# **2**.

#### e. Confusion table:

True class	Classified class		
	Setosa	Versicolor	Virginica
Setosa	20	0	0
Versicolor	0	20	0
Virginica	0	0	20

### f. Scatter plot for the PCA projected Iris data:

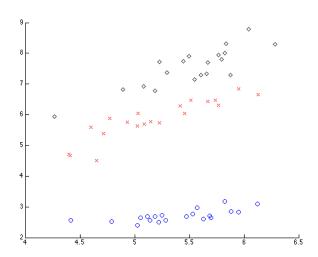


Figure 1: 2D projected test dataset

**g.** The original 4D Iris test dataset was projected into 2D data samples using PCA before classification task is performed and for the given set of test data we found that there is no classification error using MLE classifier which can be seen from the scatter plot and the confusion table.

## 3.

c. The classification task of the Iris data is a 3-class classification problem and for the Multiple discriminant analysis which is a generalization of Fisher's linear discriminant involves (3-1) discriminant functions hence the dimensionality of projection is not possible to get up to 3.

### e. Confusion table (MDA):

True class	Classified class		
	Setosa	Versicolor	Virginica
Setosa	20	0	0
Versicolor	0	20	0
Virginica	0	0	20

g. Scatter plot for the PCA projected Iris data with MDA:

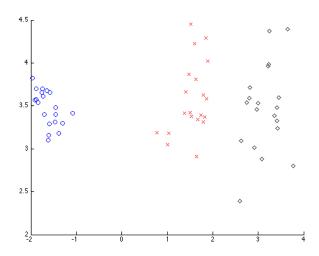


Figure 2: 2D projected test dataset

**g.** Same as the classification result of the PCA function, projected 2D dataset produced by MDA function also work really well with MLE classifier and we could also get zero classification error for the given dataset.

4.

**b.** Display original and approximated images:

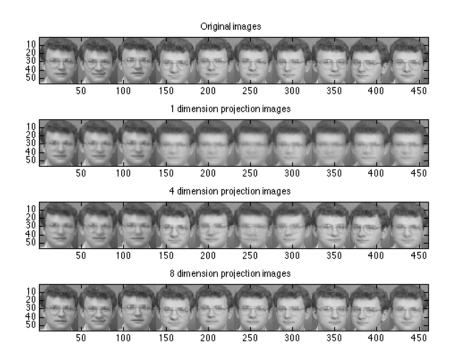


Figure 3: Original and approximated images

**c.** Proportion of variances(beta\_k) and approximation error(e\_square).

```
k:1 => beta_k = 0.40158, e_square = 631257.3661
k:4 => beta_k = 0.78715, e_square = 224526.7043
k:8 => beta_k = 0.98096, e_square = 20080.7289
```

# Appendix:

```
assignment 4.m
%
\%\ CS7720\ Spring\ 2015
% Introduction to Machine Learning and Pattern Recognition
\% \ \ University \ \ of \ \ Missouri-Columbia
\% Author: Chanmann Lim
\% \ email: \ cl9p8@mail.missouri.edu
% Homework Assignment 4
clc; clear; close all;
%% Load iris data
setosa = 'setosa ;
versicolor = 'versicolor';
setosa
virginica = 'virginica,';
[x1, x2, x3, x4, y] = textread('iris.data', '%f,%f,%f,%f,%f,Kf,Tris-%s');
X = [x1 \ x2 \ x3 \ x4];
y = char(y);
X_given_setosa = X(strcomp(y, setosa), :);
X_{pca_given_versicolor} = X(strcomp(y, versicolor), :);
X_{given\_virginica} = X(strcomp(y, virginica), :);
 [\,X\_given\_setosa\_training\,,\ X\_given\_setosa\_test\,]\ =\ split\,(\,X\_given\_setosa\,)\,;
[X_given_versicolor_training, X_given_versicolor_test] = split(X_pca_given_versicolor); [X_given_virginica_training, X_given_virginica_test] = split(X_given_virginica);
%% Problem 2
problem 2
%% Problem 3
problem 3
%% Problem 4
problem_4
%% Problem 5
problem 5
%% Problem 6
problem\_6
                                                 problem 2.m
% (a) and (b) PCA
% dimensions to keep
 \begin{array}{l} X\_pca\_given\_versicolor = (W*X\_given\_versicolor\_training')'; \\ X\_pca\_given\_virginica = (W*X\_given\_virginica\_training')'; \end{array} 
 \begin{array}{l} X\_pca\_given\_setosa\_test = (W*X\_given\_setosa\_test')'; \\ X\_pca\_given\_versicolor\_test = (W*X\_given\_versicolor\_test')'; \end{array} 
X_pca_given_virginica_test = (W * X_given_virginica_test');
\% (c) Estimate Mu and Sigma
[\begin{array}{lll} Mu\_setosa\,, & Sigma\_setosa\,] & = & mle\,(\,X\_pca\_given\_setosa\,)\,; \end{array}
[Mu_versicolor, Sigma_versicolor] = mle(X_pca_given_versicolor);
```

```
[\,Mu\_virginica\,,\,\,Sigma\_virginica\,]\,=\,mle\,(\,X\_pca\_given\_virginica\,)\,;
% (d) MLE classification
Theta_c1 = [Mu_setosa Sigma_setosa];
Theta_c2 = [Mu_versicolor Sigma_versicolor];
Theta_c3 = [Mu_virginica Sigma_virginica];
{\tt c\_1} = {\tt classify} \, ({\tt X\_pca\_given\_setosa\_test} \, , \, \, {\tt Theta\_c1} \, , \, \, {\tt Theta\_c2} \, , \, \, {\tt Theta\_c3} \, );
% (e) confusion table
\begin{array}{lll} & \text{confusion\_table}\,(1\,,\,\,:) = [\mathbf{sum}(c\_1\!=\!\!1) \ \mathbf{sum}(c\_1\!=\!\!2) \ \mathbf{sum}(c\_1\!=\!\!3)]; \\ & \text{confusion\_table}\,(2\,,\,\,:) = [\mathbf{sum}(c\_2\!=\!\!1) \ \mathbf{sum}(c\_2\!=\!\!2) \ \mathbf{sum}(c\_2\!=\!\!3)]; \\ & \text{confusion\_table}\,(3\,,\,\,:) = [\mathbf{sum}(c\_3\!=\!\!1) \ \mathbf{sum}(c\_3\!=\!\!2) \ \mathbf{sum}(c\_3\!=\!\!3)]; \\ \end{array}
display (confusion table);
% (f) plot PCA projected data
figure:
scatter\left(X_pca_given_setosa_test\left(:,1\right),\ X_pca_given_setosa_test\left(:,2\right),\ 'ob'\right);\ \mathbf{hold}\ on;
 \begin{array}{l} \text{scatter}\left(X\_\text{pca\_given\_versicolor\_test}\left(:,1\right),\ X\_\text{pca\_given\_versicolor\_test}\left(:,2\right),\ \text{'xr'}\right);\\ \text{scatter}\left(X\_\text{pca\_given\_virginica\_test}\left(:,1\right),\ X\_\text{pca\_given\_virginica\_test}\left(:,2\right),\ \text{'dk'}\right);\ \textbf{hold}\ \ \text{off}; \\ \end{array} 
                                                                        problem 3.m
\% \ Y - input \ target \ vector \ for \ MDA
[X_given_setosa_training; X_given_versicolor_training; X_given_virginica_training]', Y);
% (a) and (b) MDA projection
X_pca_given_setosa = (W * X_given_setosa_training')';
X_pca_given_versicolor = (W * X_given_versicolor_training')';
X_pca_given_virginica = (W * X_given_virginica_training')';
 \begin{array}{l} X\_pca\_given\_setosa\_test = (W * X\_given\_setosa\_test')'; \\ X\_pca\_given\_versicolor\_test = (W * X\_given\_versicolor\_test')'; \\ X\_pca\_given\_virginica\_test = (W * X\_given\_virginica\_test')'; \end{array} 
% (d) Estimate Mu and Sigma
[Mu_setosa, Sigma_setosa] = mle(X_pca_given_setosa);
[Mu_versicolor, Sigma_versicolor] = mle(X_pca_given_versicolor);
[Mu_virginica, Sigma_virginica] = mle(X_pca_given_virginica);
% (e) MLE classification
Theta c1 = [Mu \text{ setosa Sigma setosa}];
Theta_c2 = [Mu_versicolor Sigma_versicolor];
Theta_c3 = [Mu_virginica Sigma_virginica];
c_1 = classify(X_pca_given_setosa_test, Theta_c1, Theta_c2, Theta_c3);
% (f) confusion table
\begin{array}{lll} \text{confusion\_table}\,(1\,,\,\,:) &=& [\mathbf{sum}(c\_1\!=\!\!1) \; \mathbf{sum}(c\_1\!=\!\!2) \; \mathbf{sum}(c\_1\!=\!\!3)]; \\ \text{confusion\_table}\,(2\,,\,\,:) &=& [\mathbf{sum}(c\_2\!=\!\!1) \; \mathbf{sum}(c\_2\!=\!\!2) \; \mathbf{sum}(c\_2\!=\!\!3)]; \\ \text{confusion\_table}\,(3\,,\,\,:) &=& [\mathbf{sum}(c\_3\!=\!\!1) \; \mathbf{sum}(c\_3\!=\!\!2) \; \mathbf{sum}(c\_3\!=\!\!3)]; \\ \end{array}
display (confusion table);
% (g) plot MDA projected data
scatter\left(X_pca_given_setosa_test\left(:,1\right),\ X_pca_given_setosa_test\left(:,2\right),\ 'ob'\right);\ \mathbf{hold}\ on;
scatter(X\_pca\_given\_versicolor\_test(:,1), X\_pca\_given\_versicolor\_test(:,2), 'xr'); \\ scatter(X\_pca\_given\_virginica\_test(:,1), X\_pca\_given\_virginica\_test(:,2), 'dk'); \\ \textbf{hold} \quad off; \\
                                                                        problem 4.m
% Initialization
clear all; close all; clc; warning off all;
% Setup
```

```
{\rm Nfolder} \, = \, 1; \, \, \% \, \# \, \, of \, \, folders
Nfile = 10; \% # of files
\% Read images from input\{i\} folder
\label{eq:limit_limit} \begin{array}{ll} Im = readimages(\ 'input'\ ,\ 1:Nfolder\ ,\ 'pgm'\ ,\ 1:Nfile\ ); \\ [R,\ \tilde{\ }] = size(Im\{1\ ,1\}); \ \% \ \# \ of \ rows \ and \ colums \ per \ image \end{array}
% Convert images to vectors
Imv = mat2vec(Im);
% PCA approximation
k = [1 4 8]; % dimensions to be preserved
x \text{ bar} = \text{mean}(\text{Imv}\{1\}, 2); \% \text{ the sample mean}
[\overline{D}, N] = size(Imv\{1\}); \% \# original dimensions and training samples
% (a) and (b)
\% Plot a 4-by-1 subplotting system
figure;
subplot (4,1,1);
image(uint8(cell2mat(Im))); % image printing (have to convert double precision numbers into 8-bit integ
axis image;
title ('Original_images');
subplot_counter = 2;
\mathbf{for} \quad i = 1{:}N
        x = Imv\{1\}(:, i);
         Im_approximation(:, i) = pca_approximation(x, W, x_bar);
    % Image Reconstructing (from data points (vectors))
    Imr = vec2mat({Im_approximation}, R);
    subplot(4,1, subplot_counter);
    image(uint8(cell2mat(Imr)));
    axis image;
    title ([num2str(m) '_dimension_projection_images']);
    subplot_counter = subplot_counter + 1;
end
colormap(gray(256));
% (c)
% Covariance S = E[(x-x_bar) * (x-x_bar) '];
S = \mathbf{cov}(\operatorname{Imv}\{1\}');
[\tilde{\ },\ D]\ =\ \mathbf{eig}(S);
Lambda = sort(diag(D), 'descend'); \% l1 > l2 > ...
for m=k
    beta_k = sum(Lambda(1:m)) / sum(Lambda);
    e square = sum(Lambda(m+1:end));
    display(['k:', num2str(m), '_=>_beta_k_=_', num2str(beta_k), ',_e_square_=_', num2str(e_square)]);
                                           problem 5.m
% Initialization
clear all; close all; clc; warning off all;
Nfolder = 5; \% # of folders (one person per folder)
Nfile = 10; % # of files
% Read images from input{i} folder
Im = readimages ( 'ImageFaceID/input' , 1:Nfolder, 'pgm', 1:Nfile);
[R, C]=size(Im\{1,1\}); \% \# of rows and column per image
\% Convert images to vectors
Imv = mat2vec(Im);
X_{test} = [Imv\{1\}(:, 6:10) Imv\{2\}(:, 6:10) Imv\{3\}(:, 6:10) Imv\{4\}(:, 6:10) Imv\{5\}(:, 6:10)];
% PCA approximation
```

```
M= [1 4 10]; % dimensions to be preserved K= [1 3 5]; % \# of neighbors in Knn
\% Both the training targets (labels) and test targets
% since our training and set are order in symmetry targets = [ones(1,5) ones(1,5)*2 ones(1,5)*3 ones(1,5)*4 ones(1,5)*5];
targets_size = length(targets);
error_rate_table = ones(3, 3);
row = 1:
col = 1;
for m⊨M
      [~\tilde{},~\tilde{},~\tilde{},~\tilde{},~\tilde{},W] = PCA(X_{training},~[],~m);
      X_training_pca = W * X_training;
     X_{\text{test\_pca}} = W * X_{\text{test}};
      for k=K
           classification = Nearest\_Neighbor(X\_training\_pca\,,\ targets\,,\ X\_test\_pca\,,\ k);
           error_rate_table(row, col) = 1 - (sum(classification == targets) / targets_size);
           row = row + 1;
     \mathbf{end}
      col = col + 1;
     row = 1;
display(error_rate_table);
                                                    problem 6.m
% Initialization
clc; clear all; close all;
% Load data
SalmonLightness = load('SalmonLightness.dat');
SeabassLightness = load('SeabassLightness.dat');
Total = length(SalmonLightness) + length(SeabassLightness);
P_salmon = length(SalmonLightness) / Total;
P_seabass = length(SeabassLightness) / Total;
H = [0.8 \ 0.2];
x_range = 0:0.1:12;
for h=H
      p lightness given salmon = parzen window(SalmonLightness, x range, h);
      p_lightness_given_seabass = parzen_window(SeabassLightness, x_range, h);
      p_lightness = p_lightness_given_salmon * P_salmon + ...
           p_lightness_given_seabass * P_seabass;
     plot(x_range, p_lightness_given_salmon, 'r'); hold on;
plot(x_range, p_lightness_given_seabass, '--k');
plot(x_range, p_lightness, '--g'); hold off;
legend('P(lightness|salmon)', 'P(lightness|seabass)', 'P(lightness)');
title(['PDFs_with_h=', num2str(h)]);
                                                      classify.m
function [ c ] = classify( X, Theta_1, Theta_2, Theta_3 )
\% classify - Classify X given Theta \{1\ 2\ and\ 3\}
\% by comparing the value of discriminant function g(x)
     for each parameter theta.
%
\% Return:
%
     c-classification\ vector
%
% where value of
    c = 1 \ (Iris-setosa)
     c = 2 (Iris - versicolor)
     c = 3 (Iris-virginica)
      [r, ~\tilde{}] = size(X);
```

```
c = zeros(r, 1);
     mu column = 1;
     sigma\_column = 2:3;
     \mathbf{for} \hspace{0.2cm} k\!=\!1\!:\!r
         x \, = \, X(\, k \, , \  \, : \, ) \, \, \dot{\,} ;
          [\,\tilde{\ }\ ,\ c\,(\,k\,\,,:\,)\,\,]\ =\ \text{max}\,(\,[\,
              \label{eq:g_mle}  \ensuremath{\mathtt{g_mle}}(x\,,\ \ \mbox{Theta} \ensuremath{\mathtt{1}}(:\,,\ \mbox{mu\_column})\,,\ \ \mbox{Theta} \ensuremath{\mathtt{1}}(:\,,\ \mbox{sigma\_column})) \ \ \ldots
              end
end
                                                  g mle.m
\mathbf{function} \ [ \ \mathbf{g} \ ] \ = \ \mathbf{g}_{\mathbf{m}} \mathbf{le}(\ \mathbf{x} \,, \ \mathbf{mu}, \ \mathbf{Sigma} \ )
Compute log(P(x|w))
%
% Input:
%
    mu - mean \ of \ P(x/w)
    Sigma - covariance matrix of P(x/w)
     d = length(x);
     x \text{ tilde} = x - mu;
     g = - d/2*log(2*pi) \dots
         -1/2*\log(\det(Sigma)) ...
         - 1/2*x_tilde; /Sigma*x_tilde;
end
                                                    mle.m
function [ m, P ] = mle( dataset )
% mle - Maximum likelihood estimator for mean and covariance
         of \ 1-D \ and \ 2-D \ Gaussian \ dataset
    m: the estimated mean (sample mean)
    P: the estimated biased variance for 1-D dataset
%
%
               and covariance matrix for 2-D dataset
%
\% Note:
   P = [var1 \ cov(1,2); \ cov(1,2) \ var2]
%
% where
%
                   - biased variance of x1
    var1
%
     cov(1, 2)
                   -E[(x1-mean_x1)(x2-mean_x2)]
%
                   - biased variance of x2
    m = mean(dataset);
     P = cov(dataset, 1);
end
                                             parzen window.m
\mathbf{function} \ [ \ \mathrm{pdf} \ ] \ = \ \mathrm{parzen\_window} \left( \ \mathrm{X}, \ \mathrm{x\_range} \,, \ \mathrm{h} \ \right)
\% PARZEN_WINDOW density estimation
     pdf = zeros(length(x_range), 1);
     for i=1:length(x range)
         x = x_range(i);
          delta = (1/sqrt(2*pi)) .* exp(-((x-X)/h).^2 / 2);
          pdf(i, 1) = sum(delta) / (length(X) * h);
     end
end
                                           pca_approximation.m
function [ x tilda ] = pca approximation(x, W, x bar)
\% pca_approximation - PCA approximation of x given Eigenvector W
     [~,~M] = size(W); \% \# of preserved dimensions
     distance = x - x_bar;
```

```
x_{tilda} = zeros(size(x,1), 1);
     \mathbf{for} \quad i = 1:M
         x_{tilda} = x_{tilda} + (W(:, i)' * distance) * W(:, i);
     {\tt x\_tilda} \, = \, {\tt x\_tilda} \, + \, {\tt x\_bar} \, ;
                                                     \operatorname{split.m}
Training set : row 11 to 40
     Test \ set
                    : row 1 to 10 and 41 to 50
     {\tt training} \; = \; {\tt dataset} \, (\, 11{:}40 \, , \; \; :) \, ;
     test = dataset([1:10 \ 41:50], :);
                                                  strcomp.m
function [ y ] = strcomp( x, str )
% strcomp - Compare each row of 'x' with 'str'
% Return 1 for the rows that equal to 'str' and 0 otherwise
     [r, c] = size(x);
     y = zeros(r, 1);
     \mathbf{for} \ k=1:r
     y = y = c;
end
```