



Hyperbolic Geometry - 1

Main Ref: << An Introduction to Geometric Topology >> Martelli

• Roughly speaking, there are "three" kind of geometries in Riemannian geometry: S^n , \mathbb{R}^n , H^n , responding to the unique simply connected, complete, Riemannian m-fld with constant sectional curvature 1, 0, -1 (positive, flat, negative)

In this seminar, I will introduce several Hyperbolic model. I will list them as below. They have different advantages and drawbacks. We will use one of them as long as it is convenient.

Model	name	advantage
1:	Hyperboloid	→ easy to calculate ↓ (projection)
2:	Projection Poincaré disk	→ easy to see
3:	Half plane model	↓ (inversion) → has a nice ∞
4:	Klein model	→ geodesics are "lites" (easy to see)

And we will follow the path above to study them. In each model, we will care about

① How does they look like?

② What is the subspace? (geodesically submfld)

③ the metric tensor calculation.

④ Some geometric properties.



§ 1 Hyperboloid model. (I^n)

Recall how we get S^n ? From Euclidean inner product

$\langle x, y \rangle_E := \sum_{i=1}^n x_i y_i = 1$. So we can generalize this thing. Firstly, we give the defn of "scalar product"

Def 1 (Scalar product)

symmetric.

Let V be an vector space. $\langle \cdot, \cdot \rangle$ is a bilinear form and nondegenerate. We call it is a scalar product with signature (p, q) . ($p+q = \dim V$) if it can be represented by $\begin{pmatrix} I_p & 0 \\ 0 & I_q \end{pmatrix}$ for some special basis.

In \mathbb{R}^{n+1} , $\langle x, y \rangle_L := \sum_{i=1}^n x_i y_i - x_{n+1} y_{n+1}$ is called the Lorentzian scalar product. its signature is $(n, 1)$. $\langle x, y \rangle_E := \sum_{i=1}^{n+1} x_i y_i$ is the traditional inner product. its --- is $(n+1, 0)$.

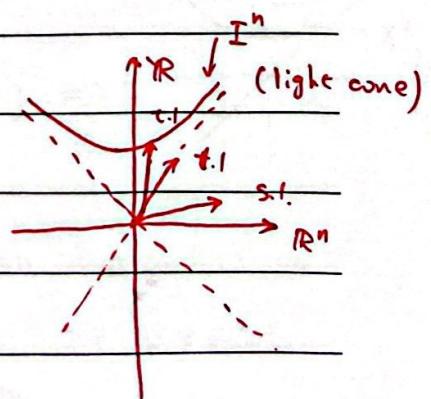
Def 2 (Hyperboloid I^n)

$$I^n := \{x \in \mathbb{R}^{n+1} \mid \langle x, x \rangle_L = -1, \underline{\underline{x_{n+1} > 0}}\}$$

• time-like vector, if $\langle x, x \rangle_L < 0$

• light-like vector, if $\langle x, x \rangle_L = 0$

• space-like vector, if $\langle x, x \rangle_L > 0$.





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[Naive question]: Does I^n is a mfld? Riemannian Mfld?

[Prop 3] For any scalar product \langle , \rangle on \mathbb{R}^{n+1} , The function

$f: \mathbb{R}^{n+1} \rightarrow \mathbb{R}$ given by $f(x) = \langle x, x \rangle$ is everywhere

Smooth and has differential, $\forall y \in T_x \mathbb{R}^{n+1} \cong \mathbb{R}^{n+1}$

$$f_{*x}(y) = 2\langle x, y \rangle.$$

If: consider $r(t) = x + ty$. then

$$\begin{aligned} f_{*x}(y) &= f_{*x}(r(0)) = \frac{d}{dt}|_{t=0} f(r(t)) \\ &= \frac{d}{dt}|_{t=0} \langle x + ty, x + ty \rangle = 2\langle x, y \rangle. \end{aligned}$$

□

[Corollary 4] I^n is a Riemannian Mfld.

If: ① Since \langle , \rangle_L is nondegenerate $\Rightarrow f_x$ is surjective \Rightarrow
-1 is the regular value of f . $\Rightarrow I^n$ is a mfld.

② To check I^n is a Riemannian mfld

that's why
we first

introduce this
model.

because the
tangent

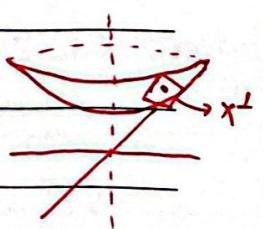
space has
a nice

straightforward
expression!

[Step 1]: what is the tangent space?

$$T_x I^n = \ker f_{*x} = \{y | \langle x, y \rangle_L = 0\} := x^\perp$$

(this is really similar to S^{n-1})



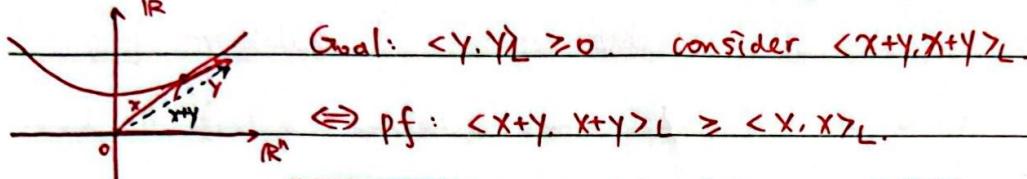
[Step 2]: what is the metric tensor \Leftrightarrow Find an inner product on x^\perp .

[Claim]: $\langle , \rangle_L|_{x^\perp}$ gives an inner product. i.e. $\forall y \in x^\perp$.

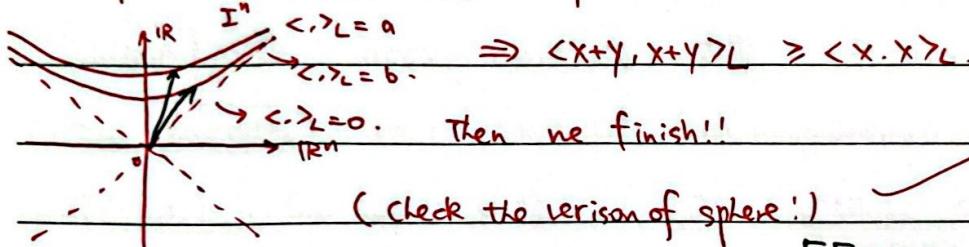
$$\langle y, y \rangle_L \geq 0. \text{ and } = 0 \text{ iff } y = 0.$$



Pf of claim: (Note that $\langle x \cdot y \rangle_L = 0$, although they are not look like "or-")



observation: $x+y$ lies below θ_{xy}^n !!



Exercise: For different scalar
produce $\langle \cdot, \cdot \rangle$, $\langle x \cdot x \rangle = c$
diffeomorphic iff signature same

Now we study the Isometries of I^n .

Defns: $f: I^n \rightarrow I^n$ is called an Isometry if

① it is a diffeomorphism.

② $\forall x \in I^n$, $u, v \in T_x I^n$, $\langle f_{*x}(u), f_{*x}(v) \rangle_L = \langle u, v \rangle_L$

a Riemann Exercise.

$\Leftrightarrow \forall p, q \in I^n$, $\langle f(p), f(q) \rangle_{I^n} = \langle p, q \rangle_L$

$\Leftrightarrow \langle Ax, Ay \rangle_L = \langle x, y \rangle_L$

Thm 6: $Isom(I^n) = O^+(n, 1) = \{A \mid A^T \begin{pmatrix} I_n & 0 \\ 0 & -1 \end{pmatrix} A = \begin{pmatrix} I_n & 0 \\ 0 & -1 \end{pmatrix}, A \text{ preserve the upper half}\}$.

證明 (⇒) trivial $O^+(n, 1) \subseteq Isom(I^n)$

(⇒) We will use a fact from Riemannian mfld: If M, n

are compact Riemannian mfld, f, g are two isometries, $f(p) = g(p)$.

$f_{*p} = g_{*p}$ then $f = g$. Thus we only need to for any $f \in Isom(I^n)$.

Find a matrix $A \in O^+(n, 1)$ and some $p \in I^n$

① $f(p) = A(p)$ ② $f_{*p} = A$. \rightarrow then $f = A$



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Now we have $f \in \text{Isom}(I^n)$ is arbitrary. How to find A?

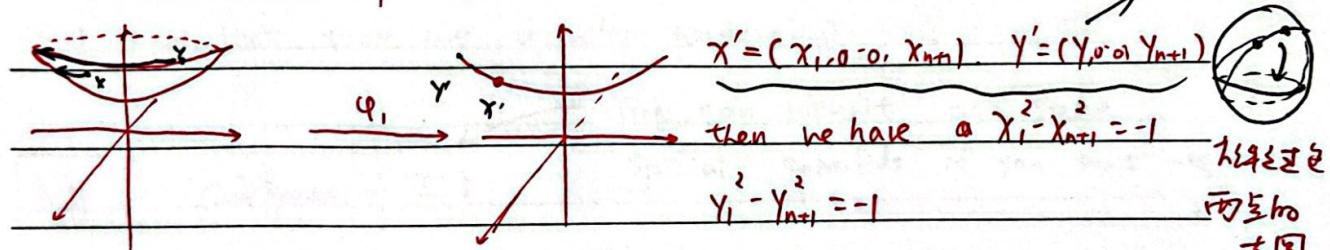
Step 4 specialize f. we also need to find some p. we also need to find a special p. \rightarrow choose $x_0 = (0, -1, 0, 1)$. and $x_1 := f(x_0)$.
 $\exists p, f(p) = x_0$ (f is diffeomorphism).

$$x_1 \rightarrow x_0.$$

LEMMA: $O^+(n, 1)$ acts transitively on I^n \longleftrightarrow thus we can transform

key observation: we can rotate first n-coordinate. ie. $(A_1)_i A_i O(n)$

$\in O^+(n, 1)$. For any $x, y \in I^n$. $\exists \varphi_i \in O^+(n, 1)$. such that think sphere



Let $x_1 = \sinh t_1$, $x_{n+1} = \cosh t_1$, $y_1 = \sinh t_2$, $y_{n+1} = \cosh t_2$, we have another

rotation: $\begin{pmatrix} \cosh(t_2-t_1) & 0 & \sinh(t_2-t_1) \\ 0 & I^{n-2} & 0 \\ \sinh(t_2-t_1) & 0 & \cosh(t_2-t_1) \end{pmatrix} := \varphi_2$. 双曲旋转变换.

sends x' to y' (Direct Calculation) □

启发: 將双曲旋转变换大圖!! (\mathbb{H}^n vs S^n)

Now consider $\varphi \in O^+(n, 1)$. and $\varphi(x_1) = x_0$. so we have

$\forall f \in \text{Isom}(I^n)$. $\varphi \circ f(x_0) = x_0$. $\rightarrow T_{x_0} I^n = \{(x, \dots, x_{n+1})\}$.

Step 5: suppose $(\varphi \circ f)_{*x_0} = B$, then $B \in O(n)$. (direct calculation)
 \Rightarrow choose $C = (B_1) \in O^+(n, 1)$. then

$$\textcircled{1} (\varphi \circ f)_{*x_0} = C_{*x_0} = C. \quad \textcircled{2} \varphi \circ f(x_0) = x_0 = C(x_0) = x_0$$

$$\Rightarrow \varphi \circ f = C \Rightarrow f = \varphi^{-1}C \in O^+(n, 1)! \quad \square$$



Rmk: $O(n) \subseteq O^+(n, 1)$. We have not a explicit formula of $O^+(n, 1)$.

So we still not know the explicit Isometry group. Actually they are quite complicated. We will only talk about the lower dimension isometry group.

Now we introduce the "subspaces" of I^n . More precisely we will define some submfds of I^n directly. And then we will show that they are actually geodesically.

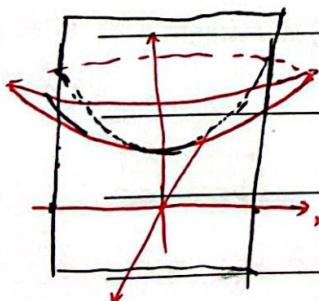
Defn 7 (subspaces of I^n)

Special submfds if you have not study RGr.

A k -dimensional subspace of I^n is the intersection of

$(k+1)$ -dimensional vector subspace of \mathbb{R}^{n+1} with I^n . does not contain

contain origin!!! We will only say "affine" if it



Rmk: For $k+1$ -vector subspaces $W \subseteq \mathbb{R}^{n+1}$ Following are Eq.

① $W \cap I^n \neq \emptyset$

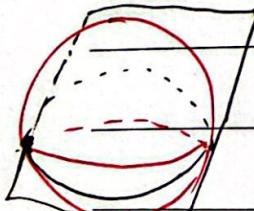
y

② W contains at least a time-like vector

③ the signature of $\langle \cdot, \cdot \rangle_W$ is $(k, 1)$.

Let $W \cap I^n = S$. Then $\forall x \in S, T_x S \xrightarrow{k \text{ dim.}} \mathbb{R}^k, x \in S$.

We can choose $(x, T_x S)$ as a basis of W .





From the rmk. we have an important corollary:

Corollary 8 A k -subspace of \mathbb{I}^n is itself isometric to \mathbb{I}^k .

The non-empty intersection of two subspaces is always a subspace.

An isometry of \mathbb{R}^n , \mathbb{I}^n sends k -subspace to k -subspace

Defn 9 (lines) A 1-subspace is a line. i.e. a 2-vector subspaces intersection with \mathbb{I}^n .

(the line in \mathbb{R}^n are the line, the line in the S^n are the big circle, the line in \mathbb{I}^n are the hyperbolic lines).

Now we talk about the geodesics. We can a $r(t) \in M^n \subseteq \mathbb{R}^{n+1}$

is a geodesic if ① $r'(t) \in M^n$. ② $\langle r'(t), r''(t) \rangle = 1$. ③ $\underbrace{r'(t)}$ projects to the tangent space are zero. \rightarrow 在 \mathbb{R}^n 中是直的. 在 S^n 和 \mathbb{I}^n 都不是直的. $\langle V \cdot V \rangle_E = 1$, $\langle V \cdot V \rangle_L = 1$

Thm 10: Let $p \in M$. be a point and $V \in T_p M$ a "unit" vector. The geodesic r exiting from p with velocity V is

- $r(t) = p + tV$ if $M = \mathbb{R}^n$
- $r(t) = \cos t \cdot p + \sin t \cdot V$ if $M = S^n$
- $r(t) = \cosh t \cdot p + \sinh t \cdot V$ if $M = \mathbb{I}^n$.



Pf: We take I^n as an example. What we need to show?

① $r(t) \in I^n \Leftrightarrow \langle r(t), r'(t) \rangle_L = -1$

$$\langle \cosh t \cdot p + \sinh t \cdot v, \cosh t \cdot p + \sinh t \cdot v \rangle_L = (\cosh t)^2 \cdot (-1) + (\sinh t)^2 \cdot (1) = -1$$

② $r(t) = \sinh t \cdot p + \cosh t \cdot v$ is unit speed vector.

$$\langle r(t), r(t) \rangle = -\sinh^2 t + \cosh^2 t = 1.$$

③ $\ddot{r}(t) = \cosh t \cdot p + \sinh t \cdot v = r(t)$. $r(t) \perp T_{r(t)} I^n \Rightarrow \checkmark$.

Then $r(t)$ is the geodesic.

[Thm 11] all geodesics \Leftrightarrow lines.

From linearity \Rightarrow lines are geodesics $\cosh t \cdot p + \sinh t \cdot v \subseteq W$.

Suppose $W = \text{span}\{p, v\}$, then we need to check

$$W \cap I^n = \{\cosh t \cdot p + \sinh t \cdot v\}.$$

" \subseteq " is trivial.

" \supseteq " we need to parameterize the $W \cap I^n$. $\forall q \in W \cap I^n$, we

can use $\sigma(n, 1)$ tends $l = W \cap I^n \rightarrow x_1^2 - x_{n+1}^2 = -1$.

$\rightarrow \sinh t, \cosh t \dots$ we can easily \dots □

[Prop 12] Let $p, q \in M$. we have

• $M = S^n$. $\cos(d(p, q)) = \langle p, q \rangle_E$

• $M = I^n$. $\cos(d(p, q)) = -\langle p, q \rangle_L$.