ROS control

Arm Control

arm_joint_state   arm_publish_joints

convert_joint_msg   arm_real_to_sim

Hands Control

get_angle_hands   set_angle_hands

Base Control

base_status   teleop_real_base

send_velocity

Sensors Control

wait_data   read_sensor

sensors\info

arm\joints_state

hand\get_angle

base\status

Real to Simulation

arm\pose

hand\set_angle

base\vel

Simulation to Real

ROS Master

PyBullet