## **Max Kramer**

I affirm that I have adhered to the honor code on this assignment.

Hello again, scientist! I'll write in italics, and problems for you will always be in **bold**. As a general rule, I expect you to do at least as much writing as I do. Code should be part of your solution, but I expect variables to be clear and explanation to involve complete sentences. Cite your sources; if you work with someone in the class on a problem, that's an extremely important source.

## Problem 10.1.

You can write a linear transformation with respect to whatever set of bases you want, but some bases are better than others. Check it out.

```
A = [0 3 -6 6 4 -5; 3 -7 8 -5 8 9; 3 -9 12 -9 6 15];
size(A)
rank(A)

ans =
    3    6

ans =
```

As a linear map, A takes  $R^6$  (in the standard basis) onto  $R^3$  (in the standard basis). That means that Col(A) is a basis for  $R^3$ . Lay Chapter 6 Theorem 4 says that the pivot columns of A form a basis for  $R^3$ . Find that basis, and call it  $B = [b1 \ b2 \ b3]$ .

```
B = A(:,[1 \ 2 \ 5])
B = \begin{bmatrix} 0 & 3 & 4 \\ 3 & -7 & 8 \\ 3 & -9 & 6 \end{bmatrix}
```

The pivot columns of A are 1, 2, and 5. The above command creates a matrix B from the 1st, 2nd, and 5th columns of A.

Show me the matrix C which represents the transformation A as a map from R^6 (in the standard basis) to R^3 in the B basis. Here's a good way to do that: compose the matrix A with an appropriate change of basis.

```
C = B * A
rref(C)
rref(A)
```

$$C = \begin{bmatrix} 21 & -57 & 72 & -51 & 48 & 87 \\ 3 & -14 & 22 & -19 & 4 & 42 \\ -9 & 18 & -18 & 9 & -24 & -6 \end{bmatrix}$$

$$ans = \begin{bmatrix} 1 & 0 & -2 & 3 & 0 & -24 \\ 0 & 1 & -2 & 2 & 0 & -7 \\ 0 & 0 & 0 & 0 & 1 & 4 \end{bmatrix}$$

$$ans = \begin{bmatrix} 1 & 0 & -2 & 3 & 0 & -24 \\ 0 & 1 & -2 & 2 & 0 & -7 \\ 0 & 0 & 0 & 0 & 1 & 4 \end{bmatrix}$$

The matrix C is a linear map from  $R^6$  to  $R^3$  created by composing the matrix A with a transformation matrix for the B-basis.

If you did the previous part right, then C = rref(A). (Wait, what!?!?!) Actually, that's what row reduction is: it's a change of basis of the codomain. This is why row reduction can (and often will) change Col(A), but it doesn't change Row(A) or Null(A): those live in the domain, and the basis for the domain hasn't changed.

Here's one more.

Find a basis  $M = [m1 \ m2 \ m3]$  for which L=rref(K) is the coordinate matrix for K, where K takes the standard basis of  $R^4$  to the standard basis of  $R^3$  and L takes the standard basis of  $R^4$  to the M-basis of  $R^3$ .

```
M = horzcat(K(:,[1 2]),[5;7;4])
L = M * K;
rref(L)
rref(K)

M =

1     2     5
4     5     7
```

| 6           | 7           | 4            |              |
|-------------|-------------|--------------|--------------|
| ans =       |             |              |              |
| 1<br>0<br>0 | 0<br>1<br>0 | -1<br>2<br>0 | -2<br>3<br>0 |
| ans =       |             |              |              |
| 1<br>0      | 0<br>1      | -1<br>2      | -2<br>3      |
| 0           | 0           | 0            | 0            |

The matrix M is created by combining 2 vectors in Col(K) with a third linearly independent vector, creating a set of three linearly independent vectors with 3 elements each, forming the M basis for R^3. When M is multiplied by K, the resultant matrix L is row equivalent to rref(K).

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