Chapter 6: Prune and Search (Supplementary)

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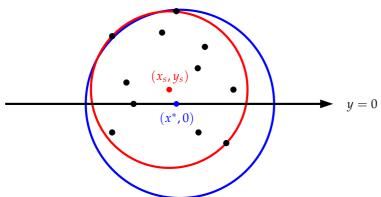
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General 1-center problem (cont'd)

Center of optimum circle lying on y=0

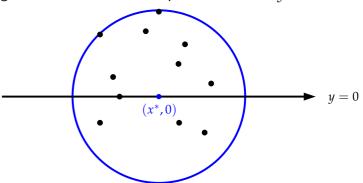
Let (x_s, y_s) be the center of the optimum circle containing all points.



General 1-center problem

Center of optimum circle lying on y = 0

Imagine that we have a set of points and a line y = 0 as follows.



▶ By using the constrained 1-center algorithm, we can determine the exact location of x^* on this line.

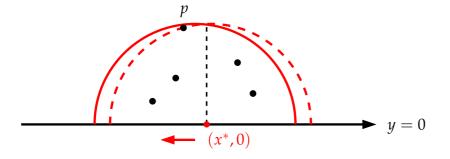
General 1-center problem (cont'd)

Center of optimum circle lying on y=0

- Actually, using the information of x^* , we can determine whether $y_s > 0$, $y_s < 0$ or $y_s = 0$.
- ▶ By the same reason (i.e., using the information of y^* obtained by solving the constrained 1-center problem on the line x = 0), we can also determine whether $x_s > 0$, $x_s < 0$ or $x_s = 0$.
- Let *I* be the set of points which are farthest from $(x^*, 0)$.

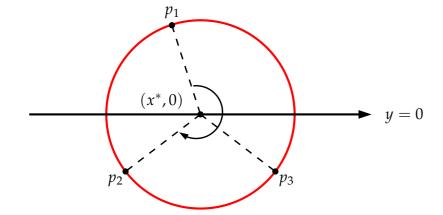
Case 1: I contains only one point p

- ln this case, the x-value of p must be equal to x^* .
- ightharpoonup Otherwise, we can move x^* towards p along the line y=0.
- It contradicts with our assumption that $(x^*, 0)$ is an optimal solution on the line y = 0.



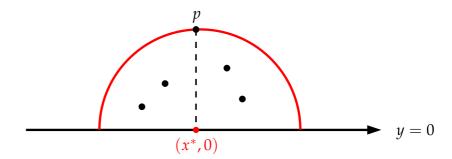
Case 2: I contains more than one point

- Find the smallest arc spanning all the points in *I*.
- Let the two end points of this arc be p_1 and p_2 .
- ▶ If this arc is of degree greater than or equal to 180° , $y_s = 0$.



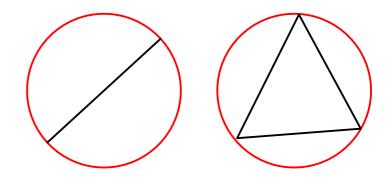
Case 1: I contains only one point p (cont'd)

- ▶ In other words, if p is the only farthest point of $(x^*, 0)$, then its x-value must be equal to x^* .
- ▶ Thus, we can conclude that y_s has the same sign as that of the y-value of p.



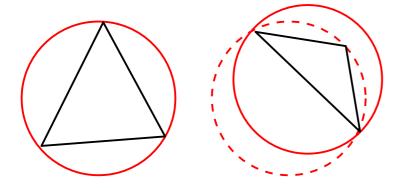
Case 2: I contains more than one point (cont'd)

▶ Note that a smallest circle containing a set of points is defined by either two points or three points of this set.



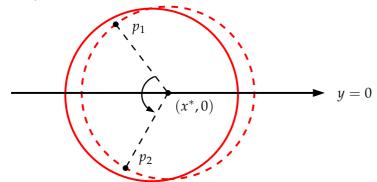
Case 2: I contains more than one point (cont'd)

- ► Three points define the boundary of a smallest circle enclosing all these three points if and only if they do not form an obtuse triangle (left figure).
- ▶ Otherwise, we can replace this circle by using the circle with the longest edge of this triangle as the diameter (right figure).



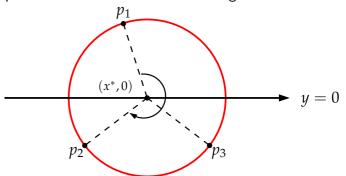
Case 2: I contains more than one point (cont'd)

- ightharpoonup Suppose that the arc spanning all farthest points is of degree less than 180° .
- ▶ The x-values of end points p_1 and p_2 must be of opposite signs of x^* .
- Assume otherwise, we can move x^* towards the direction where p_1 and p_2 are located, which actually is impossible.



Case 2: I contains more than one point (cont'd)

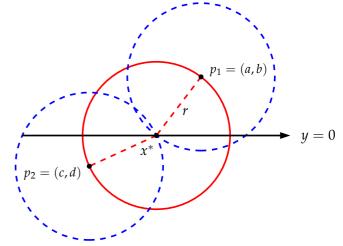
▶ If the degree of the arc spanning all farthest points is $> 180^{\circ}$, then there must be at least three such farthest points and these three points do not form an obtuse triangle.



It means that the present smallest circle is already optimal and hence we conclude that $y_s = 0$ (which is also true when the degree of the arc spanning all farthest points is 180°).

Case 2: I contains more than one point (cont'd)

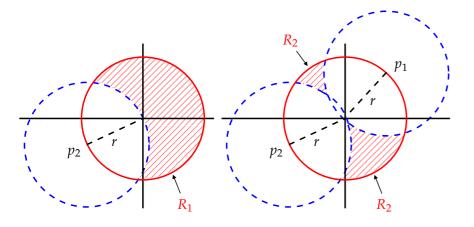
Therefore, we assume that $p_1 = (a,b)$ and $p_2 = (c,d)$ with $a > x^*, b > 0$ and $c < x^*, d < 0$, and use r as the radius to draw three circles centered at p_1, p_2 and $(x^*, 0)$, respectively.



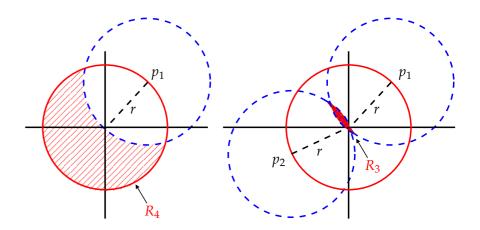
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Case 2: *I* contains more than one point (cont'd)

► Through these three circles, we can find four regions in the circle centered at $(x^*, 0)$: R_1, R_2, R_3 and R_4 .



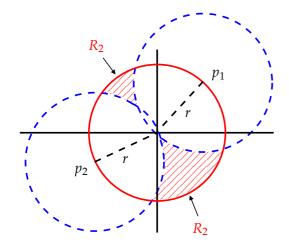
Case 2: I contains more than one point (cont'd)



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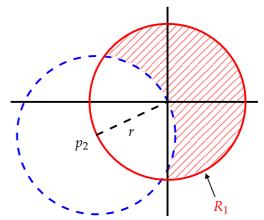
Case 2: I contains more than one point (cont'd)

▶ Clearly, the distance between any point x in R_2 and p_1 (or p_2) is greater than r and hence the center of the optimum circle cannot be located in R_2 .



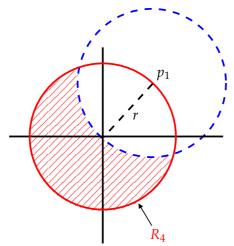
Case 2: I contains more than one point (cont'd)

▶ The distance between any point x in R_1 and p_2 is larger than r, and hence the center of the optimum circle cannot be located in R_1 .



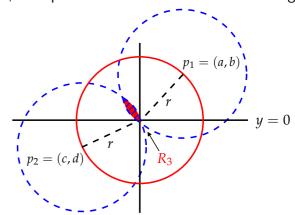
Case 2: *I* contains more than one point (cont'd)

The distance between any point x in R_4 and p_1 is larger than r, and hence the center of the optimum circle cannot be located in R_4 .



Case 2: *I* contains more than one point (cont'd)

 \triangleright Therefore, the optimum center must be located in region R_3 .



- ▶ Clearly, moving $(x^*, 0)$ towards the midpoint of the line $\overline{p_1p_2}$ (which is in R_3) will obtain a smaller circle to cover all points.
- ▶ It implies that the sign of y_s must be the sign of $\frac{b+d}{2} = \frac{y_1+y_2}{2}$.

Procedure 6-2

Procedure 6-2:

Input: A set S of points, a line $y = y^*$ and (x^*, y^*) , where (x^*, y^*) is the solution of the constrained 1-center problem for S.

Output: Whether $y_s > y^*$, $y_s < y^*$ or $y_s = y^*$, where (x_s, y_s) is the optimal solution of the 1-center problem for S.

1. Find I which is the set of points that are farthest from (x^*, y^*) .

2. Case 1 I contains only one point $p=(x_p,y_p)$. If $y_p>y^*$, report $y_s>y^*$ and exit. If $y_p< y^*$, report $y_s< y^*$ and exit.

Procedure 6-2 (cont'd)

3. Case 2 I contains more than one point.

In I, find $p_1=(x_1,y_1)$ and $p_2=(x_2,y_2)$ which are the two end points forming the smallest arc spanning all of the points in I.

if the degree of this arc is greater than or equal to 180° then Report $y_s = y^*$ and exit.

endif

if the degree of this arc is small than 180° then

Let
$$y_c = \frac{y_1 + y_2}{2}$$
.

If $y_c > y^*$, report $y_s > y^*$ and exit.

If $y_c < y^*$, report $y_s < y^*$ and exit.

endif

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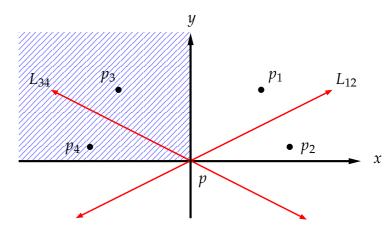
Basic idea of prune and search algorithm

1-center problem

- Let us consider four planar points shown on the next slide.
- For two pairs (p_1, p_2) and (p_3, p_4) , we draw bisectors L_{12} and L_{34} of line segments $\overline{p_1p_2}$ and $\overline{p_3p_4}$, respectively.
- ▶ Let L_{12} and L_{34} intersect at a point, say p.
- \blacktriangleright Move the origin of the coordinate system to p.
- Also rotate the x-axis such that L_{34} has a negative slope and L_{12} has a positive slope.

Basic idea of prune and search algorithm (cont'd)

1-center problem



Suppose that the center of the optimum circle must be in the shaded area.

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Basic idea of prune and search algorithm (cont'd)

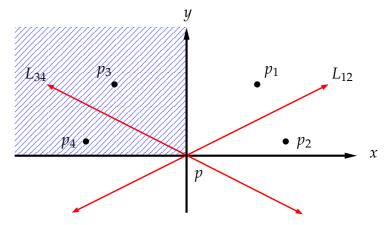
1-center problem

- We apply the constrained 1-center algorithm, requiring that the center be located on y = 0.
- After that, we utilize Procedure 6-2 to find out that we should move upward (since we assume $(x_s, y_s) \in 2$ nd quadrant).
- We then repeat this process by applying the constrained 1-center algorithm again to x = 0.
- ▶ We wll find out that we should move to the left (because we assume $(x_s, y_s) \in 2$ nd quadrant).
- ▶ Therefore, the optimal location (x_s, y_s) must be located in the shaded region.
- ▶ Because there is one bisection which does not intersect with the shaded region, we can eliminate one point from consideration.

Basic idea of prune and search algorithm (cont'd)

1-center problem

- ightharpoonup In our case, L_{12} does not intersect with the shaded region.
- Since p_1 is at the same side of the shaded region, p_1 is nearer to the optimal center than p_2 and hence we can eliminate p_1 .



Prune and search algorithm

1-center problem

Algorithm: Prune and search method for 1-center problem

Input: A set $S = \{p_1, p_2, ..., p_n\}$ of n points. **Output:** The smallest enclosing circle for S.

- 1. If *S* contains no more than 16 points, solve the problem by a brute and force method.
- 2. Form disjoint pairs of points $(p_1, p_2), (p_3, p_4), \ldots, (p_{n-1}, p_n)$. For each (p_i, p_{i+1}) , find the perpendicular bisector of $\overline{p_i p_{i+1}}$. Denote them as $L_{i/2}$ for $i=2,4,\ldots,n$. Compute the slope s_k of L_k for $k=1,2,\ldots,n/2$.
- 3. Compute the median of s_k 's and denote it as s_m .

Prune and search algorithm (cont'd)

1-center problem

4. Rotate the coordinate system so that the *x*-axis coincides with $y=s_mx$.

Let the set of L_k 's with positive (negative) slopes be I^+ (I^-). /* Note that both of them are of size n/4 */

- 5. Construct disjoint pairs of the lines (L_{i+}, L_{i-}) for i = 1, ..., n/4, where $L_{i+} \in I^+$ and $L_{i-} \in I^-$.
- Find the intersection of each pair of them and denote it by (a_i, b_i) . 6. Find the median of b_i 's and denote it as y^* .
 - Apply the constrained 1-center algorithm to S, requiring that the center of circle be located on $y = y^*$. Let this constrained 1-center be (x', y^*) .

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Prune and search algorithm (cont'd)

1-center problem

- 7. Apply Procedure 6-2 using S and (x', y^*) as the parameters. If $y_s = y^*$, report " (x', y^*) is the optimal solution" and exit. Otherwise, report $y_s > y^*$ or $y_s < y^*$.
- 8. Find the median of a_i 's and denote it by x^* . Apply the constrained 1-center algorithm to S, requiring that the center of circle be located on $x = x^*$. Let this constrained 1-center be (x^*, y') .
- 9. Apply Procedure 6-2 using S and (x^*, y') as the parameters. If $x_s = x^*$, report " (x^*, y') is the optimal solution" and exit. Otherwise, report $x_s > x^*$ or $x_s < x^*$.

Prune and search algorithm (cont'd)

1-center problem

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10. Case 1 x_s > x^* and y_s > y^* /* 1st quadrant */
Find all (a_i, b_i)'s such that a_i < x^* and b_i < y^*.

Let (a_i, b_i) be the intersection of L_{i+} and L_{i-}.

Let L_{i-} be the bisector of p_j and p_k.

Prune away p_j (resp. p_k) if p_j (resp. p_k) is closer to (x^*, y^*).

Case 2 x_s < x^* and y_s > y^* /* 2nd quadrant */

Find all (a_i, b_i)'s such that a_i > x^* and b_i < y^*.

Let (a_i, b_i) be the intersection of L_{i+} and L_{i-}.

Let L_{i+} be the bisector of p_j and p_k.

Prune away p_j (resp. p_k) if p_j (resp. p_k) is closer to (x^*, y^*).
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Prune and search algorithm (cont'd)

1-center problem

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10. Case 3 x_s < x^* and y_s < y^* /* 3rd quadrant */
Find all (a_i, b_i)'s such that a_i > x^* and b_i > y^*.

Let (a_i, b_i) be the intersection of L_{i+} and L_{i-}.

Let L_{i-} be the bisector of p_j and p_k.

Prune away p_j (resp. p_k) if p_j (resp. p_k) is closer to (x^*, y^*).

Case 4 x_s > x^* and y_s < y^* /* 4th quadrant */

Find all (a_i, b_i)'s such that a_i < x^* and b_i > y^*.

Let (a_i, b_i) be the intersection of (a_i, b_i) is closer to (a_i, b_i).

Prune away (a_i, b_i) if (a_i, b_i) is closer to (a_i, b_i).

11. Let (a_i, b_i) be the remaining points and go to step 1.
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Time of prune and search algorithm

1-center problem

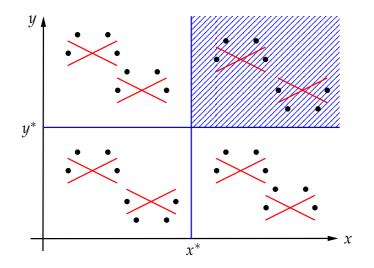
- Assume that there are $n = 16^k$ points for some k.
- ▶ There are $\frac{n}{2}$ bisectors formed in step 2.
- After step 4, $\frac{n}{4}$ of them have positive slops and $\frac{n}{4}$ of them have negative slops.
- ▶ Hence, there are a total $\frac{n}{4}$ intersections formed in step 5.
- Since x^* (y^*) is the median of a_i 's (b_i 's), there are $\frac{n}{4} \times \frac{1}{4} = \frac{n}{16}$ (a_i, b_i)'s for each case in step 10.

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Time of prune and search algorithm (cont'd)

1-center problem

Assume that the optimal solution lies in the shaded area.



Time of prune and search algorithm (cont'd)

1-center problem

- It can be verified that for each pair of intersection in the region with $x < x^*$ and $y < y^*$, the point above the line with negative slope can be pruned.
- For each such (a_i, b_i) , exactly one point is pruned away.
- ► Hence, $\frac{n}{16}$ points are pruned away in each iteration.
- ▶ Since each iteration takes $\mathcal{O}(n)$ time, the total time complexity of the prune and search algorithm is $\mathcal{O}(n)$.