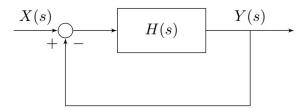
Problem 1. Find the LSI system with real impulse response and transfer function H(s) that satisfies:

- The response of the system to e^t is e^t .
- The system has three finite poles and no finite zero.
- The system has a pole at s = j.
- The step response of the below system is asymptotically 1 at $t \to +\infty$.



Problem 2. The signal $y(t) = e^{-2t}u(t)$ is the output of a causal all-pass system for which the transfer function is $H(s) = \frac{s-1}{s+1}$

- (a) Find and sketch at least two possible inputs x(t) that result in y(t) as the output.
- (b) What is the input x(t) if it is known that

$$\int_{-\infty}^{+\infty} |x(t)| \mathrm{d}t < \infty$$

(c) What is the input x(t) if it is known that a stable (but not necessarily causal) system exists that outputs x(t) for the input y(t)? Find the impulse response h(t) of this filter, and show by direct convolution that it has the claimed property (i.e., (y*h)(t) = x(t)).

Problem 3. Find the impulse response of the following systems defined by differential equations. Assume that all systems are initially at rest.

(a)
$$\frac{d^2}{dt^2}y(t) + 11\frac{d}{dt}y(t) + 24y(t) = 5\frac{d}{dt}x(t) + 3x(t)$$

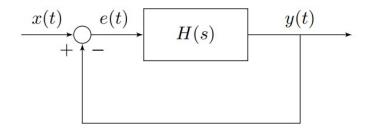
(b)
$$\frac{d^4}{dt^4}y(t) + 4\frac{d}{dt}y(t) = 3\frac{d}{dt}x(t) + 2x(t)$$

Problem 4. We have an LSI system with transfer function

$$H(s) = \frac{\omega_n^2}{s^2 + 2\xi\omega_n s}$$

where ω_n and ξ are constants. We add a unit-gain feedback to this system as shown in the following figure. Assume that the input to the overall system is the unit-step signal and define the error signal as:

$$e(t) = x(t) - y(t)$$



- (a) Evaluate $I_1 = \int_0^{+\infty} te'(t) dt$.
- (b) Assuming $\xi > 1$, find $I_2 = \int_0^{+\infty} |te'(t)| dt$.

Problem 5. X(s) is the Laplace transform of x(t) about which we know

- (1) x(t) is real and even.
- (2) X(s) has four poles and no zeros in the finite s-plane.
- (3) X(s) has a pole at $s = \frac{1}{2}e^{j\pi/4}$.
- $(4) \int_{-\infty}^{+\infty} x(t) dt = 4.$

Determine x(t) and its ROC.

Problem 6. x(t) and y(t) are right-sided signals that satisfy

$$\frac{\mathrm{d}}{\mathrm{d}t}x(t) = -2y(t) + \delta(t),$$
$$\frac{\mathrm{d}}{\mathrm{d}t}y(t) = 2x(t).$$

Determine Y(s) and X(s), along with their regions of convergence.