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Prior of Gradient Descent Convergence:
        Let there be a cost function C(\vec{X}) where \vec{X}.
        Therefore, by definition of Gradient Descent
                  X = X - X VC - (The subscript represents
             where a is the learning rate
              (hyperparameter) and \nabla C = \begin{bmatrix} \frac{\partial C}{\partial x_1} \\ \frac{\partial C}{\partial x_2} \end{bmatrix}
         Using O.
              c(xi) = c(x- 4 VG)
                    = C(xo) - x VCo (VCo) [ Laylor's expansion in
            . C($\vec{x}_1) = C($\vec{x}_0) - α |∇C_0|^2 linear order]
             1118 C(X) = C(K) - x 1001/2
                   C(\overrightarrow{X}_n): C(X_{n-1}) - \times |\nabla C_{n-1}|^2
            . Adding all the egns,
                   C(Xn) = C(Ko) - x ( \( \S 1 \nabla C_1 \)
            ds n tends to so, we can see that the summation in the
        R. H. S. is an infinite sum, for infinite sums to converge to a
     value, lim \nabla C_k = 0 (Contrapositive of divergence test statement).
       Therefore, if our cost function is bounded from below,
C(Xo) + C(Xo) is finite. Therefore, $\frac{1}{2} |\nabla C_i|^2 is finite. Therefore.
      as lin VCx = 0. This shows that our gradient becomes zero
     at sufficiently high number of iterations.
              du, - k-0,
                      lim c(xk+) = c(xk+)-XF/V(k) = c(xk)
                       Therefore, cost function reaches a minimum
urhich is stable. (as C(\vec{x}_n) \leq C(\vec{x}_{n-1}) \leq \cdots \leq C(\vec{x}_1) \leq C(\vec{x}_0))
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