAR ; *** UPDATE ARx AS IN PREVIOUS BRANCH ***
   000c   8b00      NOP ; *** INSERTED FOR PIPELINE ALIGNMENT ***
11
12         * -p option indirect addressing after NORM instruction
13
14 000d   8b8a      LARP   AR2
15 000e   a080      NORM   *
   000f   8b00      NOP ; *** INSERTED FOR PIPELINE PROTECTION ***
   0010   8b00      NOP ; *** INSERTED FOR PIPELINE PROTECTION ***
16 0011   8213'     SAR 2,x       ; pipeline conflict
17 0012   8280      SAR AR2,*     ; pipeline conflict
18
19 0013   0000   x  .word  00h

No Errors, No Warnings
```

For a detailed description of porting TMS320C2x code to the TMS320C5x, refer to the *TMS320C5x User's Guide*. For a detailed description of porting TMS320C2x code to the TMS320C2xx, refer to the *TMS320C2xx User's Guide* (scheduled to be published in the second quarter of 1995).

3.4.2   Porting Code Written for 'C2x or 'C5x to the 'C2xx (–pp Option)

If you have an existing body of code that was written using the .TMS32025 and .TMS32050 symbols so that the code compiles for either processor, you can easily port this code to the TMS320C2xx with the –v2xx option and the –pp option combined. The –pp option defines both the .TMS32025 and the .TMS3202xx symbols and resolves the porting inconsistences described in subsection 3.4.1. This allows you to port code written as shown in Example 3–2 directly to the TMS320C2xx without modification.

Example 3–2.Basic TMS320C25 and TMS320C50 Assembly Construct

```
        .if .tms32050
            .
            .
        code specific to 'C50
            .
            .
        .endif
        .if .tms32025
            .
            .
        code specific to 'C25
            .
            .
        .endif
```

If Example 3–3 was assembled for the TMS320C2xx without the –pp switch, the line .if .tms32025 would have to be changed to .if .tms32025 || .tms3202xx in order to assemble properly. With the –pp switch, since the .tms32025 symbol is defined by the assembler, the code segment does not have to be changed.

Example 3–3.Porting TMS320C25 and TMS320C50 to TMS320C2xx

```
        .
        .
.if .tms32050
BD  label        ; delayed branch, specific to 'C50
.endif

INSTR1
INSTR2

.if .tms32025
B   label        ; C25 does not have delayed branch
.endif
        .
        .
```

This option is provided as a convenience for porting existing code to the TMS320C2xx devices. The –pp option will work only if the –v2xx option is used when assembling.

3.4.3   Programming the TMS320 Pipeline (–w Option)

The TMS320C1x and TMS320C2x processors use a pipelined instruction execution. This pipeline is basically transparent, except in cases where it is broken, such as by branch instructions. For more information about each of the processor's pipelines, refer to the appropriate TMS320 user's guide.

Because of the TMS320C5x hardware enhancements, such as the four-phase pipeline and memory-mapped registers, there may be pipeline conflicts. The –w assembler option warns you of the following pipeline conflicts:

❑   WARNING – CONTEXT SWITCH IN DELAYED SEQUENCE

This warning indicates a context switch during a delayed sequence context change. The following instructions change the processor context:

TRAP[D]	CALA[D]	BACC[D]	RETI
BCND[D]	CC[D]	RETC[D]	RETE
B[D]	CALL[D]	BANZ[D]	INTR

❑   WARNING – POSSIBLE PIPE HIT AT BRANCH ADDRESS

This warning indicates that a NORM instruction was found during a delayed sequence context change. The NORM instruction may cause a pipeline conflict.

❑   WARNING – DELAYED JUMP MISSES SECOND WORD

This warning indicates that a two-word instruction is in the second word of a delayed sequence context switch. The second word will be fetched from the branch address.

❑   WARNING – POSSIBLE PIPE CONFLICT WITH NORM

This warning indicates use of indirect addressing in the two words following a NORM instruction. This may cause a pipeline conflict.

❑   WARNING – POSSIBLE PIPE HIT WITH ARx ACCESS

This warning indicates an access to an AR register as a memory address. This may cause a pipeline conflict.

Note: – w Does Not Provide Warnings for All Pipeline Conflicts

Be aware of the effects of pipelined execution when you program the TMS320C5x. The –w switch does not provide warnings for all pipeline conflicts. There are subtle situations that the assembler cannot detect.

Example 3–4 shows the –w option's effect on TMS320C25 code.

Example 3–4.–w Option Effect on Ported Code

```
 1         * –w switch context switch
 2
 3 0000    8b89      LARP   AR1
 4 0000    3080   x  SUB *
 5
 6 0002    f388      BCNDD  x,eq
   0003    0001'
 7 0004    2080      ADD *
 8 0005    7980      B   Y  ; context switch during delayed sequence
   0006    0009'
********** WARNING – CONTEXT SWITCH IN DELAYED SEQUENCE
 9
10 0007    2080      ADD *
11 0008    2080      ADD *
12
13 0009    8B00   y  NOP
14
15
16         * –w switch norm pipeline conflict
17
18 000a    8b8a      LARP   AR2
19 000B    a080      NORM   *  ; norm hits ar2 in execute phase
20 000c    820e      SAR AR2,exp
********** WARNING – PROBABLE PIPE CONFLICT WITH NORM
LAST ERROR AT 8
0021   000d0200      LAR AR2,0
********** WARNING – PROBABLE PIPE CONFLICT WITH NORM
LAST ERROR AT 20
22
23 000e    0000   exp .WORD  OOh
24
25         * –w switch arx as an address pipeline conflict
26
27
28 000f    101b      LAC AR3,AR3      ; modifies ar3 in fourth phase
********** WARNING – POSSIBLE PIPE HIT WITH ARx ACCESS
LAST ERROR AT 21
29 0010    2080      ADD *           ; uses ar3 in second phase

No Errors, 4 Warnings
```

For a detailed description of pipeline conflicts, including a list of the instructions that will potentially cause conflicts and methods for using these instructions, refer to the *TMS320C5x User's Guide.*

3.5 Naming Alternate Directories for Assembler Input

The .copy, .include, and .mlib directives tell the assembler to use code from external files. The .copy and .include directives tell the assembler to read source statements from another file, and the .mlib directive names a library that contains macro functions. Chapter 4, *Assembler Directives*, contains examples of the .copy, .include, and .mlib directives. The syntax for these directives is:

> **.copy** *"filename"*
>
> **.include** *"filename"*
>
> **.mlib** *"filename"*

The *filename* names a copy/include file that the assembler reads statements from or a macro library that contains macro definitions. The filename may be a complete pathname, a partial pathname, or a filename with no path information. The assembler searches for the file in:

1) The directory that contains the current source file. The current source file is the file being assembled when the .copy, .include, or .mlib directive is encountered.

2) Any directories named with the –i assembler option

3) Any directories set with the environment variable A_DIR

You can augment the assembler's directory search algorithm by using the –i assembler option or the environment variable.

3.5.1 –i Assembler Option

The –i assembler option names an alternate directory that contains copy/include files or macro libraries. The format of the –i option is as follows:

> **dspa** **–i***pathname source filename*

You can use up to 10 –i options per invocation; each –i option names one pathname. In assembly source, you can use the .copy, .include, or .mlib directive without specifying path information. If the assembler doesn't find the file in the directory that contains the current source file, it searches the paths designated by the –i options.

For example, assume that a file called source.asm is in the current directory; source.asm contains the following directive statement:

```
.copy "copy.asm"
```

	Pathname for copy.asm	**Invocation Command**
DOS	c:\dsp\files\copy.asm	dspa –ic:\dsp\files source.asm
UNIX	/dsp/files/copy.asm	dspa –i/dsp/files source.asm

The assembler first searches for copy.asm in the current directory because source.asm is in the current directory. Then the assembler searches in the directory named with the –i option.

3.5.2 A_DIR Environment Variable

An environment variable is a system symbol that you define and assign a string to. The assembler uses the environment variable **A_DIR** to name alternate directories that contain copy/include files or macro libraries. The command syntax for assigning the environment variable is as follows:

DOS set A_DIR = *pathname;another pathname ...*
UNIX setenv A_DIR **"***pathname;another pathname ...* **"**

The *pathnames* are directories that contain copy/include files or macro libraries. You can separate the pathnames with a semicolon or with blanks. In assembly source, you can use the .copy, .include, or .mlib directive without specifying any path information. If the assembler doesn't find the file in the directory that contains the current source file or in directories named by –i, it searches the paths named by the environment variable.

For example, assume that a file called source.asm contains these statements:

```
.copy "copy1.asm"
.copy "copy2.asm"
```

	Pathname	**Invocation Command**
DOS	c:\320\files\copy1.asm c:\dsys\copy2.asm	set A_DIR=c:\dsys; c:\exec\source dspa –ic:\320\files source.asm
UNIX	/320/files/copy1.asm /dsys/copy2.asm	set A_DIR=/dsys; /exec.source dspa –i/320/files source.asm

The assembler first searches for copy1.asm and copy2.asm in the current directory because source.asm is in the current directory. Then the assembler searches in the directory named with the –i option and finds copy1.asm. Finally, the assembler searches the directory named with A_DIR and finds copy2.asm.

The environment variable remains set until you reboot the system or reset the variable by entering one of these commands:

DOS   `set A_DIR=`
UNIX   `setenv A_DIR " "`

3.6 Source Statement Format

TMS320 assembly language source programs consist of source statements that can contain assembler directives, assembly language instructions, macro directives, and comments. Source statement lines can be as long as the source file format allows, but the assembler reads up to 200 characters per line. If a statement contains more than 200 characters, the assembler truncates the line and issues a warning.

The following are examples of source statements:

```
SYM1      .set     2      ; Symbol SYM1 = 2
Begin:    LDPK     SYM1   ; Load DP with 2
          .word    016h   ; Initialize a word with 016h
```

A source statement can contain four ordered fields. The general syntax for source statements is as follows:

[*label*] [:]   *mnemonic*   [*operand list*]   [*;comment*]

Follow these guidelines:

❏ All statements must begin with a label, a blank, an asterisk, or a semicolon.

❏ Labels are optional; if used, they must begin in column 1.

❏ One or more blanks must separate each field. Tab characters are equivalent to blanks.

❏ Comments are optional. Comments that begin in column 1 can begin with an asterisk or a semicolon (* or ;), but comments that begin in any other column **mus**t begin with a semicolon.

3.6.1 Label Field

Labels are optional for all assembly language instructions and for most (but not all) assembler directives. When used, a label must begin in column 1 of a source statement. A label can contain up to 32 alphanumeric characters (A–Z, a–z, 0–9, _, and $). Labels are case sensitive, and the first character cannot be a number. A label can be followed by a colon (:); the colon is not treated as part of the label name. If you don't use a label, the first character position must contain a blank, a semicolon, or an asterisk.

When you use a label, its value is the current value of the section program counter (the label points to the statement it's associated with). If, for example, you use the .word directive to initialize several words, a label would point to the first word. In the following example, the label Start has the value 40h.

```
    .       .               .           .
    .       .               .           .
    .       .               .           .
 9     003F            * Assume some other code was assembled
10     0040    000A    Start:  .word 0Ah,3,7
       0041    0003
       0042    0007
```

A label on a line by itself is a valid statement. The label assigns the current value of the section program counter to the label; this is equivalent to the following directive statement:

```
label  .set  $  ;  $ provides the current value of the SPC
```

When a label appears on a line by itself, it points to the instruction on the next line (the SPC is not incremented):

```
3   0050                Here:
4   0050    0003            .word 3
```

3.6.2 Mnemonic Field

The mnemonic field follows the label field. The mnemonic field must not start in column 1; if it does, it will be interpreted as a label. The mnemonic field can contain one of the following opcodes:

❑ Machine-instruction (such as ABS, MPYU, SPH)
❑ Assembler directive (such as .data, .list, .set)
❑ Macro directive (such as .macro, .var, .mexit)
❑ Macro call

3.6.3 Operand Field

The operand field is a list of operands that follow the mnemonic field. An operand can be a constant (see Section 3.7, page 3-17), a symbol (see Section 3.9, page 3-20), or a combination of constants and symbols in an expression (see Section 3.10, page 3-25). You must separate operands with commas.

3.6.4 Comment Field

A comment can begin in any column and extends to the end of the source line. A comment can contain any ASCII character, including blanks. Comments are printed in the assembly source listing, but they do not affect the assembly.

A source statement that contains only a comment is valid. If it begins in column 1, it can start with semicolon (;) or asterisk (*). Comments that begin anywhere else on the line must begin with a semicolon. The asterisk identifies a comment only if it appears in column 1.

3.7 Constants

The assembler supports six types of constants:

❏ Binary integer
❏ Octal integer
❏ Decimal integer
❏ Hexadecimal integer
❏ Character
❏ Assembly-time

The assembler maintains each constant internally as a 32-bit quantity. Constants are not sign-extended. For example, the constant 0FFH is equal to 00FF (base 16) or 255 (base 10); it does not equal –1.

3.7.1 Binary Integers

A binary integer constant is a string of up to 16 binary digits (0s and 1s) fol-lowed by the suffix **B** (or **b**). If fewer than 16 digits are specified, the assembler right-justifies the value and zero-fills the unspecified bits. These are examples of valid binary constants:

00000000B Constant equal to 0_{10} or 0_{16}

0100000b Constant equal to 32_{10} or 20_{16}

01b Constant equal to 1_{10} or 1_{16}

11111000B Constant equal to 248_{10} or $0F8_{16}$

3.7.2 Octal Integers

An octal integer constant is a string of up to 6 octal digits (0 through 7) followed by the suffix **Q** (or **q**). These are examples of valid octal constants:

10Q Constant equal to 8_{10} or 8_{16}

100000Q Constant equal to $32,768_{10}$ or $8,000_{16}$

226q Constant equal to 150_{10} or 96_{16}

3.7.3 Decimal Integers

A decimal integer constant is a string of decimal digits, ranging from –32,768 to 65,535. These are examples of valid decimal constants:

1000 Constant equal to 1000_{10} or $3E8_{16}$

–32768 Constant equal to $-32,768_{10}$ or $8,000_{16}$

25 Constant equal to 25_{10} or 19_{16}

3.7.4 Hexadecimal Integers

A hexadecimal integer constant is a string of up to 4 hexadecimal digits followed by the suffix **H** (or **h**). Hexadecimal digits include the decimal values 0–9 and the letters A–F and a–f. A hexadecimal constant must begin with a decimal value (0–9). If fewer than 4 hexadecimal digits are specified, the assembler right-justifies the bits. These are examples of valid hexadecimal constants:

78h   Constant equal to 120_{10} or 0078_{16}

0FH   Constant equal to 15_{10} or $000F_{16}$

37ACh   Constant equal to $14,252_{10}$ or $37AC_{16}$

3.7.5 Character Constants

A character constant is a string of one or two characters enclosed in single quotes. The characters are represented internally as 8-bit ASCII characters. Two consecutive single quotes are required to represent each single quote that is part of a character constant. A character constant consisting only of two single quotes is valid and is assigned the value 0. If only one character is specified, the assembler right-justifies the bits. These are examples of valid character constants:

'a'   Defines the character constant *a* and is represented internally as 61_{16}

'C'   Defines the character constant *C* and is represented internally as 43_{16}

''''   Defines the character constant *'* and is represented internally as 27_{16}

''   Defines a null character and is represented internally as 00_{16}

Note the difference between character constants and character strings (Section 3.8, page 3-19, discusses character strings). A character constant represents a single integer value; a string is a list of characters.

3.7.6 Assembly-Time Constants

If you use the .set directive to assign a value to a symbol, the symbol becomes a constant. To use this constant in expressions, the value that is assigned to it must be absolute. For example:

```
shift3    .set   3
          LAC*,shift3,AR1
```

You can also use the .set directive to assign symbolic constants for register names. In this case, the symbol becomes a synonym for the register:

```
AuxR1     .set   AR1
          LAC*,0,AuxR1
```

3.8 Character Strings

A character string is a string of characters enclosed in *double* quotes. Double quotes that are part of character strings are represented by two consecutive double quotes. The maximum length of a string varies and is defined for each directive that requires a character string. Characters are represented internally as 8-bit ASCII characters.

These are examples of valid character strings:

"sample program"   defines the 14-character string *sample program.*

"PLAN ""C"""   defines the 8-character string *PLAN "C".*

Character strings are used for the following:

❑ Filenames as in .copy "filename"
❑ Section names as in .sect "section name"
❑ Data initialization directives as in .byte "charstring"
❑ Operand of .string directive

3.9 Symbols

Symbols are used as labels, constants, and substitution symbols. A symbol name is a string of up to 32 alphanumeric characters (A–Z, a–z, 0–9, $, and _). The first character in a symbol cannot be a number, and symbols cannot contain embedded blanks. The symbols you define are case sensitive; for example, the assembler recognizes ABC, Abc, and abc as three unique symbols. You can override case sensitivity with the –c assembler option. A symbol is valid only during the assembly in which it is defined, unless you use the .global directive to declare it as an external symbol.

3.9.1 Labels

Symbols used as labels become symbolic addresses associated with locations in the program. Labels used locally within a file must be unique. Mnemonic opcodes and assembler directive names (without the . prefix) are valid label names.

Labels can also be used as the operands of .global, .ref, .def, or .bss directives; for example:

```
        .global   label1

label2  nop
        add     label1
        b       label2
```

3.9.2 Symbolic Constants

Symbols can be set to constant values. By using constants, you can equate meaningful names with constant values. The .set and .struct/.tag/.endstruct directives enable you to set constants to symbolic names. Symbolic constants **cannot** be redefined. The following example shows how these directives can be used:

```
K      .set   1024            ; constant definitions
maxbuf .set   2*K

item   .struct                ; item structure definition
       .int   value           ; constant offsets value = 0
       .int   delta           ; constant offsets delta = 1
i_len  .endstruct

array  .tag   item            ; array declaration
       .bss   array, i_len*K

       .ADD   array.delta      ; array+1
```

The assembler also has several predefined symbolic constants; these are discussed in the next section.

3.9.3 Defining Symbolic Constants (–d Option)

The –d option equates a constant value with a symbol. The symbol can then be used in place of a value in assembly source. The format of the –d option is as follows:

> **dspa   –d**name=[value]

The name is the name of the symbol you want to define. The value is the value you want to assign to the symbol. If the value is omitted, the symbol will be set to 1.

Within assembler source, you may test the symbol with the following directives:

Type of Test	Directive Usage
Existence	`.if $isdefed("name")`
Nonexistence	`.if $isdefed("name") = 0`
Equal to value	`.if name = value`
Not equal to value	`.if name != value`

Note that the argument to the $isdefed built-in function must be enclosed in quotes. The quotes cause the argument to be interpreted literally rather than as a substitution symbol.

3.9.4 Predefined Symbolic Constants

The assembler has several predefined symbols, including the following:

❑ **$**, the dollar sign character, represents the current value of the section program counter (SPC).

❑ **Register symbols**, including:
  ■ AR0–AR1 for the TMS320C1x and
  ■ AR0–AR7 for the TMS320C2x/C2xx/5x

❑ **Port address symbols**, including:

  ■ PA0–PA7 for the TMS320C1x and
  ■ PA0–PA15 for the TMS320C2x/C2xx/5x

❑ **Version symbols** are predefined assembler constants that you can use to direct the assembler to produce code for various target processors. Use the version symbols with the target version switch or the .version directive.

Version Symbols	−Version Option	.version Directive
.TMS32010	−v10	10
.TMS32016	−v16	16
.TMS32020	−v20	20
.TMS32025	−v25	25
.TMS3202XX	−v2xx	29
.TMS32050	−v50	50
.TMS320XX	processor version	

The .TMS320XX constant is set to the value of the version switch. For example, if the assembler is invoked with the following command:

```
dspa −v20 filename
```

then .TMS320XX equals 20; therefore, TMS32020 equals one or true and TMS32010, TMS32016, TMS32025, TMS32050, and TMS3202XX all equal zero or false.

You can use the version symbols to direct the assembler to produce code for specific target devices. For example, the following example can produce code for differing target devices, depending on how you invoked the assembler.

```
if      .TMS320xx = 50
        .
        .
.endif
.if     .TMS32020
        .
        .
.endif
```

❑ **Symbols** that are defined by using the .mmregs directive.

Note: Register Symbols

The values of **register symbols** are AR0 = 0, AR1 = 1, AR2 = 2, and so forth
on TMS320C1x/C2x/C2xx devices; but on TMS320C5x devices, they equal
their memory-mapped addresses and values. In other words, the assembler
interprets the context of symbols as follows:

```
            ADD *+, AR7
            ADD AR7
```

In the first example above, AR7 has a value of 7; in the second example, AR7
is the address of AR7, which has a value of 17.

3.9.5 Substitution Symbols

Symbols can be assigned a string value (variable). This enables you to alias
character strings by equating them to symbolic names. Symbols that repre-
sent character strings are called substitution symbols. When the assembler
encounters a substitution symbol, its string value is substituted for the symbol
name. Unlike symbolic constants, substitution symbols can be redefined.

A string can be assigned to a substitution symbol anywhere within a program;
for example:

```
    .asg  "ar0",   SP   ;   stack pointer
    .asg  "*+",    INC  ;   indirect auto-increment
    .asg  "*-",    DEC  ;   indirect auto-decrement

    ADD   label, INC, SP
```

When you are using macros, substitution symbols are important because
macro parameters are actually substitution symbols that are assigned a macro
argument. The following code shows how substitution symbols are used in
macros:

```
add2   .macro   src,dest ;  add2 macro definition

       lac    a
       add    b
       sac    dest

       .endm

*add2 invocation
       add2  loc1, loc2  ;  assign "loc1" argument to a
```

For more information about macros, see Chapter 6.

3.9.6   Local Labels

Local labels are special labels whose scope and effect are temporary. A local label has the form $n, where n is a decimal digit in the range 0–9. For example, $4 and $1 are valid local labels.

Normal labels must be unique (they can be declared only once), and they can be used as constants in the operand field. Local labels, however, can be undefined and defined again.

A local label can be undefined, or reset, in one of four ways:

❑ By using the .newblock directive
❑ By changing sections (using a .sect, .text, or .data directive)
❑ By entering an include file (specified by the .include or .copy directive)
❑ By leaving an include file (specified by the .include or .copy directive)

This is an example of code that declares and uses a local label legally:

```
Label1:   lac a
          sub b
          blz $1
          lac b
          b  $2
$1        lac a
$2        add c
          .newblock ; Undefine $1 so it can be used again
          blez $1
          sacl c
$1        nop
```

The following code uses a local label illegally:

```
Label1:   lac a
          sub b
          blz $1
          lac b
          b  $2
$1        lac a
$2        add c
          blez $1 ;
          sacl c
$1        nop   ; WRONG $1 is multiply defined
```

Local labels are especially useful in macros. If a macro contains a normal label and is called more than once, the assembler issues a multiple-definition error. However, if you use a local label and .newblock within a macro, the local label is used and reset each time the macro is expanded.

Up to ten local labels can be in effect at one time. After you undefine a local label, you can define it and use it again. Local labels do not appear in the object code symbol table.

3.10 Expressions

An expression is a constant, a symbol, or a series of constants and symbols separated by arithmetic operators. The range of valid expression values is –32,768 to 32,767. Three main factors influence the order of expression evaluation:

Parentheses   Expressions enclosed in parentheses are always evaluated first.

8/(4/2) = 4, but 8/4/2 = 1

You **cannot** substitute braces ({ }) or brackets ([ ]) for parentheses.

Precedence groups   Operators, listed in Table 3–1, are divided into four precedence groups. When parentheses do not determine the order of expression evaluation, the highest precedence operation is evaluated first.

8 + 4/2 = 10 (4/2 is evaluated first)

Left-to-right evaluation   When parentheses and precedence groups do not determine the order of expression evaluation, the expressions are evaluated from left to right, except for Group 1, which is evaluated from right to left.

8/4*2 = 4, but 8/(4*2) = 1

3.10.1 Operators

Table 3–1 lists the operators that can be used in expressions. They are listed according to precedence group.

Table 3–1. Operators Used in Expressions (Precedence)

Group	Operator	Description
1	+	Unary plus
	–	Unary minus
	~	1s complement
2	*	Multiplication
	/	Division
	%	Modulo
	<<	Left shift
	>>	Right shift
3	+	Addition
	–	Subtraction
	^	Bitwise exclusive-OR
	|	Bitwise OR
	&	Bitwise AND
4	<	Less than
	>	Greater than
	<=	Less than or equal to
	>=	Greater than or equal to
	= or ==	Equal to
	!=	Not equal to

Note: Group 1 operators are evaluated right to left. All other operators are evaluated left to right.

3.10.2 Expression Overflow and Underflow

The assembler checks for overflow and underflow conditions when arithmetic operations are performed at assembly time. It issues a Value Truncated warning whenever an overflow or underflow occurs. The assembler **does not** check for overflow or underflow in multiplication.

3.10.3 Well-Defined Expressions

Some assembler directives require well-defined expressions as operands. Well-defined expressions contain only symbols or assembly-time constants that are defined before they are encountered in the expression. The evaluation of a well-defined expression must be absolute.

This is an example of a well-defined expression:

```
1000h+X
```

where X was previously defined as an absolute symbol.

3.10.4 Conditional Expressions

The assembler supports relational operators that can be used in any expression; they are especially useful for conditional assembly. Relational operators include the following:

=	Equal to	**= =**	Equal to
! =	Not equal to		
<	Less than	**< =**	Less than or equal to
>	Greater than	**> =**	Greater than or equal to

Conditional expressions evaluate to 1 if true and 0 if false; they can be used only on operands of equivalent types, e.g., absolute value compared to absolute value, but not absolute value compared to relocatable value.

3.10.5 Relocatable Symbols and Legal Expressions

Table 3–2 summarizes valid operations on absolute, relocatable, and external symbols. An expression cannot multiply or divide by a relocatable or external symbol. An expression cannot contain unresolved symbols that are relocatable with respect to other sections.

Symbols or registers that have been defined as global with the .global directive can also be used in expressions; in Table 3–2, these symbols and registers are referred to as *external*.

Relocatable registers can be used in expressions; the addresses of these registers are relocatable with respect to the register section they were defined in, unless they have been declared as external.

Table 3–2. Expressions With Absolute and Relocatable Symbols

If A is...	and	If B is...	, then	A + B is...	and	A – B is...
absolute		absolute		absolute		absolute
absolute		external		external		illegal
absolute		relocatable		relocatable		illegal
relocatable		absolute		relocatable		relocatable
relocatable		relocatable		illegal		absolute †
relocatable		external		illegal		illegal
external		absolute		external		external
external		relocatable		illegal		illegal
external		external		illegal		illegal

† A and B must be in the same section; otherwise, this is illegal.

Following examples of expressions that use relocatable and absolute symbols. These examples use four symbols that are defined in the same section:

```
.global extern_1    ;  Defined in an external module
intern_1: .word '"D'; Relocatable, defined in current module
LAB1:  .set 2        ;  LAB1 = 2
intern_2             ;  Relocatable, defined in current module
```

❏ **Example 1**

The statements in this example use an absolute symbol, LAB1 (which is defined above to have a value of 2). The first statement loads the value 51 into the accumulator. The second statement loads the value 27 into the accumulator.

```
LACK  LAB1  +  ((4+3) *  7)    ;  ACC = 51
LACK  LAB1  +  4  +  (3*7)      ;  ACC = 27
```

❏ **Example 2**

All legal expressions can be reduced to one of two forms:

relocatable symbol ± *absolute symbol*

or

absolute value

Unary operators can be applied only to absolute values; they cannot be applied to relocatable symbols. Expressions that cannot be reduced to contain only one relocatable symbol are illegal. The first statement in the following example is valid; the statements that follow it are invalid.

```
LACK extern_1 – 10       ; Legal
LACK 10-extern_1         ; Can't negate reloc. symbol
LACK –(intern_1)         ; Can't negate reloc. symbol
LACK extern_1/10         ; / isn't an additive operator
LACK intern_1 + extern_1 ; Multiple relocatables
```

❏ **Example 3**

The first statement below is legal; although intern_1 and intern_2 are relocatable, their difference is absolute because they're in the same section. Subtracting one relocatable symbol from another reduces the expression to *relocatable symbol + absolute value*. The second statement is illegal because the sum of two relocatable symbols is not an absolute value.

```
LACK   intern_1 – intern_2 + extern_1    ; Legal
LACK   intern_1 + intern_2 + extern_1    ; Illegal
```

❏ **Example 4**

An external symbol's placement is important to expression evaluation. Although the statement below is similar to the first statement in the previous example, it is illegal due to left-to-right operator precedence; the assembler attempts to add intern_1 to extern_1.

```
LACK   intern_1 + extern_1 – intern_2    ; Illegal
```

3.11 Source Listings

A source listing shows source statements and the object code they produce. To obtain a listing file, invoke the assembler with the –l (lowercase L) option.

Two banner lines, a blank line, and a title line are at the top of each source listing page. Any title supplied by a .title directive is printed on this line; a page number is printed to the right of the title. If you don't use the .title directive, the title area is left blank. The assembler inserts a blank line below the title line.

Each line in the source file may produce a line in the listing file that shows a source statement number, an SPC value, the object code assembled, and the source statement (see Example 3–5). A source statement may produce more than one word of object code. The assembler lists the SPC value and object code on a separate line for each additional word. Each additional line is listed immediately following the source statement line.

Field 1: Source Statement Number

Line Number

The source statement number is decimal. The assembler numbers source lines as it encounters them in the source file; some statements increment the line counter but are not listed. (For example, .title statements and statements following a .nolist are not listed.) The difference between two consecutive source line numbers indicates the number of intervening statements in the source file that are not listed.

Include File Letter

The assembler may precede a line with a letter; the letter indicates that the line is assembled from an included file.

Nesting Level Number

The assembler may precede a line with a number; the number indicates the nesting level of macro expansions or loop blocks.

Field 2: Section Program Counter

This field contains the section program counter (SPC) value, which is hexadecimal. All sections (.text, .data, .bss, and named sections) maintain separate SPCs. Some directives do not affect the SPC and leave this field blank.

Field 3: Object Code

This field contains the hexadecimal representation of the object code. All machine instructions and directives use this field to list object code. This field also indicates the relocation type by appending one of the following characters to the end of the field:

!	undefined external reference
'	.text relocatable
"	.data relocatable
+	.sect relocatable
–	.bss, .usect relocatable
^	.asect relocatable

Field 4: Source Statement Field

This field contains the characters of the source statement as they were scanned by the assembler. The assembler accepts a maximum line length of 200 characters. Spacing in this field is determined by the spacing in the source statement.

Example 3–5 shows an assembler listing with each of the four fields identified.

Example 3–5. An Assembler Listing

```
        2                   .global   RESET, INT0 INT1, INT2
        3                   .global   TINT, RINT, XINT, USER
        4                   .global   ISR0, ISR1, ISR2
        5                   .global   time, rcv, xmt, proc
        6
        7                   .copy "init.inc"
  A  1            initmac  .macro
  A  2            ! initialize macro
  A  3                rovm  ; disable oflow
  A  4                ldpk 0 ; dp = 0
  A  5                larp 7 ; arp = ar7
  A  6                lack 03fh ; acc = 03fh
  A  7                sacl 4 ; enable ints
  A  8                  .endm
        8            *
        9            *******************************************
       10            * Reset and interrupt vectors     *
       11            *******************************************
       12 0000          .sect  "reset"
       13 0000  ff80   RESET: B   init
          0001  0008+
       14 0002  ff80   INT0:  B   ISR0
          0003  0000!
       15 0004  ff809  INT1:  B   ISR1
          0005  0000!
       16 0006  ff80   INT2   B   ISR2
          0007  0000!
       17            *
       18 0000          .sect  "ints"
       19 0000  ff80   TINT   B   time
          0001  0000!
       20 0002  ff80   RINT   B   rcv
          0003  0000!
       21 0004  ff80   XINT   B   xmt
          0005  0000!
       22 0006  ff80   USER   B   proc
          0007  0000!
       23            *******************************************
       24            * Initialize processor         *
       25            *******************************************
       26 0008     init:  initmac
  1     0008  ce02     rovm   ; disable oflow
  1     0009  c800     ldpk 0 ; dp = 0
  1     000a  558f     larp 7 ; arp = ar7
  1     000b  ca3f     lack 03fh ; acc = 03fh
  1     000c  6004     sac14  ; enable ints
       27 000d  ca00     zac; zero acc
       28 000e  c760     lark ar7, 060h    ; ar7 -> B2
       29 000f  cb1f     rptk 31
       30 0010  60a0     sacl *+   ; zero out
```

Field 1 Field 2 Field 3   Field 4

3.12 Cross-Reference Listings

A cross-reference listing shows symbols and their definitions. To obtain a cross-reference listing, invoke the assembler with the –x option or use the .option directive. The assembler will append the cross-reference to the end of the source listing.

Example 3–6. An Assembler Cross-Reference Listing

```
LABEL                        VALUE    DEFN    REF

INT0                         0002+     14      2
INT1                         0004+     15      2
INT2                         0006+     16      2
ISR0                         REF                4     14
ISR1                         REF                4     15
ISR2                         REF                4     16
RESET                        0000+     13      2
RINT                         0002+     24      3
TINT                         0000+     23      3
VECS                         0006+     26      3
XINT                         0004+     27
init                         0000+     34     13
```

Label   column contains each symbol that was defined or referenced during the assembly.

Value   column contains a 4-digit hexadecimal number, which is the value assigned to the symbol *or* a name that describes the symbol's attributes. A value may be followed by a character that describes the symbol's attributes. Table 3–3 lists these characters and names.

Definition   (DEFN) column contains the statement number that defines the symbol. This column is blank for undefined symbols.

Reference   (REF) column lists the line numbers of statements that reference the symbol. A blank in this column indicates that the symbol was never used.

Table 3–3. Symbol Attributes

Character or Name	Meaning
REF	External reference (.global symbol)
UNDF	Undefined
'	Symbol defined in a .text section
"	Symbol defined in a .data section
+	Symbol defined in a .sect section
–	Symbol defined in a .bss or .usect section

3.13 Enhanced Instruction Forms

Enhanced instructions are single mnemonics that perform the functions of several similar instructions. These instructions are valid for the TMS320C2x, TMS320C2xx, and TMS320C5x devices.

The assembler interprets the operands of enhanced instructions to determine the correct opcode, as shown below:

Enhanced Instructions		Base Instructions	
ADD	x	ADD	x
ADD	*+	ADD	*+
ADD	#100	ADDK	100
ADD	#3000	ADLK	3000
ADD	*+,16	ADDH	*+

For more information about enhanced instructions, see Section 5.2, page 5-5.

Assembler Directives

Assembler directives supply program data and control the assembly process. Assembler directives enable you to do the following:

❏ Assemble code and data into specified sections
❏ Reserve space in memory for uninitialized variables
❏ Control the appearance of listings
❏ Initialize memory
❏ Assemble conditional blocks
❏ Define global variables
❏ Specify libraries from which the assembler can obtain macros
❏ Examine symbolic debugging information

The first part of this chapter (Sections 4.1 through 4.9) describes the directives according to function, and the second part (Section 4.10) is an alphabetical reference. This chapter includes the following topics:

Topic	Page

4.1   Directives Summary

Table 4–1 summarizes the assembler directives. All source statements that contain a directive may have a label and a comment. To improve readability, they are not shown as part of the directive syntax.

Table 4–1. Assembler Directives Summary

Directives That Define Sections	
Mnemonic and Syntax	*Description*
.asect *"section name", address*	Assemble into an absolute named (initialized) section (This directive is obsolete)
.bss *symbol, size in words* [*, blocking flag*]	Reserve size words in the .bss (uninitialized data) section
.data	Assemble into the .data (initialized data) section
.sect *"section name"*	Assemble into a named (initialized) section
.text	Assemble into the .text (executable code) section
symbol **.usect** *"section name", size in words*, [*blocking flag*]	Reserve size words in a named (uninitialized) section

Directives That Initialize Constants (Data and Memory)	
Mnemonic and Syntax	*Description*
.bes *size in bits*	Reserve size bits in the current section; a label points to the end of the reserved space
.bfloat *value*	Initialize a 32-bit, IEEE single-precision, floating-point constant; do not allow object to span a page boundary
.blong $value_1$ [, ... , $value_n$]	Initialize one or more 32-bit integers; do not allow object to span a page boundary
.byte $value_1$ [, ... , $value_n$]	Initialize one or more successive bytes in the current section
.field *value* [*, size in bits*]	Initialize a variable-length field
.float *value*	Initialize a 32-bit, IEEE single-precision, floating-point constant
.int $value_1$ [, ... , $value_n$]	Initialize one or more16-bit integers
.long $value_1$ [, ... , $value_n$]	Initialize one or more 32-bit integers
.space *size in bits*	Reserve size bits in the current section; a label points to the beginning of the reserved space
.string *"$string_1$"* [, ... , *"$string_n$"*]	Initialize one or more text strings
.word $value_1$ [, ... , $value_n$]	Initialize one or more 16-bit integers

Table 4–1.Directives Summary (Continued)

Directives That Align the Section Program Counter (SPC)	
Mnemonic and Syntax	*Description*
.align	Align the SPC on a page boundary
.even	Align the SPC on an even word boundary

Directives That Format the Output Listing	
Mnemonic and Syntax	*Description*
.drlist	Enable listing of all directive lines (default)
.drnolist	Inhibit listing of certain directive lines
.fclist	Allow false conditional code block listing (default)
.fcnolist	Inhibit false conditional code block listing
.length *page length*	Set the page length of the source listing
.list	Restart the source listing
.mlist	Allow macro listings and loop blocks (default)
.mnolist	Inhibit macro listings and loop blocks
.nolist	Stop the source listing
.option *{B	D	F	L	M	T	X}*	Select output listing options
.page	Eject a page in the source listing
.sslist	Allow expanded substitution symbol listing
.ssnolist	Inhibit expanded substitution symbol listing (default)
.tab *size*	Set tab size
.title *"string"*	Print a title in the listing page heading
.width *page width*	Set the page width of the source listing

Table 4–1. Directives Summary (Continued)

Directives That Reference Other Files	
Mnemonic and Syntax	*Description*
.copy [*"*]*filename*[*"*]	Include source statements from another file
.def $symbol_1$ [, ... , $symbol_n$]	Identify one or more symbols that are defined in the current module and used in other modules
.global $symbol_1$ [, ... , $symbol_n$]	Identify one or more global (external) symbols
.include [*"*]*filename*[*"*]	Include source statements from another file
.mlib [*"*]*filename*[*"*]	Define macro library
.ref $symbol_1$ [, ... , $symbol_n$]	Identify one or more symbols that are used in the current module but defined in another module

Conditional Assembly Directives	
Mnemonic and Syntax	*Description*
.break [*well-defined expression*]	End .loop assembly if condition is true. The .break construct is optional.
.else	Assemble code block if the .if condition is false. The .else construct is optional.
.elseif *well-defined expression*	Assemble code block if the .if condition is false and the .elseif condition is true. The .elseif construct is optional.
.endif	End .if code block
.endloop	End .loop code block
.if *well-defined expression*	Assemble code block if the condition is true
.loop [*well-defined expression*]	Begin repeatable assembly of a code block

Table 4–1. Directives Summary (Concluded)

Assembly-Time Symbols	
Mnemonic and Syntax	*Description*
.asg [*"*] *character string* [*"*], *substitution symbol*	Assign a character string to a substitution symbol
.endstruct	End structure definition
.equ	Equate a value with a symbol
.eval *well-defined expression*, *substitution symbol*	Perform arithmetic on numeric substitution symbols
.newblock	Undefine local labels
.set	Equate a value with a symbol
.struct	Begin structure definition
.tag	Assign structure attributes to a label

Miscellaneous Directives	
Mnemonic and Syntax	*Description*
.emsg *string*	Send user-defined error messages to the output device
.end	End program
.label *symbol*	Define a loadtime relocatable label in a section
.mmregs	Enter memory-mapped registers into symbol table
.mmsg *string*	Send user-defined messages to the output device
.port	Turn on the assembler porting switch
.sblock *"section name"* [,*"section name"*, . . .]	Designate sections for blocking
.version *generation #number*	Set processor version
.wmsg *string*	Send user-defined warning messages to the output device

4.2 Directives That Define Sections

Six directives associate the various portions of an assembly language pro-
gram with the appropriate sections:

❏ **.asect** creates initialized named sections that have *absolute addresses*.
A section defined with .asect can contain code or data. (Within an absolute
section, you can use the **.label** directive to define relocatable labels.)

❏ **.bss** reserves space in the .bss section for uninitialized variables.

❏ **.data** identifies portions of code in the .data section. The .data section usu-
ally contains initialized data.

❏ **.sect** defines initialized named sections and associates subsequent code
or data with that section. A section defined with .sect can contain code or
data.

❏ **.text** identifies portions of code in the .text section. The .text section usu-
ally contains executable code.

❏ **.usect** reserves space in an uninitialized named section. The .usect
directive is similar to the .bss directive, but it allows you to reserve space
separately from the .bss section.

Chapter 2 discusses COFF sections in detail.

Example 4–1 shows how you can use sections directives to associate code
and data with the proper sections. This is an output listing; column 1 shows line
numbers, and column 2 shows the SPC values. (Each section has its own pro-
gram counter, or SPC.) When code is first placed in a section, its SPC equals
0. When you resume assembling into a section after other code is assembled,
the section's SPC resumes counting as if there had been no intervening code.

In each section listed below, the directives in Example 4–1 perform the tasks
indicated:

.text	initializes words with the values 1, 2, 3, 4, 5, 6, 7, and 8.
.data	initializes words with the values 9, 10, 11, 12, 13, 14, 15, and 16.
var_defs	initializes words with the values 17 and 18.
.bss	reserves 19 words.
xy	reserves 20 words.

The .bss and .usect directives do not end the current section or begin new sec-
tions; they reserve the specified amount of space, and then the assembler re-
sumes assembling code or data into the current section.

Example 4–1.Sections Directives

```
 1              *********************************************
 2              *  Start assembling into the .text section  *
 3              *********************************************
 4 0000                   .text
 5 0000 0001              .word     1, 2
   0001 0002
 6 0002 0003              .word     3, 4
   0003 0004
 7
 8              *********************************************
 9              *  Start assembling into the .data section  *
10              *********************************************
11 0000                   .data
12 0000 0009              .word     9, 10
   0001 000A
13 0002 000B              .word     11, 12
   0003 000C
14
15              *********************************************
16              *  Start assembling into a named, initial-  *
17              *  ized section, var_defs                   *
18              *********************************************
19 0000                   .sect     "var_defs"
20 0000 0011              .word     17, 18
   0001 0012
21
22              *********************************************
23              *  Resume assembling into the .data section *
24              *********************************************
25 0004                   .data
26 0004 000D              .word     13, 14
   0005 000E
27 0000                   .bss      sym, 19    ; Reserve space
28                                             ; in .bss
29 0006 000F              .word     15, 16     ; Still in .data
   0007 0010
30
31              *********************************************
32              **  Resume assembling into the .text section *
33              *********************************************
34 0004                   .text
35 0004 0005              .word     5, 6
   0005 0006
36 0000      usym    .usect    "xy",20    ; Reserve space
37                                             ; in xy
38 0006 0007              .word     7, 8       ; Still in .text
   0007 0008
```

4.3   Directives That Initialize Constants

Several directives assemble values for the current section:

❑ The **.bes** and **.space** directives reserve a specified number of bits in the current section. The assembler fills these reserved bits with 0s.

You can reserve a specified number of words by multiplying the number of bits by 16.

■ When you use a label with .space, it points to the *first* word that contains reserved bits.

■ When you use a label with .bes, it points to the *last* word that contains reserved bits.

Figure 4–1 shows the .space and .bes directives. Assume that the following code has been assembled for this example:

```
45 0007   0100                .word 100h,200h
   0008   0200
46 0009          Res_1:     .space 17
47 000B   000F              .word 15
48 000C          Res_2:     .bes   20
49 000E   00BA              .byte 0BAh
```

Res_1 points to the first word in the space reserved by .space. Res_2 points to the last word in the space reserved by .bes.

Figure 4–1. The .space and .bes Directives
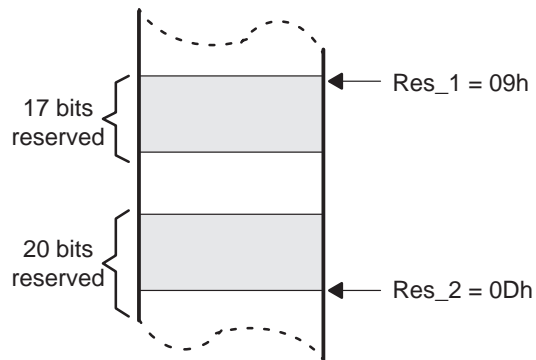
❑ **.byte** places one or more 8-bit values into consecutive words of the current section. This directive is similar to .word, except that the width of each value is restricted to 8 bits.

❑ The **.field** directive places a single value into a specified number of bits in the current word. With a field, you can pack multiple fields into a single word; the assembler does not increment the SPC until a word is filled.

Figure 4–2 shows how fields are packed into a word. For this example, assume the following code has been assembled. Notice that the SPC doesn't change (the fields are packed into the same word):

```
1   0000   0003          .field   3,3
2   0000   0008          .field   8,6
3   0000   0010          .field   16,5
```

Figure 4–2. The .field Directive
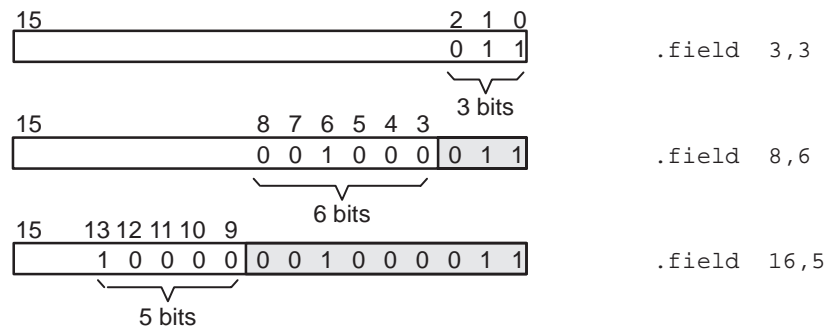
❑ **.float** and **.bfloat** calculate the single-precision 32-bit IEEE floating-point representation of a single floating-point value and store it in two consecutive words in the current section. The least significant word is stored first. The .bfloat directive guarantees the object will not span a page boundary.

❑ **.int** and **.word** place one or more 16-bit values into consecutive words in the current section.

❑ **.long** and **.blong** place 32-bit values into consecutive two-word blocks in the current section. The least significant word is stored first. The .blong directive guarantees the object will not span a page boundary.

❑ **.string** places 8-bit characters from one or more character strings into the current section. This directive is similar to .byte, except that two characters are packed into each word. The last word in a string is padded with null characters (0s) if necessary.

> **Note: The .byte, .word, .int, .long, .string, .float, and .field**
> **Directives in a .struct/.endstruct Sequence**
>
> The .byte, .word, .int, .long, .string, .float, and .field directives *do not* initialize
> memory when they are part of a .struct/.endstruct sequence; rather, they de-
> fine a member's size. For more information about the .struct/.endstruct direc-
> tives, refer to Section 4.8.

Figure 4–3 compares the .byte, .int, .long, .float, .word, and .string direc-
tives. For this example, assume the following code has been assembled:

```
1   0000    aa                  .byte     0AAh, 0BBh
    0001    bb
2   0002    cccc                .word     0CCCCh
3   0003    dddd                .int      0DDDDh
4   0004    ffff                .long     0EEEEFFFFh
    0005    eeee
5   0006    6865                .string   "help"
    0007    6c70
6   0008    ffa8                .float    1.99999
    0009    3fff
```

Figure 4–3. Initialization Directives
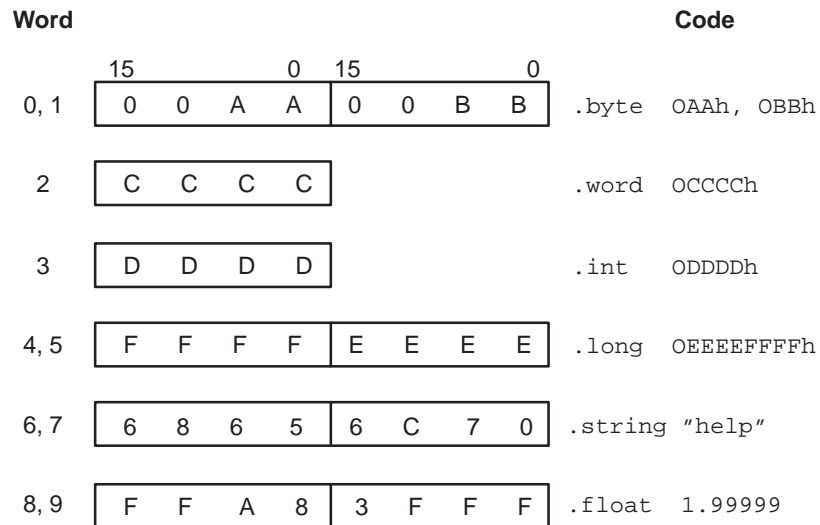
4.4   Directives That Align the Section Program Counter

❑   The **.align** directive aligns the SPC at a 128-word boundary. This ensures that the code following the .align directive begins on a page boundary. If the SPC is already aligned at a page boundary, it is not incremented. Figure 4–4 shows the .align directive; assume that the following code has been assembled:

```
1   0000    0004        .byte     4
2   0080                .align
3   0080    4572        .string   "Error"
    0081    726F
    0082    7200
4   0100                .align
5   0100    0004        .byte     4
```

Figure 4–4. The .align Directive
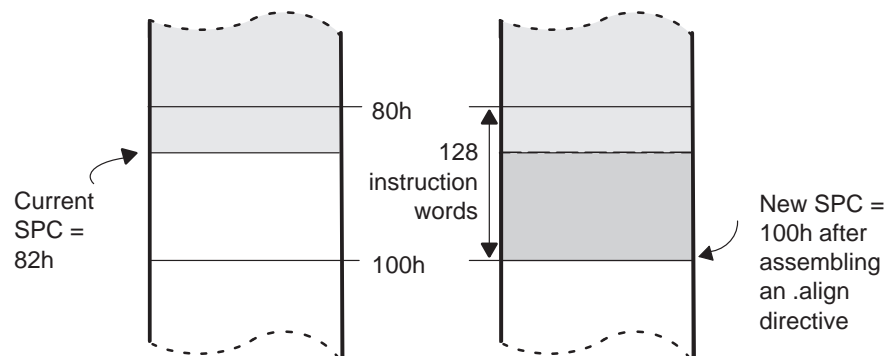
The .even directive

❑   The **.even** directive aligns the SPC so that it points to the next full word. You should use .even after using the .field directive; if the .field directive doesn't fill a word, the .even directive forces the assembler to write out the full word and fill the unused bits with 0s.

Figure 4–2, page 4-9, illustrates the .field directive; Figure 4–5 shows the effect of assembling an .even directive after a .field directive. Assume that the following code has been assembled:

```
11 0005    0001            .field    1,2
12 0005    0003            .field    3,4
13 0005    0006            .field    6,3
14 0006                    .even
```

Figure 4–5. The .even Directive


```
0 0 0 0 0 0 0 | 1 1 0 0 0 1 1 0 1
```

These bits are filled with 0s after   These bits were filled
assembling an .even directive.   by a .field directive.
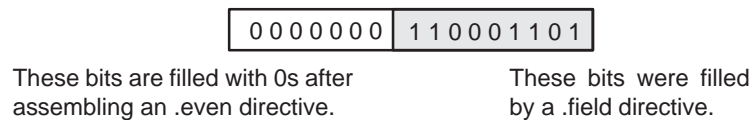
4.5 Directives That Format the Output Listing

The following directives format the listing file:

❏ The **.drlist** and **.drnolist** directives turn the printing of directive lines to the listing file on and off. You can use the .drnolist directive to inhibit the printing of the following directives: .asg, .eval, .var, .sslist, .mlist, .fclist, .ssnolist, .mnolist, .fcnolist, .emsg, .wmsg, .mmsg, .length, .width, and .break. You can use the .drlist directive to turn the listing on again.

❏ The source code contains a listing of false conditional blocks that do not generate code. The **.fclist** and **.fcnolist** directives turn this listing on and off. You can use the .fclist directive to list false conditional blocks exactly as they appear in the source code. You can use the .fcnolist directive to list only the conditional blocks that are actually assembled.

❏ The **.length** directive controls the page length of the listing file. You can use this directive to adjust listings for various output devices.

❏ The **.list** and **.nolist** directives turn the output listing on and off. You can use the .nolist directive to prevent the assembler from printing selected source statements in the listing file. Use the .list directive to turn the listing on again.

❏ The **.mlist** and **.mnolist** directives allow and inhibit macro expansion and loop block listings. You can use the .mlist directive to print all macro expansions and loop blocks to the listing.

❏ The **.option** directive controls certain features in the listing file. This directive has the following operands:

    B   limits the listing of .byte directives to one line.
    D   limits the listing of .int and .word directives to one line.
    F   resets the B, D, L, M, and T directives.
    L   limits the listing of .long directives to one line.
    M   turns off macro expansions in the listing.
    T   limits the listing of .string directives to one line.
    X   produces a cross-reference listing of symbols. (You can also obtain a cross-reference listing by invoking the assembler with the –x option.)

❏ The **.page** directive causes a page eject in the output listing.

❏ The **.sslist** and **.ssnolist** directives allow and inhibit substitution symbol expansion listing. These directives are useful for debugging the expansion of substitution symbols.

❏ The **.tab directive** defines tab size.

❏ The **.title** directive supplies a title that the assembler prints at the top of each page.

❏ The **.width** directive controls the page width of the listing file. You can use this directive to adjust listings for various output devices.

4.6   Directives That Reference Other Files

These directives supply information for or about other files:

❑ The **.copy** and **.include** directives tell the assembler to begin reading source statements from another file. When the assembler finishes reading the source statements in the copy/include file, it resumes reading source statements from the current file. The statements read from a copied file are printed in the listing file; the statements read from an included file are *not* printed in the listing file.

❑ The **.def** directive identifies a symbol that is defined in the current module and that can be used by another module. The assembler enters the symbol in the symbol table.

❑ The **.global** directive declares a symbol external so that it is available to other modules at link time. (For more information on external symbols see subsection 2.7.1, page 2-22.) The .global directive does double duty, acting as a .def for defined symbols and as a .ref for undefined symbols. The linker will resolve an undefined global symbol only if it is used in the program.

❑ The **.mlib** directive supplies the assembler with the name of an archive library that contains macro definitions. When the assembler encounters a macro that is not defined in the current module, it searches for it in the macro library specified with .mlib.

❑ The **.ref** directive identifies a symbol that is used in the current module but defined in another module. The assembler marks the symbol as an undefined external symbol and puts it in the object symbol table so that the linker can resolve its definition.

4.7 Conditional Assembly Directives

Conditional assembly directives enable you to instruct the assembler to assemble certain sections of code according to a true or false evaluation of an expression. Two sets of directives allow you to assemble conditional blocks of code:

❑ The **.if/.elseif/.else/.endif** directives tell the assembler to conditionally assemble a block of code according to the evaluation of an expression.

.if *expression*	marks the beginning of a conditional block and assembles code if the .if condition is true.
.elseif *expression*	marks a block of code to be assembled if .if is false and .elseif is true.
.else	marks a block of code to be assembled if .if is false.
.endif	marks the end of a conditional block and terminates the block.

❑ The **.loop/.break/.endloop** directives tell the assembler to repeatedly assemble a block of code according to the evaluation of an expression.

.loop *expression*	marks the beginning of a repeatable block of code.
.break *expression*	tells the assembler to continue to repeatedly assemble when the .break expression is false, and to go to the code immediately after .endloop if the expression is true.
.endloop	marks the end of a repeatable block.

The assembler supports several relational operators that are useful for conditional expressions. For more information about relational operators, refer to subsection 3.10.4, page 3-27.

4.8   Assembly-Time Symbol Directives

Assembly-time symbol directives equate meaningful symbol names to constant values or strings.

❑   The **.asg** directive assigns a character string to a substitution symbol. The value is stored in the substitution symbol table. When the assembler encounters a substitution symbol, it replaces the symbol with its character string value. Substitution symbols can be redefined.

```
.asg   "10, 20, 30, 40", coefficients

.byte  coefficients
```

❑   The **.set** and **.equ** directives set a constant value to a symbol. The symbol is stored in the symbol table and cannot be refined; for example:

```
bval   .set   0100h
       .byte  bval, bval*2, bval+12
       B      bval
```

The .set and .equ directives produce no object code. The two directives are identical and can be used interchangeably.

❑   The **.struct/.endstruct** directives set up C-like structure definitions, and the **.tag** directive assigns the C-like structure characteristics to a label.

The C-like structure definition enables you to group similar elements together. Element offset calculation is then left to the assembler. The .struct/.endstruct directives do not allocate memory. They simply create a symbolic template that can be used repeatedly.

By assigning structure characteristics to a label, the .tag directive simplifies the symbolic representation and provides the ability to define structures that contain other structures.The .tag directive does not allocate memory, and the structure tag (stag) must be defined before it's used.

```
type   .struct              ; structure tag definition
x      .int
y      .int
t_len  .endstruct

coord  .tag   type          ; declare coord (coordinate)

add    coord.y

       .bss   coord, t_len ; actual memory allocation
```

❑ The **.eval** directive evaluates an expression, translates the results into a character, and assigns the character string to a substitution symbol. This directive is useful for manipulating counters; for example:

```
.asg      1 , x
.loop
.byte     x*10h
.break    x = 4
.eval     x+1, x
.endloop
```

❑ The **.newblock** directive resets local labels. Local labels are symbols of the form $n. (n is a decimal digit.) They are defined when they appear in the label field. Local labels are temporary labels that can be used as operands for jump instructions. The .newblock directive undefines local labels, thus limiting their scope. (For more information on local labels, see subsection 3.9.6, page 3-24.)

4.9 Miscellaneous Directives

These directives enable miscellaneous functions or features:

❑ The **.end** directive terminates assembly. It should be the last source state-
  ment of a program. This directive has the same effect as an end-of-file.

❑ The **.label** directive defines a special symbol that refers to the loadtime
  address within the current section. This is useful when a section loads at
  one address but runs at another. For example, you may want to load a
  block of performance-critical code into slower off-chip memory to save
  space, and move it to high-speed memory to run.

❑ The **.mmregs** directive defines symbolic names for the memory-mapped
  register. Using .mmregs is the same as executing a .set for all memory-
  mapped registers—for example, greg .set 5—and makes it unnecessary
  to define these symbols. See Table 4–2, page 4-58, for a list of memory-
  mapped registers.

❑ The **.port** directive turns on the assembler porting switch. It is equivalent
  to using the –p command line switch (see Section 3.4, page 3-6). If you
  use the .port directive while assembling for a target other than a
  TMS320C5x, it will have no effect.

❑ The **.sblock** directive designates sections for blocking. Blocking is an ad-
  dress alignment mechanism similar to page alignment, but weaker. A
  blocked section is guaranteed to not cross a page boundary (128 words)
  if it is smaller than a page, or to start on a page boundary if it is larger than
  a page. The .sblock directive allows specification of blocking for initialized
  sections only, not uninitialized sections declared with .usect or the .bss
  section. The section names may or may not be enclosed in quotes.

❑ The **.version** directive is the same as the –v assembler option. This tells
  the assembler which generation processor the code is for. Valid device
  numbers are 10, 16, 20, 25, and 50. The default is 25. The .version direc-
  tive must appear before an instruction, or else an error will occur.

These three directives enable you to define your own error and warning messages:

❑ The **.emsg** directive sends error messages to the standard output device. The .emsg directive generates errors in the same manner as the assembler, incrementing the error count and preventing the assembler from producing an object file.

❑ The **.mmsg** directive sends assembly-time messages to the standard output device. The .mmsg directive functions in the same manner as the .emsg and .wmsg directives, but it does not set the error or warning counts and does not prevent the assembler from producing an object file.

❑ The **.wmsg** directive sends warning messages to the standard output device. The .wmsg directive functions in the same manner as the .emsg directive, but it increments the warning count and does not prevent the assembler from producing an object file.

4.10 Directives Reference

The remainder of this chapter is a reference. Generally, the directives are organized alphabetically, one directive per page; however, related directives (such as .if/.else/.endif) are presented together on one page. Here's an alphabetical table of contents for the directives reference:

Syntax	**.align**	
Description	The **.align** directive aligns the section program counter (SPC) on the next 128-word boundary. This ensures that subsequent code begins on a page boundary. The assembler assembles words containing NOPs up to the next 128-word boundary. This directive is useful for aligning code on a page boundary.	

Using the .align directive has two effects:

❏ The assembler aligns the SPC on a 128-word boundary *within* the current section.

❏ The assembler sets a flag that forces the linker to align the section so that individual alignments remain intact when a section is loaded into memory.

Example   In this example, SPC is aligned on the next 128-word boundary to ensure that the code that follows it starts on a new page of memory. Figure 4–6 shows how this code aligns the SPC.

```
1    0000                    .data
2          00FF  Val1    .set    0FFh
3          0076  Val2    .set    76q
4          0001  PP1     .set    1
5          0002  PP2     .set    2
6          0003  PP3     .set    3
7                ;          .
8                ;          .
9                ;          .
10   0080                    .align
11   0080  5202  Page_2: LDP     PP2
12   0081  207F          LAC     Val1
13   0082  0076          ADD     Val2
```

Figure 4–6. The .align Directive

(a) Val1 .set 0FFh
    Val2 .set 78q

0h

80h

SPC = 0h

SPC = 80h

(b) .align
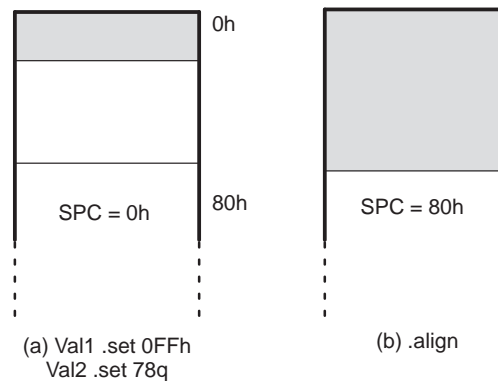
Syntax

.asect **"**section name**"**,address

Description

The **.asect** directive defines a named section whose addresses are absolute with respect to *address*. This command is obsolete. Any section can now be loaded and run at two separate addresses with the linker. The command functions as before for compatibility.

❑ The *section name* identifies the name of the absolute section. The *name* must be enclosed in double quotes.

❑ The *address* identifies the section's absolute starting address in target memory. This address is required the first time that you assemble into a specific absolute section. If you use .asect to continue assembling into an absolute section that already contains code, you *cannot* use the address parameter.

Absolute sections are useful for loading sections of code from off-chip memory into faster on-chip memory. In order to use an absolute section, you must specify the location you want the section to execute from as the address parameter.

Most sections directives create sections with relocatable addresses. The starting SPC value for these sections is always zero; the linker then relocates them where appropriate. The starting SPC value for an absolute section, however, is the specified *address.* The addresses of all code assembled into an absolute section are offsets from the specified address. The linker *does* relocate sections defined with .asect; any labels defined within an absolute section, however, retain their absolute (runtime) addresses. Thus, references to these labels refer to their runtime addresses, even though the section is not initially loaded at its runtime address.

All labels in an absolute section have absolute addresses. The .label directive creates labels with relocatable addresses; this allows you to define a symbol that points to the section's loadtime location in off-chip memory.

After you define a section with .asect, you can use the .sect directive later in the program to continue assembling code into the absolute section.

Note: The .asect Directive Is Obsolete

The .asect directive is obsolete because the SECTIONS directive now allows separate load and run addresses for *any* section; however, the .asect directive is fully functional to allow compatibility with previous versions of the assembler. For more information, refer to Section 8.7, page 8-24.

Syntax   **.asg** [**″**] *character string*[**″**]*, substitution symbol*
                                .eval *well-defined expression, substitution symbol*

Description   The **.asg** directive assigns character strings to substitution symbols. It can be
                      used in many of the same ways as the .set directive, but while .set assigns a
                      constant value (cannot be redefined) to a symbol, .asg assigns a character
                      string (can be redefined) to a substitution symbol.

❑ The assembler assigns the *character string* to the substitution symbol.
   The quotation marks are optional. If there are no quotation marks, the as-
   sembler reads characters up to the first comma and removes leading and
   trailing blanks. In either case, a character string is read and assigned to
   the substitution symbol.

❑ The *substitution symbol* is a required parameter that must be a valid
   symbol name. The substitution symbol may be 32 characters long and
   must begin with a letter. Remaining characters of the symbol can be a
   combination of alphanumeric characters, underscores, and dollar signs.

❑ The *well-defined expression* is a required parameter for the .eval directive.
   A well-defined expression contains only symbols or assembly-time con-
   stants that have been defined before they appear in the expression.

The **.eval** directive performs arithmetic on substitution symbols. This directive
evaluates the expression and assigns the string value of the result to the sub-
stitution symbol. The .eval directive is especially useful as a counter in
.loop/.endloop blocks.

Example   This example shows how .asg and .eval can be used.

```
 1                      .sslist ; show expanded sub. symbols
 2
 3                *
 4                *  .asg/.eval example
 5                *
 6                      .asg       *+,    INC
 7                      .asg       ar0,   FP
 8
 9   0000  cc64   add        #100
10   0001  55a8   mar        INC,   FP
#                 mar        *+,    ar0
11
12                      .asg       0,     x
13                .loop      5
14                      .eval      x+1,   x
15                .word      x
16                .endloop
 1                      .eval      x+1,   x
#                       .eval      0+1,   x
 1   0002  0001   .word      x
#                 .word      1
 1                      .eval      x+1,   x
#                       .eval      1+1,   x
 1   0003  0002   .word      x
#                 .word      2
 1                      .eval      x+1,   x
#                       .eval      2+1,   x
 1   0004  0003   .word      x
#                 .word      3
 1                      .eval      x+1,   x
#                       .eval      3+1,   x
 1   0005  0004   .word      x
#                 .word      4
 1                      .eval      x+1,   x
#                       .eval      4+1,   x
 1   0006  0005   .word      x
#                 .word      5
```

Syntax .bss *symbol*, *size in words* [, *blocking flag*]

Description The **.bss** directive reserves space for variables in the .bss section. Use this directive to allocate variables in RAM.

❏ The *symbol* is a required parameter. It defines a symbol that points to the first location reserved by the directive. The symbol name should correspond to the variable that you're reserving space for.

❏ The *size* is a required parameter. It must be an absolute expression. The assembler allocates size words in the .bss section. There is no default size.

❏ The *blocking flag* is an optional parameter. If you specify a value greater than 0 for this parameter, the assembler allocates size words contiguously. This means that the allocated space will not cross a page boundary unless size is greater than a page, in which case, the object will start on a page boundary.

The assembler follows two rules when it allocates space in the .bss section:

Rule 1 Whenever a hole is left in memory (as shown in Figure 4–7), the .bss directive attempts to fill it. When a .bss directive is assembled, the assembler searches its list of holes left by previous .bss directives and tries to allocate the current block into one of the holes. (This is the standard procedure, whether the blocking flag option has been specified or not.)

Rule 2 If the assembler does not find a hole large enough to contain the requested space, it checks to see whether the blocking flag option is requested.

❏ If you do not request blocking, the memory is allocated at the current SPC.

❏ If you request blocking, the assembler checks to see whether there is enough space between the current SPC and the page boundary. If there is not enough space here, the assembler creates another hole and allocates the space on the next page.

The blocking option allows you to reserve up to 128 words in the .bss section and ensure that they fit on one page of memory. (Of course, you can reserve more than 128 words at a time, but they cannot fit on a single page.) The following example code reserves two blocks of space in the .bss section.

```
memptr:     .bss     a,64,1
memptr1:    .bss     b,70,1
```

Each block must be contained within the boundaries of a single page; after the first block is allocated, however, the second block cannot fit on the current page. As Figure 4–7 shows, the second block is allocated on the next page.

Figure 4–7. Allocating .bss Blocks Within a Page

Memory

0 a — Memory allocated by first .bss directive; 64 words left in the first page.

Hole in memory left because second .bss directive required more than 64 words.

Page Boundary 127 —

b — Memory allocated by second .bss directive; 58 words left in the second page.

Unused memory.

256 —
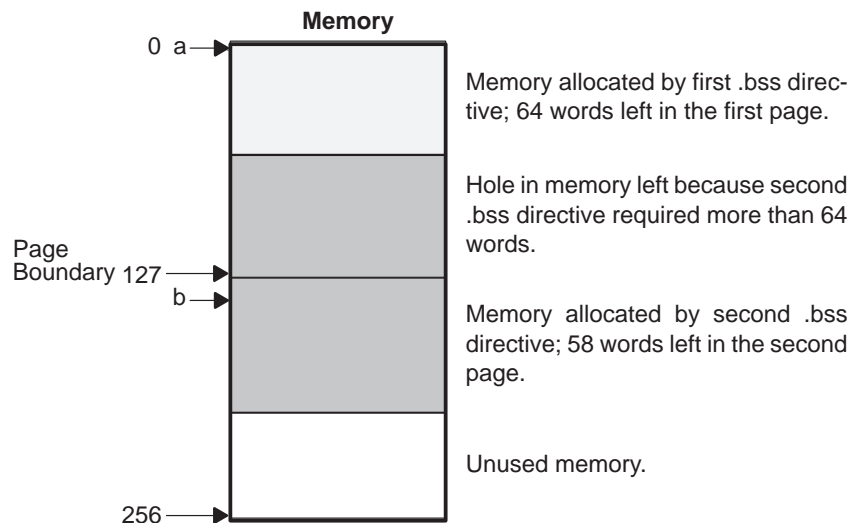
Section directives for initialized sections (.text, .data, .sect, and .asect) end the current section and tell the assembler to begin assembling into another section. Section directives for uninitialized sections (.bss and .usect), however, do not affect the current section. The assembler assembles the .bss or .usect directive and then resumes assembling code into the current section. For more information about COFF sections, see Chapter 2.

Example

In this example, the .bss directive is used to allocate space for two variables, temp and array. The symbol temp points to 4 words of uninitialized space (at .bss SPC = 04h). The symbol array points to 100 words of uninitialized space (at .bss SPC = 0); this space must be allocated contiguously within a page. Symbols declared with the .bss directive can be referenced in the same manner as other symbols and can also be declared external.

```
 1                   **************************************
 2                   *    Begin assembling into .text     *
 3                   **************************************
 4  0000                    .text
 5  0000   CA00            LACK       0
 6
 7                   **************************************
 8                   *  Allocate 4 words in .bss for the  *
 9                   *  symbol named temp                 *
10                   **************************************
11  0000            Var_1: .bss      temp, 4
12
13                   **************************************
14                   *            Still in .text          *
15                   **************************************
16  0001   0056            ADD        56h
17  0002   3873            MPY        73h
18
19                   **************************************
20                   * Allocate 100 words in .bss for the *
21                   * symbol named array; this part of   *
22                   * bss must fit on a single page       *
23                   **************************************
24  0004             .bss        array, 100 , 1
25
26                   **************************************
27                   *            Still in .text          *
28                   **************************************
29  0003   6000            SACL       Var_1
30
31                   **************************************
32                   *   Declare external .bss symbols    *
33                   **************************************
34                    .global    array, temp
```

Syntax   **.byte**   *value$_1$* [, ... , *value$_n$*]

Description   The **.byte** directive places one or more 8-bit values into consecutive words in the current section. Each *value* can be either:

❑ An expression that the assembler evaluates and treats as an 8-bit signed number, or

❑ A character string enclosed in double quotes. Each character in a string represents a separate value.

Values are not packed or sign-extended; each byte occupies the 8 least significant bits of a full 16-bit word. The assembler truncates values that are greater than 8 bits. You can define up to 100 values per .byte instruction. However, the line length, including label (if any), the .byte directive itself and all values, cannot exceed 200 characters. Each character in a string is counted as a separate operand.

If you use a label, it points to the location where the assembler places the first byte.

When you use .byte in a .struct/.endstruct sequence, .byte defines a member's size; it does not initialize memory. For more information about .struct/.endstruct, refer to Section 4.8.

Example   In this example, several 8-bit values—10, –1, abc, and a—are placed into consecutive words in memory. The label *strx* has the value 100h, which is the location of the first initialized word.

```
0    0000                       .space    100h * 16
1    0100    0A    strx    .byte    10,-1,"abc",'a'
     0101    FF
     0102    61
     0103    62
     0104    63
     0105    61
```

Syntax

> **.copy** [″]*filename*[″]
>
> **.include** [″]*filename*[″]

Description

The **.copy** and **.include** directives tell the assembler to read source statements from a different file. The statements that are assembled from a copy file are printed in the assembly listing. The statements that are assembled from an included file are *not* printed in the assembly listing, regardless of the number of .list/.nolist directives that are assembled. The assembler:

1) Stops assembling statements in the current source file

2) Assembles the statements in the copied/included file

3) Resumes assembling statements in the main source file, starting with the statement that follows the .copy or .include directive

The *filename* is a required parameter that names a source file. It may be enclosed in double quotes and must follow operating system conventions. You can specify a full pathname (for example, c:\320\file1.asm). If you do not specify a full pathname, the assembler searches for the file in:

1) The directory that contains the current source file

2) Any directories named with the –i assembler option

3) Any directories specified by the environment variable A_DIR

For more information about the –i option and the environment variable, see Section 3.5, page 3-12.

The .copy and .include directives can be nested within a file being copied or included. The assembler limits this type of nesting to ten levels; the host operating system may set additional restrictions. The assembler precedes the line numbers of copied files with a letter code to identify the level of copying. An **A** indicates the first copied file, **B** indicates a second copied file, etc.

Example 1 In this example, the .copy directive is used to read and assemble source statements from other files; then the assembler resumes assembling into the current file.

copy.asm (source file)	byte.asm (first copy file)	word.asm (second copy file)

```.space 29```
```.copy "byte.asm"```
 	
```**Back in original file```
```.string "done"```
	```** In byte.asm```
	```.byte 32,1+ 'A'```
	```.copy "word.asm"```
	```** Back in byte.asm```
	```.byte 67h + 3q```
		```** In word.asm```
		```.word 0ABCDh, 56q```

Listing file:

```
          1  0000                      .space   29
          2                            .copy    "byte.asm"
A         1                    ** In byte.asm
A         2  0002     20               .byte    32, 1 + 'A'
             0003     42
A         3                            .copy    "word.asm"
B         1                    ** In word.asm
B         2  0004     ABCD             .word    0ABCDh, 56q
             0005     002E
A         4                    ** Back in byte.asm
A         5  0006     6A               .byte    67h+3
             0003
             0004              ** Back in original file
             0005  0007  446F  .string "Done"
                   0008  6E65
```

Example 2 In this example, the .include directive is used to read and assemble source statements from other files; then the assembler resumes assembling into the current file.

include.asm (source file)	byte2.asm (first include file)	word2.asm (second include file)

```.space 29```
```.include "byte2.asm"```
 	
```**Back in original file```
```.string "done"```
	```** In byte2.asm```
	```.byte 32,1+ 'A'```
	```.include "word2.asm"```
	```** Back in byte.asm```
	```.byte 67h + 3q```
		```** In word2.asm```
		```.word 0ABCDh, 56q```

Listing file:

```
1 0000                  .space 29
2                        .include "byte2.asm"
3
4                ** Back in original file
5 0007   446F        .string "Done"
  0008   6E65
```

Syntax   **.data**

Description   The **.data** directive tells the assembler to begin assembling source code into the .data section; .data becomes the current section. The .data section is normally used to contain tables of data or preinitialized variables.

The assembler assumes that .text is the default section. Therefore, at the beginning of an assembly, the assembler assembles code into the .text section unless you use a section control directive.

For more information about COFF sections, see Chapter 2.

Example   In this example, code is assembled into the .data and .text sections.

```
 1                   ****************************************
 2                   **      Reserve space in .data       **
 3                   ****************************************
 4 0000                      .data
 5 0000                      .space   0CCh
 6
 7                   ****************************************
 8                   **        Assemble into .text        **
 9                   ****************************************
10 0000                      .text
11      0000  Index   .set      0
12 0000  2000          LAC       Index
13
14                   ****************************************
15                   **        Assemble into .data        **
16                   ****************************************
17 000C  Table:      .data
18 000D  FFFF                .word     -1    ; Assemble 16-bit
19                                           ; constant into .data
20 000E  FF                  .byte     0FFh  ; Assemble 8-bit
21                                           ; constant into .data
22
23                   ****************************************
24                   **        Assemble into .text        **
25                   ****************************************
26 0001                      .text
27 0001  000C                ADD       Table
28
29                   ****************************************
30                   **   Resume assembling into .data at  **
31                   **   address 0Fh                       **
32                   ****************************************
33 000F                      .data
```

| **Syntax** | **.drlist** |
| | **.drnolist** |

Description   Two directives enable you to control the printing of assembler directives to the listing file:

The **.drlist** directive enables the printing of all directives to the listing file.

The **.drnolist** directive suppresses the printing of the following directives to the listing file:

❑ .asg	❑ .fcnolist	❑ .sslist
❑ .break	❑ .length	❑ .ssnolist
❑ .emsg	❑ .mlist	❑ .var
❑ .eval	❑ .mmsg	❑ .width
❑ .fclist	❑ .mnolist	❑ .wmsg

By default, the assembler prints all directives to the listing file as if the .drlist directive had been used.

Example   This example shows how .drnolist inhibits the listing of the directives listed on the previous page.

Source file:

```
*
*    .drlist/.drnolist example
*
        .length 65
        .width  85
        .asg    0, x
        .loop   2
        .eval   x+1, x
        .endloop

        .drnolist

        .length 55
        .width  95
        .asg    1, x
        .loop   3
        .eval   x+1, x
        .endloop
```

Listing file:

```
     1                           *
     2                           *    .drlist/.drnolist example
     3                           *
     4                                   .length 65
     5                                   .width  85
     6                                   .asg    0, x
     7                                   .loop   2
     8                                   .eval   x+1, x
     9                                   .endloop
1                                        .eval   0+1, x
1                                        .eval   1+1, x
    10
    12
    16                                   .loop   3
    17                                   .eval   x+1, x
    18                                   .endloop
```

Syntax   **.emsg** *string*
                                      .mmsg *string*
                                      .wmsg *string*

Description   These directives allow you to define your own error and warning messages. The assembler tracks the number of errors and warnings it encounters and prints these numbers on the last line of the listing file.

❑ The **.emsg** directive sends error messages to the standard output device in the same manner as the assembler, incrementing the error count and preventing the assembler from producing an object file.

❑ The **.wmsg** directive sends warning messages to the standard output device in the same manner as the .emsg directive, but it increments the warning count rather than the error count, and it does not prevent the assembler from producing an object file.

❑ The **.mmsg** directive sends assembly-time messages to the standard output device in the same manner as the .emsg and .wmsg directives, but it does not set the error or warning counts, and it does not prevent the assembler from producing an object file.

Example   In this example. the macro MSG_EX requires one parameter. The first time the macro is invoked, it has a parameter, PARAM, and it assembles normally. The second time, the parameter is missing, and an error is generated.

Source file:

```
MSG_EX   .macro a
.if    $symlen(a) = 0
.emsg  "ERROR -- MISSING PARAMETER"
.else
 ADDI   @a, R4
.endif
.endm

MSG_EX
```

Listing file:

```
     2 MSG_EX     .macro a
     3            .if    $symlen(a) = 0
     4            .emsg    "ERROR -- MISSING PARAMETER"
     5            .else
     6            ADDI    @a,R4
     7            .endif
     8
     9            .endm
    10
    11 00000000 MSG_EX
1              .if    $symlen(a) = 0
1              .emsg    "ERROR -- MISSING PARAMETER"
 ********* USER ERROR  -  ERROR -- MISSING PARAMETER
1              .else
1              ADDI    @a,R4
1              .endif
1

        1 Error,  No Warnings
```

The following message is sent to standard output when the file is assembled:

```
"emsg.asm" line 11: ** USER ERROR **
  ERROR -- MISSING PARAMETER

 1 Error,  No Warnings

Errors in source - Assembler Aborted
```

Syntax		**.end**	

Description The **.end** directive is optional and terminates assembly. It should be the last source statement of a program. The assembler will ignore any source statements that follow an .end directive.

This directive has the same effect as an end-of-file character. You can use .end when you're debugging and would like to stop assembling at a specific point in your code.

Note: Use .endm to End a Macro

Do not use the .end directive to terminate a macro; use the .endm macro directive instead.

Example This example shows how the .end directive terminates assembly. If any source statements follow the .end directive, the assembler ignores them.

```
1   0000         Start: .space    300
2         000F   temp   .set      15
3   0000                .bss      loc1,48h
4   0013  CE1B          ABS
5   0014  000F          ADD       temp
6   0015  6000          SACL      loc1
7                       .end
```

Syntax	**.even**

Description   The **.even** directive aligns the section program counter (SPC) at the next full word. When you use the .field directive, you can follow it with the .even directive. This forces the assembler to write out a partially filled word before initializing fields in the next word. The assembler will fill the unused bits with 0s. If the SPC is already on a word boundary (no word is partially filled), .even has no effect.

When you use .even in a .struct/.endstruct sequence, .even aligns structure members; it does not initialize memory. For more information about .struct/.endstruct, refer to Section 4.8, page 4-16.

Example   In this example, word 0 is initialized with several fields; the .even directive causes the next field to be placed in word 1.

```
 1                   ********************************
 2                   *   Initialize a 3-bit field   *
 3                   ********************************
 4   0000   0003               .field   03h,3
 5
 6                   ********************************
 7                   *   Initialize a 6-bit field   *
 8                   ********************************
 9   0000   0008               .field   08h,6
10
11                   ********************************
12                   *   Initialize a 5-bit field   *
13                   ********************************
14   0000   000F               .field   0Fh,5
15
16                   ********************************
17                   *      Write out the word      *
18                   ********************************
19   0001                      .even
20
21                   ********************************
22                   *   This field is in the next  *
23                   *             word             *
24                   ********************************
25   0001   0002               .field   02h,2
```

Figure 4–8 shows how this example initializes word 0. The first 14 bits are initialized by .field directives; the remaining bits are set to 0 by the .even directive.

Figure 4–8. The .even Directive
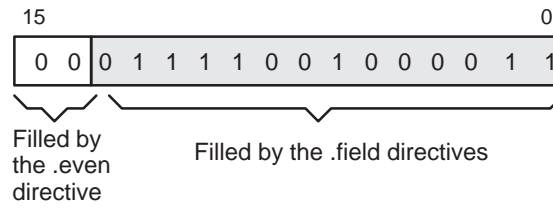
Syntax   **.fclist**

                       .fcnolist

Description   Two directives enable you to control the listing of false conditional blocks:

The **.fclist** directive allows the listing of false conditional blocks (conditional blocks that do not produce code).

The **.fcnolist** directive suppresses the listing of false conditional blocks until a .fclist directive is encountered. With .fcnolist, only code in conditional blocks that are actually assembled appears in the listing. The .if, .elseif, .else, and .endif directives do not appear.

By default, all conditional blocks are listed; the assembler acts as if the .fclist directive had been used.

Example   This example shows the assembly language file and the listing file for code with and without the conditional blocks listed.

Source file:

```
a    .set    1
b    .set    0
     .fclist
     .if     a
     addk    #1024
     .else
     adlk    #1024*10
     .endif
     .fcnolist
     .if     b
     addk    #1024
     .else
     adlk    #1024*10
     .endif
```

Listing file:

```
1      0001  a       .set    1
2      0000  b       .set    0
3            .fclist
4
5            .if     a
6   0000  d002  addk    #1024
    0001  0400
7            .else
8            adlk    #1024*10
9            .endif
10
11           .fcnolist
12
17  0002  d002  adlk    #1024*10
    0003  2800
```

Syntax	**.field** *value* [, *size in bits*]

Description   The **.field** directive initializes multiple-bit fields within a single word of memory. This directive has two operands:

❑ *Value* is a required parameter; it is an expression that is evaluated and placed in the field. If the value is relocatable, *size* must be 16.

❑ *Size* is an optional parameter; it specifies a number from 1 to 16, which is the number of bits in the field. If you do not specify a size, the assembler assumes the size is 16 bits. If you specify a value that cannot fit into size bits, the assembler truncates the value and issues a warning message. For example, .field 3,1 causes the assembler to truncate the value 3 to 1; the assembler also prints the message:

```
***warning – value truncated
```

Successive field directives pack values into the specified number of bits in the current word, starting at the least significant bit. If the assembler encounters a field size that does not fit into the current word, it writes out the word, increments the SPC, and begins packing fields into the next word. You can use the .even directive to force the next .field directive to begin packing into a new word.

If you use a label, it points to the word that contains the field.

When you use .field in a .struct/.endstruct sequence, .field defines a member's size; it does not initialize memory. For more information about .struct/ .endstruct, refer to Section 4.8, page 4-16.

Example   This example shows how fields are packed into a word. Notice that the SPC
                     does not change until a word is filled and the next word is begun.

```
 1                    *******************************
 2                    *   Initialize a 14-bit field   *
 3                    *******************************
 4   0000   0ABC             .field   0ABCh, 14
 5
 6                    *******************************
 7                    *   Initialize a 5-bit field    *
 8                    *   in a new word               *
 9                    *******************************
10   0001   000A  L_F:       .field   0Ah, 5
11
12                    *******************************
13                    *   Initialize a 4-bit field    *
14                    *   in the same word            *
15                    *******************************
16   0001   000C             .field   0Ch,4
17
18                    *******************************
19                    *   Initialize a 3-bit field    *
20                    *   in the same word            *
21                    *******************************
22   0001   0001  x:         .field   01h,3
23
24                    *******************************
25                    *   16-bit relocatable field    *
26                    *   in the next word            *
27                    *******************************
28   0002   0001'            .field   x
```

Figure 4–9 shows how the directives in this example affect memory.

Figure 4–9. The .field Directive
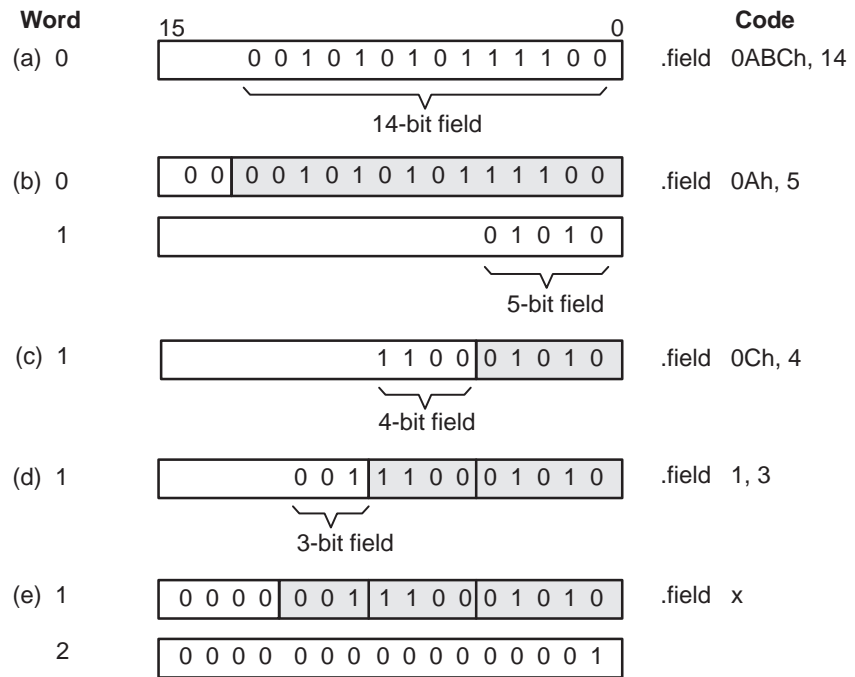
Syntax   **.float**   *value*

                                         .bfloat   *value*

Description   The **.float** and **.bfloat** directives place the floating-point representation of a single floating-point constant into a word in the current section. The .bfloat directive guarantees that the object will not span a page boundary.

Value must be a floating-point constant or a symbol that has been equated to a floating-point constant. Each constant is converted to a floating-point value in IEEE single-precision (32-bit) format.

The 32-bit value consists of three fields:

❑ A 1-bit sign field (*s*)
❑ An 8-bit biased exponent (*e*)
❑ A 23-bit fraction (*f*)

The value is stored least significant word first, most significant word second, in the following format:

```
31 30      23 22              0
 s    e              f
```
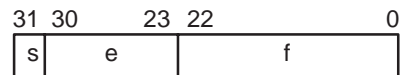
When you use .float in a .struct/.endstruct sequence, .float defines a member's size; it does not initialize memory. For more information about .struct/ .endstruct, refer to Section 4.8, page 4-16.

Example   This example shows .float and .bfloat directives:

```
1    0000    594f        .float      −1.0e25
     0001    e904
2    0002    0000        .bfloat      3
     0003    4040
3    0004    0000        .float      123
     0005    42f6
```

Syntax	**.global** $symbol_1$ $[, ... , symbol_n]$
	.def $symbol_1$ $[, ... , symbol_n]$
	.ref $symbol_1$ $[, ... , symbol_n]$

Description

The **.global**, **.def**, and **.ref** directives identify global symbols, which are defined externally or can be referenced externally.

The **.def** directive identifies a symbol that is defined in the current module and can be accessed by other files. The assembler places this symbol in the symbol table.

The **.ref** directive identifies a symbol that is used in the current module but defined in another module. The linker resolves this symbol's definition at link time.

The **.global** directive acts as a .ref or a .def, as needed.

A global *symbol* is defined in the same manner as any other symbol; that is, it appears as a label or is defined by the .set, .bss, or .usect directive. As with all symbols, if a global symbol is defined more than once, the linker issues a multiple-definition error. .ref always creates a symbol table entry for a symbol, whether the module uses the symbol or not; .global, however, creates an entry only if the module actually uses the symbol.

A symbol may be declared global for two reasons:

❑ If the symbol is *not defined in the current module* (including macro, copy, and include files), the .global or .ref directive tells the assembler that the symbol is defined in an external module. This prevents the assembler from issuing an unresolved reference error. At link time, the linker looks for the symbol's definition in other modules.

❑ If the symbol *is defined in the current module*, the .global or .def directive declares that the symbol and its definition can be used externally by other modules. These types of references are resolved at link time.

Example

This example shows four files:

file1.lst and **file3.lst** are equivalent. Both files define the symbol Init and make it available to other modules; both files use the external symbols x, y, and z. file1.lst uses the .global directive to identify these global symbols; file3.lst uses .ref and .def to identify the symbols.

file2.lst and **file4.lst** are equivalent. Both files define the symbols x, y, and z and make them available to other modules; both files use the external symbol Init. file2.lst uses the .global directive to identify these global symbols; file4.lst uses .ref and .def to identify the symbols.

file1.lst:

```
 1               ; Global symbol defined in this file
 2                       global    Init
 3               ; Global symbols defined in file2.lst
 4                       .global   x, y, z
 5   0000        Init:
 6   0000 0056           ADD       56h
 7   0001 0000           .word     x
 8               ;       .
 9               ;       .
10               ;       .
11                       .end
```

file2.lst:

```
 1               ; Global symbols defined in this file
 2                       .global   x, y, z
 3               ; Global symbol defined in file1.lst
 4                       .global   Init
 5        0001   x:      .set      1
 6        0002   y:      .set      2
 7        0003   z:      .set      3
 8   0000 0000           .word     Init
 9               ;       .
10               ;       .
11               ;       .
12                       .end
```

file3.lst:

```
 1               ; Global symbol defined in this file
 2                       .def      Init
 3               ; Global symbols defined in file4.lst
 4                       .ref      x, y, z
 5   0000        Init:
 6   0000 0056           ADD       56h
 7   0001 0000           .word     x
 8               ;       .
 9               ;       .
10               ;       .
11                       .end
```

file4.lst:

```
 1               ; Global symbols defined in this file
 2                       .def      x, y, z
 3               ; Global symbol defined in file3.lst
 4                       .ref      Init
 5        0001   x:      .set      1
 6        0002   y:      .set      2
 7        0003   z:      .set      3
 8   0000 0000           .word     Init
 9               ;       .
10               ;       .
11               ;       .
12                       .end
```

Syntax
> **.if**   *well-defined expression*
> **.elseif**   *well-defined expression*
> **.else**
> **.endif**

Description   Four directives provide conditional assembly:

The **.if** directive marks the beginning of a conditional block. The *well-defined expression* is a required parameter.

❏   If the expression evaluates to *true* (nonzero), the assembler assembles the code that follows the expression (up to a .elseif, .else, or .endif).

❏   If the expression evaluates to *false* (0), the assembler assembles code that follows a .elseif (if present), .else (if present), or .endif (if no .elseif or .else is present).

The **.elseif** directive identifies a block of code to be assembled when the .if expression is false (0) and the .elseif expression is true (nonzero). When the .elseif expression is false, the assembler continues to the next .elseif (if present), .else (if present), or .endif. The .elseif directive is optional in the conditional block, and more than one .elseif can be used. If an expression is false and there is no .elseif statement, the assembler continues with the code that follows a .else (if present) or .endif.

The **.else** directive identifies a block of code that the assembler assembles when the .if expression and all .elseif expressions are false (0). This directive is optional in the conditional block; if an expression is false and there is no .else statement, the assembler continues with the code that follows the .endif.

The **.endif** directive terminates a conditional block.

The .elseif and .else directives can be used in the same conditional assembly block, and the .elseif directive can be used more than once within a conditional assembly block.

For information about relational operators, see subsection 3.10.4, page 3-27.

Example   This example shows conditional assembly.

```
 1        0001   sym1   .set   1
 2        0002   sym2   .set   2
 3        0003   sym3   .set   3
 4        0004   sym4   .set   4
 5               If_4:  .if    sym4 = sym2 * sym2
 6  0000 0004           .byte  sym4   ;  Equal values
 7                      .else
 8                      .byte  sym2 * sym2; Unequal values
 9                      .endif
10               If_5:  .if sym1 <= 10
11  0001 000A           .byte  10      ; Less than/equal
12                      .else
13                      .byte  sym1   ; Greater than
14                      .endif
15               If_6:  .if sym3 * sym2 != sym4 + sym2
16                      .byte  sym3 * sym2 ;Unequal values
17                      .else
18  0002 0006           .byte  sym4 + sym2  ;Equal values
19                      .endif
20               If_7   .if    sym1 = 2
21                      .byte  sym1
22                      .elseif sym2 + sym3 = 5
23  0003 0005           .byte  sym2 + sym3
24                      .endif
```

Syntax   **.int**   *value*$_1$ *[, ... , value*$_n$*]*
                              .**word**   *value*$_1$ *[, ... , value*$_n$*]*

Description   The **.int** and **.word** directives are equivalent; they place one or more values into consecutive 16-bit fields in the current section.

The *values* can be either absolute or relocatable expressions. If an expression is relocatable, the assembler generates a relocation entry that refers to the appropriate symbol; the linker can then correctly patch (relocate) the reference. This allows you to initialize memory with pointers to variables or labels.

You can use as many values as fit on a single line. If you use a label, it points to the first initialized word.

When you use .int or .word in a .struct/.endstruct sequence, they define a member's size; they do not initialize memory. For more information about .struct/.endstruct, refer to Section 4.8, page 4-16.

Example 1   This example uses the .int directive to initialize words.

```
1  0000                  .space 73h
2  0000                  .bss   page,128
3  0080                  .bss   symptr,3
4  0008 2056   Inst:  LAC   056h
5  0009 000A           .int  10, symptr, −1, 35+'a', Inst
   000A 0080
   000B FFFF
   000C 0084
   000D 0008
```

Example 2   In this example, the .word directive is used to initialize words. The symbol WordX points to the first word that is reserved.

```
1  0000 0C80   WordX: .word 3200, 1+'AB', −0AFh, 'X'
   0001 4143
   0002 FF51
   0003 0058
```

Syntax	**.label** *symbol*

Description   The **.label** directive defines a special *symbol* that refers to the loadtime address rather than the runtime address within the current section. Most sections created by the assembler have relocatable addresses. The assembler assembles each section as if it started at 0, and the linker relocates it to the address at which it loads and runs.

For some applications, it is desirable to have a section load at one address and run at a *different* address. For example, you may wish to load a block of performance-critical code into slower off-chip memory to save space, and then move the code to high-speed on-chip memory to run it.

Such a section is assigned two addresses at link time, a load address and a run address. All labels defined in the section are relocated to refer to the runtime address so that references to the section (such as branches) are correct when the code runs.

The .label directive creates a special label that refers to the *loadtime* address. The label is useful primarily to designate where the section was loaded for purposes of the code that relocates the section.

Example   This example shows the use of a loadtime address label.

```
;---------------------------------------------
; .label Example
;---------------------------------------------
        .sect  ".examp"
        .label examp_load; load address of section
start:                  ; run address of section
        <code>
finish:                 ; run address of section end
        .label examp_end ; load address of section end
```

For more information about assigning runtime and loadtime addresses in the linker, refer to Section 8.8, page 8-33.

Syntax

> **.length**   *page length*
> **.width**   *page width*

Description

The **.length** directive sets the page length of the output listing file. It affects the current and following pages; you can reset the page length with another .length directive.

- ❑ Default length: 60 lines
- ❑ Minimum length: 1 line
- ❑ Maximum length: 32,767 lines

The **.width** directive sets the page width of the output listing file. It affects the next line assembled and the lines following; you can reset the page width with another .width directive.

- ❑ Default width: 80 characters
- ❑ Minimum width: 80 characters
- ❑ Maximum width: 200 characters

The width refers to a full line in a listing file; the line counter value, SPC value, and object code are counted as part of the width of a line. Comments and other portions of a source statement that extend beyond the page width are truncated in the listing.

The assembler does not list the .width and .length directives.

Example

In this example, the page length and width are changed.

```
********************************************
**        Page length = 65 lines          **
**        Page width  = 85 characters      **
********************************************
          .length    65
          .width     85


********************************************
**        Page length = 55 lines          **
**        Page width  = 100 characters     **
********************************************
          .length    55
          .width     100
```

Syntax   **.list**
                                    .nolist

Description   Two directives enable you to control the printing of the source listing:

The **.list** directive allows the printing of the source listing.

The **.nolist** directive suppresses the source listing output until a .list directive is encountered. The .nolist directive can be used to reduce assembly time and the source listing size. It can be used in macro definitions to inhibit the listing of the macro expansion.

The assembler does not print the .list or .nolist directives or the source statements that appear after a .nolist directive. However, it continues to increment the line counter. You can nest the .list/.nolist directives. Each .nolist needs a matching .list to restore the listing.

By default, the source listing is printed to the listing file; the assembler acts as if a .list directive has been used.

 Note: Creating a Listing File (–l option)

 If you don't request a listing file when you invoke the assembler, the assembler ignores the .list directive.

Example   This example shows how the .copy directive inserts source statements from another file. The first time this directive is encountered, the assembler lists the copied source lines in the listing file. The second time this directive is encountered, the assembler does not list the copied source lines, because a .nolist directive was assembled. Note that the .nolist, the second .copy, and the .list directives do not appear in the listing file. Note also that the line counter is incremented, even when source statements are not listed.

Source file:

```
            .copy      "copy2.asm"
* Back in original file
            .nolist
            .copy      "copy2.asm"
            .list
* Back in original file
            .string    "Done"
```

Listing file:

```
    1                       .copy   "copy2.asm"
A   1               * In copy2.asm (copy file)
A   2 0000    0020          .word   32, 1+'A'
      0001    0042
    2
    3               * Back in original file
    9 0004    446F          .string "Done"
      0005    6E65
```

Syntax .long value₁ [, ... , value_n]

 .blong value₁ [, ... , value_n]

Description The **.long** and **.blong** directives place one or more 32-bit values into consecu-
tive words in the current section. The least significant word is stored first. The
.blong directive guarantees that the object will not span a page boundary.

The *value* operand can be either an absolute or relocatable expression. If an
expression is relocatable, the assembler generates a relocation entry that
refers to the appropriate symbol; the linker can then correctly patch (relocate)
the reference. This allows you to initialize memory with pointers to variables
or with labels.

You can use up to 100 values, but they must fit on a single source statement
line. If you use a label, it points to the first word that is initialized.

When you use .long in a .struct/.endstruct sequence, .long defines a member's
size; it does not initialize memory. For more information about .struct/
.endstruct, refer to Section 4.8, page 4-16.

Example This example shows how the .long and .blong directives initialize double
words.

```
2   0008    ABCD    Dat1:  .long     0ABCDh,'A'+100h,'g','o'
    0009    0000
    000A    0041
    000B    0000
    000C    0067
    000D    0000
    000E    006F
    000F    0000
3   0010    0008           .blong    Dat1,0AABBCCDDh
    0011    0000
    0012    CCDD
    0013    AABB
```

Syntax

                 .loop *[well-defined expression]*
                 .break *[well-defined expression]*
                 .endloop

Description

Three directives enable you to repeatedly assemble a block of code:

The **.loop** directive begins a repeatable block of code. The optional expression evaluates to the loop count (the number of loops to be performed). If there is no expression, the loop count defaults to 1024, unless the assembler first encounters a .break directive with an expression that is true (nonzero) or omitted.

The **.break** directive is optional, along with its expression. When the expression is false (0), the loop continues. When the expression is true (non-zero) or omitted, the assembler breaks the loop and assembles the code after the .endloop directive.

The **.endloop** directive terminates a repeatable block of code; it executes when the .break directive is true (nonzero) or when number of loops performed equals the loop count given by .loop

Example

This example illustrates how .loop, .break, and .endloop can be used with the .eval directive. The code in the first six lines expands to the code listed immediately afterward.

```
1                    .eval 0, x
2            coef    .loop
3                    .word      x*100
4                    .eval      x+1, x
5                    .break     x = 6
6                    .endloop
1    0000  0000      .word      0*100
1                    .eval      0+1, x
1                    .break     1 = 6
1    0001  0064      .word      1*100
1                    .eval      1+1, x
1                    .break     2 = 6
1    0002  00c8      .word      2*100
1                    .eval      2+1, x
1                    .break     3 = 6
1    0003  012c      .word      3*100
1                    .eval      3+1, x
1                    .break     4 = 6
1    0004  0190      .word      4*100
1                    .eval      4+1, x
1                    .break     5 = 6
1    0005  01f4      .word      5*100
1                    .eval      5+1, x
1                    .break     6 = 6
```

Syntax   **.mlib**   ["]*filename*["]

Description   The **.mlib** directive provides the assembler with the name of a macro library.
A macro library is a collection of files that contain macro definitions. These files
are bound into a single file (called a library or archive) by the archiver. Each
member of a macro library may contain one macro definition that corresponds
to the name of the file. Macro library members must be *source* files (not object
files).

The *filename* of a macro library member must be the same as the macro name,
and its extension must be .asm. The filename must follow host operating sys-
tem conventions; it may be enclosed in double quotes. You can specify a full
pathname (for example, c:\320\macs.lib). If you do not specify a full pathname,
the assembler searches for the file in:

1)   The directory that contains the current source file
2)   Any directories named with the –i assembler option
3)   Any directories specified by the environment variable A_DIR

For more information about the –i option and the environment variable, see
Section 3.5, page 3-12.

When the assembler encounters a .mlib directive, it opens the library and
creates a table of the library's contents. The assembler enters the names of
the individual library members into the opcode table as library entries. This re-
defines any existing opcodes or macros that have the same name. If one of
these macros is called, the assembler extracts the entry from the library and
loads it into the macro table. The assembler expands the library entry in the
same way it expands other macros, but it does not place the source code into
the listing. Only macros that are actually called from the library are extracted,
and they are extracted only once.

Example

In this example, a macro library is created that defines two macros, inc1 and dec1. The file inc1.asm contains the definition of inc1, and dec1.asm contains the definition of dec1.

inc1.asm	dec1.asm
```* Macro for incrementing``` ```inc1 .MACRO reg``` ``` LARP reg``` ``` ADRK 1``` ``` .ENDM```	```* Macro for decrementing``` ```dec1 .MACRO reg``` ``` LARP reg``` ``` SBRK 1``` ``` .ENDM```

Use the archiver to create a macro library:

```
dspar –a mac inc1.asm dec1.asm
```

Now you can use the .mlib directive to reference the macro library and define the inc1 and dec1 macros:

```
      1   0000            .mlib  "mac.lib"
      2   0000            inc1  AR0       ; Macro call
1         0000   5588   LARP  AR0
1         0001   7E01   ADRK  1
      3   0002            dec1  AR1       ; Macro call
1         0002   5589   LARP  AR1
1         0003   7F01   SBRK  1
```

Syntax   **.mlist**

                              .mnolist

Description   Two directives enable you to control the listing of macro and repeatable block expansions in the listing file:

The **.mlist** directive allows macro and .loop/.endloop block expansions in the listing file.

The **.mnolist** directive suppresses macro and .loop/.endloop block expansions in the listing file.

By default, all code encountered in macros and .loop/.endloop blocks is listed; the assembler acts as if the .mlist directive had been used.

Example   In this example, a macro named str_3 is defined. The first time the macro is called, the macro expansion is listed (by default). The second time the macro is called, the macro expansion is not listed, because a .mnolist directive was assembled. The third time the macro is called, the macro expansion is again listed because a .mlist directive was assembled.

```
        1                 str_3    .MACRO    p1,p2,p3
        2                          .string   ":p1:",":p2:",":p3:"
        3                          .ENDM
        4
        5 0000                     str_3     "red","green","blue"
1         0000 7265                .string   "red","green","blue"
          0001 6467
          0002 7265
          0003 656e
          0004 626c
          0005 7565
        6
        7                          .mnolist
        8 0006                     str_3     "red","green","blue"
        9
       10                          .mlist
       11 000c                     str_3     "red","green","blue"
1         000c 7265                .string   "red","green","blue"
          000d 6467
          000e 7265
          000f 656e
          0010 626c
          0011 7565
```

Syntax   **.mmregs**

Description   The **.mmregs** directive defines global symbolic names for the TMS320 registers and places them in the global symbol table. It is equivalent to executing greg .set 5, imr .set 4, etc. The symbols are local and absolute. Using the .mmregs directive makes it unnecessary to define these symbols.

If you use TMS320C50, TMS320C25, or TMS320C2xx, the symbols are placed as shown in Table 4–2.

Table 4–2. Memory-Mapped Registers

Name	C2x Only	C2xx Only	C5x Address Dec	Hex	Description
			0–3	0–3	Reserved
IMR	4	4	4	4	Interrupt mask register
GREG	5	5	5	5	Global memory allocation register
IFR		6	6	6	Interrupt flag register
PMST			7	7	Processor mode status register
RPTC			8	8	Repeat counter register
BRCR			9	9	Block repeat counter register
PASR			10	A	Block repeat program address start register
PAER			11	B	Block repeat program address end register
TREG0			12	C	Temporary register used for multiplicand
TREG1			13	D	Temporary register used for dynamic shift count
TREG2			14	E	Temporary register used as bit pointer in dynamic bit test
DBMR			15	F	Dynamic bit manipulation register
AR0			16	10	Auxiliary register zero
AR1			17	11	Auxiliary register one
AR2			18	12	Auxiliary register two
AR3			19	13	Auxiliary register three

Table 4–2.Memory-Mapped Registers (Continued)

Name	C2x Only	C2x Only	C5x Address Dec	Hex	Description
AR4			20	14	Auxiliary register four
AR5			21	15	Auxiliary register five
AR6			22	16	Auxiliary register six
AR7			23	17	Auxiliary register seven
INDX			24	18	Index register
ARCR			25	19	Auxiliary register compare register
CBSR1			26	1A	Circular buffer 1 start register
CBER1			27	1B	Circular buffer 1 end register
CBSR2			28	1C	Circular buffer 2 start register
CBER2			29	1D	Circular buffer 2 end register
CBCR			30	1E	Circular buffer control register
BMAR			31	1F	Block move address register
DRR	0	0	32	20	Data receive register
DXR	1	1	33	21	Data transmit register
SPC			34	22	Serial port control register
			35	23	Reserved
TIM	2	2	36	24	Timer register
PRD	3	3	37	25	Period register
TCR			38	26	Timer control register
			39	27	Reserved
PDWSR			40	28	Program S/W wait-state register
IOWSR			41	29	I/O S/W wait-state register
CWSR			42	2A	S/W wait-state control register
			43–47	2B–2F	Reserved

Syntax   **.newblock**

Description   The **.newblock** directive undefines any local labels currently defined. Local
                        labels are temporary; the .newblock directive resets them and terminates their
                        scope.

                        A local label is a label in the form $n, where n is a single decimal digit. A local
                        label, like other labels, points to an instruction word. Unlike other labels, local
                        labels cannot be used in expressions. Local labels are not included in the sym-
                        bol table.

                        After a local label has been defined and (perhaps) used, you should use the
                        .newblock directive to reset it. The .text, .data, and .sect directives also reset
                        local labels. Local labels that are defined within an include file are not valid out-
                        side of the include file.

Example   This example shows how the local label $1 is declared, reset, and then
                        declared again.

```
 1 0000   2000-  Label1:lac    a
 2 0001   1001-         sub     b
 3 0002   f380          blz    $1
   0003   0007
 4 0004   2001-         lac     b
 5 0005   ff80           b     $2
   0006   0008
 6 0007   2000-  $1     lac     a
 7 0008   0002-  $2     add     c
 8                      .newblock ; Undefine $1 to use it again
 9 0009   f280          blez   $1
   000a   000c
10 000b   6002-         sacl    c
11 000c   5500   $1     nop
```

Syntax   **.option**   *option list*

Description   The **.option** directive selects several options for the assembler output listing.
                       Option list is a list of options separated by commas; each option selects a list-
                       ing feature. These are valid options:

                       B   limits the listing of .byte directives to one line.

                       D   limits the listing of .int and .word directives to one line.

                       F   resets the B, D, L, M, and T directives.

                       L   limits the listing of .long directives to one line.

                       M   turns off macro expansions in the listing.

                       T   limits the listing of .string directives to one line.

                       X   produces a symbol cross-reference listing.

                       Options *are not* case-sensitive.

Example   This example shows how to limit the listings of the .byte, .word, .long, and
.string directives to one line each.

```
 1                  *********************************************
 2                  *  Limit the listing of .byte, .int, .word,*
 3                  *   .long, and .string directives to 1 line *
 4                  *   each                                    *
 5                  *********************************************
 6 0000                      .option   B,D,L,T
 7 0000 00BD                 .byte     -'C',0B0h,5
 8 0003 CCDD                 .long     0AABBCCDDh,536+'A'
 9 0007 15AA                 .word     5546,78h
10 0009 0015                 .int      010101b,356q,85
11 000C 4578                 .string   "Extended Registers"
12
13                  *********************************************
14                  *        Reset the listing options       *
15                  *********************************************
16 0015                      .option   f
17 0015   BD                 .byte     -'C',0B0h,5
   0016   B0
   0017
18 0018 CCDD                 .long     0AABBCCDDh,536+'A'
   0018 AABB
   001A 0259
   001A 0000
19 001C 15AA                 .word     5546,78h
   001D 0078
20 001E 0015                 .int      010101b,356q,85
   001F 00EE
   0020 0055
21 0021 4578                 .string   "Extended Registers"
   0022 7465
   0023 6E64
   0024 6564
   0025 2052
   0026 6567
   0027 6973
   0028 7465
   0029 7273
```

Syntax	**.page**

Description   The **.page** directive produces a page eject in the listing file. The .page directive is not printed in the source listing, but the assembler increments the line counter when it encounters it. Using the .page directive to divide the source listing into logical divisions improves program readability.

Example   This example shows how the .page directive causes the assembler to begin a new page of the source listing.

Source file:

```
        .title   "**** Page Directive Example ****"
;          .
;          .
;          .
        .page
```

Listing file:

```
DSP COFF Assembler, Version X.XX       Tue Feb 7 1:29:32 1995
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**** Page Directive Example ****                              PAGE    1

   2              ;          .
   3              ;          .
   4              ;          .
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**** Page Directive Example ****                              PAGE    2
```

Syntax   **.port**

Description   The **.port** directive turns on the assembler porting switch and is equivalent to
                        using the –p command line switch (see subsection 3.4.1, page 3-6). If you use
                        the .port directive while assembling for a target other than a TMS320C2xx or
                        TMS320C5x, it will have no effect. Use the corresponding –v option on the
                        command line to tell the assembler whether to create code for the
                        TMS320C2xx or the TMS320C5x.

Example   In this example, the 'C2x to 'C5x porting switch is turned on.

```
 1  ****************************************************
 2  **   Turn on C2x to C5x port switch               **
 3  ****************************************************
 4          .port
 5  0000    b90a      LACK   10
 6  0001    7c01  L1 SBRK   1
 7  0002    90aa      SACL   *+,AR2
 8  0003    90a0      SACL   *+
 9  0004    f304      BGZ L1, AR1
    0005    001'  ; *** DELAYED BRANCH REPLACES PREVIOUS INSTRUCTION ***
    0006    8b09      MAR ; *** UPDATE ARx AS IN PREVIOUS BRANCH ***
    0007    8b00      NOP ; *** INSERTED FOR PIPELINE ALIGNMENT ***
10
11  0008    2080  L2 ADD *
12  0009    f100      BBNZ   L2,AR1
    000a    0008  ; *** DELAYED BRANCH REPLACES PREVIOUS INSTRUCTION ***
    000b    8b09      MAR ; *** UPDATE ARx AS IN PREVIOUS BRANCH ***
    000c    8b00      NOP ; *** INSERTED FOR PIPELINE ALIGNMENT ***
13
14  000d    8b8a      LARP   AR2
15  000e    a080      NORM   *
    000f    8b00      NOP ; *** INSERTED FOR PIPELINE PROTECTION ***
    0010    8b00      NOP ; *** INSERTED FOR PIPELINE PROTECTION ***
16  0011    8213'     SAR 2,x       ; pipeline conflict
17  0012    8280      SAR AR2,*      ; pipeline conflict
18
19  0013    0000   x  .word 00h
```

Syntax   **.sblock**   [”]*section name*[”]   [, ”*section name*”, . . .]

Description   The **.sblock** directive designates sections for blocking. Blocking is an address alignment mechanism similar to page alignment, but weaker. A blocked section is guaranteed to not cross a page boundary (128 words) if it is smaller than a page, or to start on a page boundary if it is larger than a page. This directive allows specification of blocking for initialized sections only, not uninitialized sections declared with the .usect or .bss directives. The *section names* may or may not be enclosed in quotes.

Example   In this example, the .text and .data sections are designated for blocking.

```
1 ****************************************
2 ** Specify blocking for the .text     **
3 ** and .data sections                 **
4 ****************************************
5          .sblock       .text, .data
```

Syntax   **.sect**   **"**section name**"**

Description   The **.sect** directive defines a named section that can be used like the default
.text and .data sections. The .sect directive begins assembling source code
into the named section.

The section name identifies a section that the assembler assembles code into.
The name is significant to eight characters and must be enclosed in double
quotes.

The .sect directive is similar to the .asect directive; however, .asect creates a
named section that has *absolute addresses.* If you use the .asect directive to
define an absolute named section, you can use the .sect directive later in the
program to continue assembling code into the absolute section.

For more information about COFF sections, see Chapter 2.

Example   This example shows how two special-purpose sections, Sym_Defs and Vars,
are defined and how code assembles into them.

```
 1              ***********************************************
 2              **    Begin assembling into .text section    **
 3 0000                 .text
 4 0000 2078            LAC    78h ; Assembled into   .text
 5 0001 0036            ADD    36h ; Assembled into   .text
 6
 7              ***********************************************
 8              **    Begin assembling into Sym_Defs section **
 9      0000            .sect    "Sym_Defs"
10 0000 CCCC            .float  0.05; Assembled into   Sym_Defs
   0001 3D4C
11 0002 00AA X:         .word   0AAh; Assembled into   Sym_Defs
12 0003 0002            ADD     X  ; Assembled into   Sym_Defs
13
14              ***********************************************
15              **    Begin assembling into Vars section     **
16 0000                 .sect    "Vars"
17 0010   Word_Len  .set   16
18 0020   DWord_Len .set   Word_Len * 2
19 0008   Byte_Len  .set   Word_Len / 2
20 0053   Str       .set   53h
21
22              ***********************************************
23              **    Resume assembling into .text section   **
24 0002                 .text
25 0002 0042            ADD     42h ; Assembled into  .text
26 0003 03              .byte   3, 4; Assembled into  .text
   0004 04
27
28              ***********************************************
29              **    Resume assembling into Vars section    **
30 0000                 .sect    "Vars"
31 0000 000D            .field  13, Word_Len
32 0001 000A            .field  0Ah, Byte_Len
33 0001 0008            .field  10q, DWord_Len / 8
```

Syntax

symbol   **.set**   *value*

symbol   **.equ**   *value*

Description

The **.set** and **.equ** directives equate a constant value with a symbol. The symbol can then be used in place of a value in assembly source. This allows you to equate meaningful names with constants and other values. The .set and .equ directives are identical and can be used interchangeably.

❏   The *symbol* must appear in the label field.

❏   The symbols in the *value* expression must be previously defined.

Undefined external symbols and symbols that are defined later in the module cannot be used in the expression. If the expression is relocatable, the symbol to which it is assigned is also relocatable.

The value of the expression appears in the object field of the listing. This value is not part of the actual object code and is not written to the output file.

Symbols defined with .set can be made externally visible with the .def or .global directive. In this way, you can define global absolute constants.

Example

This example shows how symbols can be assigned with .set and .equ.

```
 1                          *************************************
 2                          * Equate symbol FP to register R31  *
 3                          *  and use it instead of R31         *
 4                          *************************************
 5       001f         FP      .set    R31
 6 0000  9a1f                 MOV     *FP, A
 7
 8                          *************************************
 9                          * Set symbol count to an integer    *
10                          * expression and use it as an       *
11                          * immediate operand                 *
12                          *************************************
13       0035         count   .equ    100/2 + 3
14 0002  2235                 MOV     #count, A
15
16                          *************************************
17                          * Set symbol symtab to relocatable  *
18                          * expression                        *
19                          *************************************
20 0004  000a         label   .word   10
21       '0005        symtab  .set    label+1
22 0006  '0005                .word   symtab
23
24                          *************************************
25                          * Set symbol nsyms to another       *
26                          * symbol (count) and use it instead *
27                          * of count                          *
28                          *************************************
29       0035         nsyms   .equ    count
30 0008  2235                 MOV     #nsyms, A
```

Syntax

> **.space**   *size in bits*
>
> **.bes**   *size in bits*

Description

The **.space** and **.bes** directives reserve *size* number of bits in the current section and fill them with 0s. The section program counter is incremented to point to the word following the reserved space.

When you use a label with the .space directive, it points to the *first* word reserved. When you use a label with the .bes directive, it points to the *last* word reserved.

Example

This example shows how memory is reserved with .space and .bes.

```
 1                 ***************************************
 2                 *  Begin assembling into .text       *
 3                 ***************************************
 4    0000                        .text
 5
 6                 ***************************************
 7                 *  Reserve 0F0h bits (15 words) in   *
 8                 *  the .text section                 *
 9                 ***************************************
10  0000                          .space    0F0h
11  000F 0100                     .word     100h,200h
    0010 0200
12
13                 ***************************************
14                 *  Begin assembling into .data       *
15                 ***************************************
16  0000                          .data
17  0000 496E                     .string   "In .data"
    0001 202E
    0002 6461
    0003 7461
18
19                 ***************************************
20                 *  Reserve 100 bits in the .data     *
21                 *  section; Res_1 points to the      *
22                 *  first word that contains reserved *
23                 *  bits                              *
24                 ***************************************
25  0004          Res_1:    .space    100
26  000B 000F                     .word     15
27  000C 0004                     .word     Res_1
28
29                 ***************************************
30                 *  Reserve 20 bits in the .data      *
31                 *  section; Res_2 points to the      *
32                 *  last word that contains reserved  *
33                 *  bits                              *
34                 ***************************************
35  000E          Res_2:    .bes      20
36  000F 003                      .word     36h
37  0010 000E                     .word     Res_2
```

Syntax   **.sslist**

                        .ssnolist

Description   Two directives enable you to control substitution symbol expansion in the listing file:

The **.sslist** directive allows substitution symbol expansion in the listing file. The expanded line appears below the actual source line.

The **.ssnolist** directive suppresses substitution symbol expansion in the listing file.

By default, all substitution symbol expansion in the listing file is suppressed; the assembler acts as if the .ssnolist directive had been used. Lines with the pound (#) character denote expanded substitution symbols.

Example   This example shows code that, by default, suppresses the listing of substitution symbol expansion, and it shows the .sslist directive assembled, instructing the assembler to list substitution symbol code expansion.

```
 1   0000                     .bss     x, 1
 2   0001                     .bss     y, 1
 3               ADD2   .macro     a,b
 4                            LAC      a
 5                            ADD      b
 6                            SACL     b
 7                            .endm
 8
 9                            .asg     "*+", INC
10                            .asg     ar0 , FP
11
12   0000   5588             LARP     FP
13   0001   55a0             MAR      INC
14
15   0002                    ADD2     x,y
1    0002   2000-            LAC      x
1    0003   0001-            ADD      y
1    0004   6001-            SACL     y
 16
 17                          .sslist
 18
 19  0005   5588             LARP     FP
#                            LARP     ar0
 20  0006   55a0             MAR      INC
#                            MAR      *+
 21
 22  0007                    ADD2     x,y
1     0007   2000-           LAC      a
#                            LAC      x
1     0008   0001-           ADD      b
#                            ADD      y
1     0009   6001            SACL     b
#                            SACL     y
```

Syntax	**.string** ″*string₁*″ [, ... , ″*stringₙ*″]

Description   The **.string** directive places 8-bit characters from a character string into the current section. The data is packed so that each word contains two 8-bit bytes. Each *string* is either:

❏ An expression that the assembler evaluates and treats as a 16-bit signed number, or

❏ A character string enclosed in double quotes. Each character in a string represents a separate byte.

Values are packed into words, starting with the most significant byte of the word. Any unused space is padded with null bytes (0s). This directive differs from .byte in that .byte does not pack values into words.

The assembler truncates any values that are greater than 8 bits. You may have up to 100 operands, but they must fit on a single source statement line.

If you use a label, it points to the first word that is initialized.

When you use .string in a .struct/.endstruct sequence, .string defines a member's size; it does not initialize memory. For more information about .struct/.endstruct, refer to Section 4.8, page 4-16.

Example   This example shows 8-bit values placed into words in the current section.

```
1  0000 4142   Str_Ptr:.string "ABCD"
   0001 4344
2  0002 4142           .string 41h,42h,43h,44h
   0003 4344
3  0004 4175           .string "Austin","SanAntonio","Houston"
   0005 7374
   0006 696E
   0007 5361
   0008 6E20
   0009 416E
   000A 746F
   000B 6E69
   000C 6F48
   000D 6F75
   000E 7374
   000F 6F6E
4  0010 3000           .string 36 + 12
```

Syntax

[*stag*]	**.struct**	[*expr*]
[*mem_0*]	*element*	[*expr_0*]
[*mem_1*]	*element*	[*expr_1*]
.	.	.
.	.	.
.	.	.
[*mem_n*]	**.tag** *stag*	[*expr_n*]
.	.	.
.	.	.
.	.	.
[*mem_N*]	*element*	[*expr_N*]
[*size*]	**.endstruct**	
label	**.tag**	*stag*

Description

The **.struct** directive assigns symbolic offsets to the elements of a data structure definition. This enables you to group similar data elements together and then let the assembler calculate the element offset. This is similar to a C structure or a Pascal record. The .struct directive does not allocate memory; it merely creates a symbolic template that can be used repeatedly.

The **.endstruct** directive terminates the structure definition.

The **.tag** directive gives structure characteristics to a *label*, simplifying the symbolic representation and providing the ability to define structures that contain other structures. The .tag directive does not allocate memory. The structure tag (stag) of a .tag directive must have been previously defined.

stag   is the structure's tag. Its value is associated with the beginning of the structure. If no stag is present, the assembler puts the structure members in the global symbol table with the value of their absolute offset from the top of the structure.

expr   is an optional expression indicating the beginning offset of the structure. Structures default to start at 0.

mem_n   is an optional label for a member of the structure. This label is absolute and equates to the present offset from the beginning of the structure. A label for a structure member cannot be declared global.

element   is one of the following descriptors: .string, .byte, .word, .float, .tag, or .field. All of these, except .tag, are typical directives that initialize memory. Following a .struct directive, these directives describe the structure element's size. They do not allocate memory. A .tag directive is a special case because a stag must be used (as in the definition).

expr$_n$	is an optional expression for the number of elements described. This value defaults to 1. A .string element is considered to be one byte in size, and a .field element is one bit.
size	is an optional label for the total size of the structure.

Note: Directives That Can Appear in a .struct/.endstruct Sequence

The only directives that can appear in a .struct/.endstruct sequence are element descriptors, conditional assembly directives, the .align directive (which aligns the member offsets on byte boundaries) and the .even directive (which aligns the member offsets on word boundaries). Empty structures are illegal.

These examples show various uses of the .struct, .tag, and .endstruct directives.

Example 1

```
1        0000   real_rec  .struct                    ; stag
2        0000   nom       .int                       ; member1  = 0
3        0001   den       .int                       ; member2  = 1
4        0002   real_len  .endstruct                 ; real_len = 2
5
6  0000  2001-            add   real+real_rec.den     ; access structure elem
7
8  0000                   .bss  real, real_len        ; allocate
```

Example 2

```
1
2  0000  0000   cplx_rec  .struct                    ; stag
3        0000   reali     .tag      real_rec         ; member1  = 0
4        0002   imagi     .tag      real_rec         ; member2  = 2
5        0004   cplx_len  .endstruct                 ; cplx_len = 4
6
7               complex   .tag      cplx_rec         ; assign structure attrib
8
9  0001  2002-            add       complex.reali    ; access structure
10 0002  9002-            sac1      complex.reali
11
12 0003  2005-            add       complex.imagi
13
14 0002                   .bss      complex,cplx_len ; allocate space
```

Example 3

```
1  0000                   .struct            ; no stag puts memNs into
2                                            ; global symbol table
3  0000   x        .int                      ; create 3 dim templates
4  0001   y        .int
5  0002   x        .int
6  0003            .endstruct
```

Example 4

```
1       0000  bit rec   .struct              ; stag
2       0000  stream    .string    64
3       0040  bit7      .field     7         ; bits1 = 64
4       0040  bit9      .field     9         ; bits2 = 64
5       0041  bit10     .field     10        ; bits3 = 65
6       0042  x_int     .int                 ; x_int = 67
7       0042  bit_len   .endstruct           ; length = 68
8
9             bits      .tag       bit_rec
10 0004 2046–           add        bits.bit7 ; move into acc
11 0005 bfb0            add   #007Fh          ; mask off garbage bits
        007f
12
13 0006                 .bss  bits, bit_rec
```

Syntax   **.tab** *size*

Description   The **.tab** directive defines the tab size. Tabs encountered in the source input
                    will be translated to *size* spaces in the listing. The default tab size is eight
                    spaces.

Example   Each of the following lines consists of a single tab character followed by a NOP
                    instruction.

```
 1                      ;default tab size
 2 0000 5500          nop
 3 0001 5500          nop
 4 0002 5500          nop
 5                .tab 4
 6 0003 5500      nop
 7 0004 5500      nop
 8 0005 5500      nop
 9                        .tab 16
10 0006 5500              nop
11 0007 5500              nop
12 0008 5500              nop
13
```

Syntax   **.text**

Description   The **.text** directive tells the assembler to begin assembling into the .text section, which usually contains executable code. The section program counter is set to 0 if nothing has yet been assembled into the .text section. If code has already been assembled into the .text section, the section program counter is restored to its previous value in the section.

.text is the default section. Therefore, at the beginning of an assembly, the assembler assembles code into the .text section unless you specify another sections directive (.data or .sect).

For more information about COFF sections, see Chapter 2.

Example   This example shows code assembled into the .text and .data sections. The .data section contains integer constants, and the .text section contains character strings.

```
 1                  *****************************************
 2                  *  Begin assembling into .data section  *
 3                  *****************************************
 4  0000                    .data
 5  0000    0A              .byte    0Ah,0Bh
    0001    0B
 6
 7                  *****************************************
 8                  *  Begin assembling into .text section  *
 9                  *****************************************
10  0000                    .text
11  0000    4142    Start: .string   "A","B","C"
    0001    4300
12  0002    5859    End:   .string   "X","Y","Z"
    0003    5A00
13  0004    0000            ADD      Start
14  0005    0002            ADD      End
15
16                  *****************************************
17                  * Resume assembling into .data section  *
18                  *****************************************
19  0002                    .data
20  0002    0C              .byte    0Ch,0Dh
    0003    0D
21
22                  *****************************************
23                  * Resume assembling into .text section  *
24                  *****************************************
25  0006                    .text
26  0006    5175            .string   "Quit"
    0007    6974
```

Syntax   **.title**   *"string"*

Description   The **.title** directive supplies a title that is printed in the heading on each listing page. The source statement itself is not printed, but the line counter is incremented.

The *string* is a quote-enclosed title of up to 65 characters. If you supply more than 65 characters, the assembler truncates the string and issues a warning.

The assembler prints the title on the page that follows the directive and on subsequent pages until another .title directive is processed. If you want a title on the first page, the first source statement must contain a .title directive.

Example   In this example, one title is printed on the first page and a different title on succeeding pages.

Source file:

```
            .title    "**** Fast Fourier Transforms ****"
;          .
;          .
;          .
            .title    "**** Floating Point Routines ****"
           .page
```

Listing file:

```
DSP COFF Assembler, Version X.XX        Tue Feb 7 13:47:26 1995
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 **** Fast Fourier Transforms ****                              PAGE    1

   2              ;          .
   3              ;          .
   4              ;          .
DSP COFF Assembler, Version X.XX        Tue Feb 7 13:47:26 1995
Copyright (c)  1987–1995 Texas Instruments Incorporated

 **** Floating Point Routines ****                             PAGE    2
```

Syntax *symbol* **.usect** **"***section name***"**, *size in words* , [*blocking flag*]

Description The **.usect** directive reserves space for variables in an uninitialized, named section. This directive is similar to the .bss directive; both simply reserve space for data and have no contents. However, .usect defines sections that can be placed anywhere in memory, independently of the .bss section.

❑ The *symbol* points to the first location reserved by this invocation of the .usect directive. The symbol corresponds to the name of the variable for which you're reserving space.

❑ The *section name* must be enclosed in double quotes; only the first 8 characters are significant. This parameter names the uninitialized section.

❑ The *size* is an expression that defines the number of words that are reserved in section *name.*

❑ The *blocking flag* is optional. If specified and nonzero, the flag means that this section will be blocked. Blocking is an address mechanism similar to alignment, but weaker. It means that a section is guaranteed not to cross a page boundary (128 words) if it is smaller than a page, and to start on a page boundary if it is larger than a page. This blocking applies to the section, not to the object declared with this instance of the .usect directive.

Other sections directives (.text, .data, .sect, and .asect) end the current section and tell the assembler to begin assembling into another section. The .usect and the .bss directives, however, do not affect the current section. The assembler assembles the .usect and the .bss directives and then resumes assembling into the current section.

Variables that can be located contiguously in memory can be defined in the same specified section; to do so, repeat the .usect directive with the same section name.

For more information about COFF sections, see Chapter 2.

Example This example shows how to use the .usect directive to define two uninitialized, named sections, var1 and var2. The symbol ptr points to the first word reserved in the var1 section. The symbol array points to the first word in a block of 100 words reserved in var1, and dflag points to the first word in a block of 50 words in var1. The symbol vec points to the first word reserved in the var2 section.

Figure 4–10, page 4-78, shows how this example reserves space in two uninitialized sections, var1 and var2.

```
 1                   ************************************
 2                   *       Assemble into .text        *
 3                   ************************************
 4 0000              .text
 5 0000 2003         LAC         03h
 6
 7                   ************************************
 8                   *       Reserve 1 word in var1     *
 9                   ************************************
10 0000     ptr      .usect      "var1", 1
11
12                   ************************************
13                   *  Reserve 100 more words in var1  *
14                   ************************************
15 0001     array    .usect      "var1", 100
16
17 0001 0037         ADD         037h   ; Still in .text
18
19                   ************************************
20                   *   Reserve 50 more words in var1  *
21                   ************************************
22 0065     dflag    .usect      "var1", 50
23
24 0002 0065         ADD         dflag  ; Still in .text
25
26                   ************************************
27                   *      Reserve 100 words in var2   *
28                   ************************************
29 0000     vec      .usect      "var2", 100
30
31 0003 0000         ADD         vec    ; Still in .text
32
33                   ************************************
34                   * Declare an external .usect symbol *
35                   ************************************
36                   .global     array
```

Figure 4–10. The .usect Directive

100 words reserved in var2

151 words reserved in var1
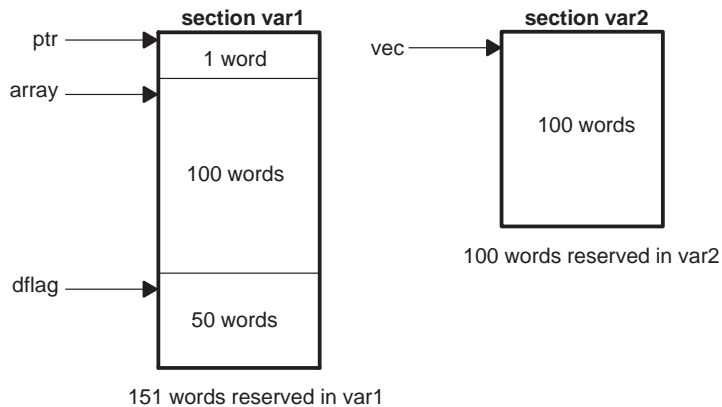
Syntax   **.version** *generation #number*

Description   The **.version** directive tells the assembler which generation processor this code is for. Valid device numbers are 10, 16, 20, 25, and 50. The version directive must appear before an instruction, or else an error will occur. The version directive can be used instead of the –v command line option.

10 refers to TMS320C1x devices

16 refers to the TMS320C16 device

20 refers to TMS320C20 device

25 refers to the TMS320C2x devices

29 refers to the TMS320C2xx devices

50 refers to TMS320C5x devices

Instruction Set Summary

The TMS320C1x, TMS320C2x, TMS320C2xx, and TMS320C5x devices support a base set of general-purpose instructions as well as arithmetic-intensive instructions that are particularly suited for DSP and other numeric-intensive applications.

This chapter contains a table that summarizes the TMS320C1x, TMS320C2x, TMS320C2xx, and TMS320C5x instructions alphabetically. Each table entry shows the syntax for the instruction, indicates which devices support the instruction, and describes instruction operation. Section 5.1 describes the abbreviations used in the table and shows a sample table entry.

The TMS320C2x, TMS320C2xx and TMS320C5x devices have *enhanced instructions*; enhanced instructions are single mnemonics that perform the functions of several similar instructions. Section 5.2 summarizes the enhanced instructions.

This chapter does not cover topics such as opcodes, instruction timing, or addressing modes; the following documents cover such topics in detail:

TMS320C1x User's Guide	(literature number SPRU013)
TMS320C2x User's Guide	(literature number SPRU014)
TMS320C2xx User's Guide	(literature number SPRU127)
TMS320C5x User's Guide	(literature number SPRU056)

These user's guides also contain alphabetical presentations of the instruction sets, similar to the directives reference that begins on page 4-20.

5.1   Using the Summary Table

To help you read the summary table, this section provides an example of a table entry and a list of acronyms.

An Example of a Table Entry

In cases where more than one syntax is used, the first syntax is usually for direct addressing, and the second is usually for indirect addressing. Where three or more syntaxes are used, the syntaxes are normally specific to the device.

This is how the AND instruction appears in the table:

Syntax	1x	2x	2xx	5x	Description
AND *dma*	√	√	√	√	**AND With Accumulator**
AND {*ind*} [,*next ARP*]	√	√	√	√	TMS320C1x and TMS320C2x devices: AND the contents of the addressed data memory location with the 16 LSBs of the accumulator. The 16 MSBs of the accumulator are ANDed with 0s.
AND # *lk* [,*shift*]			√	√	TMS320C2xx and TMS320C5x devices: AND the contents of the addressed data or a 16-bit immediate value to memory location of the accumulator. The 16 MSBs of the accumulator are ANDed with 0s. If a shift is specified, left-shift the constant before the AND. Low-order bits below and high-order bits above the shifted value are treated as 0s.

The first column, *Syntax*, states the mnemonic and the syntaxes for the AND instruction.

The checks in the second through the fifth columns, *(1x, 2x, 2xx, 5x)*, indicate the devices that can be used with each of the syntaxes.

1x   refers to the TMS320C1x devices
2x   refers to the TMS320C2x devices, including TMS320C25
2xx   refers to the TMS320C2xx devices
5x   refers to the TMS320C5x devices

In this example, you can use the first two syntaxes with TMS320C1x, TMS320C2x, TMS320C2xx, and TMS320C5x devices, but you can use the last syntax only with TMS320C2xx, and TMS320C5x devices.

The sixth column, *Description*, briefly describes how the instruction functions. Often, an instruction functions slightly differently for the different devices: read the entire description before using the instruction.

Symbols and Acronyms

The following table lists the instruction set symbols and acronyms used throughout this chapter:

Table 5–1. Symbols and Acronyms Used in the Instruction Set Summary

Symbol	Description	Symbol	Description
# lk	16-bit immediate value	INTM	interrupt mask bit
# k	8-bit immediate value	INTR	interrupt mode bit
{ind}	indirect address	OV	overflow bit
ACC	accumulator	P	program bus
ACCB	accumulator buffer	PA	port address
AR	auxiliary register	PC	program counter
ARCR	auxiliary register compare	PM	product shifter mode
ARP	auxiliary register pointer	pma	program memory address
BMAR	block move address register	RPTC	repeat counter
BRCR	block repeat count register	shift*n*	shift data
C	carry bit	src	source address
DBMR	dynamic bit manipulation register	ST	status register
dma	data memory address	SXM	sign-extension mode bit
DP	data memory page pointer	TC	test/control bit
dst	destination address	T	temporary register
FO	format status list	TREGn	TMS320C5x temporary register (0–2)
FSX	external framing pulse	TXM	transmit mode status register
IMR	interrupt mask register	XF	XF pin status bit

Based on the device, this is how the indirect address {ind} is interpreted:

{ind}   **'C1x**:   { * | * + | *– }
           'C2x: { * | * + | *– | *0+ | *0– | *BR0+ | *BR0– }
           'C2xx: { * | * + | *– | *0+ | *0– | *BR0+ | *BR0– }
           'C5x: { * | * + | *– | *0+ | *0– | *BR0+ | *BR0– }

For example:

```
ADD {ind}
```

is interpreted as:

'C1x devices   ADD { * | * + | *– }
'C2x devices   ADD { * | * + | *– | *0+ | *0– | *BR0+ | *BR0– }
'C2xx devices   ADD { * | * + | *– | *0+ | *0– | *BR0+ | *BR0– }
'C5x devices   ADD { * | * + | *– | *0+ | *0– | *BR0+ | *BR0– }

Based on the device, this is the valid entries for shift$n$ are:

shift   **'C1x**:   0–15 bits
         'C2x: 0–15 bits
         'C2xx: 0–16 bits
         'C5x: 0–16 bits

shift1   **'C1x**:   n/a
         'C2x: 0–15 bits
         'C2xx: 0–16 bits
         'C5x: 0–16 bits

shift2   **'C1x**:   n/a
         'C2x: n/a
         'C2xx: 0–15 bits
         'C5x: 0–15 bits

5.2 Enhanced Instructions

An enhanced instruction is a single mnemonic that performs the functions of several similar instructions. For example, one mnemonic, ADD, performs the ADD, ADDH, ADDK, and ADLK functions. These enhanced instructions are valid for TMS320C2x, TMS320C2xx, and TMS320C5x devices (not TMS320C1x).

Table 5–2 below summarizes the enhanced instructions and the functions that the enhanced instructions perform (based on TMS320C1x/2x mnemonics).

Table 5–2. Summary of Enhanced Instructions

Enhanced Instruction	Includes These Operations
ADD	ADD, ADDH, ADDK, ADLK
AND	AND, ANDK
BCND	BBNZ, BBZ, BC, BCND, BGEZ, BGZ, BIOZ, BLEZ, BLZ, BNC, BNV, BNZ, BV, BZ
BLDD	BLDD, BLKD
BLDP	BLDP, BLKP
CLRC	CLRC, CNFD, EINT, RC, RHM, ROVM, RSXM, RTC, RXF
LACC	LAC, LACC, LALK, ZALH
LACL	LACK, LACL, ZAC, ZALS
LAR	LAR, LARK, LRLK
LDP	LDP, LDPK
LST	LST, LST1
MAR	LARP, MAR
MPY	MPY, MPYK
OR	OR, ORK
RPT	RPT, RPTK
SETC	CNFP, DINT, SC, SETC, SHM, SOVM, SSXM, STC, SXF
SUB	SUB, SUBH, SUBK

For more information about enhanced instructions, refer to Section 3.13, page 3-34.

5.3 Instruction Set Summary Table

Syntax	1x	2x	2xx	5x	Description
ABS	√	√	√	√	**Absolute Value of Accumulator**
					If the contents of the accumulator are less than zero, replace the contents with the 2s complement of the contents. If the contents are ≥ 0, the accumulator is not affected.
ADCB				√	**Add ACCB to Accumulator With Carry**
					Add the contents of the ACCB and the value of the carry bit to the accumulator. If the result of the addition generates a carry from the accumulator's MSB, the carry bit is set to 1.
ADD *dma* [*,shift*]	√	√	√	√	**Add to Accumulator With Shift**
ADD {*ind*} [*,shift* [*,next ARP*]]	√	√	√	√	TMS320C1x and TMS320C2x devices: add the contents of the addressed data memory location to the accumulator; if a shift is specified, left-shift the contents of the location before the add. During shifting, low-order bits are zero-filled, and high-order bits are sign-extended.
ADD *# k*			√	√	
ADD *# lk* [*,shift2*]			√	√	
					TMS320C2xx and TMS320C5x devices: add the contents of the addressed data memory location or an immediate value to the accumulator; if a shift is specified, left-shift the data before the add. During shifting, low-order bits are zero-filled, and high-order bits are sign-extended if SXM = 1.
ADDB				√	**Add ACCB to Accumulator**
					Add the contents of the ACCB to the accumulator.
ADDC *dma*		√	√	√	**Add to Accumulator With Carry**
ADDC {*ind*} [*,next ARP*]		√	√	√	Add the contents of the addressed data memory location and the carry bit to the accumulator.
ADDH *dma*	√	√	√	√	**Add High to Accumulator**
ADDH {*ind*} [*,next ARP*]	√	√	√	√	Add the contents of the addressed data memory location to the 16 MSBs of the accumulator. The LSBs are not affected. If the result of the addition generates a carry, the carry bit is set to 1.
					TMS320C2x, TMS320C2xx, and TMS320C5x devices: If the result of the addition generates a carry from the accumulator's MSB, the carry bit is set to 1.

Syntax	1x	2x	2xx	5x	Description
ADDK *# k*		√	√	√	**Add to Accumulator Short Immediate**
					TMS320C1x devices: Add an 8-bit immediate value to the accumulator.
					TMS320C2x, TMS320C2xx, and TMS320C5x devices: Add an 8-bit immediate value, right-justified, to the accumulator with the result replacing the accumulator contents. The immediate value is treated as an 8-bit positive number; sign extension is suppressed.
ADDS *dma*	√	√	√	√	**Add to Accumulator With Sign Extension Suppressed**
ADDS {*ind*} [*,next ARP*]	√	√	√	√	
					Add the contents of the addressed data memory location to the accumulator. The value is treated as a 16-bit unsigned number; sign extension is suppressed.
ADDT *dma*		√	√	√	**Add to Accumulator With Shift Specified by T Register**
ADDT {*ind*} [*,next ARP*]		√	√	√	
					Left-shift the contents of the addressed data memory location by the value in the 4 LSBs of the T register; add the result to the accumulator. If a shift is specified, left-shift the data before the add. During shifting, low-order bits are zero-filled, and high-order bits are sign-extended if SXM = 1.
					TMS320C2xx and TMS320C5x devices: If the result of the addition generates a carry from the accumulator's MSB, the carry bit is set to 1.
ADLK *# lk* [*,shift*]		√	√	√	**Add to Accumulator Long Immediate With Shift**
					Add a 16-bit immediate value to the accumulator; if a shift is specified, left-shift the value before the add. During shifting, low-order bits are zero-filled, and high-order bits are sign-extended if SXM = 1.
ADRK *# k*		√	√	√	**Add to Auxiliary Register Short Immediate**
					Add an 8-bit immediate value to the current auxiliary register.

Syntax	1x	2x	2xx	5x	Description
AND *dma*	√	√	√	√	**AND With Accumulator**
AND {*ind*} [,*next ARP*]	√	√	√	√	TMS320C1x and TMS320C2x devices: AND the contents of the addressed data memory location with the 16 LSBs of the accumulator. The 16 MSBs of the accumulator are ANDed with 0s.
AND # *lk* [,*shift*]			√	√	
					TMS320C2xx and TMS320C5x devices: AND the contents of the addressed data memory location or a 16-bit immediate value with the contents of the accumulator. The 16 MSBs of the accumulator are ANDed with 0s. If a shift is specified, left-shift the constant before the AND. Low-order bits below and high-order bits above the shifted value are treated as 0s.
ANDB				√	**AND ACCB to Accumulator**
					AND the contents of the ACCB to the accumulator.
ANDK # *lk* [,*shift*]		√	√	√	**AND Immediate With Accumulator With Shift**
					AND a 16-bit immediate value with the contents of the accumulator; if a shift is specified, left-shift the constant before the AND.
APAC	√	√	√	√	**Add P Register to Accumulator**
					Add the contents of the P register to the accumulator.
					TMS320C2x, TMS320C2xx, and TMS320C5x devices: before the add, left-shift the contents of the P register as defined by the PM status bits.
APL [# *lk*] ,*dma*				√	**AND Data Memory Value With DBMR or Long Constant**
APL [# *lk,*] {*ind*} [,*next ARP*]				√	
					AND the data memory value with the contents of the DBMR or a long constant. If a long constant is specified, it is ANDed with the contents of the data memory location. The result is written back into the data memory location previously holding the first operand. If the result is 0, the TC bit is set to 1; otherwise, the TC bit is cleared.
B *pma*	√				**Branch Unconditionally**
B *pma* [, {*ind*} [,*next ARP*]]		√	√		Branch to the specified program memory address.
					TMS320C2x and TMS320C2xx devices: modify the current AR and ARP as specified.

Syntax	1x	2x	2xx	5x	Description
B[*D*] *pma* [*, {ind}* [*,next ARP*]]				√	**Branch Unconditionally With Optional Delay**
					Modify the current auxiliary register and ARP as specified and pass control to the designated program memory address. If you specify a delayed branch (BD), the next two instruction words (two 1-word instructions or one 2-word instruction) are fetched and executed before branching.
BACC		√	√		**Branch to Address Specified by Accumulator**
					Branch to the location specified by the 16 LSBs of the accumulator.
BACC[*D*]				√	**Branch to Address Specified by Accumulator With Optional Delay**
					Branch to the location specified by the 16 LSBs of the accumulator.
					If you specify a delayed branch (BACCD), the next two instruction words (two 1-word instructions or one 2-word instruction) are fetched and executed before branching.
BANZ *pma*	√				**Branch on Auxiliary Register Not Zero**
BANZ *pma* [*, {ind}* [*,next ARP*]]		√	√		If the contents of the 9 LSBs of the current auxiliary register (TMS320C1x) or the contents of the entire current auxiliary register (TMS320C2x) are ≠ 0, branch to the specified program memory address.
					TMS320C2x and TMS320C2xx devices: modify the current AR and ARP (if specified) or decrement the current AR (default). TMS320C1x devices: decrement the current AR.
BANZ[*D*] *pma* [*, {ind}* [*,next ARP*]]				√	**Branch on Auxiliary Register Not Zero With Optional Delay**
					If the contents of the current auxiliary register are ≠ 0, branch to the specified program memory address. Modify the current AR and ARP as specified, or decrement the current AR.
					If you specify a delayed branch (BANZD), the next two instruction words (two 1-word instructions or one 2-word instruction) are fetched and executed before branching.

Syntax	1x	2x	2xx	5x	Description
BBNZ *pma* [, {*ind*} [,*next ARP*]]		√	√	√	**Branch on Bit ≠ Zero**
					If the TC bit = 1, branch to the specified program memory address.
					TMS320C2x devices: modify the current AR and ARP as specified.
					TMS320C2xx and TMS320C5x devices: if the –p porting switch is used, modify the current AR and ARP as specified.
BBZ *pma* [, {*ind*} [,*next ARP*]]		√	√	√	**Branch on Bit = Zero**
BBZ *pma*				√	If the TC bit = 0, branch to the specified program memory address.
					TMS320C2x devices: modify the current AR and ARP as specified.
					TMS320C2xx and TMS320C5x devices: modify the current AR and ARP as specified when the –p porting switch is used.
BC *pma* [, {*ind*} [, *next ARP*]]		√		√	**Branch on Carry**
BC *pma*			√	√	If the C bit = 1, branch to the specified program memory address.
					TMS320C2x devices: modify the current AR and ARP as specified.
					TMS320C2xx and TMS320C5x devices: modify the current AR and ARP as specified when the –p porting switch is used.
BCND *pma* [*cond$_1$*] [, *cond$_2$*] [...]			√		**Branch Conditionally**
					Branch to the program memory address if the specified conditions are met. Not all combinations of conditions are meaningful.
BCND[*D*] *pma* [*cond$_1$*] [, *cond$_2$*] [...]				√	**Branch Conditionally With Optional Delay**
					Branch to the program memory address if the specified conditions are met. Not all combinations of conditions are meaningful.
					If you specify a delayed branch (BCNDD), the next two instruction words (two 1-word instructions or one 2-word instruction) are fetched and executed before branching.

Syntax	1x	2x	2xx	5x	Description
BGEZ *pma*	√		√	√	**Branch if Accumulator ≥ Zero**
BGEZ *pma* [,{*ind*} [,*next ARP*]]		√		√	If the contents of the accumulator ≥ 0, branch to the specified program memory address.
					TMS320C2x devices: modify the current AR and ARP as specified.
					TMS320C2xx and TMS320C5x devices: modify the current AR and ARP as specified when the –p porting switch is used.
BGZ *pma*	√		√	√	**Branch if Accumulator > Zero**
BGZ *pma* [, {*ind*} [,*next ARP*]]		√		√	If the contents of the accumulator are > 0, branch to the specified program memory address.
					TMS320C2x devices: modify the current AR and ARP as specified.
					TMS320C2xx and TMS320C5x devices: modify the current AR and ARP as specified when the –p porting switch is used.
BIOZ *pma*	√		√	√	**Branch on I/O Status = Zero**
BIOZ *pma* [, {*ind*} [, *next ARP*]]		√		√	If the $\overline{\text{BIO}}$ pin is low, branch to the specified program memory address.
					TMS320C2x devices: modify the current AR and ARP as specified.
					TMS320C2xx and TMS320C5x devices: modify the current AR and ARP as specified when the –p porting switch is used.
BIT *dma, bit code*		√	√	√	**Test Bit**
BIT {*ind*}, *bit code* [,*next ARP*]		√	√	√	Copy the specified bit of the data memory value to the TC bit in ST1.
BITT *dma*		√	√	√	**Test Bit Specified by T Register**
BITT {*ind*} [,*next ARP*]		√	√	√	TMS320C1x, TMS320C2x, TMS320C2xx devices: copy the specified bit of the data memory value to the TC bit in ST1. The 4 LSBs of the T register specify which bit is copied.
					TMS320C5x devices: copy the specified bit of the data memory value to the TC bit in ST1. The 4 LSBs of the TREG2 specify which bit is copied.

Syntax	1x	2x	2xx	5x	Description
BLDD *# lk, dma*			√	√	**Block Move From Data Memory to Data Memory**
BLDD *# lk*, {*ind*} [*,next ARP*]			√	√	Copy a block of data memory into data memory. The block of data memory is pointed to by *src*, and the destination block of data memory is pointed to by *dst*.
BLDD *dma, # lk*			√	√	
BLDD {*ind*}, *# lk* [*,next ARP*]			√	√	TMS320C2xx devices: the word of the source and/or the destination space can be pointed at with a long immediate value or a data memory address. You can use the RPT instruction with BLDD to move consecutive words, pointed at indirectly in data memory, to a contiguous program memory space. The number of words to be moved is one greater than the number contained in the RPTC at the beginning of the instruction.
BLDD BMAR, *dma*				√	
BLDD BMAR, {*ind*} [*,next ARP*]				√	
BLDD *dma* BMAR				√	
BLDD {*ind*}, BMAR [*,next ARP*]				√	
					TMS320C5x devices: the word of the source and/or the destination space can be pointed at with a long immediate value, the contents of the BMAR, or a data memory address. You can use the RPT instruction with BLDD to move consecutive words, that are pointed at indirectly in data memory, to a contiguous program memory space. The number of words to be moved is one greater than the number contained in the RPTC at the beginning of the instruction.
BLDP *dma*				√	**Block Move From Data Memory to Program Memory**
BLDP {*ind*} [*,next ARP*]				√	
					Copy a block of data memory into program memory pointed to by the BMAR. You can use the RPT instruction with BLDP to move consecutive words, that are pointed indirectly at in data memory to a contiguous program memory space pointed at by the BMAR.
BLEZ *pma*	√		√	√	**Branch if Accumulator ≤ Zero**
BLEZ *pma* [*,* {*ind*} [*,next ARP*]]		√	√	√	If the contents of the accumulator are ≤ 0, branch to the specified program memory address.
					TMS320C2x devices: modify the current AR and ARP as specified.
					TMS320C2xx and TMS320C5x devices: modify the current AR and ARP as specified when the –p porting switch is used.

Syntax	1x	2x	2xx	5x	Description
BLKD *dma1, dma2*		√	√	√	**Block Move From Data Memory to Data Memory**
BLKD *dma1, {ind}* [*,next ARP*]		√	√	√	Move a block of words from one location in data memory to another location in data memory. Modify the current AR and ARP as specified. RPT or RPTK must be used with BLKD, in the indirect addressing mode, if more than one word is to be moved. The number of words to be moved is one greater than the number contained in RPTC at the beginning of the instruction.
BLKP *pma, dma*		√	√	√	**Block Move From Program Memory to Data Memory**
BLKP *pma, {ind}* [*,next ARP*]		√	√	√	Move a block of words from a location in program memory to a location in data memory. Modify the current AR and ARP as specified. RPT or RPTK must be used with BLKD, in the indirect addressing mode, if more than one word is to be moved. The number of words to be moved is one greater than the number contained in RPTC at the beginning of the instruction.
BLPD *#pma, dma*			√	√	**Block Move From Program Memory to Data Memory**
BLPD *# pma, {ind}* [*,next ARP*]			√	√	
BLPD BMAR, *dma*				√	Copy a block of program memory into data memory. The block of program memory is pointed to by *src*, and the destination block of data memory is pointed to by *dst*.
BLPD BMAR, *{ind}* [*,next ARP*]				√	TMS320C2xx devices: the word of the source space can be pointed at with a long immediate value. You can use the RPT instruction with BLPD to move consecutive words, that are pointed at indirectly in data memory to a contiguous program memory space.
					TMS320C5x devices: the word of the source space can be pointed at with a long immediate value, or the contents of the BMAR. You can use the RPT instruction with BLPD to move consecutive words, that are pointed at indirectly in data memory to a contiguous program memory space.
BLZ *pma*	√		√	√	**Branch if Accumulator < Zero**
BLZ *pma* [*, {ind}* [*,next ARP*]]		√	√		If the contents of the accumulator are < 0, branch to the specified program memory address.
					TMS320C2x devices: modify the current AR and ARP as specified.
					TMS320C2xx and TMS320C5x devices: modify the current AR and ARP as specified when the –p porting switch is used.

Syntax	1x	2x	2xx	5x	Description
BNC *pma* [, {*ind*} [,*next ARP*]]		√	√	√	**Branch on No Carry**
					If the C bit = 0, branch to the specified program memory address.
					TMS320C2x devices: modify the current AR and ARP as specified.
					TMS320C2xx and TMS320C5x devices: modify the current AR and ARP as specified when the –p porting switch is used.
BNV *pma* [, {*ind*} [,*next ARP*]]		√	√	√	**Branch if No Overflow**
					If the OV flag is clear, branch to the specified program memory address.
					TMS320C2x devices: modify the current AR and ARP as specified.
					TMS320C2xx and TMS320C5x devices: modify the current AR and ARP as specified when the –p porting switch is used.
BNZ *pma*	√				**Branch if Accumulator ≠ Zero**
BNZ *pma* [, {*ind*} [,*next ARP*]]		√	√	√	If the contents of the accumulator ≠ 0, branch to the specified program memory address.
					TMS320C2x devices: modify the current AR and ARP as specified.
					TMS320C2xx and TMS320C5x devices: modify the current AR and ARP as specified when the –p porting switch is used.
BSAR [*shift*]				√	**Barrel Shift**
					In a single cycle, execute a 1- to 16-bit right-barrel arithmetic shift of the accumulator. The sign extension is determined by the sign-extension mode bit in ST1.
BV *pma*	√				**Branch on Overflow**
BV *pma* [, {*ind*} [,*next ARP*]]		√	√	√	If the OV flag is set, branch to the specified program memory address and clear the OV flag.
					TMS320C2x, TMS320C2xx, and TMS320C5x devices: modify the current AR and ARP as specified.
					TMS320C2xx and TMS320C5x devices: to modify the AR and ARP, use the –p porting switch.

Syntax	1x	2x	2xx	5x	Description
BZ *pma*	√		√	√	**Branch if Accumulator = Zero**
BZ *pma* [, {*ind*} [,*next ARP*]]		√			If the contents of the accumulator = 0, branch to the specified program memory address.
					TMS320C2x, TMS320C2xx and TMS320C5x devices: modify the current AR and ARP as specified.
					TMS320C2xx and TMS320C5x devices: to modify the AR and ARP, use the –p porting switch.
CALA	√	√	√		**Call Subroutine Indirect**
					The contents of the accumulator specify the address of a subroutine. Increment the PC, push the PC onto the stack, then load the 12 (TMS320C1x) or 16 (TMS320C2x/C2xx) LSBs of the accumulator into the PC.
CALA[*D*]				√	**Call Subroutine Indirect With Optional Delay**
					The contents of the accumulator specify the address of a subroutine. Increment the PC and push it onto the stack; then load the 16 LSBs of the accumulator into the PC.
					If you specify a delayed branch (CALAD), the next two instruction words (two 1-word instructions or one 2-word instruction) are fetched and executed before the call.
CALL *pma*	√				**Call Subroutine**
CALL *pma* [,{*ind*} [,*next ARP*]]		√	√		The contents of the addressed program memory location specify the address of a subroutine. Increment the PC by 2, push the PC onto the stack, then load the specified program memory address into the PC.
					TMS320C2x and TMS320C2xx devices: modify the current AR and ARP as specified.
CALL[*D*] *pma* [,{*ind*} [, *next ARP*]]				√	**Call Unconditionally With Optional Delay**
					The contents of the addressed program memory location specify the address of a subroutine. Increment the PC and push the PC onto the stack; then load the specified program memory address (symbolic or numeric) into the PC. Modify the current AR and ARP as specified.
					If you specify a delayed branch (CALLD), the next two instruction words (two 1-word instructions or one 2-word instruction) are fetched and executed before the call.

Syntax	1x	2x	2xx	5x	Description
CC *pma* [*cond$_1$*] [,*cond$_2$*] [,...]			√		**Call Conditionally**
					If the specified conditions are met, control is passed to the pma. Not all combinations of conditions are meaningful.
CC[*D*] *pma* [*cond$_1$*] [,*cond$_2$*] [,...]				√	**Call Conditionally With Optional Delay**
					If the specified conditions are met, control is passed to the pma. Not all combinations of conditions are meaningful.
					If you specify a delayed branch (CCD), the next two instruction words (two 1-word instructions or one 2-word instruction) are fetched and executed before the call.
CLRC *control bit*			√	√	**Clear Control Bit**
					Set the specified control bit to a logic 0. Maskable interrupts are enabled immediately after the CLRC instruction executes.
CMPL		√	√	√	**Complement Accumulator**
					Complement the contents of the accumulator (1s complement).
CMPR *CM*		√	√	√	**Compare Auxiliary Register With AR0**
					Compare the contents of the current auxiliary register to AR0, based on the following cases:
					If CM = 00$_2$, test whether AR(ARP) = AR0.
					If CM = 01$_2$, test whether AR(ARP) < AR0.
					If CM = 10$_2$, test whether AR(ARP) > AR0.
					If CM = 11$_2$, test whether AR(ARP) ≠ AR0.
					If the result is true, load a 1 into the TC status bit; otherwise, load a 0 into the TC bit. The comparison does not affect the tested registers.
					TMS320C5x devices: compare the contents of the auxiliary register with the ARCR.
CNFD		√	√	√	**Configure Block as Data Memory**
					Configure on-chip RAM block B0 as data memory. Block B0 is mapped into data memory locations 512h–767h.
					TMS320C5x devices: block B0 is mapped into data memory locations 512h–1023h.

Syntax	1x	2x	2xx	5x	Description
CNFP		√	√	√	**Configure Block as Program Memory**
					Configure on-chip RAM block B0 as program memory. Block B0 is mapped into program memory locations 65280h–65535h.
					TMS320C5x devices: block B0 is mapped into data memory locations 65024h–65535h.
CONF *2-bit constant*		√			**Configure Block as Program Memory**
					Configure on-chip RAM block B0/B1/B2/B3 as program memory. For information on the memory mapping of B0/B1/B2/B3, refer to the *TMS320C2x User's Guide*.
CPL [*, # lk*] *dma*				√	**Compare DBMR or Immediate With Data Value**
CPL [*, # lk*] {*ind*} [*,next ARP*]				√	Compare two quantities: if the two quantities are equal, set the TC bit to 1; otherwise, clear the TC bit.
CRGT				√	**Test for ACC > ACCB**
					Compare the contents of the ACC with the contents of the ACCB. Then load the larger signed value into both registers and modify the carry bit according to the comparison result. If the contents of ACC are greater than or equal to the contents of ACCB, set the carry bit to 1.
CRLT				√	**Test for ACC < ACCB**
					Compare the contents of the ACC with the contents of the ACCB. Then load the smaller signed value into both registers and modify the carry bit according to the comparison result. If the contents of ACC are less than the contents of ACCB, clear the carry bit.
DINT	√	√	√	√	**Disable Interrupts**
					Disable all interrupts; set the INTM to 1. Maskable interrupts are disabled immediately after the DINT instruction executes. DINT does not disable the unmaskable interrupt $\overline{RS}$; DINT does not affect the IMR.
DMOV *dma*	√	√	√	√	**Data Move in Data Memory**
DMOV {*ind*} [*,next ARP*]	√	√	√	√	Copy the contents of the addressed data memory location into the next higher address. DMOV moves data only within on-chip RAM blocks.
					TMS320C2x, TMS320C2xx, and TMS320C5x devices: the on-chip RAM blocks are B0 (when configured as data memory), B1, and B2.

Syntax	1x	2x	2xx	5x	Description
EINT	√	√	√	√	**Enable Interrupts**
					Enable all interrupts; clear the INTM to 0. Maskable interrupts are enabled immediately after the EINT instruction executes.
EXAR				√	**Exchange ACCB With ACC**
					Exchange the contents of the ACC with the contents of the ACCB.
FORT *1-bit constant*		√			**Format Serial Port Registers**
					Load the FO with a 0 or a 1. If FO = 0, the registers are configured to receive/transmit 16-bit words. If FO = 1, the registers are configured to receive/transmit 8-bit bytes.
IDLE		√	√	√	**Idle Until Interrupt**
					Forces an executing program to halt execution and wait until it receives a reset or an interrupt. The device remains in an idle state until it is interrupted.
IDLE2				√	**Idle Until Interrupt—Low-Power Mode**
					Removes the functional clock input from the internal device; this allows for an extremely low-power mode. The IDLE2 instruction forces an executing program to halt execution and wait until it receives a reset or unmasked interrupt.
IN *dma, PA*	√	√	√	√	**Input Data From Port**
IN *{ind}, PA* [*,next ARP*]	√	√	√	√	Read a 16-bit value from one of the external I/O ports into the addressed data memory location.
					TMS320C1x devices: this is a 2-cycle instruction. During the first cycle, the port address is sent to address lines A2/PA2–A0/PA0; $\overline{DEN}$ goes low, strobing in the data that the addressed peripheral places on data bus D15–D0.
					TMS320C2x devices: the $\overline{IS}$ line goes low to indicate an I/O access, and the $\overline{STRB}$, R/$\overline{W}$, and READY timings are the same as for an external data memory read.
					TMS320C2xx, and TMS320C5x devices: the $\overline{IS}$ line goes low to indicate an I/O access, and the $\overline{STRB}$, $\overline{RD}$, and READY timings are the same as for an external data memory read.

Syntax	1x	2x	2xx	5x	Description
INTR *k*			√	√	**Soft Interrupt**
					Transfer program control to the program memory address specified by *k* (*k* is defined in the table below). This instruction allows you to use your software to execute any interrupt service routine.
					<table><tr><td>***k***</td><td>**Interrupt**</td><td>**Location**</td></tr><tr><td>0</td><td>RS</td><td>0h</td></tr><tr><td>1</td><td>INT1</td><td>2h</td></tr><tr><td>2</td><td>INT2</td><td>4h</td></tr><tr><td>3</td><td>INT3</td><td>6h</td></tr><tr><td>4</td><td>TINT</td><td>8h</td></tr><tr><td>5</td><td>RINT</td><td>Ah</td></tr><tr><td>6</td><td>XINT</td><td>Ch</td></tr><tr><td>7</td><td>TRNT</td><td>Eh</td></tr><tr><td>8</td><td>TXNT</td><td>10h</td></tr><tr><td>9</td><td>INT4</td><td>12h</td></tr><tr><td>10</td><td>reserved interrupt</td><td>14h</td></tr><tr><td>11</td><td>reserved interrupt</td><td>16h</td></tr><tr><td>12</td><td>reserved interrupt</td><td>18h</td></tr><tr><td>13</td><td>reserved interrupt</td><td>20h</td></tr><tr><td>14</td><td>TRAP</td><td>22h</td></tr><tr><td>15</td><td>NMI</td><td>24h</td></tr></table>
LAC *dma* [,*shift*]	√	√	√	√	**Load Accumulator With Shift**
LAC {*ind*} [,*shift* [,*next ARP*]]	√	√	√	√	Load the contents of the addressed data memory location into the accumulator. If a shift is specified, left-shift the value before loading it into the accumulator. During shifting, low-order bits are zero-filled, and high-order bits are sign-extended if SXM = 1.
LACB				√	**Load Accumulator With ACCB**
					Load the contents of the accumulator buffer into the accumulator.
LACC *dma* [,*shift$_1$*]		√	√	√	**Load Accumulator With Shift**
LACC {*ind*} [,*shift$_1$* [,*next ARP*]]		√	√	√	Load the contents of the addressed data memory location or the 16-bit constant into the accumulator. If a shift is specified, left-shift the value before loading it into the accumulator. During shifting, low-order bits are zero-filled, and high-order bits are sign-extended if SXM = 1.
LACC *# lk* [,*shift$_2$*]		√	√	√	
LACK *8-bit constant*	√	√	√	√	**Load Accumulator Immediate Short**
					Load an 8-bit constant into the accumulator. The 24 MSBs of the accumulator are zeroed.

Syntax	1x	2x	2xx	5x	Description
LACL *dma*			√	√	**Load Low Accumulator and Clear High Accumulator**
LACL {*ind*} [*,next ARP*]			√	√	
LACL *# k*			√	√	Load the contents of the addressed data memory location or zero-extended 8-bit constant into the 16 LSBs of the accumulator. The MSBs of the accumulator are zeroed. The data is treated as a 16-bit unsigned number.
					TMS320C2xx: a constant of 0 will clear the contents of the accumulator to 0 with no sign-extension.
LACT *dma*		√	√	√	**Load Accumulator With Shift Specified by T Register**
LACT {*ind*} [*,next ARP*]		√	√	√	
					Left-shift the contents of the addressed data memory location by the value specified in the 4 LSBs of the T register; load the result into the accumulator. If a shift is specified, left-shift the value before loading it into the accumulator. During shifting, low-order bits are zero-filled, and high-order bits are sign-extended if SXM = 1.
LALK *# lk* [*,shift*]		√	√	√	**Load Accumulator Long Immediate With Shift**
					Load a 16-bit immediate value into the accumulator. If a shift is specified, left-shift the constant before loading it into the accumulator. During shifting, low-order bits are zero-filled, and high-order bits are sign-extended if SXM = 1.
LAMM *dma*				√	**Load Accumulator With Memory-Mapped Register**
LAMM {*ind*} [*,next ARP*]				√	
					Load the contents of the addressed memory-mapped register into the low word of the accumulator. The 9 MSBs of the data memory address are cleared, regardless of the current value of DP or the 9 MSBs of AR (ARP).
LAR *AR, dma*	√	√	√	√	**Load Auxiliary Register**
LAR *AR,* {*ind*} [*,next ARP*]	√	√	√	√	TMS320C1x and TMS320C2x devices: load the contents of the addressed data memory location into the designated auxiliary register.
LAR *AR, # k*			√	√	
LAR *AR, # lk*			√	√	TMS320C25, TMS320C2xx, and TMS320C5x devices: load the contents of the addressed data memory location or an 8-bit or 16-bit immediate value into the designated auxiliary register.
LARK *AR, 8-bit constant*	√	√	√	√	**Load Auxiliary Register Immediate Short**
					Load an 8-bit positive constant into the designated auxiliary register.

Syntax	1x	2x	2xx	5x	Description
LARP *1-bit constant*	√				**Load Auxiliary Register Pointer**
LARP *3-bit constant*		√	√	√	TMS320C1x devices: load a 1-bit constant into the auxiliary register pointer (specifying AR0 or AR1).
					TMS320C2x, TMS320C2xx, and TMS320C5x devices: load a 3-bit constant into the auxiliary register pointer (specifying AR0–AR7).
LDP *dma*	√	√	√	√	**Load Data Memory Page Pointer**
LDP {*ind*} [*,next ARP*]	√	√	√	√	TMS320C1x devices: load the LSB of the contents of the addressed data memory location into the DP register. All high-order bits are ignored. DP = 0 defines page 0 (words 0–127), and DP = 1 defines page 1 (words 128–143/255).
LDP *# k*			√	√	
					TMS320C2x, TMS320C2xx, and TMS320C5x devices: load the 9 LSBs of the addressed data memory location or a 9-bit immediate value into the DP register. The DP and 7-bit data memory address are concatenated to form 16-bit data memory addresses.
LDPK *1-bit constant*	√				**Load Data Memory Page Pointer Immediate**
LDPK *9-bit constant*		√	√	√	TMS320C1x devices: load a 1-bit immediate value into the DP register. DP = 0 defines page 0 (words 0–127), and DP = 1 defines page 1 (words 128–143/255).
					TMS320C2x, TMS320C2xx, and TMS320C5x devices: load a 9-bit immediate into the DP register. The DP and 7-bit data memory address are concatenated to form 16-bit data memory addresses. DP $\geq$ 8 specifies external data memory. DP = 4 through 7 specifies on-chip RAM blocks B0 or B1. Block B2 is located in the upper 32 words of page 0.
LMMR *dma, # lk*				√	**Load Memory-Mapped Register**
LMMR {*ind*}, *# lk* [*,next ARP*]				√	Load the contents of the memory-mapped register pointed at by the 7 LSBs of the direct or indirect data memory value into the long immediate addressed data memory location. The 9 MSBs of the data memory address are cleared, regardless of the current value of DP or the 9 MSBs of AR (ARP).
LPH *dma*		√	√	√	**Load High P Register**
LPH {*ind*} [*,next ARP*]		√	√	√	Load the contents of the addressed data memory location into the 16 MSBs of the P register; the LSBs are not affected.
LRLK *AR, lk*		√	√	√	**Load Auxiliary Register Long Immediate**
					Load a 16-bit immediate value into the designated auxiliary register.

Syntax	1x	2x	2xx	5x	Description
LST *dma*	√	√	√	√	**Load Status Register**
LST {*ind*} [,*next ARP*]	√	√	√	√	Load the contents of the addressed data memory location into the ST (TMS320C1x) or into ST0 (TMS320C2x/2xx/5x).
LST # *n, dma*		√	√	√	**Load Status Register n**
LST # *n,* {*ind*} [,*next ARP*]		√	√	√	Load the contents of the addressed data memory location into ST*n*.
LST1 *dma*		√	√	√	**Load ST1**
LST1 {*ind*} [,*next ARP*]		√	√	√	Load the contents of the addressed data memory location into ST1.
LT *dma*	√	√	√	√	**Load T Register**
LT {*ind*} [,*next ARP*]	√	√	√	√	Load the contents of the addressed data memory location into the T register (TMS320C1x/2x/2xx) or TREG0 (TMS320C5x).
LTA *dma*	√	√	√	√	**Load T Register and Accumulate Previous Product**
LTA {*ind*} [,*next ARP*]	√	√	√	√	Load the contents of the addressed data memory location into T register (TMS320C1x/2x/2xx) or TREG0 (TMS320C5x) and add the contents of the P register to the accumulator.
					TMS320C2x, TMS320C2xx, and TMS320C5x devices: before the add, shift the contents of the P register as specified by the PM status bits.
LTD *dma*	√	√	√	√	**Load T Register, Accumulate Previous Product, and Move Data**
LTD {*ind*} [,*next ARP*]	√	√	√	√	Load the contents of the addressed data memory location into the T register (TMS320C1x/2x/2xx) or TREG0 (TMS320C5x), add the contents of the P register to the accumulator, and copy the contents of the specified location into the next higher address (note that both data memory locations must reside in on-chip data RAM).
					TMS320C2x, TMS320C2xx, and TMS320C5x devices: before the add, shift the contents of the P register as specified by the PM status bits.
LTP *dma*		√	√	√	**Load T Register, Store P Register in Accumulator**
LTP {*ind*} [,*next ARP*]		√	√	√	Load the contents of the addressed data memory location into the T register (TMS320C1x/2x/2xx) or TREG0 (TMS320C5x). Store the contents of the product register into the accumulator.

Syntax	1x	2x	2xx	5x	Description
LTS *dma*		√	√	√	**Load T Register, Subtract Previous Product**
LTS {*ind*} [,*next ARP*]		√	√	√	Load the contents of the addressed data memory location into the T register (TMS320C1x/2x/2xx) or TREG0 (TMS320C5x). Shift the contents of the product register as specified by the PM status bits, and subtract the result from the accumulator.
MAC *pma, dma*		√	√	√	**Multiply and Accumulate**
MAC *pma,* {*ind*} [,*next ARP*]		√	√	√	Multiply a data memory value by a program memory value and add the previous product (shifted as specified by the PM status bits) to the accumulator.
MACD *dma, pma*		√	√	√	**Multiply and Accumulate With Data Move**
MACD *pma,* {*ind*} [,*next ARP*]		√	√	√	Multiply a data memory value by a program memory value and add the previous product (shifted as specified by the PM status bits) to the accumulator. If the data memory address is in on-chip RAM block B0, B1, or B2, copy the contents of the address to the next higher address.
MADD *dma*				√	**Multiply and Accumulate With Data Move and Dynamic Addressing**
MADD {*ind*} [,*next ARP*]				√	
					Multiply a data memory value by a program memory value and add the previous product (shifted as defined by the PM status bits) into the accumulator. The program memory address is contained in the BMAR; this allows for dynamic addressing of coefficient tables.
					MADD functions the same as the MADS, with the addition of data move for on-chip RAM blocks.
MADS *dma*		√	√	√	**Multiply and Accumulate With Dynamic Addressing**
MADS {*ind*} [,*next ARP*]		√	√	√	
					Multiply a data memory value by a program memory value and add the previous product (shifted as defined by the PM status bits) into the accumulator. The program memory address is contained in the BMAR; this allows for dynamic addressing of coefficient tables.
MAR *dma*	√	√	√	√	**Modify Auxiliary Register**
MAR {*ind*} [,*next ARP*]	√	√	√	√	Modify the current AR or ARP as specified. MAR acts as NOP in indirect addressing mode.

Syntax	1x	2x	2xx	5x	Description
MPY *dma*	√	√	√	√	**Multiply**
MPY {*ind*} [*,next ARP*]	√	√	√	√	TMS320C1x and TMS320C2x devices: multiply the contents of the T register by the contents of the addressed data memory location; place the result in the P register.
MPY *# k*			√	√	
MPY *# lk*			√	√	
					TMS320C2xx and TMS320C5x devices: multiply the contents of the T register (TMS320C2xx) or TREG0 (TMS320C5x) by the contents of the addressed data memory location or a 13-bit or 16-bit immediate value; place the result in the P register.
MPYA *dma*		√	√	√	**Multiply and Accumulate Previous Product**
MPYA {*ind*} [*,next ARP*]		√	√	√	Multiply the contents of the T register (TMS320C2x/2xx) or TREG0 (TMS320C5x) by the contents of the addressed data memory location; place the result in the P register. Add the previous product (shifted as specified by the PM status bits) to the accumulator.
MPYK *13-bit constant*	√	√	√	√	**Multiply Immediate**
					Multiply the contents of the T register (TMS320C2x/2xx) or TREG0 (TMS320C5x) by a signed 13-bit constant; place the result in the P register.
MPYS *dma*		√	√	√	**Multiply and Subtract Previous Product**
MPYS {*ind*} [*,next ARP*]		√	√	√	Multiply the contents of the T register (TMS320C2x/2xx) or TREG0 (TMS320C5x) by the contents of the addressed data memory location; place the result in the P register. Subtract the previous product (shifted as specified by the PM status bits) from the accumulator.
MPYU *dma*		√	√	√	**Multiply Unsigned**
MPYU {*ind*} [*,next ARP*]		√	√	√	Multiply the unsigned contents of the T register (TMS320C2x/2xx) or TREG0 (TMS320C5x) by the unsigned contents of the addressed data memory location; place the result in the P register.
NEG		√	√	√	**Negate Accumulator**
					Negate (2s complement) the contents of the accumulator.
NMI			√	√	**Nonmaskable Interrupt**
					Force the program counter to the nonmaskable interrupt vector location 24h. NMI has the same effect as a hardware nonmaskable interrupt.
NOP	√	√	√	√	**No Operation**
					Perform no operation.

Syntax	1x	2x	2xx	5x	Description
NORM		√	√	√	**Normalize Contents of Accumulator**
NORM {*ind*}		√	√	√	Normalize a signed number in the accumulator.
OPL [*# lk,*] *dma*				√	**OR With DBMR or Long Immediate**
OPL [*# lk,*] {*ind*} [*,next ARP*]				√	If a long immediate is specified, OR it with the value at the specified data memory location; otherwise, the second operand of the OR operation is the contents of the DBMR. The result is written back into the data memory location previously holding the first operand.
OR *dma*	√	√	√	√	**OR With Accumulator**
OR {*ind*} [*,next ARP*]	√	√	√	√	TMS320C1x and TMS320C2x devices: OR the 16 LSBs of the accumulator with the contents of the addressed data memory location. The 16 MSBs of the accumulator are ORed with 0s.
OR *# lk* [*,shift*]			√	√	TMS320C2xx and TMS320C5x devices: OR the 16 LSBs of the accumulator or a 16-bit immediate value with the contents of the addressed data memory location. If a shift is specified, left-shift before ORing. Low-order bits below and high-order bits above the shifted value are treated as 0s.
ORB				√	**OR ACCB With Accumulator**
					OR the contents of the ACCB with the contents of the accumulator. ORB places the result in the accumulator.
ORK *# lk* [*,shift*]		√	√	√	**OR Immediate With Accumulator with Shift**
					OR a 16-bit immediate value with the contents of the accumulator. If a shift is specified, left-shift the constant before ORing. Low-order bits below and high-order bits above the shifted value are treated as 0s.
OUT *dma, PA*	√	√	√	√	**Output Data to Port**
OUT {*ind*}, *PA* [*,next ARP*]	√	√	√	√	Write a 16-bit value from a data memory location to the specified I/O port.
					TMS320C1x devices: the first cycle of this instruction places the port address onto address lines A2/PA2–A0/PA0. During the same cycle, $\overline{WE}$ goes low, and the data word is placed on the data bus D15–D0.
					TMS320C2x, TMS320C2xx, and TMS320C5x devices: the $\overline{IS}$ line goes low to indicate an I/O access; the $\overline{STRB}$, R/$\overline{W}$, and READY timings are the same as for an external data memory write.

Syntax	1x	2x	2xx	5x	Description
PAC	√	√	√	√	**Load Accumulator With P Register**
					Load the contents of the P register into the accumulator.
					TMS320C2x, TMS320C2xx, and TMS320C5x devices: before the load, shift the P register as specified by the PM status bits.
POP	√	√	√	√	**Pop Top of Stack to Low Accumulator**
					Copy the contents of the top of the stack into the 12 (TMS320C1x) or 16 (TMS320C2x/2xx/5x) LSBs of the accumulator and then pop the stack one level. The MSBs of the accumulator are zeroed.
POPD *dma*		√	√	√	**Pop Top of Stack to Data Memory**
POPD {*ind*} [,*next ARP*]		√	√	√	Transfer the value on the top of the stack into the addressed data memory location and then pop the stack one level.
PSHD *dma*		√	√	√	**Push Data Memory Value Onto Stack**
PSHD {*ind*} [,*next ARP*]		√	√	√	Copy the addressed data memory location onto the top of the stack. The stack is pushed down one level before the value is copied.
PUSH	√	√	√	√	**Push Low Accumulator Onto Stack**
					Copy the contents of the 12 (TMS320C1x) or 16 (TMS320C2x/2xx/5x) LSBs of the accumulator onto the top of the hardware stack. The stack is pushed down one level before the value is copied.
RC		√	√	√	**Reset Carry Bit**
					Reset the C status bit to 0.
RET	√	√	√		**Return From Subroutine**
					Copy the contents of the top of the stack into the PC and pop the stack one level.
RET[*D*]				√	**Return From Subroutine With Optional Delay**
					Copy the contents of the top of the stack into the PC and pop the stack one level.
					If you specify a delayed branch (RETD), the next two instruction words (two 1-word instructions or one 2-word instruction) are fetched and executed before the return.
RETC [*cond₁*] [,*cond₂*] [,...]			√		**Return Conditionally**
					If the specified conditions are met, RETC performs a standard return. Not all combinations of conditions are meaningful.

Syntax	1x	2x	2xx	5x	Description
RETC[*D*] [*cond₁*] [,*cond₂*] [,...]				√	**Return Conditionally With Optional Delay** If the specified conditions are met, RETC performs a standard return. Not all combinations of conditions are meaningful. If you specify a delayed branch (RETCD), the next two instruction words (two 1-word instructions or one 2-word instruction) are fetched and executed before the return.
RETE				√	**Enable Interrupts and Return From Interrupt** Copy the contents of the top of the stack into the PC and pop the stack one level. RETE automatically clears the global interrupt enable bit and pops the shadow registers (stored when the interrupt was taken) back into their corresponding strategic registers. The following registers are shadowed: ACC, ACCB, PREG, ST0, ST1, PMST, ARCR, INDX, TREG0, TREG1, TREG2.
RETI				√	**Return From Interrupt** Copy the contents of the top of the stack into the PC and pop the stack one level. RETI also pops the values in the shadow registers (stored when the interrupt was taken) back into their corresponding strategic registers. The following registers are shadowed: ACC, ACCB, PREG, ST0, ST1, PMST, ARCR, INDX, TREG0, TREG1, TREG2.
RFSM		√			**Reset Serial Port Frame Synchronization Mode** Reset the FSM status bit to 0.
RHM		√	√	√	**Reset Hold Mode** Reset the HM status bit to 0.
ROL		√	√	√	**Rotate Accumulator Left** Rotate the accumulator left one bit.
ROLB				√	**Rotate ACCB and Accumulator Left** Rotate the ACCB and the accumulator left by one bit; this results in a 65-bit rotation.
ROR		√	√	√	**Rotate Accumulator Right** Rotate the accumulator right one bit.
RORB				√	**Rotate ACCB and Accumulator Right** Rotate the ACCB and the accumulator right one bit; this results in a 65-bit rotation.

Syntax	1x	2x	2xx	5x	Description
ROVM	√	√	√	√	**Reset Overflow Mode**
					Reset the OVM status bit to 0; this disables overflow mode.
RPT *dma*		√	√	√	**Repeat Next Instruction**
RPT {*ind*} [,*next ARP*]		√	√	√	TMS320C2x devices: load the 8 LSBs of the addressed value into the RPTC; the instruction following RPT is executed the number of times indicated by RPTC + 1.
RPT # *k*			√	√	
RPT # *lk*			√	√	
					TMS320C2xx and TMS320C5x devices: load the 8 LSBs of the addressed value or an 8-bit or 16-bit immediate value into the RPTC; the instruction following RPT is repeated *n* times, where *n* is RPTC+1.
RPTB *pma*				√	**Repeat Block**
					RPTB repeats a block of instructions the number of times specified by the memory-mapped BRCR without any penalty for looping. The BRCR must be loaded before RPTB is executed.
RPTK # *k*		√	√	√	**Repeat Instruction as Specified by Immediate Value**
					Load the 8-bit immediate value into the RPTC; the instruction following RPTK is executed the number of times indicated by RPTC + 1.
RPTZ # *lk*				√	**Repeat Preceded by Clearing the Accumulator and P Register**
					Clear the accumulator and product register and repeat the instruction following RPTZ *n* times, where *n* = *lk*+1.
RSXM		√	√	√	**Reset Sign-Extension Mode**
					Reset the SXM status bit to 0; this suppresses sign extension on shifted data values for the following arithmetic instructions: ADD, ADDT, ADLK, LAC, LACT, LALK, SBLK, SUB, and SUBT.
RTC		√	√	√	**Reset Test/Control Flag**
					Reset the TC status bit to 0.
RTXM		√			**Reset Serial Port Transmit Mode**
					Reset the TXM status bit to 0; this configures the serial port transmit section in a mode where it is controlled by an FSX.
RXF		√	√	√	**Reset External Flag**
					Reset XF pin and the XF status bit to 0.

Syntax	1x	2x	2xx	5x	Description
SACB				√	**Store Accumulator in ACCB**
					Copy the contents of the accumulator into the ACCB.
SACH *dma* [*,shift*]	√	√	√	√	**Store High Accumulator With Shift**
SACH {*ind*} [*,shift* [*,next ARP*]]	√	√	√	√	Copy the contents of the accumulator into a shifter. Shift the entire contents 0, 1, or 4 bits (TMS320C1x) or from 0 to 7 bits (TMS320C2x/2xx/5x), and then copy the 16 MSBs of the shifted value into the addressed data memory location. The accumulator is not affected.
SACL *dma*	√				**Store Low Accumulator With Shift**
SACL *dma* [*,shift*]	√	√	√	√	TMS320C1x devices: Store the 16 LSBs of the accumulator into the addressed data memory location. A shift value of 0 must be specified if the ARP is to be changed.
SACL {*ind*} [*,shift* [*,next ARP*]]		√	√	√	TMS320C2x, TMS320C2xx, and TMS320C5x devices: Store the 16 LSBs of the accumulator into the addressed data memory location. If a shift is specified, shift the contents of the accumulator before storing. Shift values are 0, 1, or 4 bits (TMS320C20) or from 0 to 7 bits (TMS320C2x/2xx/5x).
SAMM *dma*				√	**Store Accumulator in Memory-Mapped Register**
SAMM {*ind*} [*,next ARP*]				√	Store the low word of the accumulator in the addressed memory-mapped register. The upper 9 bits of the data address are cleared, regardless of the current value of DP or the 9 MSBs of AR (ARP).
SAR *AR, dma*	√	√	√	√	**Store Auxiliary Register**
SAR *AR,* {*ind*} [*,next ARP*]	√	√	√	√	Store the contents of the specified auxiliary register in the addressed data memory location.
SATH				√	**Barrel-Shift Accumulator as Specified by T Register 1**
					If bit 4 of TREG1 is a 1, barrel-shift the accumulator right by 16 bits; otherwise, the accumulator is unaffected.
SATL				√	**Barrel-Shift Low Accumulator as Specified by T Register 1**
					Barrel-shift the accumulator right by the value specified in the 4 LSBs of TREG1.
SBB				√	**Subtract ACCB From Accumulator**
					Subtract the contents of the ACCB from the accumulator. The result is stored in the accumulator; the accumulator buffer is not affected.

Syntax	1x	2x	2xx	5x	Description
SBBB				√	**Subtract ACCB From Accumulator With Borrow**
					Subtract the contents of the ACCB and the logical inversion of the carry bit from the accumulator. The result is stored in the accumulator; the accumulator buffer is not affected. Clear the carry bit if the result generates a borrow.
SBLK # *lk* [,*shift*]		√	√	√	**Subtract From Accumulator Long Immediate With Shift**
					Subtract the immediate value from the accumulator. If a shift is specified, left-shift the value before subtracting. During shifting, low-order bits are zero-filled, and high-order bits are sign-extended if SXM = 1.
SBRK # *k*		√	√	√	**Subtract From Auxiliary Register Short Immediate**
					Subtract the 8-bit immediate value from the designated auxiliary register.
SC		√	√	√	**Set Carry Bit**
					Set the C status bit to 1.
SETC *control bit*			√	√	**Set Control Bit**
					Set the specified control bit to a logic 1. Maskable interrupts are disabled immediately after the SETC instruction executes.
SFL		√	√	√	**Shift Accumulator Left**
					Shift the contents of the accumulator left one bit.
SFLB				√	**Shift ACCB and Accumulator Left**
					Shift the concatenation of the accumulator and the ACCB left one bit. The LSB of the ACCB is cleared to 0, and the MSB of the ACCB is shifted into the carry bit.
SFR		√	√	√	**Shift Accumulator Right**
					Shift the contents of the accumulator right one bit. If SXM = 1, SFR produces an arithmetic right shift. If SXM = 0, SFR produces a logic right shift.
SFRB				√	**Shift ACCB and Accumulator Right**
					Shift the concatenation of the accumulator and the ACCB right 1 bit. The LSB of the ACCB is shifted into the carry bit. If SXM = 1, SFRB produces an arithmetic right shift. If SXM = 0, SFRB produces a logic right shift.
SFSM		√			**Set Serial Port Frame Synchronization Mode**
					Set the FSM status bit to 1.

Syntax	1x	2x	2xx	5x	Description
SHM		√	√	√	**Set Hold Mode**
					Set the HM status bit to 1.
SMMR *dma, # lk*				√	**Store Memory-Mapped Register**
SMMR {*ind*}, *# lk* [,*next ARP*]				√	Store the memory-mapped register value, pointed at by the 7 LSBs of the data memory address, into the long immediate addressed data memory location. The 9 MSBs of the data memory address of the memory-mapped register are cleared, regardless of the current value of DP or the upper 9 bits of AR(ARP).
SOVM	√	√	√	√	**Set Overflow Mode**
					Set the OVM status bit to 1; this enables overflow mode. (The ROVM instruction clears OVM.)
SPAC	√	√	√	√	**Subtract P Register From Accumulator**
					Subtract the contents of the P register from the contents of the accumulator.
					TMS320C2x, TMS320C2xx, and TMS320C5x devices: before the subtraction, shift the contents of the P register as specified by the PM status bits.
SPH *dma*		√	√	√	**Store High P Register**
SPH {*ind*} [,*next ARP*]		√	√	√	Store the high-order bits of the P register (shifted as specified by the PM status bits) at the addressed data memory location.
SPL *dma*		√	√	√	**Store Low P Register**
SPL {*ind*} [,*next ARP*]		√	√	√	Store the low-order bits of the P register (shifted as specified by the PM status bits) at the addressed data memory location.
SPLK *# lk, dma*			√	√	**Store Parallel Long Immediate**
SPLK *# lk,* {*ind*} [,*next ARP*]				√	Write a full 16-bit pattern into a memory location. The parallel logic unit (PLU) supports this bit manipulation independently of the ALU, so the accumulator is unaffected.
SPM *2-bit constant*		√	√	√	**Set P Register Output Shift Mode**
					Copy a 2-bit immediate value into the PM field of ST1. This controls shifting of the P register as shown below:

$PM = 00_2$ Multiplier output is not shifted.
$PM = 01_2$ Multiplier output is left-shifted one place and zero-filled.
$PM = 10_2$ Multiplier output is left-shifted four places and zero-filled.
$PM = 11_2$ Multiplier output is right-shifted six places and sign-extended; the LSBs are lost.

Syntax	1x	2x	2xx	5x	Description
SQRA *dma*		√	√	√	**Square and Accumulate Previous Product**
SQRA {*ind*} [*,next ARP*]		√	√	√	Add the contents of the P register (shifted as specified by the PM status bits) to the accumulator. Then load the contents of the addressed data memory location into the T register (TMS320C2x/2xx) or TREG0 (TMS320C5x), square the value, and store the result in the P register.
SQRS *dma*		√	√	√	**Square and Subtract Previous Product**
SQRS {*ind*} [*,next ARP*]		√	√	√	Subtract the contents of the P register (shifted as specified by the PM status bits) to the accumulator. Then load the contents of the addressed data memory location into the T register (TMS320C2x/2xx) or TREG0 (TMS320C5x), square the value, and store the result in the P register.
SST *dma*	√	√	√	√	**Store Status Register**
SST {*ind*} [*,next ARP*]	√	√	√	√	Store the contents of the ST (TMS320C1x) or ST0 (TMS320C2x/2xx/5x) in the addressed data memory location.
SST *# n dma*			√	√	**Store Status Register n**
SST *# n* {*ind*} [*,next ARP*]			√	√	Store ST*n* in data memory.
SST1 *dma*		√	√	√	**Store Status Register ST1**
SST1 {*ind*} [*,next ARP*]		√	√	√	Store the contents of ST1 in the addressed data memory location.
SSXM		√	√	√	**Set Sign-Extension Mode**
					Set the SXM status bit to 1; this enables sign extension.
STC		√	√	√	**Set Test/Control Flag**
					Set the TC flag to 1.
STXM		√			**Set Serial Port Transmit Mode**
					Set the TXM status bit to 1.

Syntax	1x	2x	2xx	5x	Description
SUB *dma* [*,shift*]	√	√	√	√	**Subtract From Accumulator With Shift**
SUB {*ind*} [*,shift* [*,next ARP*]]	√	√	√	√	TMS320C1x and TMS320C2x devices: subtract the contents of the addressed data memory location from the accumulator. If a shift is specified, left-shift the value before subtracting. During shifting, low-order bits are zero-filled, and high-order bits are sign-extended if SXM = 1.
SUB *# k*			√	√	
SUB *# lk* [*,shift2*]			√	√	
					TMS320C2xx and TMS320C5x devices: subtract the contents of the addressed data memory location or an 8- or 16-bit constant from the accumulator. If a shift is specified, left-shift the data before subtracting. During shifting, low-order bits are zero-filled, and high-order bits are sign-extended if SXM = 1.
SUBB *dma*		√	√	√	**Subtract From Accumulator With Borrow**
SUBB {*ind*} [*,next ARP*]		√	√	√	Subtract the contents of the addressed data memory location and the value of the carry bit from the accumulator. The carry bit is affected in the normal manner.
SUBC *dma*	√	√	√	√	**Conditional Subtract**
SUBC {*ind*} [*,next ARP*]	√	√	√	√	Perform conditional subtraction. SUBC can be used for division.
SUBH *dma*	√	√	√	√	**Subtract From High Accumulator**
SUBH {*ind*} [*,next ARP*]	√	√		√	Subtract the contents of the addressed data memory location from the 16 MSBs of the accumulator. The 16 LSBs of the accumulator are not affected.
SUBK *# k*		√	√	√	**Subtract From Accumulator Short Immediate**
					Subtract an 8-bit immediate value from the accumulator. The data is treated as an 8-bit positive number; sign extension is suppressed.
SUBS *dma*	√	√	√	√	**Subtract From Low Accumulator With Sign Extension Suppressed**
SUBS {*ind*} [*,next ARP*]	√	√	√	√	Subtract the contents of the addressed data memory location from the accumulator. The data is treated as a 16-bit unsigned number; sign extension is suppressed.

Syntax	1x	2x	2xx	5x	Description
SUBT *dma*		√	√	√	**Subtract From Accumulator With Shift Specified by T Register**
SUBT {*ind*} [*,next ARP*]		√	√	√	
					Left-shift the data memory value as specified by the 4 LSBs of the T register (TMS320C2x/2xx) or TREG1 (TMS320C5x), and subtract the result from the accumulator. If a shift is specified, left-shift the data memory value before subtracting. During shifting, low-order bits are zero-filled, and high-order bits are sign-extended if SXM = 1.
SXF		√	√	√	**Set External Flag**
					Set the XF pin and the XF status bit to 1.
TBLR *dma*	√	√	√	√	**Table Read**
TBLR {*ind*} [*,next ARP*]	√	√	√	√	Transfer a word from program memory to a data memory location. The program memory address is in the 12 (TMS320C1x) or 16 (TMS320C2x/2xx/5x) LSBs of the accumulator.
TBLW *dma*	√	√	√	√	**Table Write**
TBLW {*ind*} [*,next ARP*]	√	√	√	√	Transfer a word from data memory to a program memory location. The program memory address is in the 12 (TMS320C1x) or 16 (TMS320C2x/2xx/5x) LSBs of the accumulator.
TRAP		√	√	√	**Software Interrupt**
					The TRAP instruction is a software interrupt that transfers program control to program memory address 30h (TMS320C2x) or 22h (TMS320C2xx/5x) and pushes the PC + 1 onto the hardware stack. The instruction at address 30h or 22h may contain a branch instruction to transfer control to the TRAP routine. Putting the PC + 1 on the stack enables an RET instruction to pop the return PC.
XC *n* [*,cond$_1$*] [*,cond$_2$*] [*,...*]				√	**Execute Conditionally**
					Execute conditionally the next *n* instruction words where $1 \leq n \leq 2$. Not all combinations of conditions are meaningful.

Syntax	1x	2x	2xx	5x	Description
XOR *dma*	√	√	√	√	**Exclusive-OR With Accumulator**
XOR {*ind*} [,*next ARP*]	√	√	√	√	TMS320C1x and TMS320C2x devices: exclusive-OR the contents of the addressed data memory location with 16 LSBs of the accumulator. The MSBs are not affected.
XOR # *lk* [,*shift*]			√	√	
					TMS320C2xx and TMS320C5x devices: exclusive-OR the contents of the addressed data memory location or a 16-bit immediate value with the accumulator. If a shift is specified, left-shift the value before XORing. Low-order bits below and high-order bits above the shifted value are treated as 0s.
XORB				√	**Exclusive-OR of ACCB With Accumulator**
					Exclusive-OR the contents of the accumulator with the contents of the ACCB. The results are placed in the accumulator.
XORK # *lk* [,*shift*]		√	√	√	**XOR Immediate With Accumulator With Shift**
					Exclusive-OR a 16-bit immediate value with the accumulator. If a shift is specified, left-shift the value before XORing. Low-order bits below and high-order bits above the shifted value are treated as 0s.
XPL [# *lk*] ,*dma*				√	**Exclusive-OR of Long Immediate or DBMR With Addressed Data Memory Value**
XPL [# *lk*,] {*ind*} [,*next ARP*]				√	
					If a long immediate value is specified, XOR it with the addressed data memory value; otherwise, XOR the DBMR with the addressed data memory value. Write the result back to the data memory location. The accumulator contents are not disturbed.
ZAC	√	√	√	√	**Zero Accumulator**
					Clear the contents of the accumulator to 0.
ZALH *dma*	√	√	√	√	**Zero Low Accumulator and Load High Accumulator**
ZALH {*ind*} [,*next ARP*]	√	√	√	√	
					Clear the 16 LSBs of the accumulator to 0 and load the contents of the addressed data memory location into the 16 MSBs of the accumulator.
ZALR *dma*		√	√	√	**Zero Low Accumulator, Load High Accumulator With Rounding**
ZALR {*ind*} [,*next ARP*]		√	√	√	
					Load the contents of the addressed data memory location into the 16 MSBs of the accumulator. The value is rounded by 1/2 LSB; that is, the 15 LSBs of the accumulator (0–14) are cleared, and bit 15 is set to 1.

Syntax	1x	2x	2xx	5x	Description
ZALS *dma*	√	√	√	√	**Zero Accumulator, Load Low Accumulator With Sign Extension Suppressed**
ZALS {*ind*} [*,next ARP*]	√	√	√	√	
					Load the contents of the addressed data memory location into the 16 LSBs of the accumulator. The 16 MSBs are zeroed. The data is treated as a 16-bit unsigned number.
ZAP				√	**Zero the Accumulator and Product Register**
					The accumulator and product register are zeroed. The ZAP instruction speeds up the preparation for a repeat multiply/accumulate.
ZPR				√	**Zero the Product Register**
					The product register is cleared.

Macro Language

The assembler supports a macro language that enables you to create your own "instructions." This is especially useful when a program executes a particular task several times. The macro language lets you:

❑ Define your own macros and redefine existing macros
❑ Simplify long or complicated assembly code
❑ Access macro libraries created with the archiver
❑ Define conditional and repeatable blocks within a macro
❑ Manipulate strings within a macro
❑ Control expansion listing

This chapter discusses the following topics:

6.1   Using Macros

Programs often contain routines that are executed several times. Instead of repeating the source statements for a routine, you can define the routine as a macro and call the macro in the places where you would normally repeat the routine. This simplifies and shortens your source program.

Using a macro is a three-step process.

Step 1:   Define the macro. You must define macros before you can use them in your program. There are two methods for defining macros:

❑   Macros can be defined at the beginning of a **source file** or in a **.include/.copy** file. Refer to Section 6.2 for more information.

❑   Macros can also be defined in a **macro library**. A macro library is a collection of files in archive format created by the archiver. Each member of the archive file (macro library) may contain one macro definition corresponding to the member name. You can access a macro library by using the .mlib directive. Macro libraries are discussed in Section 6.4, page 6-13.

Step 2:   Call the macro. After you have defined a macro, you can call it by using the macro name as an opcode in the source program. This is referred to as a *macro call*.

Step 3:   Expand the macro. The assembler expands your macros when the source program calls them. During expansion, the assembler passes arguments by variable to the macro parameters, replaces the macro call statement with the macro definition, then assembles the source code. By default, the macro expansions are printed in the listing file. You can turn off expansion listing by using the .mnolist directive. For more information, refer to Section 6.8, page 6-18.

When the assembler encounters a macro definition, it places the macro name in the opcode table. This redefines any previously defined macro, library entry, directive, or instruction mnemonic that has the same name as the encountered macro. This allows you to expand the functions of directives and instructions, as well as to add new instructions.

6.2   Defining Macros

You can define a macro anywhere in your program, but you must define it before you can use it. Macros can be defined at the beginning of a source file or in an .include/.copy file; they can also be defined in a macro library. For more information about macro libraries, refer to Section 6.4, page 6-13.

Macro definitions can be nested, and they can call other macros, but all elements of the macro must be defined in the same file. Nested macros are discussed in Section 6.9, page 6-19.

A macro definition is a series of source statements in the following format:

macname   **.macro**   [*parameter₁*] [*,parameter₂*] ... [*,parameterₙ*]

model statements or macro directives

[.mexit]

.endm

macname	names the macro. You must place the name in the source statement's label field. The first 32 characters of a macro name are significant. The assembler places the macro name in the internal opcode table, replacing any instruction or previous macro definition with the same name.
.macro	is a directive that identifies the source statement as the first line of a macro definition. You must place .macro in the opcode field.
[*parameters*]	are optional substitution symbols that appear as operands for the .macro directive. Parameters are discussed in Section 6.3, page 6-5.
model statements	are instructions or assembler directives that are executed each time the macro is called.
macro directives	are used to control macro expansion.
[.mexit]	functions as a "goto .endm". The .mexit directive is useful when error testing confirms that macro expansion will fail.
.endm	terminates the macro definition.

Example 6–1 shows the definition, call, and expansion of a macro.

Example 6–1. Macro Definition, Call, and Expansion

```
Macro definition: The following code defines a macro, add3, with 3 parameters:

 3  *   add3   p1, p2, p3
 4  *          p3 = p1 + p2 + p3
 5
 6      add3   .macro p1, p2, p3
 7
 8             lac    p1
 9             add    p2
10             add    p3
11             sacl   p3
12             .endm
```

Macro Call: The following code calls the add3 macro with 3 arguments:

```
13
14 0000        add3   a, b, c
```

Macro Expansion: The following code shows the substitution of the macro definition for the macro call. The assembler passes the arguments (supplied in the macro call) by variable to the parameters (substitution symbols).

```
   0000 2000 lac    a
   0001 0001 add    b
   0002 0002 add    c
   0003 6002 sacl   c

15
16
17 *   Reserve space for vars
18 0000        .bss   a,1
19 0001        .bss   b,1
20 0002        .bss   c,1
```

If you want to include comments with your macro definition but *don't* want those comments to appear in the macro expansion, use an exclamation point to precede your comments. If you *do* want your comments to appear in the macro expansion, use an asterisk or semicolon. For more information about macro comments, refer to Section 6.7, page 6-17.

6.3 Macro Parameters/Substitution Symbols

If you want to call a macro several times, with different data each time, you can assign parameters to it. This enables you to pass information to the macro each time you call it. The macro language supports a special symbol called a **substitution symbol**, which is used for macro parameters. In this chapter, we use the terms *macro parameters* and *substitution symbols* interchangeably.

6.3.1 Substitution Symbols

Macro parameters are substitution symbols that represent a character string. These symbols can also be used outside of macros to equate a character string to a symbol name.

Valid substitution symbols may be 32 characters long and *must begin with a letter*. The remainder of the symbol can be a combination of alphanumeric characters, underscores, and dollar signs.

Substitution symbols used as macro parameters are local to the macro they are defined in. You can define up to 32 local substitution symbols (including substitution symbols defined with the .var directive) per macro. For more information about the .var directive, refer to page 6-12.

During macro expansion, the assembler passes arguments by variable to the macro parameters. The character-string equivalent of each argument is assigned to the corresponding parameter. Parameters without corresponding arguments are set to the null string. If the number of arguments exceeds the number of parameters, the last parameter is assigned the character-string equivalent of all remaining arguments.

If you pass a list of arguments to one parameter, or if you pass a comma or semicolon to a parameter, you must enclose the arguments in quotation marks.

At assembly time, the assembler first replaces the substitution symbol with its corresponding character string, then translates the source code into object code.

Example 6–2 shows the expansion of a macro with varying numbers of arguments.

Example 6–2.Calling a Macro With Varying Numbers of Arguments

```
Macro Definition

Parms   .macro a,b,c
;          a = :a:
;          b = :b:
;          c = :c:
        .endm

Calling the macro Parms

        Parms   100,label        Parms    100,label,x,y
;          a = 100                    ;    a = 100
;          b = label                  ;    b = label
;          c = " "                    ;    c = x,y


        Parms   100, , x          Parms    "100,200,300",x,y
;          a = 100                    ;    a = 100,200,300
;          b = " "                    ;    b = x
;          c = x                      ;    c = y


        Parms   """string""",x,y
;          a = "string"
;          b = x
;          c = y
```

6.3.2   Directives That Define Substitution Symbols

You can manipulate substitution symbols with the **.asg** and **.eval** directives.

❑ The **.asg** directive assigns a character string to a substitution symbol.

The syntax of the .asg directive is:

> **.asg** ["] *character string* ["], *substitution symbol*

The quotation marks are optional. If there are no quotation marks, the assembler reads characters up to the first comma and removes leading and trailing blanks. In either case, a character string is read and assigned to the substitution symbol.

Example 6–3 shows character strings being assigned to substitution symbols.

Example 6–3.Using the .asg Directive

```
        .asg   ar0 ,FP             ; frame pointer
        .asg   *+  ,Ind            ; indirect addressing
        .asg   *bro+,Rc_Prop       ; reverse carry propagation
        .asg   """string""",strng  ; string
        .asg   "a,b,c" ,parms      ; parameters
        mar    Ind,FP              ; mar *+, AR0
```

❑ The **.eval** directive performs arithmetic on numeric substitution symbols.

The syntax of the .eval directive is:

.eval *well-defined expression, substitution symbol*

The **.eval** directive evaluates the expression and assigns the **string value** of the result to the substitution symbol. If the expression is not well defined, the assembler generates an error and assigns the null string to the symbol.

Example 6–4 shows arithmetic being performed on substitution symbols.

Example 6–4. Using the .eval Directive

```
        .asg        1,counter
        .loop       100
        .word       counter
        .eval       counter + 1,counter
        .endloop
```

In Example 6–4, the .asg directive could be replaced with the .eval directive (.eval 1, counter) without changing the output. In simple cases like this, you can use .eval and .asg interchangeably. However, you must use .eval if you want to calculate a *value* from an expression. While .asg only assigns a character string to a substitution symbol, .eval evaluates an expression and then assigns the character string equivalent to a substitution symbol.

6.3.3 Built-In Substitution Symbol Functions

The following built-in substitution symbol functions enable you to make decisions based on the string value of substitution symbols. These functions always return a value, and they can be used in expressions. Built-in substitution symbol functions are especially useful in conditional assembly expressions. Parameters to these functions are substitution symbols or character-string constants.

In Table 6–1 function definitions, *a* and *b* are parameters that represent substitution symbols or character string constants. The term *string* refers to the string value of the parameter.

Table 6–1. Substitution Symbol Functions

Function	Return Value
$symlen(a)	length of string a
$symcmp(a,b)	< 0 if a < b 0 if a = b > 0 if a > b
$firstch(a,ch)	index of the first occurrence of character constant ch in string a
$lastch(a,ch)	index of the last occurrence of character constant ch in string a
$isdefed(a)	1 if string a is defined in the symbol table 0 if string a is not defined in the symbol table
$ismember(a,b)	top member of list b is assigned to string a 0 if b is a null string
$iscons(a)	1 if string a is a binary constant 2 if string a is an octal constant 3 if string a is a hexadecimal constant 4 if string a is a character constant 5 if string a is a decimal constant
$isname(a)	1 if string a is a valid symbol name 0 if string a is not a valid symbol name
$isreg(a)†	1 if string a is a valid predefined register name 0 if string a is not a valid predefined register name

† For more information about predefined register names, refer to Section 3.9, page 3-20.

Example 6–5 shows built-in substitution symbol functions.

Example 6–5. Using Built-In Substitution Symbol Functions

```
        .asg   label, a                 ; a = label
        .if    ($symcmp(a,"label") = 0) ; evaluates to true
        sub    a
        .endif
        .asg   "x,y,z"   ,   list        ; list = x,y,z
        .if    ($ismember(a, list))      ; a = x  list = y,z
        sub a                            ; sub      x
        .endif
```

6.3.4   Recursive Substitution Symbols

When the assembler encounters a substitution symbol, it attempts to substitute the corresponding character string. If that string is also a substitution symbol, the assembler performs substitution again. The assembler continues doing this until it encounters a token that is not a substitution symbol or until it encounters a substitution symbol that it has already encountered during this evaluation.

In Example 6–6, the x is substituted for z, z is substituted for y, and y is substituted for x. The assembler recognizes this as infinite recursion and ceases substitution.

Example 6–6.Recursive Substitution

```
        .asg    "x",z  ; declare z and assign z = "x"
        .asg    "z",y  ; declare y and assign y = "z"
        .asg    "y",x  ; declare x and assign x = "y"
        add x


*       add x           ; recursive expansion
```

6.3.5   Forced Substitution

In some cases, substitution symbols are not recognizable to the assembler. The forced substitution operator, which is a set of colons, enables you to force the substitution of a symbol's character string. Simply enclose a symbol in colons to force the substitution. Do not include any spaces between the colons and the symbol.

The syntax for the forced substitution operator is:

:*symbol***:**

The assembler expands substitution symbols enclosed in colons before expanding other substitution symbols.

You can use the forced substitution operator only inside macros, and you cannot nest a forced substitution operator within another forced substitution operator.

Example 6–7 shows how the forced substitution operator is used.

Example 6–7. Using the Forced Substitution Operator

```
force   .macro x
        .asg      0,x
        .loop 8   ;.loop/.endloop are discussed on page 6-14
AUX:x:  .set   x
        .eval  x+1,x
        .endloop
        .endm
```
The force macro would generate the following source code:
```
AUX0    .set   0
AUX1    .set   1
   .
   .
   .
AUX7    .set   7
```

6.3.6 Accessing Individual Characters of Subscripted Substitution Symbols

In a macro, you can access the individual characters (substrings) of a substitution symbol with subscripted substitution symbols. You must use the forced substitution operator for clarity.

You can access substrings in two ways:

❑ :*symbol* (*well-defined expression*):

This method of subscripting evaluates to a character string with one character.

❑ :*symbol* (*well-defined expression$_1$*, *well-defined expression$_2$*):

In this method, expression$_1$ represents the substring's starting position, and expression$_2$ represents the substring's length. You can specify exactly where to begin subscripting and the exact length of the resulting character string. *The index of substring characters begins with 1, not 0.*

Example 6–8 and Example 6–9 show built-in substitution symbol functions used with subscripted substitution symbols.

Example 6–8.Using Subscripted Substitution Symbols to Redefine an Instruction

```
addx        .macro      a
            .var        tmp
            .asg        :a(1):,tmp
            .if         $symcmp(tmp,"#") = 0
addk        a
            .elseif     $symcmp(tmp,"*") = 0
add         a
            .else
            .emsg       "Bad Macro Parameter"
            .endif
            .endm

            addx        #100        ;macro call
            addx        *+          ;macro call
```

In Example 6–8, subscripted substitution symbols redefine the add instruction so that it handles short immediates.

Example 6–9.Using Subscripted Substitution Symbols to Find Substrings

```
substr      .macro      start,strg1,strgh2,pos
            .var        len1,len2,i,tmp
            .if         $symlen(start) = 0
            .eval       start,1
            .endif
            .eval       0,pos
            .eval       1,i
            .eval       $symlen(strg1),len1
            .eval       $symlen(strg2),len2
            .loop
            .break      i = (len2 – len1 + 1)
            .asg        ":strg2(i,len1):",tmp
            .if         $symcmp(strg1,tmp) = 0
            .eval       i,pos
            .break
            .else
            .eval       i + 1,i
            .endif
            .endloop
            .endm

            .asg        0,pos
            .asg        "ar1 ar2 ar3 ar4",regs
            substr      1,"ar2",regs,pos
            .word       pos
```

In Example 6–9, the subscripted substitution symbol is used to find a substring strg1, beginning at position start in the string strg2. The position of the substring strg1 is assigned to the substitution symbol pos.

6.3.7 Substitution Symbols as Local Variables in Macros

If you want to use substitution symbols as local variables within a macro, you can use the **.var** directive to define up to 32 local macro substitution symbols (including parameters) per macro. The .var directive creates temporary substitution symbols with the initial value of the null string. These symbols are not passed in as parameters, and they are lost after expansion.

.var sym_1 [,sym_2] ... [,sym_n]

The .var directive is used in Example 6–8 and Example 6–9.

6.4 Macro Libraries

One way to define macros is by creating a macro library. A macro library is a collection of files that contain macro definitions. You must use the archiver to collect these files, or members, into a single file (called an archive). Each member of a macro library contains one macro definition. The files must be unassembled source files. The macro name and the member name must be the same, and the macro filename's extension must be .asm. For example:

Macro Name	Filename in Macro Library
simple	simple.asm
add3	add3.asm

You can access the macro library by using the .mlib assembler directive. The syntax for .mlib is:

.mlib *macro library filename*

When the assembler encounters an .mlib directive, it opens the library and creates a table of the library's contents. The assembler enters the names of the individual members into the opcode tables as library entries; this redefines any existing opcodes or macros that have the same name. If one of these macros is called, the assembler extracts the entry from the library and loads it into the macro table.

The assembler expands the library entry in the same way it expands other macros. You can control the listing of library entry expansions with the .mlist directive. For more information about the .mlist directive, refer to Section 6.8, page 6-18. Only macros that are actually called from the library are extracted, and they are extracted only once. For more information about the .mlib directive, refer to page 4-55.

You can create a macro library with the archiver by simply including the desired files in an archive. A macro library is no different from any other archive, except that the assembler expects the macro library to contain macro definitions. The assembler expects *only* macro definitions in a macro library; putting object code or miscellaneous source files into the library may produce undesirable results.

6.5   Using Conditional Assembly in Macros

The conditional assembly directives are **.if/.elseif/.else/.endif** and **.loop/.break/.endloop**. They can be nested within each other up to 32 levels. The format of a conditional block is:

> **.if** *well-defined expression*
>
> **[.elseif** *well-defined expression***]**
>
> **[.else]**
>
> **.endif**

The .elseif and .else directives are optional, and the .elseif directive can be used more than once within a conditional assembly code block. When .elseif and .else are omitted and the .if expression is false (zero), the assembler continues to the code following the .endif directive. For more information on the .if/.elseif/.else/.endif directives, see page 4-46.

The **.loop/.break/.endloop** directives enable you to assemble a code block repeatedly. The format of a repeatable block is:

> **.loop** [*well-defined expression*]
>
> **[.break** [*well-defined expression*]**]**
>
> **.endloop**

The .loop directive's optional expression evaluates to the loop count (the number of loops to be performed). If the expression is omitted, the loop count defaults to 1024 unless the assembler encounters a .break directive with an expression that is true (nonzero). For more information on the .loop/.break/.endloop directives, see page 4-54.

The .break directive and its expression are optional. If the expression evaluates to false, the loop continues. The assembler breaks the loop when the .break expression evaluates to true or when the .break expression is omitted. When the loop is broken, the assembler continues with the code after the .endloop directive.

Example 6–10, Example 6–11, and Example 6–12 show the .loop/.break/ .endloop directives, properly nested conditional assembly directives, and built-in substitution symbol functions are used in a conditional assembly code block.

Example 6–10. The .loop/.break/.endloop Directives

```
        .asg   1,x
        .loop            ;   "infinite"

        .break (x == 10) ;   if x == 10, quit loop/break with
*                                                   expression

        .eval  x+1,x
        .endloop
```

Example 6–11. Nested Conditional Assembly Directives

```
        .asg   1,x
        .loop         ;   "infinite"

        .if (x == 10);   if x == 10 quit loop
        .break        ;   force break
        .endif

        .eval   x+1,x
        .endloop
```

Example 6–12. Built-In Substitution Symbol Functions Used in a Conditional Assembly Code Block

```
        .fcnolist
*
*Subtract Double
*
subx    .macro a            ; subtract double

        .if $symcmp(a,"*")
        subh *+             ; subtract high
        subs *–             ; subtract low
        .elseif $symcmp(a,"*+")
        subh *+             ; subtract high
        subs *+             ; subtract low
        .elseif $symcmp(a,"*–")
        subs *–             ; subtract low
        subh *–             ; subtract high
        .else
        subh a              ; subtract high
        subs a + 1              ; subtract low
        .endif

        .endm

*Macro Call
        subx *+
```

For more information about conditional assembly directives, refer to Section 4.7, page 4-15.

6.6   Using Labels in Macros

All labels in an assembly language program must be unique. This includes labels in macros. If a macro is expanded more than once, its labels are defined more than once. *Defining a label more than once is illegal*. The macro language provides a method of defining labels in macros so that the labels are unique. Simply follow the label with a question mark, and the assembler will replace the question mark with a unique number. When the macro is expanded, *you will not see the unique number in the listing file*. Your label will appear with the question mark, as it did in the macro definition. You cannot declare this label as global. The syntax for a unique label is:

*label***?**

Example 6–13 shows unique label generation in a macro.

Example 6–13. Unique Labels in a Macro

```
;   define macro

MIN         .macro     a,b

            lac        a
            sub        b
            blz        m1?
            lac        b
            b          m2?
m1?         lac        a
m2?
            .endm

;   call macro

            MIN        x,#100

;   expand macro

            lac        x
            sub        #100
            blz        m1?
            lac        #100
            b          m2?
m1?         lac        x
m2?
```

The maximum label length is shortened to allow for the unique suffix. For example, if the macro is expanded fewer than 10 times, the maximum label length is 126 characters. If the macro is expanded from 10 to 99 times, the maximum label length is 125. The label with its unique suffix is shown in the cross-listing file.

6.7 Producing Messages in Macros

The macro language supports three directives that enable you to define your own assembly-time error and warning messages. These directives are useful when you want to create messages specific to your needs. The last line of the listing file shows the error and warning counts. These counts alert you to problems in your code and are especially useful during debugging.

.emsg   sends error messages to the listing file. The .emsg directive generates errors in the same manner as the assembler, incrementing the error count and preventing the assembler from producing an object file.

.wmsg   sends warning messages to the listing file. The .wmsg directive functions in the same manner as the .emsg directive but increments the warning count and does not prevent the generation of an object file.

.mmsg   sends warnings or assembly-time messages to the listing file. The .mmsg directive functions in the same manner as the .emsg directive but does not set the error count or prevent the generation of an object file.

Macro comments are comments that appear in the definition of the macro *but do not show up in the expansion of the macro.* An exclamation point in column 1 identifies a macro comment. If you want your comments to appear in the macro expansion, precede your comment with an asterisk or semicolon.

Example 6–14 shows user messages in macros and macro comments that will not appear in the macro expansion.

Example 6–14. Producing Messages in a Macro

```
TEST    .MACRO    x,y
!
!   This macro checks for the correct number of parameters.
!   The macro generates an error message if x and y are not
!                                           present.
!
        .if    ($symlen(x) == 0|$symlen(y) == 0)) ; Test for
                                              ; proper input
        .emsg  "ERROR – missing parameter in call to TEST"
        .mexit
        .else
          .
          .
        .endif
        .if
          .
          .
        .endif
        .endm

    1 error, no warnings
```

6.8 Formatting the Output Listing

Macros, substitution symbols, and conditional assembly directives may hide information. You may need to see this hidden information, so the macro language supports an expanded listing capability.

By default, the assembler shows macro expansions and false conditional blocks in the list output file. You may want to turn this listing off or on within your listing file. Four sets of directives enable you to control the listing of this information:

❑ **Macro and Loop Expansion Listing**

.mlist   expands macros and .loop/.endloop blocks. The .mlist directive prints all code encountered in those blocks.*.*

.mnolist   suppresses the listing of macro expansions and .loop/ .endloop blocks.

For macro and loop expansion listing, .mlist is the default.

❑ **False Conditional Block Listing**

.fclist   causes the assembler to include in the listing file all conditional blocks that do not generate code (false conditional blocks). Conditional blocks appear in the listing exactly as they appear in the source code.

.fcnolist   suppresses the listing of false conditional blocks. Only the code in conditional blocks that actually assemble appears in the listing. The .if, .elseif, .else, and .endif directives do not appear in the listing.

For false conditional block listing, .flist is the default.

❑ **Substitution Symbol Expansion Listing**

.sslist   expands substitution symbols in the listing. This is useful for debugging the expansion of substitution symbols. The expanded line appears below the actual source line.

.ssnolist turns off substitution symbol expansion in the listing.

For substitution symbol expansion listing, .ssnolist is the default.

❑ **Directive Listing**

.drlist   causes the assembler to print to the listing file all directive lines.

.drnolist suppresses the printing of the following directives in the listing file: .asg, .eval, .var, .sslist, .mlist, .fclist, .ssnolist, .mnolist, .fcnolist, .emsg, .wmsg, .mmsg, .length, .width, and .break.

For directive listing, .drlist is the default.

6.9 Using Recursive and Nested Macros

The macro language supports recursive and nested macro calls. This means that you can call other macros in a macro definition. You can nest macros up to 32 levels deep. When you use recursive macros, you call a macro from its own definition (the macro calls itself).

When you create recursive or nested macros, you should pay close attention to the arguments that you pass to macro parameters because the assembler uses dynamic scoping for parameters. This means that the called macro uses the environment of the macro from which it was called.

Example 6–15 shows nested macros. Note that the y in the in_block macro hides the y in the out_block macro. The x and z from the out_block macro, however, are accessible to the in_block macro.

Example 6–15. Using Nested Macros

```
in_block  .macro y,a
                .           ; visible parameters are y,a and
                .           ;     x,z from the calling macro
          .endm

out_block .macro x,y,z
                .           ; visible parameters are x,y,z
                .
          in_block x,y ; macro call with x and y as
                       ;      arguments
                .
                .
          .endm
          out_block     ; macro call
```

Example 6–16 shows recursive macros. The fact macro produces assembly code necessary to calculate the factorial of n where n is an immediate value. The result is placed in data memory address loc. The fact macro accomplishes this by calling fact1, which calls itself recursively.

Example 6–16. Using Recursive Macros

```
fact    .macro n,loc      ; n is an integer constant
                          ; loc memory address = n!
        .if    n < 2      ; 0! = 1! = 1
        lack   1
        sacl   loc
        .else
        lack   n          ; n >= 2 so, store n at loc
        sacl   loc        ; decrement n, and do the
        .eval  n – 1,n    ;     factorial of n – 1
        fact1             ; call fact with current
                          ;     environment
        .endif

        .endm

fact1   .macro

        .if    n > 1
        lt     loc        ; multiply present factorial
        mpyk   n          ;      by present position
        pac
        sacl   loc        ; save result
        .eval  n – 1,n    ; decrement position
        fact1             ; recursive call
        .endif

        .endm
```

6.10 Macro Directives Summary

Table 6–2. Creating Macros

Mnemonic and Syntax	Description
macname **.macro** [*parameter₁*]...[,*parameterₙ*]	Define macro
.mlib *filename*	Identify library containing macro definitions
.mexit	Go to .endm
.endm	End macro definition

Table 6–3. Manipulating Substitution Symbols

Mnemonic and Syntax	Description
.asg ["]*character string*["], *substitution symbol*	Assign character string to substitution symbol
.eval *well-defined expression*, *substitution symbol*	Perform arithmetic on numeric substitution symbols
.var *substitution symbol*[₁...,*substitution symbolₙ*]	Define local macro symbols

Table 6–4. Conditional Assembly

Mnemonic and Syntax	Description
.if *well-defined expression*	Assemble code block if the condition is true
.elseif *well-defined expression*	Assemble code block if the .if condition is false and the .elseif condition is true. The .elseif construct is optional.
.else	Assemble code block if the .if condition is false. The .else construct is optional.
.endif	End .if code block
.loop [*well-defined expression*]	Begin repeatable assembly of a code block
.break [*well-defined expression*]	End .loop assembly if condition is true. The .break construct is optional.
.endloop	End .loop code block

Table 6–5. Producing Assembly-Time Messages

Mnemonic and Syntax	Description
.emsg	Send error message to standard output
.wmsg	Send warning message to standard output
.mmsg	Send assembly-time message to standard output

Table 6–6. Formatting the Listing

Mnemonic and Syntax	Description
.drlist	Enable listing of all directive lines (default)
.drnolist	Inhibit listing of the following directives lines: .asg, .eval, .var, .sslist, .mlist, .fclist, .ssnolist, .mnolist, .fcnolist, .emsg, .mmsg, .wmsg, .length, .width, and .break
.fclist	Allow false conditional code block listing (default)
.fcnolist	Inhibit false conditional code block listing
.mlist	Allow macro listings (default)
.mnolist	Inhibit macro listings
.sslist	Allow expanded substitution symbol listing
.ssnolist	Inhibit expanded substitution symbol listing (default)

Archiver Description

The **archiver** allows you to collect a group of files into a single archive file. For example, you can collect several macros into a macro library. The assembler will search the library and use the members that are called as macros by the source file. You can also use the archiver to collect a group of object files into an object library. The linker will include in the library the members that resolve external references during the link.

These are the topics covered in this chapter:

7.1 Archiver Overview

The TMS320C1x/C2x/C2xx/C5x archiver lets you combine several individual files into a single file called an archive or a library. Each file within the archive is called a member**.** Once you have created an archive, you can use the archiver to add, delete, or extract members.

You can build libraries from any type of file. Both the assembler and the linker accept archive libraries as input; the assembler can use libraries that contain individual source files, and the linker can use libraries that contain individual object files.

One of the most useful applications of the archiver is building libraries of object modules. For example, you can write several arithmetic routines, assemble them, and use the archiver to collect the object files into a single, logical group. You can then specify the object library as linker input. The linker will search the library and include members that resolve external references.

You can also use the archiver to build macro libraries. You can create several source files, each of which contains a single macro, and use the archiver to collect these macros into a single, functional group. The .mlib assembler directive lets you specify the name of a macro library; during the assembly process, the assembler will search the specified library for the macros that you call. Chapter 6 discusses macros and macro libraries in detail.

7.2 Archiver Development Flow

Figure 7–1 shows the archiver's role in the assembly language development process. Both the assembler and the linker accept libraries as input.

Figure 7–1. Archiver Development Flow
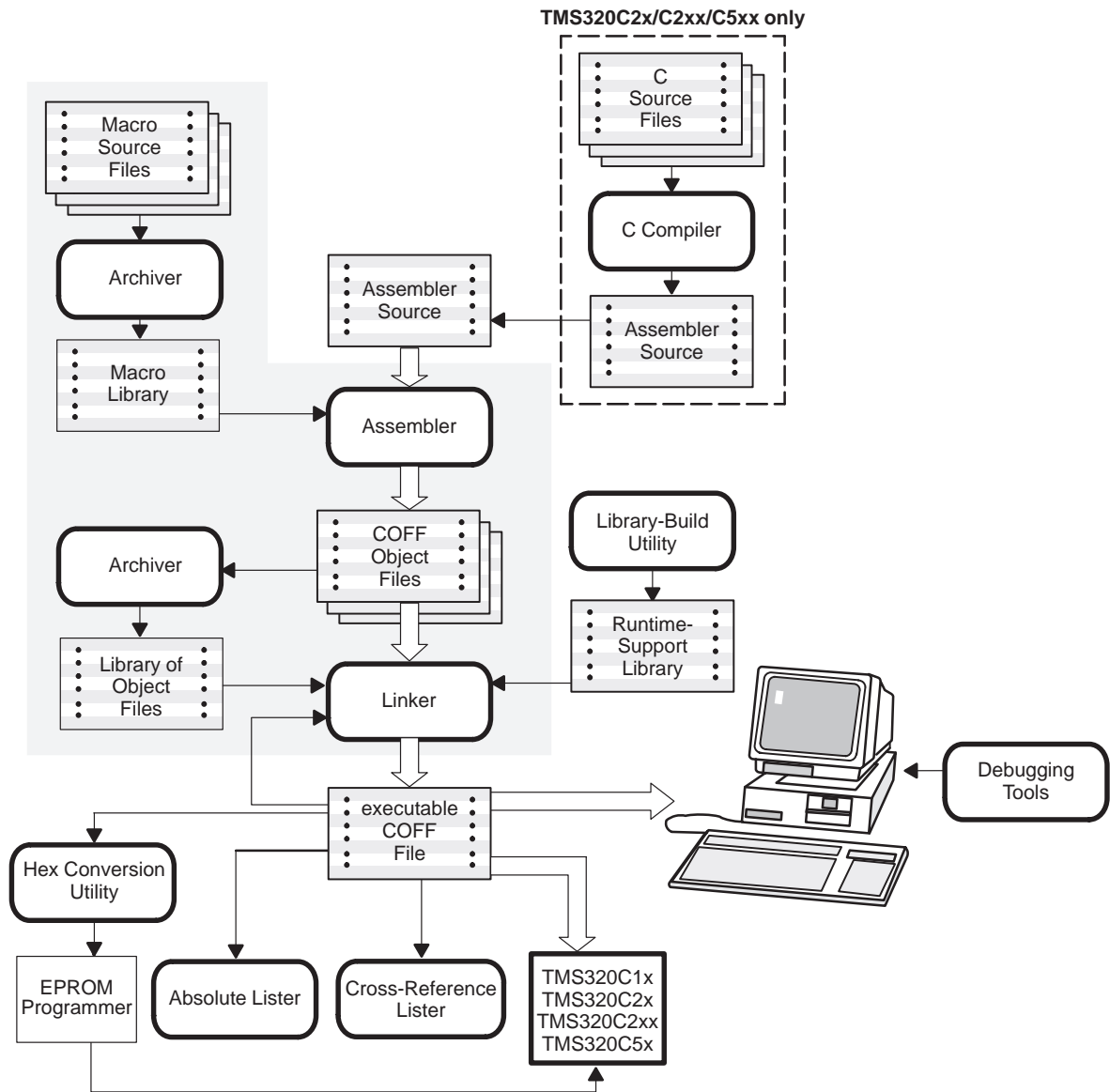
7.3 Invoking the Archiver

To invoke the archiver, enter:

> **dspar** [–]*command*[*option*] *libname* [*filename$_1$* ... *filename$_n$*]

dspar   is the command that invokes the archiver.

libname   names an archive library. If you don't specify an extension for *libname,* the archiver uses the default extension *.lib*.

filename   names individual member files that are associated with the library. If you don't specify an extension for a *filename,* the archiver uses the default extension *.obj*.

Note: Naming Library Members

It is possible (but not desirable) for a library to contain several members with the same name. If you attempt to delete, replace, or extract a member, and the library contains more than one member with the specified name, the archiver deletes, replaces, or extracts the first member with that name.

---

command   tells the archiver how to manipulate the library members. A command can be preceded by an optional hyphen. You must use one of the following commands when you invoke the archiver, but you can use only one command per invocation. Valid archiver commands are:

    a   adds the specified files to the library. This command does not replace an existing member that has the same name as an added file; it simply *appends* new members to the end of the archive.

    d   deletes the specified members from the library.

    r   replaces the specified members in the library. If you don't specify filenames, the archiver replaces the library members with files of the same name in the current directory. If the specified file is not found in the library, the archiver adds it instead of replacing it.

    t   prints a table of contents of the library. If you specify filenames, only those files are listed. If you don't specify any filenames, the archiver lists all the members in the specified library.

x   extracts the specified files. If you don't specify member names, the archiver extracts all library members. When the archiver extracts a member, it simply copies the member into the current directory; it *doesn't* remove it from the library.

In addition to one of the *commands,* you can specify the following *options*:

–e   tells the archiver not to use the default extension .obj for member names. This allows the use of filenames without extensions.

–q   (quiet) suppresses the banner and status messages.

–s   prints a list of the global symbols that are defined in the library. (This option is valid only with the –a, –r, and –d commands.)

–v   (verbose) provides a file-by-file description of the creation of a new library from an old library and its constituent members.

7.4 Archiver Examples

The following are examples of how to use the archiver:

❑ **Example 1**

This example creates a library called function.lib that contains the files sine.obj, cos.obj, and flt.obj.

```
dspar –a function sine cos flt
DSP Archiver              Version x.xx
Copyright (c) 1987–1995 Texas Instruments Incorporated
   ==>   new archive 'function.lib'
   ==>   building archive 'function.lib'
```

Because Example 1 and 2 use the default extensions (.lib for the library and .obj for the members), it is not necessary to specify extensions in these examples.

❑ **Example 2**

You can print a table of contents of function.lib with the –t option:

```
dspar –t function
DSP Archiver              Version x.xx
Copyright (c) 1987–1995 Texas Instruments Incorporated
     FILE NAME    SIZE   DATE
----------------  -----  -----------------------
     sine.obj     248    Mon Nov 19 01:25:44 1984
     cos.obj      248    Mon Nov 19 01:25:44 1984
     flt.obj      248    Mon Nov 19 01:25:44 1984
```

❑ **Example 3**

You can explicitly specify extensions if you don't want the archiver to use the default extensions; for example:

```
dspar –av function.fn sine.asm cos.asm flt.asm
DSP Archiver              Version x.xx
Copyright (c) 1987–1995 Texas Instruments Incorporated
   ==>   add 'sine.asm'
   ==>   add 'cos.asm'
   ==>   add 'flt.asm'
   ==>   building archive 'function.fn'
```

This creates a library called function.fn that contains the files sine.asm, cos.asm, and flt.asm. (–v is the verbose option.)

❏ **Example 4**

If you want to add new members to the library, specify:

```
dspar –as function tan.obj arctan.obj area.obj
DSP Archiver            Version x.xx
Copyright (c) 1987–1995 Texas Instruments Incorporated
   ==>    symbol defined: 'K2'
   ==>    symbol defined: 'Rossignol'
   ==>    building archive 'function.lib'
```

Because this example doesn't specify an extension for the libname, the archiver adds the files to the library called function.lib. If function.lib didn't exist, the archiver would create it. (The –s option tells the archiver to list the global symbols that are defined in the library.)

❏ **Example 5**

If you want to modify a library member, you can extract it, edit it, and re-place it. In this example, assume there's a library named macros.lib that contains the members push.asm, pop.asm, and swap.asm.

```
dspar –x macros push.asm
```

The archiver makes a copy of push.asm and places it in the current direc-tory; it doesn't remove push.asm from the library. Now you can edit the ex-tracted file. To replace the copy of push.asm in the library with the edited copy, enter:

```
dspar –r macros push.asm
```

Linker Description

The TMS320C1x/C2x/C2xx/C5x linker creates executable modules by combining COFF object files. The concept of COFF sections is basic to linker operation; Chapter 2 discusses the COFF format in detail.

As the linker combines object files, it:

❑ Allocates sections into the target system's configured memory.
❑ Relocates symbols and sections to assign them to final addresses.
❑ Resolves undefined external references between input files.

The linker command language controls memory configuration, output section definition, and address binding. The language supports expression assignment and evaluation and provides two powerful directives, MEMORY and SECTIONS, that allow you to:

❑ Define a memory model that conforms to target system memory.
❑ Combine object file sections.
❑ Allocate sections into specific areas of memory.
❑ Define or redefine global symbols at link time.

8.1 Linker Development Flow

Figure 8–1 illustrates the linker's role in the assembly language development process. The linker accepts several types of files as input, including object files, command files, libraries, and partially linked files. The linker creates an executable COFF object module that can be downloaded to one of several development tools or executed by a TMS320 device.

Figure 8–1. Linker Development Flow
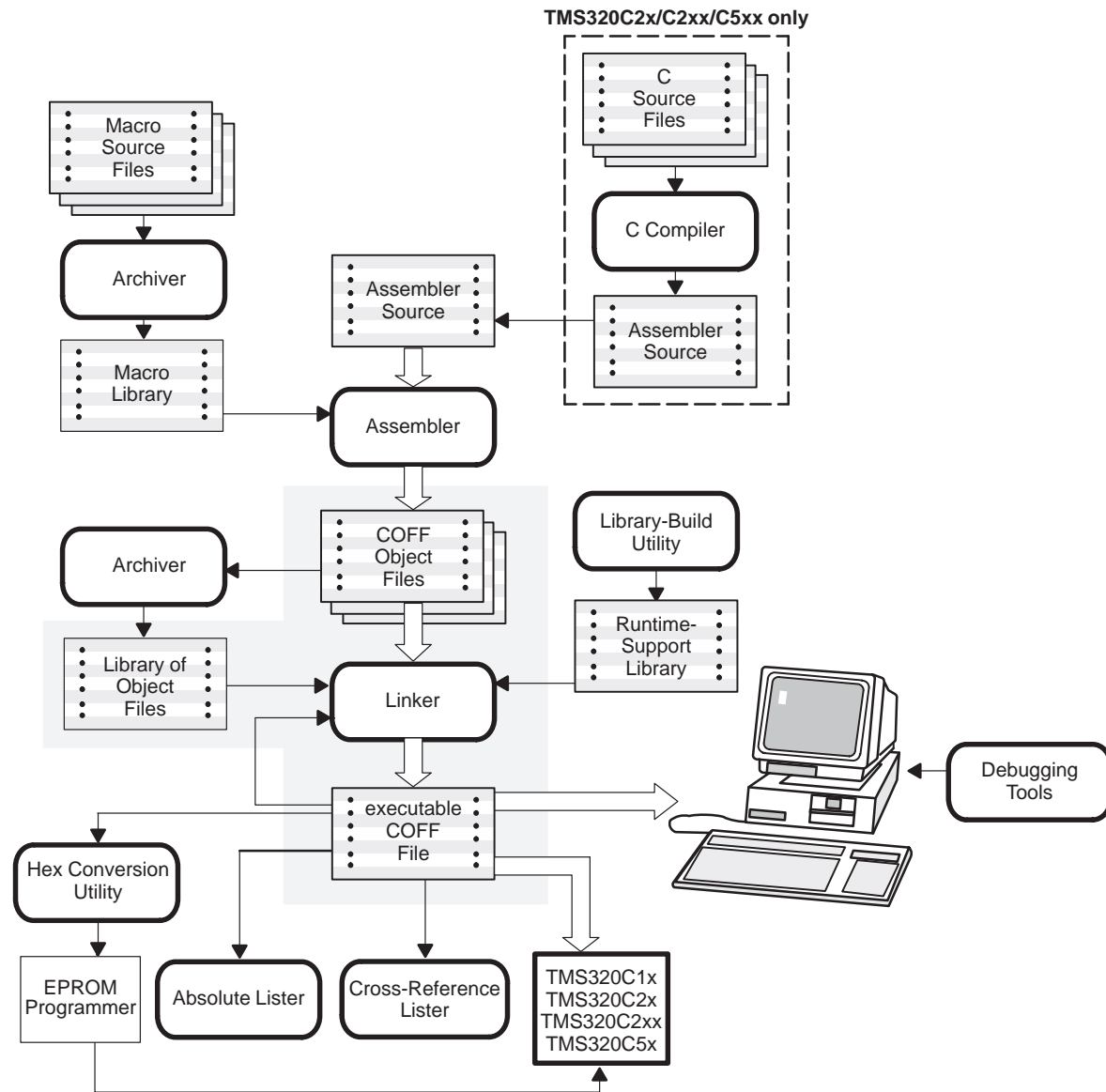
8.2   Invoking the Linker

The general syntax for invoking the linker is:

> **dsplnk** [*−options*] *filename$_1$. ... filename$_n$*

dsplnk   is the command that invokes the linker.

options   can appear anywhere on the command line or in a linker com-
               mand file. (Options are discussed in Section 8.3.)

filenames   can be object files, linker command files, or archive libraries.
               The default extension for all input files is *.obj*; any other exten-
               sion must be explicitly specified. The linker can determine
               whether the input file is an object or ASCII file that contains
               linker commands. The default output filename is *a.out*.

There are three methods for invoking the linker:

❏ Specify options and filenames on the command line. This example links
   two files, file1.obj and file2.obj, and creates an output module named
   link.out.

```
dsplnk file1.obj file2.obj −o link.out
```

❏ Enter the **dsplnk** command with no filenames or options; the linker will
   prompt for them:

```
Object files [.obj] :
Command files :
Output file [a.out] :
Options :
```

   ■ For *object files,* enter one or more object filenames. The default exten-
      sion is *.obj.* Separate the filenames with spaces or commas; if the last
      character is a comma, the linker will prompt for an additional line of
      object filenames.

   ■ For *command files,* enter one or more command filenames.

   ■ The *output file* is the name of the linker output module. This overrides
      any −o options entered with any of the other prompts. If there are no −o
      options and you do not answer this prompt, the linker will create an
      object file with a default filename of *a.out*.

   ■ The *options* prompt is for additional options. You can also enter them
      in a command file. Enter them with hyphens, as you would on the com-
      mand line.

❑ Put filenames and options in a linker command file. For example, assume that the file linker.cmd contains the following lines:

```
–o link.out
file1.obj
file2.obj
```

Now you can invoke the linker from the command line; specify the command filename as an input file:

dsplnk linker.cmd

When you use a command file, you can also specify other options and files on the command line. For example, you could enter:

dsplnk –m link.map linker.cmd file3.obj

The linker reads and processes a command file as soon as it encounters the filename on the command line, so it links the files in this order: file1.obj, file2.obj, and file3.obj. This example creates an output file called link.out and a map file called link.map.

8.3 Linker Options

Linker options control linking operations. They can be placed on the command line or in a command file and must be preceded by a hyphen (–). The order in which options are specified is unimportant, except for the –l and –i options. Options can be separated from arguments (if they have them) by a space. Table 8–1 summarizes the linker options.

Table 8–1. Linker Options Summary

Option	Description
–a	Produce an absolute, executable module. This is the default; if neither –a nor –r is specified, the linker acts as if –a is specified.
–ar	Produce a relocatable, executable object module.
–b	Disable merge of symbolic debugging information.
–c	Use linking conventions defined by the ROM autoinitialization model of the TMS320C2x/C2xx/C5x C compiler.
–cr	Use linking conventions defined by the RAM autoinitialization model of the TMS320C2x/C2xx/C5x C compiler.
–e *global_symbol*	Define a *global_symbol* that specifies the primary entry point for the output module.
–f *fill_value*	Set the default fill value for holes within output sections; *fill_value* is a 16-bit constant.
–h	Make all global symbols static.
–heap *size*	Set heap size (for the dynamic memory allocation in C) to *size* words and define a global symbol that specifies the heap size. Default = 1K words.
–i *dir* †	Alter the library-search algorithm to look in *dir* before looking in the default location. This option must appear before the –l option.
–l *filename* †	Name an archive library file as linker input; *filename* is an archive library name.
–m *filename* †	Produce a map or listing of the input and output sections, including holes, and place the listing in *filename.*
–o *filename* †	Name the executable output module. The default filename is a.out.
–q	Request a quiet run (suppress the banner).
–r	Produce a relocatable output module.
–s	Strip symbol table information and line number entries from the output module.
–stack *size*	Set the C system stack size to *size* words and define a global symbol that specifies the stack size. Default = 1K words.
–u *symbol*	Place the unresolved external symbol *symbol* into the output module's symbol table.
–v0	Generate version 0 COFF format.
–w	Generate a warning when an output section that is not specified with the SECTIONS directive is created.
–x	Force rereading of libraries. Resolves back references.

† The *directory* or *filename* must follow operating system conventions.

8.3.1 Relocation Capabilities (–a and –r Options)

The linker performs relocation, which is the process of adjusting all references to a symbol when the symbol's address changes. The linker supports two options (–a and –r) that allow you to produce an absolute or a relocatable output module. If neither –a nor –r is specified, the linker acts as if –a is specified by default.

❑ **Producing an Absolute Output Module (–a Option)**

When you use the **–a** option without the –r option, the linker produces an absolute, executable output module. Absolute files contain *no* relocation information. Executable files contain the following:

■ Special symbols defined by the linker (subsection 8.13.4, page 8-53, describes these symbols)

■ An optional header that describes information such as the program entry point

■ *No* unresolved references

The following example links file1.obj and file2.obj and creates an absolute output module called a.out:

```
dsplnk –a file1.obj file2.obj
```

❑ **Producing a Relocatable Output Module (–r Option)**

When you use the **–r** option without the –a option, the linker retains relocation entries in the output module. If the output module will be relocated (at load time) or relinked (by another linker execution), use –r to retain the relocation entries.

The linker produces an *unexecutable* file when you use the –r option without –a. A file that is not executable does not contain special linker symbols or an optional header. The file may contain unresolved references, but these references do not prevent creation of an output module.

The following example links file1.obj and file2.obj and creates a relocatable output module called a.out:

```
dsplnk –r file1.obj file2.obj
```

The output file a.out can be relinked with other object files or relocated at load time. (Linking a file that will be relinked with other files is called partial linking. For more information, refer to Section 8.17, page 8-64.)

❑ **Producing an *Executable* Relocatable Output Module (–ar)**

If you invoke the linker with both the –a and –r options, the linker produces an *executable, relocatable* object module. The output file contains the special linker symbols, an optional header, and all resolved symbol references; however, the relocation information is retained.

The following example links file1.obj and file2.obj and creates an executable, relocatable output module called xr.out:

```
dsplnk –ar file1.obj file2.obj –o xr.out
```

You can string the options together (dsplnk –ar) or enter them separately (dsplnk –a –r).

❑ **Relocating or Relinking an Absolute Output Module**

The linker issues a warning message (but continues executing) when it encounters a file that contains no relocation or symbol table information. Relinking an absolute file can be successful only if each input file contains no information that needs to be relocated (that is, each file has no unresolved references and is bound to the same virtual address that it was bound to when the linker created it).

8.3.2 Disable Merge of Symbolic Debugging Information (–b Option)

By default, the linker eliminates duplicate entries of symbolic debugging information. Such duplicate information is commonly generated when a C program is compiled for debugging. For example:

```
–[ header.h ]–
typedef struct
{
   <define some structure members>
} XYZ;

–[ f1.c ]–
#include "header.h"
...

–[ f2.c ]–
#include "header.h"
...
```

When these files are compiled for debugging, both f1.obj and f2.obj will have symbolic debugging entries to describe type XYZ. For the final output file, only one set of these entries is necessary. The linker will eliminate the duplicate entries automatically.

Use the –b option if you do not want the linker to keep such duplicate entries. Using the –b option has the effect of the linker running faster and using less machine memory.

8.3.3 C Language Options (–c and –cr Options)

The –c and –cr options cause the linker to use linking conventions that are required by the TMS320C2x/C2xx/C5x C compiler.

❏ The **–c** option tells the linker to use the ROM autoinitialization model.
❏ The **–cr** option tells the linker to use the RAM autoinitialization model.

For more information about linking C code, refer to Section 8.16, page 8-60, and subsection 8.16.5, page 8-63.

8.3.4 Define an Entry Point (–e *global symbol* Option)

The memory address at which a program begins executing is called the *entry point*. When a loader loads a program into target memory, the program counter must be initialized to the entry point; the PC then points to the beginning of the program.

The linker can assign one of four possible values to the entry point. These values are listed below in the order in which the linker tries to use them. If you use one of the first three values, it must be an external symbol in the symbol table.

❏ The value specified by the –e option. The syntax is **–e** *global symbol* in which global symbol defines the entry point and must appear as an external symbol in one of the input files.

❏ The value of symbol _c_int0 (if present). _c_int0 **must** be the entry point if you are linking code produced by the C compiler.

❏ The value of symbol _main (if present)

❏ Zero (default value)

This example links file1.obj and file2.obj. The symbol begin is the entry point; begin must be defined as external in file1 or file2.

```
dsplnk -e begin file1.obj file2.obj
```

8.3.5 Set Default Value (–f *cc* Option)

The –f option fills the holes formed within output sections or initializes uninitialized sections when they are combined with initialized sections. This allows you to initialize memory areas during link time without reassembling a source file. The argument *cc* is a 16-bit constant (up to four hexadecimal digits). If you do not use –f, the linker uses 0 as the default fill value.

This example fills holes with the hexadecimal value ABCD.

```
dsplnk -f 0ABCDh file1.obj file2.obj
```

8.3.6 Make All Global Symbols Static (–h Option)

The –h option makes global symbols static. This is useful when you are using partial linking to link related object files into self-contained modules, then relinking the modules into a final system. If global symbols in one module have the same name as global symbols in other modules, but you want to treat them as separate symbols, use the –h option when building the modules. These global symbols, which would normally be visible to the other modules and possibly cause redefinition problems in the final link, are made static so that they are not visible to the other modules.

For example, assume that b1.obj, b2.obj, and b3.obj are related and reference a global variable GLOB. Also assume that d1.obj, d2.obj, and d3.obj are related and reference a separate global variable GLOB. You can link the related files together with the following commands:

```
dsplnk –h –r b1.obj b2.obj b3.obj –o bpart.out
dsplnk –h –r d1.obj d2.obj d3.obj –o dpart.out
```

The –h option guarantees that bpart.out and dpart.out will not have global symbols and, therefore, that two distinct versions of GLOB will exist. The –r option is used to allow bpart.out and dpart.out to retain their relocation entries. These two partially linked files can then be linked together safely with the following command:

```
    dsplnk bpart.out dpart.out –o system.out
```

8.3.7 Define Heap Size (–heap *constant* Option)

The TMS320C2x/C2xx/C5x C compiler uses an uninitialized section called .sysmem for the C dynamic memory allocation. You can set the size of this memory pool at link time by using the –heap option. Specify the size as a constant immediately after the option:

```
dsplnk –heap 0x0800 /* defines a 2k heap (.sysmem section)*/
```

The linker creates the .sysmem section only if there is a .sysmem section in an input file.

The linker also creates a global symbol _ _SYSMEM_SIZE and assigns it a value equal to the size of the heap. The default size is 1K words.

For more information about linking C code, see Section 8.16, page 8-60.

8.3.8 Alter the Library Search Algorithm (–i *dir* Option/C_DIR)

Usually, when you want to specify a library as linker input, you simply enter the library name as you would any other input filename; the linker looks for the library in the current directory. For example, suppose the current directory contains the library object.lib. Assume that this library defines symbols that are referenced in the file file1.obj. This is how you link the files:

```
dsplnk file1.obj object.lib
```

If you want to use a library that is not in the current directory, use the –l (lower-case L) linker option. The syntax for this option is **–l** *filename.* The *filename* is the name of an archive library; the space between –l and the filename is optional.

You can augment the linker's directory search algorithm by using the –i linker option or the environment variable. The linker searches for object libraries in the following order:

1) It searches directories named with the –i linker option.

2) It searches directories named with the environment variable C_DIR.

3) If C_DIR is not set, it searches directories named with the assembler's environment variable, A_DIR.

4) It searches the current directory.

–i Linker Options

The –i linker option names an alternate directory that contains object libraries. The syntax for this option is **–i** *dir. dir* names a directory that contains object libraries; the space between –i and the directory name is optional.

When the linker is searching for object libraries named with the –l option, it searches through directories named with –i first. Each –i option specifies only one directory, but you can use several –i options per invocation. When you use the –i option to name an alternate directory, it must precede the –l option on the command line or in a command file.

For example, assume that there are two archive libraries called r.lib and lib2.lib. The table below shows the directories that r.lib and lib2.lib reside in, how to set the environment variable, and how to use both libraries during a link. Select the row for your operating system:

	Pathname	Invocation Command
DOS	\ld and \ld2	dsplnk f1.obj f2.obj–i\ld –i\ld2 –lr.lib –llib2.lib
UNIX	\ld and \ld2	dsplnk f1.objf 2.obj–i/ld –i/ld2 –lr.lib –llib2.lib

Environment Variable (C_DIR)

An environment variable is a system symbol that you define and assign a string to. The linker uses an environment variable named *C_DIR* to name alternate directories that contain object libraries. The commands for assigning the environment variable are:

For DOS: `set`   `C_DIR=`*pathname;another pathname ...*

For UNIX: `setenv`   `C_DIR` "*pathname;another pathname ...* "

The *pathnames* are directories that contain object libraries. Use the –l option on the command line or in a command file to tell the linker which libraries to search for.

For example, assume that two archive libraries called r.lib and lib2.lib reside in different directories. The table below shows the directories that r.lib and lib2.lib reside in, how to set the environment variable, and how to use both libraries during a link. Select the row for your operating system:

	Pathname	**Invocation Command**
DOS	`\ld and \ld2`	`set    C_DIR=\ldir;\ldir2` `dsplnk f1.obj f2.obj –l r.lib –l lib2.lib`
UNIX	`\ld and \ld2`	`setenv C_DIR /ldir ;/ldir2` `dsplnk f1.obj f2.obj –l r.lib –l lib2.lib`

Note that the environment variable remains set until you reboot the system or reset the variable by entering:

For DOS: `set`   `C_DIR=`

For UNIX: `setenv`   `C_DIR / /`

The assembler uses an environment variable named A_DIR to name alternate directories that contain copy/include files or macro libraries. If C_DIR is not set, the linker will search for object libraries in the directories named with A_DIR. Section 8.5, page 8-19, contains more information about object libraries.

8.3.9 Create a Map File (–m *filename* Option)

The –m option creates a link map listing and puts it in *filename.* This map describes:

❑ Memory configuration
❑ Input and output section allocation
❑ The addresses of external symbols after they have been relocated

The map file contains the name of the output module and the entry point; it may also contain up to three tables:

❑ A table showing the new memory configuration if any nondefault memory is specified

❑ A table showing the linked addresses of each output section and the input sections that make up the output sections

❑ A table showing each external symbol and its address. This table has two columns: the left column contains the symbols sorted by name, and the right column contains the symbols sorted by address.

This example links file1.obj and file2.obj and creates a map file called map.out:

```
dsplnk file1.obj file2.obj –m map.out
```

Example 8–15, page 8-66, shows an example of a map file.

8.3.10 Name an Output Module (–o *filename* Option)

The linker creates an output module when no errors are encountered. If you do not specify a filename for the output module, the linker gives it the default name a.out. If you want to write the output module to a different file, use the –o option. The *filename* is the new output module name.

This example links file1.obj and file2.obj and creates an output module named run.out:

```
dsplnk –o run.out file1.obj file2.obj
```

8.3.11 Specify a Quiet Run (–q Option)

The –q option suppresses the linker's banner when –q is the first option on the command line or in a command file. This option is useful for batch operation.

8.3.12 Strip Symbolic Information (–s Option)

The –s option creates a smaller output module by omitting symbol table information and line number entries. The –s option is useful for production applications when you must create the smallest possible output module.

This example links file1.obj and file2.obj and creates an output module, stripped of line numbers and symbol table information, named nosym.out:

```
dsplnk –o nosym.out -s file1.obj file2.obj
```

Using the –s option limits later use of a symbolic debugger and may prevent a file from being relinked.

8.3.13 Define Stack Size (–stack *constant* Option)

The TMS320C2x/C2xx/C5x C compiler uses an uninitialized section, .stack, to allocate space for the runtime stack. You can set the size of the .stack section at link time with the –stack option. Specify the size as a constant immediately after the option:

```
dsplnk –stack 0x1000 /* defines a 4K stack (.stack section) */
```

If you specified a different stack size in an input section, the input section stack size is ignored. Any symbols defined in the input section remain valid; only the stack size will be different.

When the linker defines the .stack section, it also defines a global symbol, __STACK_SIZE, and assigns it a value equal to the size of the section. The default stack size is 1K words.

8.3.14 Introduce an Unresolved Symbol (–u *symbol* Option)

The –u option introduces an unresolved symbol into the linker's symbol table. This forces the linker to search a library and include the member that defines the symbol. The linker must encounter the –u option *before* it links in the member that defines the symbol.

For example, suppose a library named rts.lib contains a member that defines the symbol symtab; none of the object files being linked reference symtab. However, suppose you plan to relink the output module, and you would like to include the library member that defines symtab in this link. Using the –u option as shown below forces the linker to search rts.lib for the member that defines symtab and to link in the member.

```
dsplnk -u symtab file1.obj file2.obj rts.lib
```

If you do not use –u, this member is not included, because there is no explicit reference to it in file1.obj or file2.obj.

8.3.15 Generate Version 0 COFF format (–v0 Option)

By default, the linker generates an improved version of COFF (version 1) that supports more relocation entries. However, not all fixed-point debuggers have been updated to support the new COFF format. Use the –v0 option to generate the old COFF format if you are using any of the following (or earlier) versions of the debuggers:

Debugger Tool	Debugger Version
TMS320C2x Emulator	Version 6.40
TMS320C2x Simulator	Version 3.00
TMS320C5x (PG 1.x) Emulator	Version 6.50
TMS320C5x (PG 2.x) Emulator	Version 7.07
TMS320C5x Simulator	Version 1.20

8.3.16 Warning Switch (–w Option)

The –w option generates a warning message if an output section that is not explicitly specified with the SECTIONS directive is created. For example:

```
-[ fl.asm ]-

.sect "xsect"
.word 0

-[ link.cmd ]-

SECTIONS
{
    <no output section specifications reference xsect>
}
```

The linker creates an output section called xsect that consists of the input section xsect from other object files; the linker then uses the default allocation rules to allocate this output section into memory. If you used the –w switch when linking, the preceding example would generate the message:

```
>> warning: creating output section xsect without SECTIONS specification
```

8.3.17 Exhaustively Read Libraries (–x Option)

The linker normally reads input files, including archive libraries, only once: when they are encountered on the command line or in the command file. When an archive is read, any members that resolve references to undefined symbols are included in the link. If an input file later references a symbol defined in a previously read archive library (this is called a *back reference*), the reference will not be resolved.

With the –x option, you can force the linker to repeatedly reread all libraries. The linker will continue to reread libraries until no more references can be resolved. For example, if a.lib contains a reference to a symbol defined in b.lib, and b.lib contains a reference to a symbol defined in a.lib, you can resolve the mutual dependencies by listing one of the libraries twice, as in:

```
dsplnk –la.lib –lb.lib –la.lib
```

or you can force the linker to do it for you:

```
dsplnk –x –la.lib –lb.lib
```

Linking with the –x option may be slower, so you should use it only as needed.

8.4 Linker Command Files

Linker command files allow you to put linking information in a file; this is useful when you invoke the linker often with the same information. Linker command files are also useful because they allow you to use the MEMORY and SEC-TIONS directives to customize your application. You must use these directives in a command file; you cannot use them on the command line. Command files are ASCII files that contain one or more of the following:

❑ Input filenames, which specify object files, archive libraries, or other command files. (If a command file calls another command file as input, this statement must be the *last* statement in the calling command file. The linker does not return from called command files.)

❑ Linker options, which can be used in the command file in the same manner that they are used on the command line.

❑ The MEMORY and SECTIONS linker directives. The MEMORY directive defines the target memory configuration. The SECTIONS directive controls how sections are built and allocated.

❑ Assignment statements, which define and assign values to global symbols.

To invoke the linker with a command file, enter the **dsplnk** command and follow it with the name of the command file:

dsplnk *command_filename*

The linker processes input files in the order that it encounters them. If the linker recognizes a file as an object file, it links it. Otherwise, it assumes that a file is a command file and begins reading and processing commands from it. Command filenames are case sensitive, regardless of the system used.

Example 8–1 shows a sample linker command file called link.cmd.

Example 8–1.Linker Command File

```
a.obj              /*  First input filename        */
b.obj              /*  Second input filename       */
-o prog.out        /*  Option to specify output file */
-m prog.map        /*  Option to specify map file   */
```

The sample file in Example 8–1 contains only filenames and options. (You can place comments in a command file by delimiting them with /* and */.) To invoke the linker with this command file, enter:

```
dsplnk link.cmd
```

You can place other parameters on the command line when you use a command file:

```
dsplnk –r link.cmd c.obj d.obj
```

The linker processes the command file as soon as it encounters the filename, so a.obj and b.obj are linked into the output module before c.obj and d.obj.

You can specify multiple command files. If, for example, you have a file called names.lst that contains filenames and another file called dir.cmd that contains linker directives, you could enter:

```
dsplnk names.lst dir.cmd
```

One command file can call another command file; this type of nesting is limited to 16 levels. If a command file calls another command file as input, this statement must be the *last* statement in the calling command file.

Blanks and blank lines are insignificant in a command file, except as delimiters. This applies to the format of linker directives in a command file, also. Example 8–2 shows a sample command file that contains linker directives. (Linker directive formats are discussed in later sections.)

Example 8–2. Command File With Linker Directives

```
a.obj b.obj c.obj          /* Input filenames      */
-o prog.out -m prog.map     /* Options              */

MEMORY                      /* MEMORY directive     */
{
  RAM:   origin = 100h      length = 0100h
  ROM:   origin = 01000h    length = 0100h
}

SECTIONS                    /* SECTIONS directive   */
{
  .text:  > ROM
  .data:  > ROM
  .bss:   > RAM
}
```

The following names are reserved as keywords for linker directives. Do not use them as symbol or section names in a command file.

Example 8–3. Linker Command File

align	GROUP	origin
ALIGN	l (lowercase L)	ORIGIN
attr	len	page
ATTR	length	PAGE
block	LENGTH	range
BLOCK	load	run
COPY	LOAD	RUN
DSECT	MEMORY	SECTIONS
f	NOLOAD	spare
fill	o	type
FILL	org	TYPE
group		UNION

Constants in Command Files

Constants can be specified with either of two syntax schemes: the scheme used for specifying decimal, octal, or hexadecimal constants used in the assembler (see Section 3.7, page 3-17) or the scheme used for integer constants in C syntax.

Examples:

	Decimal	Octal	Hexadecimal
Assembler Format:	32	40q	20h
C Format:	32	040	0x20

8.5 Object Libraries

An object library is a partitioned archive file that contains complete object files as members. Usually, a group of related modules is grouped together into a library. When you specify an object library as linker input, the linker includes any library members that define existing unresolved symbol references. You can use the TMS320 archiver to build and maintain libraries. Chapter 7 contains more information about the archiver.

Using object libraries can reduce link time and the size of the executable module. Normally, if an object file that contains a function is specified at link time, it is linked whether it is used or not; however, if that same function is placed in an archive library, it is included only if it is referenced.

The order in which libraries are specified is important because the linker includes only those members that resolve symbols that are undefined when the library is searched. The same library can be specified as often as necessary; it is searched each time it is included. Alternatively, the –x option can be used (see subsection 8.3.17, page 8-15). A library has a table that lists all external symbols defined in the library; the linker searches through the table until it determines that it cannot use the library to resolve any more references.

The following example links several files and libraries. Assume that:

❏   Input files f1.obj and f2.obj both reference an external function named clrscr.

❏   Input file f1.obj references the symbol origin.

❏   Input file f2.obj references the symbol fillclr.

❏   Member 0 of library libc.lib contains a definition of origin.

❏   Member 3 of library liba.lib contains a definition of fillclr.

❏   Member 1 of both libraries defines clrscr.

If you enter

```
dsplnk f1.obj liba.lib f2.obj libc.lib
```

then:

❏   Member 1 of liba.lib satisfies both references to clrscr because the library is searched and clrscr is defined before f2.obj references it.

❏   Member 0 of libc.lib satisfies the reference to origin.

❏   Member 3 of liba.lib satisfies the reference to fillclr.

If, however, you enter

```
dsplnk f1.obj f2.obj libc.lib liba.lib
```

then the references to clrscr are satisfied by member 1 of libc.lib.

If none of the linked files reference symbols defined in a library, you can use the –u option to force the linker to include a library member. The next example creates an undefined symbol rout1 in the linker's global symbol table. If you enter:

```
dsplnk –u rout1 libc.lib
```

and if any members of libc.lib define rout1, the linker includes those members.

It is not possible to control the allocation of individual library members; members are allocated according to the SECTIONS directive default allocation algorithm.

Subsection 8.3.8, page 8-10, describes methods for specifying directories that contain object libraries.

8.6　The MEMORY Directive

The linker determines where output sections should be allocated into memory; it must have a model of target memory to accomplish this task. The MEMORY directive allows you to specify a model of target memory so that you can define the types of memory your system contains and the address ranges they occupy. The linker maintains the model as it allocates output sections and uses it to determine which memory locations can be used for object code.

The memory configurations of TMS320 systems differ from application to application. The MEMORY directive allows you to specify a variety of configurations. After you use MEMORY to define a memory model, you can use the SECTIONS directive to allocate output sections into defined memory.

Refer to Section 2.3, page 2-10, for details on how the linker handles sections. Refer to Section 2.4, page 2-18, for information on the relocation of sections.

8.6.1　Default Memory Model

The assembler enables you to assemble code for TMS320C1x, TMS320C2x, TMS320C2xx, or TMS320C5x devices (you can use the –v assembler option to identify the device; refer to page 3-5). The assembler inserts a field in the output file's header, identifying the device you selected. The linker reads this information from the object file's header. If you do not use the MEMORY directive, the linker uses a default memory model specific to the named device. For more information about the default memory model, refer to subsection 8.11.1, page 8-45.

8.6.2　MEMORY Directive Syntax

The MEMORY directive identifies ranges of memory that are physically present in the target system and can be used by a program. Each memory range has a *name*, a *starting address*, and a *length*.

TMS320 devices have separate memory spaces for program memory, data memory, and I/O memory; these spaces occupy the same address ranges. The linker allows you to configure these address spaces separately by using the MEMORY directive's PAGE option. PAGE 0 refers to program memory, and PAGE 1 refers to data memory. The linker treats these two pages as completely separate memory spaces.

When you use the MEMORY directive, be sure to identify all memory ranges that are available for loading code. Memory defined by the MEMORY directive is *configured*; any memory that you do not explicitly account for with MEMORY is *unconfigured*. The linker does not place any part of a program into unconfigured memory. You can represent nonexistent memory spaces by simply not including an address range in a MEMORY directive statement.

The MEMORY directive is specified in a command file by the word MEMORY (uppercase), followed by a list of memory range specifications enclosed in braces. The MEMORY directive in Example 8–4 defines a system that has 4K words of ROM at address 0h in program memory, 32 words of RAM at address 60h in data memory, and 512 words at address 200h in data memory. (Assume that you are running a TMS320C25 in microcomputer mode.)

Example 8–4.The MEMORY Directive

```
/**************************************************/
/*    Sample command file with MEMORY directive   */
/**************************************************/
file1.obj    file2.obj          /*    Input files    */
–o prog.out                      /*    Options        */

MEMORY
{
   PAGE 0: ROM:  origin = 0h    ,  length = 1000h
   PAGE 1: B2:   origin = 60h   ,  length = 20h
           B0B1: origin = 200h  ,  length = 200h
}
```

MEMORY directive → MEMORY

PAGE options

names — origins — lengths
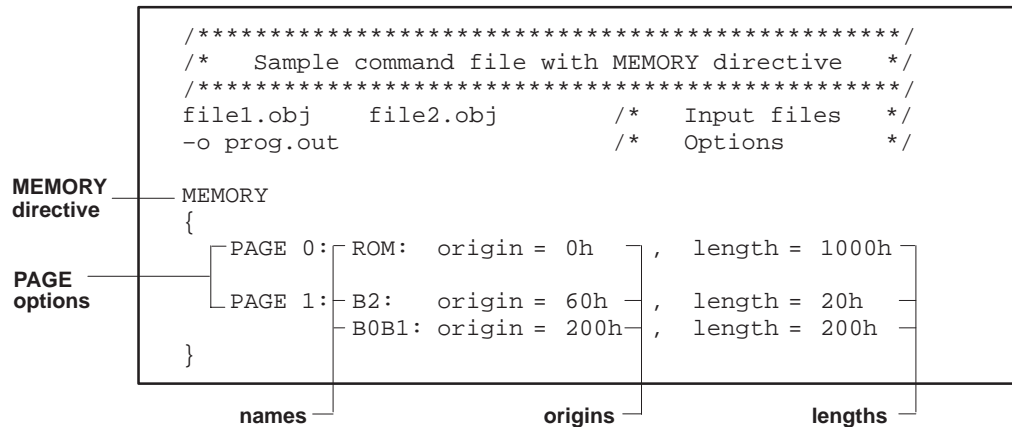
You could then use the SECTIONS directive to tell the linker where to link the sections. For example, you could allocate the .text and .data sections into the memory area named ROM and allocate the .bss section into B2 or B0B1.

The general syntax for the MEMORY directive is:

MEMORY
{
    PAGE 0 : *name 1* [*(attr)*] **:** **origin =** *constant*   **,length =** *constant;*
    PAGE *n* **:** *name n* [*(attr)*] **:** **origin =** *constant*   **,length =** *constant;*
}

PAGE   Identifies a memory space. You can specify up to 255 pages; usually, PAGE 0 specifies program memory, and PAGE 1 specifies data memory. If you do not use the PAGE option, the linker acts as if you specified PAGE 0. Each PAGE represents a completely independent address space. Configured memory on PAGE 0 can overlap configured memory on PAGE 1.

name   Names a memory range. A memory name may be one to eight characters; valid characters include A–Z, a–z, \$, ., and _. The names have no special significance to the linker; they simply identify memory ranges. Memory range names are internal to the linker and are not retained in the output file or in the symbol table. Memory ranges on separate pages can have the same name; within a page, however, all memory ranges must have unique names and must not overlap.

attr   Specifies one to four attributes associated with the named range. Attributes are optional; when used, they must be enclosed in parentheses. Attributes restrict the allocation of output sections into certain memory ranges. If you do not use any attributes, you can allocate any output section into any range with no restrictions. Any memory for which no attributes are specified (including all memory in the default model) has all four attributes. Valid attributes include:

         R   specifies that the memory can be read.
         W   specifies that the memory can be written to.
         X   specifies that the memory can contain executable code.
         I   specifies that the memory can be initialized.

origin   Specifies the starting address of a memory range; enter as *origin*, *org*, or *o*. The value, specified in bytes, is a 16-bit constant and may be decimal, octal, or hexadecimal.

length   Specifies the length of a memory range; enter as *length*, *len*, or *l*. The value, specified in bytes, is a 16-bit constant and may be decimal, octal, or hexadecimal.

Figure 8–2 illustrates the memory map defined by Example 8–4.

Figure 8–2. Defined in Example 8–4
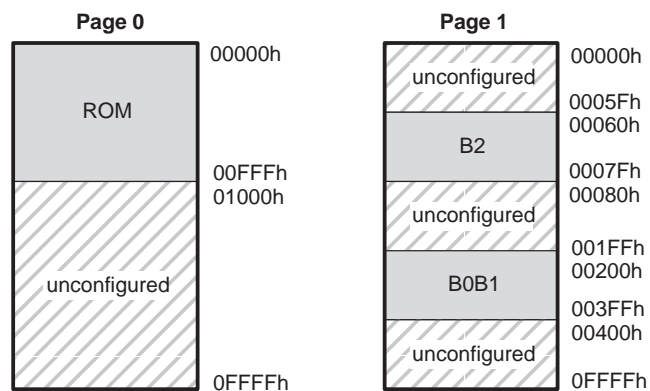
8.7   The SECTIONS Directive

The SECTIONS directive:

❏ Describes how input sections are combined into output sections

❏ Defines output sections in the executable program

❏ Specifies where output sections are placed in memory (in relation to each other and to the entire memory space)

❏ Permits renaming of output sections

Refer to Section 2.3, page 2-10, for details on how the linker handles sections. Refer to Section 2.4, page 2-18, for information on the relocation of sections.

8.7.1   Default Sections Configuration

If you do not specify a SECTIONS directive, the linker uses a default algorithm for combining and allocating the sections. Section 8.11, page 8-45, describes this algorithm in detail.

8.7.2   SECTIONS Directive Syntax

Note: Compatibility With Previous Versions

In previous versions of the linker, many of these constructs were specified differently. The linker accepts the older forms.

The SECTIONS directive is specified in a command file by the word SECTIONS (uppercase), followed by a list of output section specifications enclosed in braces.

The general syntax for the SECTIONS directive is:

```
SECTIONS
{
    name : [property, property, property,...]
    name : [property, property, property,...]
    name : [property, property, property,...]
}
```

Each section specification, beginning with *name*, defines an output section. (An output section is a section in the output file.) After the section *name* is a list of properties that define the section's contents and how it is allocated. The properties can be separated by commas. Possible properties for a section are:

❑ **Load allocation**, which defines where in memory the section is to be loaded

Syntax: **load =** *allocation*   **or**
allocation   **or**
 > *allocation*

❑ **Run allocation**, which defines where in memory the section is to be run

Syntax: **run =** *allocation*   **or**
run > *allocation*

❑ **Input sections**, which defines the input sections that constitute the output section

Syntax: { input_sections }

❑ **Section type**, which defines flags for special section types

Syntax: **type = COPY**   **or**
type = DSECT   **or**
type = NOLOAD

For more information on section types, see Section 8.12, page 8-49.

❑ **Fill value**, which defines the value used to fill uninitialized holes

Syntax: **fill =** *value*   **or**
name: ... { ... } **=** *value*

For more information on creating and filling holes, see Section 8.14, page 8-54.

Example 8–5 shows a SECTIONS directive in a sample linker command file. Figure 8–3 shows how these sections are allocated in memory.

Example 8–5.The SECTIONS Directive

```
/***********************************************/
/* Sample command file with SECTIONS directive */
/***********************************************/
file1.obj file2.obj          /* Input files  */
-o prog.out                  /* Options      */

SECTIONS
{
   .text:      load = ROM
   .const:     load = ROM run = 0800h
   .bss:       load = RAM,
   vectors:    load = 0h
        {
            t1.obj(.intvec1)
            t2.obj(.intvec2)
            endvec = .;
        }
   .data:      align = 16
}
```

SECTIONS directive — (points to SECTIONS line)

section specifications — (points to section entries)
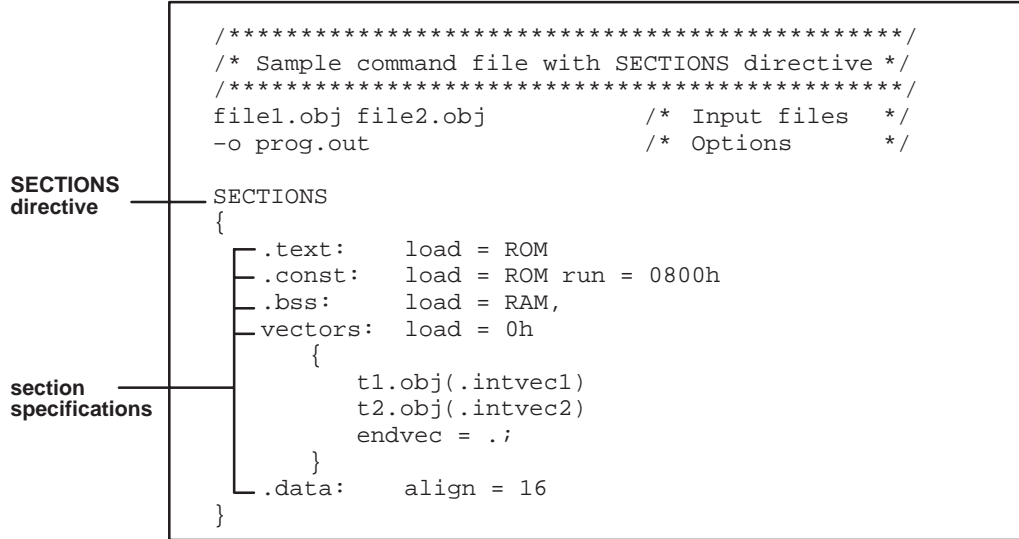
Figure 8–3 shows the five output sections defined by the SECTIONS directive in Example 8–5: .vectors, .text, .const, .bss, and .data.

Figure 8–3. Section Allocation Defined by Example 8–5

ROM

00h	.vectors — bound at 0
	.text — allocated in ROM
	.const — allocated in ROM

RAM

	.bss — allocated in RAM
	.data — aligned on 16-word boundary
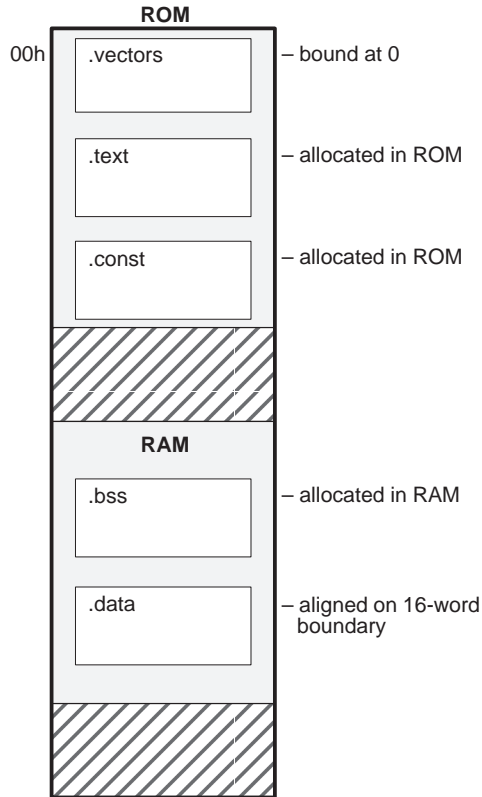
The **.vectors** section is composed of the .intvec1 section from t1.obj and the .intvec2 section from t2.obj.

The **.text** section combines the .text sections from file1.obj and file2.obj. The linker combines all sections named .text into this section. The application must relocate the section to run at 0800h.

The **.const** section combines the .const sections from file1.obj and file2.obj.

The **.bss** section combines the .bss sections from file1.obj and file2.obj.

The **.data** section combines the .data sections from file1.obj and file2.obj. The linker will place it anywhere there is space for it (in RAM in this illustration) and align it to a 16-word boundary.

8.7.3 Specifying the Address of Output Sections (Allocation)

The linker assigns each output section two locations in target memory: the location where the section will be loaded and the location where it will be run. Usually, these are the same, and you can think of each section as having only a single address. In any case, the process of locating the output section in the target's memory and assigning its address(es) is called allocation. For more information about using separate load and run allocation, see Section 8.8, page 8-33.

If you do not tell the linker how a section is to be allocated, it uses a default algorithm to allocate the section. Generally, the linker puts sections wherever they fit into configured memory. You can override this default allocation for a section by defining it within a SECTIONS directive and providing instructions on how to allocate it.

You control allocation by specifying one or more allocation parameters. Each parameter consists of a keyword, an equal sign or greater-than sign, and a value that can be enclosed in parentheses. If load and run allocation is separate, all parameters following the keyword load apply to load allocation, and those following the keyword run apply to run allocation. Possible allocation parameters are:

Binding   allocates a section at a specific address.

```
.text: load = 0x1000
```

Memory   allocates the section into a range defined in the MEMORY directive with the specified name (like ROM) or attributes.

```
.text: load > ROM
```

Alignment   uses the align keyword to specify that the section should start on an address boundary.

```
.text: align = 0x80
```

Blocking   uses the block keyword to specify that the section must fit between two address boundaries: if the section is too big, it will start on an address boundary.

```
.text: block(0x80)
```

Page   specifies the memory page to be used (see Section 8.10, page 8-40).

```
.text: PAGE 0
```

For the load (usually the only) allocation, you may simply use a greater-than sign and omit the load keyword:

```
.text: > ROM                 .text: {...} > ROM
.text: > 0x1000
```

If more than one parameter is used, you can string them together as follows:

```
.text: > ROM align 16 PAGE 2
```

Or, if you prefer, use parentheses for readability:

```
.text: load = (ROM align(16) PAGE (2))
```

Binding

You can supply a specific starting address for an output section by following the section name with an address:

```
.text: 0x1000
```

This example specifies that the .text section must begin at location 1000h. The binding address must be a 16-bit constant.

Output sections can be bound anywhere in configured memory (assuming there is enough space), but they cannot overlap. If there is not enough space to bind a section to a specified address, the linker issues an error message.

Note: Binding and Alignment or Named Memory Are Incompatible

You cannot bind a section to an address if you use alignment or named memory. If you try to do this, the linker issues an error message.

Named Memory

You can allocate a section into a memory range that is defined by the MEMORY directive. This example names ranges and links sections into them:

```
MEMORY
{
   ROM (RIX) : origin = 0h,     length = 1000h
   RAM (RWIX): origin = 3000h, length = 1000h
}
SECTIONS
{
   .text  :              > ROM
   .data ALIGN(128) :    > RAM
   .bss   :              > RAM
}
```

In this example, the linker places .text into the area called ROM. The .data and .bss output sections are allocated into RAM. You can align a section within a named memory range; the .data section is aligned on a 128-word boundary within the RAM range.

Similarly, you can link a section into an area of memory that has particular attributes. To do this, specify a set of attributes (enclosed in parentheses) instead of a memory name. Using the same MEMORY directive declaration, you can specify:

```
SECTIONS
{
   .text: > (X)   /* .text --> executable memory    */
   .data: > (RI)  /* .data --> read or init memory   */
   .bss : > (RW)  /* .bss --> read or write memory   */
}
```

In this example, the .text output section can be linked into either the ROM or RAM area because both areas have the X attribute. The .data section can also go into either ROM or RAM because both areas have the R and I attributes. The .bss output section, however, must go into the RAM area because only RAM is declared with the W attribute.

You cannot control where in a named memory range a section is allocated, although the linker uses lower memory addresses first and avoids fragmentation when possible. In the preceding examples, assuming that no conflicting assignments exist, the .text section would start at address 0. If a section must start on a specific address, use binding instead of named memory.

Alignment and Blocking

You can tell the linker to place an output section at an address that falls on an n-word boundary, where n is a power of 2. For example:

```
.text: load = align(128)
```

allocates .text so that it falls on a page boundary.

Blocking is a weaker form of alignment that allocates a section anywhere **within** a block of size n. If the section is larger than the block size, the section will begin on that boundary. As with alignment, n must be a power of 2. For example:

```
bss: load = block(0x80)
```

allocates .bss so that the section either is contained in a single 128K-word page or begins on a page.

You can use alignment or blocking alone or in conjunction with a memory area, but alignment and blocking cannot be used together.

8.7.4 Specifying Input Sections

An input section specification identifies the sections from input files that are combined to form an output section. The linker combines input sections by concatenating them in the order in which they are specified. The size of an output section is the sum of the sizes of the input sections that constitute it.

Example 8–6 shows the most common type of section specification; note that no input sections are listed.

Example 8–6. The Most Common Method of Specifying Section Contents

```
SECTIONS
{
    .text:
    .data:
    .bss:
}
```

In Example 8–6, the linker takes all the .text sections from the input files and combines them into the .text output section. The linker concatenates the .text input sections in the order that it encounters them in the input files. The linker performs similar operations with the .data and .bss sections. You can use this type of specification for any output section.

You can explicitly specify the input sections that form an output section. Each input section is identified by its filename and section name:

```
SECTIONS
{
    .text :                  /* Build .text output section      */
    {
     f1.obj(.text)      /* Link .text section from f1.obj   */
     f2.obj(sec1)       /* Link sec1 section from f2.obj    */
     f3.obj             /* Link ALL sections from f3.obj    */
     f4.obj(.text,sec2) /* Link .text and sec2 from f4.obj  */
    }
}
```

It is not necessary for input sections to have the same name as each other or as the output section they become part of. If a file is listed with no sections, *all* of its sections are included in the output section. If any additional input sections have the same name as an output section but are not explicitly specified by the SECTIONS directive, they are automatically linked in at the end of the output section. For example, if the linker found more .text sections in the preceding example, and these .text sections *were not* specified anywhere in the SECTIONS directive, the linker would concatenate these extra sections after f4.obj(sec2).

The specifications in Example 8–6 are actually a shorthand method for the following:

```
SECTIONS
{
    .text: { *(.text) }
    .data: { *(.data) }
    .bss:  { *(.bss)  }
}
```

The specification *(.text) means *the unallocated .text sections from all the input files.* This format is useful when:

❑ You want the output section to contain all input sections that have a specified name, but the output section name is different than the input sections' names.

❑ You want the linker to allocate the input sections *before* it processes additional input sections or commands within the braces.

The following example illustrates two purposes above:

```
SECTIONS
{
   .text  :  {
                   abc.obj(xqt)
                     *(.text)
           }
   .data  :  {
                   *(.data)
                   fil.obj(table)
             }
}
```

In this example, the .text output section contains a named section xqt from file abc.obj, which is followed by all the .text input sections. The .data section contains all the .data input sections, followed by a named section table from the file fil.obj. This method includes all the unallocated sections. For example, if one of the .text input sections was already included in another output section when the linker encountered *(.text), the linker could not include that first .text input section in the second output section.

8.8 Specifying a Section's Runtime Address

At times, you may want to load code into one area of memory and run it in another. For example, you may have performance-critical code in a ROM-based system. The code must be loaded into ROM, but it would run faster in RAM.

The linker provides a simple way to accomplish this. You can use the SECTIONS directive to direct the linker to allocate a section twice: once to set its load address and again to set its run address. For example:

```
.fir: load = ROM, run = RAM
```

Use the *load* keyword for the load address and the *run* keyword for the run address.

Refer to Section 2.5, page 2-20, for an overview on runtime relocation.

8.8.1 Specifying Load and Run Addresses

The load address determines where a loader will place the raw data for the section. All references to the section (such as labels in it) refer to its run address. The application must copy the section from its load address to its run address; this does *not* happen automatically when you specify a separate run address.

If you provide only one allocation (either load or run) for a section, the section is allocated only once and will load and run at the same address. If you provide both allocations, the section is allocated as if it were two sections of the same size. This means that both allocations occupy space in the memory map and cannot overlay each other or other sections. (The UNION directive provides a way to overlay sections; see subsection 8.9.1, page 8-37.)

If either the load or run address has additional parameters, such as alignment or blocking, list them after the appropriate keyword. Everything related to allocation after the keyword *load* affects the load address until the keyword *run* is seen, after which, everything affects the run address. The load and run allocations are completely independent, so any qualification of one (such as alignment) has no effect on the other. You may also specify run first, then load. Use parentheses to improve readability. The examples below specify load and run addresses:

```
.data: load = ROM, align = 32, run = RAM
```

(align applies only to load)

```
.data: load = (ROM align 32), run = RAM
```

(identical to previous example)

```
.data: run   =  RAM, align 32,
       load  =  align 16
```

(align 32 in RAM for run; align 16 anywhere for load)

8.8.2 Uninitialized Sections

Uninitialized sections (such as .bss) are not loaded, so their only significant address is the run address. The linker allocates uninitialized sections only once. If you specify both run and load addresses, the linker warns you and ignores the load address. Otherwise, if you specify only one address, the linker treats it as a run address, regardless of whether you call it load or run. The example below specifies load and run addresses for an uninitialized section:

```
.bss: load = 0x1000, run = RAM
```

A warning is issued, load is ignored, and space is allocated in RAM. All of the following examples have the same effect. The .bss section is allocated in RAM.

```
.bss: load = RAM
.bss: run = RAM
.bss: > RAM
```

8.8.3 Referring to the Load Address by Using the .label Directive

Normally, any reference to a symbol in a section refers to its runtime address. However, it may be necessary at runtime to refer to a load-time address. Specifically, the code that copies a section from its load address to its run address must have access to the load address. The .label directive defines a special symbol that refers to the section's load address. Thus, whereas normal symbols are relocated with respect to the run address, .label symbols are relocated with respect to the load address. For more information on the .label directive, see page 4-49.

Note: The .asect Directive Is Obsolete

Allowing separate allocation of run addresses in the linker makes the .asect directive obsolete. Any .asect section can be written as a normal section (with .sect) and given an *absolute* run address at link time. However, the .asect directive continues to work exactly as before and can still be used. Also, the .label directive in an .asect section works exactly as it did before: it defines a relocatable symbol. Now, however, .label can *also* be used in *any* section to define a relocatable symbol that refers to the load address.

Example 8–7. Copying a Section From ROM to RAM

```
;------------------------------------------------------
;  define a section to be copied from ROM to RAM
;------------------------------------------------------
          .sect  ".fir"
          .label fir_src      ; load address of section
fir:                          ; run address of section
          <code here>         ; code for the section

       .label fir_end         ; load address of section end

;------------------------------------------------------
;  copy .fir section from ROM into RAM
;------------------------------------------------------
       .text

       LARK   AR3,fir_src      ; get load address
       LACK   fir              ; get run address
       MAR    *,AR3
       RPTK   fir_end – fir_src – 1
       TBLW   *+               ; block copy

;------------------------------------------------------
;  jump to section, now in RAM
;------------------------------------------------------
       CALL   fir              ; call runtime address
```

Linker Command File

```
/****************************************************/
/* PARTIAL LINKER COMMAND FILE FOR FIR EXAMPLE      */
/****************************************************/
MEMORY
{
   PAGE 0 :  ONCHIP :  origin = 0800h,  length = 02400h
   PAGE 0 :  PROG   :  origin = 02C00h, length = 0D200h
   PAGE 1 :  DATA   :  origin = 0800h,  length = 0F800h
}

SECTIONS
{
   .text: load = PROG PAGE 0
   .fir:  load = DATA PAGE 1, run = ONCHIP PAGE 0
}
```

Figure 8–4 illustrates the runtime execution of this example.

Figure 8–4. Runtime Execution of Example 8–7
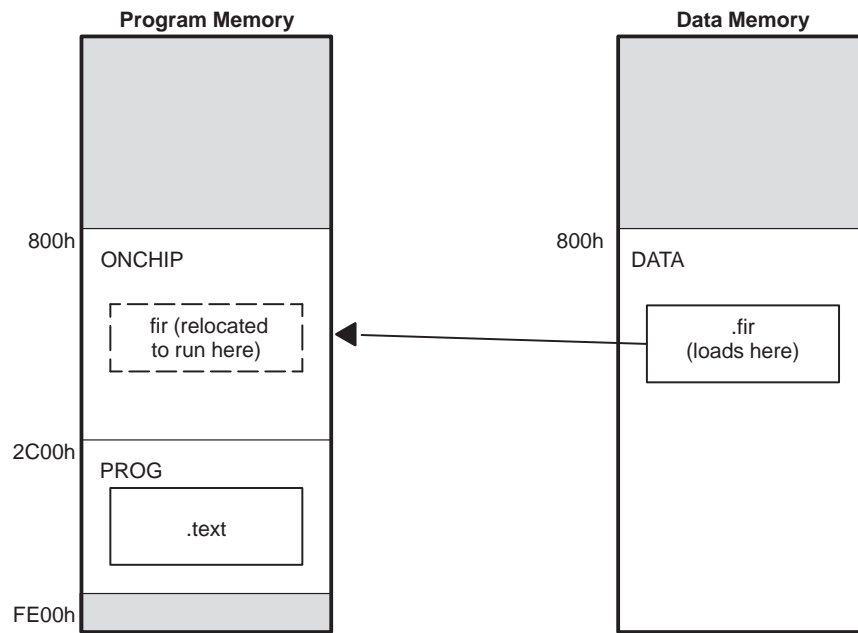
8.9 Using UNION and GROUP Statements

Two SECTIONS statements allow you to conserve memory: GROUP and UNION. Unioning sections causes the linker to allocate them to the same run address. Grouping sections causes the linker to allocate them contiguously in memory.

8.9.1 Overlaying Sections With the UNION Statement

For some applications, you may want to allocate more than one section to run at the same address. For example, you may have several routines you want in on-chip RAM at various stages of execution. Or you may want several data objects that will not be active at the same time to share a block of memory. The UNION statement within the SECTIONS directive provides a way to allocate several sections at the same run address.

Example 8–8. The UNION Statement

```
SECTIONS
{
    .text: load = ROM
    UNION: run = RAM
    {
        .bss1: { file1.obj(.bss) }
        .bss2: { file2.obj(.bss) }
    }
        .bss3: run = RAM { globals.obj(.bss) }
}
```

In Example 8–8, the .bss sections from file1.obj and file2.obj are allocated at the same address in RAM. In the memory map, the union occupies as much space as its largest component. The components of a union remain independent sections; they are simply allocated together as a unit.

Allocation of a section as part of a union affects only its *run address*. Under no circumstances can sections be overlaid for loading. If an initialized section is a union member (an initialized section has raw data, such as .text), its load allocation must be separately specified. For example:

Example 8–9. Separate Load Addresses for UNION Sections

```
UNION: run = RAM
{
    .text1: load = ROM, { file1.obj(.text) }
    .text2: load = ROM, { file2.obj(.text) }
}
```

Figure 8–5. Memory Allocation Defined by Example 8–8 and Example 8–9
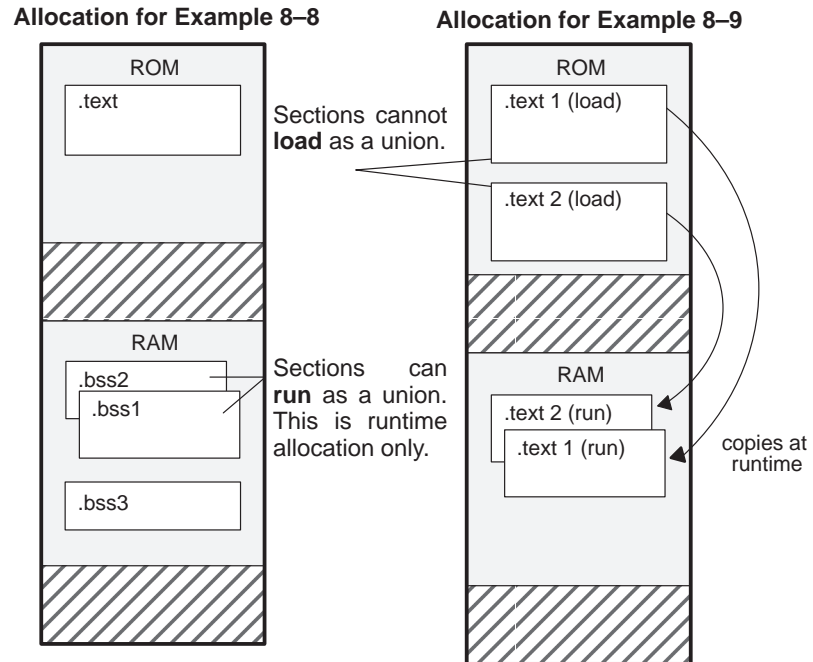
Since the .text sections contain data, they cannot *load* as a union, although they can be *run* as a union. Therefore, each requires its own load address. If you fail to provide a load allocation for an initialized section within a union, the linker issues a warning and allocates load space anywhere it fits in configured memory.

Uninitialized sections are not loaded and do not require load addresses.

The UNION statement applies only to allocation of run addresses, so it is redundant to specify a load address for the union itself. For purposes of alloca-tion, the union is treated as an uninitialized section: any one allocation speci-fied is considered a run address, and, if both are specified, the linker issues a warning and ignores the load address.

Note: Union and Overlay Page Are Not the Same

The UNION capability and the *overlay page* capability (see Section 8.10 on page 8-40) may sound similar because they both deal with overlays. They are, in fact, quite different. UNION allows multiple sections to be overlaid *within the same memory space*. Overlay page, on the other hand, defines *multiple memory spaces*. It is possible to use the page facility to approximate the function of UNION, but this is cumbersome.

8.9.2 Grouping Output Sections Together

The SECTIONS directive has a GROUP option that forces several output sections to be allocated contiguously. For example, assume that a section named *term_rec* contains a termination record for a table in the .data section. You can force the linker to allocate *.data* and *term_rec* together.

Example 8–10. Allocate Sections Together

```
SECTIONS
{
    .text           /* Normal output section          */
    .bss            /* Normal output section          */
    GROUP 1000h :   /* Specify a group of sections    */
    {
       .data        /* First section in the group     */
       term_rec     /* Allocated immediately after .data */
    }
}
```

You can use binding, alignment, or named memory to allocate a GROUP in the same manner as a single output section. In the preceding example, the GROUP is bound to address 1000h. This means that .data is allocated at 1000h, and *term_rec* follows it in memory.

You can also use the GROUP option to allocate output sections to a single run address but to separate load addresses. If you specify only a run address for a GROUP, then you must specify a load address for each member of the group that is an initialized section.

Example 8–11. Specify One Run Address and Separate Load Addresses

```
GROUP run = ONCHIP      /* All 3 sections grouped to run ONCHIP   */
{
  .text : load = ROM1   /* but .text loads in ROM1                */
  .data : load = ROM2   /* .data loads in ROM2                    */
  .bss                  /* .bss is uninitialized ==> doesn't load */
}
```

In this example, three output sections—.text, .data, and .bss—are grouped and are allocated to a run address in the memory range ONCHIP. The .text section is allocated to a load address in the memory range ROM1. The .data section is allocated to a load address in the memory range ROM2. The .bss section is an uninitialized section that is not loaded and therefore does not require a load address.

8.10 Overlay Pages

Some target systems use a memory configuration in which all or part of the memory space is overlaid by shadow memory. This allows the system to map different banks of physical memory into and out of a single address range in response to hardware selection signals. In other words, multiple banks of physical memory overlay each other at one address range. You may want the linker to load various output sections into each of these banks or into banks that are not mapped at loadtime.

The linker supports this feature by providing *overlay pages*. Each page represents an address range that must be configured separately with the MEMORY directive. You can then use the SECTIONS directive to specify the sections to be mapped into various pages.

8.10.1 Using the MEMORY Directive to Define Overlay Pages

To the linker, each overlay page represents a completely separate memory comprising the full 16-bit range of addressable locations. This allows you to link two or more sections at the same (or overlapping) addresses if they are on different pages.

Pages are numbered sequentially, beginning with 0. If you do not use the PAGE option, the linker allocates initialized sections into PAGE 0 (program memory) and uninitialized sections into PAGE 1 (data memory).

For example, assume that your system can select between two banks of physical memory for data memory space: address range A00h to FFFFh for PAGE 1 and 0A00h to 2BFF for PAGE 2. Although only one bank can be selected at a time, you can initialize each bank with different data. This is how you use the MEMORY directive to obtain this configuration:

Example 8–12. Memory Directive With Overlay Pages

```
MEMORY
{
    PAGE 0 : ONCHIP   : origin = 0800h,   length =   0240h
             PROG     : origin = 02C00h,  length =   0D200h
    PAGE 1 : OVR_MEM  : origin = 0A00h,   length =   02200h
           : DATA     : origin = 02C00h,  length =   0D400h
    PAGE 2 : OVR_MEM  : origin = 0A00h,   length =   02200h
}
```

Example 8–12 defines three separate address ranges. Page 0 defines an area of on-chip program memory and the rest of program memory space. Page 1 defines the first overlay memory area and the rest of data memory space. Page 2 defines another area of overlay memory for data space. Both OVR_MEM ranges cover the same address range. This is possible because each range is on a different page and therefore represents a different memory space.

Figure 8–6 shows overlay pages defined by the MEMORY directive in Example 8–12 and the SECTIONS directive in Example 8–13.

Figure 8–6. Overlay Pages Defined by Example 8–12 and Example 8–13
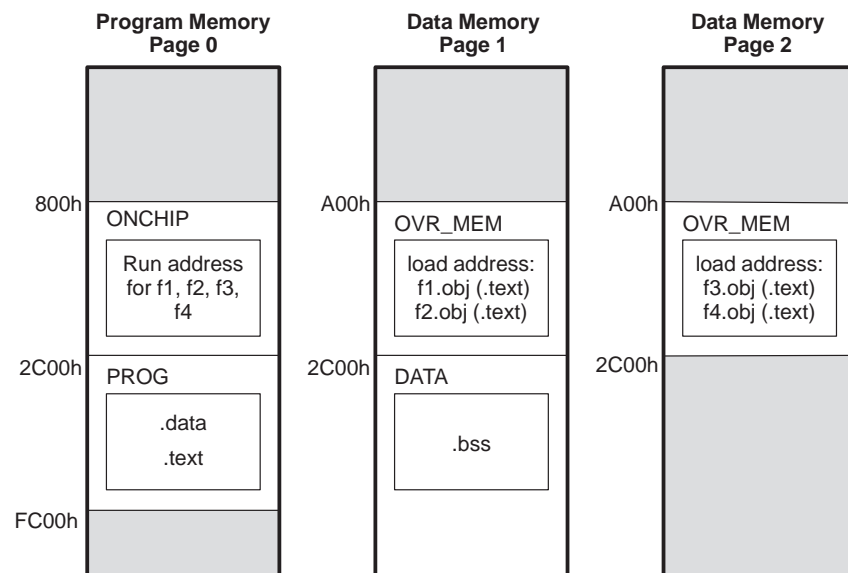
8.10.2 Using Overlay Pages With the SECTIONS Directive

Assume that you are using the MEMORY directive as shown in Example 8–12. Further assume that your code consists of, besides the usual sections, four modules of code that you want to load in data memory space but that you intend to run in the on-chip RAM in program memory space. Example 8–13 shows how to use the SECTIONS directive overlays accordingly.

Example 8–13. SECTIONS Directive Definition for Overlays in Figure 8–6

```
SECTIONS
{
   UNION :  run = ONCHIP
   {
      S1 :  load = OVR_MEM PAGE 1
      {
         s1_load = 0A00h;
         s1_start = .;
         f1.obj (.text)
         f2.obj (.text)
         s1_length = . – s1_start;
      }
      S2 :  load = OVR_MEM PAGE 2
      {
         s2_load = 0A00h;
         s2_start = .;
         f3.obj (.text)
         f4.obj (.text)
         s2_length = . – s2_start;
      }
   }

   .text: load = PROG PAGE 0
   .data: load = PROG PAGE 0
   .bss : load = DATA PAGE 1
}\
```

The four modules of code are f1, f2, f3, and f4. The modules f1 and f2 are combined into output section S1, and f3 and f4 are combined into output section S2. The PAGE specifications for S1 and S2 tell the linker to link these sections into the corresponding pages. As a result, they are both linked to load address A00h, but in different memory spaces. When the program is loaded, a loader can configure hardware so that each section is loaded into the appropriate memory bank.

Output sections S1 and S2 are placed in a union that has a run address in on-chip RAM. The application must move these sections at runtime before executing them. You can use the symbols s1_load and s1_length to move section S1, and s2_load and s2_length to move section S2. The special symbol "." refers to the current run address, not the current load address.

Within a page, you can bind output sections or use named memory areas in the usual way. In Example 8–13, S1 could have been allocated:

```
S1 : load = 01200h, PAGE = 1  { . . . }
```

This binds S1 at address 1200h in PAGE 1. You can also use page as a qualifier on the address. For example:

```
S1 : load = (01200h PAGE 1)  { . . . }
```

If you do not specify any binding or named memory range for the section, the linker allocates the section into the page wherever it can (just as it normally does with a single memory space). For example, S2 could also be specified as:

```
S2 : PAGE 2  { . . . }
```

Because OVR_MEM is the only memory on PAGE 2, it is not necessary (but it is acceptable) to specify = OVR_MEM for the section.

8.10.3 Page Definition Syntax

To specify overlay pages as illustrated in Example 8–12 and Example 8–13, use the following syntax for the MEMORY directive:

MEMORY
{
  PAGE 0 : *memory range*
            memory range

  PAGE *n* : *memory range*
            memory range
}

Each page is introduced by the keyword PAGE and a page number, followed by a colon and a list of memory ranges the page contains. **Bold** portions must be entered as shown. Memory ranges are specified in the normal way. You can define up to 255 overlay pages.

Because each page represents a completely independent address space, memory ranges on different pages can have the same name. Configured memory on any page can overlap configured memory on any other page. Within a single page, however, all memory ranges must have unique names and must not overlap.

Memory ranges listed outside the scope of a PAGE specification default to PAGE 0. Consider the following example:

```
MEMORY
{
            ROM   : org =   0h     len =   1000h
            EPROM : org =  1000h   len =   1000h
            RAM   : org =  2000h   len = 0E000h
   PAGE  1:  XROM  : org =   0h     len =   1000h
            XRAM  : org =  2000h   len = 0E000h
}
```

The memory ranges ROM, EPROM, and RAM are all on PAGE 0 (since no page is specified). XROM and XRAM are on PAGE 1. Note that XROM on PAGE 1 overlays ROM on PAGE 0, and XRAM on PAGE 1 overlays RAM on PAGE 0.

In the output link map (obtained with the –m linker option), the listing of the memory model is keyed by pages. This provides an easy method of verifying that you specified the memory model correctly. Also, the listing of output sections has a PAGE column that identifies the memory space into which each section will be loaded.

8.11 Default Allocation Algorithm

The MEMORY and SECTIONS directives provide flexible methods for building, combining, and allocating sections. However, any memory locations or sections that you choose *not* to specify must still be handled by the linker. The linker uses default algorithms to build and allocate sections within the specifications you supply. Subsections 8.11.1 and 8.11.2 describe default allocation algorithms.

8.11.1 Allocation Algorithm

If you do not use the MEMORY and SECTIONS directives, the linker allocates output sections as though the following definitions are specified.

❑ **Default allocation for TMS320C1x devices**

```
MEMORY
{
   PAGE 0: PROG: origin = 0x0600  length = 0x0A00
   PAGE 1: DATA: origin = 0x0000  length = 0x0080
}
SECTIONS
{
   .text:    PAGE = 0
   .data:    PAGE = 0
   .cinit:   PAGE = 0    /* For −c and −cr */
   .bss:     PAGE = 1
}
```

❑ **Default allocation for TMS320C2x devices**

```
MEMORY
{
   PAGE 0: PROG: origin = 0x0020  length = 0xFEE0
   PAGE 1: DATA: origin = 0x0300  length = 0xFD00
}
SECTIONS
{
   .text:    PAGE = 0
   .data:    PAGE = 0
   .cinit:   PAGE = 0    /* For −c and −cr */
   .bss:     PAGE = 1
}
```

❑ **Default allocation for the TMS320C25 device**

```
MEMORY
{
   PAGE 0: PROG: origin = 0x1000   length = 0xEF00
   PAGE 1: DATA: origin = 0x0300   length = 0xFD00
}
SECTIONS
{
   .text:     PAGE = 0
   .data:     PAGE = 0
   .cinit:    PAGE = 0    /* For −c and −cr */
   .bss:      PAGE = 1
}
```

❑ **Default allocation for the TMS320C2xx devices**

```
MEMORY
{
   PAGE 0: PROG: origin = 0x1000   length = 0xEFFF
   PAGE 1: DATA: origin = 0x0300   length = 0xFCFF
}
SECTIONS
{
   .text:     PAGE = 0
   .data:     PAGE = 0
   .cinit:    PAGE = 0    /* For −c and −cr */
   .bss:      PAGE = 1
}
```

❑ **Default allocation for TMS320C5x devices**

```
MEMORY
{
   PAGE 0: PROG: origin = 800h   length = 0F800h
   PAGE 1: DATA: origin = 800h   length = 0F800h
}
SECTIONS
{
   .text:     PAGE = 0
   .data:     PAGE = 0
   .cinit:    PAGE = 0    /* For −c and −cr */
   .bss:      PAGE = 1
}
```

All .text input sections are concatenated to form a .text output section in the executable output file, and all .data input sections are combined to form a .data output section. The .text and .data sections are allocated into configured memory on PAGE 0, which is the program memory space. All .bss sections are combined to form a .bss output section. The .bss section is allocated into configured memory on PAGE 1, which is the data memory space.

If the input files contain initialized named sections, the linker allocates them into program memory following the .data section. If the input files contain uninitialized named sections, the linker allocates them into data memory following the .bss section. You can override this by specifying an explicit PAGE in the SECTIONS directive.

If you use a SECTIONS directive, the linker performs no part of the default allocation. Allocation is performed according to the rules specified by the SECTIONS directive and the general algorithm described in subsection 8.11.2.

8.11.2 General Rules for Forming Output Sections

An output section can be formed in one of two ways:

Rule 1   As the result of a SECTIONS directive definition.

Rule 2   By combining input sections with the same names into an output section that is not defined in a SECTIONS directive.

If an output section is formed as a result of a SECTIONS directive (rule 1), this definition completely determines the section's contents. (See Section 8.7, page 8-24, for examples of how to define an output section's content.)

An output section can also be formed when input sections are specified by a SECTIONS directive (rule 2). In this case, the linker combines all such input sections that have the same name into an output section with that name. For example, suppose the files f1.obj and f2.obj both contain named sections called Vectors and that the SECTIONS directive does not define an output section for them. The linker combines the two Vectors sections from the input files into a single output section named Vectors, allocates it into memory, and includes it in the output file.

After the linker determines the composition of all output sections, it must allocate them into configured memory. The MEMORY directive specifies which portions of memory are configured; if no MEMORY directive is used, the linker uses the default configuration.

The linker's allocation algorithm attempts to minimize memory fragmentation. This allows memory to be used more efficiently and increases the probability that your program will fit into memory. This is the the algorithm:

1) Output sections for which you have supplied a specific binding address are placed in memory at that address.

2) Output sections that are included in a specific, named memory range or that have memory attribute restrictions are allocated. Each output section is placed into the first available space within the named area, considering alignment where necessary.

3) Any remaining sections are allocated in the order in which they are defined. Sections not defined in a SECTIONS directive are allocated in the order in which they are encountered. Each output section is placed into the first available memory space, considering alignment where necessary.

Note: The PAGE Option

If you do not use the PAGE option to explicitly specify a memory space for an output section, the linker allocates the section into PAGE 0. This occurs even if PAGE 0 has no room and other pages do. To use a page other than PAGE 0, you must specify the page with the SECTIONS directive.

8.12 Special Section Types (DSECT, COPY, and NOLOAD)

You can assign three special type designations to output sections: DSECT, COPY, and NOLOAD. These types affect the way that the program is treated when it is linked and loaded. You can assign a type to a section by placing the type (enclosed in parentheses) after the section definition. For example:

```
SECTIONS
{
    sec1 2000h    (DSECT)    : {f1.obj}
    sec2 4000h    (COPY)     : {f2.obj}
    sec3 6000h    (NOLOAD)   : {f3.obj}
}
```

❑ The DSECT type creates a dummy section with the following qualities:

■ It is not included in the output section memory allocation. It takes up no memory and is not included in the memory map listing.

■ It can overlay other output sections, other DSECTs, and unconfigured memory.

■ Global symbols defined in a dummy section are relocated normally. They appear in the output module's symbol table with the same value they would have if the DSECT had actually been loaded. These symbols can be referenced by other input sections.

■ Undefined external symbols found in a DSECT cause specified archive libraries to be searched.

■ The section's contents, relocation information, and line number information are not placed in the output module.

In the preceding example, none of the sections from f1.obj are allocated, but all the symbols are relocated as though the sections were linked at address 2000h. The other sections can refer to any of the global symbols in sec1.

❑ A COPY section is similar to a DSECT section, except that its contents and associated information are written to the output module. The .cinit section that contains initialization tables for the TMS320C2x/C2xx/C5x C compiler has this attribute under the RAM model.

❑ A NOLOAD section differs from a normal output section in one respect: the section's contents, relocation information, and line number information are not placed in the output module. The linker allocates space for it, and it appears in the memory map listing.

8.13 Assigning Symbols at Link Time

Linker assignment statements allow you to define external (global) symbols and assign values to them at link time. You can use this feature to initialize a variable or pointer to an allocation-dependent value.

8.13.1 Syntax of Assignment Statements

The syntax of assignment statements in the linker is similar to that of assignment statements in the C language:

symbol	**=**	*expression;*	assigns the value of expression to symbol
symbol	**+ =**	*expression;*	adds the value of expression to symbol
symbol	**− =**	*expression;*	subtracts the value of expression from symbol
symbol	*** =**	*expression;*	multiplies symbol by expression
symbol	**/ =**	*expression;*	divides symbol by expression

The symbol should be defined externally. If it is not, the linker defines a new symbol and enters it into the symbol table. The expression must follow the rules defined in subsection 8.13.3. Assignment statements *must* terminate with a semicolon.

The linker processes assignment statements *after* it allocates all the output sections. Therefore, if an expression contains a symbol, the address used for that symbol reflects the symbol's address in the executable output file.

For example, suppose a program reads data from one of two tables identified by two external symbols, Table1 and Table2. The program uses the symbol cur_tab as the address of the current table. cur_tab must point to either Table1 or Table2. You could accomplish this in the assembly code, but you would need to reassemble the program to change tables. Instead, you can use a linker assignment statement to assign cur_tab at link time:

```
prog.obj              /* Input file                        */
cur_tab = Table1;    /* Assign cur_tab to one of the tables */
```

8.13.2 Assigning the SPC to a Symbol

A special symbol, denoted by a dot (.), represents the current value of the SPC during allocation. The linker's "." symbol is analogous to the assembler's $ symbol. The "." symbol can be used only in assignment statements within a SECTIONS directive because "." is meaningful only during allocation, and SECTIONS controls the allocation process.

The "." symbol refers to the current run address, not the current load address, of the section.

For example, suppose a program needs to know the address of the beginning of the .data section. By using the .global directive, you can create an external undefined variable called Dstart in the program. Then assign the value of "." to Dstart:

```
SECTIONS
{
    .text:    {}
    .data:    { Dstart = .; }
    .bss:     {}
}
```

This defines Dstart to be the last linked address of the .data section. (Dstart is assigned *before* .data is allocated.) The linker will relocate all references to Dstart.

A special type of assignment assigns a value to the "." symbol. This adjusts the SPC within an output section and creates a hole between two input sections. Any value assigned to "." to create a hole is relative to the beginning of the section, not to the address actually represented by ".". Assignments to "." and holes are described in Section 8.14, page 8-54.

8.13.3 Assignment Expressions

These rules apply to linker expressions:

❏ Expressions can contain global symbols, constants, and the C language operators listed in Table 8–2.

❏ All numbers are treated as long (32-bit) integers.

❏ Constants are identified by the linker in the same way as by the assembler. That is, numbers are recognized as decimal unless they have a suffix (H or h for hexadecimal and Q or q for octal). C language prefixes are also recognized (0 for octal and 0x for hex). Hexadecimal constants must begin with a digit. No binary constants are allowed.

❏ Symbols within an expression have only the value of the symbol's *address.* No type-checking is performed.

❏ Linker expressions can be absolute or relocatable. If an expression contains *any* relocatable symbols (and zero or more constants or absolute symbols), it is relocatable. Otherwise, the expression is absolute. If a symbol is assigned the value of a relocatable expression, it is relocatable; if it is assigned the value of an absolute expression, it is absolute.

The linker supports the C language operators listed in Table 8–2 in order of precedence. Operators in the same group have the same precedence. Besides the operators listed in Table 8–2, the linker also has an *align* operator that allows a symbol to be aligned on an n-word boundary within an output section *(n* is a power of 2). For example, the expression

```
. = align(16);
```

aligns the SPC within the current section on the next 16-word boundary. Because the align operator is a function of the current SPC, it can be used only in the same context as "." —that is, within a SECTIONS directive.

Table 8–2. Operators in Assignment Expressions

Group 1 (Highest Precedence)		Group 6	
!	Logical not	&	Bitwise AND
~	Bitwise not		
–	Negative		
Group 2		**Group 7**	
*	Multiplication	|	Bitwise OR
/	Division		
%	Mod		
Group 3		**Group 8**	
+	Addition	&&	Logical AND
–	Minus		
Group 4		**Group 9**	
>>	Arithmetic right shift	||	Logical OR
<<	Arithmetic left shift		
Group 5		**Group 10 (Lowest Precedence)**	
==	Equal to	=	Assignment
! =	Not equal to	+ =	$A + = B \rightarrow A = A + B$
>	Greater than	– =	$A - = B \rightarrow A = A - B$
<	Less than	* =	$A * = B \rightarrow A = A * B$
< =	Less than or equal to	/ =	$A / = B \rightarrow A = A / B$
> =	Greater than or equal to		

8.13.4 Symbols Defined by the Linker

The linker automatically defines several symbols that a program can use at runtime to determine where a section is linked. These symbols are external, so they appear in the link map. They can be accessed in any assembly language module if they are declared with a .global directive. Values are assigned to these symbols as follows:

.text   is assigned the first address of the .text output section.
(It marks the *beginning* of executable code.)

etext   is assigned the first address following the .text output section.
(It marks the *end* of executable code.)

.data   is assigned the first address of the .data output section.
(It marks the *beginning* of initialized data tables.)

edata   is assigned the first address following the .data output section.
 (It marks the *end* of initialized data tables.)

.bss   is assigned the first address of the .bss output section.
(It marks the *beginning* of uninitialized data.)

end   is assigned the first address following the .bss output section.
(It marks the *end* of uninitialized data.)

Symbols Defined Only for C Support (–c or –cr option)

__STACK_SIZE   is assigned the size of the .stack section.

__MEMORY_SIZE   is assigned the size of the .sysmem section.

8.14 Creating and Filling Holes

The linker provides you with the ability to create areas *within output sections* that have nothing linked into them. These areas are called **holes**. In special cases, uninitialized sections can also be treated as holes. The following text describes how the linker handles holes and how you can fill holes (and uninitialized sections) with a value.

8.14.1 Initialized and Uninitialized Sections

There are two rules to remember about the contents of an output section. An output section contains either:

❑ Raw data for the *entire* section, or
❑ *No* raw data.

A section that has raw data is referred to as *initialized*. This means that the object file contains the actual memory image contents of the section. When the section is loaded, this image is loaded into memory at the section's specified starting address. The .text and .data sections *always* have raw data if anything was assembled into them. Named sections defined with the .sect and .asect assembler directives also have raw data.

By default, the .bss section and sections defined with the .usect directive have no raw data (they are *uninitialized*). They occupy space in the memory map but have no actual contents. Uninitialized sections typically reserve space in RAM for variables. In the object file, an uninitialized section has a normal section header and may have symbols defined in it; however, no memory image is stored in the section.

8.14.2 Creating Holes

You can create a hole in an initialized output section. A hole is created when you force the linker to leave extra space between input sections within an output section. When such a hole is created, *the linker must follow the first guideline above and supply raw data for the hole.*

Holes can be created only *within* output sections. Space can exist *between* output sections, but such space is not a hole. There is no way to fill or initialize the space between output sections.

To create a hole in an output section, you must use a special type of linker assignment statement within an output section definition. The assignment statement modifies the SPC (denoted by ".") by adding to it, assigning a greater value to it, or aligning it on an address boundary. The operators, expressions, and syntaxes of assignment statements are described in Section 8.13, page 8-50.

The following example uses assignment statements to create holes in output sections:

```
SECTIONS
{
   outsect:
   {
      file1.obj(.text)
      . += 100h;       /* Create a hole with size 100h   */
      file2.obj(.text)
      . = align(16);  /* Create a hole to align the SPC */
      file3.obj(.text)
   }
}
```

The output section outsect is built as follows:

❑ The .text section from file1.obj is linked in.

❑ The linker creates a 256-word hole.

❑ The .text section from file2.obj is linked in after the hole.

❑ The linker creates another hole by aligning the SPC on a 16-word boundary.

❑ Finally, the .text section from file3.obj is linked in.

All values assigned to the "." symbol within a section refer to the *relative address within the section.* The linker handles assignments to the "." symbol as if the section started at address 0 (even if you have specified a binding address). Consider the statement . = align(16) in the example. This statement effectively aligns file3.obj .text to start on a 16-word boundary within outsect. If outsect is ultimately allocated to start on an address that is not aligned, file3.obj .text will not be aligned either.

Note that the "." symbol refers to the current run address, not the current load address, of the section.

Expressions that decrement "." are illegal. For example, it is invalid to use the −= operator in an assignment to ".". The most common operators used in assignments to "." are += and align.

If an output section contains all input sections of a certain type (such as .text), you can use the following statements to create a hole at the beginning or end of the output section:

```
.text:  {  .+= 100h; }    /* Hole at the beginning */
.data:  {
           *(.data)
           . += 100h; }   /* Hole at the end         */
```

Another way to create a hole in an output section is to combine an uninitialized section with an initialized section to form a single output section. *In this case, the linker treats the uninitialized section as a hole and supplies data for it.* The following example illustrates this method:

```
SECTIONS
{
   outsect:
   {
   file1.obj(.text)
   file1.obj(.bss)           /* This becomes a hole */
   }
}
```

Because the .text section has raw data, all of outsect must also contain raw data (first guideline). Therefore, the uninitialized .bss section becomes a hole.

Uninitialized sections become holes only when they are combined with initialized sections. If several uninitialized sections are linked together, the resulting output section is also uninitialized.

8.14.3 Filling Holes

When a hole exists in an initialized output section, the linker must supply raw data to fill it. The linker fills holes with a 16-bit fill value that is replicated through memory until it fills the hole. The linker determines the fill value as follows:

1) If the hole is formed by combining an uninitialized section with an initialized section, you can specify a fill value for the uninitialized section. Follow the section name with an = and a 16-bit constant. For example:

```
SECTIONS
{
   outsect:
   {
      file1.obj(.text)
      file2.obj(.bss) = 0FFh     /* Fill this hole */
   }                             /* with 00FFh      */
}
```

2) You can also specify a fill value for all the holes in an output section by supplying the fill value after the section definition:

```
SECTIONS
{
   outsect:fill = 0FF00h /* fills holes with 0FF00h  */
   {
      . += 10h;              /* This creates a hole       */
      file1.obj(.text)
      file1.obj(.bss)    /* This creates another hole*/
   }
}
```

3) If you do not specify an initialization value for a hole, the linker fills the hole with the value specified with –f. For example, suppose the command file link.cmd contains the following SECTIONS directive:

```
SECTIONS
{
    .text: { .= 100; }        /* Create a 100-word hole */
}
```

Now invoke the linker with the –f option:

```
dsplnk -f 0FFFFh link.cmd
```

This fills the hole with 0FFFFh.

4) If you do not invoke the linker with the –f option, the linker fills holes with 0s.

Whenever a hole is created and filled in an initialized output section, the hole is identified in the link map along with the value the linker uses to fill it.

8.14.4 Explicit Initialization of Uninitialized Sections

An uninitialized section becomes a hole only when it is combined with an initialized section. When uninitialized sections are combined with each other, the resulting output section remains uninitialized.

However, you can force the linker to initialize an uninitialized section by specifying an explicit fill value for it in the SECTIONS directive. This causes the entire section to have raw data (the fill value). For example:

```
SECTIONS
{
    .bss: fill = 1234h       /* Fills .bss with 1234h */
}
```

Note: Filling Sections

Because filling a section (even with 0s) causes raw data to be generated for the entire section in the output file, your output file will be very large if you specify fill values for large sections or holes.

8.15 Partial (Incremental) Linking

An output file that has been linked can be linked again with additional modules. This is known as *partial linking,* or incremental linking. Partial linking allows you to partition large applications, link each part separately, and then link all the parts together to create the final executable program.

Follow these guidelines for producing a file that you will relink:

❏ Intermediate files must have relocation information. Use the –r option when you link the file the first time.

❏ Intermediate files must have symbolic information. By default, the linker retains symbolic information in its output. Do not use the –s option if you plan to relink a file, because –s strips symbolic information from the output module.

❏ Intermediate link steps should be concerned only with the formation of output sections and not with allocation. All allocation, binding, and MEMORY directives should be performed in the final link step.

❏ If the intermediate files have global symbols that have the same name as global symbols in other files and you wish them to be treated as static (visible only within the intermediate file), you must link the files with the –h option (See subsection 8.3.6 on page 8-9.)

❏ If you are linking C code, don't use –c or –cr until the final link step. Every time you invoke the linker with the –c or –cr option the linker will attempt to create an entry point.

The following example shows how you can use partial linking:

Step 1: Link the file file1.com; use the –r option to retain relocation information in the output file tempout1.out.

```
dsplnk –r –o tempout1 file1.com
```

file1.com contains:

```
SECTIONS
{
    ss1:   {
            f1.obj
            f2.obj
             .
             .
             .
            fn.obj
            }
}
```

Step 2: Link the file file2.com; use the –r option to retain relocation information in the output file tempout2.out.

```
dsplnk –r –o tempout2 file2.com
```

file2.com contains:

```
SECTIONS
{
    ss2:    {
            g1.obj
            g2.obj
              .
              .
              .
            gn.obj
            }
}
```

Step 3: Link tempout1.out and tempout2.out:

```
dsplnk –m final.map –o final.out tempout1.out tempout2.out
```

8.16 Linking C Code

The TMS320C2x/C2xx/C5x optimizing C compiler produces assembly language source code that can be assembled and linked. For example, a C program consisting of modules prog1, prog2, etc., can be assembled and then linked to produce an executable file called prog.out:

```
dsplnk –c –o prog.out prog1.obj prog2.obj ... rtsxx.lib
```

The –c option tells the linker to use special conventions that are defined by the C environment. The archive library rtsxx.lib, where xx is either 25, 2xx, or 50, contains C runtime support functions.

For more information about C, including the runtime environment and runtime support functions, see the *TMS320C2x/C2xx/C5x Optimizing C Compiler User's Guide.*

8.16.1 Runtime Initialization

All C programs must be linked with an object module called boot.obj. When a program begins running, it executes boot.obj first. boot.obj contains code and data for initializing the runtime environment. The module performs the following tasks:

❑ Sets up the system stack

❑ Processes the runtime initialization table and autoinitializes global variables (in the ROM model)

❑ Disables interrupts and calls _main

The runtime support object library, rtsxx.lib, contains boot.obj. You can:

❑ Use the archiver to extract boot.obj from the library and then link the module in directly.

❑ Include rtsxx.lib as an input file (the linker automatically extracts boot.obj when you use the –c or –cr option).

8.16.2 Object Libraries and Runtime Support

The *TMS320C2x/C2xx/C5x Optimizing C Compiler User's Guide* describes additional runtime support functions included in *rtsxx.lib*. If your program uses any of these functions, you must link *rtsxx.lib* with your object files.

You can also create your own object libraries and link them. The linker includes and links only those library members that resolve undefined references.

8.16.3 Setting the Size of the Heap and Stack Sections

C uses two uninitialized sections called .sysmem and .stack for the memory pool used by the malloc() functions and the runtime stack, respectively. You can set the size of these by using the –heap (subsection 8.3.7, page 8-9) or –stack (subsection 8.3.13, page 8-13) option and specifying the size of the section as a constant immediately after the option. The default size for both, if the options are not used, is 1K words.

8.16.4 Autoinitialization (ROM and RAM Models)

The C compiler produces tables of data for autoinitializing global variables. These are in a named section called *.cinit*. The initialization tables can be used in either of two ways:

❑ **RAM Model** (–cr option)

Variables are initialized at *load time.* This enhances performance by reducing boot time and by saving memory used by the initialization tables. You must use a smart loader (i.e. one capable of initializing variables) to take advantage of the RAM model of autoinitialization.

When you use –cr, the linker marks the .cinit section with a special attribute. This attribute tells the linker not to load the .cinit section into memory. The linker also sets the cinit symbol to –1; this tells the C boot routine that initialization tables are not present in memory. Therefore, no runtime initialization is performed at boot time.

When the program is loaded, the loader must be able to:

■ Detect the presence of the .cinit section in the object file

■ Detect the presence of the attribute that tells it not to copy the .cinit section

■ Understand the format of the initialization tables. (This format is described in the *TMS320C2x/C2xx/C5x Optimizing C Compiler User's Guide.)*

The loader then uses the initialization tables directly from the object file to initialize variables in .bss.

Figure 8–7 illustrates the RAM autoinitialization model.

Figure 8–7. RAM Model of Autoinitialization

Object File   **Memory**

.cinit → loader

.bss
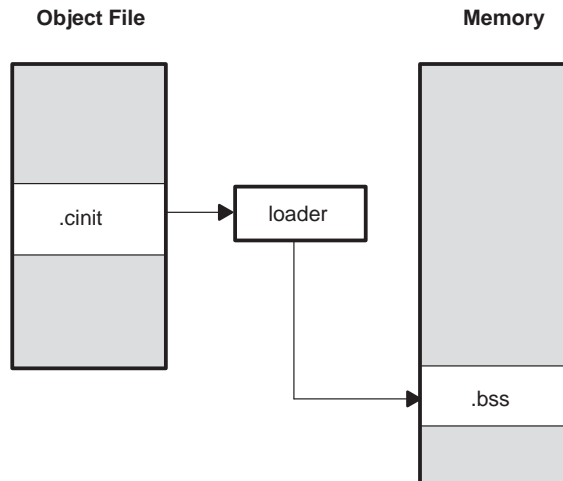
❑ **ROM Model** (–c option)

Variables are initialized at *runtime.* The .cinit section is loaded into memory along with all the other sections. The linker defines a special symbol called cinit that points to the beginning of the tables in memory. When the program begins running, the C boot routine copies data from the tables into the specified variables in the .bss section. This allows initialization data to be stored in ROM and then copied to RAM each time the program is started.

Figure 8–8 illustrates the ROM autoinitialization model.

Figure 8–8. ROM Model of Autoinitialization

Object File   **Memory**

.cinit → loader → initialization tables (possibly ROM) → boot routine → .bss
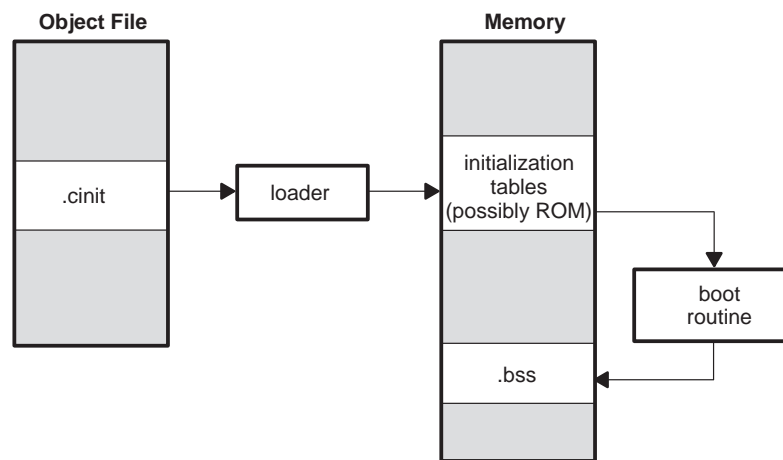
8.16.5 The –c and –cr Linker Options

The following list outlines what happens when you invoke the linker with the –c or –cr option.

❏ The symbol _c_int0 is defined as the program entry point. _c_int0 is the start of the C boot routine in boot.obj; referencing _c_int0 ensures that boot.obj is automatically linked in from the runtime support library rtsxx.lib.

❏ The .cinit output section is padded with a termination record to designate to the boot routine (ROM model) or the loader (RAM model) knows when to stop reading the initialization tables.

❏ In the ROM model (–c option), the linker defines the symbol cinit as the starting address of the .cinit section. The C boot routine uses this symbol as the starting point for autoinitialization.

❏ In the RAM model (–cr option):

■ The linker sets the symbol cinit to –1. This indicates that the initialization tables are not in memory, so no initialization is performed at run-time.

■ The STYP_COPY flag (010h) is set in the .cinit section header. STYP_COPY is the special attribute that tells the loader to perform autoinitialization directly and not to load the .cinit section into memory. The linker does not allocate space in memory for the .cinit section.

8.17 Linker Example

This example is for the TMS320C2x/C2xx/C5x C compiler. It links three object files named demo.obj, fft.obj, and tables.obj and creates a program called demo.out. The symbol SETUP is the program entry point.

Assume that target memory has the following configuration:

Program Memory

Address Range	**Contents**
0000 to 0FFF	On-chip ROM
FF00 to FFFF	On-chip RAM block B0

Data Memory

Address Range	**Contents**
0000 to 0005	I/O registers
0060 to 007F	On-chip RAM block B2
0300 to 03FF	On-chip RAM block B1

The output sections are constructed from the following input sections:

❑ A set of interrupt vectors from section int_vecs in the file tables.obj must be linked at address 0 in program ROM.

❑ Executable code, contained in the .text sections of demo.obj and fft.obj, must also be linked into program ROM.

❑ Two tables of coefficients in the .data sections of tables.obj and fft.obj must be linked into RAM block B0 in program memory. The remainder of block B0 must be initialized to the value 07A1Ch.

❑ The .bss section from fft.obj, which contains variables, must be linked into block B2 of data RAM.

❑ The .bss section from demo.obj, which contains buffers and variables, must be linked into block B1 of data RAM. The unused part of this RAM must be initialized to 0FFFFh.

Example 8–14 shows the linker command file for this example; Example 8–15 shows the map file.

Example 8–14. Linker Command File, demo.cmd

```
/**********************************************************************/
/****                 Specify Linker Options                    ****/
/**********************************************************************/

-e SETUP                   /*    Define the program entry point    */
-o demo.out                /*    Name the output file              */
-m demo.map                /*    Create an output map              */

/**********************************************************************/
/****                 Specify the Input Files                   ****/
/**********************************************************************/

demo.obj
fft.obj
tables.obj

/**********************************************************************/
/****             Specify the Memory Configuration              ****/
/**********************************************************************/

MEMORY
{
   PAGE 0: ROM:        origin = 00000h,      length = 01000h
           RAM_B0:     origin = 0FF00h,      length = 0100h
   PAGE 1: IO:         origin = 00000h,      length = 06h
           RAM_B2:     origin = 00060h,      length = 020h
           RAM_B1:     origin = 00300h,      length = 0100h
           RAM:        origin = 00400h,      length = 0FC00h
}
/**********************************************************************/
/****                 Specify the Output Sections               ****/
/**********************************************************************/
SECTIONS
{
   .text:load = ROM, page = 0         /* Link .text sections into ROM */

    int_vecs: load = 0, page = 0      /* Link interrupts at 0          */

    .data: fill = 07A1Ch, load = RAM_B0, page = 0
                                      /* Build .data section           */
   {
       tables.obj(.data)      /* .data input section                */
       fft.obj(.data)         /* .data input section                */
       . = 100h;              /* Create a hole to the end of block */
   }                          /* Fill with 7A1Ch and link into B0  */

   fftvars: load = RAM_B2, page = 1   /* Create new fftvars section   */
   {
       fft.obj(.bss)
   }                          /* Link into B2                      */

   .bss: load = RAM_B1, page = 1, fill = 0FFFFh
                             /* Remaining .bss; fill and link     */

}
/**********************************************************************/
/****                     End of Command File                   ****/
/**********************************************************************/
```

Invoke the linker with the following command:

```
dsplnk demo.cmd
```

This creates the map file shown in Example 8–15 and an output file called demo.out that can be run on a TMS320.

Example 8–15. Output Map File, demo.map

```
OUTPUT FILE NAME:    <demo.out>
ENTRY POINT SYMBOL: ″SETUP″  address:  00000020

MEMORY CONFIGURATION
          name                origin         length          attributes
          -------             --------       --------         ----------
PAGE 0:   ROM                 00000000       00001000         RWIX
          RAM_B0              0000FF00       000000100        RWIX

PAGE 1:   IO                  00000000       000000006        RWIX
          RAM_B2              00000060       000000020        RWIX
          RAM_B1              00000300       000000100        RWIX
          RAM                 00000400       00000FC00        RWIX

SECTION ALLOCATION MAP

output                                       attributes/
section   page   origin        length        input sections
-------   ----   ----------    -----------    ----------------
int_vecs  0      00000000      00000020
                 00000000        00000020     demo.obj (int_vecs)

.text     0      00000020      000001B2
                 00000020        0000014E     demo.obj (.text)
                 0000016E        00000064     fft.obj (.text)

fftvars   1      00000060      0000001A       UNINITIALIZED
                 00000060        0000001A     fft.obj (.bss)

.bss      1      00000300      0000009A
                 00000300        0000009A     demo.obj (.bss)[fill = ffff]
.data     0      0000FF00      00000100
                 0000FF00        000000A5     tables.obj (.data)
                 0000FFA5        00000014     fft.obj (.data)
                 0000FFB9        00000047     --HOLE-- [fill = 7A1C]

GLOBAL SYMBOLS
address        name                          address        name
---------      ----                          ---------      ----
00000020       SETUP                         00000020       SETUP
00010000       edata                         0000002A       start
0000039A       end                           0000006A       fft
000001D2       etext                         00000100    sub
00000300       extvar                        00000146       list
0000006A       fft                           00000150       p1asm
00000146       list                          0000015A       p2asm
00000164       main                          00000164    main
00000150       p1asm                         000001D2       etext
0000015A       p2asm                         00000300       extvar
0000002A       start                         0000039A       end
00000100       sub                           00010000       edata

[12 symbols]
```

Absolute Lister Description

The absolute lister is a debugging tool that accepts linked object files as input and creates .abs files as output. These .abs files can be assembled to produce a listing that shows the absolute addresses of object code. Manually, this could be a tedious process requiring many operations; however, the absolute lister utility performs these operations automatically.

Topics in this chapter include:

9.1 Producing an Absolute Listing

Figure 9–1 illustrates the steps required to produce an absolute listing.

Figure 9–1. Absolute Lister Development Flow
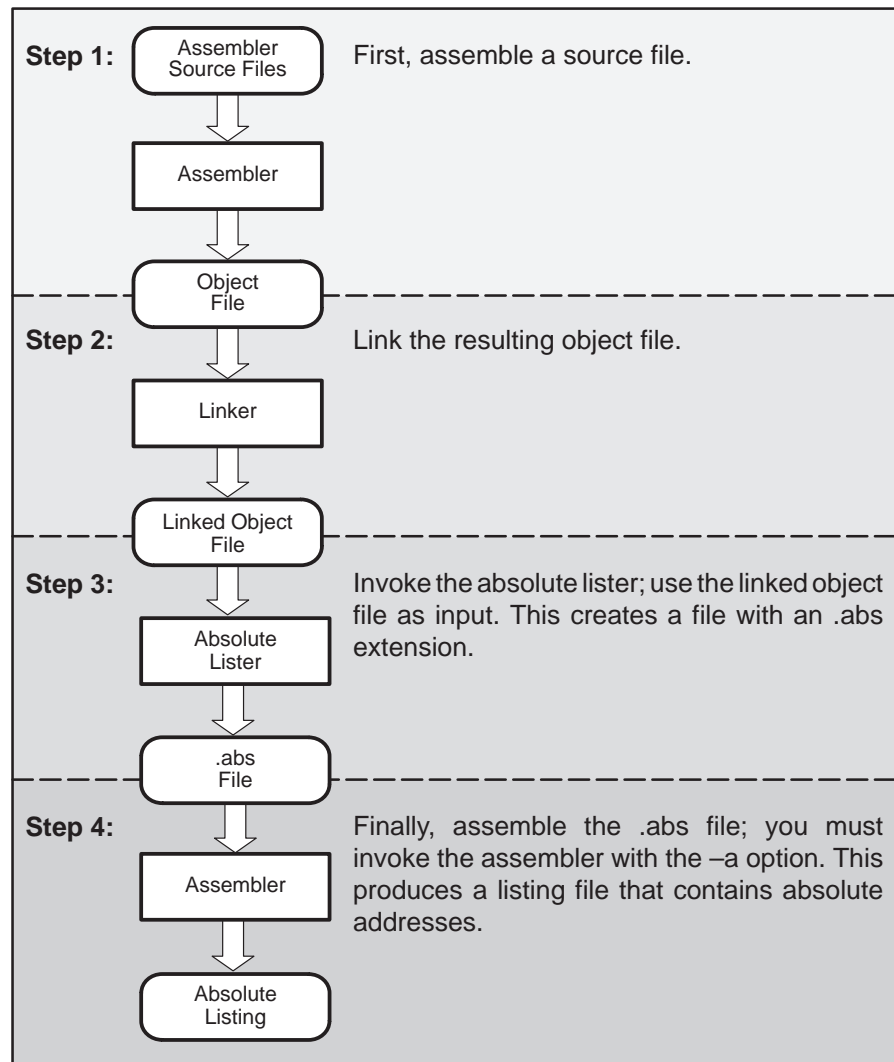
9.2   Invoking the Absolute Lister

To invoke the absolute lister, enter:

> **dspabs** [*–options*] *input file*

dspabs   is the command that invokes the absolute lister.

options   identifies the absolute lister options that you want to use. Options are not case‐sensitive and can appear anywhere on the command line following the command. Precede each option with a hyphen (–). The valid absolute lister options are as follows:

–e   enables you to change dspabs's default naming‐conventions for filename extensions on assembly files, C source files, and C header files. The three options are listed below.

❑ –ea [.]*asmext*   for assembly files (default is .asm)
❑ –ec [.]*cext*   for C source files (default is .c)
❑ –eh [.]*hext*   for C header files (default is .h)

The "." in the extensions and the space between the option and the extension are optional.

–q   (quiet) suppresses the banner and all progress information.

input file   names the linked object file. If you do not supply an extension, the absolute lister assumes that the input file has the default extension .out. If you do not supply an input filename when you invoke the absolute lister, the absolute lister will prompt you for one.

The absolute lister produces an output file for each file that was linked. These files are named with the input filenames and an extension of .abs. Header files, however, do not generate a corresponding .abs file.

Assemble these files with the –a assembler option as follows to create the absolute listing:

dspa -a *filename*.abs

The –e options affect both the interpretation of filenames on the command line and the names of the output files. They should always precede any filename on the command line.

The –e options are useful when the linked object file was created from C files compiled with the debug option. When the debug option is set, the resulting linked object file contains the name of the source files used to build it. In this case, the absolute lister will not generate a corresponding .abs file for the C header files. Also, the .abs file corresponding to a C source file will use the assembly file generated from the C source file rather than the C source file itself.

For example, suppose the C source file hello.csr is compiled with debug set; this generates the assembly file hello.s. hello.csr also includes hello.hsr. Assuming the executable file created is called hello.out, the following command will generate the proper .abs file:

```
dspabs –ea s –c csr –eh hsr hello.out
```

An .abs file will not be created for hello.hsr (the header file), and hello.abs will include the assembly file hello.s, not the C source file hello.csr.

9.3 Absolute Lister Example

This example uses three source files. module1.asm and module2.asm both include the file globals.def.

module1.asm

```
.reg   xflags,2
.reg   flags
.copy "globals.def"
.text
SBIT0 Gflag
```

module2.asm

```
copy   "globals.def"
.text
SBIT1 Gflag
```

globals.def

```
      .global  flags
Gflag .dbit    3,flags
```

The following steps create absolute listings for the files module1.asm and module2.asm:

Step 1: First, assemble module1.asm and module2.asm:

```
dspa module1
dspa module2
```

This creates two object files called module1.obj and module2.obj.

Step 2: Next, link module1.obj and module2.obj. using the following linker command file, called bittest.lnk:

```
/****************************************************/
/* File bittest.lnk -- COFF linker control file     */
/* for linking TMS320 modules                       */
/****************************************************/
-o BITTEST.OUT      /* executable output file       */
-m BITTEST.MAP      /* output map file              */

/* input files                                      */
MODULE1.OBJ
MODULE2.OBJ

/* define memory map                                */
MEMORY
{
   RFILE:       origin=0002h   length=00FEh
   EEPROM:      origin=1F00h   length=0100h
   ROM:         origin=7000h   length=1000h
}

/* define the output sections                       */
SECTIONS
{
   .reg:           >RFILE
   .data:          >EEPROM
   .text:          >ROM
}
```

Invoke the linker:

dsplnk bittest.lnk

This creates an executable object file called bittest.out; use this new file as input for the absolute lister.

Step 3: Now, invoke the absolute lister:

dspabs bittest.out

This creates two files called module1.abs and module2.abs:

module1.abs:

```
            .nolist
flags       .setsym        04h
.data       .setsym        1f00h
.edata      .setsym        1f00h
.text       .setsym        07000h
etext       .setsym        07006h
.bss        .setsym        00h
end         .setsym        00h
            .setsect       ".text",07000h
            .setsect       ".data",01f00h
            .setsect       ".bss",00h
            .setsect       ".reg",02h
            .list
            .text
            .copy     "module1.asm"
```

module2.abs:

```
            .nolist
flags       .setsym        04h
.data       .setsym        1f00h
.edata      .setsym        1f00h
.text       .setsym        07000h
etext       .setsym        07006h
.bss        .setsym        00h
end         .setsym        00h
            .setsect       ".text",07003h
            .setsect       ".data",01f00h
            .setsect       ".bss",00h
            .list
            .text
            .copy  "module2.asm"
```

These files contain the following information that the assembler needs when you invoke it in step 4:

❑ They contain .setsym directives, which equate values to global symbols. Both files contain global equates for the symbol *flags*. The symbol flags was defined in the file globals.def, which was included in module1.asm and module2.asm.

❑ They contain .setsect directives, which define the absolute addresses for sections.

❑ They contain .copy directives, which tell the assembler which assembly language source file to include.

The .setsym and .setsect directives are not useful in normal assembly; they are useful only for creating absolute listings.

Step 4: Finally, assemble the .abs files created by the absolute lister (remember that you must use the –a option when you invoke the assembler):

```
dspa  -a  module1.abs
dspa  -a  module2.abs
```

This creates two listing files called module1.lst and module2.lst. No object code is produced. These listing files are similar to normal listing files; however, the addresses shown are absolute addresses.

The absolute listing files created are:

module1.lst:

```
DSP Fixed Point COFF Assembler  Version X.XX        Wed Sep  7 16:35:25 1994
Copyright (c) 1987-1994  Texas Instruments Incorporated
                                                       PAGE    1
      14 7000                         .text
      15                              .copy    "module1.asm"
 A     1 0002                         .reg xflags,2
 A     2 0004                         .reg flags
 A     3                              .copy    "globals.def"
 B     1                              .globreg flags
 B     2       =04          Gflag     .dbit 3,flags
 A     4 7000                         .text
 A     5 7000  =73f704                SBIT0 Gflag

 No Errors,  No Warnings
```

module2.lst:

```
DSP Fixed Point COFF Assembler  Version 6.50        Wed Sep  7 16:35:25 1994
Copyright (c) 1987-1994  Texas Instruments Incorporated
                                                       PAGE    1

      13 7003                         .text
      14                              .copy    "module2.asm"
 A     1                              .copy    "globals.def"
 B     1                              .globreg flags
 B     2       ~04          Gflag     .dbit 3,flags
 A     2 7003                         .text
 A     3 7003  ~740804                SBIT1 Gflag

 No Errors,  No Warnings
```

Cross-Reference Lister

The cross-reference lister is a debugging tool. This utility accepts linked object files as input and produces a cross-reference listing as output. This listing shows symbols, their definitions, and their references in the linked source files.

Topics in this chapter include:

10.1 Producing a Cross-Reference Listing

Figure 10–1. Cross-Reference Lister Development Flow

Step 1: Assembler Source File — First, invoke the assembler with the –x option. This option produces a cross-reference table in the listing file and adds to the object file cross-reference information. By default, the assembler cross-references only global symbols. If you use the –s option when invoking the assembler, it will cross-reference local variables as well.

Assembler

Object File

Step 2: Link the object file (.obj) to obtain an executable object file (.out).

Linker

Linked Object File

Step 3: Invoke the cross-reference lister. The following section provides the command syntax for invoking the cross-reference lister utility.

Cross-Reference Lister

Cross-Reference Listing

10.2 Invoking the Cross-Reference Lister

To use the cross-reference utility, the file must be assembled with the correct options and then linked into an executable file. Assemble the assembly language files with the –x option. This option creates a cross-reference listing and adds cross-reference information to the object file. By default, the assembler cross-references only global symbols, but if assembler is invoked with the –s option, local symbols are also added. Link the object files to obtain an executable file.

To invoke the cross-reference lister, enter the following:

> **dspxref** [–*options*] [*input filename* [*output filename*]]

dspxref	is the command that invokes the cross-reference utility.
options	identifies the cross-reference lister options you want to use. Options are not case-sensitive and can appear anywhere on the command line following the command. Precede each option with a hyphen (–). The cross-reference lister options are as follows:

      –l   (lowercase L) specifies the number of lines per page for the output file. The format of the –l option is –lnum, where num is a decimal constant. For example, –l30 sets the number of lines per page in the output file to 30. The space between the option and the decimal constant is optional. The default is 60 lines per page.

      –q   (quiet) suppresses the banner and all progress information.

input filename	is a linked object file. If you omit the input filename, the utility prompts for a filename.
output filename	is the name of the cross-reference listing file. If you omit the output filename, the default filename will be the input filename with an .xrf extension.

10.3 Cross-Reference Listing Example

```
================================================================================

Symbol: done

Filename          RTYP    AsmVal     LnkVal      DefLn    RefLn     RefLn     RefLn
_____          ____    _____     _____      _____    _____     _____     _____
x.asm             STAT    '000c      380c         18       14

================================================================================

Symbol: f1

Filename          RTYP    AsmVal     LnkVal      DefLn    RefLn     RefLn     RefLn
_____          ____    _____     _____      _____    _____     _____     _____
x.asm             STAT    3.45e+00   3.45e+00      4

================================================================================

Symbol: g3

Filename          RTYP    AsmVal     LnkVal      DefLn    RefLn     RefLn     RefLn
_____          ____    _____     _____      _____    _____     _____     _____
x.asm             EDEF    ffff       ffff          3        9
y.asm             EREF    0000       ffff                   3         6

================================================================================

Symbol: start

Filename          RTYP    AsmVal     LnkVal      DefLn    RefLn     RefLn     RefLn
_____          ____    _____     _____      _____    _____     _____     _____
x.asm             STAT    '0000      3800         12       17

================================================================================

Symbol: table

Filename          RTYP    AsmVal     LnkVal      DefLn    RefLn     RefLn     RefLn
_____          ____    _____     _____      _____    _____     _____     _____
x.asm             STAT    -1000      3000         21       13

================================================================================

Symbol: y

Filename          RTYP    AsmVal     LnkVal      DefLn    RefLn     RefLn     RefLn
_____          ____    _____     _____      _____    _____     _____     _____
x.asm             EREF    0000       380d                   7        10
y.asm             EDEF    '0000      380d          5        1

================================================================================
```

The terms defined below appear in the preceding cross-reference listing:

Symbol Name   Name of the symbol listed

Filename   Name of the file where the symbol appears

RTYP   The symbol's reference type in this file. The possible reference types are:

> **STAT**   The symbol is defined in this file and is not declared as global.
>
> **EDEF**   The symbol is defined in this file and is declared as global.
>
> **EREF**   The symbol is not defined in this file but is referenced as a global.
>
> **UNDF**   The symbol is not defined in this file and is not declared as global.

AsmVal   This hexadecimal number is the value assigned to the symbol at assembly time. A value may also be preceded by a character that describes the symbol's attributes. Table 10–1 lists these characters and names.

LnkVal   This hexadecimal number is the value assigned to the symbol after linking.

DefLn   The statement number where the symbol is defined.

RefLn   The line number where the symbol is referenced. If the line number is followed by an asterisk(*), then that reference may modify the contents of the object. A blank in this column indicates that the symbol was never used.

Table 10–1. Symbol Attributes

Character	Meaning
'	Symbol defined in a .text section
"	Symbol defined in a .data section
+	Symbol defined in a .sect section
–	Symbol defined in a .bss or .usect section
=	Symbol defined in a .reg section

Hex Conversion Utility Description

The TMS320C1x/C2x/C2xx/C5x assembler and linker create object files that are in common object file format (COFF). COFF is a binary object file format that encourages modular programming and provides more powerful and flexible methods for managing code segments and target system memory.

Most EPROM programmers do not accept COFF object files as input. The hex conversion utility converts a COFF object file into one of several standard ASCII hexadecimal formats, suitable for loading into an EPROM programmer. The utility is also useful in other applications requiring hexadecimal conversion of a COFF object file (for example, when using debuggers and loaders). This utility also supports the on-chip boot loader built into the target device, automating the code creation process for the 'C26 and 'C5x.

The hex conversion utility can produce these output file formats:

❑ ASCII-Hex, supporting 16-bit addresses
❑ Extended Tektronix (Tektronix)
❑ Intel MCS-86 (Intel)
❑ Motorola Exorciser (Motorola-S), supporting 16-bit addresses
❑ Texas Instruments SDSMAC (TI-Tagged), supporting 16-bit addresses

11.1 Hex Conversion Utility Development Flow

Figure 11–1 highlights the role of the hex conversion utility in the assembly language development process.

Figure 11–1. Hex Conversion Utility Development Flow
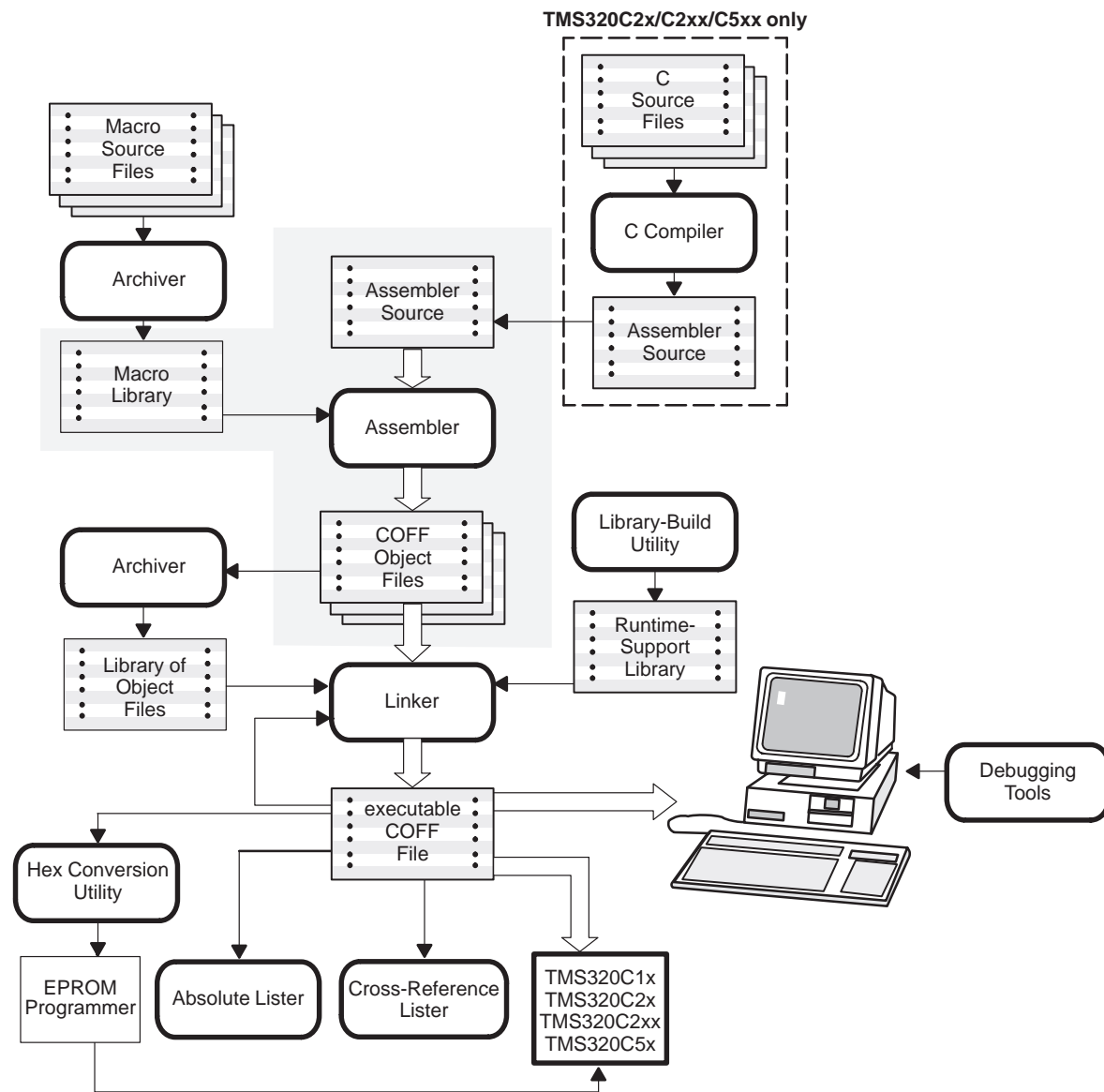
11.2 Invoking the Hex Conversion Utility

There are two basic methods for invoking the hex conversion utility:

❏ **Specify the options and filenames on the command line.** The following
example converts the file firmware.out into TI-Tagged format, producing
two output files, firm.lsb and firm.msb.

```
dsphex –t firmware –o firm.lsb –o firm.msb
```

❏ **Specify the options and filenames in a command file.** You can create
a batch file that stores command line options and filenames for invoking
the hex conversion utility. The following example invokes the utility using
a command file called hexutil.cmd:

```
dsphex hexutil.cmd
```

In addition to regular command line information, you can use the hex
conversion utility ROMS and SECTIONS directives in a command file.

Invoking the Hex Conversion Utility From the Command Line

To invoke the hex conversion utility, enter:

dsphex [–*options*] *filename*

dsphex   is the command that invokes the hex conversion utility.

–*options*   supply additional information that controls the hex conversion
process. You can use options on the command line or in a com-
mand file.

❏ All options are preceded by a dash and are not case-sensi-
tive.

❏ Several options have an additional parameter that must be
separated from the option by at least one space.

❏ Options with multicharacter names must be spelled exactly
as shown in this document; no abbreviations are allowed.

❏ Options are not affected by the order in which they are used.
The exception to this rule is the –q option, which must be
used before any other options.

Table 11–1 lists basic options. Table 11–2, page 11-27, lists
options that apply only to the 'C26 and 'C5x on-chip boot loaders.
The boot loaders are discussed in Section 11.9, page 11-26.

filename   names a COFF object file or a command file (for more informa-
tion on command files, see Section 11.3, page 11-5).

Table 11–1. Basic Options

General Options	Option	Description	Page
Control the overall operation of the hex conversion utility.	–byte	Number bytes sequentially	11-36
	–map *filename*	Generate a map file	11-19
	–o *filename*	Specify an output filename	11-22
	–q	Run quietly (when used, it must appear *before* other options)	11-5
Image Options	**Option**	**Description**	**Page**
Allow you to create a continuous image of a range of target memory.	–fill *value*	Fill holes with *value*	11-25
	–image	Specify image mode	11-24
	–zero	Reset the address origin to zero	11-35
Memory Options	**Option**	**Description**	**Page**
Allow you to configure the memory widths for your output files.	–memwidth *value*	Define the system memory word width (default 16 bits)	11-8
	–order {LS | MS}	Specify the memory word ordering	11-12
	–romwidth *value*	Specify the ROM device width (default depends on format used)	11-9
Output Formats	**Option**	**Description**	**Page**
Allow you to specify the output format.	–a	Select ASCII-Hex	11-39
	–i	Select Intel	11-40
	–m	Select Motorola-S	11-41
	–t	Select TI-Tagged	11-42
	–x	Select Tektronix	11-43

11.3 Command Files

A command file is useful if you plan to invoke the utility more than once with the same input files and options. It is also useful if you want to use the ROMS and SECTIONS hex conversion utility directives to customize the conversion process.

Command files are ASCII files that contain one or more of the following:

❑ **Options and filenames.** These are specified in a command file in exactly the same manner as on the command line.

❑ **ROMS directive.** The ROMS directive defines the physical memory configuration of your system as a list of address-range parameters. (For more information about the ROMS directive, see Section 11.5, page 11-14.)

❑ **SECTIONS directive.** The SECTIONS directive specifies which sections from the COFF object file should be selected. (For more information about the SECTIONS directive, see Section 11.6, page 11-20.) You can also use this directive to identify specific sections that will be initialized by an on-chip boot loader. (For more information on the on-chip boot loader, see Section 11.9, page 11-26.)

❑ **Comments.** You can add comments to your command file by using the /* and */ delimiters. For example:

```
/*   This is a comment   */
```

To invoke the utility and use the options you defined in a command file, enter:

dsphex *command_filename*

You can also specify other options and files on the command line. For example, you could invoke the utility by using both a command file and command line options:

```
dsphex firmware.cmd –map firmware.mxp
```

The order in which these options and file names appear is not important. The utility reads all input from the command line and all information from the command file before starting the conversion process. However, if you are using the –q option, *it must appear as the first option on the command line or in a command file.*

The **–q option** suppresses the utility's normal banner and progress information.

Examples of Command Files

❏ Assume that a command file named firmware.cmd contains these lines:

```
firmware.out    /* input file   */
-t              /* TI-Tagged    */
-o   firm.lsb  /* output file */
-o   firm.msb  /* output file */
```

You can invoke the hex conversion utility by entering:

```
dsphex firmware.cmd
```

❏ This example converts a file called appl.out into four hex files in Intel for-
mat. Each output file is one byte wide and 16K bytes long. The .text section
is converted to boot loader format.

```
appl.out          /* input file   */
-i                /* Intel format */
-map appl.mxp     /* map file     */

ROMS
{
   ROW1: origin=01000h len=04000h romwidth=8
         files={ appl.u0 appl.u1 }
   ROW2: origin 05000h len=04000h romwidth=8
         files={ app1.u2 appl.u3 }
}

SECTIONS
{   .text: BOOT
    .data, .cinit, .sect1, .vectors, .const:
}
```

11.4 Understanding Memory Widths

The hex conversion utility makes your memory architecture more flexible by allowing you to specify memory and ROM widths. In order to use the hex conversion utility, **you must understand how the utility treats word widths**. Four widths are important in the conversion process: target width, data width, memory width, and ROM width. The terms target word, data word, memory word and ROM word, refer to a word of such a width.

Figure 11–2 illustrates the three separate and distinct phases of the hex conversion utility's process flow.

Figure 11–2. Hex Conversion Utility Process Flow

Raw data in COFF files is represented in target-width-sized words. For the 'C1x/2x/2xx/5x this is 16 bits. The target width is fixed and cannot be changed.

COFF Input File

Phase I
The raw data in the COFF file is truncated to the size specified by the default data width (16 bits).

Phase II
The data-width-sized internal representation is divided into words according to size specified by the –memwidth option.

Phase III
The memwidth-sized words are broken up according to the size specified by the –romwidth option and are written to a file(s) according to the specified format (i.e. Intel, Tektronix, etc..).

Output File(s)

11.4.1 Target Width

Target width is the unit size (in bits) of raw data fields in the COFF file. This corresponds to the size of an opcode on the target processor. The width is fixed for each target and cannot be changed. The TMS320C1x, TMS320C2x, TMS320C2xx, and TMS320C5x targets have a width of 16 bits.

11.4.2 Data Width

Data width is the logical width (in bits) of the data words stored in a particular section of a COFF file. Usually, the logical data width is the same as the target width. The data width is fixed at 16 bits for the TMS320C1x/2x/2xx/5x and cannot be changed.

11.4.3 Memory Width

Memory width is the physical width (in bits) of the memory system. Usually, the memory system is physically the same width as the target processor width: a 16-bit processor has a 16-bit memory architecture. However, some applications, such as boot loaders, require target words to be broken up into multiple, consecutive, narrower memory words. Moreover, with certain processors like the 'C5x, the memory width can be narrower than the target width.

The hex conversion utility defaults memory width to the target width (in this case, 16 bits).

You can change the memory width by:

❑ Using the **–memwidth** option. This changes the memory width value for the entire file.

❑ Setting the **memwidth** parameter of the ROMS directive. This changes the memory width value for the address range specified in the ROMS directive and overrides the –memwidth option for that range. See Section 11.5, page 11-14.

For both methods, use a *value* that is a power of 2 greater than or equal to 8.

You should change the memory width default value of 16 only in exceptional situations: for example, when you need to break single target words into consecutive, narrower memory words. Situations in which memory words are narrower than target words are most common when you use on-chip boot loaders—several of which support booting from narrower memory. For example, a 16-bit TMS320C5x can be booted from 8-bit memory or an 8-bit serial port, with each 16-bit value occupying two memory locations (this would be specified as –memwidth 8).

Figure 11−3 demonstrates how the memory width is related to the data width.

Figure 11−3. Data and Memory Widths
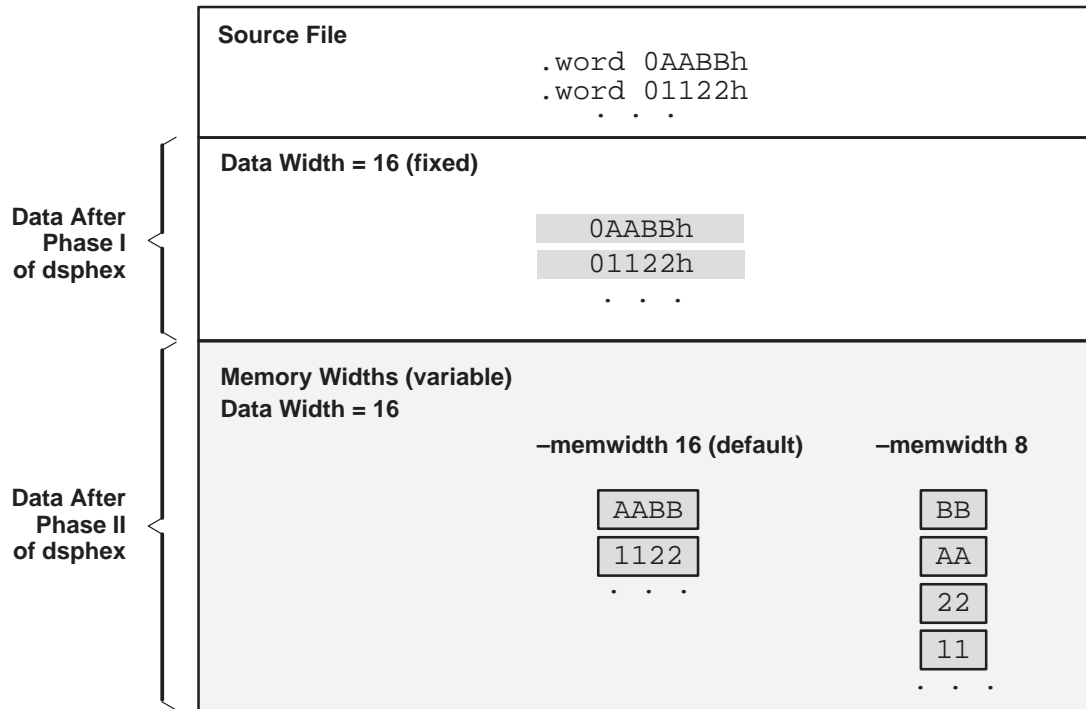
11.4.4 ROM Width

ROM width specifies the physical width (in bits) of each ROM device and corresponding output file (usually one byte or eight bits). The ROM width determines how the hex conversion utility partitions the data into output files. After the target words are mapped to the memory words, the memory words are broken into one or more output files. The number of output files is determined by the following formula:

number of files = memory width ÷ ROM width

where memory width > ROM width

For example, for a memory width of 16, you could specify a ROM width value of 16 and get a single output file containing 16-bit words. Or you can use a ROM width value of 8 to get two files, each containing 8 bits of each word.

The default ROM width that the hex conversion utility uses depends on the output format:

❏ All hex formats except TI-Tagged are configured as lists of 8-bit bytes; the default ROM width for these formats is 8 bits.

❏ TI-Tagged is a 16-bit format; the default ROM width for TI-Tagged is 16 bits.

Note: The TI-Tagged Format Is 16 Bits Wide

You cannot change the ROM width of the TI-Tagged format. The TI-Tagged format supports a 16-bit ROM width only.

You can change ROM width (except for TI-Tagged) by:

❏ Using the **–romwidth** option. This changes the ROM width value for the entire COFF file.

❏ Setting the **romwidth** parameter of the ROMS directive. This changes the ROM width value for a specific ROM address range and overrides the –romwidth option for that range. See Section 11.5, page 11-14.

For both methods, use a *value* that is a power of 2 greater than or equal to 8.

If you select a ROM width that is wider than the natural size of the output format (16 bits for TI-Tagged or 8 bits for all others), the utility simply writes multibyte fields into the file.

Figure 11–4 illustrates how the target, memory, and ROM widths are related to one another.

Figure 11–4. Data, Memory, and ROM Widths
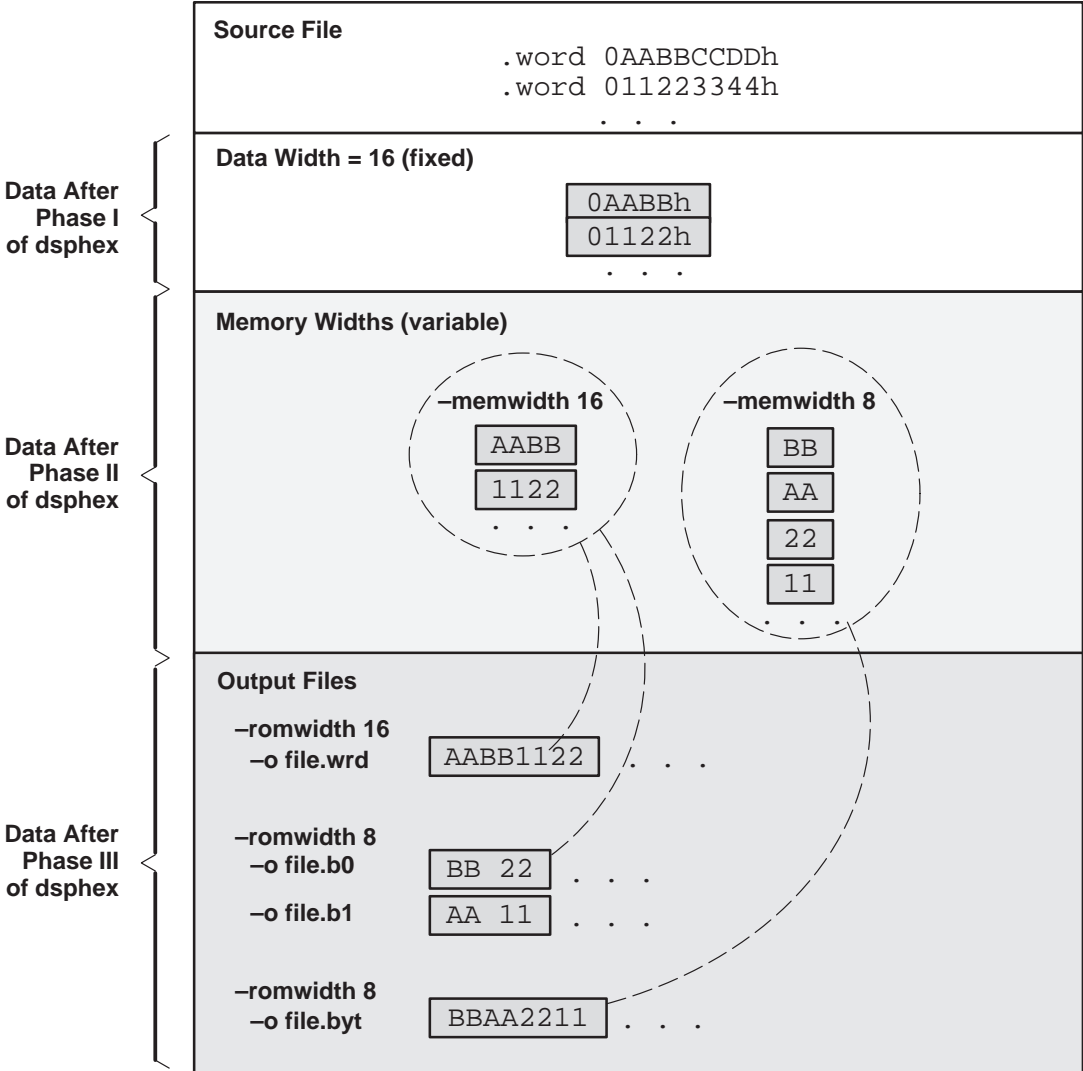
11.4.5 A Memory Configuration Example

Figure 11–5 shows a typical memory configuration example. This memory system consists of two 128K $\times$ 8-bit ROM devices.

Figure 11–5. 'C2x/C2xx/C5x Memory Configuration Example
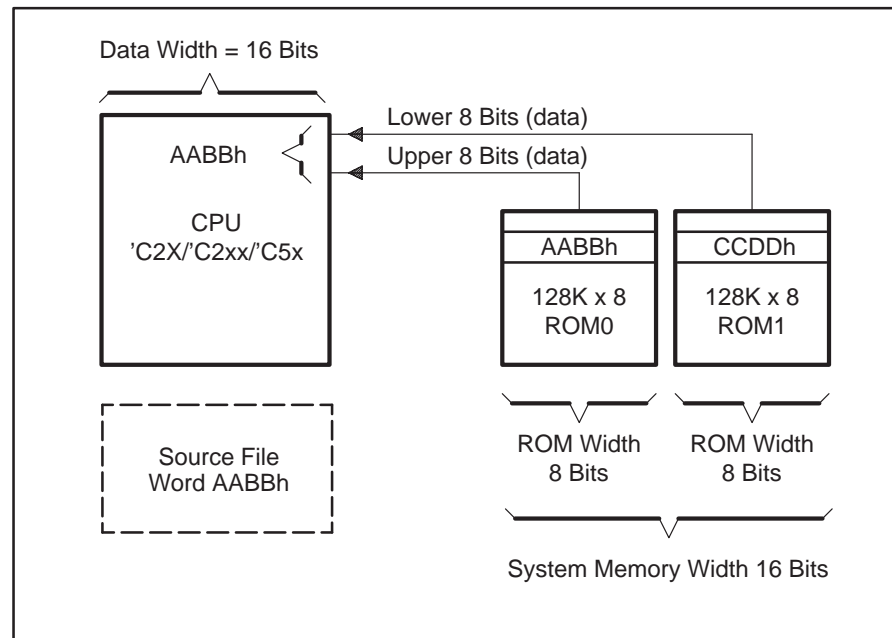
11.4.6 Specifying Word Order for Output Words

When memory words are narrower than target words (memory width < 16), target words are split into multiple consecutive memory words. There are two ways to split a wide word into consecutive memory locations in the same hex conversion utility output file:

❑ **–order MS** specifies **big-endian** ordering, in which the most significant part of the wide word occupies the first of the consecutive locations

❑ **–order LS** specifies **little-endian** ordering, in which the the least significant part of the wide word occupies the first of the consecutive locations

By default, the utility uses little-endian format because the 'C26 and 'C5x boot loaders expect the data in this order. Unless you are using your own boot loader program, avoid the using –order MS.

Note: When the –order Option Applies

❏ This option applies only when you use a memory width with a value less than 16. Otherwise, –order is ignored.

❏ This option does not affect the way memory words are split into output files. Think of the files as a set: the set contains a least significant file and a most significant file, but there is no ordering over the set. When you list filenames for a set of files, you *always* list the least significant first, regardless of the –order option.

Figure 11–6 demonstrates how –order affects the conversion process. This figure, and the previous figure, Figure 11–4, explain the condition of the data in the hex conversion utility output files.

Figure 11–6. Varying the Word Order
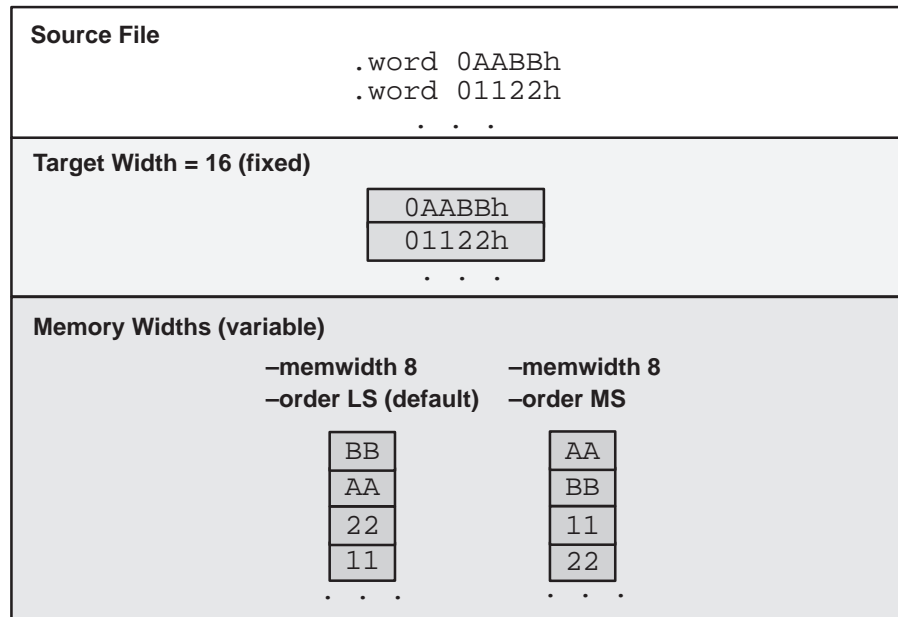
11.5 The ROMS Directive

The ROMS directive specifies the physical memory configuration of your system as a list of address-range parameters.

Each address range produces one set of files containing the hex conversion utility output data that corresponds to that address range. Each file can be used to program one single ROM device.

The ROMS directive is similar to the MEMORY directive of the TMS320C1x/C2x/C2xx/C5x linker: both define the memory map of the target address space. Each line entry in the ROMS directive defines a specific address range. The general syntax is:

```
ROMS
{
   [PAGE n:]
      romname: [origin=value,] [length=value,] [romwidth=value,]
                  [memwidth=value,] [fill=value,]
                  [files={filename1, filename2, ...}]

      romname: [origin=value,] [length=value,] [romwidth=value,]
                  [memwidth=value,] [fill=value,]
                  [files={filename1, filename2, ...}]
   ...
}
```

ROMS   begins the directive definition.

PAGE   identifies a memory space for targets that use program- and data-address spaces. If your program has been linked normally, PAGE 0 specifies program memory and PAGE 1 specifies data memory. Each memory range after the PAGE command belongs to that page until you specify another PAGE. If you don't include PAGE, all ranges belong to page 0.

romname   identifies a memory range. The name of the memory range may be one to eight characters in length. The name has no significance to the program; it simply identifies the range. (Duplicate memory range names are allowed.)

origin   specifies the starting address of a memory range. It can be entered as origin, org, or o. The associated value must be a decimal, octal, or hexadecimal constant. If you omit the origin value, the origin defaults to 0.

The following table summarizes the notation you can use to specify a decimal, octal, or hexadecimal constant:

Constant	Notation	Example
Hexadecimal	0x prefix or h suffix	0x77 or 077h
Octal	0 prefix	077
Decimal	No prefix or suffix	77

length   specifies the length of a memory range as the physical length of the ROM device. It can be entered as length, len, or l. The value must be a decimal, octal, or hexadecimal constant. If you omit the length value, it defaults to the length of the entire address space.

romwidth   specifies the physical ROM width of the range in bits (see subsection 11.4.4, page 11-9). Any value you specify here overrides the –romwidth option. The value must be a decimal, octal, or hexadecimal constant that is a power of 2 greater than or equal to 8.

memwidth   specifies the memory width of the range in bits (see subsection 11.4.3, page 11-8). Any value you specify here overrides the –memwidth option. The value must be a decimal, octal, or hexadecimal constant that is a power of 2 greater than or equal to 8. *When using the memwidth parameter, you must also specify the paddr parameter for each section in the SECTIONS directive.*

fill   specifies a fill value to use for the range. In image mode, the hex conversion utility uses this value to fill any holes between sections in a range. The value must be a decimal, octal, or hexadecimal constant with a width equal to the target width. Any value you specify here overrides the –fill option. When using fill, you must also use the –image command line option. See subsection 11.8.2, page 11-25.

files identifies the names of the output files that correspond to this range. Enclose the list of names in curly braces and order them from *least significant* to *most significant* output file.

The number of file names should equal the number of output files that the range will generate. To calculate the number of output files, refer to Section 11.4.4, page 11-9. The utility warns you if you list too many or too few filenames.

Unless you are using the –image option, all of the parameters defining a range are optional. A range with no origin or length defines the entire address space. In image mode, an origin and length are required for all ranges; the commas and equals signs are also optional.

Ranges on the same page must not overlap and must be listed in order of ascending address.

11.5.1 When to Use the ROMS Directive

If you don't use a ROMS directive, the utility defines a single default range that includes the entire program address space (PAGE 0). This is equivalent to a ROMS directive with a single range without origin or length.

Use the ROMS directive when you want to:

❑ **Program large amounts of data into fixed-size ROMs**. When you specify memory ranges corresponding to the length of your ROMs, the utility automatically breaks the output into blocks that fit into the ROMs.

❑ **Restrict output to certain segments**. You can also use the ROMS directive to restrict the conversion to a certain segment or segments of the target address space. The utility does not convert the data that falls outside of the ranges defined by the ROMS directive. Sections can span range boundaries; the utility splits them at the boundary into multiple ranges. If a section falls completely outside any of the ranges you define, the utility does not convert that section and issues no messages or warnings. In this way, you can exclude sections without listing them by name with the SECTIONS directive. However, if a section falls partially in a range and partially in unconfigured memory, the utility issues a warning and converts only the part within the range.

❑ **Use image mode.** When you use the –image option, you must use a ROMS directive. Each range is filled completely so that each output file in a range contains data for the whole range. Gaps before, between, or after sections are filled with the fill value from the ROMS directive, with the value specified with the –fill option, or with the default value of zero.

11.5.2 An Example of the ROMS Directive

The ROMS directive in Example 11–1 shows how 16K words of 16-bit memory could be partitioned for four 8K $\times$ 8-bit EPROMs.

Example 11–1. A ROMS Directive Example

```
infile.out
–image
–memwidth 16

ROMS
{
   EPROM1: org = 04000h, len = 02000h, romwidth = 8
           files = { rom4000.b0, rom4000.b1 }

   EPROM2: org = 06000h, len = 02000h, romwidth = 8,
           fill = 0FFh,
           files = { rom6000.b0, rom6000.b1 }
}
```

In this example, EPROM1 defines the address range from 4000h through 5FFFh. The range contains the following sections:

This section	Has this range
.text	4000h through 487Fh
.data	5B80H through 5FFFh

The rest of the range is filled with 0h (the default fill value). The data from this range is converted into two output files:

❑ rom4000.b0 contains bits 0 through 7
❑ rom4000.b1 contains bits 8 through 15

EPROM2 defines the address range from 6000h through 7FFFh. The range contains the following sections:

This section	Has this range
.data	6000h through 633Fh
.table	6700h through 7C7Fh

The rest of the range is filled with 0FFh (from the specified fill value). The data from this range is converted into two output files:

❑ rom6000.b0 contains bits 0 through 7
❑ rom6000.b1 contains bits 8 through 15

Figure 11–7 shows how the ROMS directive partitions the infile.out file into four output files.

Figure 11–7. The infile.out File From Example 11–1 Partitioned Into Four Output Files
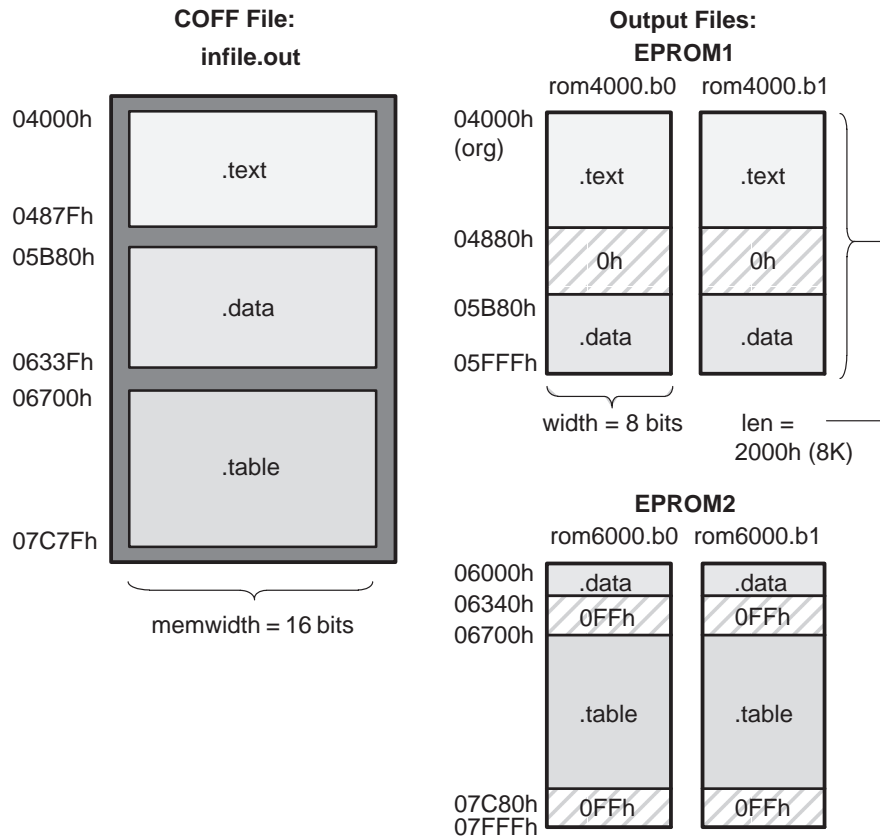
11.5.3 Creating a Map File of the ROMS directive

The map file (specified with the –map option) is advantageous when you use the ROMS directive with multiple ranges. The map file shows each range, its parameters, names of associated output files, and a list of contents (section names and fill values) broken down by address. Here's a segment of the map file resulting from the example in Example 11–1.

Example 11–2. Map File Output From Example 11–1 Showing Memory Ranges

```
-------------------------------------------------------
00004000..00005fff  Page=0  Width=8  "EPROM1"
-------------------------------------------------------
   OUTPUT FILES:   rom4000.b0   [b0..b7]
                   rom4000.b1   [b8..b15]

   CONTENTS: 00004000..0000487f .text
             00004880..00005b7f FILL = 00000000
             00005b80..00005fff .data
-------------------------------------------------------
00006000..00007fff  Page=0  Width=8  "EPROM2"
-------------------------------------------------------
   OUTPUT FILES:   rom6000.b0   [b0..b7]
                   rom6000.b1   [b8..b15]

   CONTENTS: 00006000..0000633f .data
             00006340..000066ff FILL = 000000ff
             00006700..00007c7f .table
             00007c80..00007fff FILL = 000000ff
```

11.6 The SECTIONS Directive

You can convert specific sections of the COFF file by name with the SECTIONS directive. You can also specify those sections you want the utility to configure for loading from an on-chip boot loader, and those sections that you wish to locate in ROM at a different address than the *load* address specified in the linker command file. If you:

❑ Use a SECTIONS directive, the utility converts only the sections that you list in the directive and ignores all other sections in the COFF file.

❑ Don't use a SECTIONS directive, the utility converts all initialized sections that fall within the configured memory. The TMS320C2x/2xx/5x compiler-generated initialized sections include: .text, .const, and .cinit.

Uninitialized sections are *never* converted, whether or not you specify them in a SECTIONS directive.

Note: Sections Generated by the C Compiler

The TMS320C2x/C2xx/C5x C compiler automatically generates these sections:

❑ **Initialized sections:** .text, .const, and .cinit.

❑ **Uninitialized sections:** .bss, .stack, and .sysmem.

Use the SECTIONS directive in a command file. (For more information about using a command file, see Section 11.3, page 11-5.) The general syntax for the SECTIONS directive is:

```
SECTIONS
{
   sname: [paddr=value]
   sname: [paddr=boot]
   sname: [= boot ],
   ...
}
```

SECTIONS   begins the directive definition.

sname   identifies a section in the COFF input file. If you specify a section that doesn't exist, the utility issues a warning and ignores the name.

paddr specifies the physical ROM address at which this section should be located. This value overrides the section load address given by the linker. (Refer to Section 11.10, page 11-34).This value must be a decimal, octal, or hexadecimal constant; it can also be the word **boot** (to indicate a boot table section for use with the on-chip boot loader). *If your file contains multiple sections, and if one section uses a paddr parameter, then all sections must use a paddr parameter.*

= boot configures a section for loading by the on-chip boot loader. This is equivalent to using **paddr=boot**. Boot sections have a physical address determined both by the target processor type and by the various boot-loader-specific command line options.

The commas are optional. For similarity with the linker's SECTIONS directive, you can use colons after the section names (in place of the equal sign on the boot keyboard). For example, the following statements are equivalent:

```
SECTIONS { .text: .data: boot }
SECTIONS { .text, .data = boot }
```

In the following example, the COFF file contains six initialized sections: .text, .data, .const, .vectors, .coeff, and .tables. Suppose you want only .text and .data to be converted. Use a SECTIONS directive to specify this:

```
SECTIONS { .text, .data }
```

To configure both of these sections for boot loading, add the boot keyword:

```
SECTIONS { .text = boot, .data = boot }
```

Note: Using the –boot Option and the SECTIONS Directive

When you use the SECTIONS directive with the on-chip boot loader, the –boot option is ignored. You must explicitly specify any boot sections in the SECTIONS directive. For more information about –boot and other command line options associated with the on-chip boot loader, see Table 11–2, page 11-27.

11.7 Output Filenames

When the hex conversion utility translates your COFF object file into a data format, it partitions the data into one or more output files. When multiple files are formed by splitting data into byte-wide or word-wide files, *filenames are always assigned in order from least to most significant.* This is true, regardless of target or COFF endian ordering, or of any –order option.

Assigning Output Filenames

The hex conversion utility follows this sequence when assigning output filenames:

1) **It looks for the ROMS directive.** If a file is associated with a range in the ROMS directive and you have included a list of files (files = {. . .}) on that range, the utility takes the filename from the list.

    For example, assume that the target data is 16-bit words being converted to two files, each eight bits wide. To name the output files using the ROMS directive, you could specify:

    ```
    ROMS
    {
     RANGE1: romwidth=8, files={ xyz.b0 xyz.b1 }
    }
    ```
    The utility creates the output files by writing the least significant bits (LSBs) to xyz.b0 and the most significant bits (MSBs) to xyz.b1.

2) **It looks for the –o options.** You can specify names for the output files by using the –o option. If no filenames are listed in the ROMS directive and you use –o options, the utility takes the filename from the list of –o options. The following line has the same effect as the example above using the ROMS directive:

    ```
    –o xyz.b0 –o xyz.b1
    ```
    Note that if both the ROMS directive and –o options are used together, the ROMS directive overrides the –o options.

3) **It assigns a default filename.** If you specify no filenames or fewer names than output files, the utility assigns a default filename. A default filename consists of the base name from the COFF input file plus a 2- to 3-character extension. The extension has three parts:

    a) A format character, based on the output format:

a	for ASCII-Hex
i	for Intel
t	for TI-Tagged
m	for Motorola-S
x	for Tektronix

b) The range number in the ROMS directive. Ranges are numbered starting with 0. If there is no ROMS directive, or only one range, the utility omits this character.

c) The file number in the set of files for the range, starting with 0 for the least significant file.

For example, assume coff.out is for a 16-bit target processor and you are creating Intel format output. With no output filenames specified, the utility produces two output files named coff.i0 and coff.i1.

If you include the following ROMS directive when you invoke the hex conversion utility, you would have two output files:

```
ROMS
{
   range1: o = 1000h l = 1000h
   range2: o = 2000h l = 1000h
}
```

These output files	Contain this data
coff.i01	1000h through 1FFFh
coff.i11	2000h through 2FFFh

11.8 Image Mode and the –fill Option

This section points out the advantages of operating in image mode and describes the method of producing output files with a precise, continuous image of a target memory range.

11.8.1 The –image Option

With the –image option, the utility generates a memory image by completely filling all of the mapped ranges specified in the ROMS directive.

A COFF file consists of blocks of memory (sections) with assigned memory locations. Typically, all sections are not adjacent: there are gaps between sections in the address space for which there is no data. When such a file is converted *without* the use of image mode, the hex conversion utility bridges these gaps by using the address records in the output file to skip ahead to the start of the next section. In other words, there may be discontinuities in the output file addresses. Some EPROM programmers do not support address discontinuities.

In image mode, there are no discontinuities. Each output file contains a continuous stream of data that corresponds exactly to an address range in target memory. Any gaps before, between, or after sections are filled with a fill value that you supply.

An output file converted by using image mode still has address records because many of the hexadecimal formats require an address on each line. However, in image mode, these addresses will always be contiguous.

Note: Defining the Ranges of Target Memory

If you use image mode, you must also use a ROMS directive. In image mode, each output file corresponds directly to a range of target memory. You must define the ranges. If you don't supply the ranges of target memory, the utility tries to build a memory image of the entire target processor address space—potentially a huge amount of output data. To prevent this situation, the utility requires you to explicitly restrict the address space with the ROMS directive.

11.8.2 Specifying a Fill Value

The –fill option specifies a value for filling the holes between sections. The fill value must be specified as an integer constant following the –fill option. The width of the constant is assumed to be that of a word on the target processor. For example, for the 'C2x, specifying –fill 0FFh results in a fill pattern of 00FFh. The constant value is not sign-extended.

The hex conversion utility uses a default fill value of zero if you don't specify a value with the fill option. *The –fill option is valid only when you use –image*; otherwise, it is ignored.

11.8.3 Steps to Follow in Image Mode

Step 1: Define the ranges of target memory with a ROMS directive (see Section 11.5, page 11-14).

Step 2: Invoke the hex conversion utility with the –image option. To number the bytes sequentially, use the –byte option; to reset the address origin to zero for each output file, use the –zero option. See subsection 11.10.3, page 11-36, for details on the –byte option, and page 11-35 for details on the –zero option. If you don't specify a fill value with the ROMS directive and you want a value other than the default of zero, use the –fill option.

11.9 Building a Table for an On-Chip Boot Loader

Some DSP devices, such as the 'C26 and 'C5x, have a built-in boot loader that initializes memory with one or more blocks of code or data. The boot loader uses a special table (a **boot table**) stored in memory (such as EPROM) or loaded from a device peripheral (such as a serial or communications port) to initialize the code or data. The hex conversion utility supports the boot loader by automatically building the boot table.

11.9.1 Description of the Boot Table

The input for a boot loader is the boot table (also known as a *source program*). The boot table contains records that instruct the on-chip loader to copy blocks of data contained in the table to specified destination addresses. Some boot tables also contain values for initializing various processor control registers. The boot table can be stored in memory or read in through a device peripheral.

The hex conversion utility automatically builds the boot table for the boot loader. Using the utility, you specify the COFF sections you want the boot loader to initialize, the table location, and the values for any control registers. The hex conversion utility identifies the target device type from the COFF file, builds a complete image of the table according to the format required by that device, and converts it into hexadecimal in the output files. Then, you can burn the table into ROM or load it by other means.

The boot loader supports loading from memory that is narrower than the normal width of memory. For example, you can boot a 16-bit TMS320C26 from a single 8-bit EPROM by using the –memwidth option to configure the width of the boot table. The hex conversion utility automatically adjusts the table's format and length. See the *TMS320C2x User's Guide*, *TMS320C26BFNL Boot Loader* example, for an illustration of a boot table.

11.9.2 The Boot Table Format

The boot table format is simple. Typically, there is a header record containing the width of the table and possibly some values for various control registers. Each subsequent block has a header containing the size and destination address of the block followed by data for the block. Multiple blocks can be entered; a termination block follows the last block. Finally, the table can have a footer containing more control register values. Refer to the boot-loader section in the specific device user's guide for more information.

11.9.3 How to Build the Boot Table

Table 11–2 summarizes the hex conversion utility options available for the boot loader.

Table 11–2. Boot-Loader Utility Options

Option	Description
–boot	Convert all sections into bootable form (use instead of a SECTIONS directive)
–bootorg PARALLEL	Specify the source of the boot loader table as the parallel port
–bootorg SERIAL	Specify the source of the boot loader table as the serial port
–bootorg *value*	Specify the source address of the boot loader table
–bootpage *value*	Specify the target page number of the boot loader table
–cg *value*	Set the memory configuration register ('C26 only)

To build the boot table, follow these steps:

Step 1: **Link the file**. Each block of the boot table data corresponds to an initialized section in the COFF file. Uninitialized sections are not converted by the hex conversion utility (see Section 11.6, page 11-20).

When you select a section for placement in a boot-loader table, the hex conversion utility places the section's *load address* in the destination address field for the block in the boot table. The section content is then treated as raw data for that block.

The hex conversion utility does not use the section run address. When linking, you need not worry about the ROM address or the construction of the boot table—the hex conversion utility handles this.

Step 2: **Identify the bootable sections**. You can use the –boot option to tell the hex conversion utility to configure all sections for boot loading. Or, you can use a SECTIONS directive to select specific sections to be configured (see Section 11.6, page 11-20). Note that if you use a SECTIONS directive, the –boot option is ignored.

Step 3: **Set the ROM address of the boot table**. Use the –bootorg option to set the source address of the complete table. For example, if you are using the 'C26 and booting from memory location 8000h, specify –bootorg 8000h. The address field in the the hex conversion utility output file will then start at 8000h.

If you use –bootorg SERIAL or –bootorg PARALLEL, or if you do not use the –bootorg option at all, the utility places the table at the origin of the first memory range in a ROMS directive. If you do not use a ROMS directive, the table will start at the first section load address. There is also a –bootpage option for starting the table somewhere other than page 0.

Step 4: **Set boot-loader-specific options.** Set such options as entry point and memory control registers as needed.

Step 5: **Describe your system memory configuration**. Refer to Section 11.4, page 11-7, and Section 11.5, page 11-14, for details.

The complete boot table is similar to a single section containing all of the header records and data for the boot loader. The address of this "section" is the boot table origin. As part of the normal conversion process, the hex conversion utility converts the boot table to hexadecimal format and maps it into the output files like any other section.

Be sure to leave room in your system memory for the boot table, especially when you are using the ROMS directive. The boot table cannot overlap other nonboot sections or unconfigured memory. Usually, this is not a problem; typically, a portion of memory in your system is reserved for the boot table. Simply configure this memory as one or more ranges in the ROMS directive, and use the –bootorg option to specify the starting address.

11.9.4 Booting From a Device Peripheral

You can choose to boot from a serial or parallel port by using the SERIAL or PARALLEL keyword with the –bootorg option. Your selection of a keyword depends on the target device and the channel you want to use. For example, to boot a 'C26 from its serial port, specify –bootorg SERIAL on the command line or in a command file. To boot a 'C5x from one of its parallel ports, specify –bootorg PARALLEL.

Notes:

❏ **Possible memory conflicts.** When you boot from a device peripheral, the boot table is not actually in memory; it is being received through the device peripheral. However, as explained in Step 3 on page 11-28, a memory address is assigned.

If the table conflicts with a nonboot section, put the boot table on a different page. Use the ROMS directive to define a range on an unused page and the –bootpage option to place the boot table on that page. The boot table will then appear to be at location 0 on the dummy page.

❏ **Why the System Might Require an EPROM Format for a Peripheral Boot Loader Address.** In a typical system, a parent processor boots a child processor through that child's peripheral. The boot loader table itself may occupy space in the memory map of the parent processor. The EPROM format and ROMS directive address correspond to those used by the parent processor, not those that are used by the child.

11.9.5 Setting the Entry Point for the Boot Table

After completing the boot load process, program execution starts at the address of the first block loaded (the default entry point). By using the –e option with the hex conversion utility, you can set the entry point to a different address.

For example, if you want your program to start running at address 0123h after loading, specify –e 0123h on the command line or in a command file. You can determine the –e address by looking at the map file that the linker generates.

Note: Valid Entry Points

The value must be a constant; the hex conversion utility cannot evaluate symbolic expressions like c_int00 (default entry point assigned by the TMS320C2x/C2xx/C5x C compiler).

When you use the –e option, the utility builds a dummy block of length 1 and data value 0 that loads at the specified address. Your blocks follow this dummy block. Since the dummy block is loaded first, the dummy value of 0 is overwritten by the subsequent blocks. Then, the boot loader jumps to the –e option address after the boot load is completed.

11.9.6 Using the 'C26 Boot Loader

This subsection explains and gives an example on using the hex conversion utility with the boot loader for 'C26 devices. The 'C26 boot loader has four different modes. You can select these modes by using the –bootorg and –memwidth options:

Mode	–bootorg Setting	–memwidth Setting
8-bit parallel I/O	–bootorg PARALLEL	–memwidth 8
16-bit parallel I/O	–bootorg PARALLEL	–memwidth 16
8-bit serial RS232	–bootorg SERIAL	–memwidth 8
8-bit EPROM	–bootorg 0x8000	–memwidth 8

You should set the –romwidth equal to the –memwidth unless you want to have multiple output files.

Serial and Parallel Modes

The following details summarize what the hex conversion utility does when it builds the boot table for the parallel and serial modes.

❑ In the two parallel modes, the boot table header consists of three 8-bit fields: STATUS, CONFIG, and LENGTH. The utility automatically builds these into the table:

  ■ Bits 0–2 of the STATUS field define the three MSBs of the load length.

  ■ Bit 3 of the STATUS field always has a value of 1 that enables the boot loader.

  ■ Bit 4 of the STATUS field is set to 0 for 8-bit mode and to 1 for 16-bit mode.

  ■ Bits 5–7 are reserved.

  ■ The CONFIG field is set from the –cg option you supply.

  ■ The LENGTH field contains the eight LSBs of the load length.

❑ In serial mode, an additional BAUD field serves as the first field in the header. The boot loader accepts any value that has the top bit set; the utility uses 80h. The STATUS, CONFIG, and LENGTH fields for serial mode are identical to those used in the parallel modes (see above).

❑ In both the serial and parallel modes, a single SYNC field follows the data in the boot table. The value of SYNC doesn't matter; the utility uses 0.

❑ Both of the 8-bit formats require the data to be formatted LSB first; the utility does this automatically.

The following restrictions apply to all modes:

❑ You can load only one section.
❑ The maximum length of the section is 2K words.
❑ The destination address is fixed (internal RAM block B0).

The program in Example 11–3 boots the .text section of abc.obj through the serial port. First, link .text into on-chip RAM block B0, ensuring that it's not more than 2K words long. Next, convert to hexadecimal format by using this command file:

Example 11–3. Sample Command File for Booting From a 'C26 Serial Port

```
abc.out              /* input file                     */
-c abc.i             /* output file                    */
-i                   /* Intel format                   */
-memwidth 8          /* 8-bit serial                   */
-romwidth 8          /* outfile is bytes, not words    */
-bootorg SERIAL      /* serial mode boot               */
-cg 40h              /* value for interrupt/mem config */

SECTIONS { .text: BOOT }
```

The resulting hex file is a list of 8-bit bytes that you can transmit through the serial port to boot the device.

Setting the Memory Configuration and Interrupt Mask Register (Serial and Parallel Modes)

In addition to loading data into memory, the boot loader for the 'C26 can also initialize the memory configuration and the interrupt mask register (IMR) from a value specified in the boot table. When using the hex conversion utility, you can set the value for the memory configuration and IMR with the –cg option:

–cg *value*

This option requires a constant value as its argument. The bits are defined as follows:

❑ Bits D0–D5 are loaded into the IMR.

❑ Bits D6 and D7 define the memory configuration. The following table shows how memory can be configured.

D7	D6	Program Memory	Data Memory
0	0	B0	B1, B2
0	1	B0, B1	B2
1	0	B0, B1, B3	

EPROM Mode

The 'C26 EPROM mode differs significantly from the serial and parallel modes. There is no header or footer information; instead, the boot table is a memory image of the on-chip RAM blocks, configured into 8-bit memory and ordered with the MSBs first, starting at location 08000h. To boot a 'C26 from a byte-wide EPROM, simply specify –bootorg 08000h and –memwidth 8 when invoking the hex conversion utility. The 'C26 expects to find the EPROM at address 08000h in global memory.

11.9.7 Using the 'C5x Boot Loader

This subsection explains and gives an example on using the hex conversion utility with the boot loader for 'C5x devices. The 'C5x boot loader has six different modes. You can select these modes by using the –bootorg and –memwidth options:

Mode	–bootorg Setting	–memwidth Setting
8-bit parallel I/O	–bootorg PARALLEL	–memwidth 8
16-bit parallel I/O	–bootorg PARALLEL	–memwidth 16
8-bit serial RS232	–bootorg SERIAL	–memwidth 8
16-bit serial RS232	–bootorg SERIAL	–memwidth 16
8-bit parallel EPROM	–bootorg 0x8000	–memwidth 8
16-bit parallel EPROM	–bootorg 0x8000	–memwidth 16

You should set the –romwidth equal to the –memwidth unless you want to have multiple output files.

The 'C5x can boot through either the serial or parallel interface with either 8- or 16-bit data. The format is the same for any combination: the boot table consists of a field containing the destination address, a field containing the length, and a block containing the data.

You can boot only one section. If you are booting from an 8-bit channel, 16-bit words are stored in the table with the MSBs first; the hex conversion utility automatically builds the table in the correct format.

❑ To boot from a serial port, specify –bootorg SERIAL when invoking the utility. Use either –memwidth 8 or –memwidth 16.

❑ To load from a parallel I/O port, invoke the utility by specifying –bootorg PARALLEL. Use either –memwidth 8 or –memwidth 16.

❑ To boot from external memory (EPROM), specify the source address of the boot memory by using the –bootorg option. Use either –memwidth 8 or –memwidth 16.

For example, the following command file allows you to boot the .text section of abc.out from a byte-wide EPROM at location 08000h.

Figure 11–8. Sample Command File for Booting From a 'C5x EPROM

```
abc.out                 /* input file                    */
-o abc.i                /* output file                   */
-i                      /* Intel format                  */
-memwidth 8             /* 8-bit memory                  */
-romwidth 8             /* outfile is bytes, not words   */
-bootorg 8000h          /* external memory boot          */

SECTIONS { .text: BOOT }
```

11.10　Controlling the ROM Device Address

The hex conversion utility output address field corresponds to the ROM device address. The EPROM programmer burns the data into the location specified by the hex conversion utility output file address field. The hex conversion utility offers some mechanisms to control the starting address in ROM of each section and/or to control the address index used to increment the address field. However, many EPROM programmers offer direct control of the location in ROM in which the data is burned.

11.10.1　Controlling the Starting Address

Depending on whether or not you are using the boot loader, the hex conversion utility output file controlling mechanisms are different.

❑　**Nonboot-loader mode.** The address field of the hex conversion utility output file is controlled by the following mechanisms listed from low to high priority:

1)　**The linker command file.** By default, the address field of the hex conversion utility output file is a function of the load address (as given in the linker command file) and the hex conversion utility parameter values. The relationship is summarized as follows:

$$\text{out\_file\_addr}^{\dagger} = \text{load\_addr} \times (\text{data\_width} \div \text{mem\_width})$$

out_file_addr	is the address of the output file.
load_addr	is the linker-assigned load address.
data_width	is specified as 16 bits for the TMS320C1x/ C2x/C2xx/ C5x devices. See subsection 11.4.2, page 11-8.
mem_width	is the memory width of the memory system. You can specify the memory width by the –memwidth option or by the memwidth parameter inside the ROMS directive. See Section 11.4.3, page 11-8.

† If paddr is not specified

The value of data width divided by memory width is a correction factor for address generation. When data width is larger than memory width, the correction factor *expands* the address space. For example, if the load address is 0×1 and data width divided by memory width is 2, the output file address field would be 0×2. The data is split into two consecutive locations of size of the memory width.

2) **The –paddr option of the SECTIONS directive.** When the –paddr is specified for a section, the hex conversion utility bypasses the section load address and places the section in the address specified by –paddr. The relationship between the hex conversion utility output file address field and the –paddr option can be summarized as follows:

$$\text{out\_file\_addr}^\dagger = \text{paddr\_val} + (\text{load\_addr} - \text{sect\_beg\_load\_addr}) \times (\text{data\_width} \div \text{mem\_width})$$

out_file_addr	is the address of the output file.
paddr_val	is the value supplied with the –paddr option inside the SECTIONS directive.
sec_beg_load_addr	is the section load address assigned by the linker.

$\dagger$ If paddr is not specified

The value of data width divided by memory width is a correction factor for address generation. The section beginning load address factor subtracted from the load address is an offset from the beginning of the section.

3) **The –zero option.** When you use the –zero option, the utility resets the address origin to zero for each output file. Since each file starts at zero and counts upward, any address records represent offsets from the beginning of the file (the address within the ROM) rather than actual target addresses of the data.

You must use the –zero option in conjunction with the –image option to force the starting address in each output file to be zero. If you specify the –zero option without the –image option, the utility issues a warning and ignores the –zero option.

❏ **Boot-Loader Mode.** When the boot loader is used, the hex conversion utility places the different COFF sections that are in the boot table into consecutive memory locations. Each COFF section becomes a boot table block whose destination address is equal to the linker-assigned section load address.

The address field of the the hex conversion utility output file is not related to the section load addresses assigned by the linker. The address fields are simply offsets to the beginning of the table, multiplied by the correction factor (data width divided by memory width).

The beginning of the boot table defaults to the linked load address of the first bootable section in the COFF input file, unless you use one of the following mechanisms, listed here from low- to high-priority. Higher priority mechanisms override the values set by low priority options in an overlapping range.

1) **The ROM origin specified in the ROMS directive.** The hex conversion utility places the boot table at the origin of the first memory range in a ROMS directive.

2) **The –bootorg option.** The hex conversion utility places the boot table at the address specified by the –bootorg option if you select boot loading from memory. Neither –bootorg PARALLEL nor –bootorg SERIAL affect the address field.

11.10.2 Controlling the Address Increment Index

By default, the hex conversion utility increments the output file address field according to the memory width value. If memory width equals 16, the address will increment on the basis of how many 16-bit words are present in each line of the output file.

11.10.3 The –byte Option

Some EPROM programmers may require the output file address field to contain a byte count rather than a word count. If you use the –byte option, the output file address increments once for each byte. For example, if the starting address is 0h, the first line contains eight words, and you use no –byte option, the second line would start at address 8 (8h). If the starting address is 0h, the first line contains eight words, and you use the –byte option, the second line would start at address 16 (010h). The data in both examples are the same; –byte affects only the calculation of the output file address field, not the actual target processor address of the converted data.

The –byte option causes the address records in an output file to refer to byte locations within the file, whether the target processor is byte-addressable or not.

11.10.4 Dealing With Address Holes

When memory width is different from data width, the automatic multiplication of the load address by the correction factor might create holes at the beginning of a section or between sections.

For example, assume you want to load a COFF section (.sec1) at address 0x0100 of an 8-bit EPROM. If you specify the load address in the linker command file at location 0x100, the hex conversion utility will multiply the address by 2 (data width divided by memory width = 16/8 = 2), giving the output file a starting address of 0x200. Unless you control the starting address of the EPROM with your EPROM programmer, you could create holes within the EPROM. The EPROM will burn the data starting at location 0x200 instead of 0x100. To solve this, you can:

❑ **Use the paddr parameter of the SECTIONS directive.** This forces a section to start at the specified value. Figure 11–9 shows a command file that can be used to avoid the hole at the beginning of .sec1.

Figure 11–9. Hex Command File for Avoiding a Hole at the Beginning of a Section

```
–i
a.out
–map a.map

ROMS
{
 ROM : org = 0x0100, length = 0x200, romwidth = 8,
       memwidth = 8,
}

SECTIONS
 {
    sec1: paddr = 0x100
}
```

Note: If your file contains multiple sections, and, if one section uses a paddr parameter, then all sections must use the paddr parameter.

❑ **Use the –bootorg option or use the ROMS origin parameter (for boot loading only).** As described on page 11-35, when you are boot loading, the EPROM address of the entire boot-loader table can be controlled by the –bootorg option or by the ROMS directive origin. For another example, refer to Section D.3, page D-10, or Section D.4, page D-19.

11.11 Description of the Object Formats

The hex conversion utility converts a COFF object file into one of five object formats that most EPROM programmers accept as input: ASCII-Hex, Intel MCS-86, Motorola-S, Extended Tektronix, or TI-Tagged.

Table 11–3 specifies the format options.

❏ If you use more than one of these options, the last one you list overrides the others.

❏ The default format is Tektronix (–x option).

Table 11–3.Options for Specifying Hex Conversion Formats

Option	Format	Address Bits	Default Width
–a	ASCII-Hex	16	8
–i	Intel	32	8
–m	Motorola-S	16	8
–t	TI-Tagged	16	16
–x	Tektronix	32	8

Address bits determine how many bits of the address information the format supports. Formats with 16-bit addresses support addresses up to 64K only. The utility truncates target addresses to fit in the number of available bits.

The **default width** determines the default output width. You can change the default width by using the –romwidth option or by using the –romwidth option in the ROMS directive. You cannot change the default width of the TI-Tagged format, which supports a 16-bit width only.

11.11.1 ASCII-Hex Object Format (–a Option)

The ASCII-Hex object format supports 16-bit addresses. The format consists of a byte stream with bytes separated by spaces. Figure 11–10 illustrates the ASCII-Hex format.

Figure 11–10.ASCII-Hex Object Format
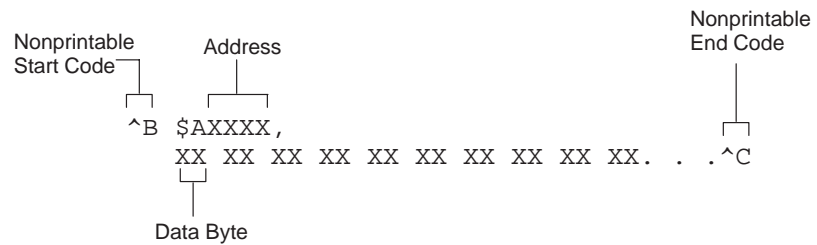
The file begins with an ASCII STX character (ctrl-B, 02h) and ends with an ASCII ETX character (ctrl-C, 03h). Address records are indicated with $AXXXX, in which XXXX is a 4-digit (16-bit) hexadecimal address. The address records are present only in the following situations:

❑ When discontinuities occur
❑ When the byte stream does not begin at address 0

You can avoid all discontinuities and any address records by using the –image and –zero options. This creates output that is simply a list of byte values.

11.11.2 Intel MCS-86 Object Format (–i Option)

The Intel object format supports 16-bit addresses and 32-bit extended addresses. Intel format consists of a 9-character (4-field) prefix—which defines the start of record, byte count, load address, and record type—the data, and a 2-character checksum suffix.

The 9-character prefix represents three record types:

Record Type	Description
00	Data record
01	End-of-file record
04	Extended linear address record

Record type *00*, the data record, begins with a colon (:) and is followed by the byte count, the address of the first data byte, the record type (00), and the checksum. Note that the address is the least significant 16 bits of a 32-bit address; this value is concatenated with the value from the most recent 04 (extended linear address) record to create a full 32-bit address. The checksum is the 2s complement (in binary form) of the preceding bytes in the record, including byte count, address, and data bytes.

Record type *01*, the end-of-file record, also begins with a colon (:), followed by the byte count, the address, the record type (01), and the checksum.

Record type *04*, the extended linear address record, specifies the upper 16 address bits. It begins with a colon (:), followed by the byte count, a dummy address of 0h, the record type (04), the most significant 16 bits of the address, and the checksum. The subsequent address fields in the data records contain the least significant bits of the address.

Figure 11–11 illustrates the Intel hexadecimal object format.

Figure 11–11. Intel Hex Object Format
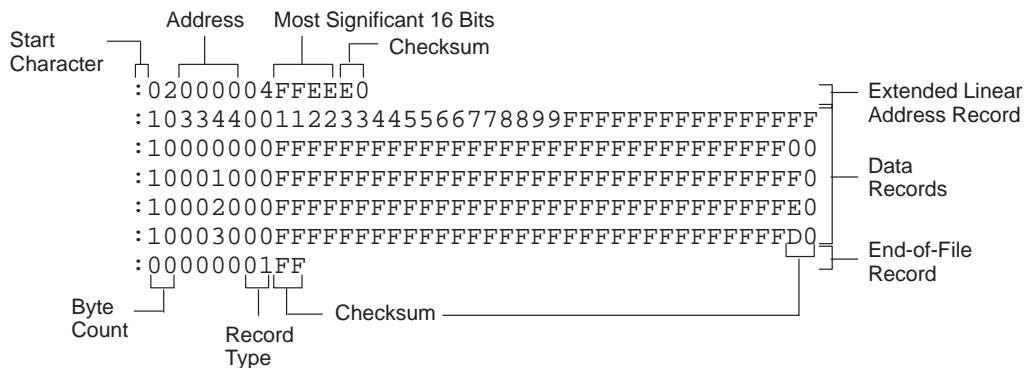
11.11.3 **Motorola Exorciser Object Format (–m Option)**

The Motorola-S format supports 16-bit addresses. It consists of a start-of-file (header) record, data records, and an end-of-file (termination) record. Each record is made up of five fields: record type, byte count, address, data, and checksum. The three record types are:

Record Type	Description
S0	Header record
S1	Code/data record
S2	Termination record

The byte count is the character pair count in the record, excluding the type and byte count itself.

The checksum is the least significant byte of the 1s complement of the sum of the values represented by the pairs of characters making up the byte count, address, and the code/data fields.

Figure 11–12 illustrates the Motorola-S object format.

Figure 11–12. Motorola-S Format
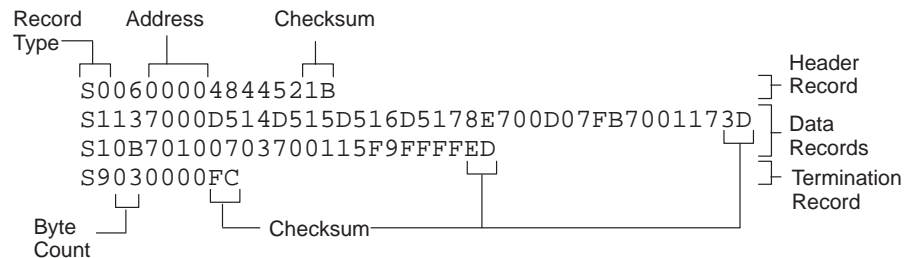
11.11.4   Texas Instruments SDSMAC Object Format (–t Option)

The TI-Tagged object format supports 16-bit addresses. It consists of a start-of-file record, data records, and end-of-file record. Each of the data records is made up of a series of small fields and is signified by a tag character. The significant tag characters are:

Tag Character	Description
K	followed by the program identifier
7	followed by a checksum
8	followed by a dummy checksum (ignored)
9	followed by a 16-bit load address
B	followed by a data word (four characters)
F	identifies the end of a data record
*	followed by a data byte (two characters)

Figure 11–13 illustrates the tag characters and fields in TI-Tagged object format.

Figure 11–13. TI-Tagged Object Format
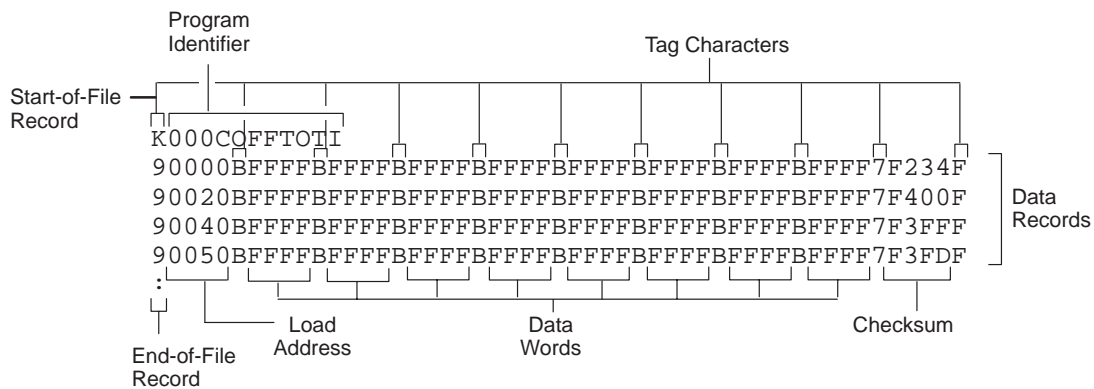
If any data fields appear before the first address, the first field is assigned address 0000h. Address fields may be expressed for any data byte, but none is required. The checksum field, which is preceded by the tag character 7, is a 2s complement of the sum of the 8-bit ASCII values of characters, beginning with the first tag character and ending with the checksum tag character (7 or 8). The end-of-file record is a colon (:).

11.11.5 Extended Tektronix Object Format (–x Option)

The Tektronix object format supports 32-bit addresses and has two types of records:

data record   contains the header field, the load address, and the object code.

termination record   signifies the end of a module.

The header field in the data record contains the following information:

Item	Number of ASCII Characters	Description
%	1	Data type is Tektronix format
Block length	2	Number of characters in the record, minus the %
Block type	1	6 = data record 8 = termination record
Checksum	2	A two-digit hex sum modulo 256 of all values in the record except the % and the checksum itself.

The load address in the data record specifies where the object code will be located. The first digit specifies the address length; this is always 8. The remaining characters of the data record contain the object code, two characters per byte.

Figure 11–14 illustrates the Tektronix object format.

Figure 11–14.Extended Tektronix Object Format
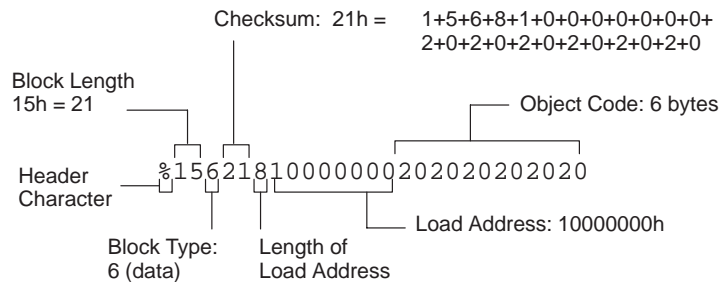
11.12 Hex Conversion Utility Error Messages

section mapped to reserved memory message

Description A section or a boot-loader table is mapped into a reserved memory area listed in the processor memory map.

Action Correct the section or boot-loader address. Refer to the device user's guide for valid memory locations.

sections overlapping

Description Two or more COFF section load addresses overlap or a boot table address overlaps another section.

Action This problem may be caused by an incorrect translation from load address to hex output file address that is performed by the hex conversion utility when memory width is less than data width. Refer to Section 11.4, page 11-7, and Section 11.10, page 11-34.

unconfigured memory error

Description This error could have one of two causes:

■ The COFF file contains a section whose load address falls outside the memory range defined in the ROMS directive.

■ The boot-loader table address is not within the memory range defined by the ROMS directive.

Action Correct the ROM range as defined by the ROMS directive to cover the memory range as needed, or modify the section load address or boot-loader table address. Remember that if the ROMS directive is not used, the memory range defaults to the entire processor address space. For this reason, removing the ROMS directive could also be a workaround.

Common Object File Format

The assembler and linker create object files in common object file format (COFF). COFF is an implementation of an object file format of the same name that was developed by AT&T for use on UNIX-based systems. This format is used because it encourages modular programming and provides more powerful and flexible methods for managing code segments and target system memory.

Sections are a basic COFF concept. Chapter 2 discusses COFF sections in detail. If you understand section operation, you will be able to use the assembly language tools more efficiently.

This appendix contains technical details about COFF object file structure. Much of this information pertains to the symbolic debugging information that is produced by the C compiler. The purpose of this appendix is to provide supplementary information on the internal format of COFF object files.

These topics are included in this appendix:

A.1 COFF File Structure

The elements of a COFF object file describe the file's sections and symbolic debugging information. These elements include:

❏ A file header
❏ Optional header information
❏ A table of section headers
❏ Raw data for each initialized section
❏ Relocation information for each initialized section
❏ Line number entries for each initialized section
❏ A symbol table
❏ A string table

The assembler and linker produce object files with the same COFF structure; however, a program that is linked for the final time does not usually contain relocation entries. Figure A−1 illustrates the overall object file structure.

Figure A−1. COFF File Structure
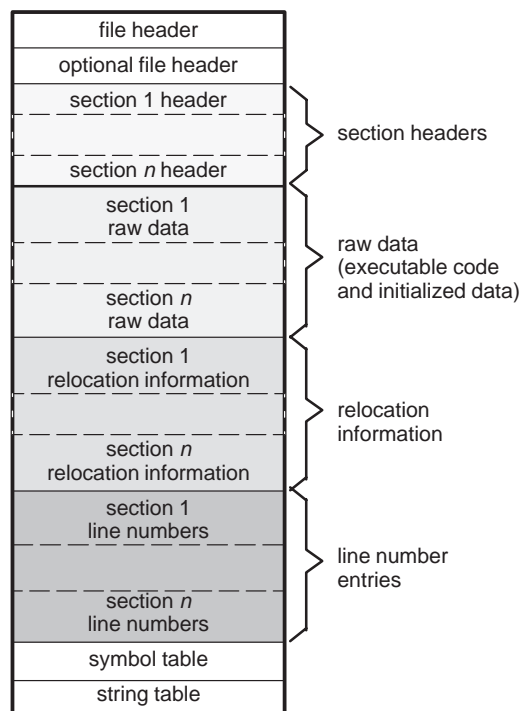
Figure A–2 shows a typical example of a COFF object file that contains the three default sections, .text, .data, and .bss, and a named section (referred to as <named>). By default, the tools place sections into the object file in the following order: .text, .data, initialized named sections, .bss, and uninitialized named sections. Although uninitialized sections have section headers, they have no raw data, relocation information, or line number entries. This is because the .bss and .usect directives simply reserve space for uninitialized data; uninitialized sections contain no actual code.

Figure A–2. COFF Object File

| file header |
| .text section header |
| .data section header |
| .bss section header |
| <named> section section header |
| .text raw data |
| .data raw data |
| <named> section raw data |
| .text relocation information |
| .data relocation information |
| <named> section relocation information |
| .text line numbers |
| .data line numbers |
| <named> section line numbers |
| symbol table |
| string table |

section headers

raw data

relocation information

line number entries

Different Versions of COFF

This appendix refers to two versions of COFF: version 0 and version 1. COFF version 0 is used in toolset versions 5.00 through 6.40. COFF version 1 is used in all later versions of the toolset. COFF version 1 tools can read COFF version 0, however, these tools will output COFF version 1, unless you use the linker –v0 option to output COFF version 0.

A.2 File Header Structure

The file header contains information that describes the general format of an object file. Table A–1 shows the structure of the Version 0 COFF file header (20 bytes). Table A–2 shows the structure of the Version 1 COFF file header (22 bytes).

Table A–1.File Header Contents for COFF Version 0

Byte Number	Type	Description
0–1	Unsigned short integer	Either magic number (092h) to indicates the file can be executed in a TMS320C2x/ C2xx/5x system; or 0c0h to indicate the COFF version.
2–3	Unsigned short integer	Number of section headers
4–7	Long integer	Time and date stamp; indicates when the file was created
8–11	Long integer	File pointer; contains the symbol table's starting address
12–15	Long integer	Number of entries in the symbol table
16–17	Unsigned short integer	Number of bytes in the optional header. This field is either 0 or 28; if it is 0, there is no optional file header.
18–19	Unsigned short integer	Flags (see Table A–3)

Table A–2.File Header Contents for COFF Version 1

Byte Number	Type	Description
0–1	Unsigned short integer	Version id; indicates version of COFF file structure.
2–3	Unsigned short integer	Number of section headers
4–7	Long integer	Time and date stamp; indicates when the file was created
8–11	Long integer	File pointer; contains the symbol table's starting address
12–15	Long integer	Number of entries in the symbol table
16–17	Unsigned short integer	Number of bytes in the optional header. This field is either 0 or 28; if it is 0, there is no optional file header.
18–19	Unsigned short integer	Flags (see Table A–3)
20–21	Unsigned short integer	Target id; magic number (092h) indicates the file can be executed in a TMS320C2x/C2xx/C5x system

Table A–3 lists the flags that can appear in bytes 18 and 19 of the file header. Any number and combination of these flags can be set at the same time (for example, if bytes 18 and 19 are set to 0003h, F_RELFLG and F_EXEC are both set.)

Table A–3.File Header Flags (Bytes 18 and 19)

Mnemonic	Flag	Description
F_10	00h	This file is built for the TMS320C1x devices.
F_20	010h	This file is built for the TMS320C2x devices.
F_25	020h	This file is built for the TMS320C2x/C5x devices.
F_RELFLG	0001h	Relocation information was stripped from the file.
F_EXEC	0002h	The file is relocatable (it contains no unresolved external references).
F_LNNO	0004h	Line numbers were stripped from the file.
F_LSYMS	0008h	Local symbols were stripped from the file.
F_LENDIAN	0100h	The file has the byte ordering used by TMS320C1x, TMS320C2x, TMS320C2xx, and TMS320C5x devices (16 bits per word, least significant byte first).

A.3 Optional File Header Format

The linker creates the optional file header and uses it to perform relocation at download time. Partially linked files do not contain optional file headers. Table A–4 illustrates the optional file header format.

Table A–4. Optional File Header Contents

Byte Number	Type	Description
0–1	Short integer	Magic number (0108h)
2–3	Short integer	Version stamp
4–7	Long integer	Size (in words) of executable code
8–11	Long integer	Size (in words) of initialized data
12–15	Long integer	Size (in words) of uninitialized data
16–19	Long integer	Entry point
20–23	Long integer	Beginning address of executable code
24–27	Long integer	Beginning address of initialized data

A.4 Section Header Structure

COFF object files contain a table of section headers that define where each section begins in the object file. Each section has its own section header.

Table A–5.Section Header Contents

Byte Number	Type	Description
0–7	Character	8-character section name, padded with nulls
8–11	Long integer	Section's physical address
12–15	Long integer	Section's virtual address
16–19	Long integer	Section size in words
20–23	Long integer	File pointer to raw data
24–27	Long integer	File pointer to relocation entries
28–31	Long integer	File pointer to line number entries
32–33	Unsigned short integer	Number of relocation entries
34–35	Unsigned short integer	Number of line number entries
36–37	Unsigned short integer	Flags (see Table A–6)
38	Character	Reserved
39	Unsigned character	Memory page number

Table A–6 lists the flags that can appear in bytes 36 and 37 of the section header.

Table A–6.Section Header Flags (Bytes 36 and 37)

Mnemonic	Flag	Description
STYP_REG	0000h	Regular section (allocated, relocated, loaded)
STYP_DSECT	0001h	Dummy section (relocated, not allocated, not loaded)
STYP_NOLOAD	0002h	Noload section (allocated, relocated, not loaded)
STYP_GROUP	0004h	Grouped section (formed from several input sections)
STYP_PAD	0008h	Padding section (loaded, not allocated, not relocated)
STYP_COPY	0010h	Copy section (relocated, loaded, but not allocated; relocation and line number entries are processed normally)
STYP_TEXT	0020h	Section contains executable code
STYP_DATA	0040h	Section contains initialized data
STYP_BSS	0080h	Section contains uninitialized data
STYP_ALIGN	0700h	Section is aligned on a page boundary

Note: The term *loaded* means that the raw data for this section appears in the object file.

The flags listed in Table A–6 can be combined; for example, if the flag's word is set to 024h, both STYP_GROUP and STYP_TEXT are set.

Figure A–3 illustrates how the pointers in a section header would point to the elements in an object file that are associated with the .text section.

Figure A–3. Section Header Pointers for the .text Section
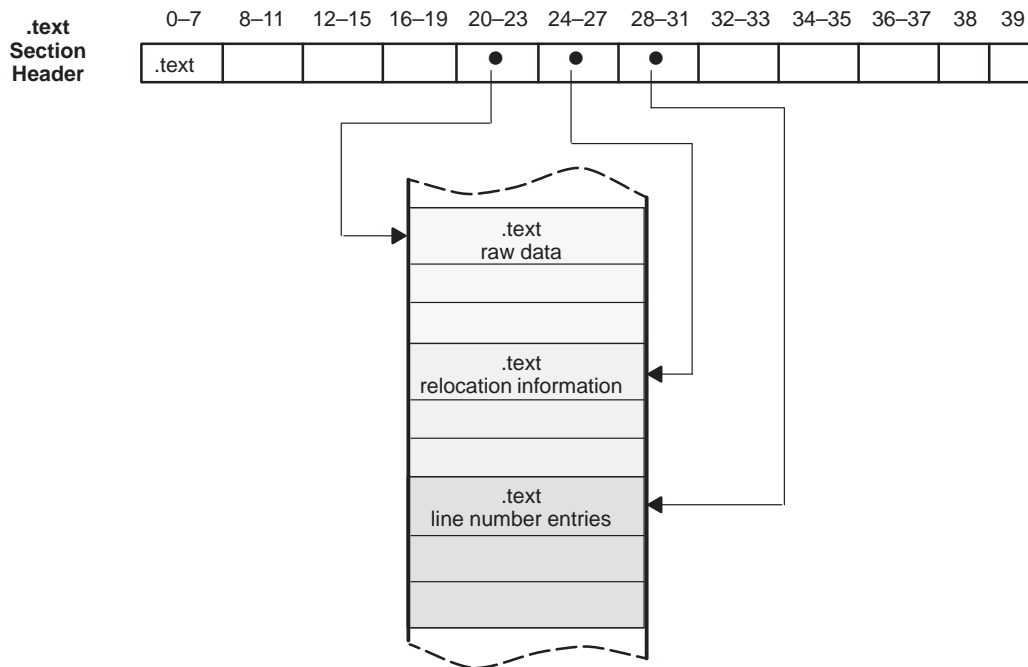
As Figure A–2, page A-3, shows, uninitialized sections (created with the .bss and .usect directives) vary from this format. Although uninitialized sections have section headers, they have no raw data, relocation information, or line number information. They occupy no actual space in the object file. Therefore, the number of relocation entries, the number of line number entries, and the file pointers are 0 for an uninitialized section. The header of an uninitialized section simply tells the linker how much space for variables it should reserve in the memory map.

A.5 Structuring Relocation Information

A COFF object file has one relocation entry for each relocatable reference. The assembler automatically generates relocation entries. The linker reads the relocation entries as it reads each input section and performs relocation. The relocation entries determine how references within each input section are treated.

Version 0 COFF file relocation information entries use the 10-byte format shown in Table A–7. Version 1 COFF file relocation information entries use the 12-byte format shown in Table A–8.

Table A–7. Relocation Entry Contents for COFF Version 0

Byte Number	Type	Description
0–3	Long integer	Virtual address of the reference
4–5	Unsigned short integer	Symbol table index (0–65535)
6–7	Unsigned short integer	Reserved
8–9	Unsigned short integer	Relocation type (see Table A–9)

Table A–8. Relocation Entry Contents for COFF Version 1

Byte Number	Type	Description
0–3	Long integer	Virtual address of the reference
4–7	Unsigned long integer	Symbol table index
8–9	Unsigned short integer	Reserved
10–11	Unsigned short integer	Relocation type (see Table A–9)

The **virtual address** is the symbol's address in the current section *before* relocation; it specifies *where* a relocation must occur. (This is the address of the field in the object code that must be patched.)

Following is an example of code that generates a relocation entry:

```
0002                        .global   X
0003   0000   FF80          B         X
       0001   0000!
```

In this example, the virtual address of the relocatable field is 0001.

The **symbol table index** is the index of the referenced symbol. In the preceding example, this field would contain the index of X in the symbol table. The amount of the relocation is the difference between the symbol's current address in the section and its assembly-time address. The relocatable field must be relocated by the same amount as the referenced symbol. In the example, X has a value of 0 before relocation. Suppose X is relocated to address 2000h. This is the relocation amount (2000h – 0 = 2000h), so the relocation field at address 1 is patched by adding 2000h to it.

You can determine a symbol's relocated address if you know which section it is defined in. For example, if X is defined in .data and .data is relocated by 2000h, X is relocated by 2000h.

If the symbol table index in a relocation entry is –1 (0FFFFh), this is called an *internal relocation.* In this case, the relocation amount is simply the amount by which the current section is being relocated.

The **relocation type** specifies the size of the field to be patched and describes how the patched value should be calculated. The type field depends on the addressing mode that was used to generate the relocatable reference. In the preceding example, the actual address of the referenced symbol (X) will be placed in a 16-bit field in the object code. This is a 16-bit direct relocation, so the relocation type is R_RELWORD. Table A–9 lists the relocation types.

Table A–9. Relocation Types (Bytes 8 and 9)

Mnemonic	Flag	Relocation Type
R_ABS	0000h	No relocation
R_RELBYTE	000Fh	8-bit direct reference to symbol's address
R_REL	002Ah	13-bit direct reference
R_RELWORD	0010h	16-bit direct reference to symbol's address
R_PARTLS7	0028h	7 LSBs of an address
R_PARTMS9	0029h	9 MSBs of an address

A.6 Line Number Table Structure

The object file contains a table of line number entries that are useful for symbolic debugging. When the C compiler produces several lines of assembly language code, it creates a line-number entry that maps these lines back to the original line of C source code that generated them. Each single line number entry contains 6 bytes of information. Table A–10 shows the format of a line-number entry.

Table A–10. Line Number Entry Format

Byte Number	Type	Description
0–3	Long integer	This entry may have one of two values:
		1) If it is the first entry in a block of line-number entries, it points to a symbol entry in the symbol table.
		2) If it is not the first entry in a block, it is the physical address of the line indicated by bytes 4–5.
4–5	Unsigned short integer	This entry may have one of two values:
		1) If this field is 0, this is the first line of a function entry.
		2) If this field is *not* 0, this is the line number of a line of C source code.

Figure A–4 shows how line number entries are grouped into blocks.

Figure A–4. Line Number Blocks

Symbol Index 1	0
physical address	line number
physical address	line number
Symbol Index *n*	0
physical address	line number
physical address	line number

As Figure A–4 shows, each entry is divided into halves:

❑ For the *first line* of a function, bytes 0–3 point to the name of a symbol or a function in the symbol table, and bytes 4–5 contain a 0, which indicates the beginning of a block.

❏ For the *remaining lines* in a function, bytes 0–3 show the physical address (the number of words created by a line of C source) and bytes 4–5 show the address of the original C source, relative to its appearance in the C source program.

The line entry table can contain many of these blocks.

Figure A–5 illustrates line number entries for a function named XYZ. As shown, the function name is entered as a symbol in the symbol table. The first portion on XYZ's block of line number entries points to the function name in the symbol table. Assume that the original function in the C source contained three lines of code. The first line of code produces 4 words of assembly language code, the second line produces 3 words, and the third line produces 10 words.

Figure A–5. Line Number Entries
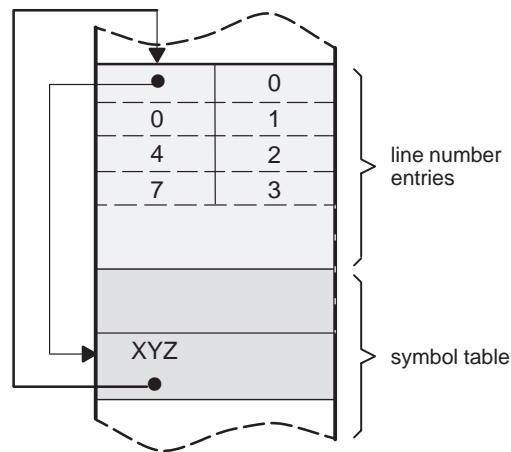
(Note that the symbol table entry for XYZ has a field that points back to the be-ginning of the line number block.)

Because line numbers are not often needed, the linker provides an option (–s) that strips line number information from the object file; this provides a more compact object module.

A.7   Symbol Table Structure and Content

The order of symbols in the symbol table is very important; they appear in the sequence shown in Figure A–6.

Figure A–6. Symbol Table Contents

filename 1
function 1
local symbols for function 1
function 2
local symbols for function 2
filename 2
function 1
local symbols for function 1
static variables
defined global symbols
undefined global symbols

Static variables refer to symbols defined in C that have storage class static outside any function. If you have several modules that use symbols with the same name, making them static confines the scope of each symbol to the module that defines it (this eliminates multiple-definition conflicts).

The entry for each symbol in the symbol table contains the symbol's:

❏ Name (or a pointer into the string table)
❏ Type
❏ Value
❏ Section it was defined in
❏ Storage class
❏ Basic type (integer, character, etc.)
❏ Derived type (array, structure, etc.)
❏ Dimensions
❏ Line number of the source code that defined the symbol

Section names are also defined in the symbol table.

All symbol entries, regardless of class and type, have the same format in the symbol table. Each symbol table entry contains the 18 bytes of information listed in Table A–11. Each symbol may also have an 18-byte auxiliary entry; the special symbols listed in Table A–12, page A-15, always have an auxiliary entry. Some symbols may not have all the characteristics listed above; if a particular field is not set, it is set to null.

Table A–11. Symbol Table Entry Contents

Byte Number	Type	Description
0–7	Character	This field contains one of the following:
		1) An 8-character symbol name, padded with nulls
		2) An offset into the string table if the symbol name is longer than 8 characters
8–11	Long integer	Symbol value; storage class dependent
12–13	Short integer	Section number of the symbol
14–15	Unsigned short integer	Basic and derived type specification
16	Character	Storage class of the symbol
17	Character	Number of auxiliary entries (always 0 or 1)

A.7.1 Special Symbols

The symbol table contains some special symbols that are generated by the compiler, assembler, and linker. Each special symbol contains ordinary symbol table information and an auxiliary entry. Table A–12 lists these symbols.

Table A–12.   Special Symbols in the Symbol Table

Symbol	Description
.file	File name
.text	Address of the .text section
.data	Address of the .data section
.bss	Address of the .bss section
.bb	Address of the beginning of a block
.eb	Address of the end of a block
.bf	Address of the beginning of a function
.ef	Address of the end of a function
.target	Pointer to a structure or union that is returned by a function
.*n*fake	Dummy tag name for a structure, union, or enumeration
.eos	End of a structure, union, or enumeration
etext	Next available address after the end of the .text output section
edata	Next available address after the end of the .data output section
end	Next available address after the end of the .bss output section

Several of these symbols appear in pairs:

❏ .bb/.eb indicate the beginning and end of a block.

❏ .bf/.ef indicate the beginning and end of a function.

❏ *n*fake/.eos name and define the limits of structures, unions, and enumerations that were not named. The .eos symbol is also paired with named structures, unions, and enumerations.

When a structure, union, or enumeration has no tag name, the compiler assigns it a name so that it can be entered into the symbol table. These names are of the form *n*fake, where *n* is an integer. The compiler begins numbering these symbol names at 0.

Symbols and Blocks

In C, a block is a compound statement that begins and ends with braces. A block always contains symbols. The symbol definitions for any particular block are grouped together in the symbol table and are delineated by the .bb/.eb special symbols. Blocks can be nested in C, and their symbol table entries can be nested correspondingly. Figure A–7 shows how block symbols are grouped in the symbol table.

Figure A–7. Symbols for Blocks

Symbol Table

Block 1:	.bb
	symbols for block 1
	.eb
Block 2:	.bb
	symbols for block 2
	.eb
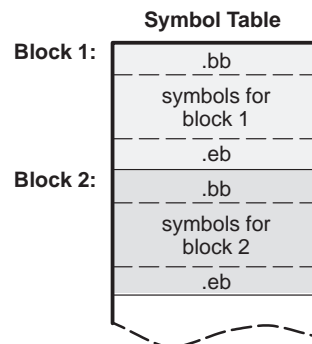
Symbols and Functions

The symbol definitions for a function appear in the symbol table as a group, delineated by .bf/.ef special symbols. The symbol table entry for the function name precedes the .bf special symbol. Figure A–8 shows the format of symbol table entries for a function.

Figure A–8. Symbols for Functions

function name
.bf
symbols for the function
.ef
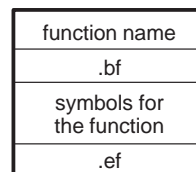
If a function returns a structure or union, a symbol table entry for the special symbol .target will appear between the entries for the function name and the .bf special symbol.

A.7.2 Symbol Name Format

The first 8 bytes of a symbol table entry (bytes 0–7) indicate a symbol's name:

❏ If the symbol name is 8 characters or less, this field has type *character*. The name is padded with nulls (if necessary) and stored in bytes 0–7.

❏ If the symbol name is greater than 8 characters, this field is treated as two long integers. The entire symbol name is stored in the string table. Bytes 0–3 contain 0, and bytes 4–7 are an offset into the string table.

A.7.3 String Table Structure

Symbol names that are longer than eight characters are stored in the string table. The field in the symbol table entry that would normally contain the symbol's name contains, instead, a pointer to the symbol's name in the string table. Names are stored contiguously in the string table, delimited by a null byte. The first four bytes of the string table contain the size of the string table in bytes; thus, offsets into the string table are greater than or equal to four.

Figure A–9 is a string table that contains two symbol names, Adaptive-Filter and Fourier-Transform. The index in the string table is 4 for Adaptive-Filter and 20 for Fourier-Transform.

Figure A–9. String Table

38			
'A'	'd'	'a'	'p'
't'	'i'	'v'	'e'
'-'	'F'	'i'	'l'
't'	'e'	'r'	'\0'
'F'	'o'	'u'	'r'
'i'	'e'	'r'	'-'
'T'	'r'	'a'	'n'
's'	'f'	'o'	'r'
'm'	'\0'		

A.7.4 Storage Classes

Byte 16 of the symbol table entry indicates the storage class of the symbol. Storage classes refer to the method in which the C compiler accesses a symbol. Table A–13 lists valid storage classes.

Table A–13. Symbol Storage Classes

Mnemonic	Value	Storage Class	Mnemonic	Value	Storage Class
C_NULL	0	No storage class	C_UNTAG	12	Union tag
C_AUTO	1	Automatic variable	C_TPDEF	13	Type definition
C_EXT	2	External symbol	C_USTATIC	14	Uninitialized static
C_STAT	3	Static	C_ENTAG	15	Enumeration tag
C_REG	4	Register variable	C_MOE	16	Member of an enumeration
C_EXTDEF	5	External definition	C_REGPARM	17	Register parameter
C_LABEL	6	Label	C_FIELD	18	Bit field
C_ULABEL	7	Undefined label	C_BLOCK	100	Beginning or end of a block; used only for the .bb and .eb special symbols
C_MOS	8	Member of a structure	C_FCN	101	Beginning or end of a function; used only for the .bf and .ef special symbols
C_ARG	9	Function argument	C_EOS	102	End of structure; used only for the .eos special symbol
C_STRTAG	10	Structure tag	C_FILE	103	Filename; used only for the .file special symbol
C_MOU	11	Member of a union	C_LINE	104	Used only by utility programs

Some special symbols are restricted to certain storage classes. Table A–14 lists these symbols and their storage classes.

Table A–14. Special Symbols and Their Storage Classes

Special Symbol	Restricted to This Storage Class	Special Symbol	Restricted to This Storage Class
.file	C_FILE	.eos	C_EOS
.bb	C_BLOCK	.text	C_STAT
.eb	C_BLOCK	.data	C_STAT
.bf	C_FCN	.bss	C_STAT
.ef	C_FCN		

A.7.5 Symbol Values

Bytes 8–11 of a symbol table entry indicate a symbol's value. A symbol's value depends on the symbol's storage class; Table A–15 summarizes the storage classes and related values.

Table A–15. Symbol Values and Storage Classes

Storage Class	Value Description	Storage Class	Value Description
C_AUTO	Stack offset in bits	C_UNTAG	0
C_EXT	Relocatable address	C_TPDEF	0
C_STAT	Relocatable address	C_ENTAG	0
C_REG	Register number	C_MOE	Enumeration value
C_LABEL	Relocatable address	C_REGPARM	Register number
C_MOS	Offset in bits	C_FIELD	Bit displacement
C_ARG	Stack offset in bits	C_BLOCK	Relocatable address
C_STRTAG	0	C_FCN	Relocatable address
C_MOU	Offset in bits	C_FILE	0

If a symbol's storage class is C_FILE, the symbol's value is a pointer to the next .file symbol. Thus, the .file symbols form a one-way linked list in the symbol table. When there are no more .file symbols, the final .file symbol points back to the first .file symbol in the symbol table.

The value of a relocatable symbol is its virtual address. When the linker relocates a section, the value of a relocatable symbol changes accordingly.

A.7.6 Section Number

Bytes 12–13 of a symbol table entry contain a number that indicates which section the symbol was defined in. Table A–16 lists these numbers and the sections they indicate.

Table A–16. Section Numbers

Mnemonic	Section Number	Description
N_DEBUG	–2	Special symbolic debugging symbol
N_ABS	–1	Absolute symbol
N_UNDEF	0	Undefined external symbol
N_SCNUM	1	.text section (typical)
N_SCNUM	2	.data section (typical)
N_SCNUM	3	.bss section (typical)
N_SCNUM	4–32,767	Section number of a named section, in the order in which the named sections are encountered

If there were no .text, .data, or .bss sections, the numbering of named sections would begin with 1.

If a symbol has a section number of 0, –1, or –2, it is not defined in a section. A section number of –2 indicates a symbolic debugging symbol, which includes structure, union, and enumeration tag names; type definitions; and the filename. A section number of –1 indicates that the symbol has a value but is not relocatable. A section number of 0 indicates a relocatable external symbol that is not defined in the current file.

A.7.7 Type Entry

Bytes 14–15 of the symbol table entry define the symbol's type. Each symbol has one basic type and one to six derived types.

Following is the format for this 16-bit type entry:

Derived Type 6	Derived Type 5	Derived Type 4	Derived Type 3	Derived Type 2	Derived Type 1	Basic Type

Size (in bits): 2   2   2   2   2   2   4
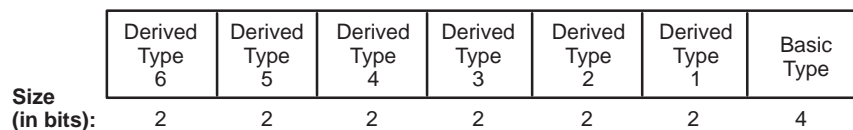
Bits 0–3 of the type field indicate the basic type. Table A–17 lists valid basic types.

Table A−17. Basic Types

Mnemonic	Value	Type
T_VOID	0	Void type
T_CHAR	2	Character
T_SHORT	3	Short integer
T_INT	4	Integer
T_LONG	5	Long integer
T_FLOAT	6	Floating point
T_DOUBLE	7	Double word
T_STRUCT	8	Structure
T_UNION	9	Union
T_ENUM	10	Enumeration
T_MOE	11	Member of an enumeration
T_UCHAR	12	Unsigned character
T_USHORT	13	Unsigned short integer

Bits 4−15 of the type field are arranged as six 2-bit fields that can indicate one to six derived types. Table A−18 lists the possible derived types.

Table A−18. Derived Types

Mnemonic	Value	Type
DT_NON	0	No derived type
DT_PTR	1	Pointer
DT_FCN	2	Function
DT_ARY	3	Array

An example of a symbol with several derived types would be a symbol with a type entry of 0000000011010011_2. This entry indicates that the symbol is an array of pointers to short integers.

A.7.8 Auxiliary Entries

Each symbol table entry may have **one** or **no** auxiliary entry. An auxiliary symbol table entry contains the same number of bytes as a symbol table entry (18), but the format of an auxiliary entry depends on the symbol's type and storage class. Table A–19 summarizes these relationships.

Table A–19.   Auxiliary Symbol Table Entries Format

| Name | Storage Class | Type Entry | | Auxiliary Entry Format |
		Derived Type 1	Basic Type	
.file	C_FILE	DT_NON	T_NULL	Filename (see Table A–20)
.text, .data, .bss	C_STAT	DT_NON	T_NULL	Section (see Table A–21)
tagname	C_STRTAG C_UNTAG C_ENTAG	DT_NON	T_NULL	Tag name (see Table A–22)
.eos	C_EOS	DT_NON	T_NULL	End of structure (see Table A–23)
fcname	C_EXT C_STAT	DT_FCN	(See note 1)	Function (see Table A–24)
arrname	(See note 2)	DT_ARY	(See note 1)	Array (see Table A–25)
.bb, .eb	C_BLOCK	DT_NON	T_VOID	Beginning and end of a block (see Table A–26 and Table A–27)
.bf, .ef	C_FCN	DT_NON	T_VOID	Beginning and end of a function (see Table A–26 and Table A–27)
Name related to a structure, union, or enumeration	(See note 2)	DT_PTR DT_ARR DT_NON	T_STRUCT T_UNION T_ENUM	Name related to a structure, union, or enumeration (see Table A–28)

Notes: 1) Any except T_MOE
2) C_AUTO, C_STAT, C_MOS, C_MOU, C_TPDEF

In Table A–19, *tagname* refers to any symbol name (including the special symbol *n*fake). *Fcname* and *arrname* refer to any symbol name.

A symbol that satisfies more than one condition in Table A–19 should have a union format in its auxiliary entry. A symbol that satisfies none of these conditions should not have an auxiliary entry.

Filenames

Each of the auxiliary table entries for a filename contains a 14-character file-name in bytes 0–13. Bytes 14–17 are unused.

Table A–20. Filename Format for Auxiliary Table Entries

Byte Number	Type	Description
0–13	Character	File name
14–17	—	Unused

Sections

Table A–21 illustrates the format of auxiliary table entries.

Table A–21. Section Format for Auxiliary Table Entries

Byte Number	Type	Description
0–3	Long integer	Section length
4–6	Unsigned short integer	Number of relocation entries
7–8	Unsigned short integer	Number of line number entries
9–17	—	Unused (zero filled)

Tag Names

Table A–22 illustrates the format of auxiliary table entries for tag names.

Table A–22. Tag Name Format for Auxiliary Table Entries

Byte Number	Type	Description
0–5	—	Unused (zero filled)
6–7	Unsigned short integer	Size of structure, union, or enumeration
8–11	—	Unused (zero filled)
12–15	Long integer	Index of next entry beyond this structure, union, or enumeration
16–17	—	Unused (zero filled)

End of Structure

Table A–23 illustrates the format of auxiliary table entries for ends of structures.

Table A–23. End-of-Structure Format for Auxiliary Table Entries

Byte Number	Type	Description
0–3	Long integer	Tag index
4–5	—	Unused (zero filled)
6–7	Unsigned short integer	Size of structure, union, or enumeration
8–17	—	Unused (zero filled)

Functions

Table A–24 illustrates the format of auxiliary table entries for functions.

Table A–24. Function Format for Auxiliary Table Entries

Byte Number	Type	Description
0–3	Long integer	Tag index
4–7	Long integer	Size of function (in bits)
8–11	Long integer	File pointer to line number
12–15	Long integer	Index of next entry beyond this function
16–17	—	Unused (zero filled)

Arrays

Table A–25 illustrates the format of auxiliary table entries for arrays.

Table A–25. Array Format for Auxiliary Table Entries

Byte Number	Type	Description
0–3	Long integer	Tag index
4–5	Unsigned short integer	Line number declaration
6–7	Unsigned short integer	Size of array
8–9	Unsigned short integer	First dimension
10–11	Unsigned short integer	Second dimension
12–13	Unsigned short integer	Third dimension
14–15	Unsigned short integer	Fourth dimension
16–17	—	Unused (zero filled)

End of Blocks and Functions

Table A–26 illustrates the format of auxiliary table entries for the ends of blocks and functions.

Table A–26. End-of-Blocks/Functions Format for Auxiliary Table Entries

Byte Number	Type	Description
0–3	—	Unused (zero filled)
4–5	Unsigned short integer	C source line number
6–17	—	Unused (zero filled)

Beginning of Blocks and Functions

Table A–27 illustrates the format of auxiliary table entries for the beginnings of blocks and functions.

Table A–27. Beginning-of-Blocks/Functions Format for Auxiliary Table Entries

Byte Number	Type	Description
0–3	—	Unused (zero filled)
4–5	Unsigned short integer	C source line number of block begin
6–11	—	Unused (zero filled)
12–15	Long integer	Index of next entry past this block
16–17	—	Unused (zero filled)

Names Related to Structures, Unions and Enumerations

Table A–28 illustrates the format of auxiliary table entries for the names of structures, unions, and enumerations.

Table A–28. Structure, Union, and Enumeration Names Format for Auxiliary Table Entries

Byte Number	Type	Description
0–3	Long integer	Tag index
4–5	—	Unused (zero filled)
6–7	Unsigned short integer	Size of the structure, union, or enumeration
8–17	—	Unused (zero filled)

Symbolic Debugging Directives

The TMS320C1x/C2x/C2xx/C5x assembler supports several directives that the TMS320C2x/C2xx/C5x C compiler uses for symbolic debugging:

❏ The **.sym** directive defines a global variable, a local variable, or a function. Several parameters allow you to associate various debugging information with the symbol or function.

❏ The **.stag**, **.etag**, and **.utag** directives define structures, enumerations, and unions, respectively. The **.member** directive specifies a member of a structure, enumeration, or union. The **.eos** directive ends a structure, enumeration, or union definition.

❏ The **.func** and **.endfunc** directives specify the beginning and ending lines of a C function.

❏ The **.block** and **.endblock** directives specify the bounds of C blocks.

❏ The **.file** directive defines a symbol in the symbol table that identifies the current source file name.

❏ The **.line** directive identifies the line number of a C source statement.

These symbolic debugging directives are not usually listed in the assembly language file that the compiler creates. If you want them to be listed, invoke the code generator with the –o option, as shown below:

```
dspcg –o input file
```

This appendix contains an alphabetical directory of the symbolic debugging directives. With the exception of the .file directive, each directive contains an example of C source and the resulting assembly language code.

Syntax   **.block**   *beginning line number*
                         .endblock   *ending line number*

Description   The **.block** and **.endblock** directives specify the beginning and end of a C block. The *line numbers* are optional; they specify the location in the source file where the block is defined.

Block definitions can be nested. The assembler will detect improper block nesting.

Example   Following is an example of C source that defines a block and the resulting assembly language code.

C source:

```
           .
           .
           .
       {                      /*  Beginning of a block   */
           int  a,b;
           a = b;
       }                      /*  End of a block         */
           .
           .
           .
```

Resulting assembly language code:

```
.block       0
.sym         _a,1,4,1,32
.sym         _b,2,4,1,32
.line        7
LDI          *+FP(2),R0
STI          R0,*+FP(1)
.endblock    7
```

Syntax	**.file** *"filename"*

Description   The **.file** directive allows a debugger to map locations in memory back to lines in a C source file. The *filename* is the name of the file that contains the original C source program. The first 14 characters of the filename are significant.

You can also use the .file directive in assembly code to provide a name in the file and improve program readability.

Example   In the following example the file named text.c contained the C source that produced this directive.

```
.file       "text.c"
```

Syntax
.func *beginning line number*

.endfunc *ending line number*

Description
The **.func** and **.endfunc** directives specify the beginning and end of a C function. The *line numbers* are optional; they specify the location in the source file where the function is defined. Function definitions cannot be nested.

Example
Following is an example of C source that defines a function and the resulting assembly language code.

C source:

```
power(x, n)             /*  Beginning of a function   */
int x,n;
{
     int i, p;
     p = 1;
     for (i = 1; i <= n; ++i)
         p = p * x;
     return p;          /*  End of function           */
}
```

Resulting assembly language code:

```
 7                               .sym    _power,_power,36,2,0
 8                               .global _power
 9
10                               .func    2
11                       ****************************************************
12                       * FUNCTION DEF : _power
13                       ****************************************************
14   00000000          _power
15   00000000 0F2B0000          PUSH    FP
16   00000001 080B0014          LDI     SP,FP
17   00000002 02740001          ADDI    1,SP
18   00000003 0F240000          PUSH    R4
19                               .sym    _x,-2,4,9,32
20                               .sym    _n,-3,4,9,32
21                               .sym    _i,1,4,1,32
22                               .sym    _p,4,4,4,32
23   00000004                    .line   5
24   00000004 08640001          LDI     1,R4
25   00000005                    .LINE   6
26   00000005 15440301          STI     R4,*+FP(1)
27   00000006          L3:
28   00000006 08400301          LDI     *+FP(1),R0
29   00000007 04C00B03          CMPI    *+FP(3),R0
30   00000008 6A090008          BGT     L2
31   00000009                    .LINE   7
32   00000009 08000004          LDI     R4,R0
33   0000000A 08410B02          LDI     *-FP(2),R1
34   0000000B 62000000!         CALL    I_MULT
35   0000000C 08040000          LDI     R0,R4
36   0000000D 08410301          LDI     *+FP(1),R1
37   0000000E 02610001          ADDI    1,R1
38   0000000F 15410301          STI     R1,*+FP(1)
39   00000010 60000006+         BR      L3
40   00000011          L2:
41   00000011                    .LINE   8
42   00000011 08000004          LDI     R4,R0
43   00000012          EPI0_1:
44   00000012 0E240000          POP     R4
45   00000013 18740001          SUBI    1,SP
46   00000014 0E2B0000          POP     FP
47   00000015 78880000          RETS
48
49                               .endfunc 11
```

Syntax   **.line**   *line number* [, *address*]

Description   The **.line** directive creates a line number entry in the object file. Line number
                       entries are used in symbolic debugging to associate addresses in the object
                       code with the lines in the source code that generated them.

                       The .line directive has two operands:

                       ❏ *Line number* indicates the line of the C source that generated a portion of
                         code. Line numbers are relative to the beginning of the current function.
                         This is a required parameter.

                       ❏ *Address* is an expression that is the address associated with the line num-
                         ber. This is an optional parameter; if you don't specify an address, the
                         assembler will use the current SPC value.

Example   The .line directive is followed by the assembly language source statements
                       that are generated by the indicated line of C source. For example, assume that
                       the lines of C source below are line 4 and 5 in the original C source; lines 5 and
                       6 produce the assembly language source statements shown below.

                       C source:

```
for (i = 1; i <= n; ++i)
    p = p * x;
```

                       Resulting assembly language code:

```
23 00000004                       .line  5
24 00000004  08640001       LDI    1,R4
25 00000005                       .line  6
26 00000005  15440301       STI    R4,*+FP(1)
27 00000006          L3:
28 00000006  08400301       LDI    *+FP(1),R0
29 00000007  04C00B03       CMPI   *+FP(3),R)
30 00000008  6A090008       BGT    L2
31 00000009                       .line  7
32 00000009  08000004       LDI    R4,R0
33 0000000A  08410B02       LDI    *-FP(2),R1
34 0000000B  62000000!      CALL   I_MULT
35 0000000C  08040000       LDI    R0,R4
36 0000000D  08410301       LDI    *+FP(1),R1
37 0000000E  02610001       ADDI   1,R1
38 0000000F  15410301       STI    R1,*+FP(1)
39 00000010  60000006+      BR     L3
```

Syntax   **.member**   *name, value* [, *type, storage class, size, tag, dims*]

Description   The **.member** directive defines a member of a structure, union, or enumeration. It is valid only when it appears in a structure, union, or enumeration definition.

❑ *Name* is the name of the member that is put in the symbol table. The first 32 characters of the name are significant.

❑ *Value* is the value associated with the member. Any legal expression (absolute or relocatable) is acceptable.

❑ *Type* is the C type of the member. Appendix A contains more information about C types.

❑ *Storage class* is the C storage class of the member. Appendix A contains more information about C storage classes.

❑ *Size* is the number of bits of memory required to contain this member.

❑ *Tag* is the name of the type (if any) or structure of which this member is a type. This name *must* have been previously declared by a .stag, .etag, or .utag directive.

❑ *Dims* may be one to four expressions separated by commas. This allows up to four dimensions to be specified for the member.

The order of parameters is significant. *Name* and *value* are required parameters. All other parameters may be omitted or empty. (Adjacent commas indicate an empty entry.) This allows you to skip a parameter and specify a parameter that occurs later in the list. Operands that are omitted or empty assume a null value.

Example   Following is an example of a C structure definition and the corresponding assembly language statements:

C source:

```
struct doc {
      char   title;
      char   group;
      int    job_number;
}  doc_info;
```

Resulting assembly language code:

```
.stag    doc,48
.member  _title,0,2,8,8
.member  _group,8,2,8,8
.member  _job_number,16,4,8,32
.eos
```

Syntax

```
.stag   name [, size]
    member definitions
.eos
.etag   name [, size]
    member definitions
.eos
.utag   name [, size]
    member definitions
.eos
```

Description   The **.stag** directive begins a structure definition. The **.etag** directive begins an enumeration definition. The **.utag** directive begins a union definition. The **.eos** directive ends a structure, enumeration, or union definition.

❏ *Name* is the name of the structure, enumeration, or union. The first 32 characters of the name are significant. This is a required parameter.

❏ *Size* is the number of bits the structure, enumeration, or union occupies in memory. This is an optional parameter; if omitted, the size is unspecified.

The .stag, .etag, or .utag directive should be followed by a number of .member directives, which define members in the structure. The .member directive is the only directive that can appear inside a structure, enumeration, or union definition.

The assembler does not allow nested structures, enumerations, or unions. The C compiler unwinds nested structures by defining them separately and then referencing them from the structure they are referenced in.

Example 5   Following is an example of a structure definition.

C source:

```
struct doc
{
    char   title;
    char   group;
    int    job_number;
}  doc_info;
```

Resulting assembly language code:

```
.stag       _doc,96
.member     _title,0,2,8,32
.member     _group,32,2,8,32
.member     _job_number,64,4,8,32
.eos
```

Example 6   Following is an example of a union definition.

C source:

```
union u_tag {
      int    val1;
      float val2;
      char  valc;
}  valu;
```

Resulting assembly language code:

```
        .utag       _u_tag,96
        .member     _val1,0,2,8,32
        .member     _val2,32,4,8,32
        .member     _valc,64,4,8,32
        .eos
```

Example 7   Following is an example of an enumeration definition.

C Source:

```
{
    enum o_ty { reg_1, reg_2, result } optypes;
}
```

Resulting assembly language code:

```
        .etag       _o_ty,32
        .member     _reg_1,0,11,16,32
        .member     _reg_2,1,11,16,32
        .member     _result,2,11,16,32
        .eos
```

Syntax   **.sym** *name, value* [, *type, storage class, size, tag, dims*]

Description   The **.sym** directive specifies symbolic debug information about a global vari-
                         able, local variable, or a function.

❏ *Name* is the name of the variable that is put in the object symbol table. The
    first 32 characters of the name are significant.

❏ *Value* is the value associated with the variable. Any legal expression
    (absolute or relocatable) is acceptable.

❏ *Type* is the C type of the variable. Appendix A contains more information
    about C types.

❏ *Storage class* is the C storage class of the variable. Appendix A contains
    more information about C storage classes.

❏ *Size* is the number of words of memory required to contain this variable.

❏ *Tag* is the name of the type (if any) or structure of which this variable is a
    type. This name *must* have been previously declared by a .stag, .etag, or
    .utag directive.

❏ *Dims* may be up to four expressions separated by commas. This allows
    up to four dimensions to be specified for the variable.

The order of parameters is significant. *Name* and *value* are required parame-
ters. All other parameters may be omitted or empty (adjacent commas indicate
an empty entry). This allows you to skip a parameter and specify a parameter
that occurs later in the list. Operands that are omitted or empty assume a null
value.

Example   These lines of C source produce the .sym directives shown below:

C source:

```
struct s { int member1, member2; } str;
int    ext;
int    array[5][10];
long   *ptr;
int    strcmp();

main(arg1,arg2)
   int    arg1;
   char   *arg2;
{
   register r1;
}
```

Resulting assembly language code:

```
.sym    _str,_str,8,2,64,_s
.sym    _ext,_ext,4,2,32
.sym    _array,_array,244,2,1600,,5,10
.sym    _ptr,_ptr,21,2,32
.sym    _main,_main,36,2,0
.sym    _arg1,_arg1,-2,4,9,32
.sym    _arg2,_arg2,-3,18,9,32
.sym    _r1,4,4,4,32
```

Example Linker Command Files

This appendix contains examples of linker command files for the TMS320C10, TMS320C25, TMS320C50, and TMS320C51. These examples use the MEMORY directive to define memory according to the standard memory maps that are illustrated in the *TMS320C1x User's Guide*, the *TMS320C2x User's Guide,* and the *TMS320C5x User's Guide*. The MEMORY and SECTIONS directives in these examples are *guidelines*; you do not have to follow them exactly. For example, you can use different output section names, and you do not have to configure any memory you do not link code into (such as I/O memory). When possible, these examples allocate output sections into on-chip memory spaces; if the sections are too large for these spaces, you can allocate them into external memory.

These examples appear in this appendix:

Topic   **Page**

C.1 Linker Command Files for the TMS320C10

Example C–1. TMS320C10 in Microcomputer Mode

```
/**********************************************************************/
/*    MC/MP- = 1 (microcomputer mode). Note that program memory     */
/*    addresses 05F4h--05FFh are not configured.                    */
/**********************************************************************/
MEMORY
{
    PAGE 0 :                                      /* Program Memory */
        Int_Prog : origin =    0h , length = 05F4h
        Ext_Prog : origin = 0600h , length = 0A00h
    PAGE 1 :                                        /* Data Memory */
        pg0_Data : origin =    0h , length =  080h
        pg1_Data : origin =  080h , length =  010h
    PAGE 2 :                                         /* I/O Memory */
        ext_IO   : origin =    0h , length =   08h
}
SECTIONS
{
    .text :        > Int_Prog  PAGE = 0
    .data :        > Int_Prog  PAGE = 0
    .bss  :        > pg0_Data  PAGE = 1
}xmps
```

Example C–2. TMS320C10 in Microprocessor Mode

```
/**********************************************************************/
/*              MC/MP- = 0 (microprocessor mode).                   */
/**********************************************************************/
MEMORY
{
    PAGE 0 :                                      /* Program Memory */
        Ext_Prog : origin =    0h , length = 01000h
    PAGE 1 :                                        /* Data Memory */
        pg0_Data : origin =    0h , length =   080h
        pg1_Data : origin =  080h , length =   010h
    PAGE 2 :                                         /* I/O Memory */
        ext_IO   : origin =    0h , length =    08h
}
SECTIONS
{
    .text :        > Ext_Prog  PAGE = 0
    .data :        > Ext_Prog  PAGE = 0
    .bss  :        > pg0_Data  PAGE = 1
}
```

C.2 Linker Command Files for the TMS320C25

Example C–3. TMS320C25 in Microprocessor Mode, Block B0 as Data Memory

```
/**********************************************************************/
/*  Block B0 is configured as data memory (CNFP) and MC/MP- = 1    */
/*  (microprocessor mode). Note that data memory locations 6h--5Fh */
/*  and 80h--1FFh are not configured.                             */
/**********************************************************************/
MEMORY
{
    PAGE 0 :                                    /* Program Memory */
        Ints     : origin =    0h , length =   020h
        Ext_Prog : origin =  020h , length = 0FEE0h
    PAGE 1 :                                       /* Data Memory */
        Regs     : origin =    0h , length =   06h
        Block_B2 : origin =  060h , length =   020h
        Int_RAM  : origin = 0200h , length =  0200h   /* B0 & B1 */
        Ext_Data : origin = 0400h , length = 0FC00h
}
SECTIONS
{
    .text :        > Ext_Prog  PAGE = 0
    .data :        > Ext_Prog  PAGE = 0
    .bss  :        > Int_RAM   PAGE = 1
}
```

Example C–4. TMS320C25 in Microcomputer Mode, Block B0 as Data Memory

```
/**********************************************************************/
/* Block B0 is defined as data memory (CNFP) and MC/MP- = 0 (micro-*/
/* computer mode). Note: program memory locations 0FB0h--0FFFh &   */
/* data memory locations 6h--5Fh and 80h--1FFh are not configured. */
/**********************************************************************/
MEMORY
{
    PAGE 0 :                                    /* Program Memory */
        Ints     : origin =    0h , length =   020h
        Prog_RAM : origin =  020h , length =  0F90h
        Ext_Prog : origin = 1000h , length = 0F000h
    PAGE 1 :                                       /* Data Memory */
        Regs     : origin =    0h , length =   06h
        Block_B2 : origin =  060h , length =   020h
        Int_RAM  : origin = 0200h , length =  0200h   /* B0 & B1 */
        Ext_Data : origin = 0400h , length = 0FC00h
}
SECTIONS
{
    .text :        > Prog_ROM  PAGE = 0
    .data :        > Prog_ROM  PAGE = 0
    .bss  :        > Int_RAM   PAGE = 1
}
```

Example C–5.   TMS320C25 in Microprocessor Mode, Block B0 as Program Memory

```
/********************************************************************/
/*   Block B0 is defined as program memory (CNFP) and MC/MP- = 1    */
/*   (microprocessor mode). Note that data memory locations 6h--5Fh */
/*   and 80h--2FFh are not configured.                              */
/********************************************************************/
MEMORY
{
    PAGE 0 :                                      /* Program Memory */
         Ints    : origin =     0h , length =   020h
         Ext_Prog : origin =    020h , length = 0FEE0h
         Block_B0 : origin = 0FF00h , length =  0100h
    PAGE 1 :                                      /* Data Memory */
         Regs    : origin =     0h , length =     06h
         Block_B2 : origin =   060h , length =   020h
         Block_B1 : origin =  0300h , length =  0100h
         Ext_Data : origin =  0400h , length = 0FC00h
}
SECTIONS
{
    .text :        > Block_B0  PAGE = 0
    .data :        > Ext_Prog  PAGE = 0
    .bss  :        > Block_B1  PAGE = 1
}
```

Example C–6.   TMS320C25 in Microcomputer Mode, Block B0 as Program Memory

```
/********************************************************************/
/* Block B0 is defined as program memory (CNFP) and MC/MP- = 0      */
/* microcomputer mode). Program memory locations 0FB0h--0FFFh &     */
/* data memory locations 6h--5Fh and 80h--2FFh are not configured. */
/********************************************************************/
MEMORY
{
    PAGE 0 :                                      /* Program Memory */
         Ints     : origin =     0h , length =   020h
         Prog_ROM : origin =   020h , length =  0F90h
         Ext_Prog : origin =  1000h , length = 0EF00h
         Block_B0 : origin = 0FF00h , length =  0100h
    PAGE 1 :                                      /* Data Memory */
         Regs     : origin =     0h , length =     06h
         Block_B2 : origin =   060h , length =   020h
         Block_B1 : origin =  0300h , length =  0100h
         Ext_Data : origin =  0400h , length = 0FC00h
}
SECTIONS
{
    .text :        > Prog_ROM  PAGE = 0
    .data :        > Block_B0  PAGE = 0
    .bss  :        > Block_B1  PAGE = 1
}
```

C.3 Linker Command Files for the TMS320C50

Example C–7. TMS320C50 in Microcomputer Mode, Block B0 as Data Memory

```
/*******************************************************************/
/* TMS320C50 in Microcomputer Mode            MC/MP– = 1        */
/* 9K RAM block mapped into program space      RAM, OVLY BITS = 1, 0 */
/* B0 configured as data memory               ST1 – CNF BIT = 0    */
/*******************************************************************/
MEMORY
{
    PAGE 0 :                                    /* Program Memory */
        Prog_ROM     : origin =     0h , length =   800h
        Prog_RAM     : origin =   800h , length =  2400h /* 9k RAM */
        Ext_Prog     : origin =  2C00h , length = 0C400h
    PAGE 1 :                                    /* Data Memory */
        Regs         : origin =     0h , length =    60h
        Scratch_RAM  : origin =    60h , length =    20h /* B2     */
        Int_RAM      : origin =   100h , length =   400h /* B0 & B1*/
        Ext_Data     : origin =   800h , length =  F800h
}
SECTIONS
{
    .text :        > Prog_ROM  PAGE = 0
    .data :        > Prog_ROM  PAGE = 0
    .bss  :        > Int_RAM   PAGE = 1
}
```

Example C–8. TMS320C50 in Microprocessor Mode, Block B0 as Data Memory

```
/*******************************************************************/
/* TMS320C50 in Microprocessor Mode           MC/MP = 0        */
/* 9K RAM block mapped into program space      RAM, OVLY BITS = 1, 0 */
/* B0 configured as data memory               ST1 – CNF BIT = 0    */
/*******************************************************************/
MEMORY
{
    PAGE 0 :                                    /* Program Memory */
        Ext_Prog     : origin =     0h , length = 10000h
    PAGE 1 :                                    /* Data Memory */
        Regs         : origin =     0h , length =    60h
        Scratch_RAM  : origin =    60h , length =    20h /* B2     */
        Int_RAM      : origin =   100h , length =   400h /* B0 & B1*/
        Ext_RAM      : origin =   800h , length =  F800h
}
SECTIONS
{
    .text :        > Ext_Prog  PAGE = 0
    .data :        > Ext_Prog  PAGE = 0
    .bss  :        > Int_RAM   PAGE = 1
}
```

Example C–9. TMS320C50 in Microcomputer Mode, Block B0 as Program Memory

```
/*******************************************************************/
/* TMS320C50 in Microcomputer Mode          MC/MP = 1           */
/* 9K RAM block mapped into data space       RAM, OVLY BITS = 0, 1 */
/* B0 configured as program memory           ST1  – CNF BIT = 1    */
/*******************************************************************/
MEMORY
{
    PAGE 0 :                                    /* Program Memory */
        Prog_ROM     : origin =    0h , length =  800h
        Ext_Prog     : origin =  800h , length = F600h
        Int_Prog     : origin = FE00h , length =  200h  /* B0     */
    PAGE 1 :                                    /* Data Memory */
        Regs         : origin =    0h , length =   60h
        Scratch_RAM  : origin =   60h , length =   20h  /* B2     */
        Int_RAM      : origin =  100h , length =  200h  /* B1     */
        Data_RAM     : origin =  800h , length = 2400h  /* 9K RAM */
        Ext_RAM      : origin = 2C00h , length = D400h
}
SECTIONS
{
    .text :       > Prog_ROM  PAGE = 0
    .data :       > Prog_ROM  PAGE = 0
    .bss  :       > Int_RAM   PAGE = 1
}
```

C.4 Linker Command Files for the TMS320C51

Example C–10. TMS320C51 in Microcomputer Mode, Block B0 as Data Memory

```
/******************************************************************/
/* TMS320C51 in Microprocessor Mode          MC/MP = 0          */
/* 1K RAM block mapped into program space    RAM, OVLY BITS = 1, 0 */
/* B0 configured as data memory              ST1  - CNF BIT = 0   */
/******************************************************************/
MEMORY
{
    PAGE 0 :                                    /* Program Memory */
        Prog_ROM     : origin =    0h , length = 2000h  /* 8k ROM */
        Prog_RAM     : origin = 2000h , length =  400h  /* 1k RAM */
        Ext_Prog     : origin = 2400h , length = DC00h
    PAGE 1 :                                    /* Data Memory */
        Regs         : origin =    0h , length =   60h
        Scratch_RAM  : origin =   60h , length =   20h  /* B2      */
        Int_RAM      : origin =  100h , length =  400h  /* B0 & B1*/
        Ext_RAM      : origin =  800h , length = F800h
}
SECTIONS
{
    .text :         > Prog_ROM  PAGE = 0
    .data :         > Prog_ROM  PAGE = 0
    .bss  :         > Int_RAM   PAGE = 1
}
```

Example C–11. TMS320C51 in Microcomputer Mode, Block B0 as Program Memory

```
/******************************************************************/
/* TMS320C51 in Microcomputer Mode          MC/MP = 1          */
/* 1K RAM block mapped into data space       RAM, OVLY BITS = 0, 1 */
/* B0 configured as program memory                               */
/******************************************************************/
MEMORY
{
    PAGE 0 :                                    /* Program Memory */
        Ext_Prog     : origin =   00h , length = FE00h
        Int_Prog     : origin = FE00h , length =  200h  /* B0     */
    PAGE 1 :                                    /* Data Memory */
        Regs         : origin =    0h , length =   60h
        Scratch_RAM  : origin =   60h , length =   20h  /* B2     */
        Int_RAM      : origin =  100h , length =  200h  /* B1     */
        Data_RAM     : origin =  800h , length =  400h  / 1k RAM  */
        Ext_RAM      : origin = 0C00h , length = F400h
}
SECTIONS
{
    .text :         > Prog_ROM  PAGE = 0
    .data :         > Prog_ROM  PAGE = 0
    .bss  :         > Int_RAM   PAGE = 1
}
```

Hex Conversion Utility Examples

The flexible hex conversion utility offers many options and capabilities. Once you understand the proper ways to configure the EPROM system and the requirements of the EPROM programmer, you will find that converting a file for a specific application is easy.

The four major examples in this appendix show how to develop a hex command file for several EPROM memory systems, avoid holes, and generate boot tables. The examples use the assembly code shown in Example D–1.

Example D–1. Assembly Code for Hex Conversion Utility Examples

```
*********************************************************
* Assemble two words into section, "sec1"              *
*********************************************************

        .sect "sec1"
        .word 1234h
        .word 5678h

*********************************************************
* Assemble two words into section, "sec2"              *
*********************************************************

        .sect "sec2"
        .word 0aabbh
        .word 0ccddh

        .end
```

D.1 Example 1: Building A Hex Command File for Two 8-Bit EPROMs

Example 1 shows how to build the hex command file you need for converting a COFF object file for the memory system shown in Figure D–1. In this system, there are two external 64K $\times$ 8-bit EPROMs interfacing with a 'C2x or 'C5x target processor. Each of the EPROMs contributes 8 bits of a 16-bit word for the target processor.

Figure D–1.A Two 8-Bit EPROM System
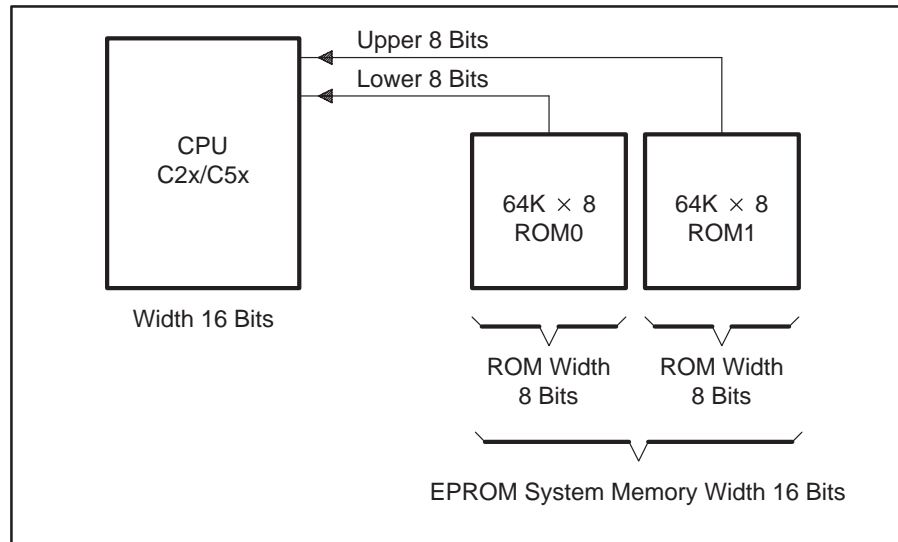
By default, the hex conversion utility uses the linker load address as the base for generating addresses in the converted output file. However, for this application, the code will reside at physical EPROM address 0x0010, rather than the address specified by the linker (0xF000). The circuitry of the target board handles the translation of this address space. The paddr parameter allocates a section and burns the code at EPROM address 0x0010.

The paddr parameter is specified within the SECTIONS directive (see Section 11.6, page 11-20, for details.). If you use the paddr parameter to specify a load address for one section included in the conversion, then you must specify a paddr for each section included in the conversion. When setting the paddr parameter, you must ensure that the specified addresses do not overlap the linker-assigned load addresses of sections that follow.

In Example 1, two sections are defined: sec1 and sec2. You can easily add a paddr option for each of these sections from within the SECTIONS directive. However, the task may become unmanageable for large applications with many sections, or in cases where section sizes may change often during code development.

To work around this problem, you can combine the sections at link stage, creating a single section for conversion. To do this, use the linker command shown in Example D–2.

Example D–2. A Linker Command File for Two 8-Bit EPROMs

```
test.obj
–o a.out
–m test.map

MEMORY
{
    PAGE 0 : EXT_PRG ; org = 0xF000 , len = 0x0100
}

SECTIONS
{
    outsec: { *(sec1)
              *(sec2)  } > EXT_PRG PAGE 0
}
```

The EPROM programmer in this example has the following system requirements:

❑ EPROM system memory width must be 16 bits.

❑ ROM1 contains the upper 8 bits of a word.

❑ ROM0 contains the lower 8 bits of a word.

❑ The hex conversion utility must locate code starting at EPROM address 0x0010.

❑ Intel format must be used.

❑ Byte increment must be selected for addresses in the hex conversion utility output file (memory width is the default).

Use the following options to select the requirements of the system:

Option	Description
–i	Create Intel format
–byte	Select byte increment for addresses in converted output file
–memwidth 16	Set EPROM system memory width to 16
–romwidth 8	Set physical ROM width to 8

With the memory width and ROM width values above, the utility will automatically generate two output files. The ratio of memory width to ROM width determines the number of output files. The ROM0 file contains the lower 8 of the 16 bits of raw data, and the ROM1 file contains the upper 8 bits of the corresponding data.

Example D–3 shows the hex command file with all of the selected options.

Example D–3.   A Hex Command File for Two 8-Bit EPROMs

```
a.out               /* COFF object input file          */
–map examp1.mxp

/*******************************************************/
/* Set parameters for EPROM programmer                 */
/*******************************************************/

–i                  /* Select Intel format             */
–byte               /* Select byte increment for addresses */

/*******************************************************/
/* Set options required to describe EPROM memory system  */
/*******************************************************/

–memwidth 16        /* Set EPROM system memory width     */
–romwidth  8        /* Set physical width of ROM device   */

ROMS
{
   PAGE 0 : EPROM : origin = 0x00, length = 0x10000,
                    files = {low8.bit, upp8.bit}
}

SECTIONS
{  outsec: paddr=0x10  }
```

Figure D–2 (a) shows the contents of the converted file for ROM0 (low8.bit) containing the lower 8 bits. Figure D–2 (b) shows the contents of the converted file for ROM1 (upp8.bit) containing the upper 8 bits of data.

Figure D–2.Data From Output File

(a) low8.bit(Lower Bits)

Data from converted output file

```
:040010003478BBDDA8
:00000001FF
```

Corresponding Map in EPROM — ROM0 (See Example D–1)

	. . .
	. . .
	. . .
0x0010	34
	78
	BB
	DD
	. . .
	. . .
	. . .
	. . .

(b) upp8.bit (Upper Bits)

Data from converted output file

```
:040010001256AACC0E
:00000001FF
```

Corresponding Map in EPROM — ROM1 (See Example D–1)

	. . .
	. . .
	. . .
0x0010	12
	56
	AA
	CC
	. . .
	. . .
	. . .
	. . .
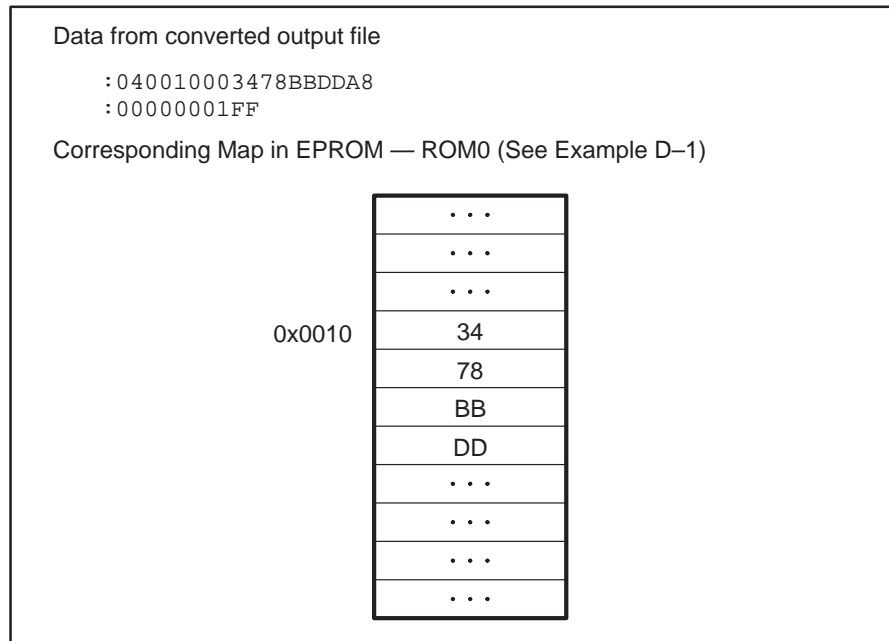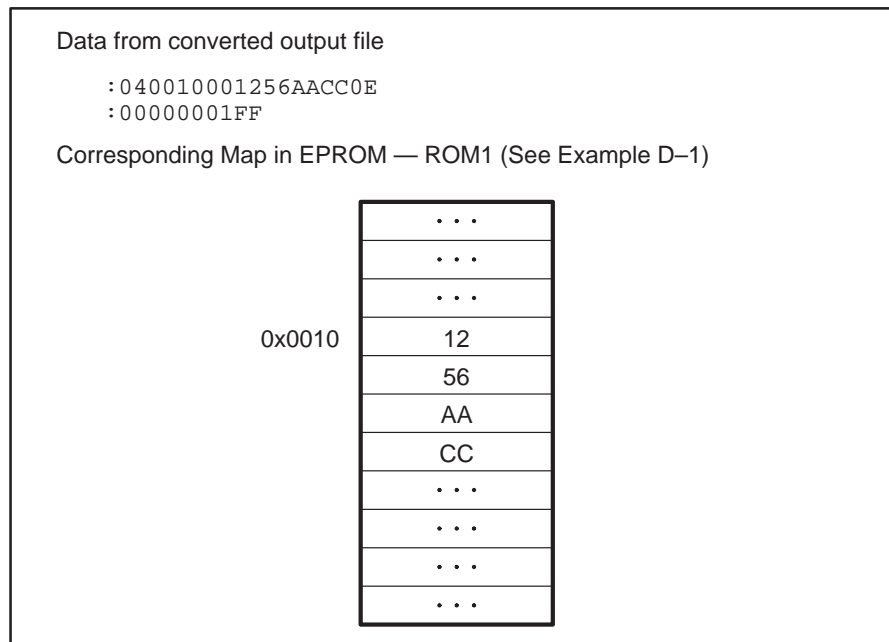
To illustrate precisely how the utility performs the conversion, specify the –map option. Although not required, the –map option generates useful information about the output. The resulting map is shown in Example D–4.

Example D–4. Map File Resulting From Hex Command File in Example D–3

```
***********************************************************************
TMS320C1x/C2x/C2xx/C5x Hex Converter                    Version x.xx
***********************************************************************
Fri Feb  3 15:26:11 1995

INPUT FILE NAME: <a.out>
OUTPUT FORMAT:   Intel

PHYSICAL MEMORY PARAMETERS
   Default data width:    16
   Default memory width:  16
   Default output width: 8

OUTPUT TRANSLATION MAP
****************************************-----------------
00000000..0000FFFF  Page=0  ROM Width=8  Memory Width=16  "EPROM"
****************************************-----------------
   OUTPUT FILES: low8.bit [b0..b7]
                 upp8.bit [b8..b15]

   CONTENTS: 00000010..00000013  Data Width=2  outsec
```

D.2 Example 2: Avoiding Holes With Multiple Sections

When the memory width is less than the data width, holes may appear at the beginning of a section or between sections. This is due to multiplication of the load address by a correction factor. See Section 11.10, page 11-34 for more information.

You must eliminate the holes between converted sections. The sections can be made contiguous in one of two ways:

❏ Specify a *paddr* for each section listed in a SECTIONS directive. This forces the hex conversion utility to use that specific address for the output file address field. You must ensure that the section addresses do not overlap. Example D–5 shows a linker command file for this method. The linker should be executed with this command file; then, the hex conversion utility should be executed with the set of commands shown in Example D–6.

❏ Link the sections together into one output section for conversion. Example D–7 shows a linker command file for this method. The linker should be executed with this command file; then, the hex conversion utility should be executed with the set of commands shown in Example D–8.

Example D–5. Linker Command File: Method One for Avoiding Holes

```
/* SPECIFY THE SYSTEM MEMORY MAP */

MEMORY
{
   PAGE 0: PRG: org = 0x0800, len = 0x0100
           EXT: org = 0xF000, len = 0x0100
}

/* SPECIFY THE SECTIONS ALLOCATION INTO MEMORY */

SECTIONS
{
   sec1 : load = EXT PAGE 0
   sec2 : load = EXT PAGE 0, run = PRG PAGE 0
}
```

Example D–6.   Hex Command File: Method One for Avoiding Holes

```
 –i
 a.out
 –map example.mxp

 ROMS
 {
  PAGE 0: ROM : org = 0x0000, length = 0x800, romwidth = 8, memwidth = 8
 }

 SECTIONS
 {
   sec1 : paddr = 0x0000
   sec2 : paddr = 0x0004
 }
```

Example D–7.   Linker Command File: Method Two for Avoiding Holes

```
* SPECIFY THE SYSTEM MEMORY MAP

MEMORY
{
  PAGE 0: PRG: org = 0x0800, len = 0x0100
          EXT : org = 0xF000, len = 0x0100
}

/* SPECIFY THE SECTIONS ALLOCATION INTO MEMORY

SECTIONS
{
  outsec : {  *(sec1)
              *(sec2) } > EXT PAGE 0
}
```

Example D–8.   Hex Command File: Method Two for Avoiding Holes

```
 –i
 a.out
 –map example.mxp

 ROMS
 {
  PAGE 0: ROM : org = 0x0100, length = 0x0800, romwidth = 8, memwidth = 8,
              files = {example.hex}
 }

 SECTIONS
 {
   outsec : paddr = 0x100
 }
```

D.3 Example 3: Generating a Boot Table for a 'C50

Example 3 shows how to use the linker and the hex conversion utility to build a boot load table for a 'C50. The assembly code used in this section is shown in Example D–1 on page D-1.

Example D–9. C Code for a 'C50

```
int array[]={1,2,3,4};

main()
{
  array[0] = 5;
}
```

Figure D–3 shows the EPROM memory system for which the output file will be generated. In this application, the single 'C50 device is booted from a 128K $\times$ 8-bit EPROM. The requirements of the system are that the boot table must reside at EPROM memory address 0.

Figure D–3.EPROM System for a 'C50
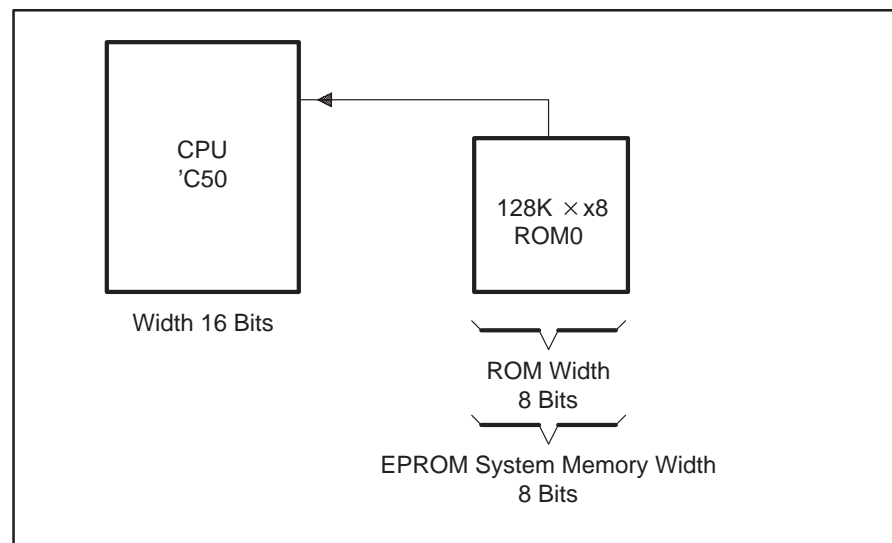
Two concerns should be addressed when the boot table is generated for the 'C50:

❑ Linking required sections for boot load

❑ Formation and placement of the boot routine selection word

Linking Required Sections for Boot Load

The on-chip boot loader loads only a single block. This may present a problem when you are loading C code compiled with the TMS320C2x/C2xx/C5x C compiler. The TMS320C2x/C2xx/C5x C compiler creates several sections or blocks when it compiles C source code. Some applications may require that all sections associated with the program be included in the boot to have a complete executable program. In this case, the individual sections must be combined into a single section for boot.

The hex conversion utility does not combine individual sections; therefore, you must use the linker to group those sections.

The sections that the compiler creates are divided into two categories: initialized sections (sections that contain data or code) and uninitialized sections (sections that reserve space but contain no actual data). Initialized sections created by the TMS320C2x/C2xx/C5x C compiler include .text, .cinit, .const, and .data. Uninitialized sections are ignored by the hex conversion utility and are not converted.

Most applications require that .text and .cinit sections are included in the boot. This allows code and information for the C boot routine (c_int0 defined in boot.asm) to load and run, initializing the C environment and branching to the main function in the applications code.

The .text and .cinit sections must be linked together as a single section in the linker command file. The .cinit section contains the initialization data and tables for all global or static C symbols that were declared with an initial value (i.e. int x = 5;). Note that the linker handles the .cinit section differently than the other sections.

When the linker encounters a .cinit section specified as an *output section* in the link, it automatically:

❑ Sets the symbol cinit to point to the start of the included .cinit section

❑ Appends a single word to the end of the section

This last word contains a zero that is used to mark the end of the initialization table. However, if .cinit is included as an *input section* only, the linker sets cinit to –1, indicating that no initialization tables were loaded. Therefore, the C boot routine, c_int0, does not attempt to initialize any of the global or static C symbols.

When linking the .cinit section into an output section other than .cinit, the linker does not perform the automatic functions listed above. Therefore, these functions must be implemented explicitly within the linker command file. Example D–10 on page D-12 shows a linker command file that places .text and .cinit into a single output section named boot_sec.

Example D–10. Linker Command File to Form a Single Boot Section for a 'C50

```
 c
−l rts50.lib
−m map
−o a.out

MEMORY
{
  PAGE 0 : PROG   : origin = 0x0800h, length = 0x1000h

  PAGE 1 : DATA   : origin = 0x0800h, length = 0x1000h
}

SECTIONS
{
  boot_sec: { *(.text)

              /**************************************/
              /* Set start address for C init table */
              /**************************************/
                 cinit = .;

              /**************************************/
              /* Include all cinit sections        */
              /**************************************/
                 *(.cinit)

              /**************************************/
              /* Reserve a single space for the zero */
              /* word to mark end of C init          */
              /**************************************/
                 .+=1;

    } fill = 0x0000,   /* Make sure fill value is 0 */
      load = PROG PAGE 0

  .data   : {} > DATA    PAGE 1
  .bss    : {} > DATA    PAGE 1
  .const  : {} > DATA    PAGE 1
  .sysmem : {} > DATA    PAGE 1
  .stack  : {} > DATA    PAGE 1
}
```

Example D–11 shows a portion of the map file generated when the linker is executed with the command file in Example D–10.

Example D–11. Section Allocation Portion of Map File Resulting From the Command File
in Example D–10

```
    SECTION ALLOCATION MAP

 output                                    attributes/
 section   page    origin      length      input sections
 --------  ----  ----------  ----------   ----------------
 boot_sec   0    00000800    00000076
                 00000800    00000004     test1.obj (.text)
                 00000804    0000002a     rts50.lib : boot.obj (.text)
                 0000082e    00000041               : exit.obj (.text)
                 0000086f    00000003     test1.obj (.cinit)
                 00000872    00000003     rts50.lib : exit.obj (.cinit)
                 00000875    00000001     --HOLE-- [fill = 0000]

 .data      1    00000800    00000000     UNINITIALIZED
                 00000800    00000000     test1.obj (.data)
                 00000800    00000000     rts50.lib : exit.obj (.data)
                 00000800    00000000               : boot.obj (.data)

 .bss       1    00000800    00000022     UNINITIALIZED
                 00000800    00000021     rts50.lib : exit.obj (.bss)
                 00000821    00000000               : boot.obj (.bss)
                 00000821    00000001     test1.obj (.bss)

 .const     1    00000800    00000000     UNINITIALIZED

 .sysmem    1    00000800    00000000     UNINITIALIZED

 .stack     1    00000822    00000400     UNINITIALIZED
                 00000822    00000000     rts50.lib : boot.obj (.stack)


 GLOBAL SYMBOLS

 address  name                            address  name
 -------- ----                            -------- ----
 00000800 .bss                            00000400 __STACK_SIZE
 00000800 .data                           00000800 edata
 00000400 __STACK_SIZE                    00000800 .bss
 00000869 _abort                          00000800 .data
 00000848 _atexit                         00000800 _main
 00000804 _c_int0                         00000804 _c_int0
 0000082e _exit                           00000821 _flag
 00000821 _flag                           00000822 end
 00000800 _main                           0000082e _exit
 0000086f cinit                           00000848 _atexit
 00000800 edata                           00000869 _abort
 00000822 end                             0000086f cinit
```

Notice that the linker placed a hole at the end of the section boot_sec with a fill value of zero, as specified in the command file. Also, the global symbol cinit coincides with the start of the first .cinit section included in the link. When the linker is executed with the command file in Example D–10, the linker issues warnings that the output file contains no .text section and that the global symbol cinit is being redefined. These warnings may be ignored in this instance.

Formation and Placement of the Boot Routine Selection Word

The boot routine selection word determines the mode in which the on-chip boot loader operates. The on-chip boot loader reads this word from location 0xFFFF in program memory. For this 'C50 application, the on-chip boot loader must operate in 8-bit parallel EPROM mode. (For more detailed information about the on-chip boot loader and the boot routine selection word, refer to the *TMS320C5x User's Guide.*)

The hex conversion utility does not automatically generate and place the boot routine selection word. Therefore, you must make sure that the correct value is placed in the correct memory address. For this 'C50 boot table the linker command file in Example D–12 performs this task.

Example D–12. Linker Command for Setting the Boot Routine Selection Word for a 'C50

```
-c  -l rts50.lib  -m map  -o a.out

MEMORY
{
  PAGE 0 : PROG   : origin = 0x0800, length = 0x1000
  PAGE 0 : BRSW   : origin = 0xffff, length = 0x0001
  PAGE 1 : DATA   : origin = 0x0800, length = 0x1000
}

SECTIONS
{
  boot_sec: { *(.text)

    cinit = .;  /* Set start address for C init table. */


    *(.cinit)   /* Include all cinit sections.          */

                /**************************************/
    .+=1;       /* Reserve a single space for the zero */
                /* word to mark end of C init.        */
                /**************************************/


    } fill = 0x0000,    /* Make sure fill value is 0  */
      load = PROG PAGE 0

                /**************************************/
                /* Create a single word section that   */
  .brsw   : {   /* contains the proper fill value for  */
                /* the needed boot routine select mode */
                /**************************************/

    .+=1;       /* Reserve a word in this section.    */

                /**************************************/
                /* Select fill value that corresponds  */
                /* to correct boot routine select mode */
                /**************************************/

      } fill = 0x0001,
        load = 0xffff PAGE 0

  .data   : {} > DATA    PAGE 1
  .bss    : {} > DATA    PAGE 1
  .const  : {} > DATA    PAGE 1
  .sysmem : {} > DATA    PAGE 1
  .stack  : {} > DATA    PAGE 1
}
```

The command file in Example D–12 on page D-15 creates a new section called .brsw that contains a single word whose value equals 0x0001. This corresponds to a boot routine selection mode for 8-bit parallel EPROM mode and a source address of 0x0000.

Executing the linker with the command file in Example D–12 yields a COFF file that can be used as input to the hex conversion utility to build the desired boot table.

Options

The hex conversion utility has options that describe the requirements for the EPROM programmer and options that describe the EPROM memory system. For Example 3, assume that the EPROM programmer has only one requirement: that the hex file be in Intel format.

In the EPROM memory system illustrated in Figure D–3 on page D-10, the EPROM system memory width is 8 bits, and the physical ROM width is 8 bits. The following options are selected to reflect the requirements of the system:

Option	Description
`-i`	Create Intel format
`-memwidth 8`	Set EPROM system memory width to 8
`-romwidth 8`	Set physical ROM width to 8

Because the application requires the building of a boot table for parallel boot mode, the following options must be selected as well:

Option	Description
`-boot`	Create a boot load table
`-bootorg 0x0000`	Place boot table at address 0x0000

Because two sections must be loaded, boot_sec and .brsw, and only one of these sections is included in the boot table, you must use a hex command file to specify which sections are bootable.

You must use a ROMS directive to specify the address range for the boot table in physical ROM. Example D–13 depicts the complete command file needed to convert the COFF file.

Example D–13. Hex Command File for Converting a COFF File

```
a.out                   /* Input COFF file            */
-i                      /* Select Intel Format        */
-map boot.mxp
-o boot.hex             /* Name hex output file boot.hex */

-memwidth 8             /* Set EPROM System Memory Width */
-romwidth 8             /* Set physical ROM width      */

-boot                   /* Build a boot table          */
-bootorg 0x0000         /* Place boot table in EPROM   */
                        /* starting at address 0x0000  */




ROMS
{
    PAGE 0 : ROM : origin = 0x0000, length = 0x20000
}


SECTIONS
{
   boot_sec : paddr=boot
   .brsw    : paddr=0x1fffe
}
```

The paddr option overrides the linked section address for a given section. Because the system memory width is 8 bits, the address space is expanded by a factor of 2 (data width divided by memory width). So the address for allocating the .brsw section is multiplied by a factor of 2: 0xFFFF * 2 –> 0x1FFFE.

In Example 3, memory width and ROM width are the same; therefore, the hex conversion utility creates a single output file. The number of output files is determined by the ratio of memwidth to romwidth.

Example D–14 on page D-18 shows the map file boot.map, resulting from executing the command file in Example D–13, which includes the –map option.

Example D–14. Map File Resulting From the Command File in Example D–13

```
  **************************************************************************
  TMS320C1x/C2x/C2xx/C5x Hex Converter                        Version x.xx
  **************************************************************************
  Wed Feb  1 10:36:16 1995

  INPUT FILE NAME: <a.out>
  OUTPUT FORMAT:   Intel

  PHYSICAL MEMORY PARAMETERS
     Default data width:    16
     Default memory width:  8 (MS-->LS)
     Default output width: 8

  BOOT LOADER PARAMETERS
     Table Address: 0000, PAGE 0


  OUTPUT TRANSLATION MAP
  ------------------------------------------------------
  00000000..0001ffff  Page=0  ROM Width=8  Memory Width=8  "ROM"
  ------------------------------------------------------
     OUTPUT FILES: boot.hex [b0..b7]

     CONTENTS: 00000000..0000000f   BOOT TABLE
                                    .text : dest=00000800
                                     size=00000002  width=00000002
               0001fffe..0001ffff  Data Width=2  .brsw
```

The hex output file boot.hex, resulting from the command file in Example D–13, is shown in Example D–15.

Example D–15. Hex Conversion Utility Output File Resulting From the Command File in Example D–13

```
:2000000008000075B901BC109021EF00BF080822BF090822BE42BF00BC005E07FFF9BE477D
:20002000BF80086FB801E38808157A8908197A8908007A890869BF80086FBC00A680B801D5
:20004000028A7B990822EF0089090012A680B801028ABEC6082BA6A0B8018B007989081C71
:2000600080A08AA08180B00100E086AEBC1006007B80083A798008468B9886801080BF9012
:2000800008019080058D1089BE308B8E7B80083A7980084680A08180B00100E0BE47BC100E
:2000A0001000BA20E34408567D800865B9018B001000B8019000BA01BF9008018B88908093
:2000C000058ABF0AFFFE8BE0108D9080B9008B897C020080EF007E80082EB90190A08B90C0
:1000E000EF0000010821000000010800000000000EE
:00000001FF
```

D.4 Example 4: Generating a Boot Table for a 'C26

Example 4 shows how to use the linker and hex conversion utility to build a boot load table for the 'C26. The assembly code used in this section is shown in Example D–1 on page D-1.

Example D–16. C Code for a 'C26

```
int array[]={1,2,3,4};

main()
{
  array[0] = 5;
}
```

For this application, assume that there are two 'C26 devices in the system. One device acts as the parent processor and boots the second processor, referred to as the child processor, via the child's I/O port. The boot table containing the applications code for the child processor is stored in an external EPROM connected to the parent, as shown in Figure D–4.

Figure D–4. Sample EPROM System for a 'C26

Parent
CPU
'C26

Child
CPU
'C26

Parallel
Port
PA0

64K × 16
ROM0

ROM Width
16 Bits

EPROM System Memory Width
16 Bits

When you link the code, there may be some question about what address to use as the load address for the bootable sections. Since the code in bootable sections is loaded via the parallel port, then only one address must be specified for the link: the final address where the code will reside in the child processor. The on-chip boot loader initially downloads to block B0, which starts at data memory address 0x0200; however, once the code is loaded, block B0 is configured as program memory. Control is then transferred to the first location in block B0 in program memory at address 0x0FA00. This is where the code will be executed from, so this is the address to which it should be linked.

As Example D–17 on page D-20 shows, the bootable code has been allocated into a single section by the linker, as described in Section D.3.

Example D–17. Linker Command File for 'C26 With Parent and Child CPUs

```
-c
-l rts25.lib
-m map

MEMORY
{
   PAGE 0 : PRG_B0 : org = 0xFA00 , length = 0x0100
   PAGE 1 : EXT: org = 0x0800 , length = 0x1000
}

SECTIONS
{
   boot_sec:{ *(.text)

             cinit = .;
             *(.cinit)
             .+=1;

            } fill = 0,
                *************************************
                /* Set run address for boot section */
                *************************************
             load = PRG_B0 PAGE 0

   .bss : {} > EXTPAGE 1
   .sysmem : {} > EXTPAGE 1
   .stack  : {} > EXTPAGE 1
}
```

Example D–18 shows a portion of the map file generated when the linker is executed with the command file in Example D–17.

Example D–18. Section Allocation Portion of Map File Resulting From the Command File in Example D–17

```
      SECTION ALLOCATION MAP

 output                                    attributes/
 section    page    origin       length    input sections
 --------   ----   ----------   ----------  ----------------
 boot_sec    0     0000fa00     00000072
                   0000fa00     00000004    test1.obj (.text)
                   0000fa04     00000027    rts25.lib : boot.obj (.text)
                   0000fa2b     00000040            : exit.obj (.text)
                   0000fa6b     00000003    test1.obj (.cinit)
                   0000fa6e     00000003    rts25.lib : exit.obj (.cinit)
                   0000fa71     00000001    --HOLE-- [fill = 0000]

 .bss        1     00000800     00000022    UNINITIALIZED
                   00000800     00000021    rts25.lib : exit.obj (.bss)
                   00000821     00000000            : boot.obj (.bss)
                   00000821     00000001    test1.obj (.bss)

 .sysmem     1     00000800     00000000    UNINITIALIZED

 .stack      1     00000822     00000400    UNINITIALIZED
                   00000822     00000000    rts25.lib : boot.obj (.stack)

 .data       1     00000000     00000000    UNINITIALIZED
                   00000000     00000000    test1.obj (.data)
                   00000000     00000000    rts25.lib : exit.obj (.data)
                   00000000     00000000            : boot.obj (.data)

 GLOBAL SYMBOLS

 address  name                             address  name
 --------  ----                            --------  ----
 00000800 .bss                             00000000 edata
 00000000 .data                            00000000 .data
 00000400 __STACK_SIZE                     00000400 __STACK_SIZE
 0000fa65 _abort                           00000800 .bss
 0000fa45 _atexit                          00000821 _flag
 0000fa04 _c_int0                          00000822 end
 0000fa2b _exit                            0000fa00 _main
 00000821 _flag                            0000fa04 _c_int0
 0000fa00 _main                            0000fa2b _exit
 0000fa6b cinit                            0000fa45 _atexit
 00000000 edata                            0000fa65 _abort
 00000822 end                              0000fa6b cinit

 [12 symbols]
```

Executing the linker with the command file in Example D–17 yields a COFF file that can be used as input to the hex conversion utility to build the desired boot table.

Options

The hex conversion utility has options that describe the requirements for the EPROM programmer and options that describe the EPROM memory system. For Example 4, assume the EPROM programmer has only one requirement: that the hex file be in Intel format.

In the EPROM memory system illustrated in Figure D–4 on page D-19, the EPROM system memory width is 16 bits, and the physical ROM width is 16 bits. The following options are selected to reflect the requirements of the system:

Option	Description
–i	Create Intel format
–memwidth 16	Set EPROM system memory width to 16
–romwidth 16	Set physical ROM width to 16

Because the application requires the building of a boot table for parallel boot mode, and the 'C26 requires that you set the memory configuration register, you must select the following options as well:

Option	Description
–boot	Create a boot load table
–bootorg PARALLEL	Select parallel boot table header
–cg 0x0000	Set the interrupt/configuration word in the boot table header to 0x0000

For this application, you must use the ROMS directive to specify the address range for the boot table. Although the boot table is being organized for transmission via a communications port, the table resides in the external EPROM memory of the parent processor. Therefore, the table requires a load address in the EPROM memory space. The ROMS directive in Example D–19 forces placement of the boot table at address 0x0000 in the physical ROM.

The hex command file containing all of the options selected is shown in Example D–19.

Example D–19. Hex Command File for 'C26 With Parent and Child CPUs

```
a.out
-o   c26boot.hex
-map c26boot.mxp

-i

-memwidth 16
-romwidth 16


-boot
-bootorg PARALLEL

ROMS
{
    PAGE 0: ROM: org = 0x0000  , length = 0x10000
}
```

The –map option was also used. The –map option is not necessary but is often useful in understanding how the utility performed the conversion. Example D–21 on page D-24 shows the map file resulting from executing the command file in Example D–20.

Example D–21. Map File (c26boot.mxp) Resulting From the Command File in Example D–19

```
  **********************************************************************
  TMS320C1x/C2x/C2xx/C5x Hex Converter                    Version x.xx
  **********************************************************************
  Wed Feb  1 17:39:59 1995

  INPUT FILE NAME: <a.out>
  OUTPUT FORMAT:   Intel

  PHYSICAL MEMORY PARAMETERS
     Default data width:    16
     Default memory width:  16
     Default output width: 16

  BOOT LOADER PARAMETERS
     Table Address: 0000, PAGE 0


  OUTPUT TRANSLATION MAP
  ----------------------------------------------------
  00000000..0000ffff  Page=0  ROM Width=16  Memory Width=16  ”ROM”
  ----------------------------------------------------
     OUTPUT FILES: c26boot.hex [b0..b15]

     CONTENTS: 00000000..00000076   BOOT TABLE
                                      boot_sec : dest=0000fa00
                                       size=00000072  width=00000002
```

The contents of the associated hex output file is shown in Example D–22.

*Example D–22. Output File (c26boot.hex) Resulting From the Command File in
Example D–19*

```
:20000000001800000071CA01C8106021CE26D0000822D1000822CE02CE08CE07D001FA6B99
:20001000CC01F680FA12FE89FA16FE89FA00FE89FA657E02D001FA6B558858A0CC01588053
:200020003290338BFB9AFA2455897F02CE26CC0158ABFB9AFA24CC01FF88FA1A7AA070A025
:200030007180C00130E076AEC8103600FB80FA37FF80FA43559876802080D0020801608016
:20004000358D2089CE24558EFB80FA37FF80FA4370A07180C00130E0CE07C8102000CD206C
:20005000F380FA52CA01FF80FA612000CC016000CD01D002080155886080358AD200FFFEEB
:2000600055E0208D6080CA0055897F023080CE26CA0160A0FE80FA2B5590CE260001082180
:0E0070000000001080000000000086A000007
:00000001FF
```

Assembler Error Messages

The assembler issues several types of error messages:

❏ Fatal
❏ Nonfatal
❏ Macro

When the assembler completes its second pass, it reports any errors that it encountered during the assembly. It also prints these errors in the listing file (if one is created); an error is printed following the source line that caused it.

This appendix lists the three types of assembler error messages in alphabetical order. Most errors are fatal errors; if an error is not fatal or if it is a macro error, this is noted in the assembler listing file. Most error messages have a *Description* of the problem and an *Action* that suggests possible remedies. Where the error message itself is an adequate description, you may find only the *Action* suggested. Where the *Action* is obvious from the description (to inspect and correct your code), the *Action* is omitted.

A

absolute value required

Description   A relocatable symbol was used where an absolute symbol was expected.

Action   Use an absolute symbol.

address required

Description   An address that this instruction requires as an operand is not supplied.

an identifier in the expression is invalid

Description   A character constant operand that a character-matching function requires is not supplied.

Action   Use a character constant.

argument must be character constant

Description   A character constant that a character-matching function requires is not supplied.

Action   Use a character constant.

B

bad field width

Description   For the .field directive, the specified value does not fit into the specified number of bits.

bad macro library format

Description   The macro library specified is not in the format expected.

Action   Make sure that the macro libraries are unassembled assembler source files. Also make sure that the macro name and member name are the same, and the extension of the file is .asm.

.break encountered outside loop block

Description   A .break directive is declared outside a loop block and .break is valid only inside a loop block.

Action   Examine code for a misplaced .endloop directive or remove the .break directive.

C

cannot open library

Description   A library name specified with the .mlib directive does not exist or is already being used.

Action   Check spelling, pathname, environment variables, etc.

cannot open listing file : *filename*

Description   The specified filename is inaccessible.

Action   Check spelling, pathname, environment variables, etc.

cannot open object file : *filename*

Description The specified filename is inaccessible.

Action Check spelling, pathname, environment variables, etc.

cannot open source file : *filename*

Description The specified filename is inaccessible.

Action Check spelling, pathname, environment variables, etc.

character constant overflows a word

Description Character constants should be limited to four characters.

close (")") missing

Description Mismatched parentheses.

close ("]") missing

Description Mismatched brackets.

close quote missing

Description Mismatched or missing quotation mark(s).

Action Enclose all strings in quotes.

comma missing

Description The assembler expected a comma but did not find one. In most cases, the instruction requires more operands than were found.

conditional block nesting level exceeded

Description Conditional block nesting cannot exceed 32 levels.

conflicts with previous section definition

Description A section is defined with .sect and redefined with .usect or vice versa.

Action Change the directives to match or else rename one of the sections.

copy file open error

Description A file specified by a .copy directive does not exist or is already being used.

Action Check spelling, pathname, environment variables, etc.

D

divide by zero

Description   An expression or well-defined expression contains invalid division.

duplicate definition

Description   The symbol appears as an operand of a REF statement, as well as in the the label field of the source, or the symbol appears more than once in the label field of the source.

Action   Examine code for above. Use .newblock to reuse local labels.

duplicate definition of a structure component

Description   A structure tag, member, or size symbol was defined elsewhere or used in a .global directive.

E

.else or .elseif needs corresponding .if

Description   An .else or .elseif directive was not preceded by an .if directive.

empty structure

Description   A .struct/.endstruct sequence must have at least one member.

expression not terminated properly

Description   An expression is not delimited by commas, parentheses, or blanks, and it should be.

F

filename missing

Description   The specified filename cannot be found.

Action   Check spelling, pathname, environment variables, etc.

floating-point number not valid in expression

Description   A floating-point expression was used where an integer expression is required.

I

illegal label

Description A label cannot be used for the second instruction of a parallel instruction pair.

Action Remove the label on the second instruction.

illegal operation in expression

Description An illegal combination of relocatable and external operands was probably used.

Action Consult Table 3–2 on page 3-28.

illegal shift count

Description Shift count must be 0–16 bits.

illegal structure definition

Description The .stag/.eos structure definition is nested or contains a debugging directive other than .member.

Action Consult the .stag/.etag/.utag/.eos description on page B-8.

illegal structure member

Description The structure definition contains a directive other than one that reserves space.

Action Consult *Directives That Initialize Constants* in Table 4–1 beginning on page 4-2.

illegal structure, union, or enumeration tag

Description The .stag directive has an operand that is not an identifier.

invalid binary constant

Description A binary constant other than 0 or 1 is specified or is not suffixed with b or B.

invalid condition value

Description The assembler does not recognize the symbol entered as a valid condition symbol.

invalid control bit

Description   The assembler does not recognize the symbol entered as a valid control bit symbol.

invalid decimal constant

Description   A digit other than 0–9 is specified.

Action   This error is most commonly caused by failure to use h or H as the suffix on a hexadecimal number. Verify that any hexadecimal numbers are suffixed with h or H.

invalid expression

Description   This may indicate invalid use of a relocatable symbol in arithmetic.

invalid floating-point constant

Description   Either the floating-point constant is incorrectly formed, or an integer constant is used where a floating-point constant is required.

Action   See page 4-43.

invalid hexadecimal constant

Description   The only valid hexadecimal digits are the integers 0–9 and the letters A–F. The constant must be suffixed with h or H, and it must begin with an integer.

invalid indirect addressing format

Description   The addressing mode specified is not appropriate.

invalid octal constant

Description   The only valid octal digits are the integers 0–8; the constant must be suffixed with q or Q.

invalid opcode

Description   The command field of the source record has an entry that is not a defined instruction, directive, or macro name.

invalid opcode for selected version

Description   The command is not valid for this version of the assembler.

invalid operand combination — check version

Action   Check the instruction description in the device user's guide.

invalid operand value

Description   Certain assembler directives use parameters. An invalid param-
eter value has been specified.

invalid option

Description   An option specified by the .option directive is invalid.

invalid register value

Description   A symbol used to represent a register is not appropriate for the
current release.

invalid relocation type

Description   A relocation type is not valid. Relocation type depends on the
addressing mode used to generate the relocatable reference.

Action   See Table A–9, page A-10, for valid relocation types.

invalid symbol

Description   The symbol has invalid characters in it. For example, it begins
with a decimal digit instead of a letter, an underscore, etc.

invalid symbol qualifier

Description   Either the symbol string is not composed of up to 32 alphanu-
meric characters (A–Z (either case), 0–9, $, and _), or it begins
with a number.

invalid version number

Description   Valid version options for the assembler, including –v10, –v16,
–v20, –v25, –v2xx, and –v50 (–v25 is the default), are not used.

L

label not defined

Description   The .label directive does not have the required *symbol* param-
eter.

label required

Description   The flagged directive has no label.

library not in archive format

Description   A file specified with an .mlib directive is not an archive file.

Action   Make sure that the macro libraries are unassembled assembler source files. Also make sure that the macro name and member name are the same, and the extension of the file is .asm.

local macro variable is not a valid symbol

Description   The operand of a .var directive is not a valid symbol.

Action   Consult subsection 6.3.7 on page 6-12.

M

macro parameter is not a valid symbol

Description   The macro parameter is not a valid identifier.

Action   See Section 6.3, beginning on page 6-5, for a discussion of macro parameters.

maximum macro nesting level exceeded

Description   The maximum nesting level is 32.

maximum number of copy files exceeded

Description   The maximum nesting level for .copy or .include files is 10.

.mexit directive encountered outside macro

Description   A .mexit directive is specified outside a macro and is valid only inside macros.

missing .endif directive

Description   An .if directive has no matching .endif.

missing .endloop directive

Description   A .loop directive has no matching .endloop.

missing .endm directive

Description   A .macro directive has no matching .endmacro directive.

missing macro name

Description   A .macro directive has no name.

missing structure tag

Description   The .tag directive has no symbol name.

N

no include/copy files in macro or loop blocks

Description   The .include and .copy directives are not allowed inside macros (.macro/.endm) or loop blocks (.loop/.break/.endloop).

no parameters for macro arguments

Description   A macro was called with arguments, but no matching parameters were found in the macro definition.

O

open "(" expected

Description   A built-in function was used improperly, or mismatched parentheses were found.

open quote missing

Description   A built-in function was used improperly, or mismatched quotes were found.

operand is invalid for selected version

Description   A specified operand is not valid for the target processor selected.

operand missing

Description   A required operand is not supplied.

overflow in floating-point constant

Description   A floating-point value is too large to be represented.

P

pass1/pass2 operand conflict

Description   A symbol in the symbol table did not have the same value in pass 1 and pass 2. This is an internal assembler error. If it occurs repeatedly, the assembler may be corrupt.

positive value required

Description   A negative or zero value was used instead of a positive value.

R

redefinition of local substitution symbol

Description   Local substitution symbols can be defined only once in a macro.

register required

Description   A register that this instruction requires as an operand is not supplied.

S

string required

Description   A required string in double quotes is not supplied.

Action   You must supply a string that is enclosed in double quotes.

substitution symbol stack overflow

Description   The maximum number of nested substitution symbols is 10.

substitution symbol string too long

Description   The maximum substitution symbol length is 200 characters.

symbol required

Description   A symbol that the .global directive requires as an operand is not supplied.

symbol used in both REF and DEF

Description   A REFed symbol is already defined.

syntax error

Description   An expression is improperly formed.

T

too many local substitution symbols

Description   The maximum number of local substitution symbols is $\approx 64,000$.

U

unbalanced symbol table entries

Description   The assembler detected improper .block nesting or illegal .func nesting.

undefined structure member

Description   A symbol referenced with structure reference notation (a.b) is not declared in a .struct/.endstruct sequence.

undefined structure tag

Description   The operand of .tag is not defined with a .struct directive.

undefined substitution symbol

Description   The operand of a substitution symbol is not defined either as a macro parameter or with a .asg or .eval directive.

undefined symbol

Description   An undefined symbol was used where a well-defined expression is required.

underflow in floating-point constant

Description   Floating-point value is too small to represent.

unexpected .endif encountered

Description   An .endif directive is not preceded by a .loop directive.

unexpected .endloop encountered

Description   An .endloop directive is not preceded by a .loop directive.

unexpected .endm directive encountered

Description   An .endm directive is not preceded by a .macro directive.

USER ERROR

Description   Output from an .emsg directive.

USER MESSAGE

Description   Output from a .mmsg directive.

USER WARNING

Description   Output from a .wmsg directive.

V

value is out of range

Description   The value specified is outside the legal range.

value truncated

Description   The value specified requires more bits to be represented than is provided in the flagged instruction. The value was truncated to fit in the specified field, but the truncated value is likely to cause the program to behave incorrectly.

Action   Specify a smaller value or specify more bits in the flagged instruction.

.var directive encountered outside macro

Description   The .var directive is specified outside a macro and is legal inside macros (.macro/.endm) only.

version number changed

Description   The .version directive was used to change versions between incompatible target processors.

W

warning — block open at end of file

Description   A .block or .func directive is missing its corresponding .endblock or .endfunc.

warning — byte value truncated

Description   The value specified does not fit in an 8-bit field. The value is truncated to fit.

warning – context switch in delayed sequence

Description   A context switch occurred during a delayed sequence context change.

warning – delayed jump misses second word

Description   A two-word instruction is in the second word of a delayed sequence context switch. The second word will be fetched from the branch address.

warning — function .sym required before .func

Description   A .sym directive defining the function does not appear before the .func directive.

warning — illegal relative branch

Description   A branch is requested to a different section.

warning — illegal version — default used

Description   The processor version specified is invalid. The TMS320C25 is used as the default.

warning — immediate operand not absolute

Description   A supplied immediate operand is not an absolute expression.

Action   Refer to Table 3–2 on page 3-28.

warning — line truncated

Description   More than 200 characters are on an input line; any characters after the 200th on an input line are ignored.

warning — null string defined

Description   An empty string (one whose length = 0) is defined for a directive that requires a string operand.

warning — possible pipe conflict with norm

Description   Indirect addressing was used in the two words following a NORM instruction. This may cause a pipeline conflict.

warning — possible pipe hit at branch address

Description   A NORM instruction was found during a delayed sequence context change. The NORM instruction may cause a pipeline conflict.

warning — possible pipe hit with arx access

Description   An access was made to an AR register as a memory address. This may cause a pipeline conflict.

warning — register converted to immediate

Description   A constant was expected as an operand.

warning — string length exceeds maximum limit

Description   The maximum length of the .title directive is 64 characters.

warning — symbol truncated

Description   The maximum length for a symbol is eight characters. The assembler ignores the extra characters.

warning — trailing operand(s)

Description   The assembler found fewer or more operands than expected in the flagged instruction.

warning — unexpected .end found in macro

Description   The .end directive was used to terminate a macro.

Action   Use the .endm macro directive instead.

warning — value out of range

Description   The value specified is outside the legal range.

warning — value truncated

Description   The expression given was too large to fit within the instruction opcode or the required number of bits.

Linker Error Messages

The linker issues several types of error messages:

❑ Syntax and command errors
❑ Allocation errors
❑ I/O errors

This appendix lists the three types of errors alphabetically within each category. In these listings, the symbol (...) represents the name of an object that the linker is attempting to interact with when an error occurs. Most error messages have a *Description* of the problem and an *Action* that suggests possible remedies. Where the error message itself is an adequate description, you may find only the *Action* suggested. Where the *Action* is obvious from the description (to inspect and correct your code), the *Action* is omitted.

Syntax/Command Errors

These errors are caused by incorrect use of linker directives, misuse of an input expression, or invalid options. Check the syntax of all expressions, and check the input directives for accuracy. Review the various options you are using, and check for conflicts.

A

absolute symbol (...) being redefined

Description   An absolute symbol is redefined; this is not allowed.

adding name (...) to multiple output sections

Description   The input section is mentioned twice in the SECTIONS directive.

ALIGN illegal in this context

Description   Alignment of a symbol is performed outside of a SECTIONS directive.

alignment for (...) must be a power of 2

Description   Section alignment was not a power of 2.

Action   Make sure that in hexadecimal, all powers of 2 consist of the integers 1, 2, 4, or 8 followed by a series of zero or more 0s.

alignment for (...) redefined

Description More than one alignment is supplied for a section.

attempt to decrement "."

Description A statements such as **.–=** is supplied; this is illegal. Assignments to **dot** can be used only to create holes.

B

binding address for (...) redefined

Description More than one binding value is supplied for a section.

blocking for (...) must be a power of 2

Description Section blocking is not a power of 2

Action Make sure that in hexadecimal, all powers of 2 consist of the integers 1, 2, 4, or 8 followed by a series of zero or more 0s.

blocking for (...) redefined

Description More than one blocking value is supplied for a section.

C

–c requires fill value of 0 in .cinit (... overridden)

Description The .cinit tables must be terminated with 0, therefore, the fill value of the .cinit section must be 0.

cannot align a section within GROUP — (...) not aligned

Description A section in a group was specified for individual alignment. The entire group is treated as one unit, so the group may be aligned or bound to an address, but the sections making up the group cannot be handled individually.

cannot resize (...), section has initialized definition in (...)

Description An *initialized* input section named .stack or .heap exists, preventing the linker from resizing the section.

cannot specify both binding and memory area for (...)

Description Both binding and memory were specified. The two are mutually exclusive.

Action If you wish the code to be placed at a specific address, use binding only.

cannot specify a page for a section within a GROUP

Description   A section was specified to a specific page within a group. The entire group is treated as one unit, so the group may be specified to a page of memory, but the sections making up the group cannot be handled individually.

E

8-bit relocation out of range at (*...***) in section (***...***), file (...)**

Description   Error message valid only for the 'C25. An overflow of an 8-bit relocation was detected.

Action   Generate an assembler listing file with the –l option. Examine the listing file for the line with the SPC that corresponds to the first two parameters above: hexadecimal address, and section address.

–e flag does not specify a legal symbol name (...)

Description   The –e option is not supplied with a valid symbol name as an operand.

entry point other than _c_int0 specified

Description   For –c or –cr option only. A program entry point other than the value of _c_int0 was supplied. The runtime conventions of the compiler assume that _c_int0 is the one and only entry point.

entry point symbol (...) undefined

Description   The symbol used with the –e option is not defined.

errors in input – (...) not built

Description   Previous errors prevent the creation of an output file.

F

fill value for (...) redefined

Description   More than one fill value is supplied for an output section. Individual holes can be filled with different values with the section definition.

fill value redefined for memory area (...)

Description   More than one fill value is supplied for an output section. Individual holes can be filled with different values with the section definition.

I

–i path too long (...)

Description   The maximum number of characters in an –i path is 256.

illegal input character

Description   There is a control character or other unrecognized character in the command file.

illegal memory attributes for (...)

Description   The attributes are not some combination of R, W, I, and X.

illegal operator in expression

Action   Review legal expression operators.

invalid path specified with –i flag

Description   The operand of the –i option (flag) is not a valid file or pathname.

invalid value for –f option

Description   The value for the –f option (flag) is not a 2-byte constant.

invalid value for –heap option

Description   The value for the –heap option (flag) is not a 2-byte constant.

invalid value for –stack flag

Description   The value for the –stack option (flag) is not a 2-byte constant.

invalid value for –v flag

Description   The value for the –v option (flag) is not a constant.

L

length redefined for memory area (...)

Description   A memory area in a MEMORY directive has more than one length.

linking files for incompatible targets (file ...)

Description   Object code assembled for different target devices cannot be linked together.

load address for UNION member ignored

Description   A load address is supplied for a UNION statement. Sections run but do not load as a union.

load address for uninitialized section (...) ignored

Description   A load address is supplied for an uninitialized section. Uninitialized sections have no load addresses—only run addresses.

load allocation required for initialized UNION member (...)

Description   A load address is supplied for an initialized section in a union. UNIONs refer to runtime allocation only. You must specify the load address for all sections within a union separately.

M

–m flag does not specify a valid filename

Description   You did not specify a valid filename for the file you are writing the output map file to.

memory area for (...) redefined

Description   More than one named memory allocation is supplied for an output section.

memory page for (...) redefined

Description   More than one page allocation is supplied for a section.

memory attributes redefined for (...)

Description   More than one set of memory attributes is supplied for an output section.

missing filename on –l

Description   No filename operand is supplied for the –l (lowercase L) option.

misuse of ”.” symbol in assignment instruction

Description   The ”.” symbol is used in an assignment statement that is outside the SECTIONS directive.

N

nesting exceeded with file (...)

Description   More than 16 levels of command file nesting is specified.

no allocation allowed for uninitialized UNION member

Description   A load address was supplied for an uninitialized section in a union. An uninitialized section in a union gets its run address from the UNION statement and has no load address, so no load allocation is valid for the member.

no allocation allowed within a GROUP–allocation for section (...) ignored

Description   A section in a group was specified for individual allocation. The entire group is treated as one unit, so the group may be aligned or bound to an address, but the sections making up the group cannot be handled individually.

no input files

Description No COFF files were supplied. The linker cannot operate without at least one input COFF file.

no load address specified for (...); using run address

Description No load address is supplied for an initialized section. If an initialized section has a run address only, the section is allocated to run and load at the same address.

O

–o flag does not specify a valid file name : *string*

Description The filename must follow the operating system file naming conventions.

origin missing for memory area (...)

Description An origin is not specified with the MEMORY directive. An origin specifies the starting address of a memory range.

origin redefined for memory area (...)

Description The origin for the memory area is specified more than once, and each memory area can have only one origin.

R

–r incompatible with –s (–s ignored)

Description Both the –r option and the –s option were used. Since the –s option strips the relocation information and –r requests a relocatable object file, these options are in conflict with each other.

S

section (...) not built

Description Most likely there is a syntax error in the SECTIONS directive.

statement ignored

Description There is a syntax error in an expression.

symbol referencing errors — (...) not built

Description Symbol references could not be resolved. Therefore, an object module could not be built.

symbol (...) from file (...) being redefined

Description A defined symbol is redefined in an assignment statement.

syntax error: scanned line = (...)

Description A syntax error has been detected at the listed line number.

T

too many arguments – use a command file

Description You used more than ten arguments on a command line or in response to prompts.

too many –i options, 7 allowed

Action More than seven –i options were used. Additional search directories can be specified with a C_DIR or A_DIR environment variable.

type flags for (...) redefined

Description More than one section type is supplied for a section. Note that type COPY has all of the attributes of type DSECT, so DSECT need not be specified separately.

type flags not allowed for GROUP or UNION

Description A type is specified for a section in a group or union. Special section types apply to individual sections only.

U

–u does not specify a legal symbol name

Description The –u option did not specify a legal symbol name that exists in one of the files that you are linking.

unexpected EOF(end of file)

Description There is a syntax error in the linker command file.

undefined symbol in expression

Description An assignment statement contains an undefined symbol.

Z

zero or missing length for memory area (...)

Description A memory range defined with the MEMORY directive did not have a nonzero length.

Allocation Errors

These error messages appear during the allocation phase of linking. They generally appear if a section or group does not fit at a certain address or if the MEMORY and SECTION directives conflict in some way. If you are using a linker command file, check that MEMORY and SECTION directives allow enough room to ensure that no sections overlap and that no sections are being placed in unconfigured memory.

B

binding address (...) for section (...) is outside all memory on page (...)

Description   Not every section falls within memory configured with the MEMORY directive.

Action   If you are using a linker command file, check that MEMORY and SECTIONS directives allow enough room to ensure that no sections are being placed in unconfigured memory.

binding address (...) for section (...) overlays (...) at (...)

Description   Two sections overlap and cannot be allocated.

Action   If you are using a linker command file, check that MEMORY and SECTIONS directives allow enough room to ensure that no sections are being placed in unconfigured memory.

binding address (...) incompatible with alignment for section (...)

Description   The binding address violates a section's alignment requirement from an .align directive or previous link.

C

can't allocate output section, (...)

Description   A section can't be allocated, because no existing configured memory area is large enough to hold it.

Action   If you are using a linker command file, check that the MEMORY and SECTIONS directives allow enough room to ensure that no sections are being placed in unconfigured memory.

I

internal symbol (...) redefined in file (...)

Description   The internal symbol was redefined in a second file. The linker ignores the second definition.

L

load address for uninitialized section (...) ignored

Description   A load address is supplied for an uninitialized section. Uninitialized sections have no load addresses—only run addresses.

M

memory types (...) and (...) on page (...) overlap

Description   Memory ranges on the same page overlap.

Action   If you are using a linker command file, check that MEMORY and SECTIONS directives allow enough room to ensure that no sections are being placed in unconfigured memory.

N

no load address specified for (...); using run address

Description   No load address is supplied for an initialized section. If an initialized section has a run address only, the section is allocated to run and load at the same address.

O

output file (...) not executable

Description   The output file created may have unresolved symbols or other problems stemming from other errors. This condition is not fatal.

S

section (...) at address (...) overlays previously allocated section (...) at address

Description   Two sections overlap and cannot be allocated.

Action   If you are using a linker command file, check that MEMORY and SECTIONS directives allow enough room to ensure that no sections overlap.

section (...), bound at address (...), won't fit into page (...) of configured memory

Description   A section can't be allocated, because no existing configured memory area is large enough to hold it.

Action   If you are using a linker command file, check that MEMORY and SECTIONS directives allow enough room for each page of memory.

section (...) enters unconfigured memory at address (...)

Description   A section can't be allocated, because no existing configured memory area is large enough to hold it.

Action   If you are using a linker command file, check that MEMORY and SECTIONS directives allow enough room to ensure that no sections are being placed in unconfigured memory.

section (...) in file (...) is too big

Description   A section can't be allocated, because no existing configured memory area is large enough to hold it.

Action   If you are using a linker command file, check that MEMORY and SECTIONS directives allow enough room to ensure that no sections are being placed in unconfigured memory.

U

undefined symbol (...) first referenced in file (...)

Description   Either a referenced symbol is not defined, or the –r option was not used. Unless the –r option is used, the linker requires that all referenced symbols be defined. This condition prevents the creation of an executable output file.

Action   Link using the –r option or define the symbol.

I/O and Internal Overflow Errors

The following error messages indicate that the input file is corrupt, nonexistent, or unreadable, or that the output file cannot be opened or written to. Messages in this category may also indicate that the linker is out of memory or table space.

C

cannot complete output file (...), write error

Description   This usually means that the file system is out of space.

cannot create output file (...)

Description   This usually indicates an illegal filename.

Action   Check spelling, pathname, environment variables, etc. The filename must conform to operating system conventions.

can't open (...)

Description   The specified file does not exist.

Action   Check spelling, pathname, environment variables, etc.

can't read (...)

Description   The file may be corrupt.

Action   If the input file is corrupt, try reassembling it.

can't seek (...)

Description   The file may be corrupt.

Action   If the input file is corrupt, try reassembling it.

can't write (...)

Description   The disk may be full or protected.

Action   Check disk volume and protection.

could not create map file (...)

Description   This usually indicates an illegal filename.

Action   Check spelling, pathname, environment variables, etc. The filename must conform to operating system conventions.

F

fail to copy (...)

Description   The file may be corrupt.

Action   If the input file is corrupt, try reassembling it.

fail to read (...)

Description   The file may be corrupt.

Action   If the input file is corrupt, try reassembling it.

fail to seek (...)

Description   The file may be corrupt.

Action   If the input file is corrupt, try reassembling it.

fail to skip (...)

Description   The file may be corrupt.

Action   If the input file is corrupt, try reassembling it.

fail to write (...)

Description   The disk may be full or protected.

Action   Check disk volume and protection.

file (...) has no relocation information

Description   You have attempted to relink a file that was not linked with –r.

file (...) is of unknown type, magic number = (...)

Description   The binary input file is not a COFF file.

I

illegal relocation type (...) found in section(s) of file (...)

Description   The binary file is corrupt.

internal error : aux table overflow

Description   This linker has an internal error.

invalid archive size for file (...)

Description   The archive file is corrupt.

I/O error on output file (...)

Description   The disk may be full or protected.

Action   Check disk volume and protection.

L

library (...) member (...) has no relocation information

Description   The library member has no relocation information. It is possible for a library member to not have relocation information; this means that it cannot satisfy unresolved references in other files when linking.

line number entry found for absolute symbol

Description   The input file may be corrupt.

Action   If the input file is corrupt, try reassembling it.

M

memory allocation failure

Description

N

no symbol map produced — not enough memory

Description   Available memory is insufficient to produce the symbol list. This is a nonfatal condition that prevents the generation of the symbol list in the map file.

R

relocation entries out of order in section (...) of file (...)

Description   The input file may be corrupt.

Action   If the input file is corrupt, try reassembling it.

relocation symbol not found: index (...), section (...), file (...)

Description   The input file may be corrupt.

Action   If the input file is corrupt, try reassembling it.

S

section (...) not found

Description   An input section specified in a SECTIONS directive was not found in the input file.

sections .text, .data, or .bss not found

Description   Information found in the COFF optional file header may be corrupt.

Action   Try reassembling and relinking the affected files.

seek to (...) failed

Description   The input file may be corrupt.

Action   If the input file is corrupt, try reassembling it.

Glossary

A

absolute address: An address that is permanently assigned to a TMS320 memory location.

absolute lister: A debugging tool that allows you to create assembler listings that contain absolute addresses.

absolute section: A named section defined with the .asect directive. In an absolute section, all addresses except those defined with .label are absolute.

alignment: A process in which the linker places an output section at an address that falls on an *n*-bit boundary, where *n* is a power of 2. You can specify alignment with the SECTIONS linker directive.

allocation: A process in which the linker calculates the final memory addresses of output sections.

archive library: A collection of individual files that have been grouped into a single file.

archiver: A software program that allows you to collect several individual files into a single file called an archive library. The archiver also allows you to delete, extract, or replace members of the archive library, as well as to add new members.

assembler: A software program that creates a machine-language program from a source file that contains assembly language instructions, directives, and macro directives. The assembler substitutes absolute operation codes for symbolic operation codes, and absolute or relocatable addresses for symbolic addresses.

assembly-time constant: A symbol that is assigned a constant value with the .set or .equ directive.

assignment statement: A statement that assigns a value to a variable.

autoinitialization: The process of initializing global C variables (contained in the .cinit section) before beginning program execution.

auxiliary entry: The extra entry that a symbol may have in the symbol table that contains additional information about the symbol (whether it is a filename, a section name, a function name, etc.).

B

binding: A process in which you specify a distinct address for an output section or a symbol.

block: A set of declarations and statements that are grouped together with braces.

.bss: One of the default COFF sections. You can use the .bss directive to reserve a specified amount of space in the memory map that can later be used for storing data. The .bss section is uninitialized.

C

C compiler: A program that translates C source statements into TMS320 fixed-point assembly language source statements.

command file: A file that contains linker options and names input files for the linker.

comment: A source statement (or portion of a source statement) that is used to document or improve readability of a source file. Comments are not compiled, assembled, or linked; they have no effect on the object file.

common object file format (COFF): An object file format that promotes modular programming by supporting the concept of *sections.*

conditional processing: A method of processing one block of source code or an alternate block of source code, according to the evaluation of a specified expression.

configured memory: Memory that the linker has specified for allocation.

constant: A numeric value that can be used as an operand.

cross-reference listing: An output file created by the assembler that lists the symbols that were defined, what line they were defined on, which lines referenced them, and their final values.

D

.data: One of the default COFF sections. The .data section is an initialized section that contains initialized data. You can use the .data directive to assemble code into the .data section.

directive: Special-purpose commands that control the actions and functions of a software tool (as opposed to assembly language instructions, which control the actions of a device).

E

emulator: A hardware development system that emulates TMS320 operation.

entry point: The starting execution point in target memory.

executable module: An object file that has been linked and can be executed in a TMS320 system.

expression: A constant, a symbol, or a series of constants and symbols separated by arithmetic operators.

external symbol: A symbol that is used in the current program module but defined in a different program module.

F

field: For the TMS320, a software-configurable data type whose length can be programmed to be any value in the range of 1–16 bits.

file header: A portion of a COFF object file that contains general information about the object file (such as the number of section headers, the type of system the object file can be downloaded to, the number of symbols in the symbol table, and the symbol table's starting address).

G

global: A kind of symbol that is either 1) defined in the current module and accessed in another, or 2) accessed in the current module but defined in another.

GROUP: An option of the SECTIONS directive that forces specified output sections to be allocated contiguously (as a group).

H

hex conversion utility: A utility that converts COFF object files into one of several standard ASCII hexadecimal formats, suitable for loading into an EPROM programmer.

high-level language debugging: The ability of a compiler to retain symbolic and high-level language information (such as type and function definitions) so that a debugging tool can use it.

hole: An area between the input sections that compose an output section that contains no actual code or data.

I

incremental linking: The linking of files that have already been linked.

initialized section: A COFF section that contains executable code or initialized data. An initialized section can be built up with the .data, .text, or .sect directive.

input section: A section from an object file that will be linked into an executable module.

L

label: A symbol that begins in column 1 of a source statement and corresponds to the address of that statement.

line number entry: An entry in a COFF output module that maps lines of assembly code back to the original C source file that created them.

linker: A software tool that combines object files to form an object module that can be allocated into TMS320 system memory and executed by the device.

listing file: An output file created by the assembler that lists source statements, their line numbers, and their effects on the SPC.

loader: A device that loads an executable module into TMS320 system memory.

M

macro: A user-defined routine that can be used as an instruction.

macro call: The process of invoking a macro.

macro definition: A block of source statements that define the name and the code that make up a macro.

macro expansion: The source statements that are substituted for the macro call and are subsequently assembled.

macro library: An archive library composed of macros. Each file in the library must contain one macro; its name must be the same as the macro name it defines, and it must have an extension of .asm.

magic number: A COFF file header entry that identifies an object file as a module that can be executed by the TMS320.

map file: An output file created by the linker that shows the memory configuration, section composition, and section allocation, as well as symbols and the addresses at which they were defined.

member: The elements or variables of a structure, union, archive, or enumeration.

memory map: A map of target system memory space that is partitioned into functional blocks.

mnemonic: An instruction name that the assembler translates into machine code.

model statement: Instructions or assembler directives in a macro definition that are assembled each time a macro is invoked.

N

named section: An initialized section that is defined with a .sect directive, or an uninitialized section that is named with a .usect directive.

O

object file: A file that has been assembled or linked and contains machine-language object code.

object format converter: A program that converts COFF object files into Intel format, Tektronix format, TI-tagged format, or Motorola-S format object files.

object library: An archive library made up of individual object files.

operand: The arguments, or parameters, of an assembly language instruction, assembler directive, or macro directive.

optional header: A portion of a COFF object file that the linker uses to perform relocation at download time.

options: Command parameters that allow you to request additional or specific functions when you invoke a software tool.

output module: A linked, executable object file that can be downloaded and executed on a target system.

output section: A final, allocated section in a linked, executable module.

overlay page: A section of physical memory that is mapped into the same address range as another section of memory. A hardware switch determines which range is active.

P

partial linking: The linking of a file that will be linked again.

R

RAM model: An autoinitialization model used by the linker when linking C code. The linker uses this model when you invoke the linker with the –cr option. The RAM model allows variables to be initialized at load time instead of runtime.

raw data: Executable code or initialized data in an output section.

relocation: A process in which the linker adjusts all the references to a symbol when the symbol's address changes.

ROM model: An autoinitialization model used by the linker when linking C code. The linker uses this model when you invoke the linker with the –c option. In the ROM model, the linker loads the .cinit section of data tables into memory, and variables are initialized at runtime.

run address: The address where a section runs.

S

SPC (section program counter):   An element of the assembler that keeps track of the current location within a section; each section has its own SPC.

section: A relocatable block of code or data that will ultimately occupy contiguous space in the TMS320 memory map.

section header: A portion of a COFF object file that contains information about a section in the file. Each section has its own header; the header points to the section's starting address, contains the section's size, etc.

section program counter: See SPC.

sign-extend: To fill the unused MSBs of a value with the value's sign bit.

simulator: A software development system that simulates TMS320 operation.

source file: A file that contains C code or TMS320 assembly language code that will be compiled or assembled to form an object file.

static: A kind of variable whose scope is confined to a function or a program. The values of static variables are not discarded when the function or program is exited; their previous value is resumed when the function or program is re-entered.

storage class: Any entry in the symbol table that indicates how a symbol should be accessed.

string table: A table that stores symbol names longer than 8 characters. (Symbol names 8 characters or longer cannot be stored in the symbol table; instead, they are stored in the string table.) The name portion of the symbol's entry points to the location of the string in the string table.

structure: A collection of one or more variables grouped together under a single name.

symbol: A string of alphanumeric characters that represents an address or a value.

symbolic debugging: The ability of a software tool to retain symbolic information so that it can be used by a debugging tool such as a simulator or an emulator.

symbol table: A portion of a COFF object file that contains information about the symbols that are defined and used by the file.

T

tag: An optional *type* name that can be assigned to a structure, union, or enumeration.

target memory: Physical memory into which executable object code is loaded.

.text: One of the default COFF sections. The .text section is an initialized section that contains executable code. You can use the .text directive to assemble code into the .text section.

U

unconfigured memory: Memory that is not defined as part of the memory map and cannot be loaded with code or data.

uninitialized section: A COFF section that reserves space in the memory map but that has no actual contents. These sections are built with the .bss and .usect directives.

UNION: An option of the SECTIONS directive that causes the linker to allocate the same run address to multiple sections.

union: A variable that can hold objects of different types and sizes.

unsigned: A kind of value that is treated as a positive number, regardless of its actual sign.

W

well-defined expression: An expression that contains only symbols or assembly-time constants that have been defined before they appear in the expression.

word: A 16-bit addressable location in target memory.

TOKEN	REFERENCE	SEE (ALSO) . . .
	A_DIR	environment variables
	alternate directories	environment variables
	assembler, directives	directives, assembler
	boot loader	on-chip boot loader
	boot table	on-chip boot loader, boot table
	C_DIR	environment variables
	_c_int0 _main	entry points
	COFF, conversion to hexadecimal format	hex conversion utility
	COFF, named sections	COFF, sections, named
	common object file format	COFF
	debugging	symbolic debugging
	default, section	COFF, section
	directives, assembler, that format output	assembler output
	dspa command	assembler, invoking
	dspabs command	absolute lister, invoking
	dspar command	archiver, invoking
	dsphex command	hex conversion utility, invoking
	dsplnk command	linker, invoking
	dspxref command	cross-reference lister, invoking
	filenames	hex conversion utility, output filenames
	fill value	holes
	hex conversion util', on-chip boot loader	on-chip boot loader
	hex conversion utility, options	on-chip boot loader, options
	image mode	hcu image mode
	installation instructions	TMS Fixed-Point DSP CGT GS
	macros, parameters	substitution symbols
	named sections	COFF, sections, named
	object formats	COFF
	output, filenames	hex conversion utility, output filenames
	output, listing	listing
	path	environment variables – alternate dir's

TOKEN	REFERENCE	SEE (ALSO) . . .
	program counters	SPC
	ROMS directive, h. c. .u.	hcu ROMS
	section directives	directives, assembler
	section program counters	SPC
	sections	COFF, sections
	SECTIONS directive, hex conv. util.	h. c. u., SECTIONS
	software installation	TMS Fixed-Point DSP CGT GS
	widths	memory widths

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