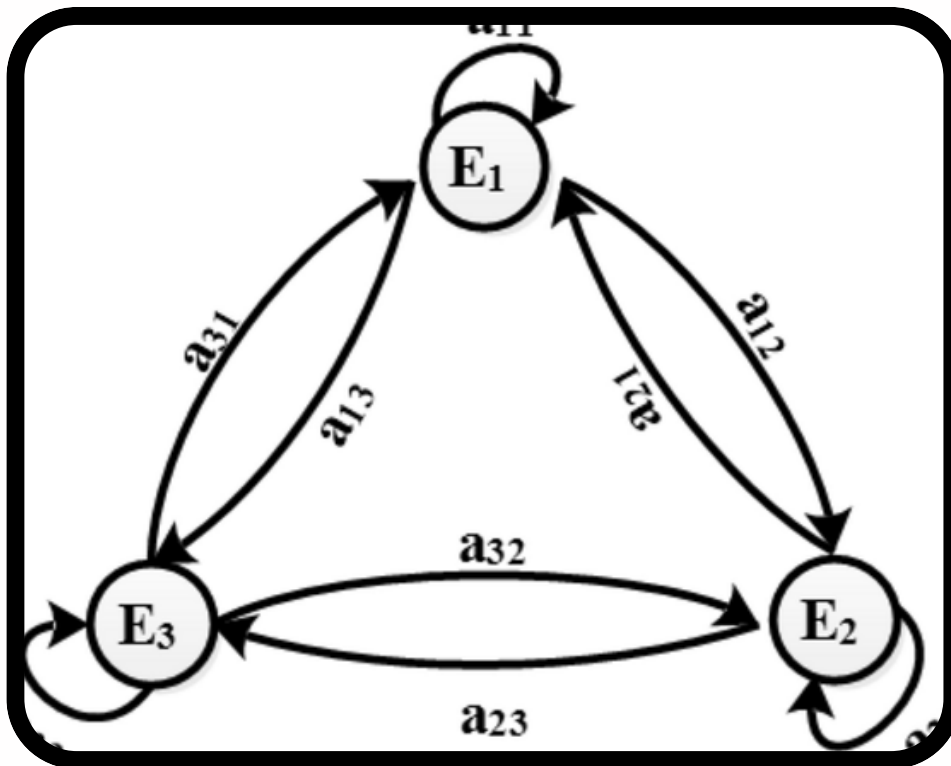


Stochastic Team

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Ashraf



Hidden Markov Chain Model
the main 3 problems of HMM

Introduction to Hidden Markov Chain

Definition

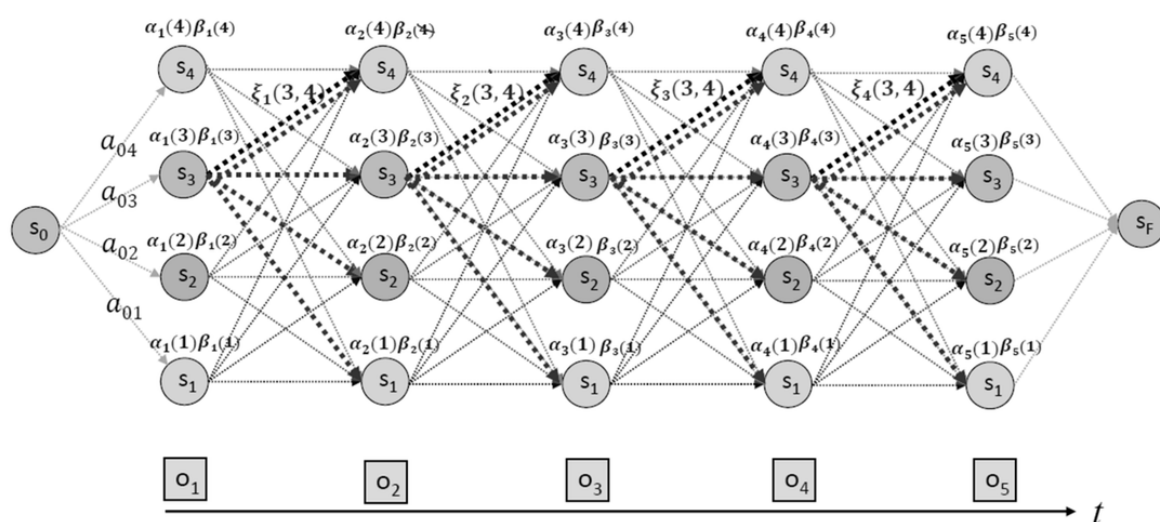
A probabilistic model that describes a system with unobservable states and observable outputs.

Applications

Speech recognition, natural language processing, and information retrieval.

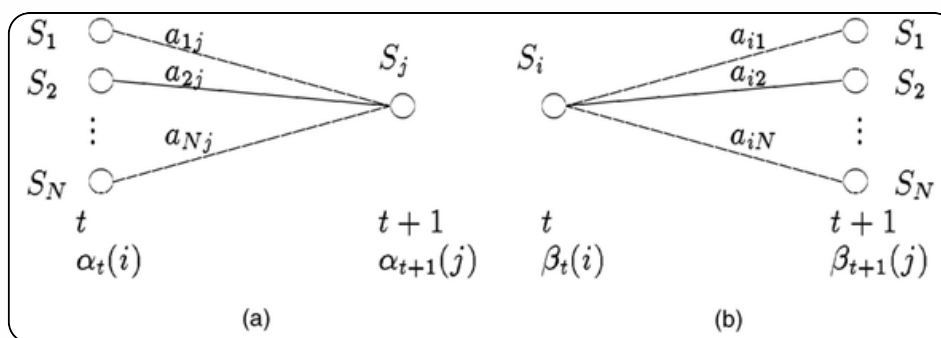
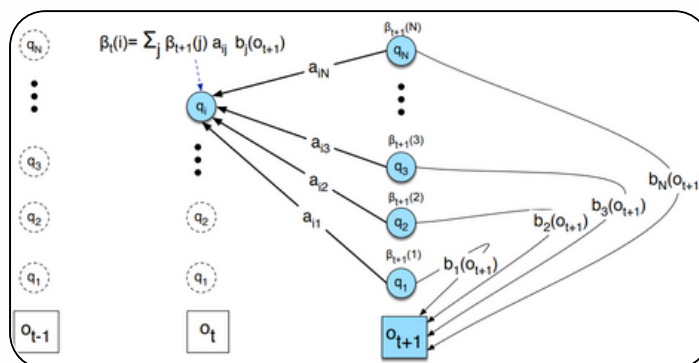
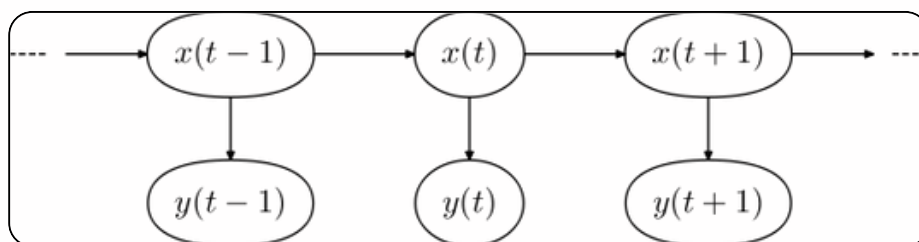
Notable Use Case

Google Translate's Language Models for word suggestions and corrections.



What do you want to start from?

- First Problem: using Forward Algorithm
- Add Backward Algorithm
- Second Problem: Using Viterbi Algorithm
- Third Problem: Using Baum-Welch Algorithm



Forward Algorithm

The Forward Algorithm is a dynamic programming algorithm used to efficiently compute the probability of a sequence of observations in a Hidden Markov Model. It does this by summing over all possible paths through the model that could have generated the observed sequence. The Forward Algorithm is a fundamental part of many other algorithms in HMMs, such as the Viterbi Algorithm and the Baum-Welch Algorithm.

Initialization

$$\alpha_1(i) = p_i b_i(o(1)), \quad i=1, \dots, N$$

Recursion

$$\alpha_{t+1}(i) = [\sum_{j=1}^N \alpha_t(j) a_{ji}] b_i(o(t+1))$$

where $i = 1, \dots, N, t = 1, \dots, T - 1$

Termination

$$P(o(1)o(2)\dots o(T)) = \sum_{j=1}^N \alpha_T(j)$$

Backward Algorithm

The Backward Algorithm is another dynamic programming algorithm used in Hidden Markov Models (HMMs). It calculates the probability of observing a partial or complete sequence of future observations, given a particular state at a specific time. The Backward Algorithm starts from the last observation and works its way backward through time, calculating the probability of being in each state at each time step. This algorithm is useful in various applications, such as speech recognition, natural language processing, and bioinformatics.

1. Initialization:

$$\beta_T(i) = 1, \quad 1 \leq i \leq N$$

2. Recursion

$$\beta_t(i) = \sum_{j=1}^N a_{ij} b_j(o_{t+1}) \beta_{t+1}(j), \quad 1 \leq i \leq N, 1 \leq t < T$$

3. Termination:

$$P(O|\lambda) = \sum_{j=1}^N \pi_j b_j(o_1) \beta_1(j)$$

Viterbi Algorithm

The Viterbi Algorithm is a dynamic programming algorithm used in Hidden Markov Models (HMMs) to find the most likely sequence of hidden states that generated a given sequence of observations. It calculates the probability of each possible state sequence recursively and selects the one with the highest probability. The Viterbi Algorithm is widely used in various applications such as speech recognition, natural language processing, and bioinformatics.

1. Initialization:

$$\begin{aligned} v_1(j) &= \pi_j b_j(o_1) & 1 \leq j \leq N \\ bt_1(j) &= 0 & 1 \leq j \leq N \end{aligned}$$

2. Recursion

$$\begin{aligned} v_t(j) &= \max_{i=1}^N v_{t-1}(i) a_{ij} b_j(o_t); & 1 \leq j \leq N, 1 < t \leq T \\ bt_t(j) &= \operatorname{argmax}_{i=1}^N v_{t-1}(i) a_{ij} b_j(o_t); & 1 \leq j \leq N, 1 < t \leq T \end{aligned}$$

3. Termination:

$$\begin{aligned} \text{The best score: } P^* &= \max_{i=1}^N v_T(i) \\ \text{The start of backtrace: } q_T^* &= \operatorname{argmax}_{i=1}^N v_T(i) \end{aligned}$$

Baum-Welch Algorithm

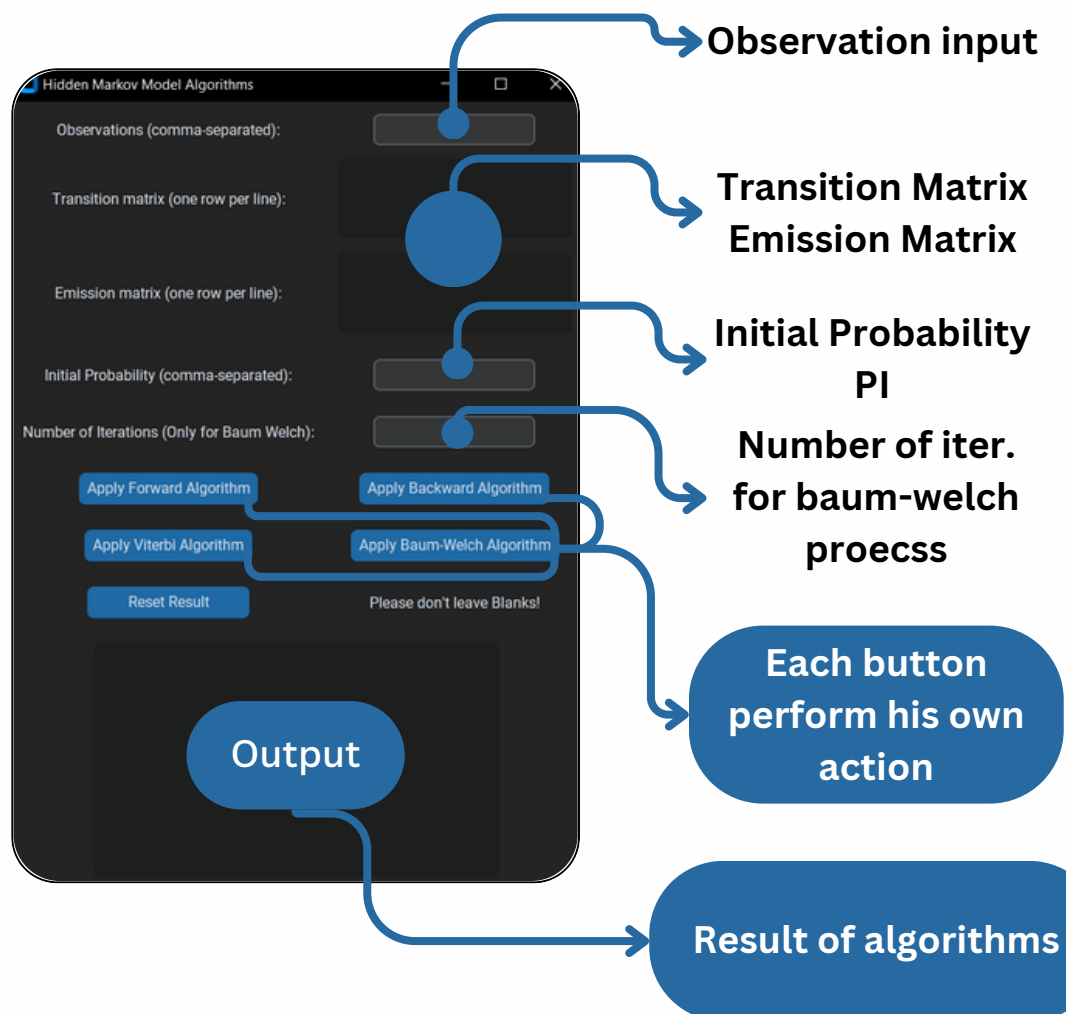
The Baum-Welch algorithm, also known as the forward-backward algorithm, is an iterative algorithm used to estimate the parameters of a hidden Markov model (HMM) given a set of observed data. It is an unsupervised learning algorithm that aims to find the maximum likelihood estimate of the model parameters.

Forward-Backward Algorithm: This step computes the forward and backward probabilities of the HMM, which are used to calculate the expected sufficient statistics for the model parameters.

Parameter Update: This step updates the model parameters based on the expected sufficient statistics obtained from the forward-backward algorithm.

Building up GUI HMM App!

we have tried to make a simple executable app about hidden markov chain, which user can add his inputs and app automatically no need to know how it runs, it's enough to see output with final answers and here's anatomy of App



Forward Algorithm Performing

The forward algorithm is used to calculate the likelihood of observing a particular sequence of observations in a Hidden Markov Model.

```
def forward_algorithm(observations, P, E, Pi):
    # Number of hidden states
    num_states = len(Pi)
    # Number of observations
    num_observations = len(observations)
    # Initialize the forward matrix
    forward_matrix = np.zeros((num_states, num_observations))
    # Init the first value of each state
    forward_matrix[:, 0] = Pi * E[:, observations[0]]
    # Print the initial forward variables
    print(f"Alpha at time 1:\n{forward_matrix[:, 0]}\n")
    # Fill in the rest of the forward matrix
    for t in range(1, num_observations):
        for j in range(num_states):
            forward_matrix[j, t] = np.sum(
                forward_matrix[:, t - 1] * P[:, j] * E[j, observations[t]]
                for i in range(num_states)
            )

    # Print the forward variables at each time step
    print(f"Alpha at time {t+1}:\n{forward_matrix[:, t]}\n")
    # Termination step: Compute the likelihood of the sequence by summation
    # of last 2 times
    likelihood = np.sum(forward_matrix[:, num_observations - 1])
    # Print the final forward matrix and likelihood
    print(
        f"Final Forward Matrix: \n{forward_matrix}\n",
        f"Likelihood of the sequence: {likelihood}",
        sep="\n",
    )
    return forward_matrix, likelihood
```

backward Algorithm Performing

This code computes the likelihood of observing a sequence in a Hidden Markov Model using the backward algorithm, focusing on the probabilities of transitioning between hidden states and emitting observations in reverse order.

```
def backward_algorithm(observations, P, E):
    # Number of hidden states
    num_states = len(P)
    # Number of observations
    num_observations = len(observations)
    # Initialize the backward matrix
    backward_matrix = np.zeros((num_states, num_observations))
    # Initialize the last column of the backward matrix to 1
    backward_matrix[:, num_observations - 1] = 1
    # Print the initial backward variables
    print(
        f"Beta at time {num_observations}:\n{backward_matrix[:, num_observations - 1]}\n"
    )
    # Fill in the rest of the backward matrix
    for t in range(num_observations - 2, -1, -1):
        for i in range(num_states):
            backward_matrix[i, t] = np.sum(
                backward_matrix[j, t + 1] * P[i, j] * E[j, observations[t + 1]]
                for j in range(num_states)
            )

        # Print the backward variables at each time step
        print(f"Beta at time {t+1}:\n{backward_matrix[:, t]}\n")

    # Termination step: Compute the likelihood of the sequence using the initial
    # probabilities and the first observation
    likelihood = np.sum(
        backward_matrix[i, 0] * P[0, j] * E[j, observations[0]]
        for j in range(num_states)
    )

    # Print the final backward matrix and likelihood
    print(
        f"Final Backward Matrix: \n{backward_matrix}\n",
        f"Likelihood of the sequence: {likelihood}",
        sep="\n",
    )

    return backward_matrix, likelihood
```

Viterbi Algorithm Performing

This code employs the Viterbi algorithm to determine the most probable sequence of hidden states in a Hidden Markov Model given a set of observations, calculating both the best path and its associated probability.

```
def viterbi_algorithm(observations, P, E, Pi):  
    # Number of hidden states  
    num_states = len(Pi)  
    # Number of observations  
    num_observations = len(observations)  
    # Initialize the Viterbi matrix  
    viterbi_matrix = np.zeros((num_states, num_observations))  
    # Initialize the backpointer matrix  
    path = np.zeros((num_states, num_observations), dtype=int)  
    # Initialization step  
    viterbi_matrix[:, 0] = Pi * E[:, observations[0]]  
    # Recursion step  
    for t in range(1, num_observations):  
        for j in range(num_states):  
            prev_probs = viterbi_matrix[:, t - 1] * P[:, j] * E[j,  
observations[t]]  
            viterbi_matrix[j, t] = round(max(prev_probs), 5)  
            path[j, t] = np.argmax(prev_probs)  
  
    # Termination step  
    best_path_prob = max(viterbi_matrix[:, -1])  
    best_last_state = np.argmax(viterbi_matrix[:, -1])  
  
    # Backtrace to find the best path  
    best_path = [best_last_state]  
    for t in range(num_observations - 1, 0, -1):  
        best_last_state = path[best_last_state, t]  
        best_path.insert(0, best_last_state)  
  
    return best_path, best_path_prob, viterbi_matrix
```

Baum-Welch Performing

This code implements the Baum-Welch algorithm, iterating through the Expectation-Maximization process to estimate the parameters (initial state probabilities, transition probabilities, and emission probabilities) of a Hidden Markov Model based on a given sequence of observations.

```
def baum_welch(Pi,Emission,Transition,observations,
num_iterations=100):
    state_numbers = len(Pi)
    # Iterate through the Baum-Welch algorithm
    for iteration in range(num_iterations):
        # E-step: Use forward and backward algorithms to calculate expected counts
        forward_matrix, forward_likelihood = forward_algorithm(
            observations, Transition, Emission, Pi)
        backward_matrix, backward_likelihood = backward_algorithm(observations, Transition, Emission)
        # M-step: Update parameters based on expected counts
        # Update initial state probabilities
        Pi = forward_matrix[:, 0] * backward_matrix[:, 0] / forward_likelihood

        # Update transition probabilities
        for i in range(state_numbers):
            for j in range(state_numbers):
                numer = sum(
                    forward_matrix[i, t]
                    * Transition[i, j]
                    * Emission[j, observations[t + 1]]
                    * backward_matrix[j, t + 1]
                    for t in range(len(observations) - 1)
                )
                denom = sum(
                    forward_matrix[i, t] * backward_matrix[i, t]
                    for t in range(len(observations) - 1)
                )
                Transition[i, j] = numer / denom
        # Update emission probabilities
        for j in range(state_numbers):
            for k in range(state_numbers):
                numer = sum(
                    forward_matrix[i, t] * backward_matrix[i, t]
                    if observations[t] == k
                    else 0
                    for t in range(len(observations) - 1)
                )
                denom = sum(
                    forward_matrix[i, t] * backward_matrix[i, t]
                    for t in range(len(observations) - 1)
                )
                Emission[j, k] = numer / denom

    return Pi, Transition, Emission
```