

Mini58 CMSIS BSP Directory

Directory Introduction for 32-bit NuMicro® Family

Directory Information

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| Document | Driver reference manual and revision history. |
| Library | Driver header and source files. |
| SampleCode | Driver sample code. |

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For additional information or questions, please contact: Nuvoton Technology Corporation.

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1 Document Information

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| CMSIS.html | Document of CMSIS version 4.5.0 |
| NuMicro Mini58 Series CMSIS BSP Revision History.pdf | This document shows the revision history of Mini58 BSP. |
| NuMicro Mini58 Driver Reference Guide.chm | This document describes the usage of drivers in Mini58 BSP. |

2 Library Information

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| CMSIS | Cortex [®] Microcontroller Software Interface Standard (CMSIS) V4.5.0 definitions by ARM [®] Corp. |
| Device | CMSIS compliant device header file. |
| StdDriver | All peripheral driver header and source files. |

3 Sample Code Information

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| Hard_Fault_Sample | Show hard fault information when hard fault happened. |
| RegBased | Sample code implemented without access standard library but access registers directly. |
| Semihost | Show how to print and get character with IDE console window. |
| StdDriver | Demonstrate the usage of Mini58 MCU peripheral driver APIs. |
| Template | A project template for Mini58 MCU. |

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| ACMP | Demonstrate Analog comparator (ACMP) comparison by comparing CPP0 (P1.5) with Band-gap voltage and shows the result on UART console. |
| ACMP_TriggerTimerCapture | Show how to use Analog comparator (ACMP) state change to trigger timer capture function. P1.5 is used as comparator positive input and Band-gap voltage as negative input. |
| ADC_Compare | Demonstrate ADC conversion and comparison function by monitoring the conversion result of channel 0. |
| ADC_Convert | Demonstrate ADC function by repeatedly convert the input of ADC channel 0 (P5.3) and shows the result on UART console. |
| ADC_PWMTrigger | Demonstrate PWM0 channel 0 trigger ADC function. |
| ADC_SequentialMode | Demonstrate ADC PWM Sequential Mode conversion and shows the result on UART console. |
| FMC_RW | Show FMC read flash IDs, erase, read, and write functions. |
| GPIO | Use GPIO driver to control the GPIO pin direction, control their high/low state, and how to use GPIO interrupts. |
| I2C_FIFO_EEPROM | Read/write EEPROM via I ² C interface using FIFO mode. |
| I2C_Interrupt_EEPROM | Read/write EEPROM via I ² C interface using interrupt mode. |
| I2C_Polling_EEPROM | Read/write EEPROM via I ² C interface using polling mode. |
| I2C_Software_GPIO | Demonstrate how to use GPIO pins to simulate I ² C interface. |
| PWM_DeadZone | Demonstrate the dead-zone feature with PWM. |
| PWM_DoubleBuffer | Demonstrate the PWM double buffer feature. |
| PMW_MaskAlign | Show how to generate 0%, 50% and 100% PWM duty |

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| | cycle. |
| PWM_PreciseCenterAligned Mode | Demonstrate PWM precise center aligned feature. |
| SPI_LoopBack | Demonstrate SPI function by connect MOSI (P0.5) with MISO (P0.6) |
| SPI_MasterFIFOmode | Demonstrate how to communicate with an off-chip SPI slave device using FIFO mode. |
| SPI_SlaveFIFOmode | Demonstrate how to communicate with an off-chip SPI master device using FIFO mode. |
| SYS_PLLClockOutput | Change system clock to different PLL frequency and output system clock from CLKO pin. |
| Timer_EventCounter | Use pin P3.4 to demonstrates timer event counter function. |
| Timer_FreeCountingMode | Use the timer pin P3.2 to demonstrate timer free counting mode function. Also display the measured input frequency to UART console. |
| Timer_Periodic | Use the timer periodic mode to generate timer interrupt every 1 second. |
| Timer_ToggleOut | Demonstrate the timer 0 toggle out function on pin P3.4. |
| Timer_TriggerCountingMode | Use the timer pin P3.2 to demonstrate timer trigger counting mode function. And displays the measured input frequency to UART console. |
| Timer_Wakeup | Use Timer to wake up system from Power-down mode periodically. |
| UART_AutoFlow | Show how to transmit and receive data using auto flow control. |
| UART_IrDA | Show how to transmit and receive UART data in UART IrDA mode. |
| UART_RS485 | Transmit and receive data in UART RS485 mode. |
| UART_TxRx_Function | Transmit and receive data from PC terminal through RS232 interface. |

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| WDT_Polling | Use polling mode to check WDT time-out state and reset WDT after time out occurs. |
| WDT_Wakeup | Use WDT to wake up system from Power-down mode periodically. |
| WWDT_Reload | Demonstrate the WWDT counter reload function. |

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