Similarly

$$\frac{\partial}{\partial x}(\mathbf{A}\mathbf{B}) = \frac{\partial \mathbf{A}}{\partial x}\mathbf{B} + \mathbf{A}\frac{\partial \mathbf{B}}{\partial x}.$$
 (A.20)

The derivative of the inverse of a matrix can be expressed as

$$\frac{\partial}{\partial r} \left(\mathbf{A}^{-1} \right) = -\mathbf{A}^{-1} \frac{\partial \mathbf{A}}{\partial r} \mathbf{A}^{-1} \tag{A.21}$$

as can be shown by differentiating the equation $\mathbf{A}^{-1}\mathbf{A} = \mathbf{I}$ using (A.20) and then right-multiplying by \mathbf{A}^{-1} . Also

$$\frac{\partial}{\partial x} \ln |\mathbf{A}| = \text{Tr}\left(\mathbf{A}^{-1} \frac{\partial \mathbf{A}}{\partial x}\right),\tag{A.22}$$

which we shall prove later. If we choose x to be one of the elements of A, we have

$$\frac{\partial}{\partial A_{ij}} \operatorname{Tr} (\mathbf{AB}) = B_{ji} \tag{A.23}$$

as can be seen by writing out the matrices using index notation. We can write this result more compactly in the form

$$\frac{\partial}{\partial \mathbf{A}} \operatorname{Tr}(\mathbf{A}\mathbf{B}) = \mathbf{B}^{\mathrm{T}}.$$
 (A.24)

With this notation, we have the following properties:

$$\frac{\partial}{\partial \mathbf{\Lambda}} \operatorname{Tr} \left(\mathbf{A}^{\mathrm{T}} \mathbf{B} \right) = \mathbf{B}, \tag{A.25}$$

$$\frac{\partial}{\partial \mathbf{A}} \text{Tr}(\mathbf{A}) = \mathbf{I}, \tag{A.26}$$

$$\frac{\partial}{\partial \mathbf{A}} \text{Tr}(\mathbf{A} \mathbf{B} \mathbf{A}^{T}) = \mathbf{A}(\mathbf{B} + \mathbf{B}^{T}), \tag{A.27}$$

which can again be proven by writing out the matrix indices. We also have

$$\frac{\partial}{\partial \mathbf{A}} \ln |\mathbf{A}| = \left(\mathbf{A}^{-1}\right)^{\mathrm{T}},\tag{A.28}$$

which follows from (A.22) and (A.24).

A.4. Eigenvectors

For a square matrix A of size $M \times M$, the eigenvector equation is defined by

$$\mathbf{A}\mathbf{u}_i = \lambda_i \mathbf{u}_i \tag{A.29}$$