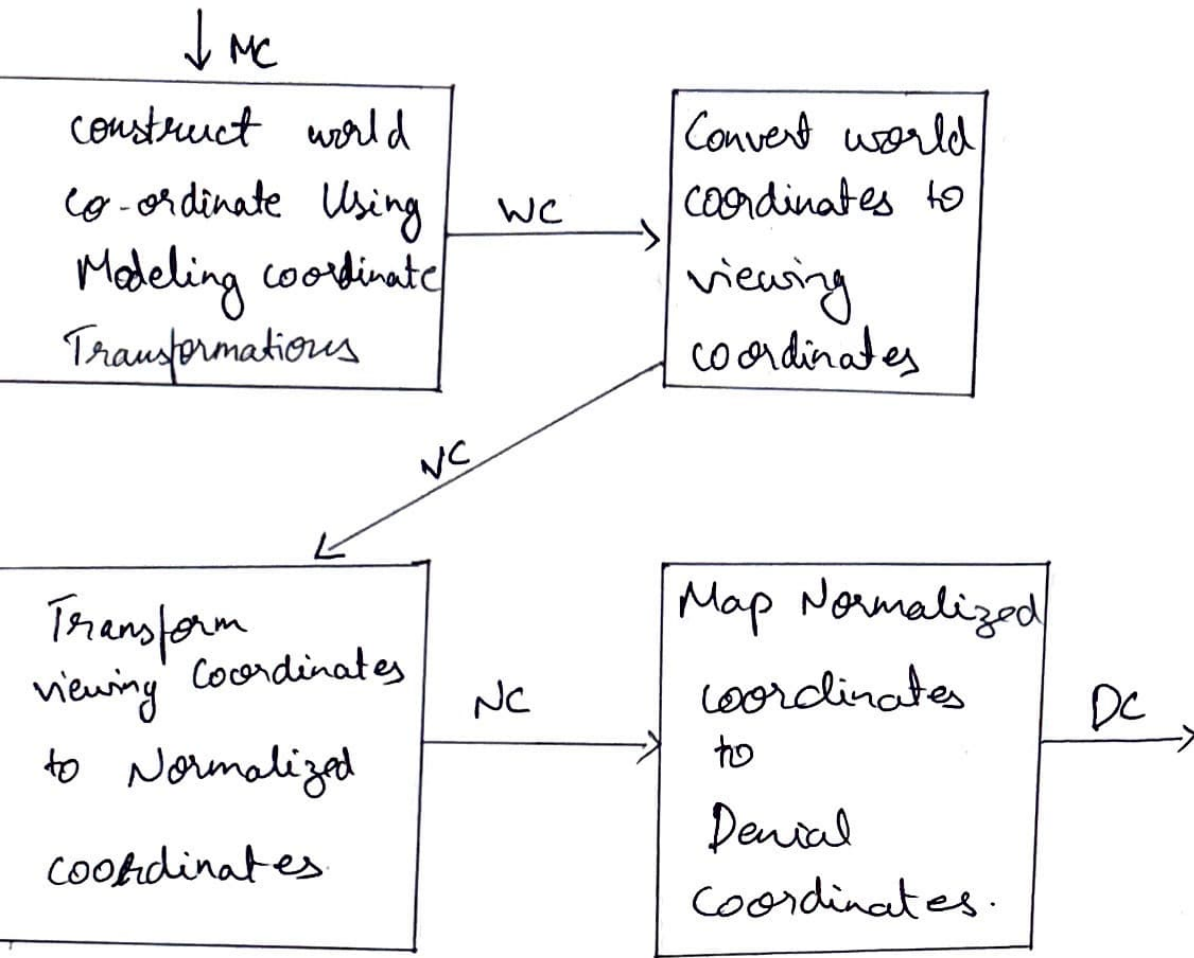


1. 2D Pipeline



- We could set up a separate 2-D, viewing coordinates reference frame for specifying clipping windows
- Systems use normalized coordinates in the range from 0 to 1, others used a range from -1 to 1,
- Clipping is usually performed in the normalized co-ordinates

2. Phong lighting Model.

⇒ Ambient lighting referred as the natural lighting.

⇒ Diffusion - The Artificial light.

⇒ Specular lighting - Refers to the shininess of the object.

$$I_{\text{amb}} = K_a I_a \rightarrow (1)$$

K_a = ambient reflectivity

I_a = intensity of ambient light

Similarly

$$\begin{aligned} I_{\text{diff}} &= K_d I_p \cos(\theta) \rightarrow (2) \\ &= K_d I_p (N \cdot L) \end{aligned}$$

$$I_{\text{spec}} = K_s I_p \cos^n \phi$$

∴ The Phong Model gives us the equation of all combined

$$\begin{aligned} \text{Total intensity } I &= K_a I_a + K_d I_p \cos \theta \\ &\quad + K_s I_p \cos^n \phi \end{aligned}$$

3. Homogeneous co-ordinates

The matrix representations of
Translation, Rotation and Scaling
are

$$P' = P + T$$

↓

Translation $P' = \overset{P}{\begin{bmatrix} x \\ y \end{bmatrix}} + \overset{T}{\begin{bmatrix} tx \\ ty \end{bmatrix}}$

Rotation $P' \Rightarrow \begin{bmatrix} x' \\ y' \end{bmatrix} = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$

Scaling $P' \Rightarrow \begin{bmatrix} s_x & 0 \\ 0 & s_y \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$

Generic $E_q \Rightarrow S.P$

$$P' = M_1 * P + M_2$$

But $x = \frac{x_h}{h}$, $y = \frac{y_h}{h}$

Translation. $\begin{bmatrix} x' \\ y' \\ 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & tx \\ 0 & 1 & ty \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ 1 \end{bmatrix}$

Rotation $\begin{bmatrix} x' \\ y' \\ 1 \end{bmatrix} = \begin{bmatrix} s_x & 0 & 0 \\ 0 & s_y & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ 1 \end{bmatrix}$

Scaling $\begin{bmatrix} x' \\ y' \\ 1 \end{bmatrix} = \begin{bmatrix} \cos \theta & -\sin \theta & 0 \\ \sin \theta & \cos \theta & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ 1 \end{bmatrix}$

4.

Raster Scan	Random Scan
<ol style="list-style-type: none"> 1) Produces jagged lines that are plotted as a discrete point set. 2) Less expensive 3) Modification difficult 4) Resolution low 5) Solid pattern is easy to fill 	<ol style="list-style-type: none"> 1) Random System produces smooth lines drawing 2) More expensive 3) Modification easy. 4) Resolution high 5) solid pattern is difficult to fill

5. Open GL functions.

- `glutCreateWindow` - Used to create a new window
- `glutCreateSubWindow` - Used to create another window within an existing one.
- `glutSetWindow` - Used to set a particular id for the window.
- `glutGetWindow` - Used to get the window ID
- `glutDestroyWindow` - To delete the window that was created.

- `glutPostRedisplay` - To display the window again & again, till forcibly closed.
- `glutFull Screen` - To represent window as a full screen mode.
- `glutPopWindow` / `glutPushWindow` - Works just like a matrix in window.
- `glutDisplayFunc` - To display
- `glutMainLoop`.
- `init()`

6. Open GL visibility detection functions.

(a). Polygon functions.

```
glCullFace(mode);
glEnable(GL_CULL_FACE);
glDisable(GL_CULL_FACE);
```

(b).

(b). Depth Buffer.

```
glutInitDisplayMode(GLUT_SINGLE | GLUT_RGB | GLUT_DEPTH);
glClear(GL_DEPTH_BUFFER_BIT);
// This works as initialization for depth buffer.
```

```

glDepthRange (near NormDepth, face NormDepth);
glClear (GL_DEPTH_BUFFER_BIT);
glClearDepth (MaxDepth);
glEnable (GL_DEPTH_TEST);
glDisable (GL_DEPTH_TEST);

```

© OpenGL Wireframe methods.

```

glPolygonMode (GL_FRONT_AND_BACK, GL_LINE);
// visible and hidden edges displayed.

```

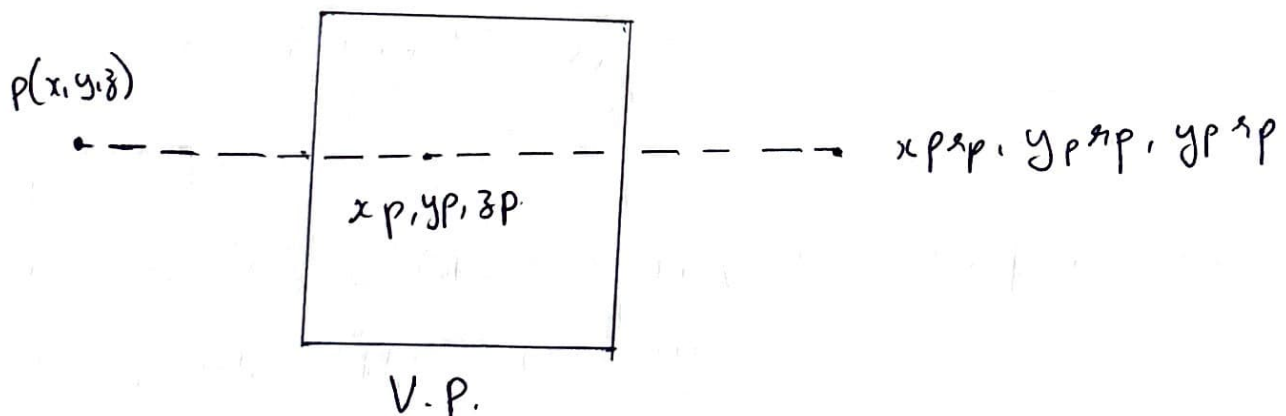
© OpenGL Depth using Functions.

```

glFogf (GL_FOG_MODE, GL_LINEAR);
glEnable (GL_FOG);

```

7. Special cases w.r.t. Perspective Projections.



Consider,

$$x' = x - (x - x_{pr})\mu$$

$$y' = y - (y - y_{pr})\mu$$

$$z' = z - (z - z_{pr})\mu$$

$$\mu = \frac{z_{pr} - z_0}{z_{pr} - z}$$

$$x_p = x \left(\frac{z_{pr} - z_{up}}{z_{pr} - z} \right) + x_{pr} \left(\frac{z_{up} - z}{z_{pr} - z} \right)$$

$$y_p = y \left(\frac{z_{pr} - z_{up}}{z_{pr} - z} \right) + y_{pr} \left(\frac{z_{up} - z}{z_{pr} - z} \right)$$

Special Cases:

① $x_{pr}, y_{pr} = 0$

$$x_p = x \left(\frac{z_{pr} - z_{up}}{z_{pr} - z} \right)$$

$$y_p = y \left(\frac{z_{pr} - z_{up}}{z_{pr} - z} \right)$$

$$\textcircled{2} \quad x_{p^1 p}, y_{p^1 p}, z_{p^1 p} = (0, 0, 0);$$

$$x_p = x\left(\frac{z_{p^1 p}}{z}\right)$$

$$y_p = y\left(\frac{z_{p^1 p}}{z}\right)$$

$$\textcircled{3} \quad z_{p^1 p} = 0.$$

$$x_p = x\left(\frac{z_{p^1 p}}{z_{p^1 p} - z}\right) - x_{p^1 p} \left(\frac{z}{z_{p^1 p} - z}\right)$$

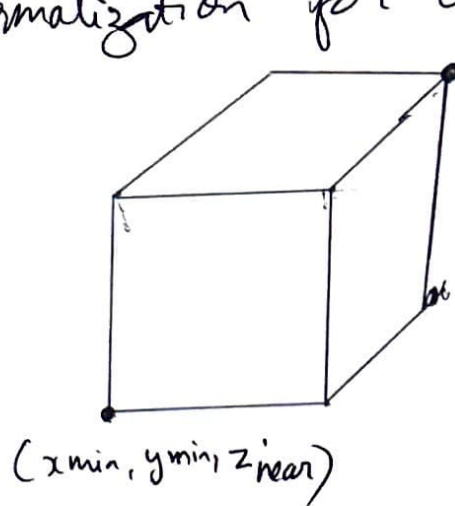
$$y_p = y\left(\frac{z_{p^1 p}}{z_{p^1 p} - z}\right) - y_{p^1 p} \left(\frac{z}{z_{p^1 p} - z}\right)$$

$$\textcircled{4} \quad x_{p^1 p} = y_{p^1 p} = z_{p^1 p} = 0.$$

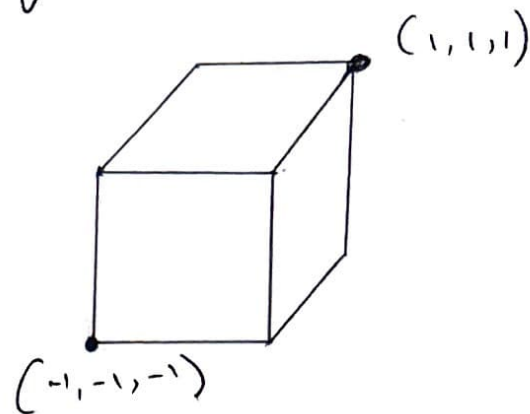
$$x_p = x\left(\frac{z_{p^1 p}}{z_{p^1 p} - z}\right) \approx$$

$$y_p = y\left(\frac{z_{p^1 p}}{z_{p^1 p} - z}\right)$$

8. Normalization for orthogonal projection.



Orthogonal projection
view



Normalized view.

consider a unit cube for normalized view with each x, y, z co-ordinate normalized in the range 0-1

Another approach is to use the range -1 to 1

orthogonal view ~~view~~ volume is.

$$M_{ortho} = \begin{bmatrix} \frac{2}{x_{max} - x_{min}} & 0 & 0 & \frac{-x_{max} + x_{min}}{x_{max} - x_{min}} \\ 0 & \frac{2}{y_{max} - y_{min}} & 0 & \frac{-y_{max} + y_{min}}{y_{max} - y_{min}} \\ 0 & 0 & \frac{-2}{z_{near} - z_{far}} & \frac{z_{near} + z_{far}}{z_{near} - z_{far}} \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

9. Bezier curve.

- Bezier curves are parametric curves that are generated with the help of control points. It is widely used in graphics and other related industry.
- It is named after French engineer, Pierre Bezier.

Bezier curves are represented as.

$$\sum_{k=0}^n P_i B_i^n(t)$$

$B_i^n(t)$ is Bernstein Polynomial.

$$B_i^n(t) = \binom{n}{i} (1-t)^{n-i} t^i$$

n = polynomial degree

t = variable

i = index.

Bezier curves can be of 2-control point (linear),

3-control point (cubic), 4 control point (quadratic)

we use, $\binom{n}{i} (1-t)^{n-i} t^i$ for every point.

10. Cohen-Sutherland line clipping.

• This algorithm works on Region Code.

(T B R L) - Top, Bottom, Right, Left.

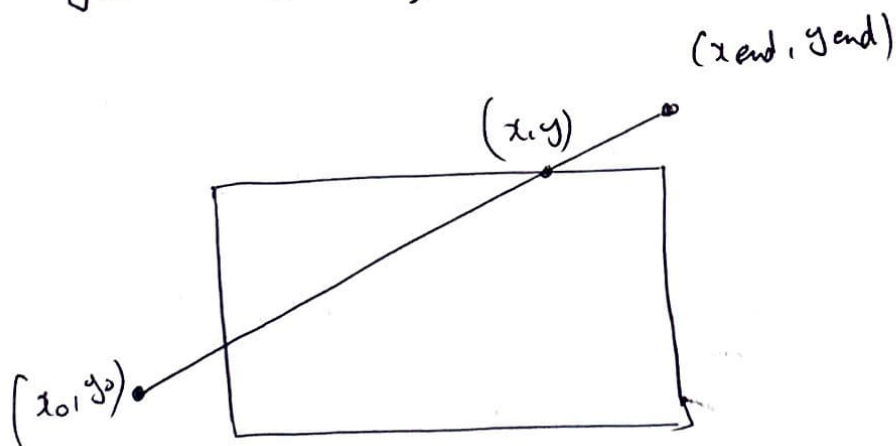
1001	1000	1010
0001	0000 clipping window	0010
0101	0100	0110

For a line - (x_0, y_0) to (x_{end}, y_{end})

$$m = (y - y_0) / (x - x_0)$$

$$m(x - x_0) = (y - y_0)$$

$$y = y_0 + m(x - x_0)$$



There are four formulae that can be used.

- $x = x_0 + m(y_{\max} - y_0)$
- $x = x_0 + \frac{1}{m}(y_{\min} - y_0)$
- $y = y_0 + m(x_{\max} - x_0)$
- $y = y_0 + \frac{1}{m}(x_{\min} - x_0)$