

# A to Z of AI/ML: A Quick Introduction to Artificial Intelligence and Machine Learning Capabilities and Tools

EngCon 2017

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# Outline

Introduction

What is AI?

Neural Networks

Convolutional Neural Networks

Do you need AI/ML?

# My Background

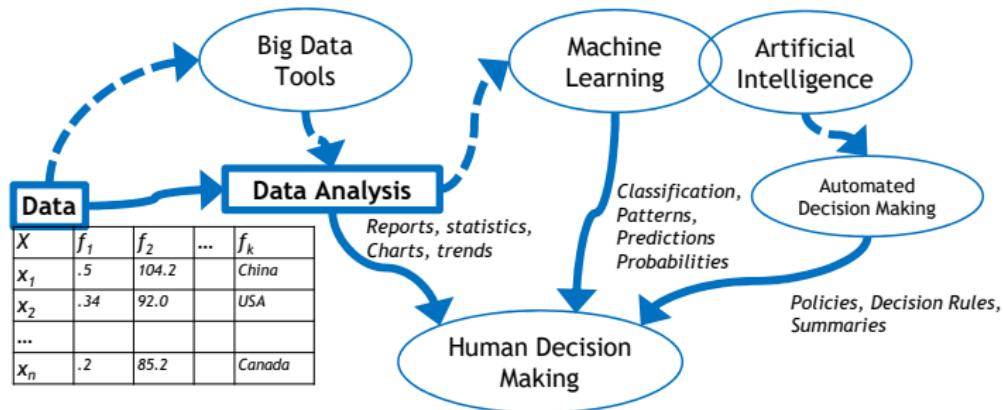
- Waterloo : Assistant Professor, ECE Department since 2015
- PhD at UBC in Computer Science with Prof. David Poole
- Postdoc at Oregon State University
- UW ECE ML Lab:  
<https://uwaterloo.ca/scholar/mcrowley/lab>
- Waterloo Institute for Complexity and Innovation (WICI)
- Research Fellow at Element<sup>AI</sup>
- Pattern Analysis and Machine Intelligence (PAMI)
- <http://waterloo.ai>
  - List of faculty
  - Research projects (co-op/internships)
  - List of spinoff companies from UWaterloo (good place for project ideas)

# What do you think of when you hear?

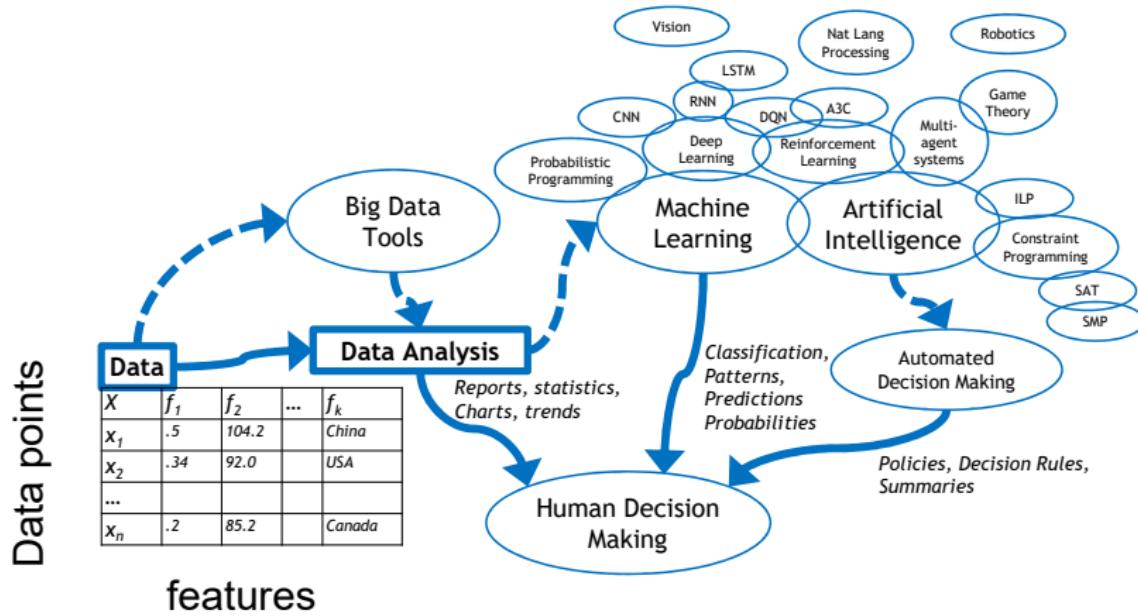
Artificial Intelligence

Machine Learning

# Data, Big Data, Machine Learning, AI, etc, etc,



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# Major Types/Areas of AI

**Artificial Intelligence:** some algorithm to enable computers to perform actions we define as requiring intelligence.

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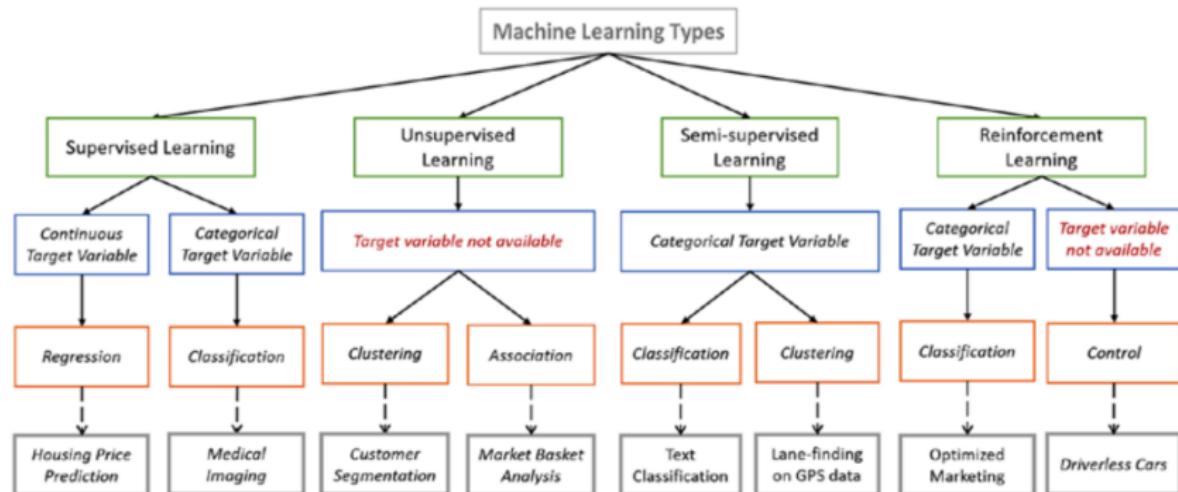
# Major Types/Areas of AI

**Artificial Intelligence:** some algorithm to enable computers to perform actions we define as requiring intelligence. **This is a moving target.**

- Search Based Heuristic Optimization (A\*)
- Evolutionary computation (genetic algorithms)
- Logic Programming (inductive logic programming, fuzzy logic)
- Probabilistic Reasoning Under Uncertainty (bayesian networks)
- Computer Vision
- Natural Language Processing
- Robotics
- **Machine Learning**

# Types of Machines Learning

Machine Learning: "*Detect patterns in data, use the uncovered patterns to predict future data or other outcomes of interest*" – Kevin Murphy, Google Research.



# Deep Learning

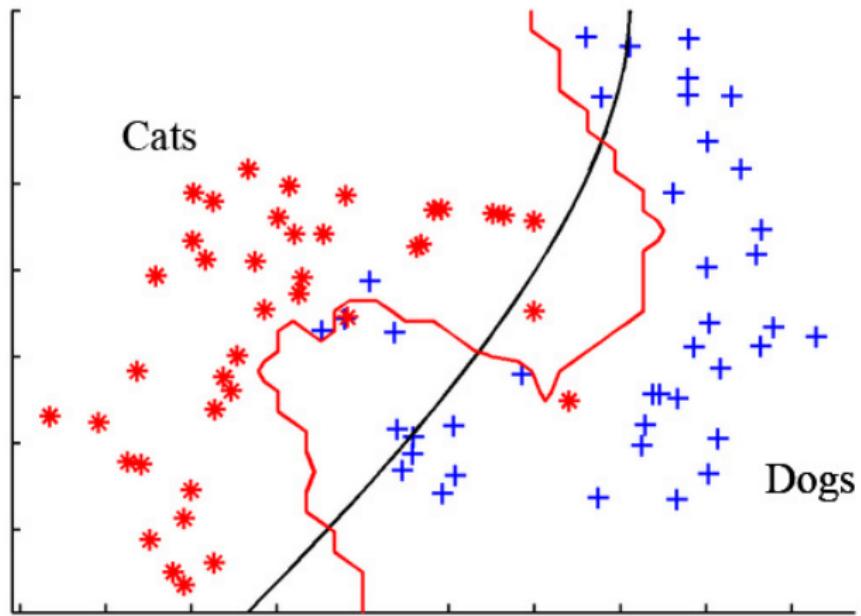
**Deep Learning:** methods which perform machine learning through the use of multilayer neural networks of some kind. Deep Learning can be applied in any of the three main types of ML:

- **Supervised Learning** : very common, enormous improvement in recent years
- **Unsupervised Learning** : just beginning, lots of potential
- **Reinforcement Learning** : recent (past 3 years) this has exploded, especially for video games

# Increasing Complexity of Supervised ML Methods

- ① mean, mode, max, min - basic statistics and patterns
- ② prediction/regression - least squares, ridge regression
- ③ linear classification - use distances and separation of data points.  
(logistic regression, SVM, KNN)
- ④ Kernel Based Classification - define a mapping from original data to a new space, allow nonlinear divisions to be found
- ⑤ Decision trees - learn rules that divide data arbitrarily (C4.5, Random Forests, AdaBoost)
- ⑥ Neural Networks - learn function using 'neurons'
- ⑦ Deep Neural Networks - same, but deep :)
- ⑧ Recurrent Neural Networks - adding links to past timesteps, learning with memory of the past
- ⑨ Convolutional Neural Networks - adding convolutional filters, good for images
- ⑩ Inception Resnets, Long-Term Short-Term Networks, Voxception Networks, .... oh it keeps going...

# One Example of ML: Classification



# Clustering vs. Classification

## Clustering

- Unsupervised
- Uses unlabeled data
- Organize patterns w.r.t. an optimization criteria
- Requires a definition of similarity
- Hard to evaluate
- Examples: K-means, Fuzzy C-means, Hierarchical Clustering, DBScan

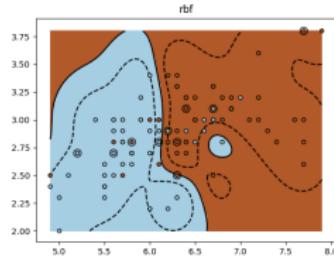
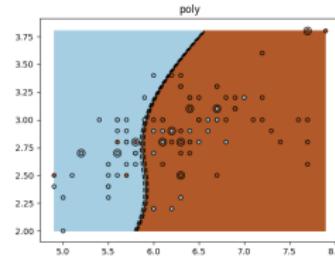
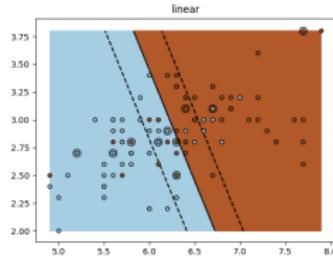
## Classification

- Supervised
- Uses labeled data
- Requires training phase
- Domain sensitive
- Easy to evaluate (you know the correct answer)
- Examples: Naive Bayes, KNN, SVM, Decision Trees, Random Forests

# Classification Performance Depends on the Algorithm

A good example of this choices is Support Vector Machines (SVMs).

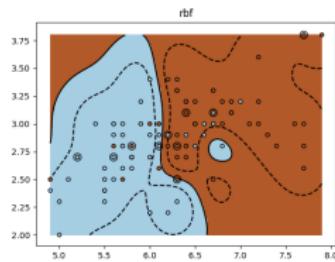
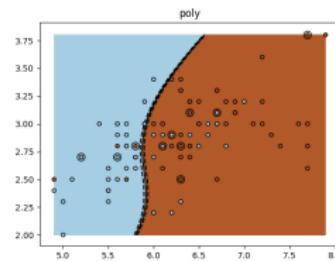
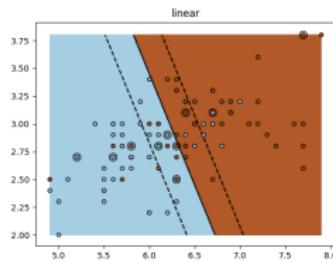
- popular until dawn of deep learning in past few years
- core idea: find a dividing hyperplane
- many variations: plane can be linear, polynomial, gaussian, high-dimensional



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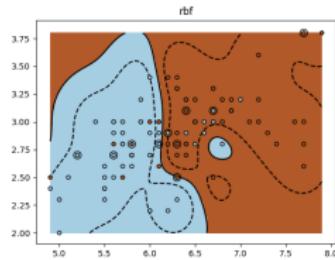
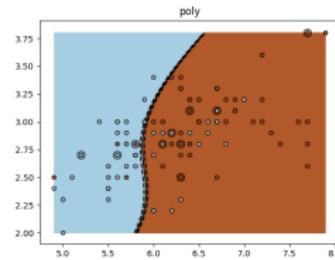
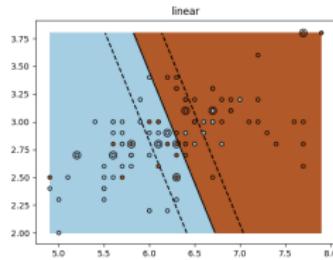


So what is the “right” approach?

# Classification Performance Depends on the Algorithm

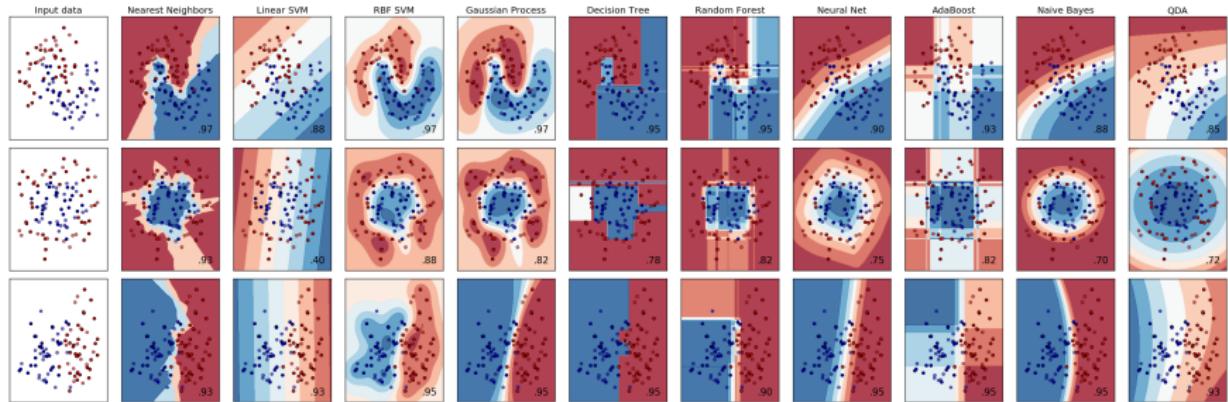
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- core idea: find a dividing hyperplane
- many variations: plane can be linear, polynomial, gaussian, high-dimensional



So what is the “right” approach? **Experimentation!**

# Classification Performance Depends on the Algorithm



So choose carefully...

See [http://scikit-learn.org/stable/auto\\_examples/classification/plot\\_classifier\\_comparison.html](http://scikit-learn.org/stable/auto_examples/classification/plot_classifier_comparison.html)

# Outline

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### What is AI?

## Neural Networks

- Building Upon Classic Machine Learning
- History Of Neural Networks
- Improving Performance

## Convolutional Neural Networks

## Do you need AI/ML?

# Linear Regression vs. Logistic Regression

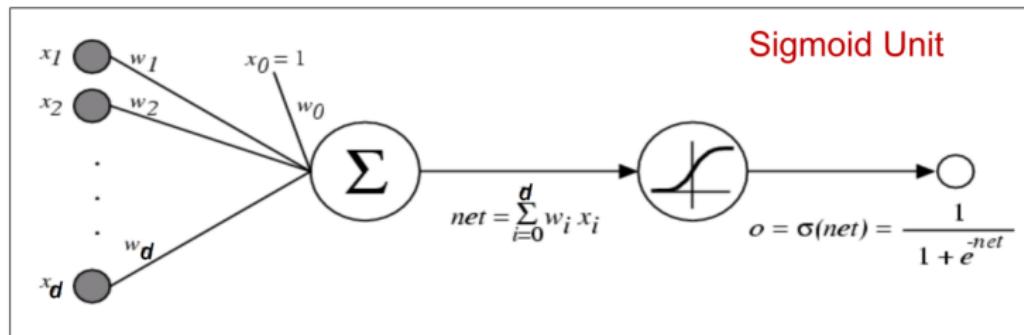
- A simple type of **Generalized Linear Model**
- Linear regression learns a function to predict a continuous variable output of continuous or discrete input variables

$$Y = b_0 + \sum(b_i X_i) + \epsilon$$

- Logistic regression predicts the probability of an outcome, the appropriate class for an input vector or the **odds** of one outcome being more likely than another.

# Logistic Regression as a Graphical Model

$$o(\mathbf{x}) = \sigma(w^T \mathbf{x}_i) = \sigma(w_0 + \sum_i w_i x_i) = \frac{1}{1 + \exp(-(w_0 + \sum_i w_i x_i))}$$



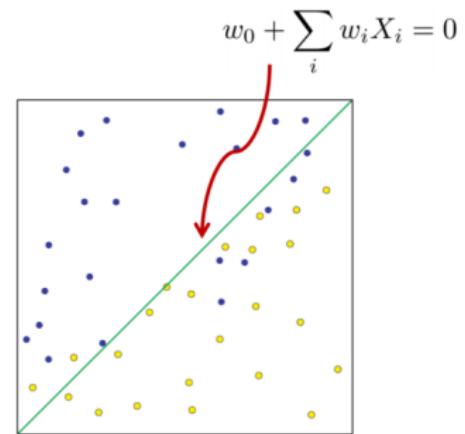
# Logistic Regression Used as a Classifier

Logistic Regression can be used as a simple linear classifier.

- Compare probabilities of each class  $P(Y = 0|X)$  and  $P(Y = 1|X)$ .
- Treat the halfway point on the sigmoid as the decision boundary.

$P(Y = 1|X) > 0.5$  classify X in class 1

$$w_0 + \sum_i w_i x_i = 0$$



# Training Logistic Regression Model via Gradient Descent

- Can't easily perform Maximum Likelihood Estimation
- The negative log-likelihood of the logistic function is given by  $NLL$  and it's gradient by  $g$

$$NLL(w) = \sum_{i=1}^N \log \left( 1 + \exp(-(w_0 + \sum_i w_i x_i)) \right)$$
$$g = \frac{\partial}{\partial w} = \sum_i (\sigma(w^T x_i) - y_i) x_i$$

Then we can update the parameters iteratively

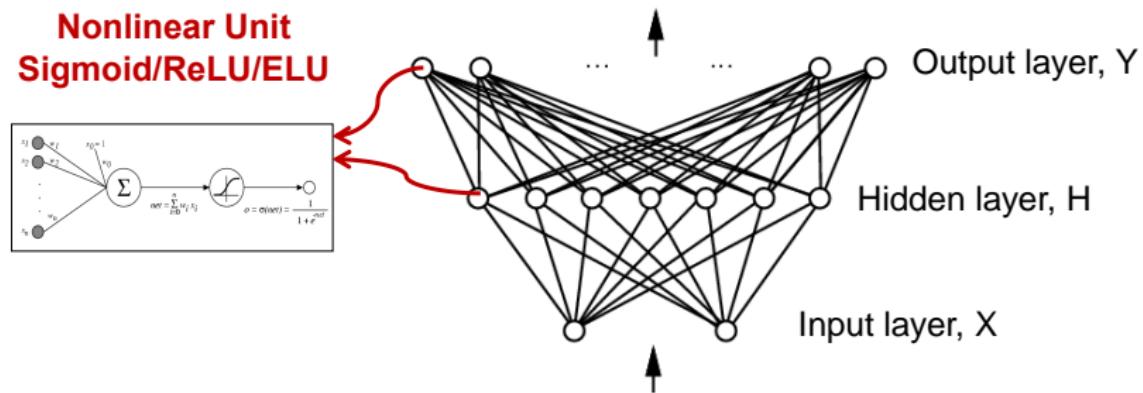
$$\theta_{k+1} = \theta_k - \eta_k g_k$$

where  $\eta_k$  is the learning rate or step size.

# Neural Networks to learn $f : X \rightarrow Y$

- $f$  can be a non-linear function
- $\mathbf{X}$  (vector of) continuous and/or discrete variables
- $\mathbf{Y}$  (vector of) continuous and/or discrete variables

Feedforward Neural networks - Represent  $f$  by network of non-linear (logistic/sigmoid/ReLU) units:



# Basic Three Layer Neural Network

## Input Layer

- vector data, each input collects **one feature**/dimension of the data and passes it on to the (first) hidden layer.

## Hidden Layer

- Each hidden unit computes a weighted sum of all the units from the input layer (or any previous layer) and passes it through a **nonlinear activation function**.

## Output Layer

- Each output unit computes a weighted sum of all the hidden units and passes it through a (possibly nonlinear) **threshold function**.

# Properties of Neural Networks

- **Universality:** Given a large enough layer of hidden units (or multiple layers) a NN can represent **any function**.
- **Representation Learning:** classic statistical machine learning is about learning functions to map input data to output. But Neural Networks, and especially Deep Learning, are more about learning **a representation** in order to perform classification or some other task.

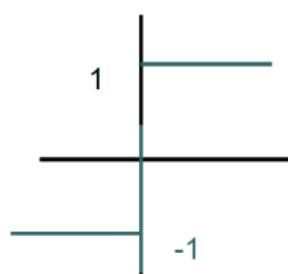
# Hidden Layer: Adding Nonlinearity

- Each hidden unit emits an output that is a nonlinear **activation function** of its net activation.

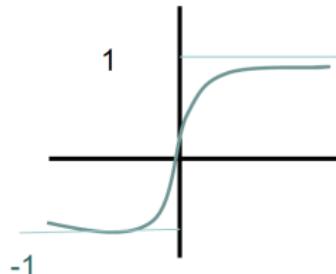
$$y_j = f(\text{net}_j)$$

- This is essential to neural networks power, if it's linear then it all becomes just linear regression.
- The output is thus thresholded through this nonlinear activation function.

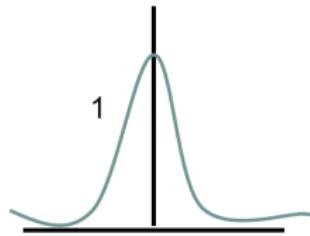
# Activation Functions



a) Threshold



b) Sigmoid

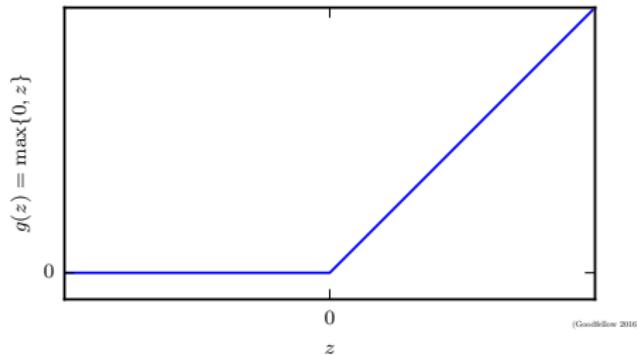


c) Gaussian

$$F_T(x) = \begin{cases} 1 & \text{if } x > \tau \\ -1 & \text{otherwise} \end{cases} \quad F_S(x) = \frac{1}{1 + e^{-cx}} \quad F_G(x) = \frac{1}{\sqrt{2\pi}} e^{-\frac{1}{2}x^2}$$

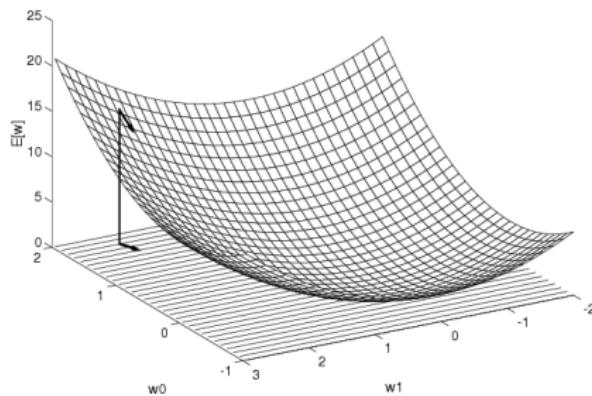
- tanh was another common function.
- sigmoid is now discourage except for final layer to obtain probabilities. Can **over-saturate** easily.
- ReLU is the new standard activation function to use.

# Rectified Linear Activation



- **Rectified Linear Units (ReLU)** have become standard  $\max(0, net_j)$ 
  - strong signals are always easy to distinguish
  - most values are zero, derivative is mostly zero
  - they do not saturate as easily as sigmoid
- new Exponential linear units - evidence that they perform better than ReLU in some situations.

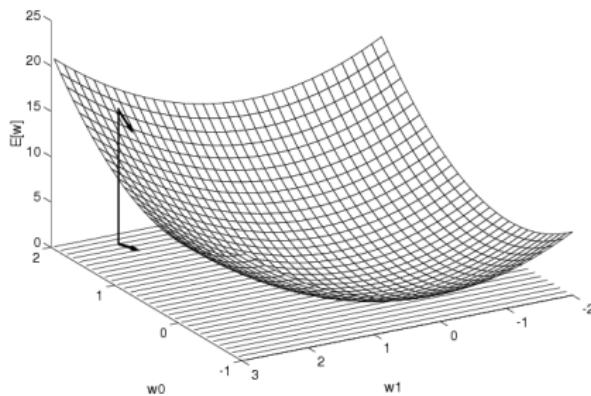
# Gradient Descent



**Error Function:** Mean Squared Error, cross-entropy loss, etc.

(Slides from Tom Mitchell ML Course, CMU, 2010)

# Gradient Descent



**Error Function:** Mean Squared Error, cross-entropy loss, etc.

**Gradient:**  $\nabla E[\mathbf{w}] = \left[ \frac{\partial E}{\partial w_0}, \frac{\partial E}{\partial w_1}, \dots, \frac{\partial E}{\partial w_d} \right]$

**Training Update Rule:**  $\Delta w_i = -\eta \frac{\partial E}{\partial w_i}$  where  $\eta$  is the training rate.

**Note:** For regression, others, this gradient is convex. In ANNs it is not. **So we must solve iteratively**

# Incremental Gradient Descent

Let error function be :  $E_l[\mathbf{w}] = \frac{1}{2}(y^l - o^l)^2$

Do until satisfied:

- For each training example  $l$  in  $D$ 
  - ① Compute the gradient  $\nabla E[\mathbf{w}]$
  - ② update weights :  $\mathbf{w} = \mathbf{w} - \eta \nabla E[\mathbf{w}]$

**Note:** can also use batch gradient descent on many points at once.

# Backpropagation Algorithm

We need an iterative algorithm for getting the gradient efficiently.

For each training example:

- ① **Forward propagation**: Input the training example to the network and compute outputs
- ② **Compute output units errors**:

$$\delta_k^I = o_k^I(1 - o_k^I)(y_k^I - o_k^I)$$

- ③ **Compute hidden units errors**:

$$\delta_h^I = o_h^I(1 - o_h^I) \sum_k w_{h,k} \delta_k^I$$

- ④ **Update network weights**:

$$w_{i,j} = w_{i,j} + \Delta w_{i,j}^I = w_{i,j} + \eta \delta_j^I o_i^I$$

# A Short History

- 40's Early work in NN goes back to the 40s with a simple model of the neuron by McCulloh and Pitt as a summing and thresholding devices.
- 1958 Rosenblatt in 1958 introduced the **Perceptron**, a two layer network (one input layer and one output node with a bias in addition to the input features).
- 1969 Marvin Minsky: 1969. Perceptrons are 'just' linear, AI goes logical, beginning of "AI Winter"
- 1980s Neural Network resurgence: Backpropagation (updating weights by gradient descent)
- 1990s SVMs! Kernels can do **anything!** (no, they can't)

# A Short History

1993 LeNet 1 for digit recognition

2003 Deep Learning (Convolutional Nets Dropout/RBMs, Deep Belief Networks)

1986, 2006 Restricted Boltzman Machines

2006 Neural Network outperform RBF SVM on MNIST handwriting dataset (Hinton et al.)

2012 AlexNet for **ImageNet** challenge - this algorithm beat competition by error rate of 16% vs 26% for next best

- ImageNet : contains 15 million annotated images in over 22,000 categories.
- ZFNet paper (2013) extends this and has good description of network structure

2012-present Google Cat Youtube, speech recognition, self driving cars, computer defeats regional Go champion, ...

2014 GoogLeNet added many layers and introduced inception modules (allows parallel computation rather than serially

# A Short History

- 2014 Generative Adversarial Networks (GANs) introduced.
- 2015 Microsoft algorithm beats human performance at ImageNet challenge.
- 2016 AlphaGo defeats one of best world players of Go Lee Sedol using Deep Reinforcement Learning.
- 2016 Deep Mind introduces A3C Deep RL algorithm that can learn to play Atari games from images by playing with no instructions.

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# Problems with ANNs

- Overfitting
- Very inefficient for images, timeseries, large numbers of inputs-outputs
- Slow to train
- Hard to interpret the resulting model
- Overfitting

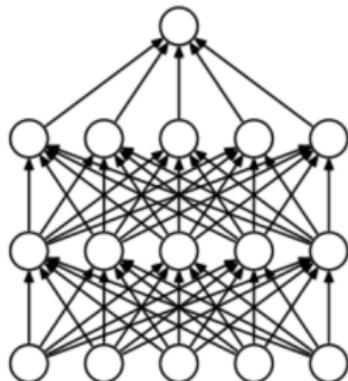
# Heuristics for Improving Backpropagation

There are a number of useful heuristics for training Neural Networks that are useful in practice (maybe we'll learn more today):

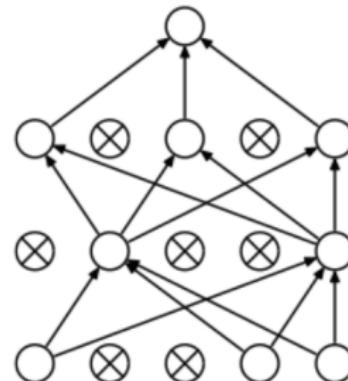
- Less hidden nodes, just enough complexity to work, not too much to overfit.
- Train multiple networks with different sizes and search for the best design.
- Validation set: train on training set until error on validation set starts to rise, then evaluate on evaluation set.
- Try different activation functions: tanh, ReLU, ELU, ...?
- Dropout (Hinton 2014) - randomly ignore certain units during training, don't update them via gradient descent, leads to hidden units that specialize
- Modify learning rate over time (cooling schedule)

# Dropout

- Dropout (Hinton 2014) - randomly ignore certain units during training, don't update them via gradient descent, leads to hidden units that specialize.
- With probability  $p$  don't include a weight in the gradient updates.
- Reduces overfitting by encouraging robustness of weights in the network.

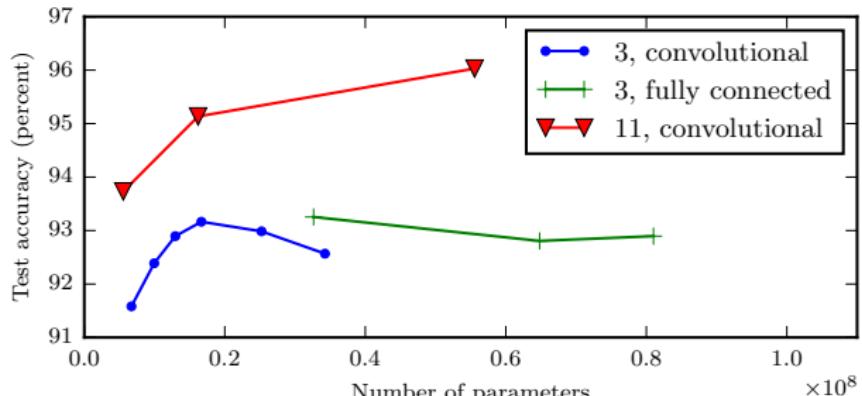


Standard Neural Net



After applying dropout.

# Large, Shallow Models Overfit More



(Goodfellow 2016)

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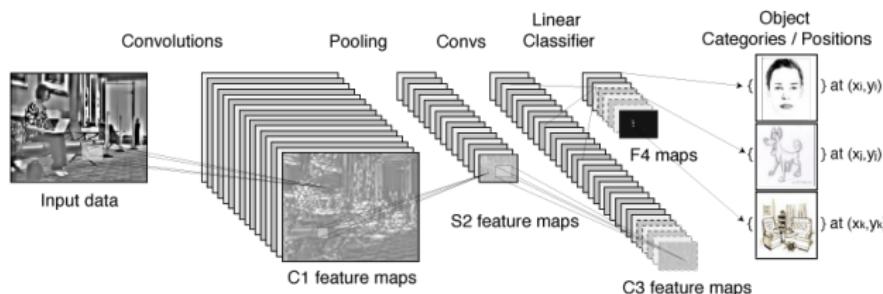
Convolutional Neural Networks

- Motivation
- Other Types of Deep Neural Networks

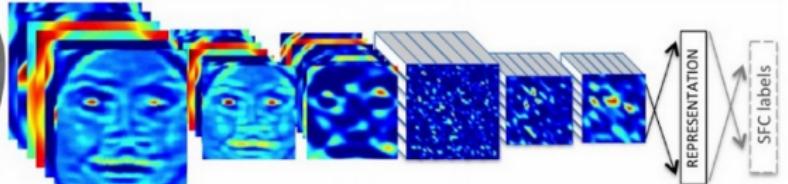
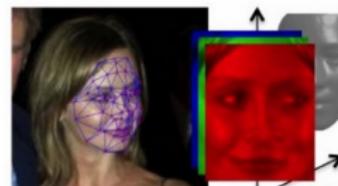
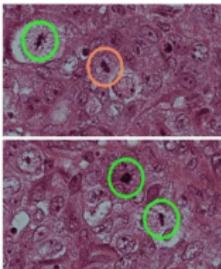
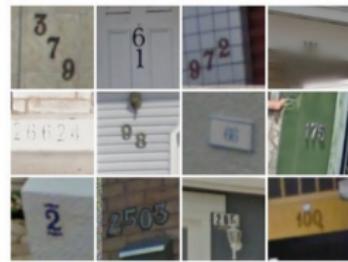
Do you need AI/ML?

# Convolutional Network Structure

- input data: image (eg. 256x256 pixels x3 channels RGB)
- output : categorical label



# Example Applications of CNNs

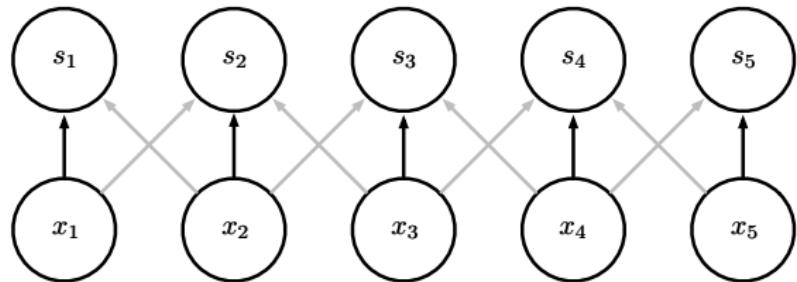


(Karpathy Blog, Oct, 25, 2015 - <http://karpathy.github.io/2015/10/25/selfie/>)

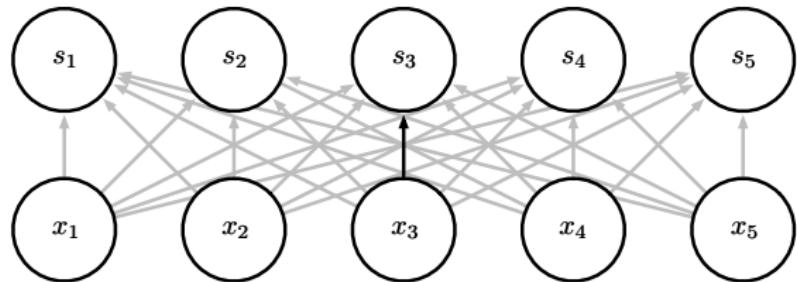
# Parameter sharing

Convolution  
shares the same  
parameters  
across all spatial  
locations

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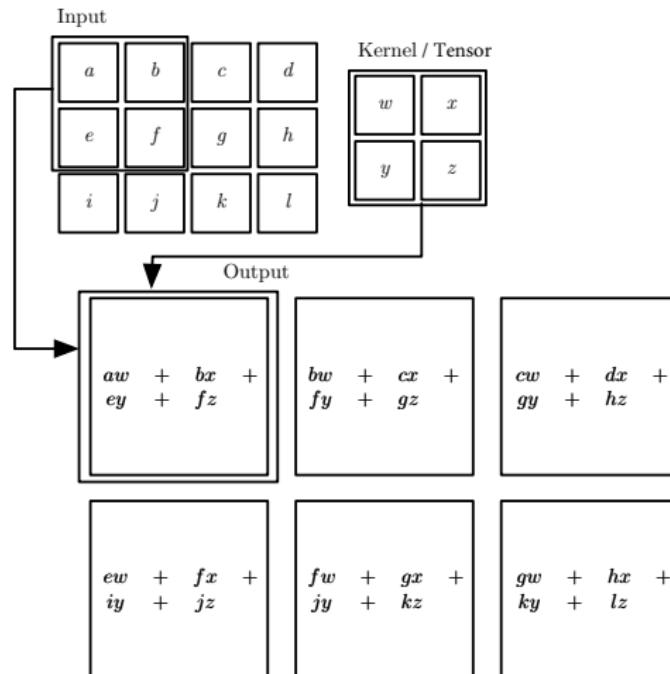


Traditional  
matrix  
multiplication  
does not share  
any parameters



(Goodfellow 2016)

# 2D Convolution



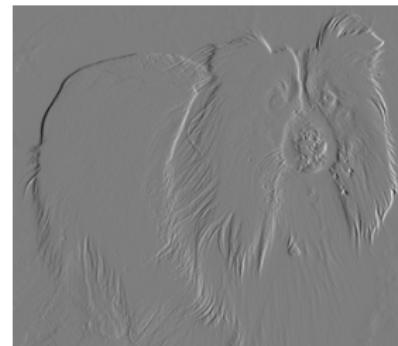
(Goodfellow 2016)

# A simple example

Edge detection by convolution with a kernel that subtracts the value from the neighbouring pixel on the left for every pixel.



Input



Output

1	-1
---	----

Kernel

(Goodfellow 2016)

# Other CNN Modification

**Pooling:** Nearby pixels tend to represent the same thing/class/object.  
So, pool responses from nearby nodes. (eg. mean, median, min, **max**)

**Strides:** number of pixels overlap between adjacent filters

**Zero padding:** removing edge pixels from filter scan, can reduce size of network and deal with edge effects

**Connectivity:** Alternate local connectivity options, partial connectivity

# Other Types of Deep Neural Networks

**RBM:** Restricted Boltzman Machines (RBM) - older directed deep model.

**RNN:** Recurrent Neural Networks (RNN) - allow links from outputs back to inputs, over time, good for time series learning

**LSTM:** Long-Term Short-Term networks - more complex form of RNN

**DeepRL:** Deep Reinforcement Learning

**GAN:** General Adversarial Networks - train two networks at once

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- integrate strategically remembered particular information from the past
- formalizes a process for *forgetting* information over time.
- useful if you need to learn patterns over time and your data features

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**DeepRL:** Deep Reinforcement Learning

- CNNs + Fully Connected Deep Network for learning a representation of a policy
- Reinforcement Learning for updating the policy through experience to make improved decision decisions
- Requires a value/reward function

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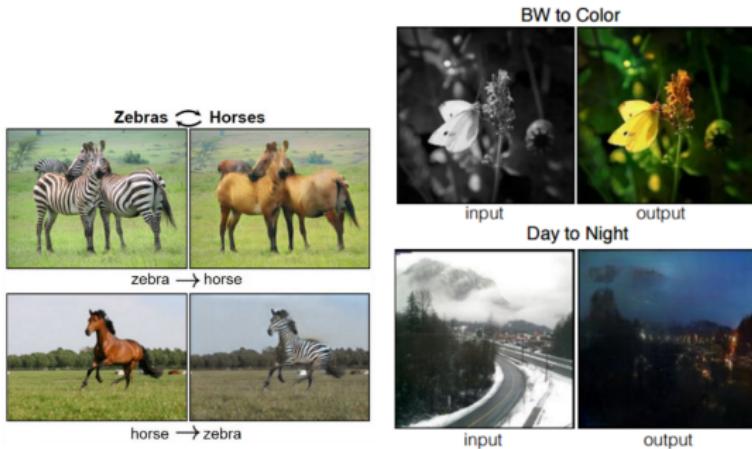
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# General Adversarial Networks



- One network produces/hallucinates new answers (generative)
- Second network distinguishes between the real and the generated answers (adversary/critic)
- Blog withCode: "GANS in 50 lines of code PyTorch code." easy way to get started

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## Do you need AI/ML?

- Defining Your Questions
- Designing Your AI/ML System
- Languages and Libraries
- Deep Learning Frameworks
- Compute Resources

# Defining Your Questions

- Is it a decision to be made?
- Is there a pattern to detect?
- Do you have data?
- What kinds of questions do you have about the data?

Yes/No questions - Did X happen? Are A and B correlated?

Timing - When did X happen?

Anomaly detection - Is X strange/abnormal/unexpected?

Classification - What kind of Y is X?

Prediction - We've seen lots of (X,Y) now we want to know (X',?)

- Do you have labels?
  - Can you give the right answer for some portion of the data?
  - Collecting labels: Automatic? Manual? Crowd-sourced? (eg. Amazon Mechanical Turk) Y
  - Yes → Supervised Learning - Lots of options
  - No → Unsupervised Learning - Some options (getting better all the time)

# Answers and Constraints

What kind of answer do you need? (increasing difficulty)

- Find patterns which are present in the data and view them
- Most likely explanation for a pattern
- Probability of (fact about X,A,B...) being true
- A policy for actions to take in the future to maximize benefit
- Guarantees that X will (or will not) happen (very hard)

How big is your data?

- Is it static?
- MB, GB, TB?
- Is it streaming?
- KB/sec, MB/sec
- How many data points/rows/events will there be?

# How to Design your AI/ML Question

## Define your task:

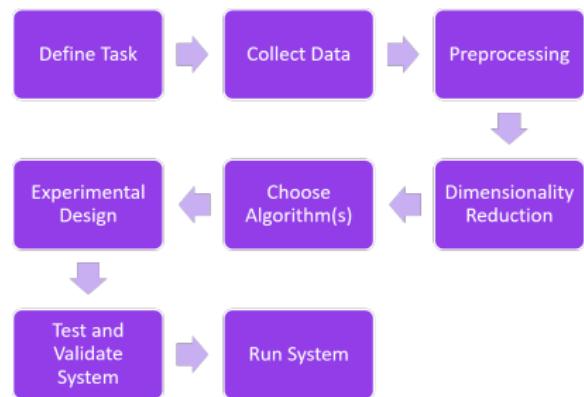
- Prediction, Clustering, Classification, Anomaly Detection?
- Define objectives, error metrics, performance standards

## Collect Data:

- Set up data stream (storage, input flow, parallelization, Hadoop)

## Preprocessing:

- Noise/Outlier Filtering
- Completing missing data (histograms, interpolation)
- Normalization (scaling data)



# How to Design your AI/ML Question

## Dimensionality Reduction / Feature Selection:

- Choose features to use/extract from data
- PCA/LDA/LLE/GDA

## Choose Algorithm:

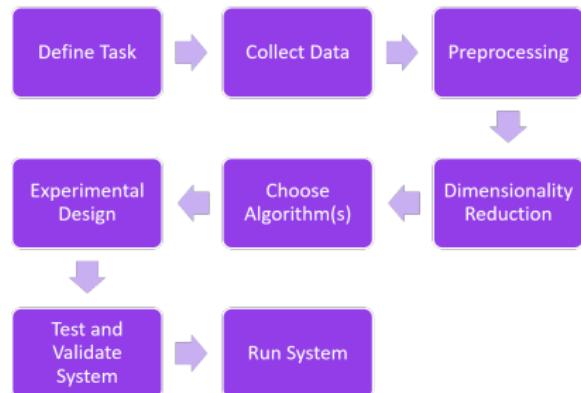
- Consider goals, questions
- Tractability

## Experimental Design:

- train/validate/test data sets
- cross-validation

## Run it! :

- Deployment



# Language Choices

Any language can be used for implementing/using AI/ML algorithms, but some make it much easier

**C++:** you can do it, may need to implement many things yourself

**Java:** many of libraries for ML (Weka is a good open source one, Deeplearning4j)

**Scala:** leaner, functional language that compile to JVM bytecode, good for prototyping, can reuse libraries for Java (Deeplearning4j)

**R:** focussed on statistical methods, more and more machine learning libraries implemented for this

**Matlab:** good for all the calculations, if you have the right libraries it's great (not cheap or very portable beyond school)

**Python:** most commonly used right now for deep learning, we're gonna need another slide ...

# Python

**numpy** - numerical libraries, implementation of matrix and linear algebra datastructures, graphing tools

**pandas** - table datastructure, statistical analysis tools (implements many useful features from R)

**scipy** - includes all of the above and more, full installation of scientific libraries, basically turns Python into R+Matlab

**scikit-learn** - many standard machine learning algorithms implemented as easy-to-use Python APIs

**jupyter notebooks** - these are powerful web-based interfaces to python for data analysis and machine learning.

# Deep Learning Frameworks

**Caffe** - older, easy to set up mockups, harder to install?

**Theano** - made out of University of Montreal, great theoretical setup, very flexible, python only

**Tensorflow** - made by Google, scales to many GPUs, servers, lots of optimization, requires planning of the whole system beforehand, most languages

**PyTorch** - easier to mock things up, try different designs, not as optimized for large scale performance as tensorflow

**MXNet** - made by Microsoft, supports most languages and OS's

**Deeplearning4j** - Java focussed framework

**Keras** - open interface to create models in multiple frameworks (tensorflow, theano, MXNet)

# Cloud Services

There are several powerful, free services you can access via a student account which you can request directly.

**AWS:** Amazon Web Service - very large, has accessible APIs to connect to, many options for hardware to run on (but the best ones will cost extra)

**Azure:** Microsoft - lots of visual tools for composing AI/ML components.

**Google Cloud ML Engine:** - uses all the latest tools and tensorflow models  
None of these provide GPU servers for free, that will cost extra. (It will still work, just be slower for deep learning.)

# Summary

## Introduction

### What is AI?

- Landscape of Big Data/AI/ML
- Classification

## Neural Networks

- Building Upon Classic Machine Learning
- History Of Neural Networks
- Improving Performance

## Convolutional Neural Networks

- Motivation
- Other Types of Deep Neural Networks

## Do you need AI/ML?

- Defining Your Questions
- Designing Your AI/ML System
- Languages and Libraries
- Deep Learning Frameworks
- Compute Resources

# Useful Books

A book for of three eras of Machine Learning:

 [Goodfellow, 2016]

Goodfellow, Bengio and Courville. “*Deep Learning*”, MIT Press, 2016.

- <http://www.deeplearningbook.org/>
- Website has free copy of book as pdf's.

 [Murphy, 2012]

Kevin Murphy, *Machine Learning: A Probabilistic Perspective*, MIT Press, 2012.

 [Duda, Pattern Classification, 2001]

R. O. Duda, P. E. Hart and D. G. Stork, *Pattern Classification (2nd ed.)*, John Wiley and Sons, 2001.

# Useful Papers and Blogs



[lecun2015]

Y. LeCun, Y. Bengio, G. Hinton, L. Y., B. Y., and H. G., "Deep learning", *Nature*, vol. 521, no. 7553, pp. 436444, 2015. Great references at back with comments on seminal papers.



[bengio2009]

Y. Bengio, "Learning Deep Architectures for AI", *Foundations and Trends in Machine Learning*, vol. 2, no. 1. 2009. An earlier general reference on the fundamentals of Deep Learning.



[krizhevsky2012]

A. Krizhevsky, G. E. Hinton, and I. Sutskever, "ImageNet Classification with Deep Convolutional Neural Networks", *Adv. Neural Inf. Process. Syst.* pp. 19, 2012. The beginning of the current craze.



[Karpathy, 2015]

Andrej Karpathy's Blog - <http://karpathy.github.io> Easy to follow explanations with code