

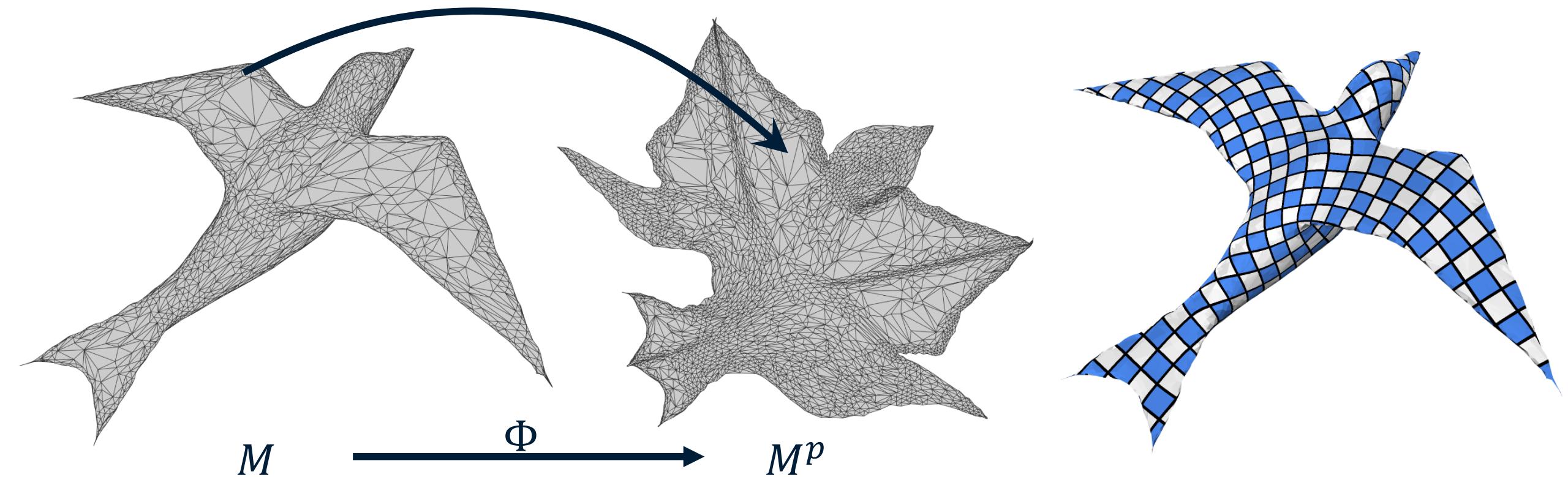
Progressive Parameterizations

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University of Science and Technology of China

Parameterizations

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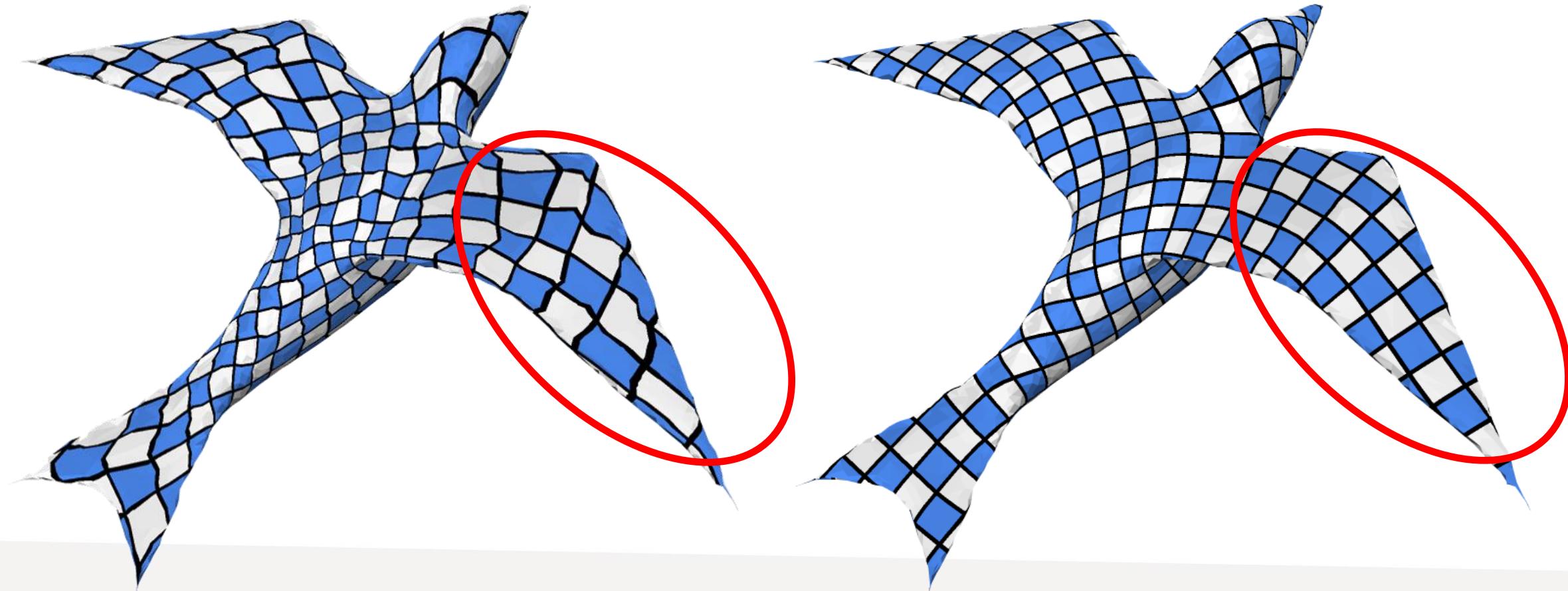
Applications

Texture mapping, remeshing, inter-surface mapping, and shape analysis

Two Basic Requirements

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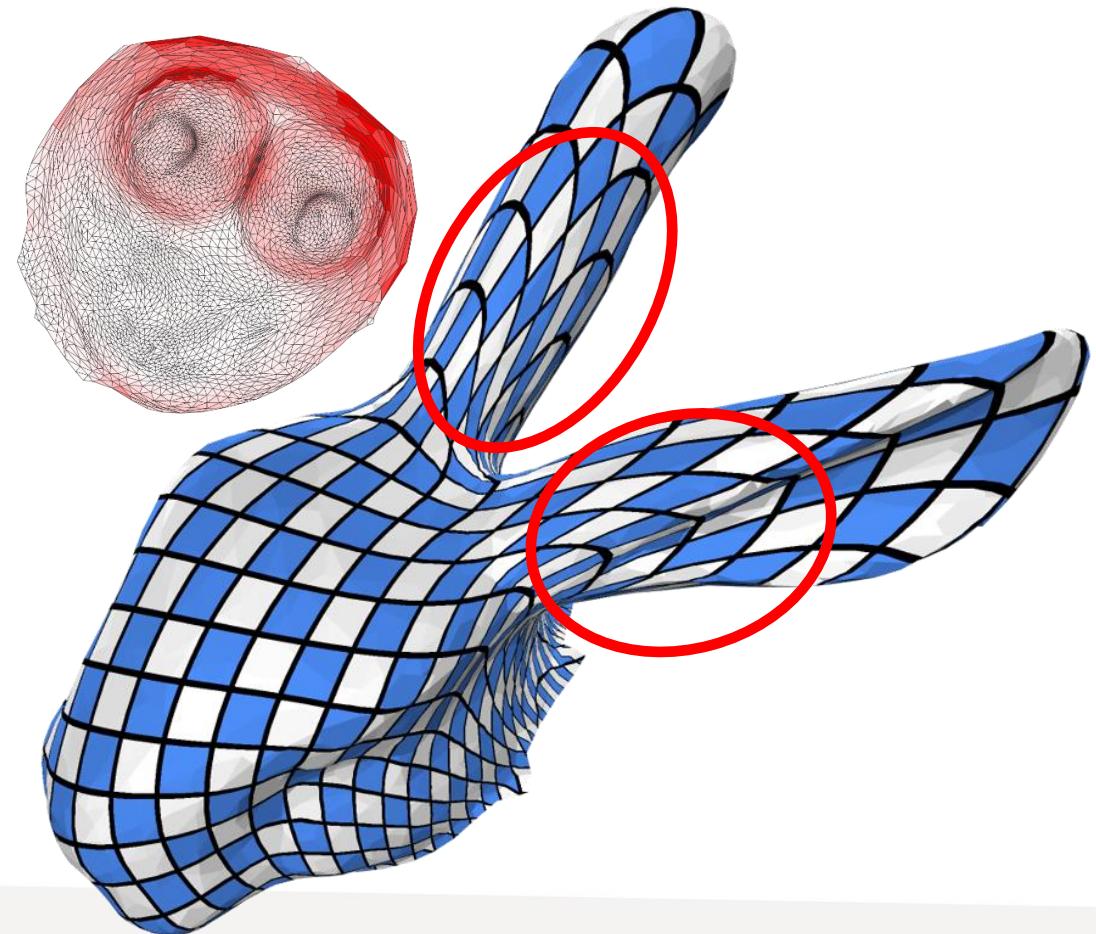
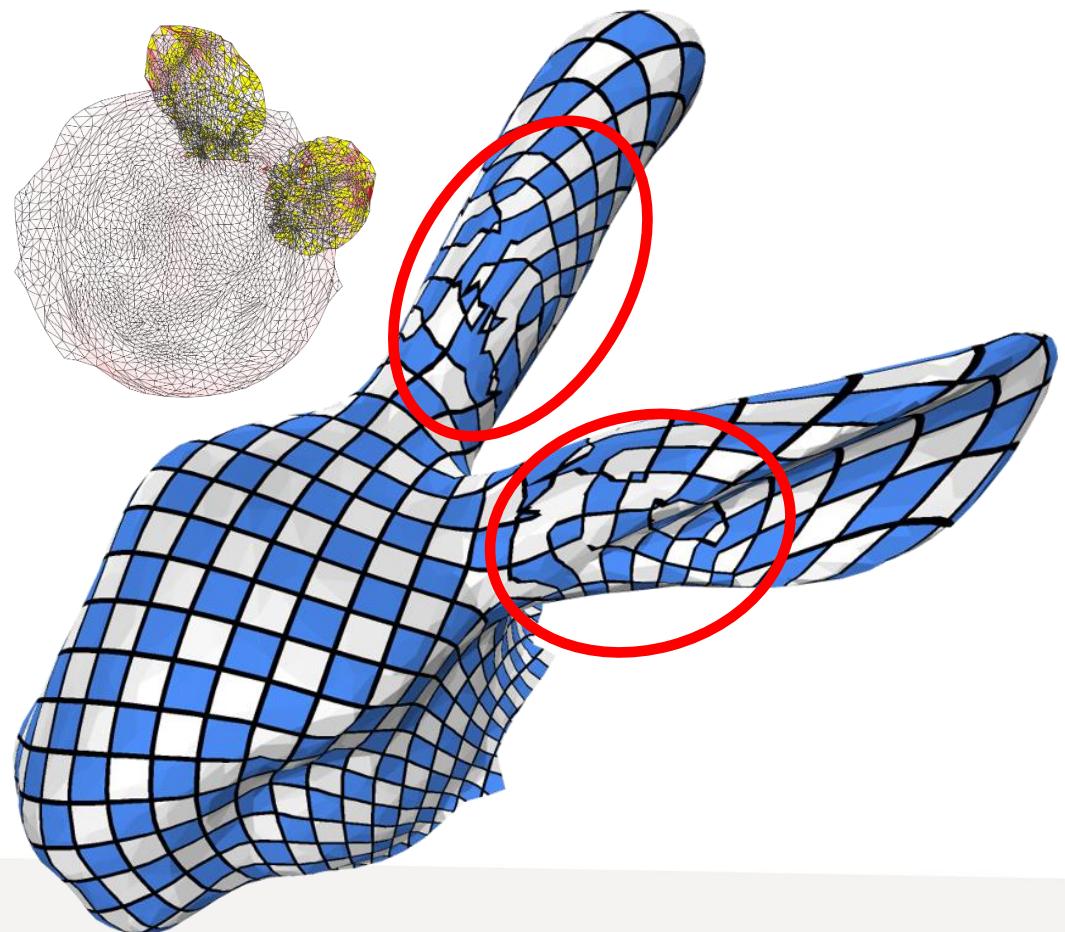
- Low distortion



Two Basic Requirements

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- Foldover-free



Existing Work

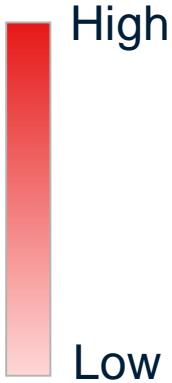
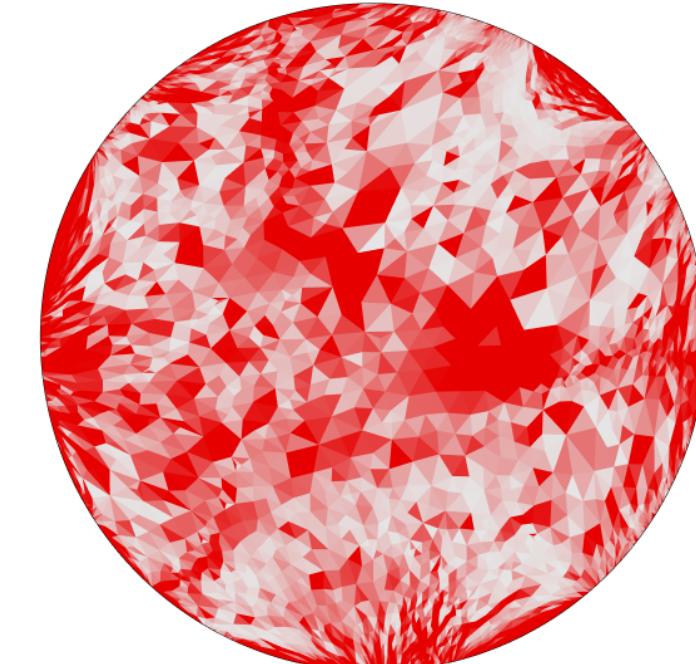
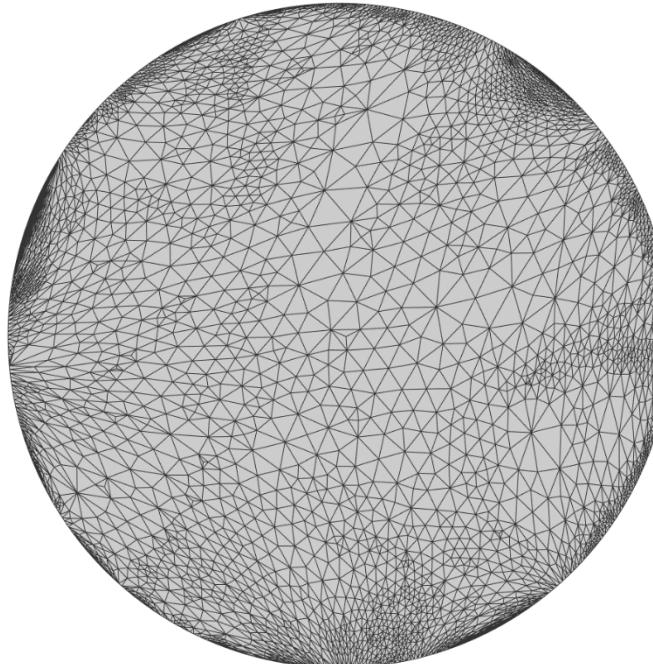
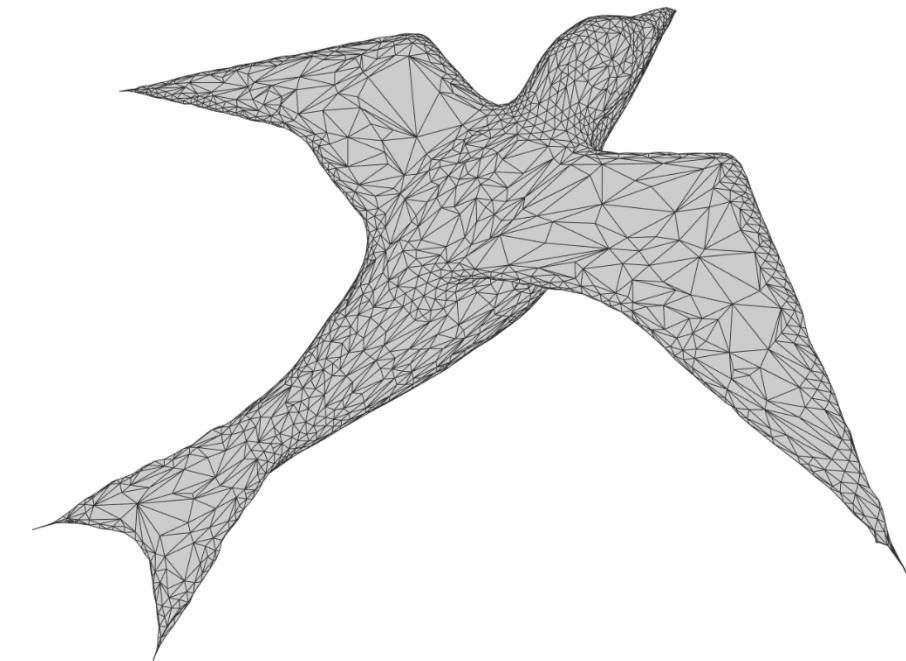
Geometric Standpoint

- Local/global methods [Liu et al. 2008; Sorkine and Alex 2007]
- Bounded distortion methods [Aigerman et al. 2014; Kovalsky et al. 2015; Lipman 2012]
- Representation based methods [Chien et al. 2016b; Fu and Liu 2016; Sheffer et al. 2005]

They cannot guarantee foldover-free!

Tutte's Embedding Method

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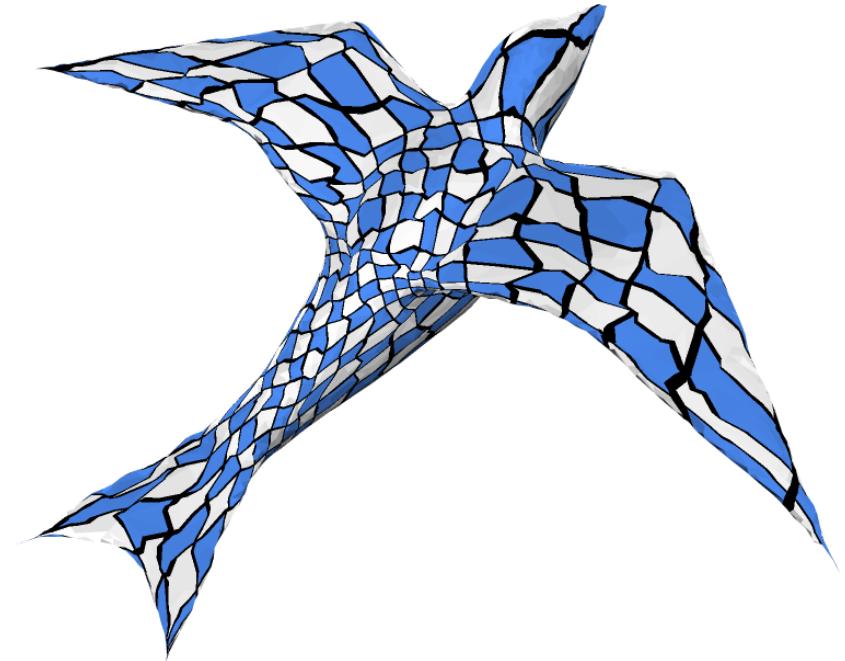
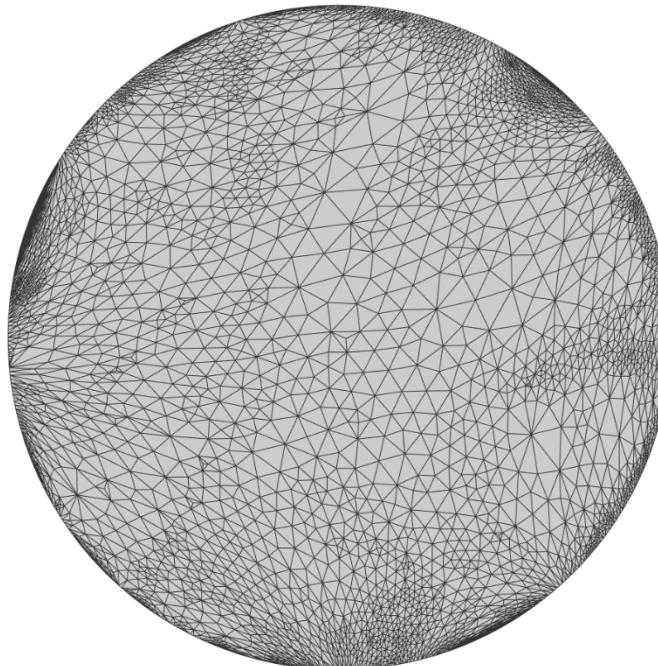
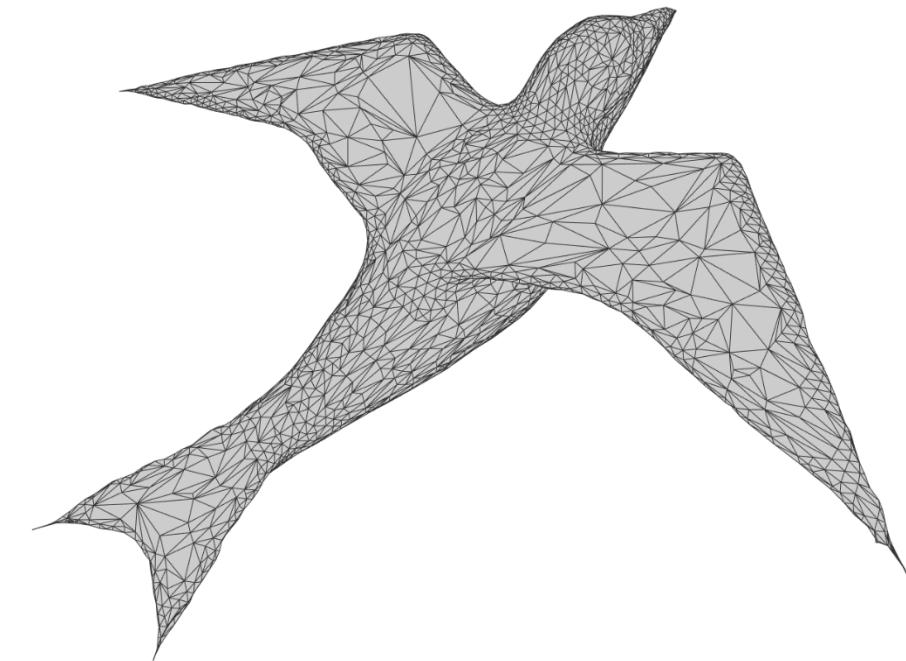


Convex boundary
Bijection guarantee

High distortion

Tutte's Embedding Method

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Convex boundary
Bijection guarantee

High distortion

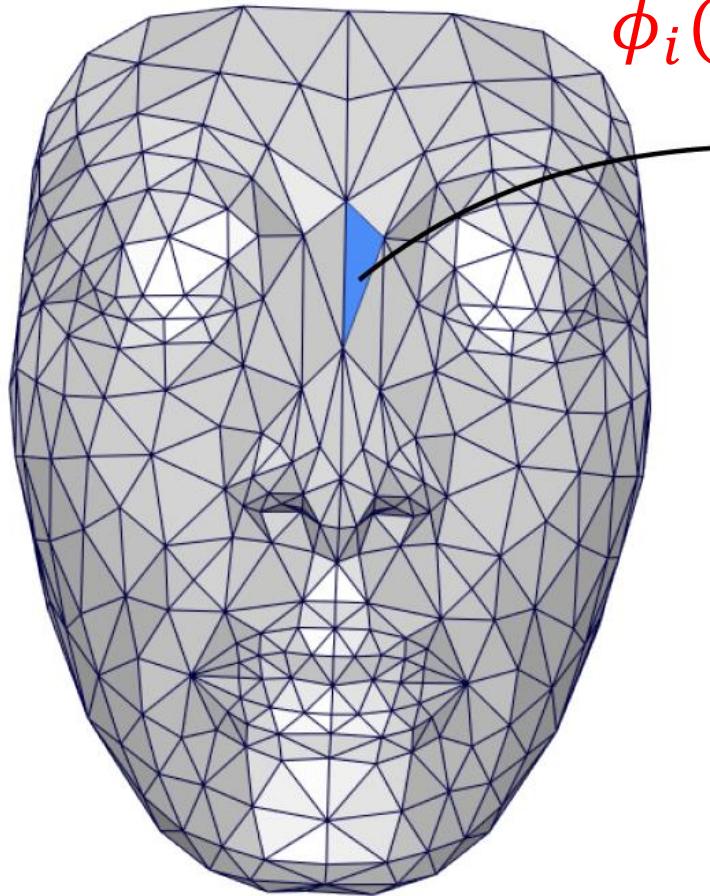
Maintenance-based Methods

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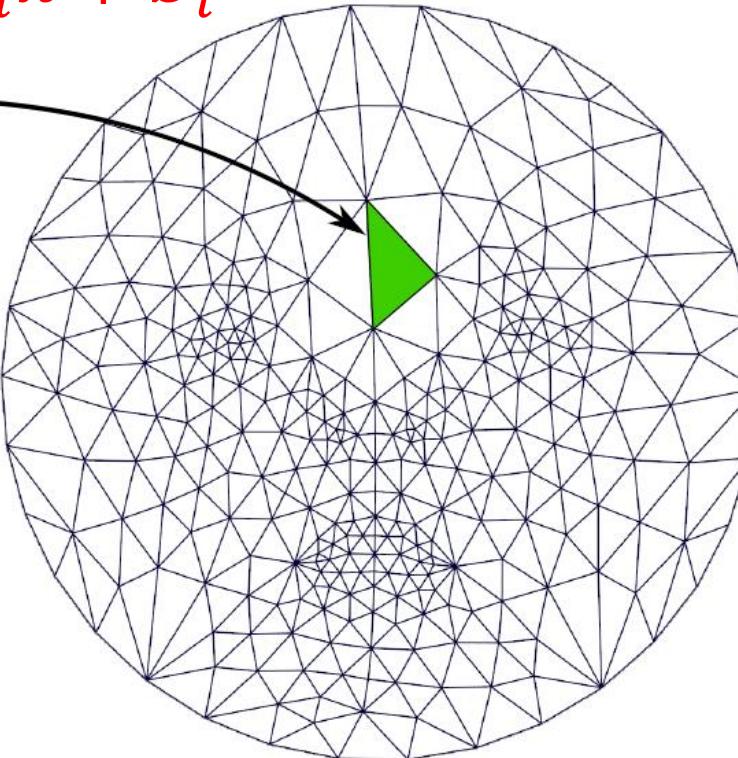
- Not violate the foldover-free constraints.



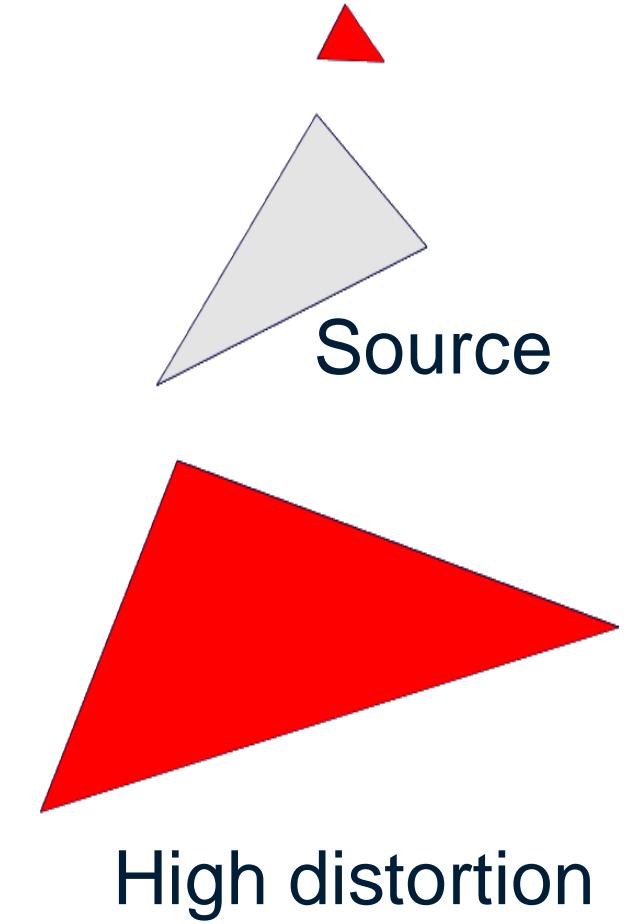
Distortion Measures



$$\phi_i(x) = J_i x + b_i$$



High distortion



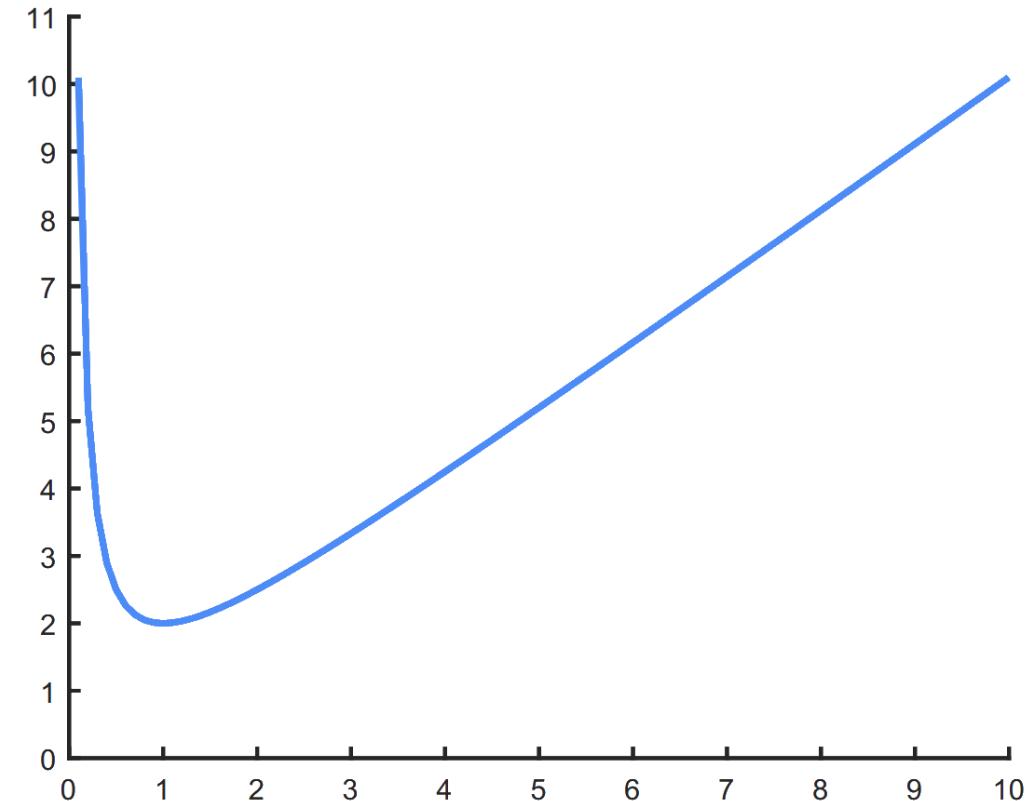
Distortion Measures

- Symmetric Dirichlet metric: [Smith and Schaefer 2015]

$$\begin{aligned} D(J_i) &= \frac{1}{4} \left(\|J_i\|_F^2 + \|J_i^{-1}\|_F^2 \right) \\ &= \frac{1}{4} \left(\sigma_i^2 + \sigma_i^{-2} + \tau_i^2 + \tau_i^{-2} \right) \end{aligned}$$

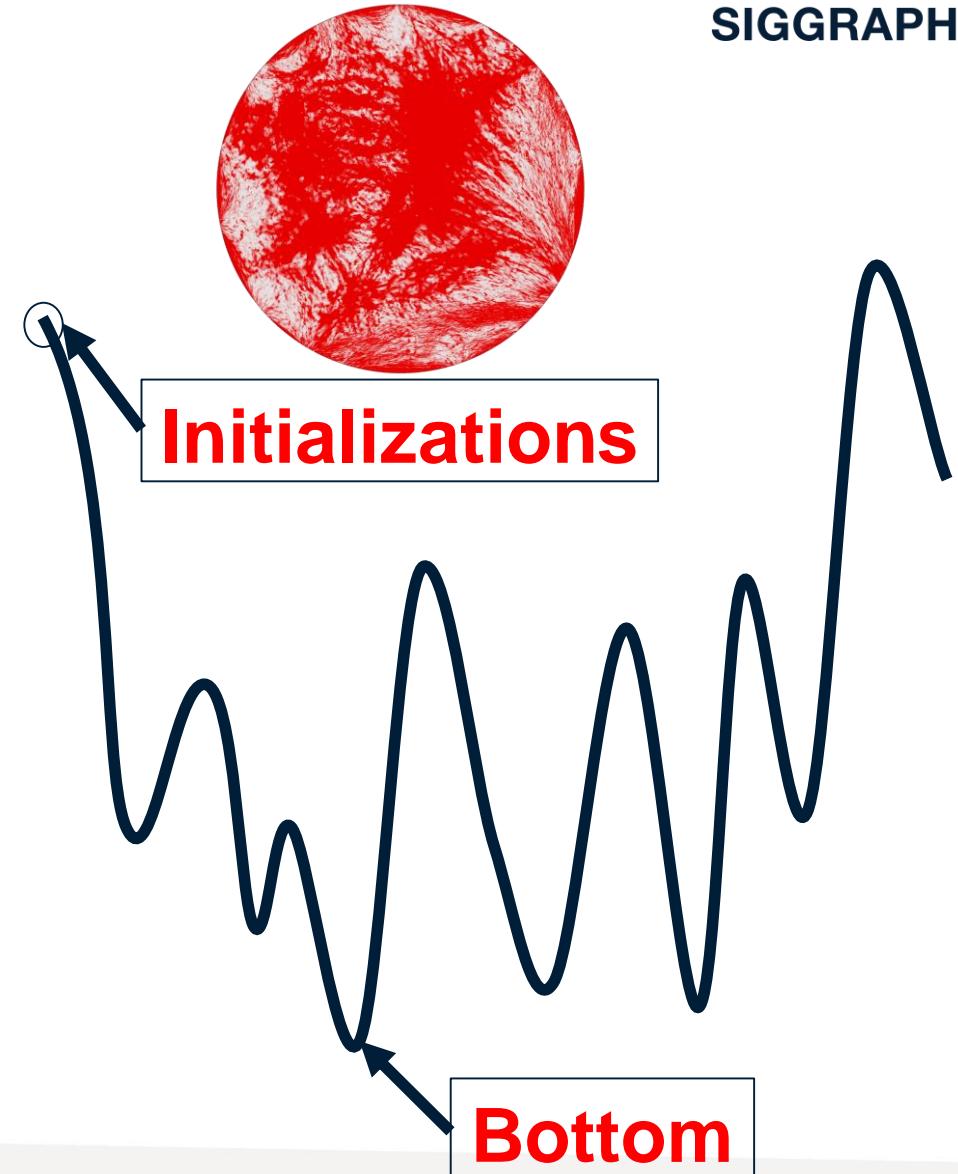
σ_i, τ_i : singular values of J_i

Opt value = 1 when $\sigma_i = \tau_i = 1$



Challenge

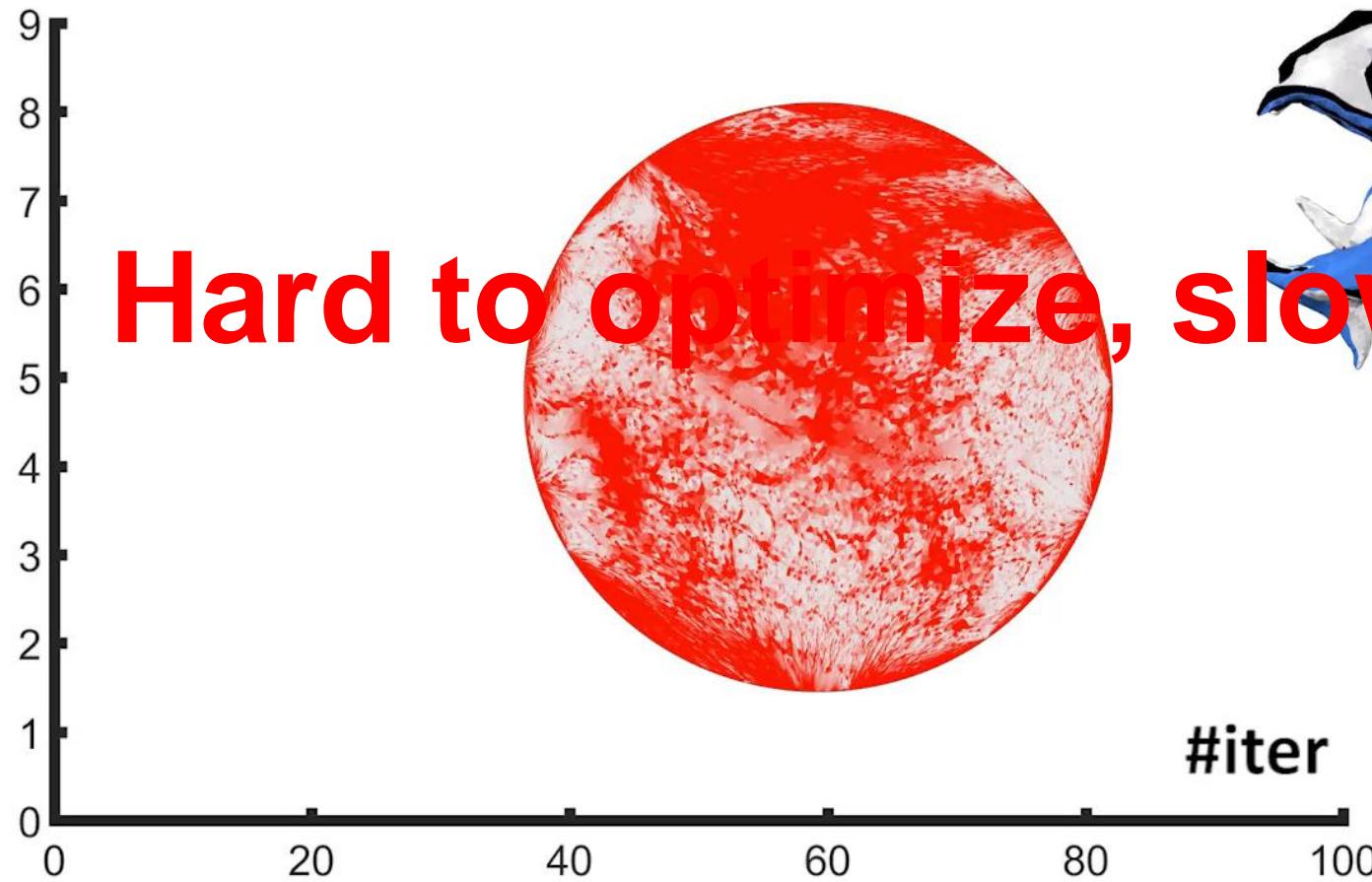
- Highly non-convex and non-linear
- Extremely large distortion on initializations



Challenge

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$\log(\text{energy})$



Existing Work

Optimization Standpoint

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- Block coordinate descent methods [Fu et al. 2015; Hormann and Greiner 2000]
- Quasi-Newton method [Smith and Schaefer 2015]
- Preconditioning methods [Claici et al. 2017; Kovalsky et al. 2016]
- Reweighting descent method [Rabinovich et al. 2017]
- Composite majorization method [Shtengel et al. 2017]

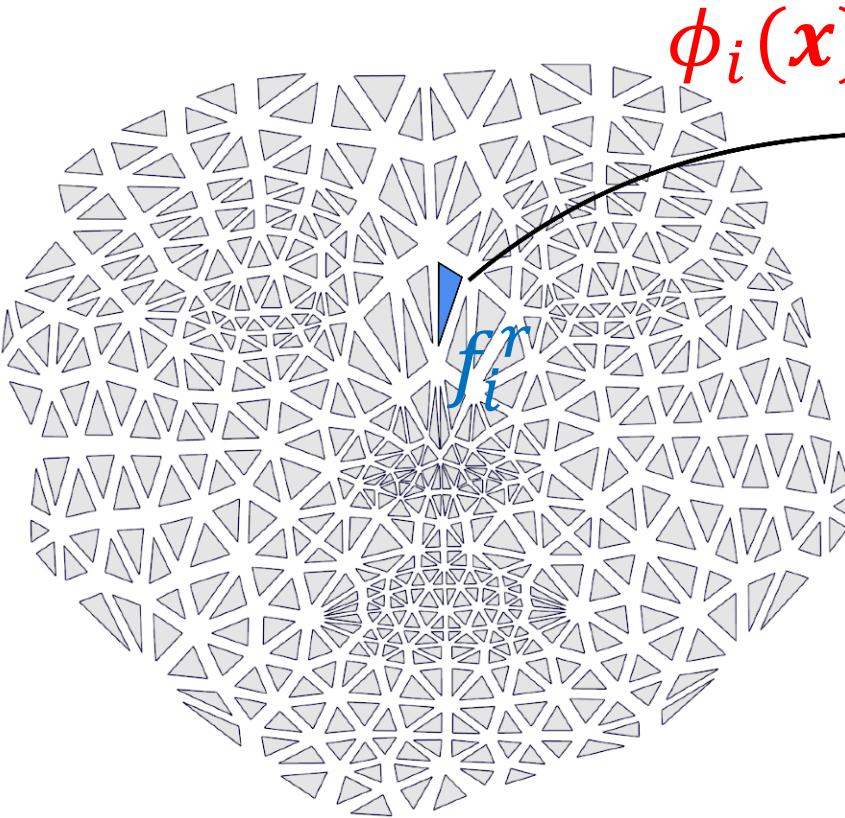
Only thinking from the view of solver!

Our Approach

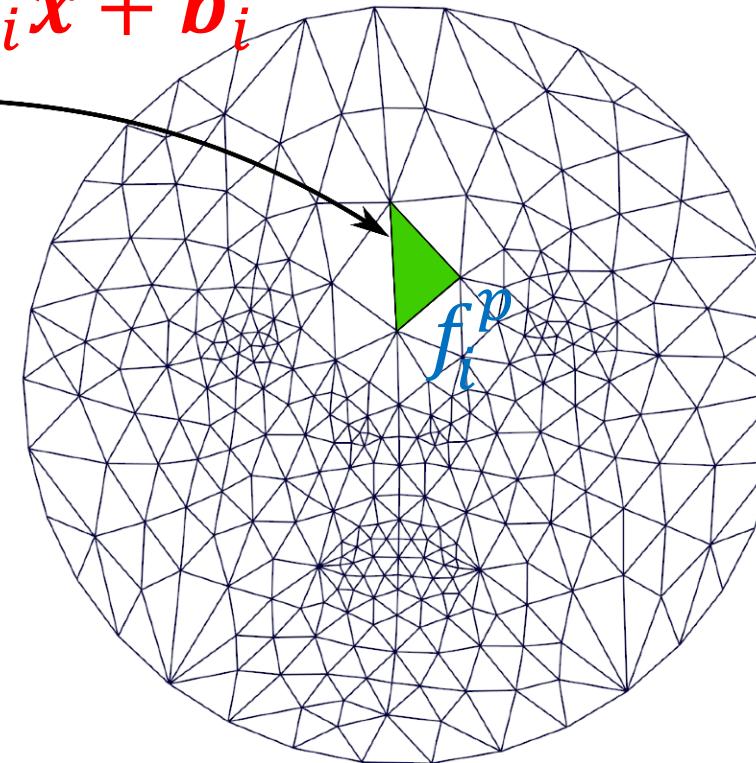
Progressive Parameterizations

Reference-guided Distortion Metric

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Reference M^r : A set of individual triangles

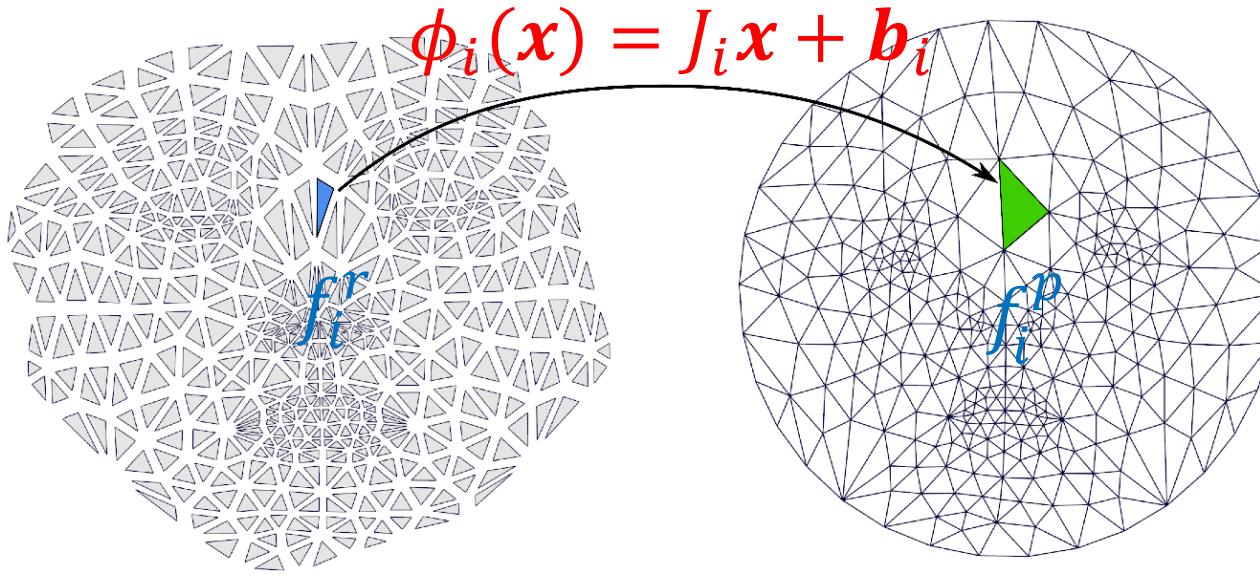


Parameterized mesh M^p

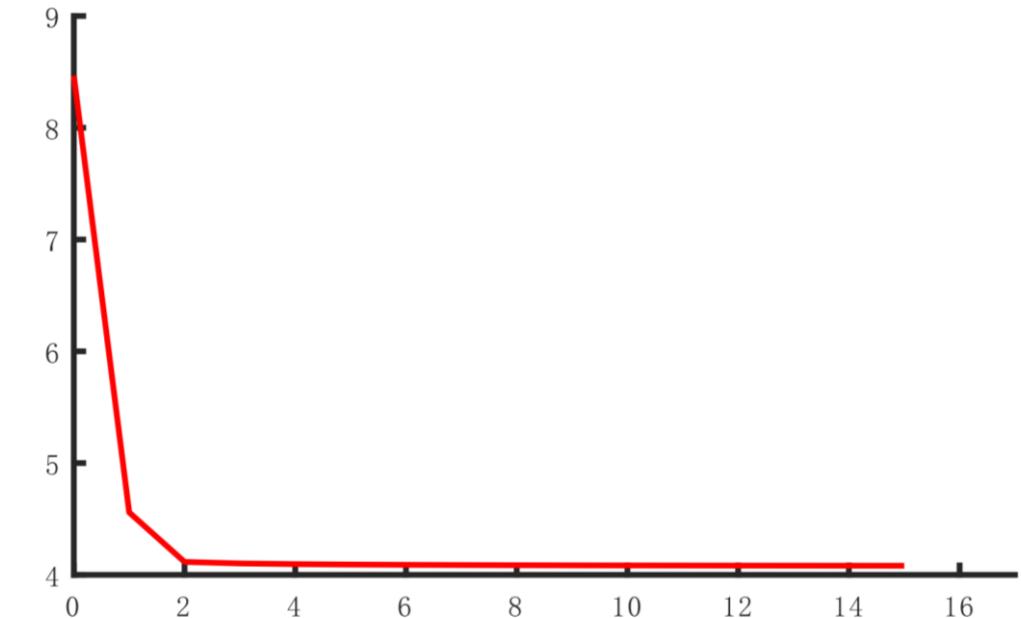
Distortion Metric:
 $D(f_i^r, f_i^p) = D(J_i)$

Input Mesh:
Ideal Reference

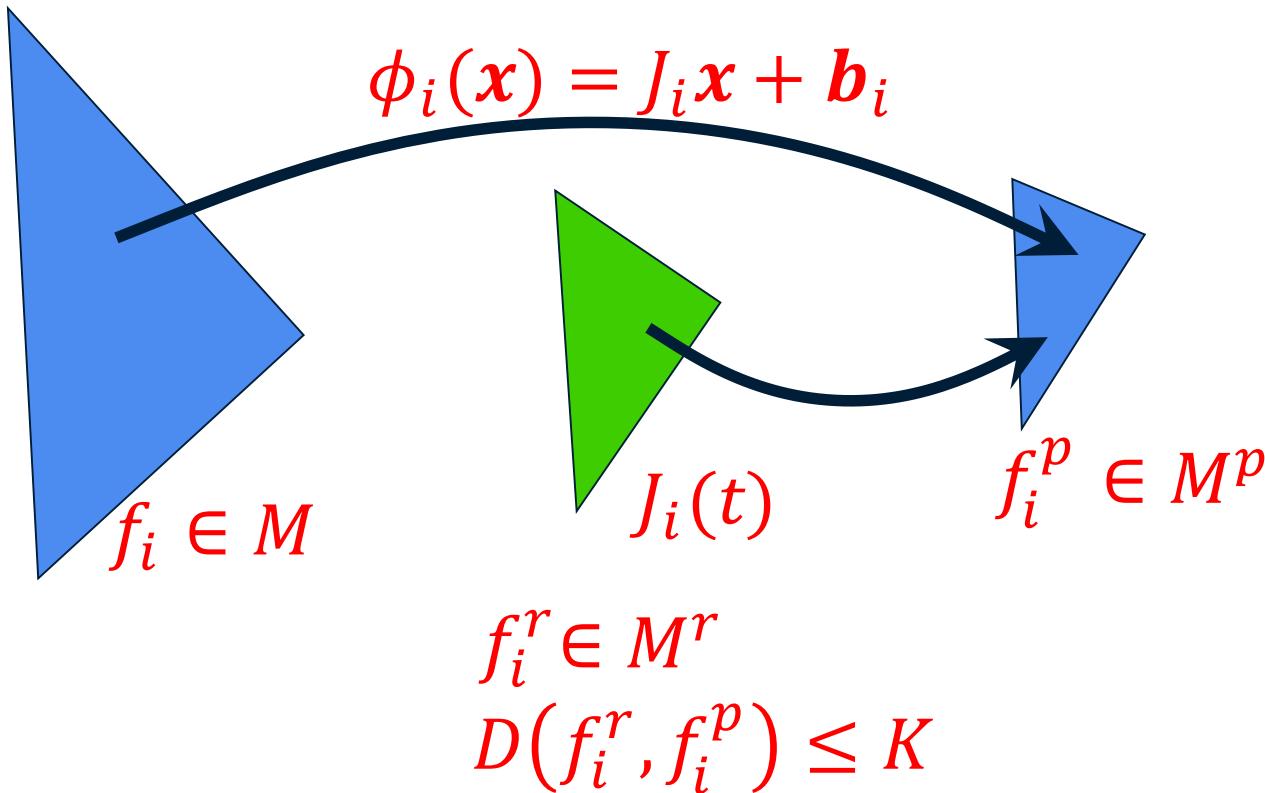
Key Observation



If all $D(f_i^r, f_i^p) \leq K, \forall i$, only a few iterations in the optimization of $E(M^r, M^p)$ are necessary.



Change The Reference



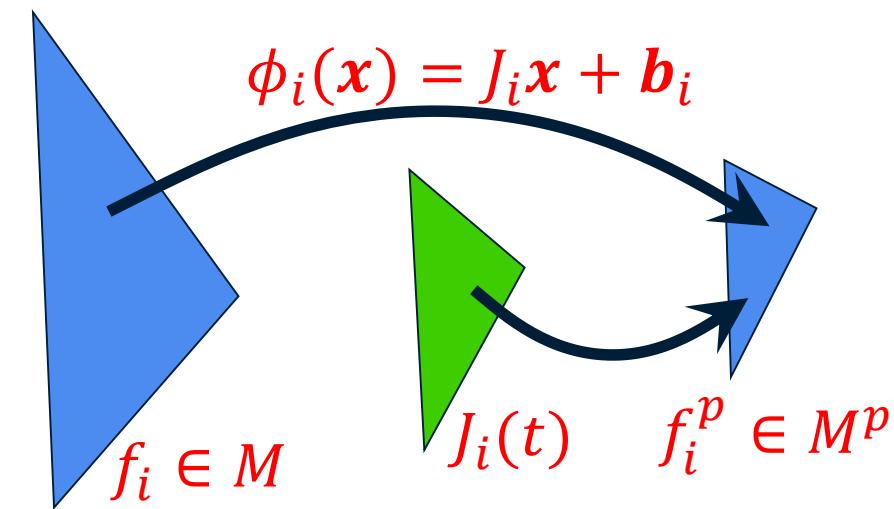
Goal: find a triangle between f_i and f_i^p as the reference f_i^r that satisfies $D(f_i^r, f_i^p) \leq K$.

Choose The Reference

- Exponential function [Alexa 2002; Grassia 1998; Rossignac and Vinacua 2011]:

$$J_i(t) = U_i \text{diag}(\sigma_i^t, \tau_i^t) V_i^T$$

$$\text{where } J_i = U_i \text{diag}(\sigma_i, \tau_i) V_i^T$$



Construction of new reference

Optimization Of The New Reference

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Progressively Construct New Reference!



Tutte's
Initialization



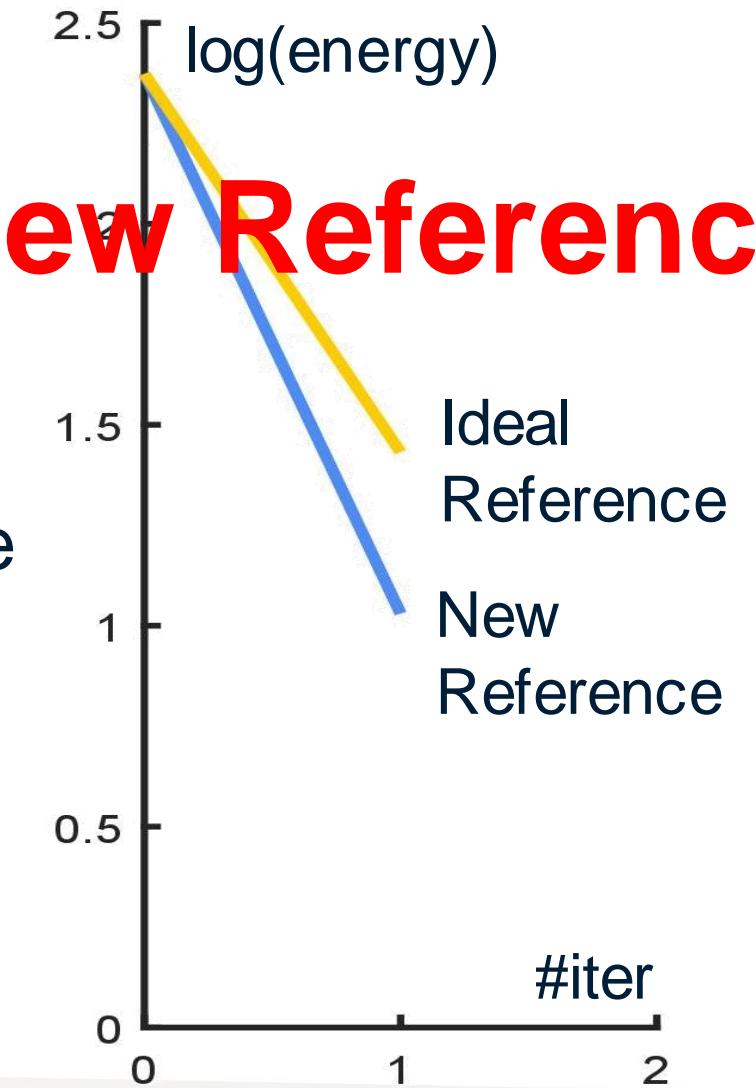
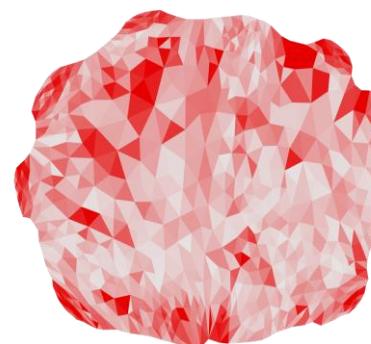
Ideal Reference



SLIM [Rabinovich et al. 2017]

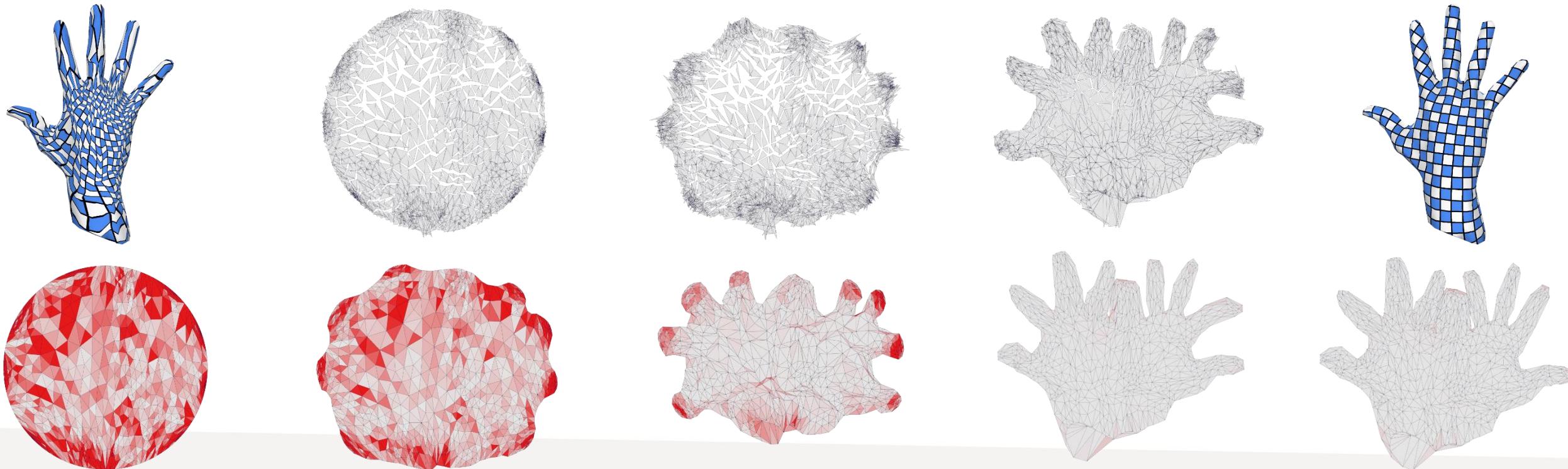
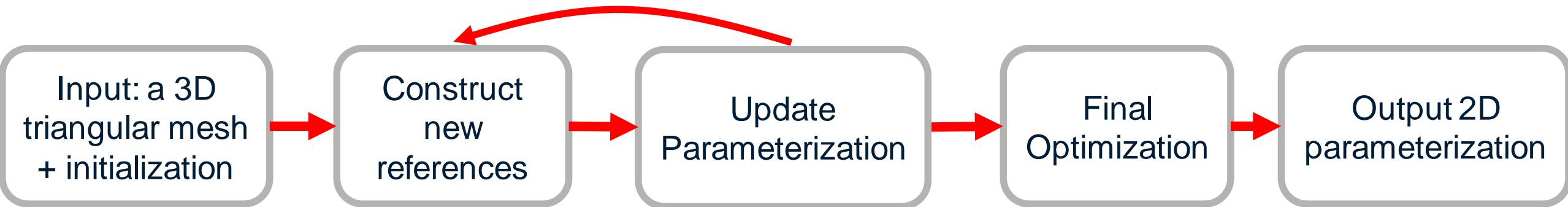


New Reference



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Hybrid Solver

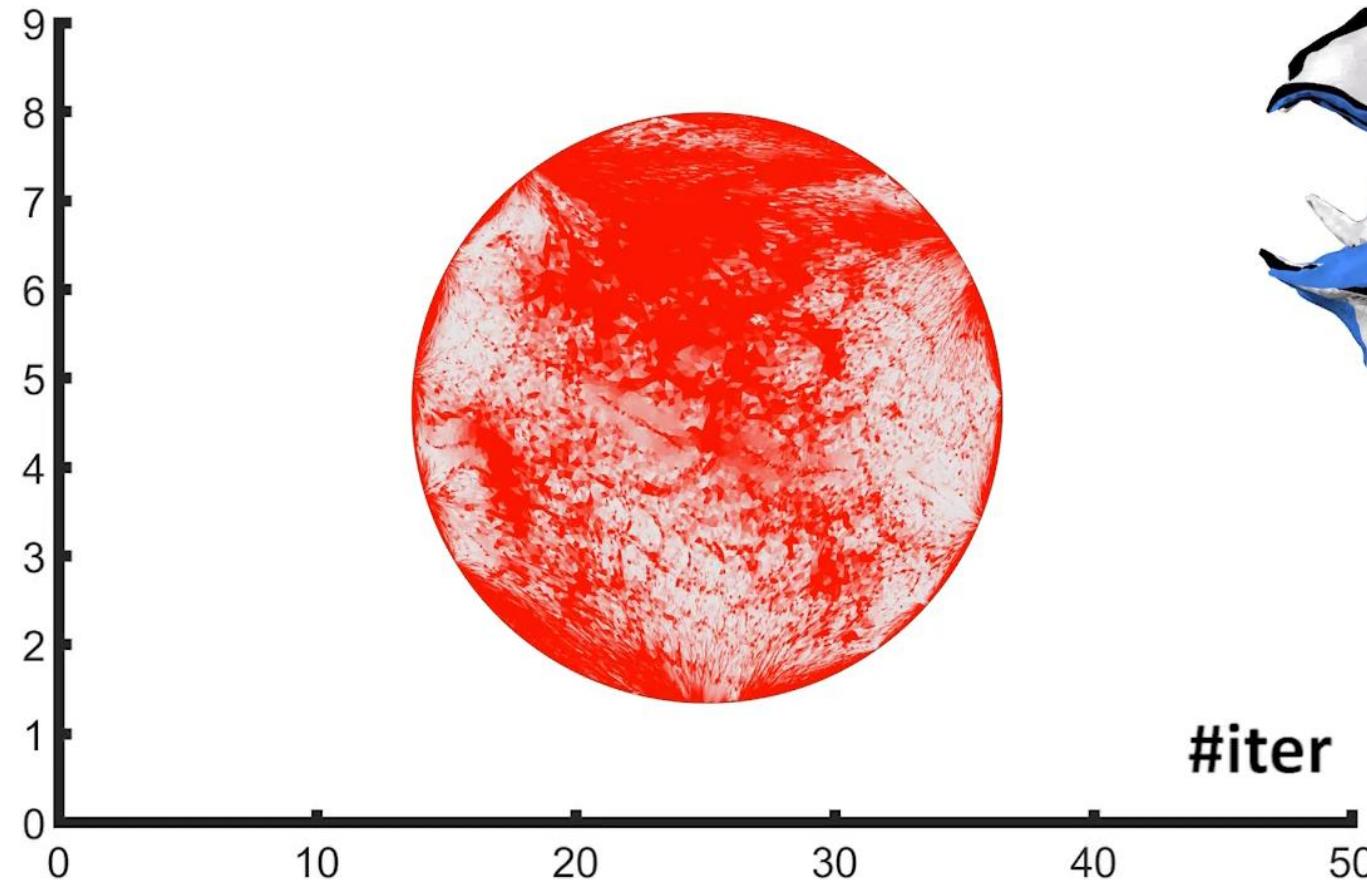
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- SLIM [Rabinovich et al. 2017]
 - Pros: effectively penalize the maximum distortion
 - Cons: a poor convergence rate
- CM [Shtengel et al. 2017]
 - Pros: converge quickly
 - Cons: cannot reduce large distortion quickly
- Hybrid
 - First perform SLIM solver
 - Then use the CM solver

The Former Dragon Example

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$\log(\text{energy})$



Experiments

AKVF [Claici et al. 17]

CM [Shtengel et al. 17]

SLIM [Rabinovich et al. 17]

Ours

2x playback

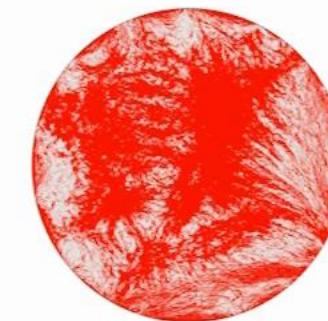


log(energy)

6
5
4
3
2
1
0

time(s)

0 20 40 60 80 100 120 140 160



#V: 900k, #F: 1792k

AKVF

[Claici et al. 17]



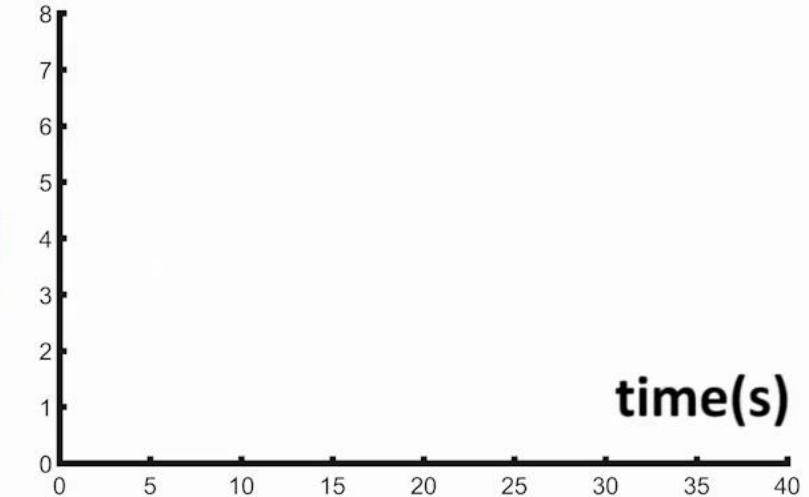
SLIM

[Rabinovich et al. 17]



playback

log(energy)



CM

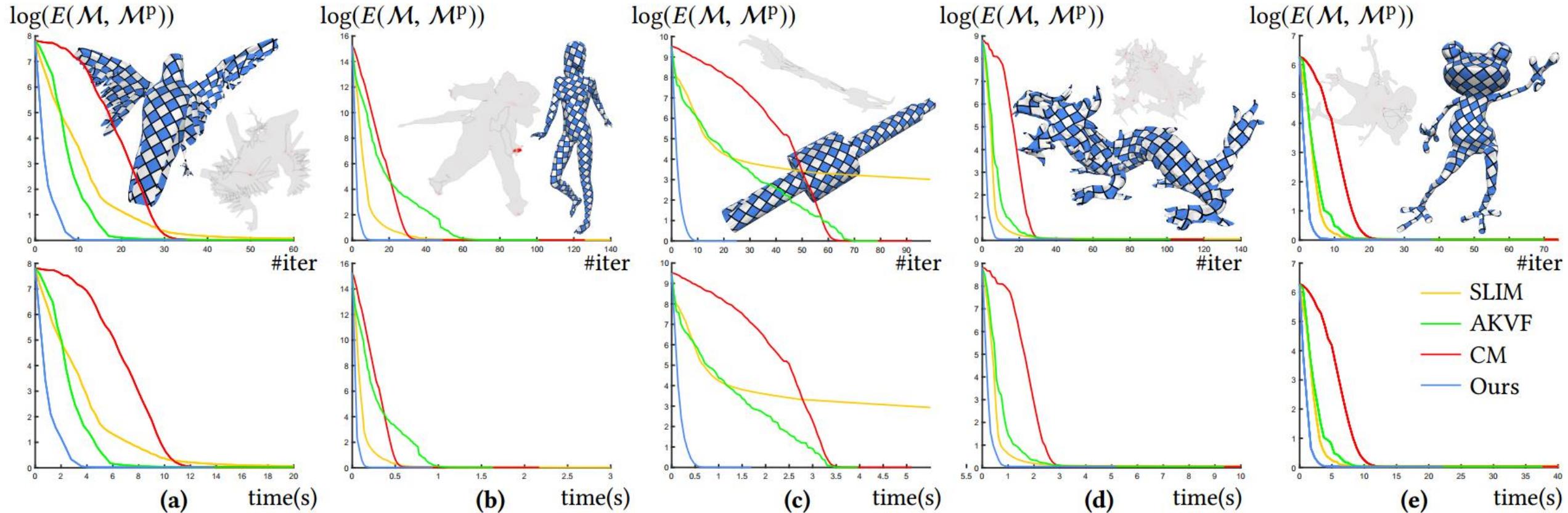
[Shtengel et al. 17]



Ours



#V: 195k, #F: 382k



Benchmark

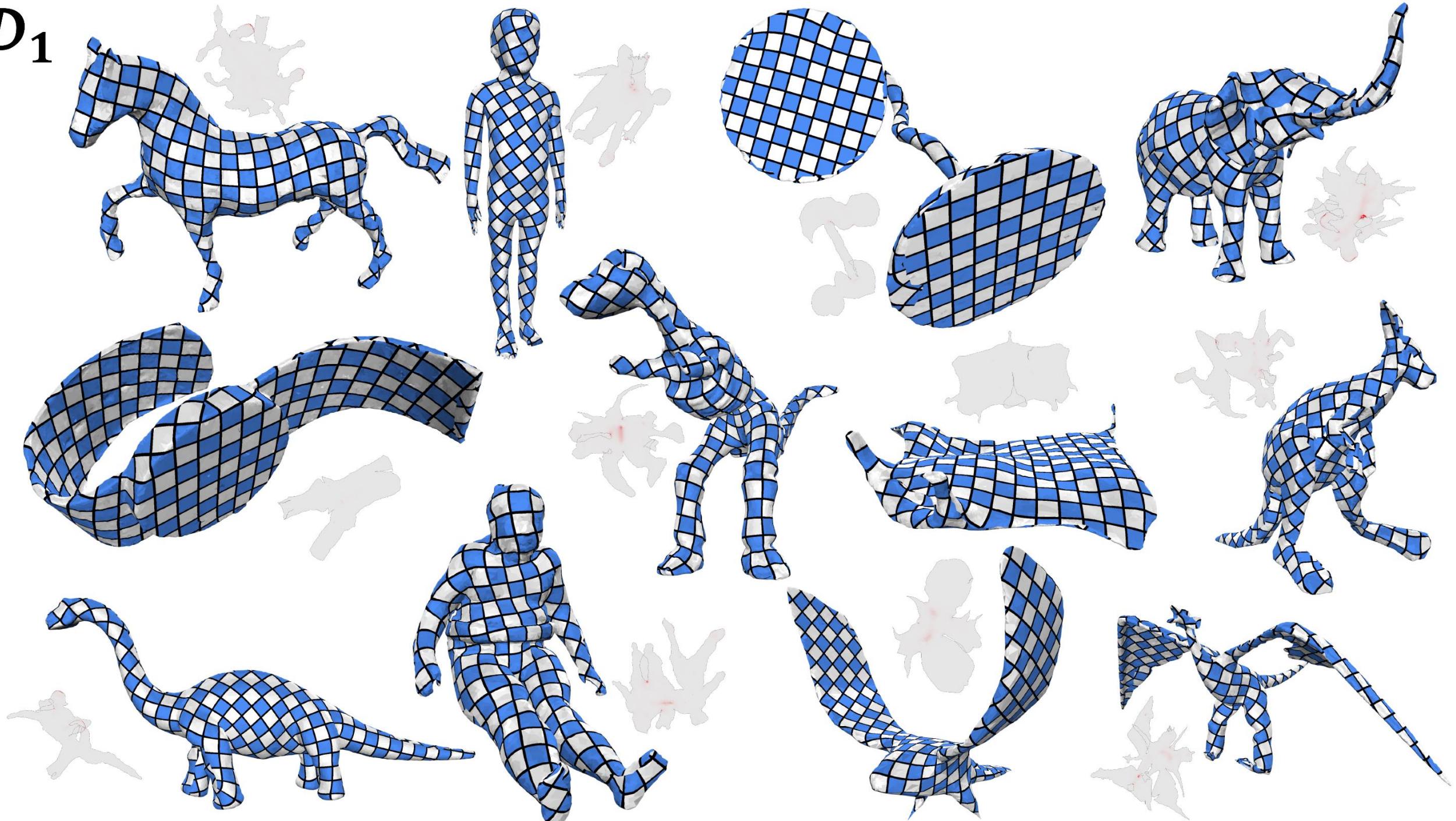
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\mathcal{D}_1 : **10273** well cut meshes

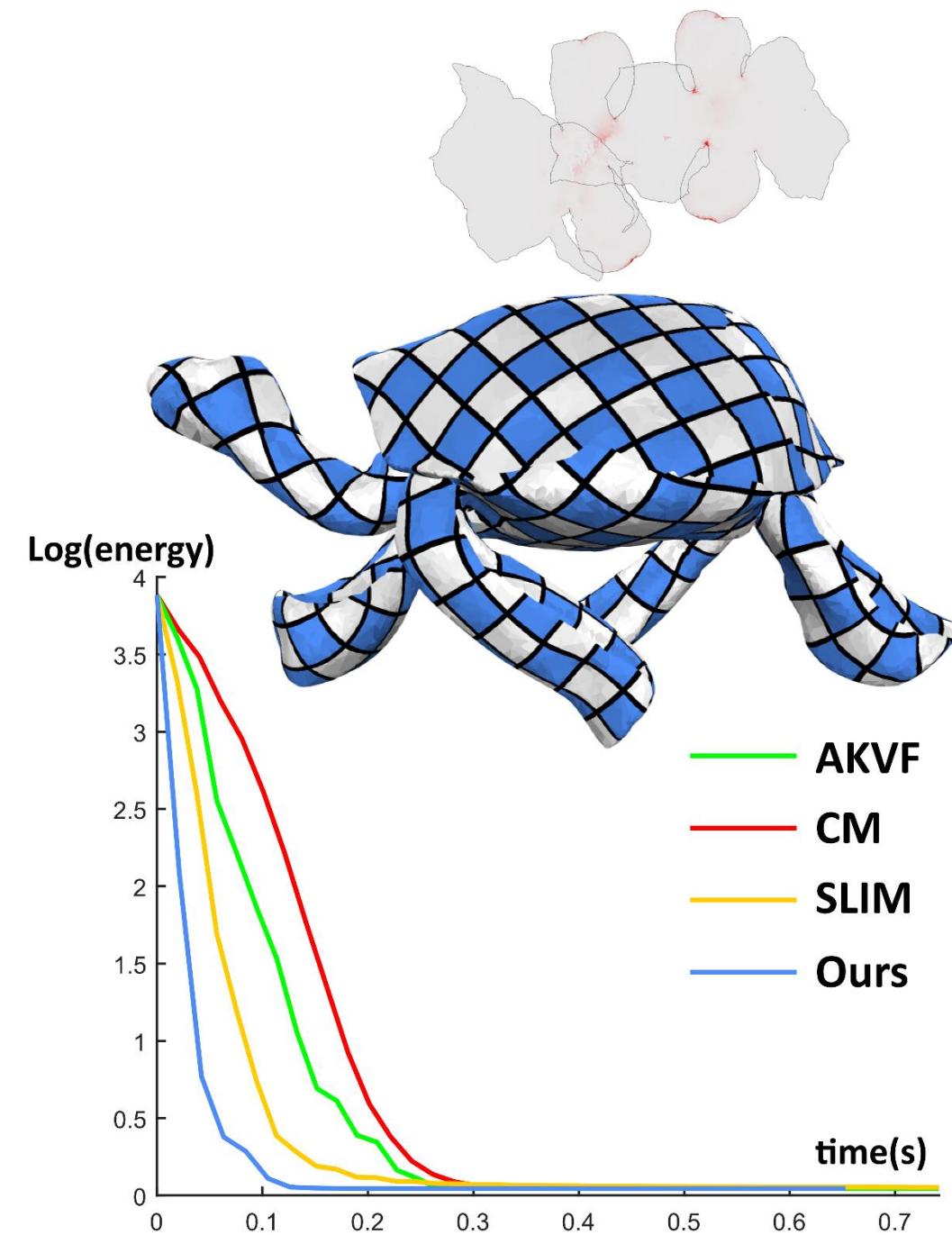
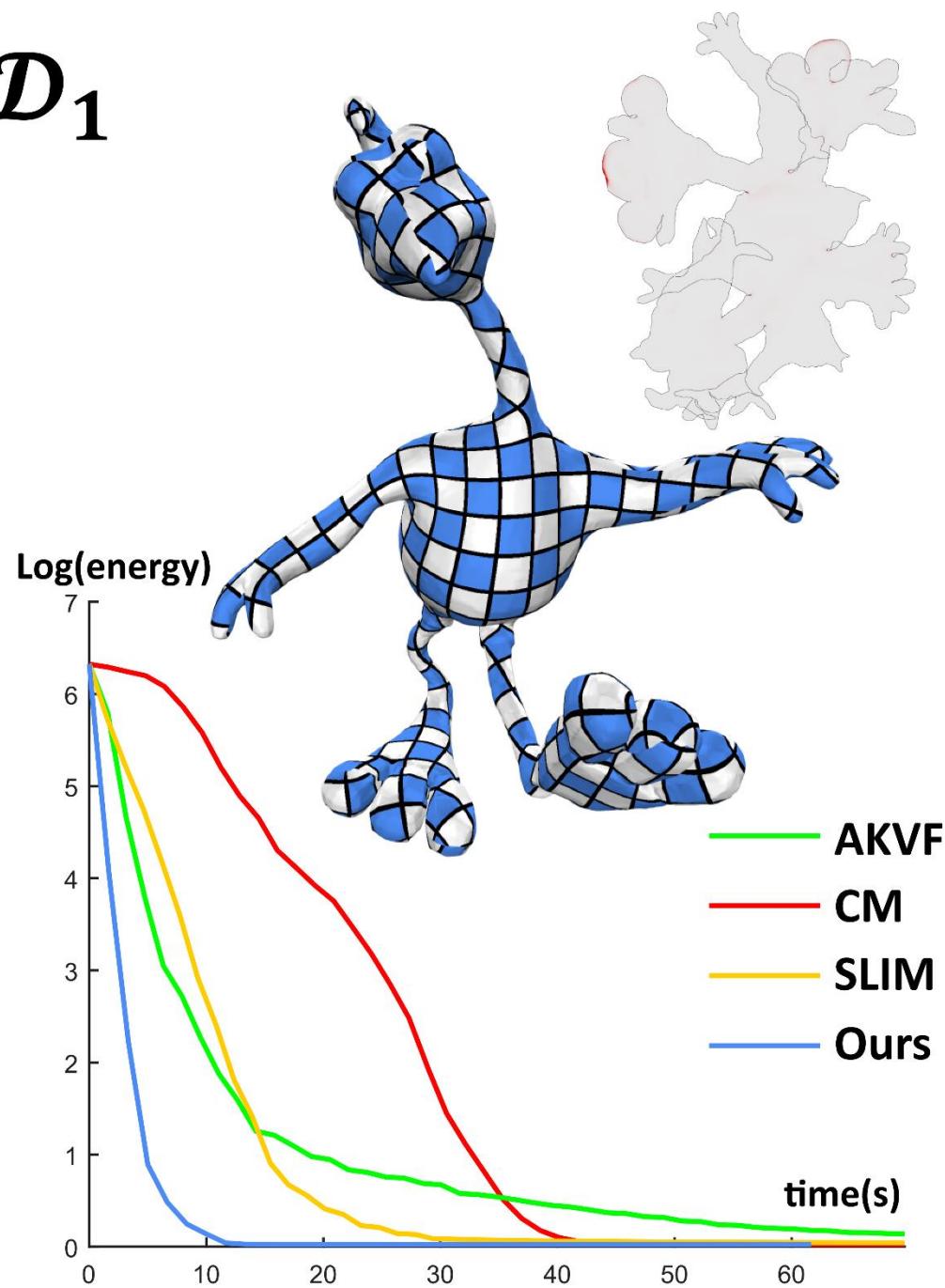
\mathcal{D}_2 : **6189** moderately bad cut meshes

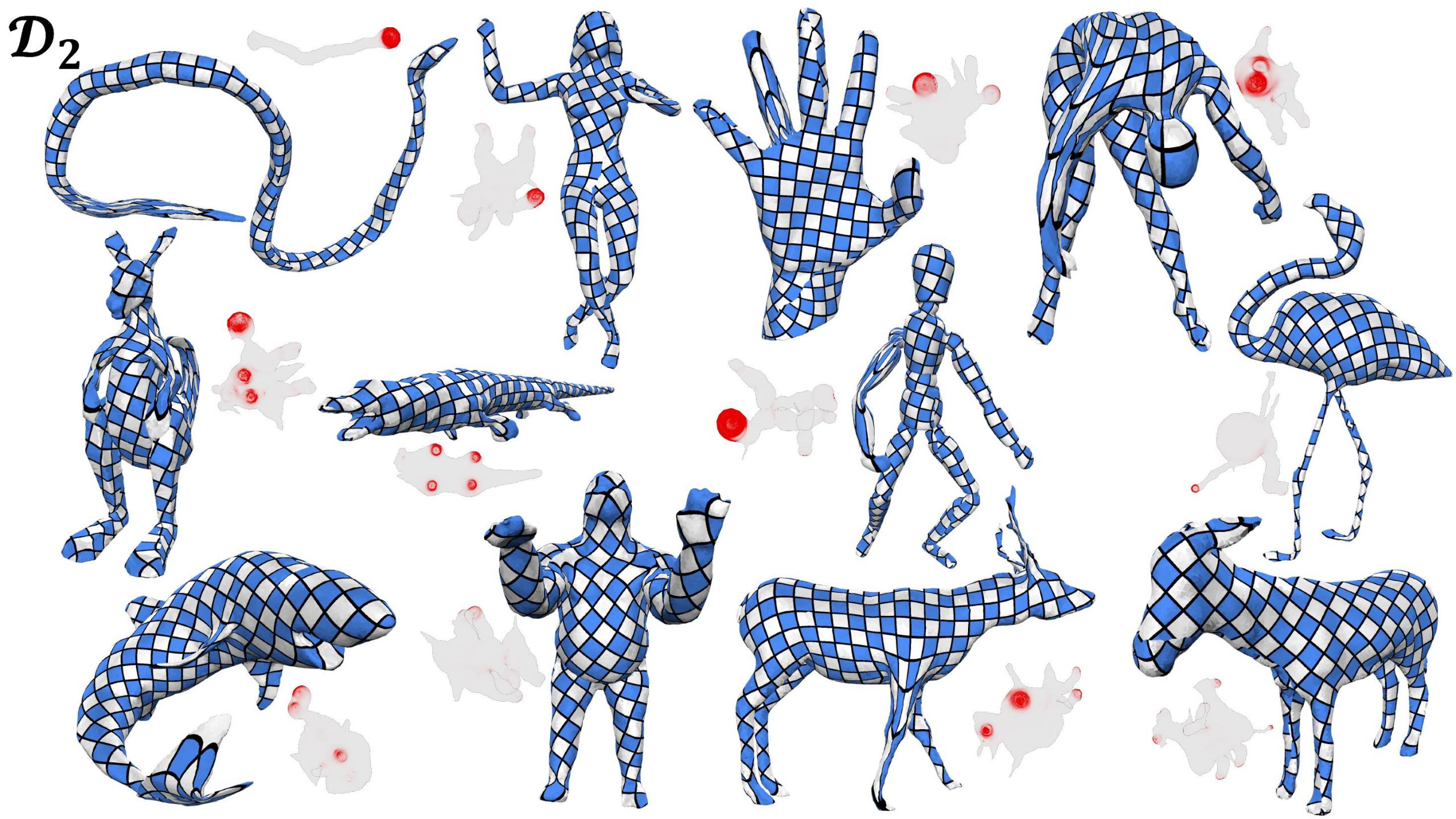
\mathcal{D}_3 : **4250** extremely challenging examples

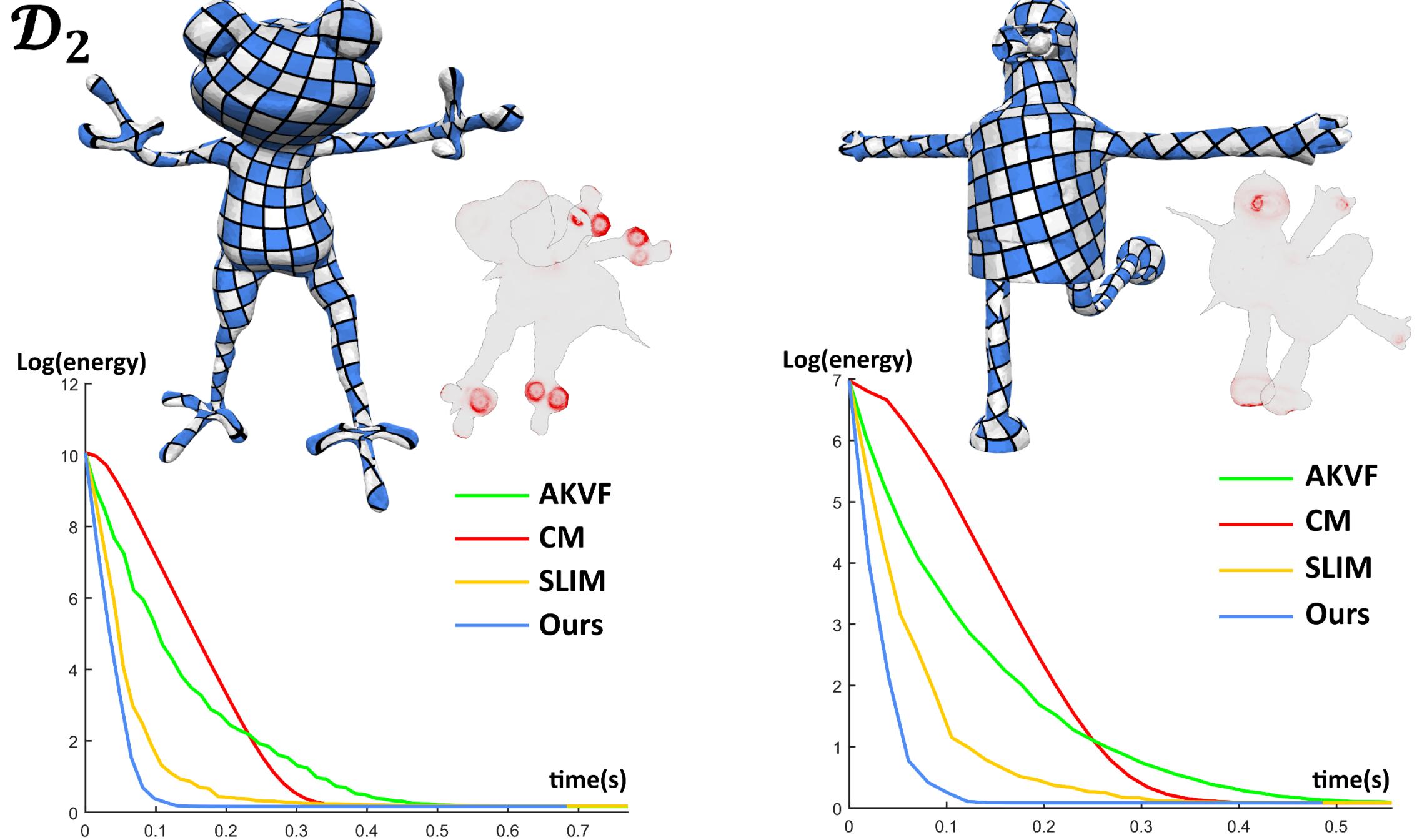
\mathcal{D}_1



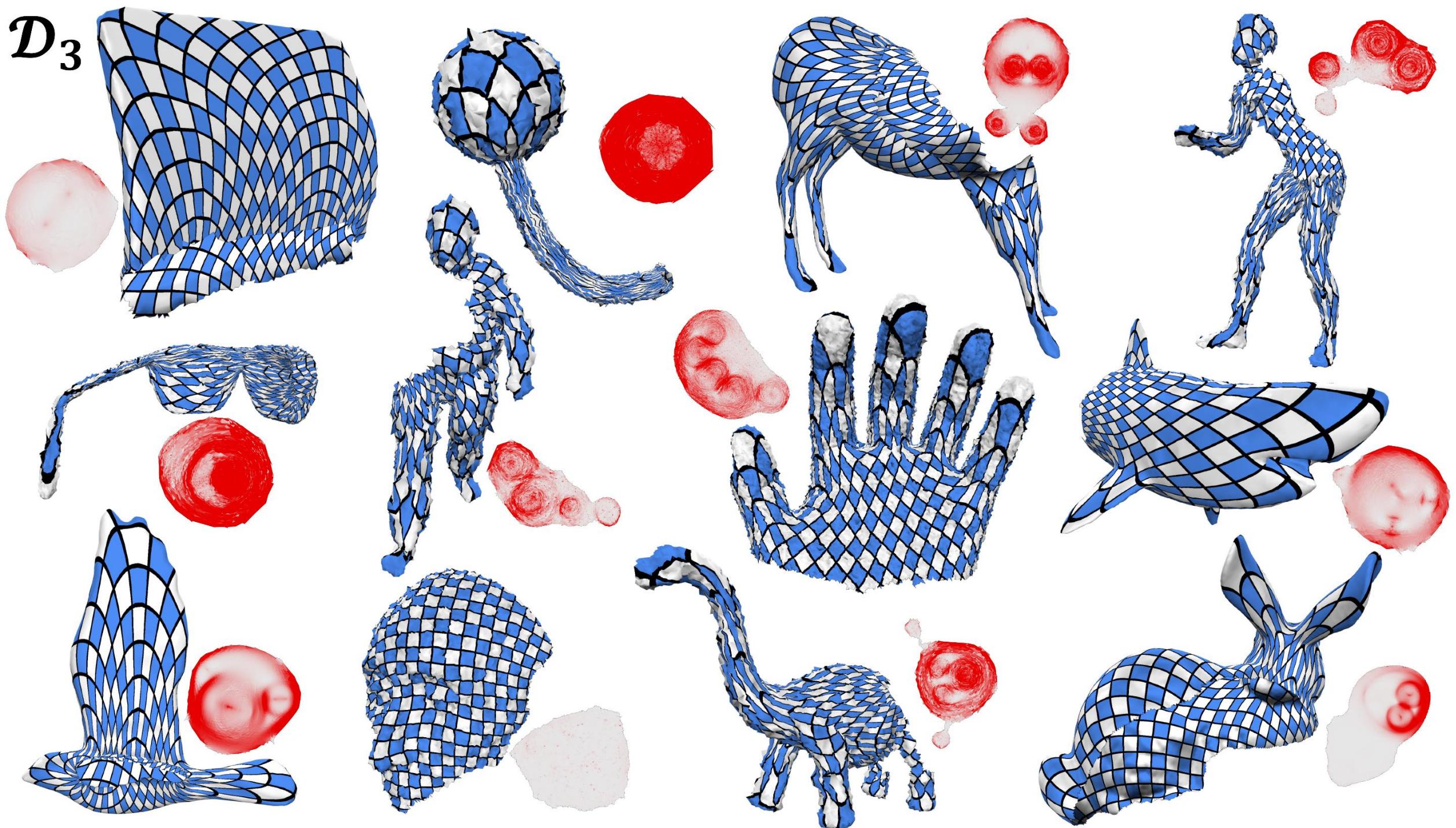
\mathcal{D}_1

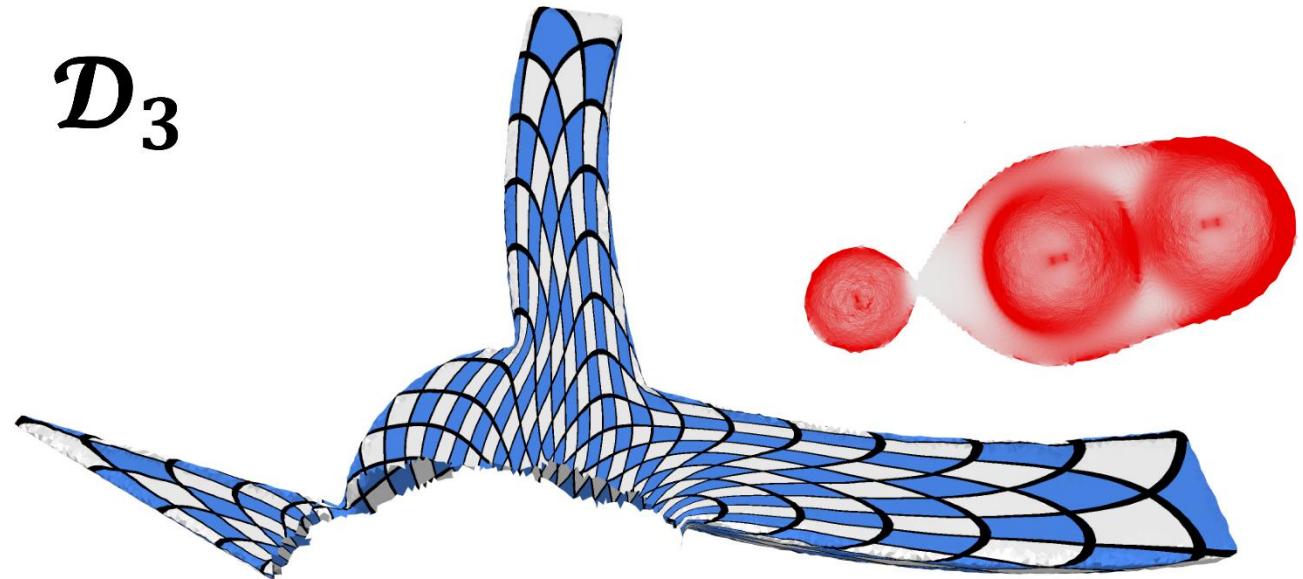


\mathcal{D}_2 

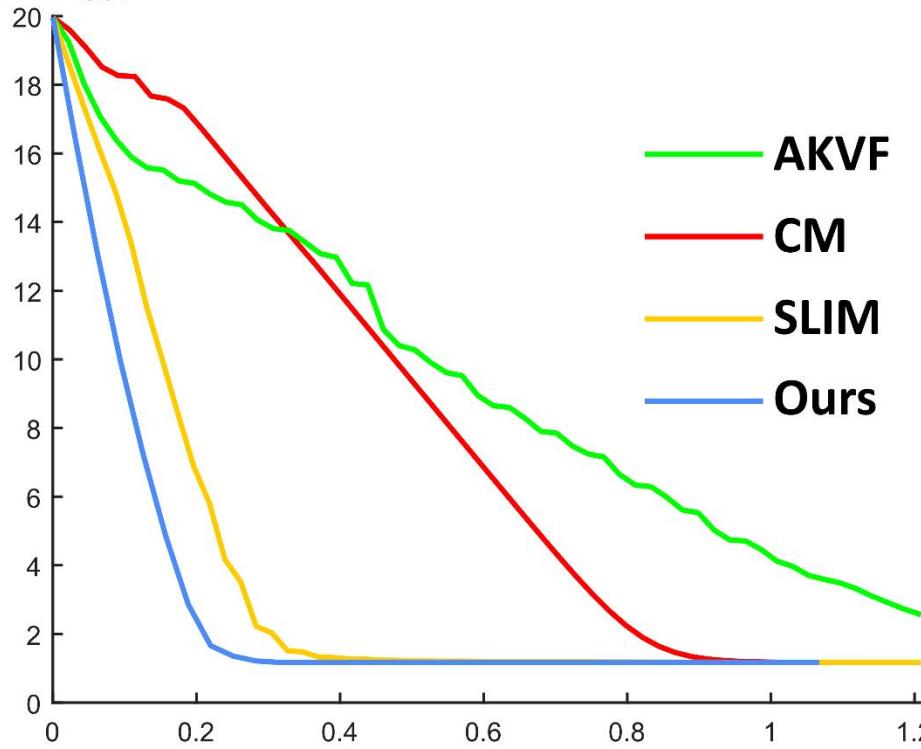


D₃

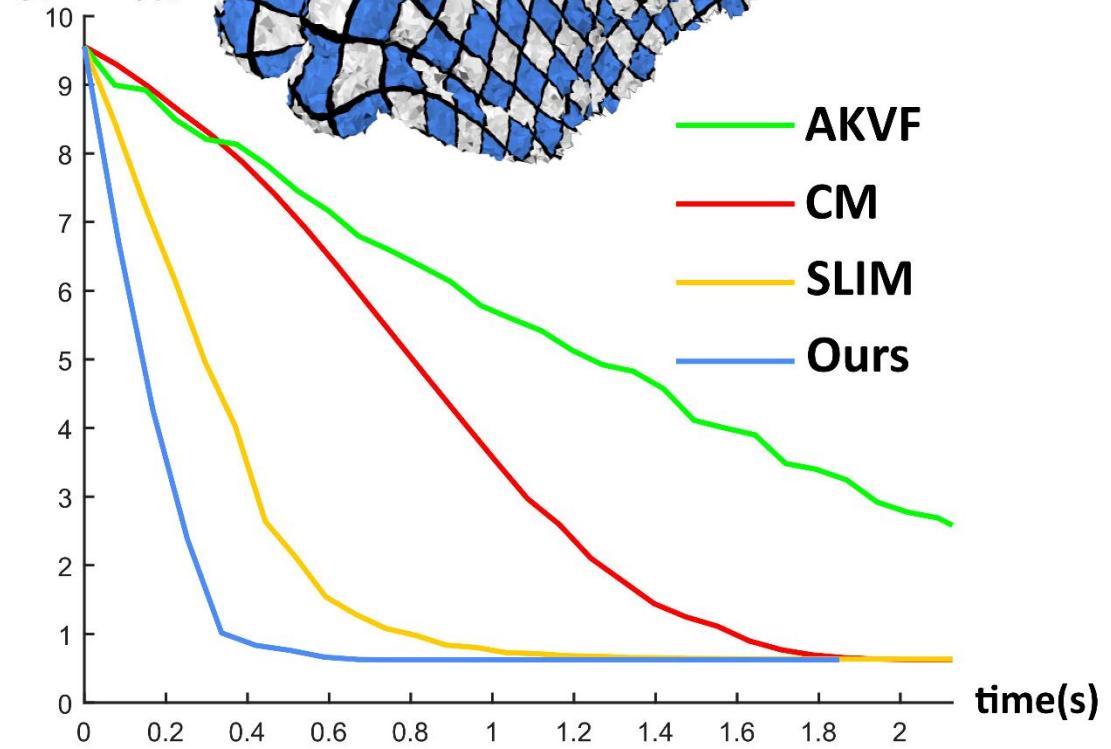


\mathcal{D}_3 

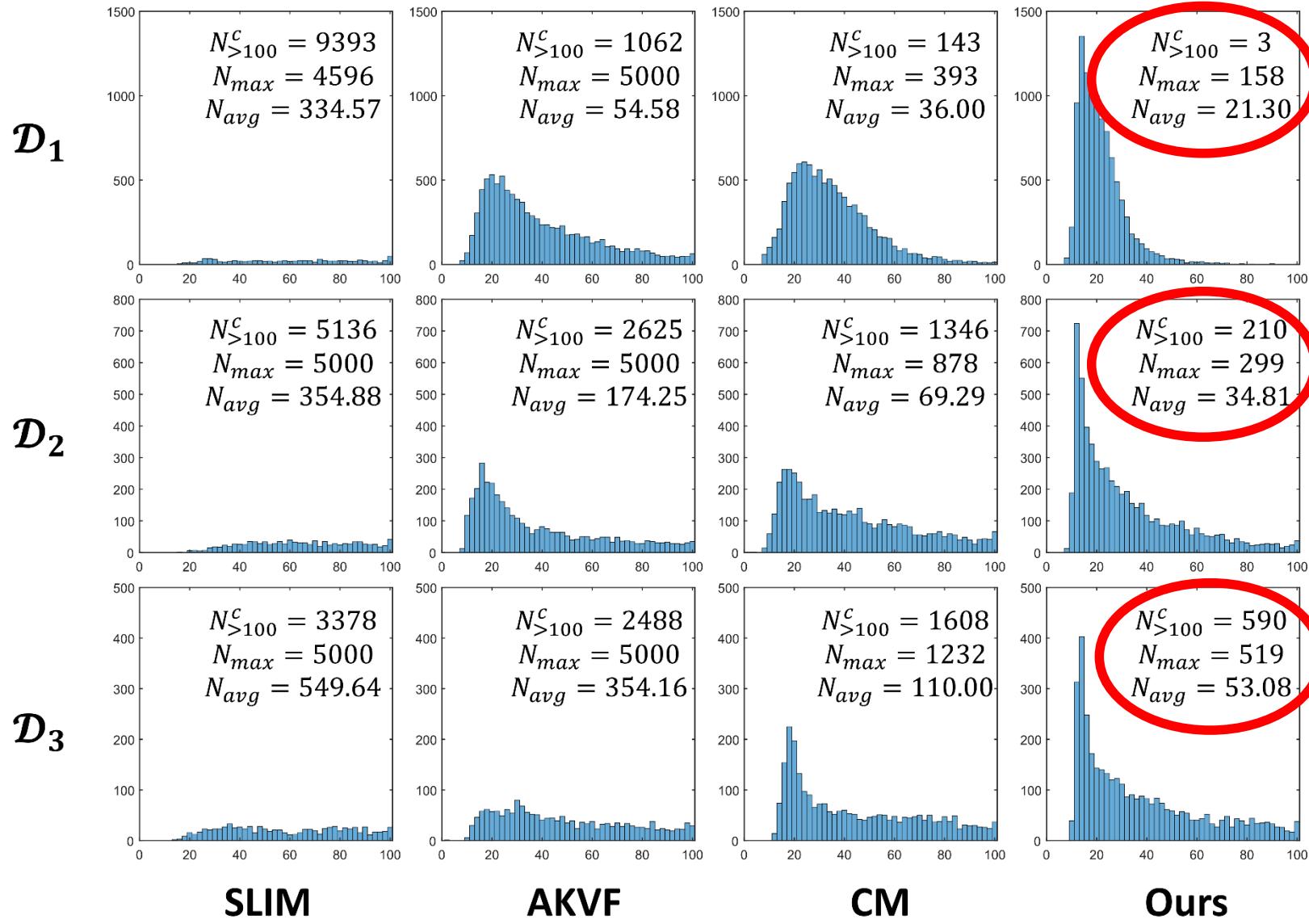
Log(energy)



Log(energy)



Distributions of iteration number



N_c : iteration number of convergence

N_{max} : maximum of N_c

N_{avg} : average of N_c

$N_{>100}^c$: the number of models whose $N_c > 100$

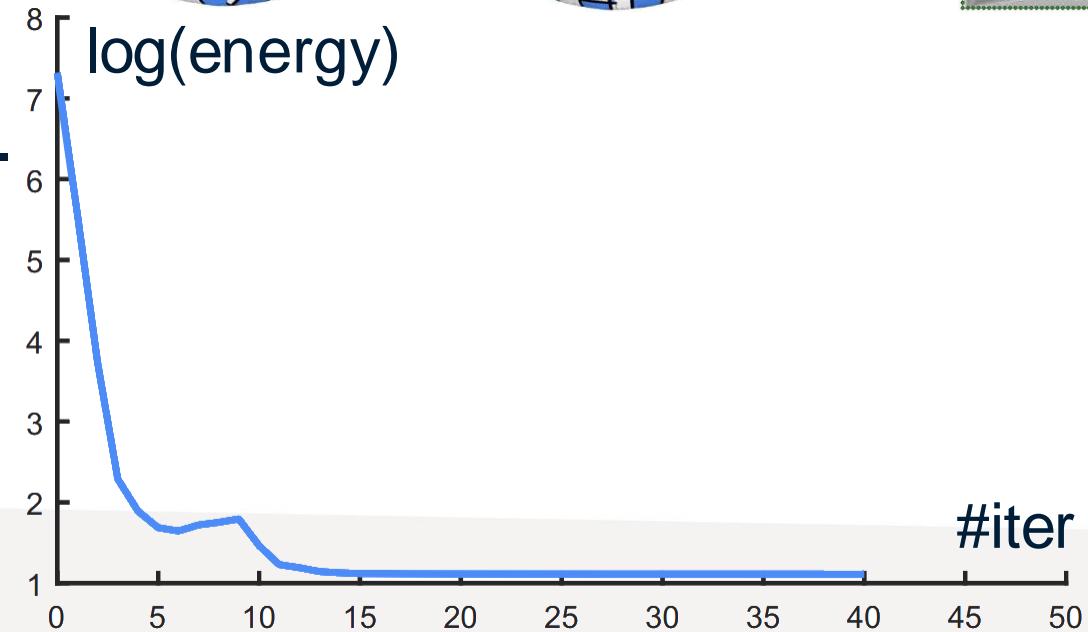
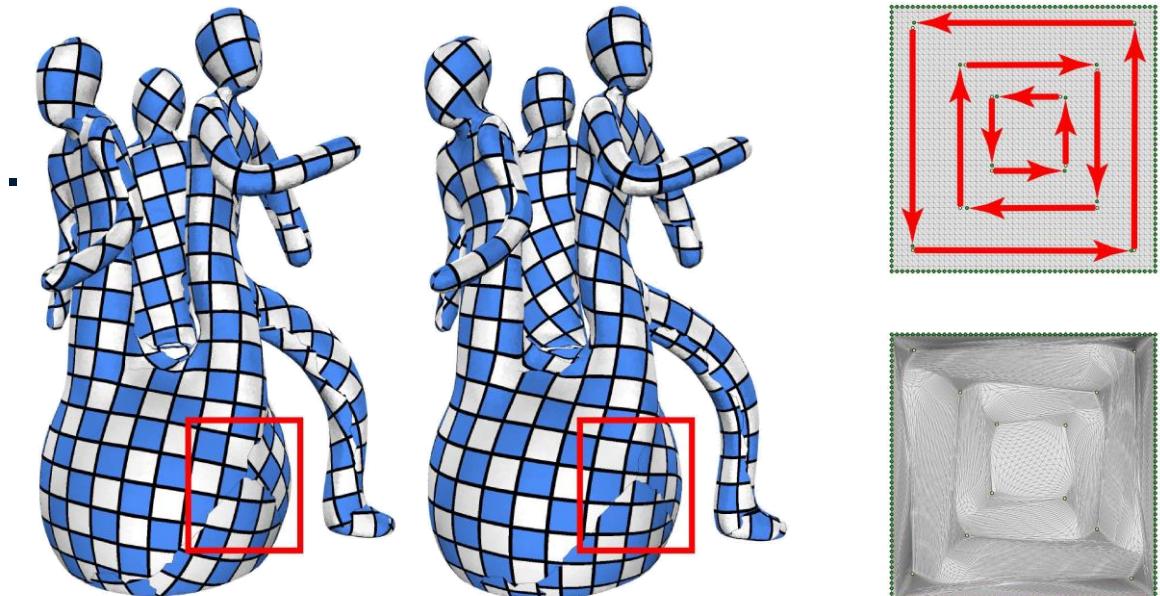
Conclusions

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- Progressive parameterizations: a novel and simple method to generate low isometric distortion parameterizations with no foldovers.
- ✓ Thinks from the view of reference triangle.
- ✓ Exhibits strong practical reliability and high efficiency.
- ✓ Demonstrates the practical robustness on a large data set containing 20712 models

Limitations

- Cannot fit constraint condition well.
- No theoretical guarantee to reduce $E(M, M^p)$ monotonously.





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Thank you!



<http://staff.ustc.edu.cn/~fuxm/projects/ProgressivePara/>