



Product Data Sheet

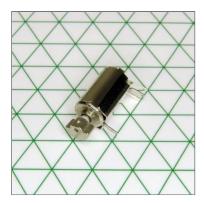
Range: Pico Vibe

Title: 6mm Vibration Motor

Type: Undefined Model: 306-114

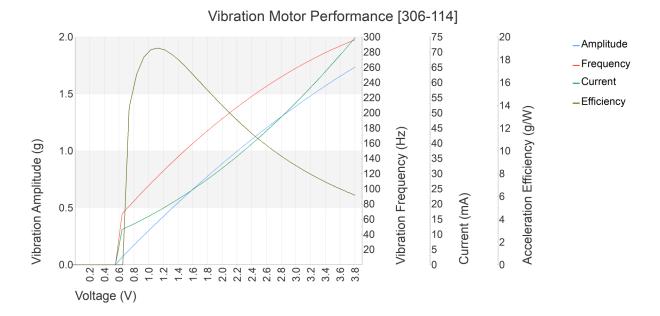
6mm Vibration Motor 10mm Type

Shown on 6mm Isometric Grid



KEY FEATURES	
Body Diameter	6 mm [+/- 0.2]
Body Length	10.4 mm [+/- 0.2]
Ecc. Weight Radius	2.5 mm [+/- 0.2]
Ecc. Weight Length	2.5 mm [+/- 0.2]
Shaft Orientation	Inline
Rated Operating Voltage	3 V
Rated Vibration Speed	15,700 rpm [+/- 3,150]
Typical Rated Operating Current	50 mA
Typical Norm. Amplitude	1.49 G

TYPICAL DC MOTOR PERFORMANCE CHARACTERISTICS



ORDERING INFORMATION

The model number fully defines the model, variant and additional features of the product. Please quote this number when ordering. For stocked types, testing and evaluation samples can be ordered directly through our online store.

FIND OUT HOW THIS PART COULD MEET YOUR SPECIFICATIONS

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DESIGN FOR APPLICATION CASE STUDIES







ENCAPSULATED VIBRATION MOTOR FOR A CPR TRAINING DUMMY

- Low volume, high value manufacturing
- Custom CNC machined enclosure
- Optimised haptic performance
- Custom PCB including FMI filters
- Part no. 334-401.001

VIBRATION MOTOR HIGHLY OPTIMISED FOR RUGGEDISED FIRE AND POLICE EMERGENCY RADIOS

- High volume production
- Optimised for emergency services application
- Ruggedised design with custom rubber 'suspension' cover
- Custom PCB with spring legs for simplified production assembly times
- Part no. 308-104.001

PRECISION SPEED AND TORQUE CONTROLLED SERVO WITH INTEGRATED TUNABLE PID LOOP FOR SINGLE-USE SCIENTIFIC INSTRUMENT.

- Medium volume, high value assembly
- Proprietary PID controller converts cost-effective motor design into a precision servo
- Adapted control software including digital IO (to customer's specification)
- Part no. 132-100.001

CUSTOMISED PRECISION GEAR MOTOR WITH ROBUST OPTICAL ENCODER

- High volume production
- Application specific output shaft
- Tailored motor performance curves
- Rear motor shaft with noise resistant optical encoder
- Part no. 212-116.001



PHYSICAL SPECIFICATION

PARAMETER	CONDITIONS	SPECIFICATION
Body Diameter	Max body diameter or max face dimension where non-circular	6 mm [+/- 0.2]
Body Length	Excl. shafts, leads and terminals	10.4 mm [+/- 0.2]
Unit Weight		1.8 g
Mounting	See drawing for details	PCB Thru-Hole
No. of Output Shafts		1
Ecc. Weight Radius	Radius from shaft for non-cylindrical weights	2.5 mm [+/- 0.2]
Ecc. Weight Length		2.5 mm [+/- 0.2]
Shaft Orientation		Inline

CONSTRUCTION SPECIFICATION

PARAMETER	CONDITIONS	SPECIFICATION
Motor Construction		Coreless
Commutation		Precious Metal Brush
No. of Poles		5
Bearing Type		Sintered Bronze

OPERATIONAL SPECIFICATION

PARAMETER	CONDITIONS	SPECIFICATION
Rated Operating Voltage		3 V
Rated Vibration Speed	At rated voltage using the inertial test load	15,700 rpm [+/- 3,150]
Max. Rated Operating Current	At rated voltage using the inertial test load	80 mA
Max. Start Voltage	Certified starting voltage. Measured at no load, where applicable	1.4 V
Rated Inertial Test Load	Mass of standard test sled	100 g
Max. Operating Voltage		3.6 V
Min. Vibration Amplitude	Peak-to-peak value at rated voltage using the inertial test load	0.92 G
Max. Start Current	At rated voltage	140 mA
Min. Insulation Resistance	At 50V DC between motor terminal and case	1 MOhm

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Model No. 306-114

Important: The characteristics of the motor is the typical operating parameters of the product. The data herein offers design guidance information only and supplied batches are validated for conformity against the specifications on the previous page.

TYPICAL PERFORMANCE CHARACTERISTICS

PARAMETER	CONDITIONS	SPECIFICATION
Typical Rated Operating Current	At rated voltage using the inertial test load	50 mA
Typical Vibration Amplitude	Peak-to-peak value at rated voltage using the inertial test load	1.49 G
Typical Start Current	At rated voltage	101 mA
Typical Vibration Efficiency	At rated voltage using the inertial test load	9.9 G/W
Typical Norm. Amplitude	Peak-to-peak vibration amplitude normalised by the inertial test load at rated voltage	1.49 G
Typical Start Voltage	Measured at no load, where applicable	0.65 V
Typical Terminal Resistance		26.5 Ohm
Typical Terminal Inductance		114 uH

TYPICAL HAPTIC CHARACTERISTICS

PARAMETER	CONDITIONS	SPECIFICATION
Typical Lag Time	At rated voltage using the inertial test load	7 ms
Typical Rise Time	At rated voltage using the inertial test load	28 ms
Typical Stop Time	At rated voltage using the inertial test load	47 ms
Typical Active Brake Time	Time taken from steady-state to 0.04 G under inverse polarity at max. voltage $$	17 ms

TYPICAL DURABILITY CHARACTERISTICS

PARAMETER	CONDITIONS	SPECIFICATION
Typical Min. Counterweight Pullout		9.8 N
Typical Max. Mech. Noise		50 dB(A)

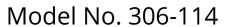
ENVIRONMENTAL CHARACTERISTICS

PARAMETER	CONDITIONS	SPECIFICATION
Max. Operating Temp.		60 Deg.C
Min. Operating Temp.		-20 Deg.C
Max. Storage & Transportation Temp.		80 Deg.C
Min. Storage & Transportation Temp.		-40 Deg.C

FIND OUT HOW THIS PART COULD MEET YOUR SPECIFICATIONS

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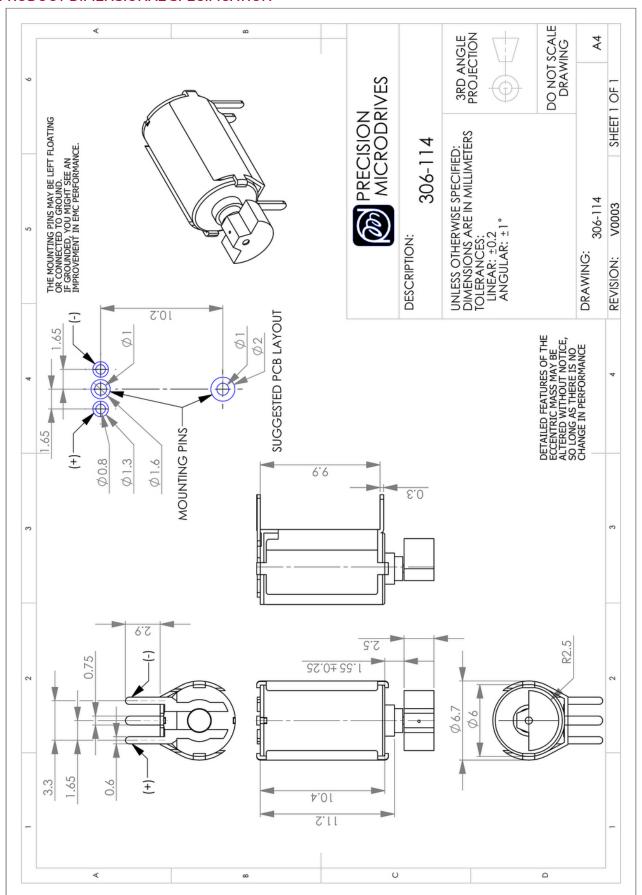
TYPICAL PACKING CONDITIONS

PARAMETER	CONDITIONS	SPECIFICATION
Carton Type		Boxed Trays

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PRODUCT DIMENSIONAL SPECIFICATION



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HOW TO ORDER

Call or email us with your order requirements at:

Email: enquiries@precisionmicrodrives.com

Phone: +44 (0) 1932 252482

Please quote the full part number when ordering or making an enquiry. Some products can be ordered in smaller volumes directly from our website: **www.precisionmicrodrives.com**

DATASHEET REVISION AND VERSION NUMBERING

We aim to provide ou customer with the most detailed product information available. Sometimes changes are necessary, and these will be controlled by our engineering change request and notification process. To track datasheet versions we use both a 'production revision number' and a 'document version number'. These can be found at the bottom of every page. Inc some cases, such as documentation errors, the document version number can increase without triggering a product revision.

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- 1. Life support devices or systems are devices or systems which,
 - 1.1. are intended for surgical implant into the body, or
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- 2. A critical component is any component of a life support device or any other system or machine whose failure to perform can be reasonably expected to cause the failure of the life support device or system, or to affect its safety or effectiveness.

BATCH NUMBERING, MANUFACTURING, TRACEABILITY AND LABELLING

Every part of manufactured by Precision Microdrives is at minimum identified and traced via a batch number. Where physically practical, we try to make each part with a batch number. In addition, some parts carry a lot code or barcode serial numbers. If traceability is a core requirement for your purchase, let us know and we'll outline the production options for you.

STANDARD QUALITY CONTROLS AND ISO 9001

Precision quality control is one of our 3 key competitive advantages. All motors that we produce undergo 100% line inspection followed by strict and detailed batch sample testing in accordance with ISO 2859. All of the processes operated at Precision Microdrives are managed within our ISO 9001 quality system.



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