

Statistical Analysis of Wasserstein GANs with Applications to Time-Series Forecasting

(arXiv: 2011.03074, with Stefan Richter)

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Learn to sample from \mathbb{P}^Y



Figure: StyleGAN 2 [Kar+19],
www.thispersondoesnotexist.com

Unconditional Problem

Goal: Learn to sample from **unknown** \mathbb{P}^Y .

Given $Y_i \sim \mathbb{P}^Y$, $i = 1, \dots, n$ **strictly stationary** with values in $[0, 1]^d$.

Sample **i.i.d.** latent noise $Z \in [0, 1]^{d_Z}$ (\mathbb{P}^Z **known**) independent of Y_1, \dots, Y_n .

Find a **generator** function $g : [0, 1]^{d_Z} \rightarrow [0, 1]^d$ such that

$$\mathbb{P}^g(Z) = \mathbb{P}^Y.$$

Conditional Problem

Goal: Learn to sample from unknown $\mathbb{P}^{Y|X=x}$ given conditional information $X = x$.

Given $(X_i, Y_i) \sim \mathbb{P}^{(X, Y)}$, $i = 1, \dots, n$ strictly stationary with values in $[0, 1]^{d_X+d_Y}$.

Sample i.i.d. latent noise $Z \in [0, 1]^{d_Z}$ (\mathbb{P}^Z known) independent of $Y_1, \dots, Y_n, X_1, \dots, X_n$.

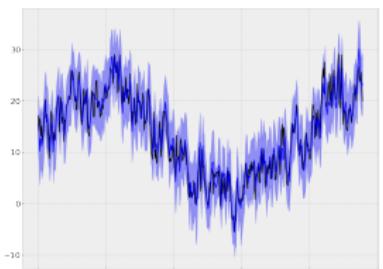
Find a generator function $g : [0, 1]^{d_Z+d_X} \rightarrow [0, 1]^d$ such that

$$\mathbb{P}^{X, g(Z, X)} = \mathbb{P}^{X, Y}.$$

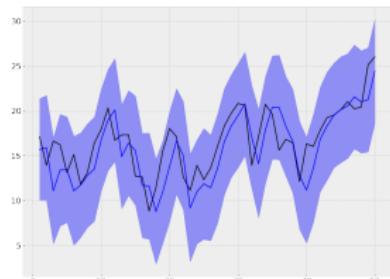
$$\rightsquigarrow \mathbb{P}^{g(Z, X)} = \mathbb{P}^{g(Z, X)|X=x} = \mathbb{P}^{Y|X=x}.$$

Example: Temperature Data in German Cities

Learn **conditional distribution** of temperatures in 32 German cities given temperatures on previous day.



(a) 478 days



(b) 50 days

Figure: Dataset from Deutscher Wetterdienst [PR20].

1-Wasserstein Objective

Dual formulation [Vil08] of W_1 -distance with **critic functions f**:

$$W_1(\mathbb{P}_1, \mathbb{P}_2) = \sup_{f: \mathbb{R}^d \rightarrow \mathbb{R}, \|f\|_L \leq 1} \int_{\mathcal{X}} f \, d\mathbb{P}_1 - \int_{\mathcal{X}} f \, d\mathbb{P}_2.$$

Approximation with **critic networks f**:

Modified network-based Wasserstein Distance

$$W_{1,n}(g) := \sup_{f \in \mathcal{R}_{\mathcal{D}}, \|f\|_L \leq 1} \{\mathbb{E}f(Y) - \mathbb{E}f(g(Z))\}.$$

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Approximation with **critic networks f**:

Modified network-based Wasserstein Distance

$$W_{1,n}(g) := \sup_{f \in \mathcal{R}_D, \|f\|_L \leq 1} \{ \mathbb{E} f(X, Y) - \mathbb{E} f(X, g(Z, X)) \}.$$

The cWGAN Estimator

Empirical Risk Minimizer

$$\hat{g}_n := \arg \min_{g \in \mathcal{R}_G} \hat{W}_{1,n}(g)$$

with

$$\hat{W}_{1,n}(g) := \sup_{f \in \mathcal{R}_D, \|f\|_L \leq 1} \left\{ \frac{1}{n} \sum_{i=1}^n f(Y_i) - \sum_{j=1}^{n\mathcal{E}} f(g(Z_j)) \right\}$$

$\mathcal{E} \propto$ number of epochs (only for the unconditional case)

ReLU Networks

For $v, x \in \mathbb{R}^p$, $p \in \mathbb{N}$, define **ReLU function** $\sigma : \mathbb{R}^d \rightarrow \mathbb{R}^d$,

$$\sigma_v(x) = \max(x - v, 0),$$

where **max component-wise**.

$L \in \mathbb{N}$ **number of hidden layers**, $p = (p_0, \dots, p_{L+1}) \in \mathbb{N}^{L+2}$ **width vector**.

$\mathcal{R}(L, p)$ ReLU networks with architecture (L, p)

$$h : \mathbb{R}^{p_0} \rightarrow \mathbb{R}^{p_{L+1}},$$

$$h(x) = W^{(L)}\sigma_{v^{(L)}}(W^{(L-1)}\sigma_{v^{(L-1)}}(\dots W^{(1)}\sigma_{v^{(1)}}(W^{(0)}x)\dots)),$$

where $W^{(l)} \in \mathbb{R}^{p_l \times p_{l+1}}$ **weight matrices** and $v^{(l)} \in \mathbb{R}^{p_l}$ **bias vectors**.

Sparse bounded ReLU Networks

$$\begin{aligned}\mathcal{R}(L, p, s) := \Big\{ h \in \mathcal{R}(L, p) \; \Big| \; & \max_{j=0, \dots, L} \|W_j\|_\infty \vee |v_j|_\infty \leq 1, \\ & \sum_{j=0}^L \|W_j\|_0 + |v_j|_0 \leq s \text{ and } \| |h|_\infty \|_{L^\infty([0,1]^{p_0})} \leq F \Big\}.\end{aligned}$$

J. Schmidt-Hieber. *Nonparametric regression using deep neural networks with ReLU activation function.* *Annals of Statistics*, 2020.

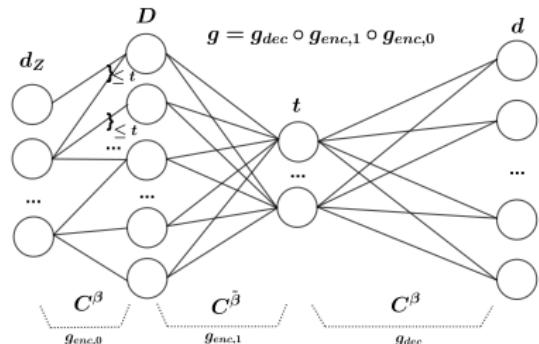
Main Result: Assumptions

Class of generator functions \mathcal{G} :

Compositions of t -sparse, β -Hölder smooth functions.

Assume

$$\exists g^* \in \mathcal{G} : \mathbb{P}^{X, g^*(Z, X)} = \mathbb{P}^{X, Y}.$$



Network Growth Assumptions: With the rate $\phi_{n\mathcal{E}} := (n\mathcal{E})^{-\frac{2\beta}{2\beta+1}}$,

- (a) $L_g \asymp \log(n\mathcal{E})$,
- (b) $\min_{i=1, \dots, L_g} p_{g,i} \asymp (n\mathcal{E}) \cdot \phi_{n\mathcal{E}}$,
- (c) $s_g \asymp (n\mathcal{E}) \cdot \phi_{n\mathcal{E}} \log(n\mathcal{E})$,
- (d) $(L_f \lesssim L_g, s_f \lesssim s_g)$ or $(L_g \lesssim L_f, s_g \lesssim s_f)$.

Main Result: Conditional Excess Risk Bound

Theorem 1 (Convergence rate for the conditional excess risk)

Suppose $F \geq K \vee 1$ and assumptions (a)-(d) hold.

If $\exists \kappa > 1, \alpha > 1 : \beta_X(k) \leq \kappa \cdot k^{-\alpha}$ for all $k \in \mathbb{N}$, then

$$\mathbb{E} W_{1,n}(\hat{g}_n) \lesssim \left(\frac{s_f L_f \log(s_f L_f)}{n} \right)^{1/2} + \sqrt{d} \phi_{n\mathcal{E}}^{1/2} \log(n\mathcal{E})^{3/2}.$$

Furthermore, with probability $\geq 1 - 3n^{-1} - \left(\frac{\log(n)}{n} \right)^{\frac{\alpha-1}{2}}$,

$$W_{1,n}(\hat{g}_n) \lesssim \left(\frac{s_f L_f \log(s_f L_f)}{n} \right)^{1/2} + \sqrt{d} \phi_{n\mathcal{E}}^{1/2} \log(n\mathcal{E})^{3/2} + \left(\frac{\log(n)}{n} \right)^{1/2},$$

where \lesssim dep. on characteristics of (X_1, Y_1) , κ, α and hyperparameters of \mathcal{G} but not on d .

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where \lesssim dep. on characteristics of (X_1, Y_1) , κ, α and hyperparameters of \mathcal{G} but not on d .

Is $W_{1,n}$ a meaningful distance measure?

Main Theorem: $\mathbb{E} W_{1,n}(\hat{g}_n) \rightarrow 0$, $n \rightarrow \infty$.

Lemma 2 (Characterization of weak convergence)

Let $a_n = n^{-\frac{2\gamma}{2\gamma+d+dx}}$ for some $\gamma \geq 1$, and suppose that

- | | |
|-------------------------------|---|
| (e) $F \geq 1$, | (g) $\min_{i=1,\dots,L} p_{f,i} \gtrsim na_n$, |
| (f) $L_f \gtrsim \log_2(n)$, | (h) $s_f \gtrsim \log(n)na_n$, |

where \gtrsim dep. on γ, d . Then, for r.v. $X_n, X \in \mathcal{P}([0, 1]^d)$, $n \in \mathbb{N}$ the following convergence statements for $n \rightarrow \infty$ are equivalent:

- | | | |
|-------------------------------|--|---|
| (i) $X_n \xrightarrow{d} X$, | (ii) $W_1(\mathbb{P}^{X_n}, \mathbb{P}^X) \rightarrow 0$, | (iii) $W_{1,n}(\mathbb{P}^{X_n}, \mathbb{P}^X) \rightarrow 0$. |
|-------------------------------|--|---|

Lemma 3 (Convergence of the estimator)

Let assumptions (e)-(h) hold with some $\gamma \geq 1$. Let $(\tilde{g}_n)_{n \in \mathbb{N}}$ be a sequence of r.v. with $\mathbb{E} W_{1,n}(\tilde{g}_n) \rightarrow 0$. Then

$$(X, \tilde{g}_n(Z, X)) \xrightarrow{d} (X, Y).$$

Synthetic Data

$$U([0, 1]^{10}) \sim (Z_i, X_i) \xrightarrow{h} \mathbb{R}^3 \xrightarrow{g^*} Y_i \in \mathbb{R}^{10}$$

Measured quantity	Number of samples n				
	64	320	960	3200	9600
CI95, unc. OT, unc.	47.92 \pm 5.72 1.634 \pm 0.077	52.26 \pm 6.24 1.630 \pm 0.102	96.16 \pm 1.18 0.970 \pm 0.130	94.50 \pm 0.86 0.412 \pm 0.029	94.56 \pm 0.84 0.342 \pm 0.026
CI95, cond. OT, cond.	24.96 \pm 3.13 7.181 \pm 0.187	23.2 \pm 1.67 6.720 \pm 0.392	45.32 \pm 7.27 7.670 \pm 0.307	94.76 \pm 1.93 1.967 \pm 0.562	94.78 \pm 0.97 1.297 \pm 0.341

Table: Coverage prob. (in %) for $I_{n,N}$ with $\alpha = 0.05$, $T(x) = \sum_{j=1}^{10} x_j$ and $W_1(\hat{\mathbb{P}}_N^{X,Y}, \hat{\mathbb{P}}_N^{X,\hat{g}_n(Z,X)})$, where $N = 1000$. Train 5 models for 700 epochs.

Conclusion

- formalize Wasserstein GANs theoretically (with growing network architectures unlike [BST20]),
- $W_{1,n}$ characterizes weak convergence,
- first convergence rates for (conditional) WGANs,
 \rightsquigarrow recommendations on network sizes,
- allow dependence (β - and ϕ -mixing),
- construct asymptotic confidence intervals for high-dim. time series forecasting,
 \rightsquigarrow simulation studies show good empirical coverage,
- explains good performance under long training for large generators and/or large dimension d .

Research interests

Rather visionary:

- Learning meaningful representations, Disentanglement, Causality
- Transfer Learning, RL, Un-/Self-supervised Learning,
- Learning from Biology: Attention, Recurrence, Modularity, Graph structures, ...

Rather solid:

- Understanding implicit assumptions and biases,
- provable guarantees and failures,
- ...

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Generator Class \mathcal{G}

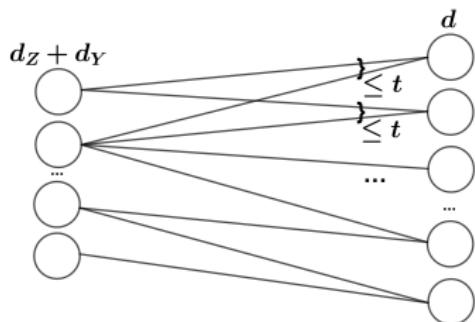
From now on assume $\exists g^* \in \mathcal{G}: \mathbb{P}^{g^*(Z)} = \mathbb{P}^Y$.

First define β -Hölder smooth $f : T \subset \mathbb{R}^t \rightarrow \mathbb{R}$ with $\beta \in \mathbb{N}$, $K > 0$:

$$C_t^\beta(T, K) := \left\{ f : T \rightarrow \mathbb{R} \mid \sum_{\alpha: 0 \leq |\alpha| < \beta} \|\partial^\alpha f\|_\infty + \sum_{\alpha: |\alpha| = \beta - 1} \sup_{x \neq y} \frac{|\partial^\alpha f(x) - \partial^\alpha f(y)|}{|x - y|_\infty} \leq K \right\}.$$

Now

$$\mathcal{G} := \left\{ g : [0, 1]^{d_Z + d_X} \rightarrow [0, 1]^d \mid g_j \in C_t^\beta([0, 1]^t, K) \quad \forall j \in \{1, \dots, d\} \right\}$$



General Generator Class

Generator class $\mathcal{G}(q, \mathbf{d}, \mathbf{t}, \beta, K)$:

$$g = g_q \circ \cdots \circ g_1 \circ g_0,$$

where $g_i : \mathbb{R}^{d_i} \rightarrow \mathbb{R}^{d_{i+1}}$ and
 $g_{ij} \in C_{t_i}^{\beta_i}([-K, K]^{t_i}, K)$ for all i, j .

→ Compositions of sparse Hölder smooth functions

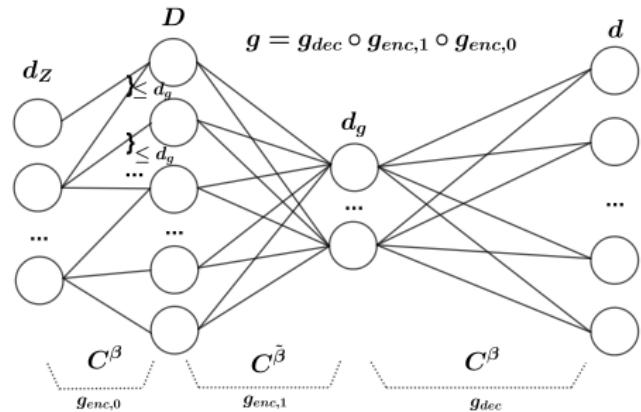


Figure: Possible Encoder-Decoder-Structure of g .

Bounding Constants in the Risk Bound

Size of \mathcal{G}	Error amplification	Constraints
$\exists i \in \{1, \dots, q\} : d_i = d$	$(d \log d)^{1/2}$	-
$\exists i \in \{0, \dots, q\} : t_i = d$	$(d^2 + \beta_i^2)6^d$	$n\mathcal{E} \gtrsim (\beta_i + 1)^{\frac{d}{2\beta_i^2 + 1}}$

Therefore:

- only applicable for low intrinsic dimensionalities t_i ,
- mitigate through longer training $\mathcal{E} \rightarrow \infty$.

Future Work

- other function/network classes (e.g. Groupsort [ALG18]),
- local minima and estimators obtained by SGD,
- include gradient penalty in theory,
- refine approximation results from [Sch17] for more insight into properties of $W_{1,n}$ and good generator architectures,
- minimax rate for excess risk,
- rate of the weak convergence,
- understand double descent...

Proof: Bound on the Estimation Error

Use entropy [DL02; DMR95] and large deviation bounds [KR05] for β -mixing seq. on:

$$\begin{aligned} e_n &\leq \dots \leq 2 \sup_{g \in \mathcal{R}_G} |\hat{W}_{1,n}(g) - W_{1,n}(g)| \\ &\leq 2 \sup_{f \in \mathcal{R}_D} \left| \frac{1}{n} \sum_{i=1}^n f(X_i) - \mathbb{E}f(X) \right| \\ &\quad + 2 \sup_{g \in \mathcal{R}_G, f \in \mathcal{R}_D} \left| \frac{1}{n\mathcal{E}} \sum_{j=1}^{n\mathcal{E}} f(g(Z_j)) - \mathbb{E}f(g(Z)) \right|. \end{aligned}$$

Proof: Empirical Process Theory

$N_{[]}(\delta, \mathcal{F}, \|\cdot\|_\infty)$ bracketing number.

Derived from [DL02]

Let $\mathcal{F} \subset \{f : \mathbb{R}^r \rightarrow \mathbb{R} \text{ measurable}\}$ with $\sup_{f \in \mathcal{F}} \|f\|_\infty \leq F$. Let

$$H := 1 \vee \log N_{[]} (2F \sum_{k=0}^{\infty} \beta_X(k), \mathcal{F}, \|\cdot\|_\infty).$$

If $\exists \kappa > 1, \alpha > 1 : \beta_X(k) \leq \kappa \cdot k^{-\alpha}$ for all $k \in \mathbb{N}$ and $H \leq n$, then there exist $C_1, C_2 > 0$ dep. on characteristics of $(X_i)_{i \in \mathbb{Z}}$ such that

$$\begin{aligned} \mathbb{E}^* \sup_{f \in \mathcal{F}} |(\hat{\mathbb{P}}_n^X - \mathbb{P}^X)f| &\leq C_1 \cdot n^{-1/2} \cdot \int_0^F \sqrt{1 + \log N_{[]}(\varepsilon, \mathcal{F}, \|\cdot\|_\infty)} d\varepsilon \\ &\quad + C_2 F \cdot \left(\frac{H}{n}\right)^{\frac{\alpha}{\alpha+1}}. \end{aligned}$$

Proof: Large Deviation Bounds

For i.i.d. and ϕ -mixing seq.: McDiarmid's inequality [Doo40; Rio00]

Coupling [Ber79; DL02]

Let $q \in \mathbb{N}$. Construct a sequence of r.v. $(X_i^0)_{i \geq 0}$ such that:

- (1) $U_i^0 := (X_{iq+1}^0, \dots, X_{iq+q}^0) \stackrel{d}{=} (X_{iq+1}, \dots, X_{iq+q}) =: U_i \quad \forall i \geq 0.$
- (2) $(U_{2i}^0)_{i \geq 0}$ is i.i.d. and so is $(U_{2i+1}^0)_{i \geq 0}$.
- (3) $\mathbb{P}(U_i \neq U_i^0) \leq \beta(q) \quad \forall i \geq 0.$

- Replace X_i by X_i^0 , (3) and Markov ineq.)
- Utilize averaging $\sum f(X_i^0) = \sum \tilde{f}(U_i^0)$ with $\tilde{f}(u) = \sum_{j=1}^q f(u_j)$
~~~ Talagrand-type inequality [KR05] includes variance bound:

$$\mathbb{P}(Z \geq \mathbb{E}Z + \varepsilon_{n,\sigma^2}(x)) \leq \exp(-x) \stackrel{!}{=} n^{-b}$$

$$\stackrel{x=b \ln(n)}{\rightsquigarrow} Z \leq \mathbb{E}Z + \varepsilon_{n,\sigma^2}(b \ln n) \text{ with prob. } \geq 1 - n^{-b}.$$

# Proof: Large Deviation Bounds

For i.i.d. and  $\phi$ -mixing seq.: McDiarmid's inequality [Doo40; Rio00]

## Coupling [Ber79; DL02]

Let  $q \in \mathbb{N}$ . Construct a sequence of r.v.  $(X_i^0)_{i>0}$  such that:

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# Proof: Approximation Error

Theorem ([Sch17], Theorem 5)

For all

$$h \in C^\beta([0, 1]^r, K), \quad k \geq 1 \quad \text{and} \quad N \geq (\beta + 1)^r \vee (K + 1)e^r,$$

there exists a network

$$\tilde{h} \in \mathcal{R}(L, (r, 6(r + \lceil \beta \rceil)N, \dots, 6(r + \lceil \beta \rceil)N, 1), s, \infty)$$

with

$$L = 8 + (k + 5)(1 + \lceil \log_2(r \vee \beta) \rceil) \quad \text{and} \quad s \leq 141(r + \beta + 1)^{3+r}N(k + 6),$$

such that,

$$\|h - \tilde{h}\|_{L^\infty([0, 1]^r)} \leq (2K + 1)(1 + r^2 + \beta^2)6^rN2^{-k} + K3^\beta N^{-\beta/r}.$$

## Approximation Error: Composition

Recall  $g = g_q \circ \cdots \circ g_0$ . Define

$$h_0 = \frac{g_0}{2F} + 1/2, \quad h_i = \frac{g_i(2F \cdot -F)}{2F} + 1/2 \quad \text{and} \quad h_q = g_q(2F \cdot -F).$$

Then  $g = g_q \circ \cdots \circ g_0 = h_q \circ \cdots \circ h_0$ .

Defining  $H_i = h_i \circ \cdots \circ h_0$  and  $\tilde{H}_i = \tilde{h}_i \circ \cdots \circ \tilde{h}_0$ ,

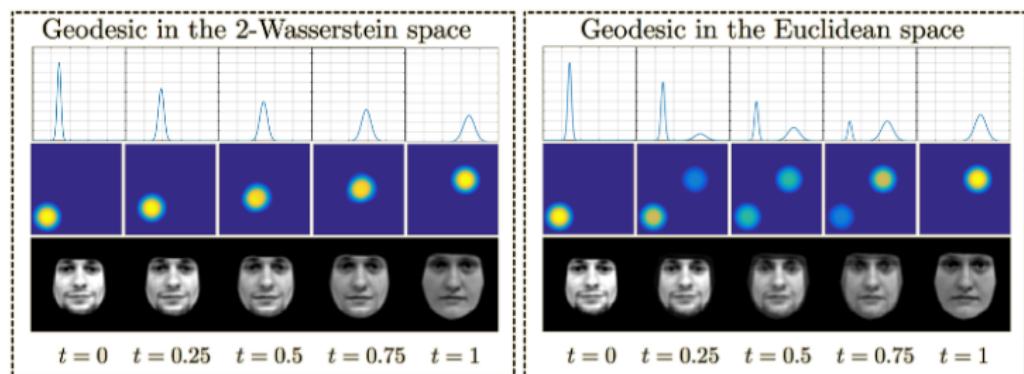
$$\begin{aligned}|H_i(x) - \tilde{H}_i(x)|_\infty &\leq |h_i \circ H_{i-1}(x) - h_i \circ \tilde{H}_{i-1}(x)|_\infty + \| |h_i - \tilde{h}_i|_\infty \|_{L^\infty([0,1]^{d_i})} \\&\leq Q |H_{i-1} - \tilde{H}_{i-1}|_\infty + \| |h_i - \tilde{h}_i|_\infty \|_{L^\infty([0,1]^{d_i})}.\end{aligned}$$

# Wasserstein Distance

$(\mathcal{X}, \|\cdot\|)$  Polish metric space, here  $\mathcal{X} = [0, 1]^d$ .  $\mathcal{P}(\mathcal{X})$  set of Borel probability measures.

$$W_p(\mu, \nu) := \inf_{\pi \in \Pi(\mu, \nu)} \left( \int_{\mathcal{X} \times \mathcal{X}} \|x - y\|^p d\pi(x, y) \right)^{1/p},$$

where  $\Pi(\mu, \nu)$  is the set of joint distributions on  $\mathcal{X} \times \mathcal{X}$  with marginals  $\mu$  and  $\nu$ .



**Figure:** Interpolation in the optimal transport framework (left) and Euclidean space (right). Source: [www.math.cmu.edu/~mthorpe/OTNotes](http://www.math.cmu.edu/~mthorpe/OTNotes)

# Conditional Encoder-Decoder-Structure

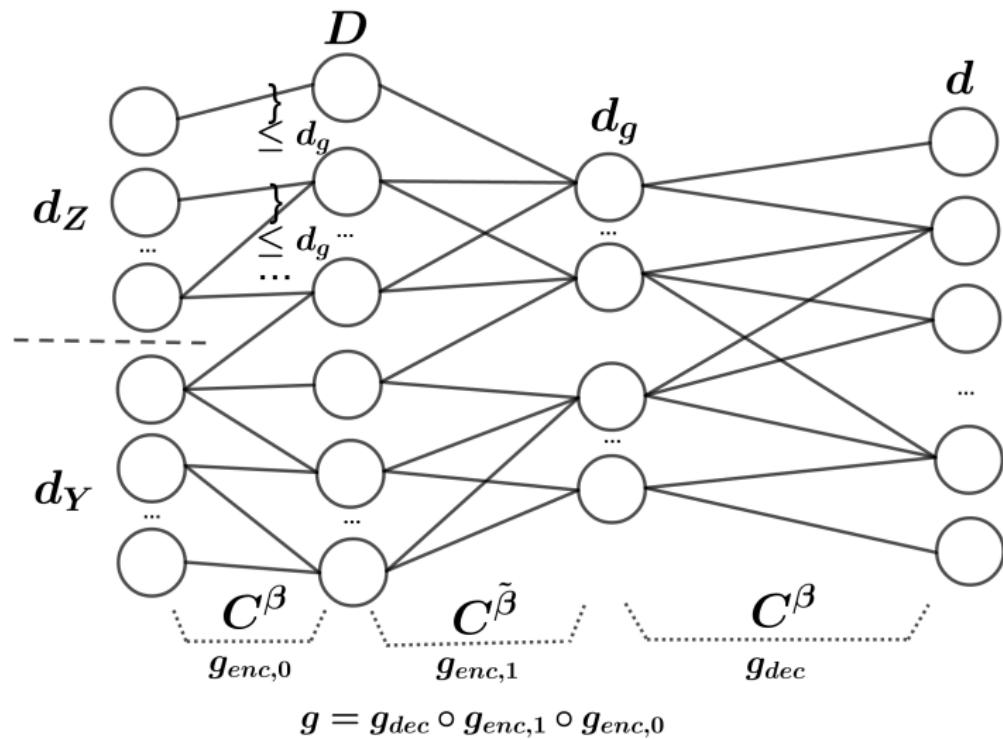


Figure: Possible Encoder-Decoder-Structure of  $g$ . [HR20]

# Risk Bound in Terms of $W_1^\gamma$

Assume  $\exists g^* \in \mathcal{G} : \mathbb{P}^{g^*}(Z) = \mathbb{P}^X$ .

Lemma 1:  $W_1^\gamma(g) \leq W_{1,n}(g) + Cn^{-\frac{\gamma}{2\gamma+d}}$ .

Main Theorem:  $\mathbb{E}W_{1,n}(\hat{g}_n) \lesssim \left( \frac{s_f L_f \log(s_f L_f)}{n} \right)^{1/2} + \sqrt{d} \phi_{n\mathcal{E}}^{1/2} \log(n\mathcal{E})^{3/2}$ .

$$\stackrel{(i) \rightarrow (iv)}{\Rightarrow} \mathbb{E}W_1^\gamma(\hat{g}_n) \lesssim n^{-\frac{\gamma}{2\gamma+d}} + \sqrt{d} \phi_{n\mathcal{E}}^{1/2} \log(n\mathcal{E})^{3/2}.$$

Choose minimal  $\gamma \geq 1$ , which recovers rate. E.g. for  $\mathcal{E} = 1$ :

$$\frac{\beta_{i^*}}{2\beta_{i^*} + t_{i^*}} = \min_{i=0,\dots,q} \frac{\beta_i}{2\beta_i + t_i} = \frac{\gamma}{2\gamma + d},$$

$$\gamma = \frac{\beta_{i^*} d}{t_{i^*}} \quad \mathbb{E}W_1^\gamma(\hat{g}_n) \lesssim \phi_n^{1/2} \log(n)^{3/2}.$$

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# Is $W_{1,n}$ a meaningful distance measure?

$$W_{1,n}(g) := \sup_{f \in \mathcal{R}(L_f, p_f, s_f), \|f\|_L \leq 1} \{\mathbb{E}f(X, Y) - \mathbb{E}f(X, g(Z, X))\}.$$

$\gamma$ -Hölder smooth integral probability metric,  $\gamma \geq 1$

$$W_1^\gamma(g) := \sup_{f \in C^\gamma([0,1]^{d+d_X}, K), \|f\|_L \leq 1} \{\mathbb{E}f(X, Y) - \mathbb{E}f(X, g(Z, X))\}.$$

Lemma 1 (Lower bound on  $W_{1,n}$ )

Let  $a_n = n^{-\frac{2\gamma}{2\gamma+d+d_X}}$ , and suppose that

- |                              |                                                   |
|------------------------------|---------------------------------------------------|
| (e) $F \geq 1,$              | (g) $\min_{i=1, \dots, L} p_{f,i} \gtrsim n a_n,$ |
| (f) $L_f \gtrsim \log_2(n),$ | (h) $s_f \gtrsim \log(n) n a_n,$                  |

where  $\gtrsim$  dep. on  $\gamma, d$ . Then there exists a  $C > 0$  only dep. on  $\gamma, d, F$  such that for any measurable  $g : [0, 1]^{d_Z+d_X} \rightarrow [0, 1]^d$ ,

$$W_1^\gamma(g) \leq W_{1,n}(g) + C a_n^{1/2}.$$

# Asymptotic Confidence Intervals

**Predict** 1-dimensional *continuous* statistic  $T(Y)$  given  $X = x$  using  
 $(X, \hat{g}_n(Z^*, X)) \xrightarrow{d} (X, Y)$ .

**Sample** N i.i.d. points  $Z_j^* \sim \mathbb{P}^Z$  indep. of  $X_i, Y_i, Z_i$ ,  $i = 1 \dots, n$ .  
**Compute**

$$\hat{F}_{n,N}(t|x) := \frac{1}{N} \sum_{j=1}^N \mathbb{1}_{\{\textcolor{teal}{T}(\hat{g}_n(Z_j^*, x)) \leq t\}}.$$

**yields** asymptotic  $(1 - \alpha)$ -confidence intervals for  $T(Y)$  given  $X = x$ ,

$$I_{n,N}(x) := \left\{ t \in \mathbb{R} : \hat{F}_{n,N}(t|x) \in \left( \frac{\alpha}{2}, 1 - \frac{\alpha}{2} \right] \right\}$$

# Temperature in German Cities

**Predict** mean temperature in Berlin given mean temperatures of  $d_X = 32$  (or  $d_X = 3$ ) German cities on the previous day.

Training set (4300 days):  
2006/07/01 - 2018/04/09.

Test set (478 days):  
2018/04/10 - 2019/07/31.

Generator:  
 $p_g = (4 + d_X, 10, 10, 10, d)$ .

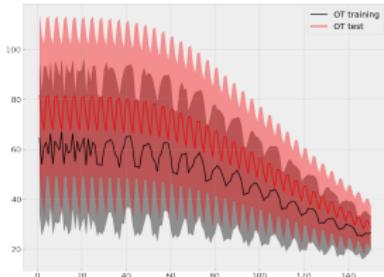
Critic:  
 $p_f = (d + d_X, 32, 32, 32, 32, 32, 1)$ .



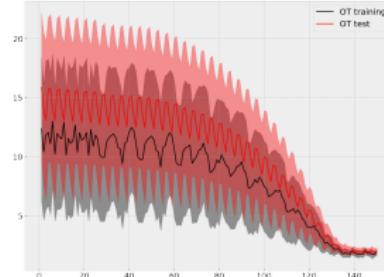
**Figure:** Data from Deutscher Wetterdienst, map from the authors of [PR20].

# Temperature in German Cities

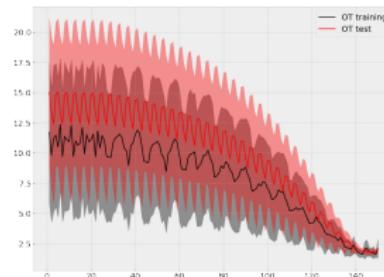
## Empirical Wasserstein Loss



(a) 32 to 32

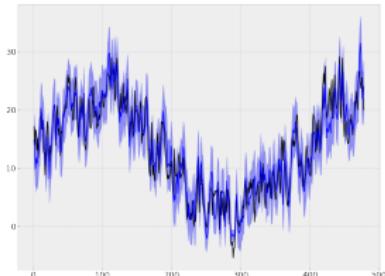


(b) 32 to 1

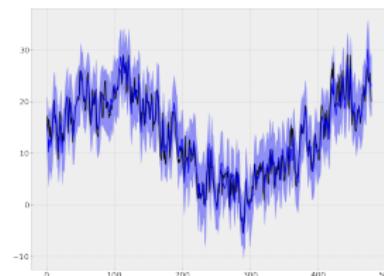


(c) 3 to 1

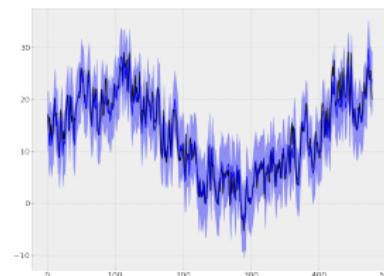
## Predictions on Test Set



(a) 32 to 32



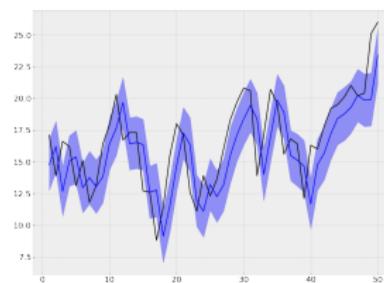
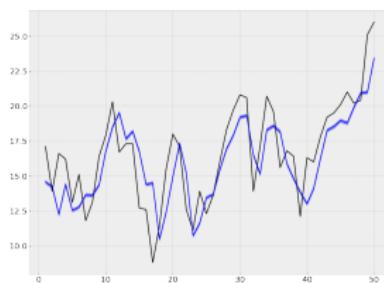
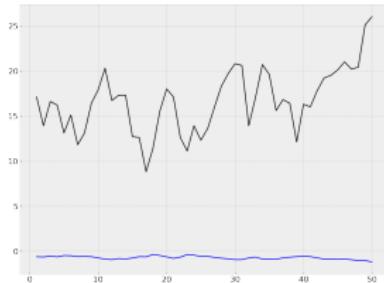
(b) 32 to 1



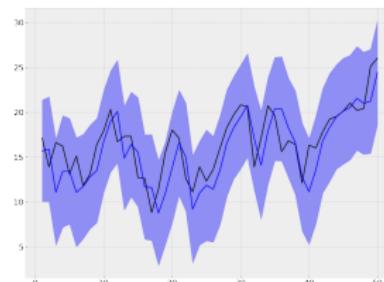
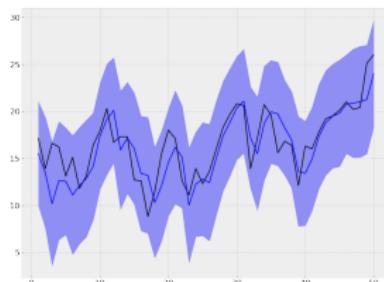
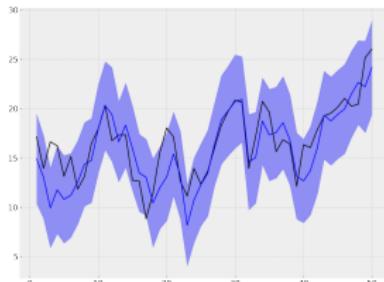
(c) 3 to 1

# Temperature in German Cities

After 150 Epochs



After 1000 Epochs



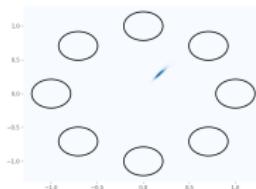
(a) 32 to 32: 70.71%  
(88.70% after 2150 ep.)

(b) 32 to 1: 89.54%

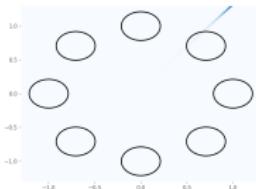
(c) 3 to 1: 89.96%

# GAN Comparison

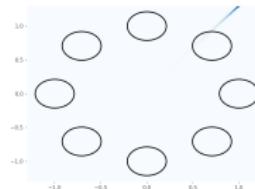
GAN [Goo+14]:



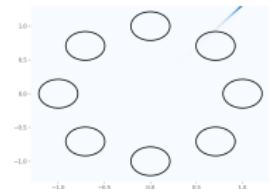
(a) 0 epochs



(b) 5 epochs

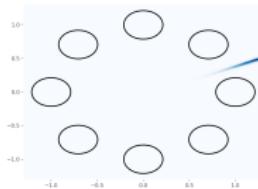


(c) 100 epochs

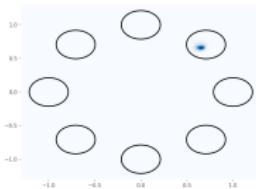


(d) 300 epochs  
 $\geq 35000$  updates

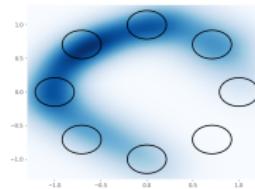
Least Squares GAN [Mao+16]:



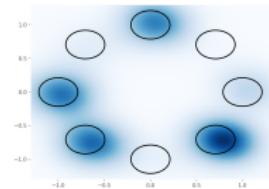
(a) 0 epochs



(b) 100 epochs



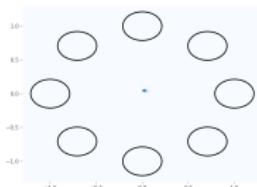
(c) 120 epochs



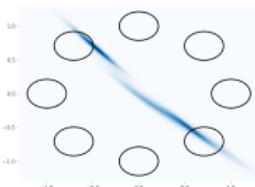
(d) 280 epochs  
 $\geq 34000$  updates

# GAN Comparison

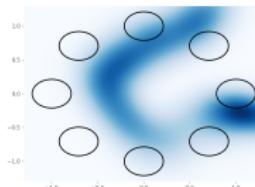
WGAN [ACB17]:



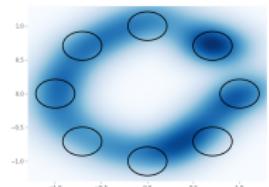
(a) 10 epochs



(b) 140 epochs

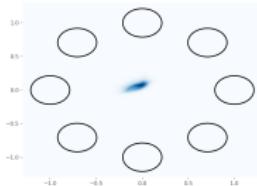


(c) 180 epochs

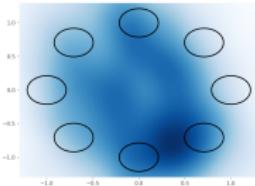


(d) 300 epochs  
 $\geq 6700$  updates

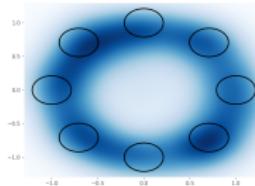
WGAN-GP [Gul+17]:



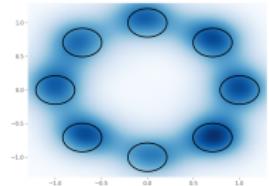
(a) 10 epochs



(b) 15 epochs



(c) 25 epochs



(d) 50 epochs  
 $\geq 1300$  updates

# Learn to generate samples from a probability distribution



Figure: WGAN-GP [Gul+17] with DC-GAN networks [RMC16] (2017)

StyleGAN2 [Kar+19] (2019): [www.thispersondoesnotexist.com](http://www.thispersondoesnotexist.com)