Embedded Systems

Assignment_1

الإسم: محمد حمدي عبداللاه

Bn: 27

تحت إشراف: دا محود نوار

التاريخ: الأحد، 17 ربيع الثاني 1446

A Comprehensive Comparison of TM4C123GH6PM and PIC16F877A Microcontrollers

> Introduction

In the world of embedded systems, microcontrollers serve as the heart of many applications, providing the processing power and control necessary for a wide range of devices. Among the many options, two microcontrollers stand out due to their unique architecture and capabilities: the TM4C123GH6PM and the PIC16F877A.

In this document we are going to compare the two devices across many aspects of view. This analysis will provide the reader with a solid foundation of knowledge, enabling an informed decision based on a clear understanding of the differences between these two devices.

> Manufacturer Information

• TM4C123GH6PM - Texas Instruments

Texas Instruments (**TI**) is a leading global semiconductor company that designs and manufactures analog, digital signal processing (DSP), and embedded processing chips. **TI** is known for its robust line of microcontrollers and processors, designed for industrial, automotive, and consumer electronics applications.

The TM4C123GH6PM is part of the **Tiva C Series**, which is widely used for high-performance, real-time embedded applications. This series is based on ARM Cortex-M architectures that we will mention in the next section.

• PIC16F877A - Microchip Technology

Microchip Technology is an American manufacturer specializing in microcontrollers, mixed-signal, analog, and flash-IP integrated circuits. Microchip's PIC microcontrollers are known for their ease of use, affordability, and wide adoption in educational applications.

The PIC16F877A belongs to the **PIC16F** family, one of the most popular **8-bit** microcontroller series in the world.

> Architecture

• TM4C123GH6PM, ARM Cortex - M4

The TM4C123GH6PM is powered by the ARM Cortex-M4 processor, a 32-bit processor built on **RISC** (Reduced Instruction Set Computing) architecture.

• PIC16F877A, 8-bit PIC Microcontroller

The PIC16F877A is based on Harvard architecture with an 8-bit RISC core.

• Key Features of both

Feature	TM4C123GH6PM	PIC16F877A
Core Architecture	32-bit ARM Cortex-M4, RISC	8-bit PIC RISC architecture
	Based	
Instruction Set	Thumb-2 (16-bit and 32-bit	35 simple instructions
	instructions)	
Floating Point Unit	Yes (hardware-based)	
(FPU)		No
DSP Instructions	Yes (includes MAC &	No
	Saturated Arithmetic)	
Harvard Architecture	Yes	Yes
Clock Speed	Yes	Yes
Code Size Optimization	Thumb-2 improves code size	Simple, minimal instruction
	efficiency	set
Power Efficiency	Power-efficient modes and	Low-power, simple
	Sleep States	architecture

• Area of Application

Application Area	TM4C123GH6PM	PIC16F877A
Real Time Systems	Ideal for high-performance	Limited to basic timing
	real-time control systems	control
Low-Power Applications	Efficient power management	Naturally low-power due to
	for advanced low-power	simple 8-bit architecture
	designs	
Educational Projects	Suitable for advanced education	Widely used for basic
	in embedded systems and real-	learning in embedded
	time applications	systems

> I/O Ports

Aspect	TM4C123GH6PM	PIC16F877A
GBIO Pins	The TM4C123GH6PM has up to 43 GPIO pins, which can be configured as input or output, with internal pull-up/pull-down resistors.	The PIC16F877A offers 33 GPIO pins that can be used as input or output with programmable control for analog or digital functions.
USB	Full-speed USB 2.0	No USB support
UART Modules	8	1
Timers	6 general-purpose 16/32-bit timers, 2 watchdog timers	3 timers (1 16-bit, 2 8-bit)
Ports Pic.	OBS ODE ODE	MCLR / VPP RAD / ANO 2 30 RB7 / PGD RAD / ANO 3 33 RB6 / PGC RA1 / ANA 3 3 3 RB5 A2 / AN2 / VREP - VCVREP 4 35 RB4 RA3 / AN3 / VREP 5 5 RB2 RA / TOCK/ CLOUT 6 3 8 8 A5 / AN4 / SS / C2OUT 7 7 8 8 RED / RO / ANS 8 3 8 8 RED / RO / ANS 8 3 8 RED / RO / INT 10 31 V/s Woo 11 V/s 30 RD7 / PSP7 V/s 12 V/s 30 RD7 / PSP6 OSC1 / CLKI 31 22 RD5 / PSP6 OSC2 / CLKO 34 RC / TLOSS / TLCK 34 RC / TLOSS / CCCP 35 RC / TK / CK RC2 / CCP1 37 RC3 / SCK / SCD RC3 / SCK / SCL 31 23 RC3 / SDI / SDI RDD / PSP0 19 22 RD3 / PSP3 RD1 / PSP1 20 RD2 / PSP2

> Memory

• TM4C123GH6PM – Memory Overview

Flash Memory: The TM4C123GH6PM comes with 256 KB of Flash memory, used to store the program code.

SRAM: It has 32 KB of SRAM, used for data storage during runtime.

• PIC16F877A – Memory Overview

Flash Memory: The PIC16F877A has 14 KB of Flash memory. It is much smaller than the TM4C123GH6PM but sufficient for basic applications.

SRAM: It includes 368 bytes of SRAM, a much smaller RAM space primarily for variable storage during program execution.

> Interrupts

TM4C123GH6PM – Interrupt's Types

- ❖ External Interrupts: The TM4C123GH6PM supports multiple external interrupts that can be triggered by GPIO pins. This allows for responsive designs that react to external events.
- ❖ Internal Interrupts: Various internal peripherals can trigger interrupts, such as timers, ADC, PWM, and communication modules (UART, SPI, I2C).
- ❖ Nested Vectored Interrupt Controller (NVIC): The Cortex-M4 core features an NVIC that supports Nested Interrupts, Dynamic Priority Level, Vector Table, and Masking (masking specific interrupts to manage critical tasks effectively).

• PIC16F877A – Interrupt's Types

- **External Interrupts**: The PIC16F877A provides two external interrupt pins (INT and RB0/INT), allowing external events to trigger interrupts.
- ❖ Internal Interrupts: Internal peripherals like timers and the ADC can also generate interrupts. However, the range of internal sources is more limited compared to the TM4C123GH6PM.

> Conclusion

The TM4C123GH6PM and PIC16F877A microcontrollers serve different application needs. The TM4C123GH6PM, with its ARM Cortex-M4 architecture, offers advanced features like larger memory, floating-point support, DSP, and sophisticated interrupt handling, making it ideal for complex applications like IoT and robotics. In contrast, the PIC16F877A, with its simpler 8-bit design, is well-suited for basic tasks, and educational projects. The choice between the two depends on specific Project requirements, balancing performance and complexity with Cost Effectiveness.