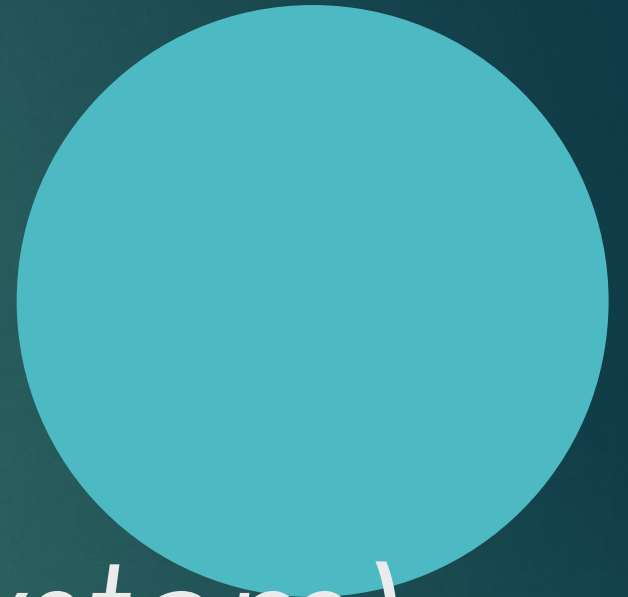


ROS2 8

(Robot Operating System)



Task 1:

You are required to create a ROS2 python pkg (iti_lab_8) that is formed of 2 nodes (node1, node2) node 1 should publish a string message once every second, and it should iterate between 2 different messages to create the following sequence (“Hi”, “Hello”, “Hi”, “Hello”, “Hi”, “Hello”). node2 should print a string message “I Heard: <msg>”



Instructors repo Link:

- 1- <https://github.com/ahmedgharieb1>
- 2- <https://github.com/M-abdeen>

Material repo :

https://github.com/ahmedgharieb1/ITI_LSV_ROS2

