

# Assignment 10

EE, SIGNALS AND SYSTEMS 1400-2

**Problem 1.** Determine the inverse  $\mathcal{Z}$ -transform of

$$X(z) = \ln(1 - 2z), \quad |z| < \frac{1}{2}$$

- (a) by using the power series  $\ln(1 - x) = -\sum_{m=1}^{\infty} \frac{x^m}{m}$ ,  $|x| < 1$ ,
- (b) by first differentiating  $X(z)$  and then using the derivative to recover  $x[n]$ .

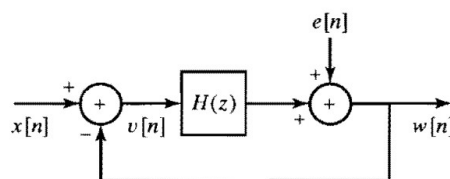
**Problem 2.**  $H(z)$  is the system function of the causal LSI system in the below figure.

- (a) Using the  $\mathcal{Z}$ -transform of signals in the figure, obtain an expression for  $W(z)$  in the form

$$W(z) = H_1(z)X(z) + H_2(z)E(z),$$

where  $H_1(z)$  and  $H_2(z)$  are expressed in terms of  $H(z)$ .

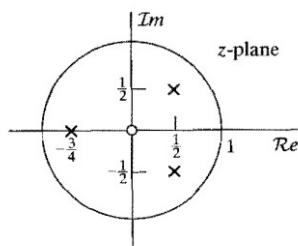
- (b) Is  $H(z)$  stable? Are  $H_1(z)$  and  $H_2(z)$  stable?



**Problem 3.** For each of the following signals, determine the  $\mathcal{Z}$ -transform and its ROC, and sketch the pole-zero diagram:

- (a)  $x[n] = a^n u[n] + b^n u[n] + c^n u[-n - 1]$ ,  $|a| < |b| < |c|$
- (b)  $x[n] = n^2 a^n u[n]$
- (c)  $e^{n^4} [\cos(\frac{\pi}{12}n)] u[n] - e^{n^4} [\cos(\frac{\pi}{12}n)] u[n - 1]$

**Problem 4.** The pole-zero diagram in the following figure corresponds to the  $\mathcal{Z}$ -transform  $X(z)$  of a causal signal  $x[n]$ . Sketch the pole-zero diagram of  $Y(z)$ , where  $y[n] = x[-n + 3]$ . Also, specify the ROC for  $Y(z)$ .



**Problem 5.** The LSI system  $\mathcal{S}$  is such that

$$x[n] = \left(\frac{1}{2}\right)^n u[n] + 2^n u[-n-1] \xrightarrow{\mathcal{S}} y[n] = 6\left(\frac{1}{2}\right)^n u[n] - 6\left(\frac{3}{4}\right)^n u[n]$$

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- (a) Find the system function  $H(z)$  of the  $\mathcal{S}$ . Plot the poles and zeros of  $\mathcal{S}$ , and indicate its ROC.
- (b) Find the impulse response  $h[n]$  of the system.
- (c) Write a difference equation that characterizes the system.
- (d) Is the system stable? Is it causal?

**Problem 6.** A causal and stable LSI system  $\mathcal{S}$  has its input  $x[n]$  and output  $y[n]$  related by the linear constant-coefficient difference equation

$$y[n] + \sum_{k=1}^{10} \alpha_k y[n-k] = x[n] + \beta x[n-1].$$

Let  $h[n]$  be the impulse response of  $\mathcal{S}$ .

- (a) Show that  $h[0]$  is nonzero.
- (b) Show that  $\alpha_1$  can be determined by knowing  $\beta$ ,  $h[0]$ , and  $h[1]$ .
- (c) If  $h[n] = (0.9)^n \cos(\pi n/4)$  for  $0 \leq n \leq 10$ , sketch the pole-zero plot for  $\mathcal{S}$ , and indicate its ROC.