

# **#5 : MIPS Programming I**

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# Arithmetic Instructions

<b>add \$s1, \$s2, \$s3</b>	$\$s1 = \$s2 + \$s3$	(add)
<b>addu \$s1, \$s2, \$s3</b>	$\$s1 = \$s2 + \$s3$	(add unsigned, no overflow)
<b>addi \$s1, \$s2, 20</b>	$\$s1 = \$s2 + 20$	(add immediate, sign-extend)
<b>addiu \$s1, \$s2, 20</b>	$\$s1 = \$s2 + 20$	(add immediate, no overflow)
<b>sub \$s1, \$s2, \$s3</b>	$\$s1 = \$s2 - \$s3$	(subtract)
<b>mul \$s1, \$s2, \$s3</b>	$\$s1 = \$s2 * \$s3$	(multiply)

# Logical Instructions

<b>and \$s1, \$s2, \$s3</b>	$\$s1 = \$s2 \& \$s3$	(and, bit-by-bit)
<b>andi \$s1, \$s2, 20</b>	$\$s1 = \$s2 \& 20$	(and immediate)
<b>or \$s1, \$s2, \$s3</b>	$\$s1 = \$s2 \mid \$s3$	(or)
<b>nor \$s1, \$s2, \$s3</b>	$\$s1 = \sim (\$s2 \mid \$s3)$	(nor)
<b>sll \$s1, \$s2, 10</b>	$\$s1 = \$s2 \ll 10$	(shift left logical)
<b>srl \$s1, \$s2, 10</b>	$\$s1 = \$s2 \gg 10$	(shift right logical)

# Load Instructions

<b>lw \$s1, 20(\$s2)</b>	$\$s1 = \text{Mem}[\$s2 + 20]$	(load word, from memory)
<b>lh \$s1, 20(\$s2)</b>	$\$s1 = \text{Mem}[\$s2 + 20]$	(load half word, sign-extend)
<b>lhu \$s1, 20(\$s2)</b>	$\$s1 = \text{Mem}[\$s2 + 20]$	(load half word, zero-extend)
<b>lb \$s1, 20(\$s2)</b>	$\$s1 = \text{Mem}[\$s2 + 20]$	(load byte, sign-extend)
<b>lbu \$s1, 20(\$s2)</b>	$\$s1 = \text{Mem}[\$s2 + 20]$	(load byte, zero-extend)
<b>li \$s1, 20</b>	$\$s1 = 20$	(load immediate)
<b>la \$s1, L</b>	$\$s1 = L$	(load address)

# Store Instructions

**sw \$s1, 20(\$s2)**

$\text{Mem}[\$s2 + 20] = \$s1$  (store word, to memory)

**sh \$s1, 20(\$s2)**

$\text{Mem}[\$s2 + 20] = \$s1$  (store half word)

**sb \$s1, 20(\$s2)**

$\text{Mem}[\$s2 + 20] = \$s1$  (store byte)

# Branch Instructions

<b>beq \$s1, \$s2, 25</b>	if ( $\$s1 == \$s2$ ) go to (PC+4+100)	(branch on equal)
<b>beq \$s1, \$s2, L</b>	if ( $\$s1 == \$s2$ ) go to L	(branch on equal)
<b>bne \$s1, \$s2, L</b>	if ( $\$s1 \neq \$s2$ ) go to L	(branch on not equal)
<b>blt \$s1, \$s2, L</b>	if ( $\$s1 < \$s2$ ) go to L	(branch on less than)
<b>bgt \$s1, \$s2, L</b>	if ( $\$s1 > \$s2$ ) go to L	(branch on greater than)
<b>ble \$s1, \$s2, L</b>	if ( $\$s1 \leq \$s2$ ) go to L	(branch on less than or equal)
<b>slt \$s1, \$s2, \$s3</b>	if ( $\$s2 < \$s3$ ) $\$s1 = 1$ else $\$s1 = 0$	(set on less than, for use with beq/bne)
<b>slti \$s1, \$s2, 20</b>	if ( $\$s2 < 20$ ) $\$s1 = 1$ else $\$s1 = 0$	(set on less than immediate)

# Jump Instructions

<b>j 2500</b>	go to 10000	(jump to target address)
<b>j L</b>	go to L	(jump to target address)
<b>jal L</b>	\$ra = PC+4; go to L	(jump and link, for procedure call)
<b>jr \$ra</b>	go to \$ra	(jump register, for procedure return)

# Pseudo-Instructions

Most assembler instructions represent machine instructions one-to-one. To **simplify programming**, the assembler can also treat common variations of machine instructions as if they were instructions in their own right. Such instructions are called **pseudo-instructions**. The hardware need not implement the pseudo-instructions and register \$at (assembler temporary) is reserved for this purpose.

<code>li \$s1, 20</code>	→	<code>addiu \$s1, \$zero, 20</code>
<code>move \$t0, \$t1</code>	→	<code>addu \$t0, \$zero, \$t1</code>
<code>blt \$s1, \$s2, L</code>	→	<code>slt \$at, \$s1, \$s2</code> <code>bne \$at, \$zero, L</code>



# Program Structure

```
_b1:    .data                # data segment (constants and global variables)
      .byte 1              # byte (8 bits) with value 1
_h1:    .half 10            # half word (16 bits) with value 10
_w1:    .word 100           # word (32 bits) with value 100
_a1:    .byte 1, 2, 3, 4    # array of 4 bytes with values 1, 2, 3 and 4
_a2:    .word 0:100         # array of 100 words with values 0
_s1:    .ascii "abc\n"      # string not null terminated
_s2:    .asciiz "123"        # string null terminated
_e1:    .space 100          # leave 100 bytes of space

      .text                # text segment (program instructions)
_main:                                     # main procedure
      ...
      li $v0, 10            # load code 10 for system call exit()
      syscall              # exit()
```

# System Calls

To request a service, **load the system call code into register \$v0** and **arguments into registers \$a0–\$a3 or \$f12** (floating point values).

Return values are put in **register \$v0 or \$f0** (floating-point results).

Service	System call code	Arguments	Result
print_int	1	\$a0 = integer	
print_float	2	\$f12 = float	
print_double	3	\$f12 = double	
print_string	4	\$a0 = string	
read_int	5		integer (in \$v0)
read_float	6		float (in \$f0)
read_double	7		double (in \$f0)
read_string	8	\$a0 = buffer, \$a1 = length	
sbrk	9	\$a0 = amount	address (in \$v0)
exit	10		
print_char	11	\$a0 = char	
read_char	12		char (in \$v0)
open	13	\$a0 = filename (string), \$a1 = flags, \$a2 = mode	file descriptor (in \$a0)
read	14	\$a0 = file descriptor, \$a1 = buffer, \$a2 = length	num chars read (in \$a0)
write	15	\$a0 = file descriptor, \$a1 = buffer, \$a2 = length	num chars written (in \$a0)
close	16	\$a0 = file descriptor	
exit2	17	\$a0 = result	