ROS2 LAB1
(Robot Operating System)

Make ros2 python package <ITI_LAB1> include 2 node (node1,node2) as shown ,node1 publish str msg (" <your name> is publish <,><counter>") counter is start with 0 ,node2 receive str msg , publish the counter and reset flag to reset counter in publisher node (max value for counter is 5) show your rqt_graph as shown save it as png image.