

FROM RESEARCH TO INDUSTRY

cea tech

[PSSM] – ORLANDO OMG MEETING

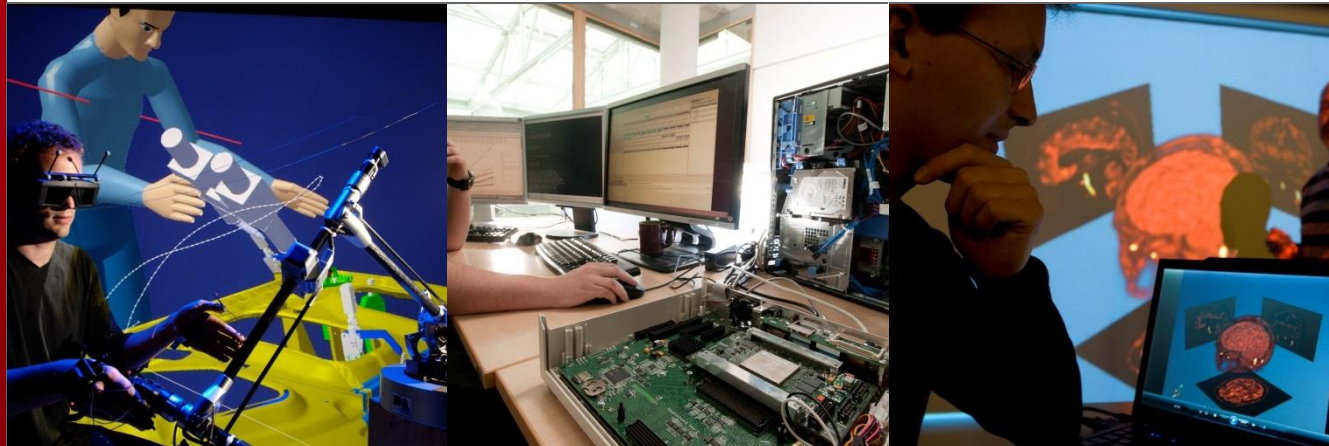
JUNE 23RD, 2016

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list



1. Deferred events semantics
 - Support other dispatching strategies than FIFO
2. State machine configuration analysis
 - Transition priority (i.e., level of nesting) shall not affect other regions
3. Test suite refactoring
 - Define alternative execution traces for each test
4. Call event semantics
 - Integrate in the semantic model a support for call events
5. Event data passing
 - Data shipped by event occurrences must be available to behaviors
6. DoActivity
 - Integrate in the semantic model the resolution discussed in Reston
7. State machine redefinition
 - Integrate in the semantic model a support for redefined state-machines

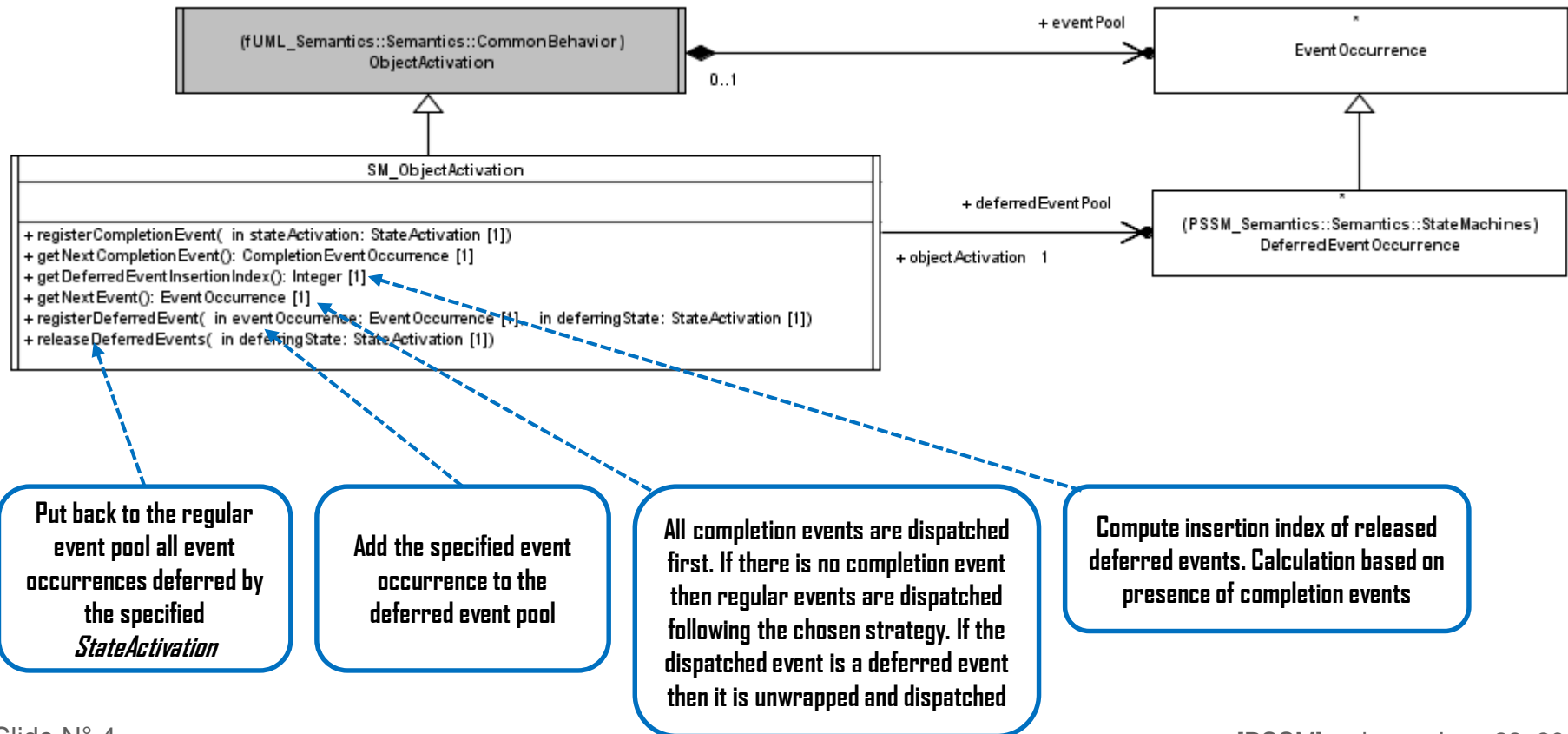
DEFERRED EVENT SEMANTICS AND DISPATCHING STRATEGIES

Problem

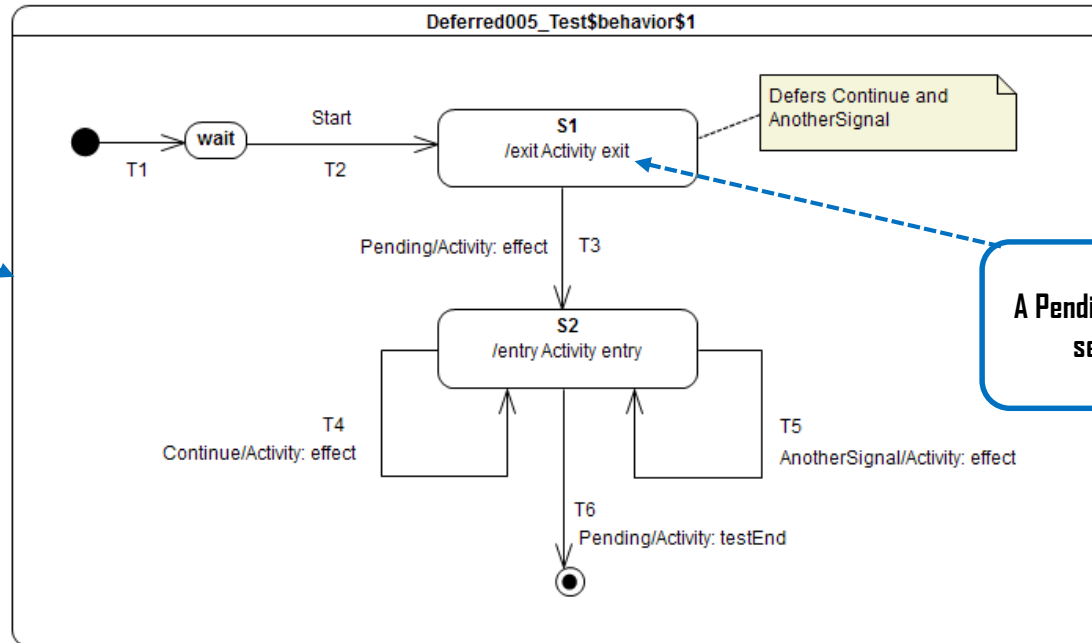
- Possibility to support alternative event dispatching strategy
 - e.g. LIFO, priority-based

Resolution

- Update to SM_ObjectActivation

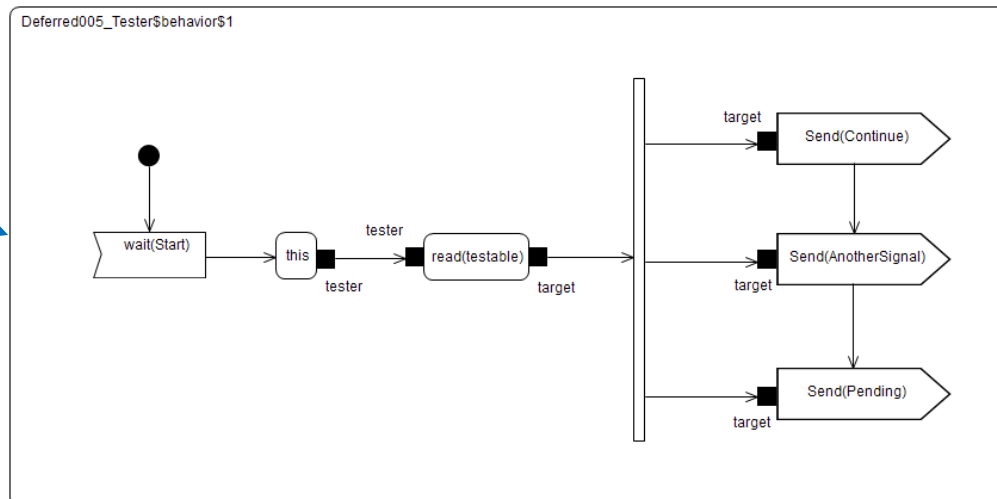


Tested state-
machine



A Pending signal event occurrence is
sent to the context object.

Stimulation
sequence



	Event pool	Deferred event	Configuration	Transitions
1	[]	[]	[] – Initial step	[T1]
2	[Start, CE(wait)]	[]	[wait]	[]
3	[Start]	[]	[wait]	[T2]
4	[Continue, CE(S1)]	[]	[S1]	[]
5	[AnotherSignal, Continue]	[]	[S1]	[]
6	[AnotherSignal]	[Continue]	[S1]	[]
7	[Pending]	[Continue, AnotherSignal]	[S1]	[T3]
8	[Pending, AnotherSignal, Continue, CE(S2)]	[]	[S2]	[]
9	[Pending, AnotherSignal, Continue]		[S2]	[T4]
10	[Pending, AnotherSignal, CE(S2)]		[S2]	[]
11	[Pending, AnotherSignal]	[]	[S2]	[T5]
12	[Pending, CE(S2)]	[]	[S2]	[]
13	[Pending]	[]	[S2]	[T6]

Deferred events are placed
back in the regular event
pool

	Event pool	Deferred event	Configuration	Transitions
1	[]	[]	[] – Initial step	[T1]
2	[Start, CE(wait)]	[]	[wait]	[]
3	[Start]	[]	[wait]	[T2]
4	[Continue, CE(S1)]	[]	[S1]	[]
5	[AnotherSignal , Continue]	[]	[S1]	[]
6	[Continue]	[AnotherSignal]	[S1]	[]
7	[Pending]	[AnotherSignal, Continue]	[S1]	[T3]
8	[Pending, AnotherSignal, Continue, CE(S2)]	[]	[S2]	[]
9	[Pending , AnotherSignal, Continue]	[]	[S2]	[T6]

Completion events
still have priority

Second Pending signal event occurrence emitted
during the execution of the S1 exit behavior is
dispatched first due to the FIFO strategy.
Therefore T6 is fired.

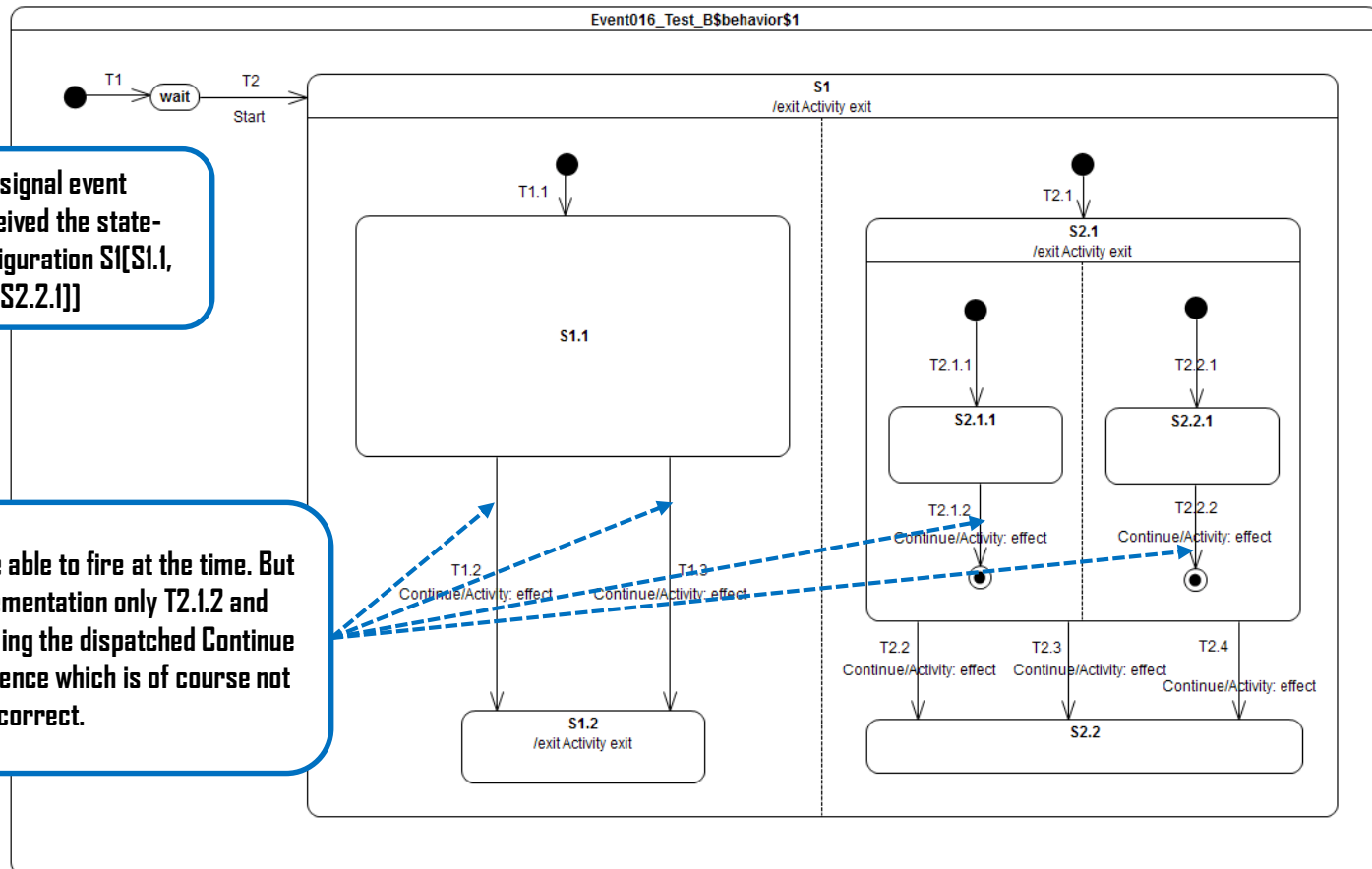
STATE MACHINE CONFIGURATION ANALYSIS

Problem

- In the presence of orthogonal regions:
 - If multiple transitions located in different regions and having different levels of nesting are able to fire using the same event occurrence, then only those with the deeper level of nesting are fired.
- Test Event 016 - B

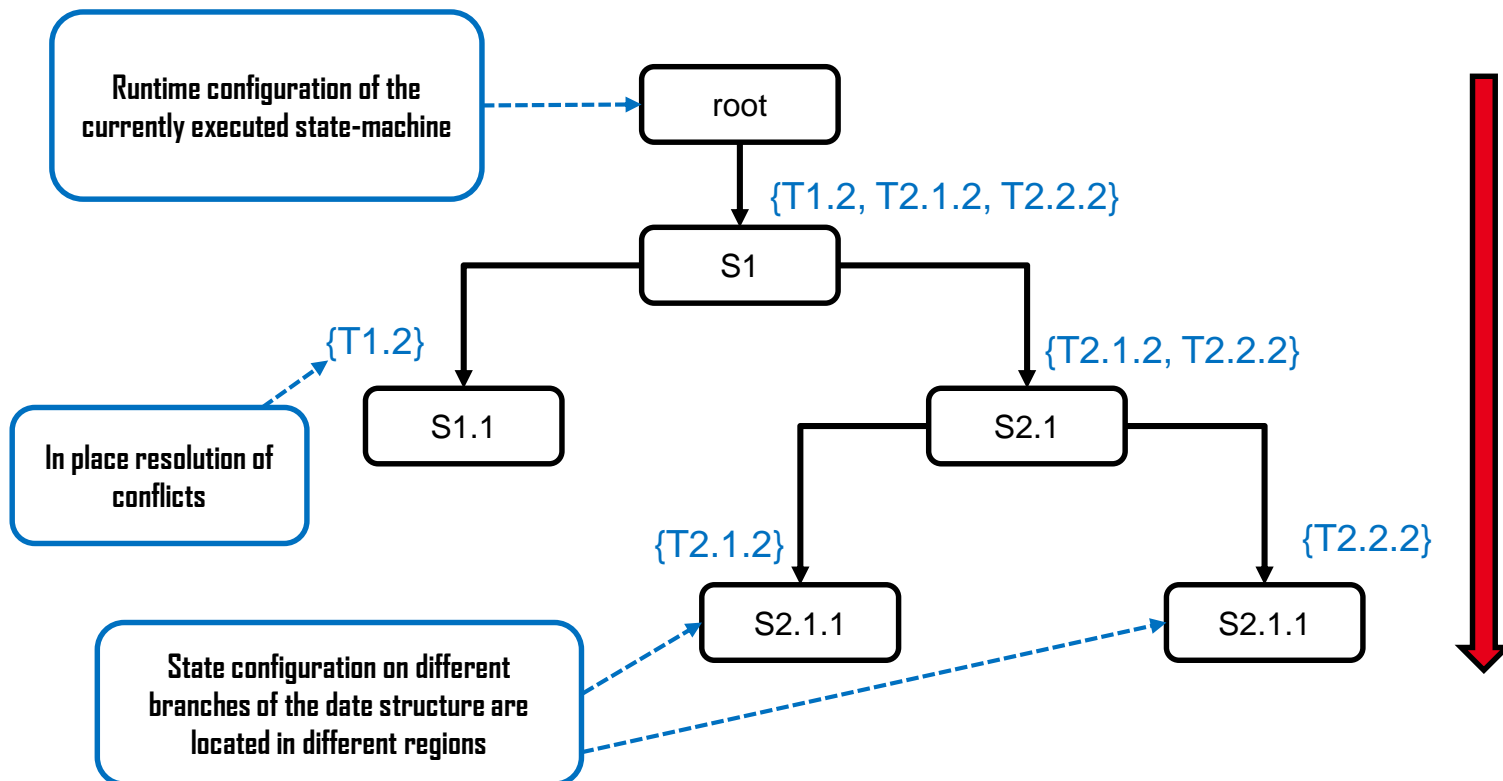
When Continue signal event occurrence is received the state-machine is the configuration SI[S1.1, S2.1[S2.1.1, S2.2.1]]

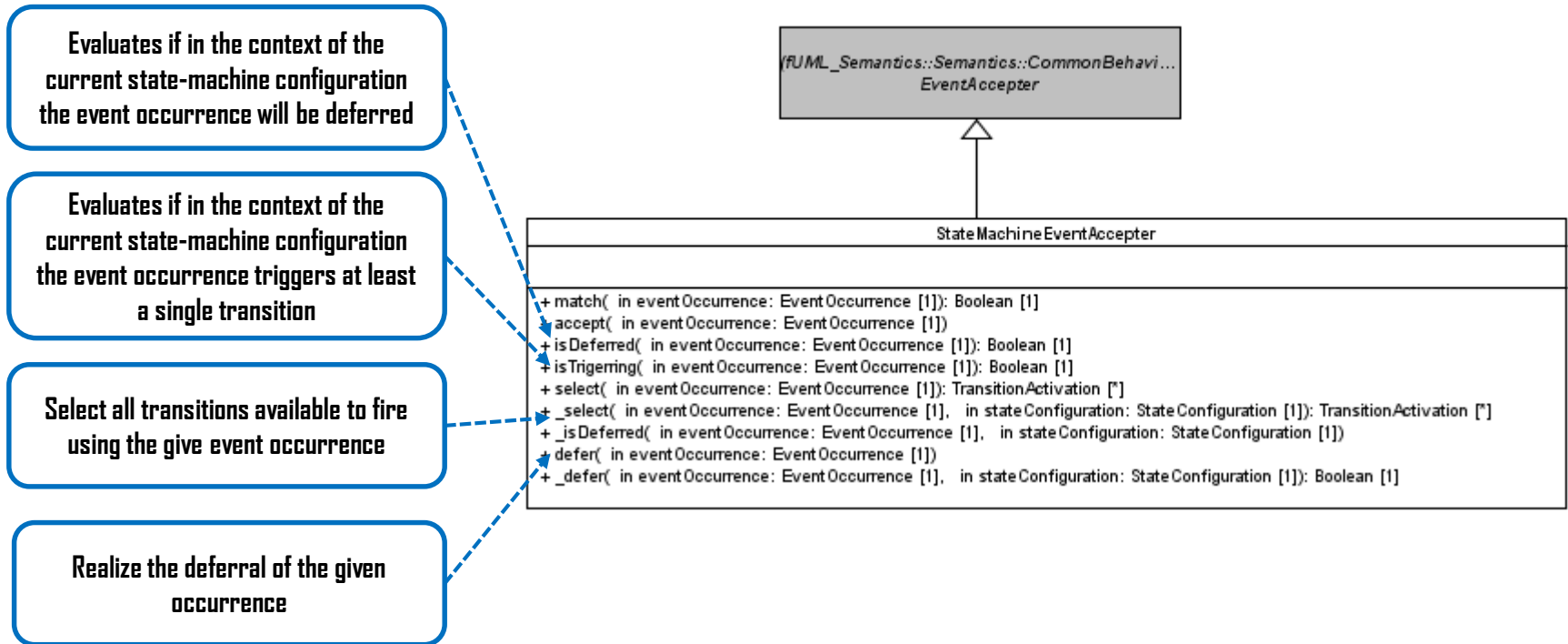
Four transitions are able to fire at the time. But in the initial implementation only T2.1.2 and T2.2.2 were fired using the dispatched Continue signal event occurrence which is of course not correct.



Resolution

- **StateMachineConfiguration**
 - Does not maintain any cartography making easier configuration analysis
- **StateMachineEventAcceptor**
 - Move to a fully recursive algorithm to analyze the configuration.
- **State machine configuration of Event016-B after 2nd RTC step**





Other changes

- **StateMachineConfiguration**
 - Attribute “cartography” was removed and all statements updating this attributes have been removed.
- **DefaultTransitionSelectionStrategy**
 - Merged into StateMachineEventAccepter

	Event pool	Deferred event	Configuration	Transitions
1	[]	[]	[] – Initial step	[T1]
2	[Start, CE(wait)]	[]	[wait]	[]
3	[Start]	[]	[wait]	[T2(T1.1, T2.1(T2.1.1, T2.2.1))]
4	[CE(S2.2.1), CE(S2.1.1), CE(S1.1)]	[]	[S1[S1.1, S2.1[S2.1.1, S2.2.1]]]	[]
5	[Continue, CE(S2.2.1), CE(S2.1.1)]	[]	[S1[S1.1, S2.1[S2.1.1, S2.2.1]]]	[]
6	[Continue, CE(S2.2.1)]	[]	[S1[S1.1, S2.1[S2.1.1, S2.2.1]]]	[]
7	[Continue]	[]	[S1[S1.1, S2.1[S2.1.1, S2.2.1]]]	[T1.3, T2.1.2, T2.2.2]
8	[Continue, CE(S1.2), CE(S2.1)]	[]	[S1[S1.2, S2.1]]	[]
9	[Continue, CE(S1.2)]	[]	[S1[S1.2, S2.1]]	[]
10	[Continue]	[]	[S1[S1.2, S2.1]]	[T2.3]
11	[Continue, CE(S2.2)]	[]	[S1[S1.2, S2.2]]	[]
12	[Continue]	[]	[S1[S1.2, S2.2]]	[T3]

Transition set firing for the same event occurrence is now correct

TEST SUITE REFINEMENT

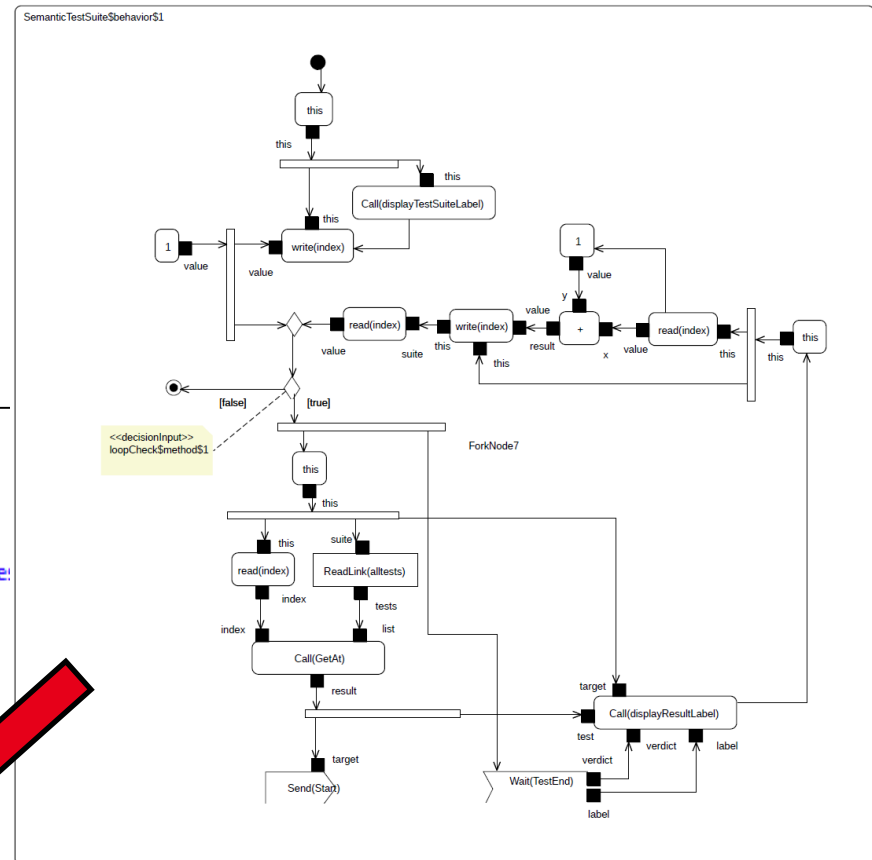
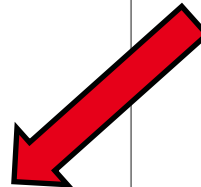
SPECIFY ALTERNATIVE EXECUTION TRACES FOR THE REQUIRED TEST CASES

The semantic test suite is now formalized using ALF which makes it a lot more readable.

1. It is notified to Start by the semantic test
2. It iteratively start the different test registered and compute the global verdict.
3. Results are displayed on the chosen output channel

```
private import Util::Protocol::Messages::TestEnd;
private import Util::Protocol::Messages::Start;

activity 'SemanticTestSuite$behavior$1' () {
  accept(Start);
  WriteLine("\n[TEST SUITE (" + IntegerFunctions::ToString(this.tests->size()) + " tests)");
  // Execute all semantic tests registered in that test suite
  Integer failures = 0;
  for(i in 1..this.tests->size()){
    // Test gets the authorization to start
    this.tests->at(i).Start();
    // Test suite waits for the results
    accept(testResult : TestEnd){
      if(testResult.verdict == false){
        failures++;
      }
    }
  }
  // There is at least one failure then the test suite is considered as failed
  if(failures > 0){
    WriteLine("\n[TEST SUITE] - " + this.name + " FAILURE (" + IntegerFunctions::ToString(failures) + " / " + IntegerFunctions::ToString(this.tests->size()) + " failed)\n");
  }
}
```



```
private import Util::Protocol::Messages::Start;
private import Util::Protocol::Messages::End;
```

```
activity 'AbstractSemanticTest$behavior$1' () {
```

```
// Wait for a start signal
```

```
accept(Start);
```

```
// Tester and target are created and started
```

```
target = this.getTestTarget();
```

```
tester = this.getTestComponent();
```

```
// Create link connection between the two
```

```
target.tester = tester;
```

```
tester.testable = target;
```

```
this.target = target;
```

```
this.tester = tester;
```

```
// Both are started
```

```
target.Start();
```

```
tester.Start();
```

```
// Wait for the arrival of the result emitted by the target
```

```
accept(executionResult : End);
```

```
this.pass = this.matches(executionResult.trace);
```

```
// Result analysis
```

```
if(!this.pass){
```

```
WriteLine("[TEST] " + this.name + " ** FAIL ** - {" + executionResult.trace + "} does not match any of the follow
```

```
for(i in 1..this.expectedTraces->size()){
```

```
WriteLine("-----> [" + IntegerFunctions::ToString(i) + "] - " + this.expectedTraces->at(i));
```

```
}
```

```
}else{
```

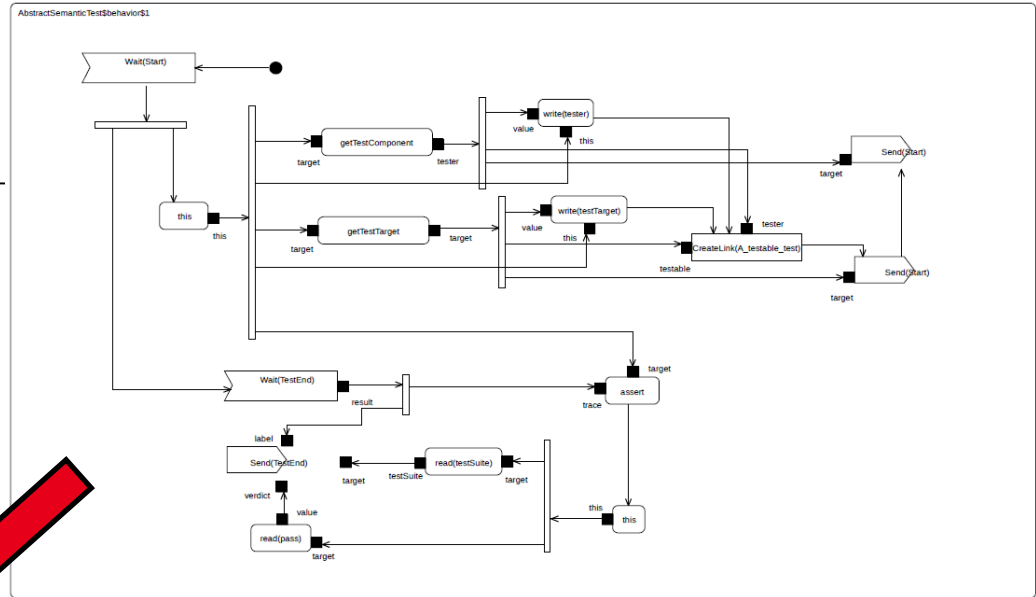
```
WriteLine("[TEST] " + this.name + " - PASS -");
```

```
}
```

```
// Provides the result back to the test suite governing this semantic test
```

```
this.testSuite.TestEnd(this.pass);
```

```
}
```



Allow a semantic test to specify a set of expected traces.

```
abstract active class SemanticTest {
```

```
public pass: Boolean;
```

```
public name: String;
```

```
public expectedTraces: String[1..*];
```

```
public abstract getTestComponent(): Tester;
```

```
public abstract getTestTarget(): Target;
```

```
@Create
```

```
public SemanticTest();
```

```
@Destroy
```

```
public destroy();
```

```
public matches(in trace: String): Boolean;
```

```
public register(in possibleTrace: String);
```

```
public receive Util::Protocol::Messages::End;
```

```
public receive Util::Protocol::Messages::Start;
```

```
} do 'AbstractSemanticTest$behavior$1'
```

Test suite

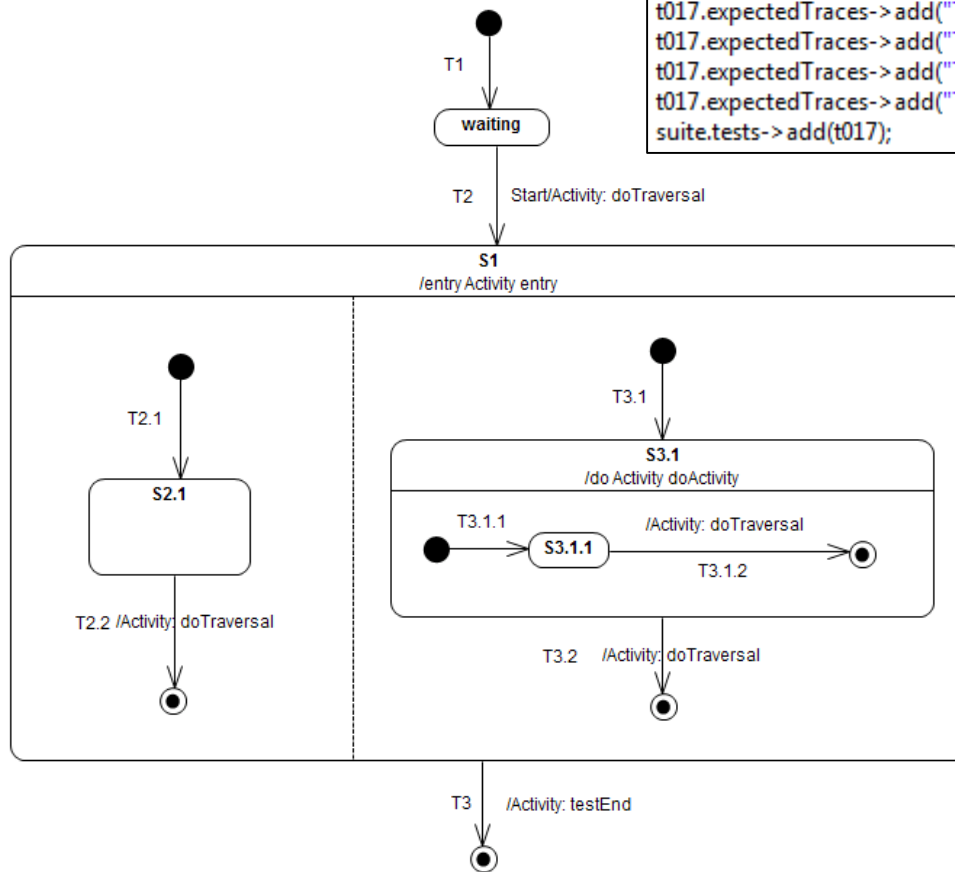
- **Transition**
 - Transition 017 – (test simplified)
 - Transition 019
- **Event**
 - Event 016
- **Entering**
 - Entering 011
 - Entering 010
- **Exiting**
 - Exiting 001
 - Exiting 003
- **Exit**
 - Exit 002
- **Entry**
 - Entry 002 – A
 - Entry 002 – B
- **Standalone**
 - Standalone 001

Test suite

- Fork
 - Fork 001
 - Fork 002
- Join
 - Join 001
 - Join 002
- Terminate
 - Terminate 001
 - Terminate 002

Set of all valid traces that can be produced with respect to UML semantics

```
/*Transition017*/
t017 = new 'Transition017_SemanticTest';
t017.name = "Transition 017";
t017.expectedTraces->add("T2(effect)::S1(entry)::T2.2(effect)::S3.1(doActivity)::T3.1.2(effect)::T3.2(effect)");
t017.expectedTraces->add("T2(effect)::S1(entry)::T2.2(effect)::T3.1.2(effect)::S3.1(doActivity)::T3.2(effect)");
t017.expectedTraces->add("T2(effect)::S1(entry)::T2.2(effect)::T3.2(effect)::S3.1(doActivity)::T3.1.2(effect)");
t017.expectedTraces->add("T2(effect)::S1(entry)::T2.2(effect)::T3.2(effect)::T3.1.2(effect)::S3.1(doActivity)");
t017.expectedTraces->add("T2(effect)::S1(entry)::S3.1(doActivity)::T2.2(effect)::T3.1.2(effect)::T3.2(effect)");
t017.expectedTraces->add("T2(effect)::S1(entry)::S3.1(doActivity)::T3.1.2(effect)::T2.2(effect)::T3.2(effect)");
t017.expectedTraces->add("T2(effect)::S1(entry)::T3.1.2(effect)::T2.2(effect)::S3.1(doActivity)::T3.2(effect)");
t017.expectedTraces->add("T2(effect)::S1(entry)::T3.1.2(effect)::S3.1(doActivity)::T2.2(effect)::T3.2(effect)");
suite.tests->add(t017);
```



T3.1.2 can fire first if S3.1.1 registered its completion first.

The doActivity invoked from S3.1 can complete before the end of the second RTC step.

T2.2 can fire first if S2.1 registers its completion event first.

BUML CONFORMANCE

CHANGES REQUIRED IN THE IMPLEMENTATION TO CONFORM TO BUML

Goal



- Make sure our execution model is implemented using the java textual surface notation for activities.
 - The execution model is an fUML model which can be executed using fUML semantics.

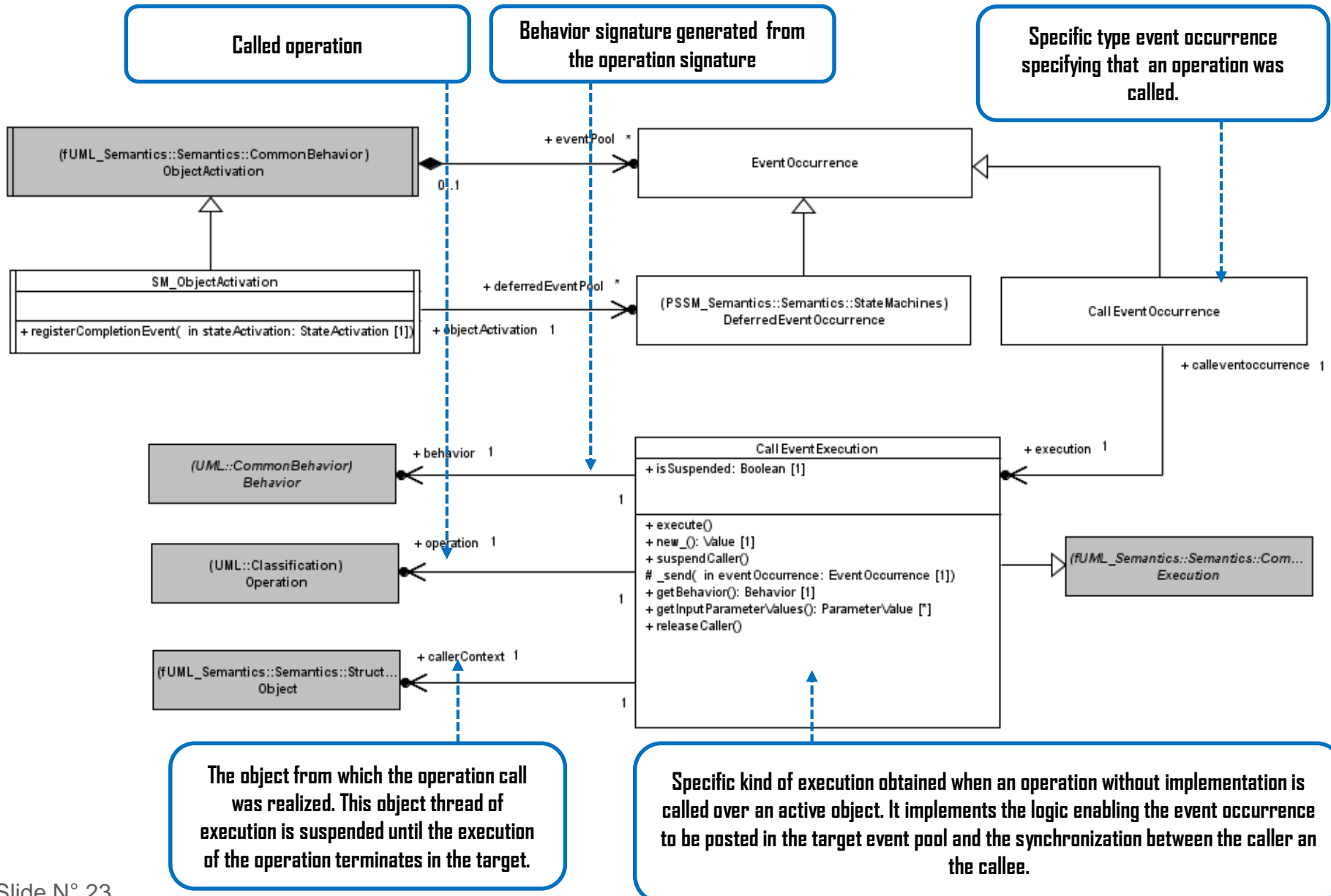
Implementation analysis

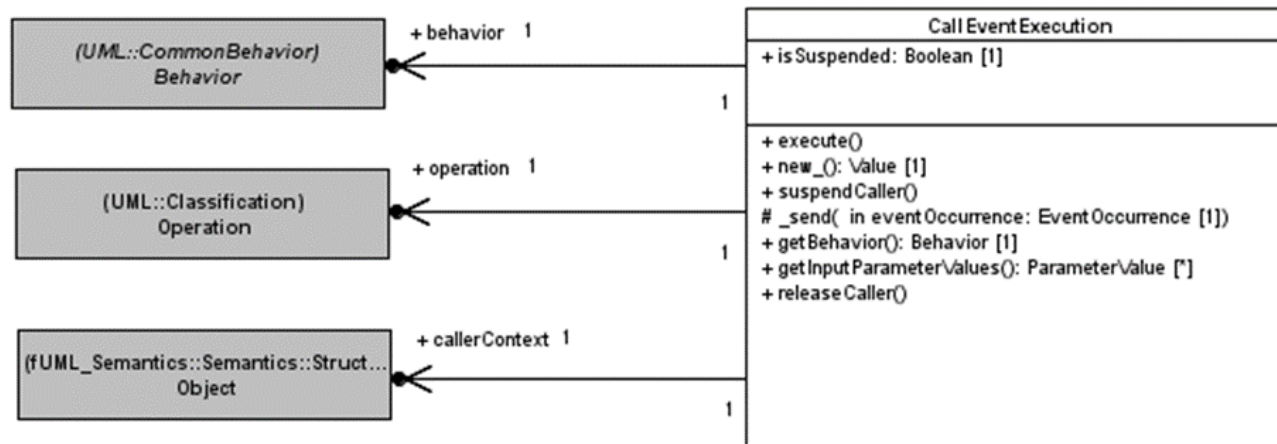
- Excel file recording most (all) of the changes that need to apply to have a implementation conforming to bUML.
- Typical changes
 - Usage of `for(<var> : <collections>)` instead of for loop using an index (see clause A.4.12 of fUML 1.2.1)
 - Usage of iterative for loop (see clause A.4.12 of fUML 1.2.1) where a parallel loop (using iterator) must be used (see clause A.5.6 of fUML 1.2.1).
 - Usage of while loop with an index starting from 0 instead of 1.
 - Usage of while loop with postfix increment to the index. This shall be replaced by the pattern `<index> = <index> + 1`.
 - Usage of constructors with parameters (see clause A.5.5)

CALL EVENT SEMANTICS

Precise semantics

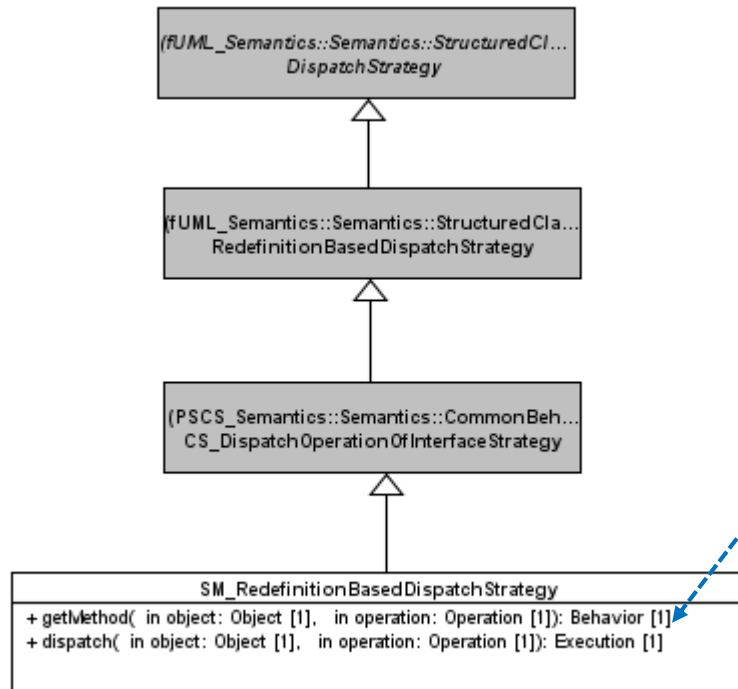
- Transition (except for redefinition), including completion transitions (with no triggers) and transitions with triggers for the following kinds of events:
 - CallEvent (for *synchronous* calls) 
 - SignalEvent 
- Agenda : April 2016





Other changes

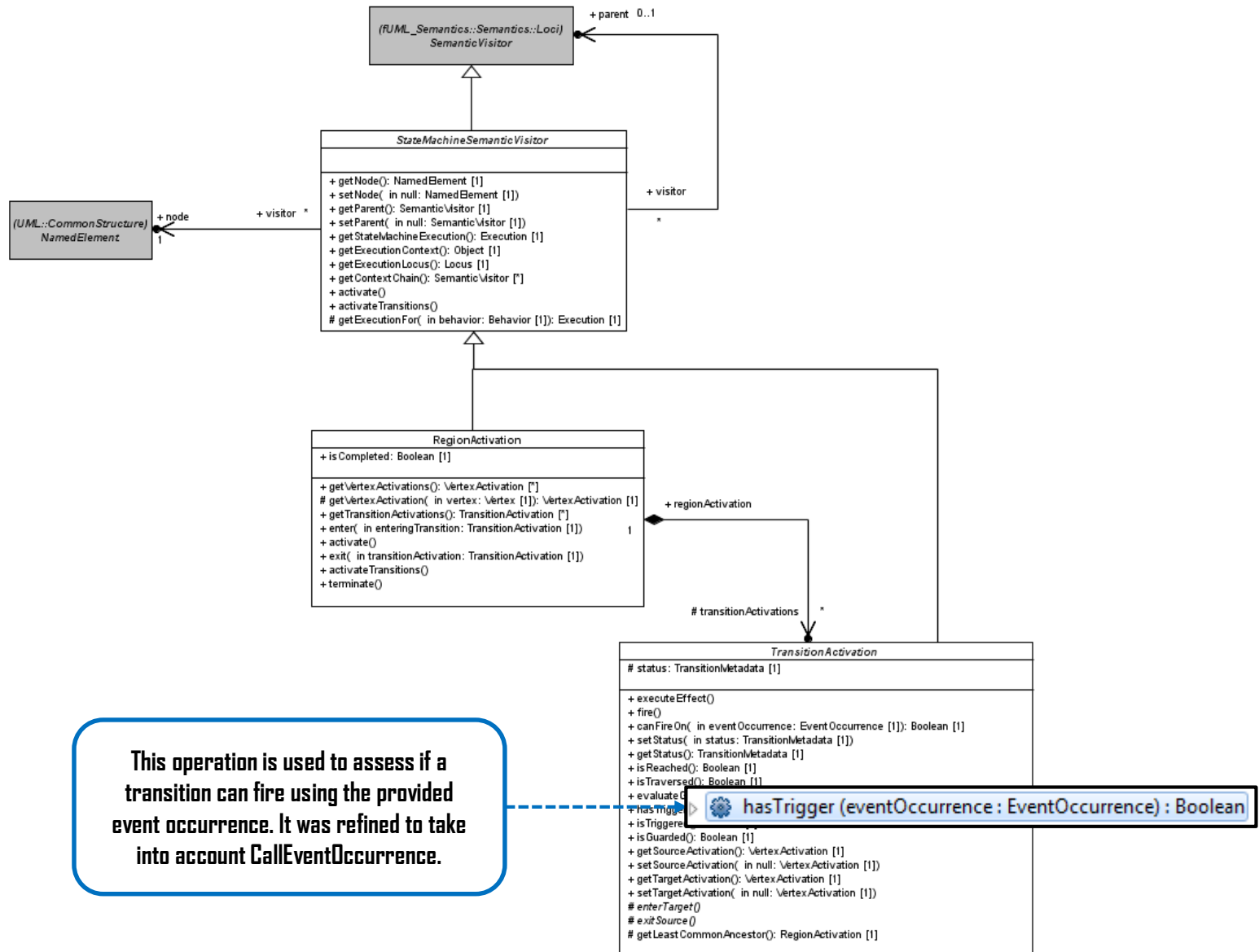
- `execute()`
 - Send the call event occurrence to the target object
 - Suspend the caller until the target notified the end of the call
- `suspendCaller()`
 - The object from which the event was sent is suspended thanks to a spin loop (needs to be improve – usage of mutex)
- `releaseCaller()`
 - The object from which the event was sent can resume its execution



This operation preserves fUML semantics. It returns the implementation of the operation given as a parameter. The only change is that if no implementation could be found then no exception is generated. Null is returned instead

SM_RedefinitionBasedDispatchStrategy

- `dispatch(...): Execution`
 - If an implementation (i.e. a behavior) could be found then the appropriate execution is instantiated.
 - If no implementation could be found then a `CallEventExecution` is created.



`hasTrigger(in EventOccurrence) : Boolean`

- Does it exist a trigger for this transition which matches the provided event occurrence.
- Matching rules:
 - If the trigger is for a Signal then the provided event occurrence must be a `SignalEventOccurrence` referencing a `SignalInstance` whose type is the signal referenced by the trigger.
 - If the trigger is for a Operation call then the provided event occurrence must be a `CallEventOccurrence` referencing an operation which must be the operation referenced by the trigger.
 - If the trigger specifies the `onPort` property then the provided event occurrence can only be a `SignalEventOccurrence`. This limitation is introduced by the fact that PSSM does not provide a `CS_EventOccurrence` related to a particular `CS_InteractionPoint`.

A. Problem

- At some point of the execution the caller (i.e. the object from which the call event was emitted) needs to be resumed.

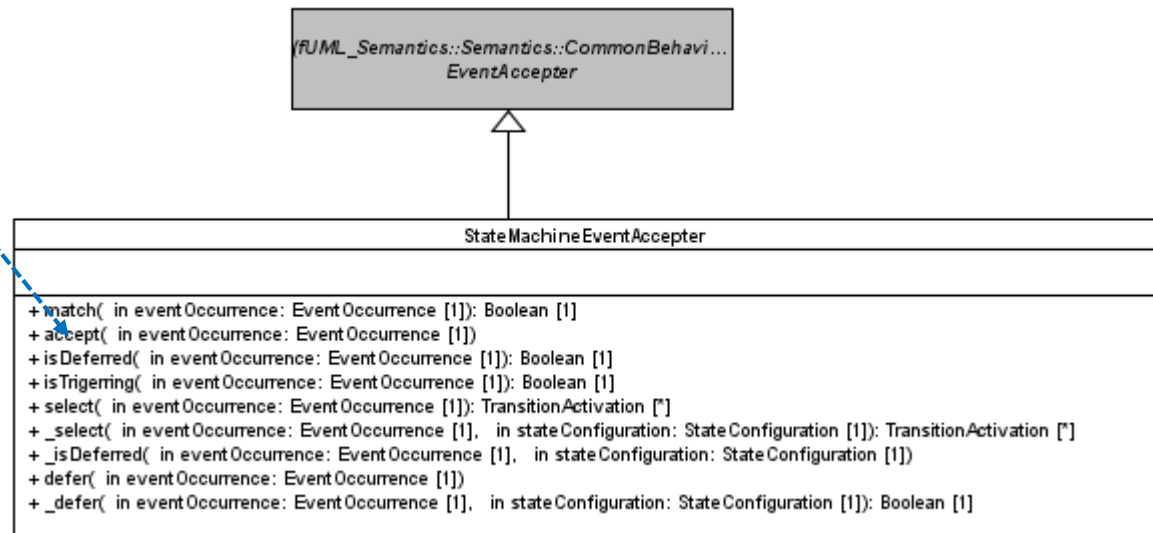
B. Proposal

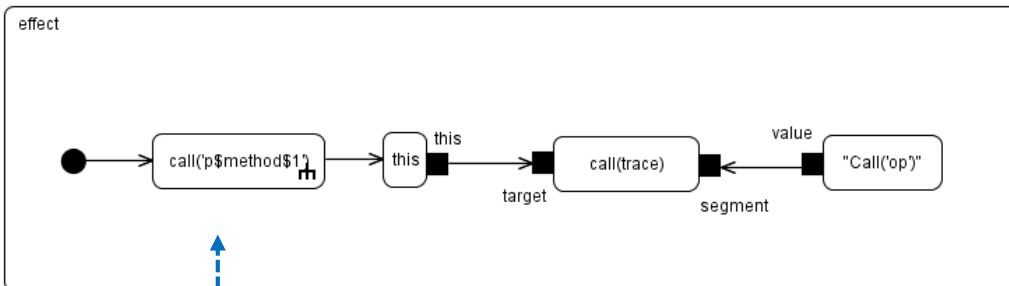
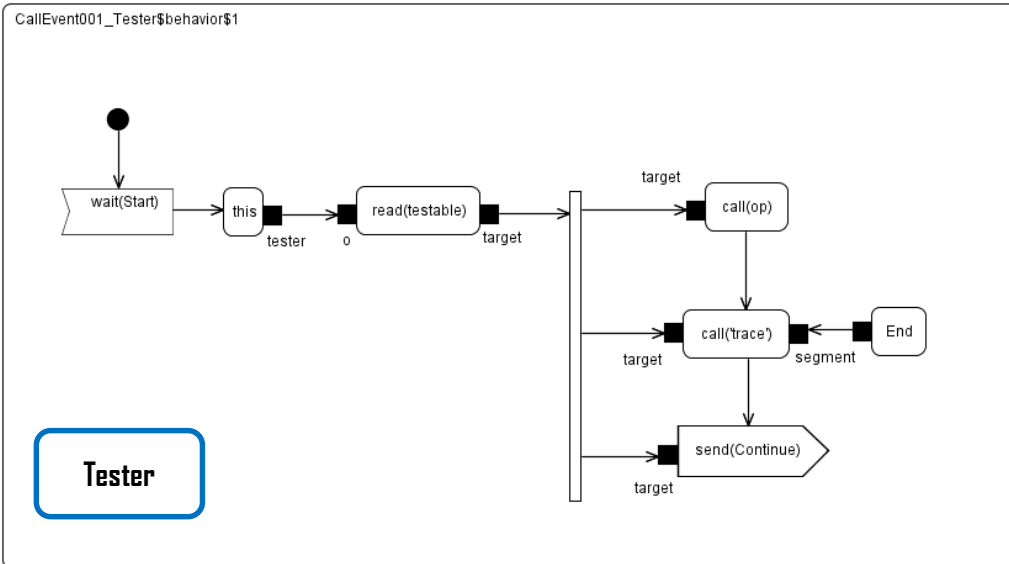
- The caller must be resumed when the RTC step in which the `CallEventOccurrence` is dispatched terminates.

C. Implementation

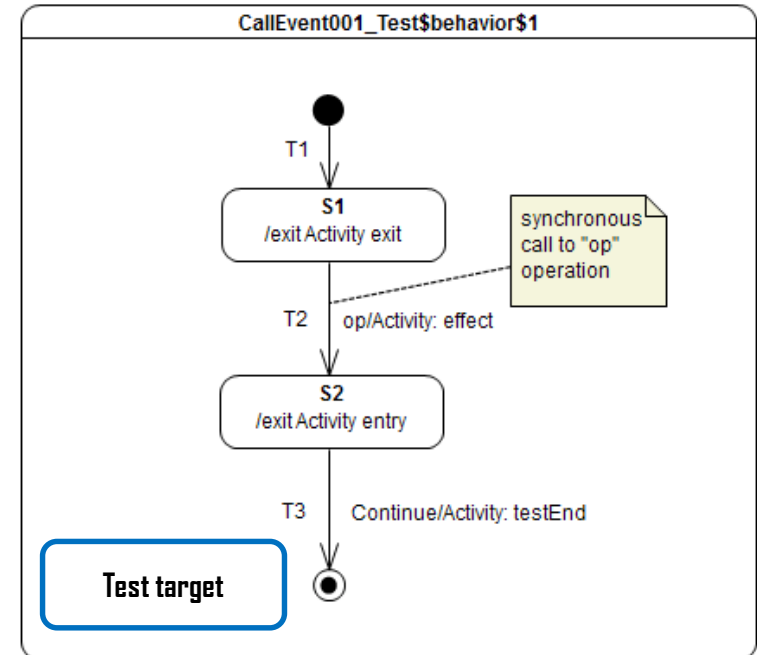
- Update `accept` operation of the state-machine event accepter

After the concurrent firing of the transitions selected for this step, if the dispatched event occurrence is a `CallEventOccurrence` then the `CallEventExecution` referenced by this event occurrence is used to notify the caller that it can resume its execution.





Implementation of the effect of transition T2. It call the behavior "p\$method\$1" which implements the operation behavior.



```
/*Test call event 001 */
ce001 = new 'CallEvent001_SemanticTest';
ce001.name = "CallEvent 001";
ce001.expectedTraces->add("S1(exit)::Call(op)::End::S2(entry)");
suite.tests->add(ce001);
```

A dashed blue arrow points from this code block to the 'Expected execution trace' box.

Expected execution trace.

	Event pool	Trace evolution	Configuration	Transitions
1	[]	[]	[] – Initial step	[T1]
2	[CE(S1)]	[]	[S1]	[]
3	[Call(op)]	[S1(exit)::call(op)]	[S1]	[T2]
4	[CE(S2)]	[S1(exit)::call(op)::End]	[S2]	[]
5	[Continue]	[S1(exit)::call(op)::End::S2(entry)]	[S2]	[T3]

EVENT DATA PASSING

Precise semantics

- Proposals shall define how data associated with event occurrences shall be accessed by transition guards and passed to transition effect behaviors and state behaviors during the process of event dispatching and transition triggering. ❌
- Agenda: May 2016

Semantics

– Signal Event Occurrence

- If the behavior has no parameter, the signal event occurrence is not passed to this behavior.
- If the behavior has one parameter, then the signal instance embedded by the signal event occurrence is passed to the behavior

– Call Event Occurrence

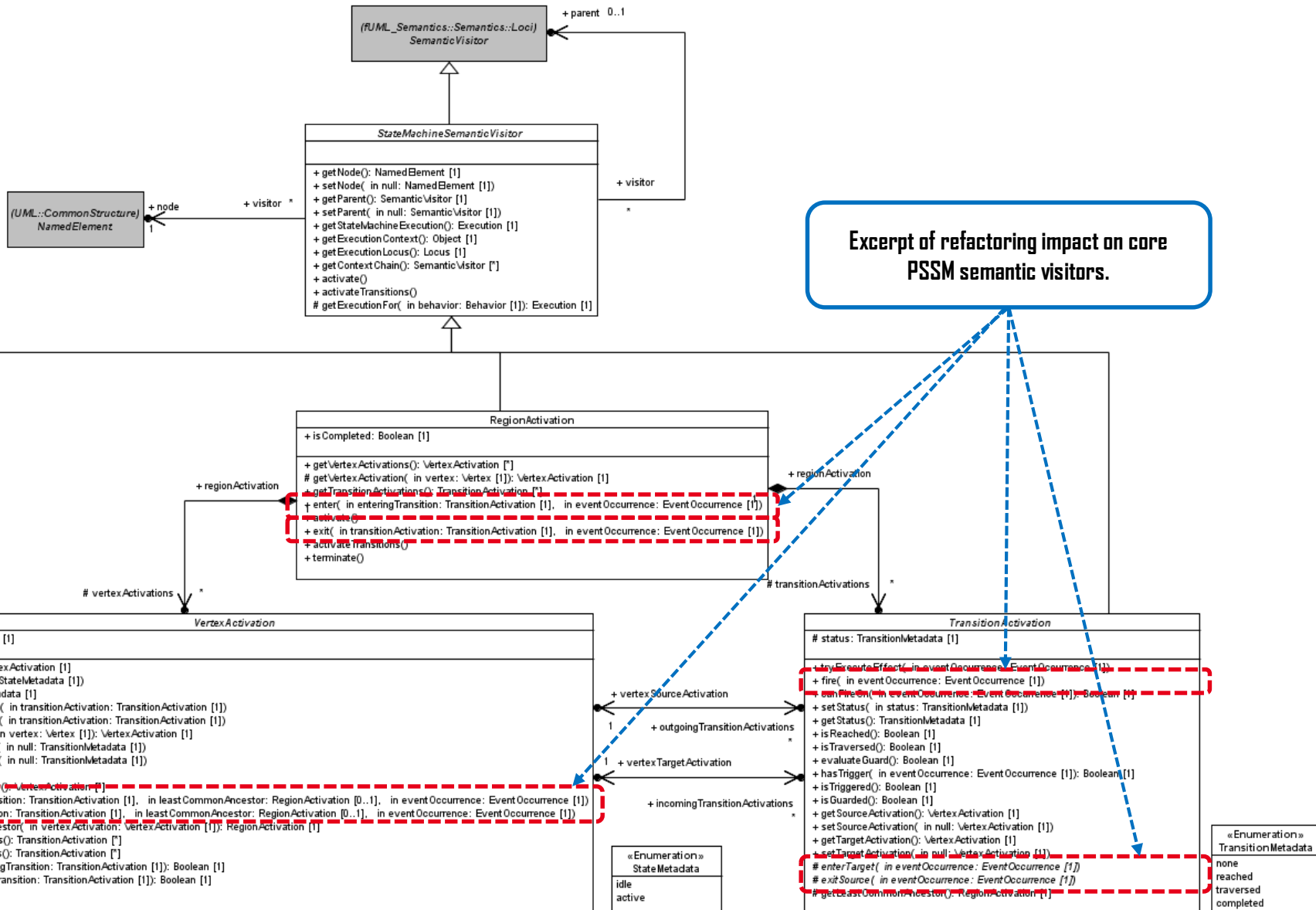
- If a Behavior has parameters, then the values of the input Parameters of for the call are passed into the Behavior Execution as the values of the corresponding input Parameters of the Behavior.
- If an effect, entry or exit Behavior is not just *input-conforming*, then the values of its output Parameters are passed out of its Behavior Execution on its completion as *potential* values for the output Parameters of the called Operation.

Refactoring

- **Proposal**
 - Enable the dispatched event occurrence to be accessible by the different visitors involved in a RTC step.

Impact on the semantic model

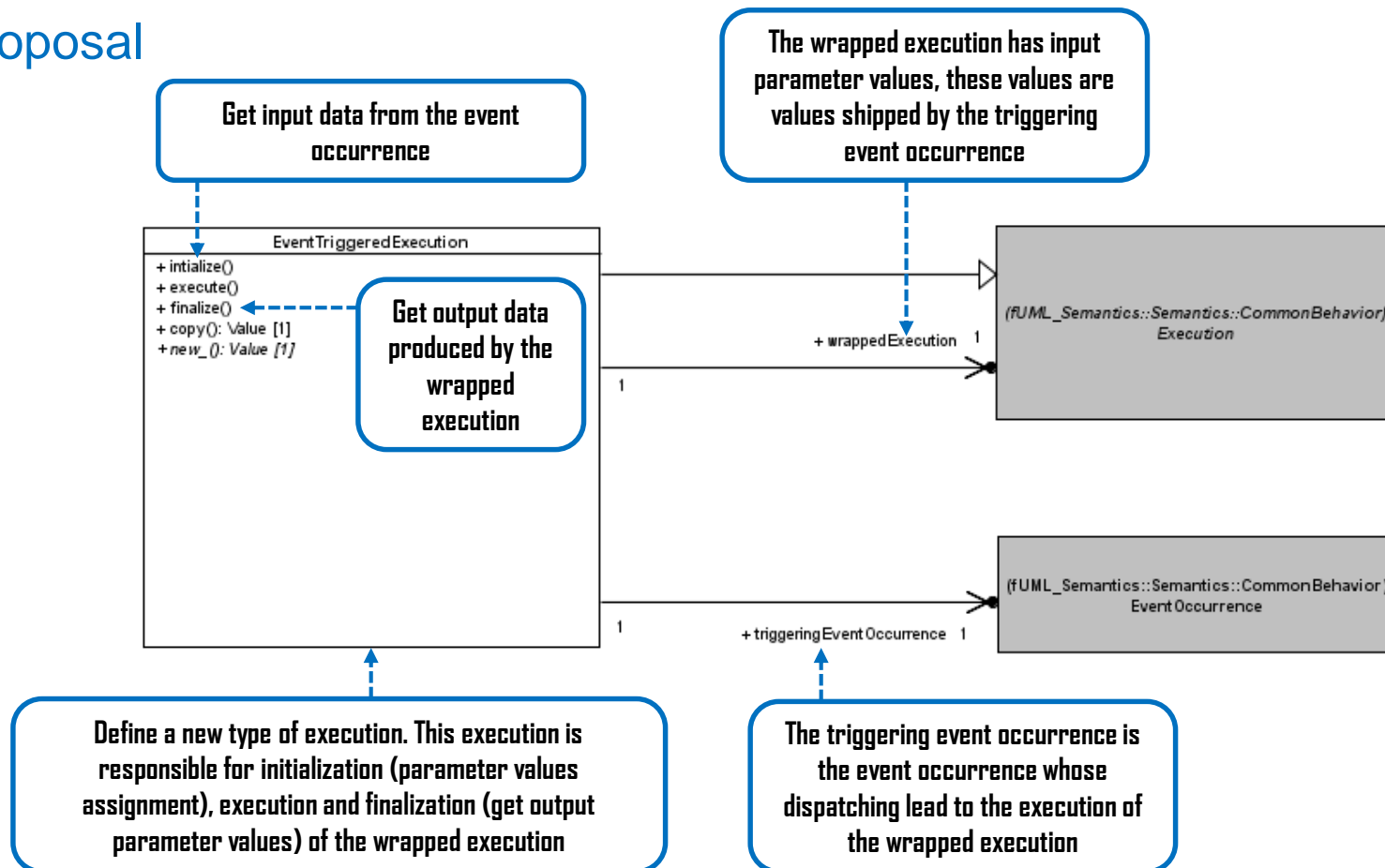
- **VertexActivation**
 - enter(in TransitionActivation, in RegionActivation, in EventOccurrence)
 - exit(in TransitionActivation, in RegionActivation, in EventOccurrence)
 - Applies to all specializations of VertexActivation and recursively
- **StateActivation**
 - tryExecuteEntry(in eventOccurrence)
 - tryInvokeDoActivity(in eventOccurrence)
 - tryExecuteExit(in eventOccurrence)
- **TransitionActivation**
 - fire(in EventOccurrence)
 - tryExecuteEffect(in eventOccurrence)
 - enterTarget(in eventOccurrence)
 - exitSource(in eventOccurrence)
- **RegionActivation**
 - enter(in TransitionActivation, in eventOccurrence)
 - exit(in TransitionActivation, in eventOccurrence)

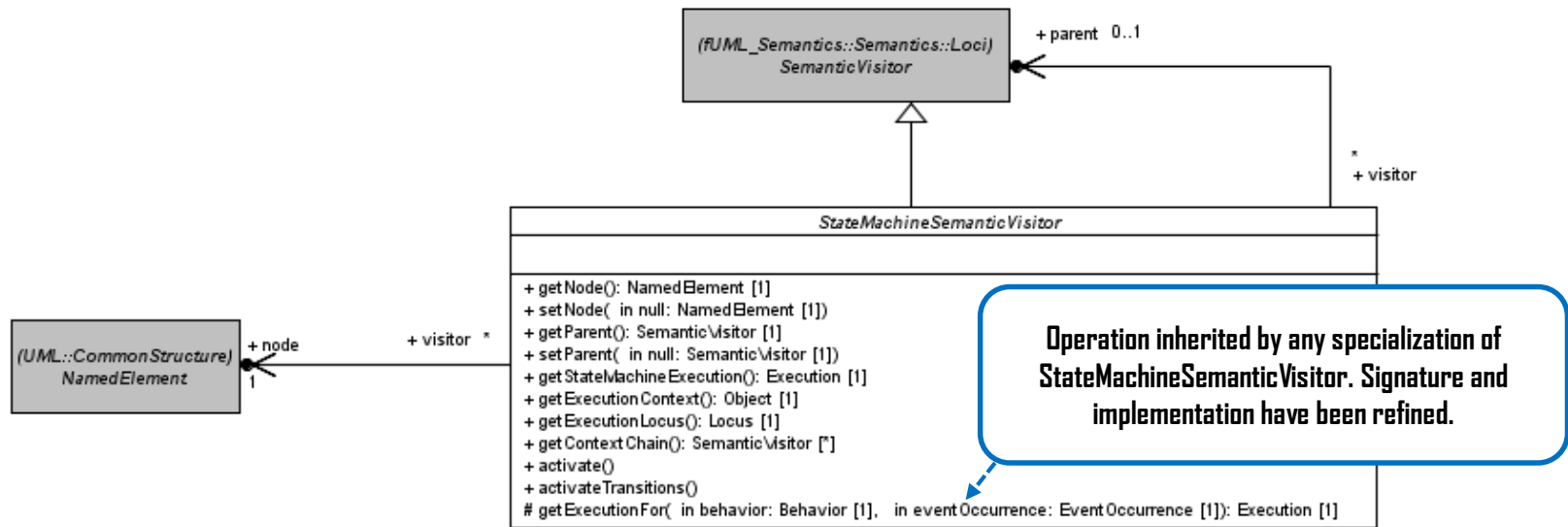


Objective

- Exploit data available in event occurrence and limit the impact of this feature implementation over the semantic model.

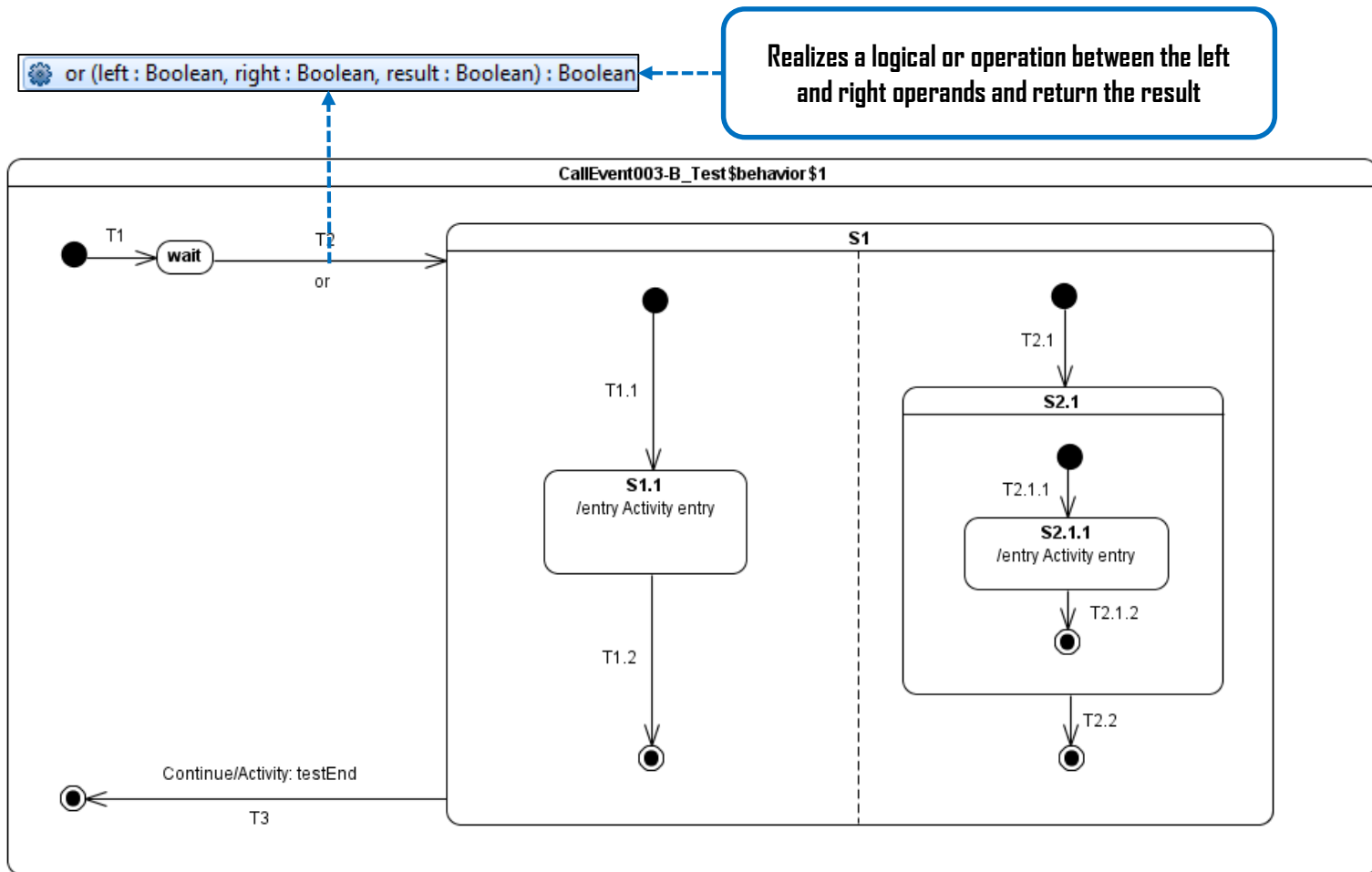
Proposal



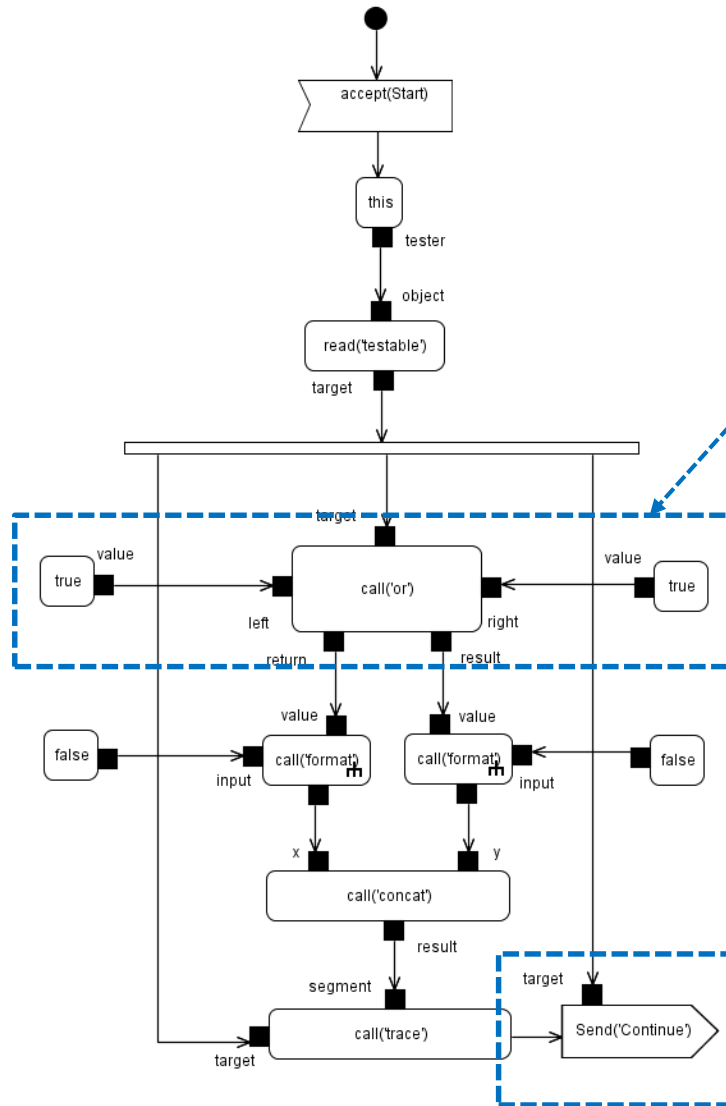


StateMachineSemanticVisitor

- `getExecutionFor(in Behavior, in EventOccurrence): Execution`
 - If there is no event occurrence specified (i.e. it is null) then a regular execution (i.e. not an `EventTriggeredExecution`) is obtained.
 - If there is an event occurrence specified the an `EventTriggeredExecution` is obtained. This execution wraps the regular execution.

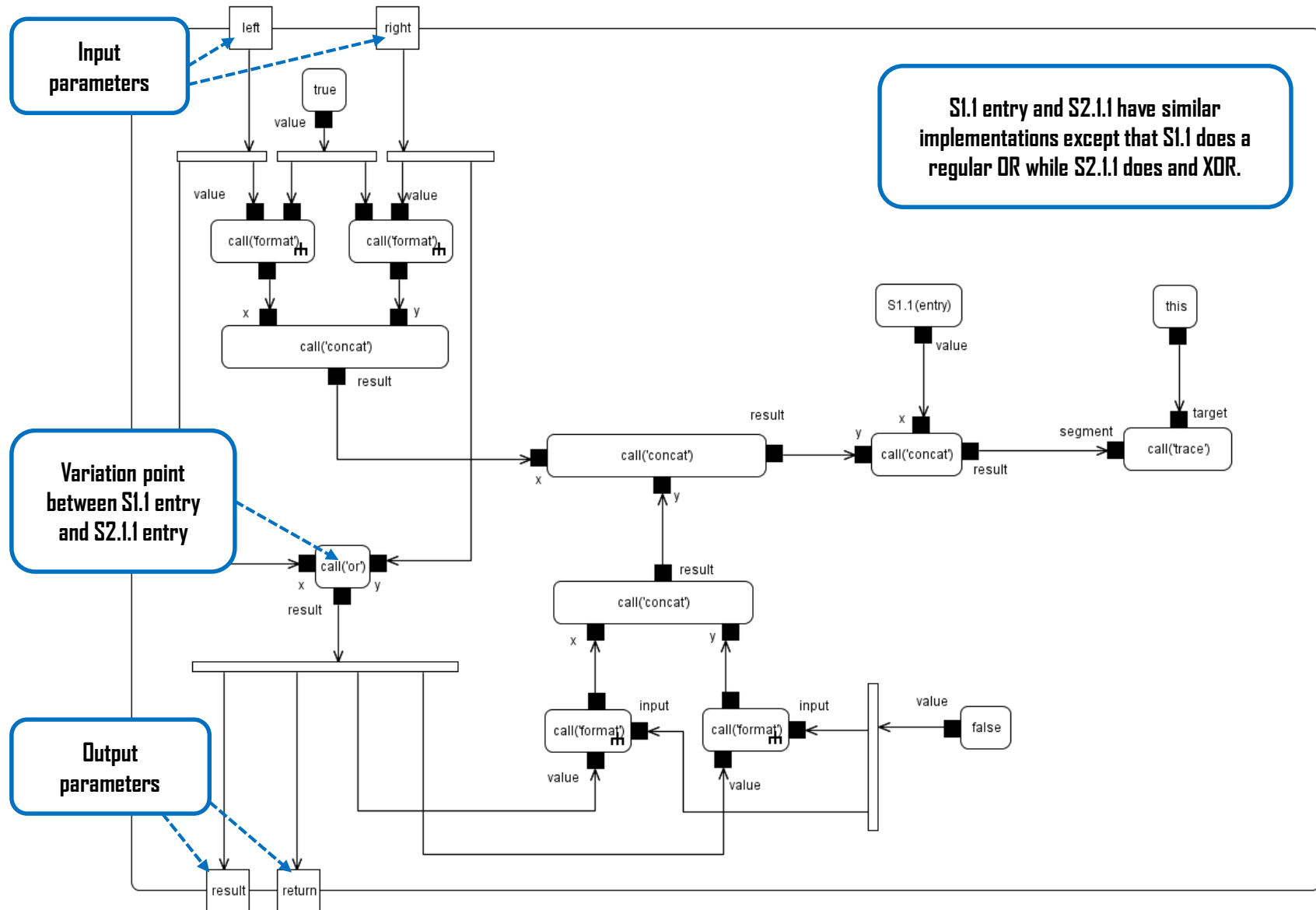


CallEvent003-B_Tester\$behavior\$1



Operation call that will trigger the transition T2. Both left and right operands will have the value true.

Signal sending that will trigger the transition T3.



	Event pool	Deferred event	Configuration	Transitions
1	[]	[]	[] – Initial step	[T1]
2	[Call(or), CE(wait)]	[]	[wait]	[]
3	[Call(or)]	[]	[wait]	[T2(T1.1, T2.1(T2.1.1))]
4	[CE(S2.1.1), CE(S1.1)]	[]	[S1[S1.1, S2.1[S2.1.1]]]	[T1.2]
5	[CE(S2.1.1)]	[]	[S1[S2.1[S2.1.1]]]	[T2.1.2]
6	[CE(S2.1)]	[]	[S1[S2.1]]	[T2.2]
7	[Continue, CE(S1)]	[]	[S1]	[]
8	[Continue]	[]	[S1]	[T3]

This could happen in a different order since there is concurrency. Indeed CE(S2.1.1) may have arrived first at the repository

First execution trace: CE(S1.1)
is dispatched first

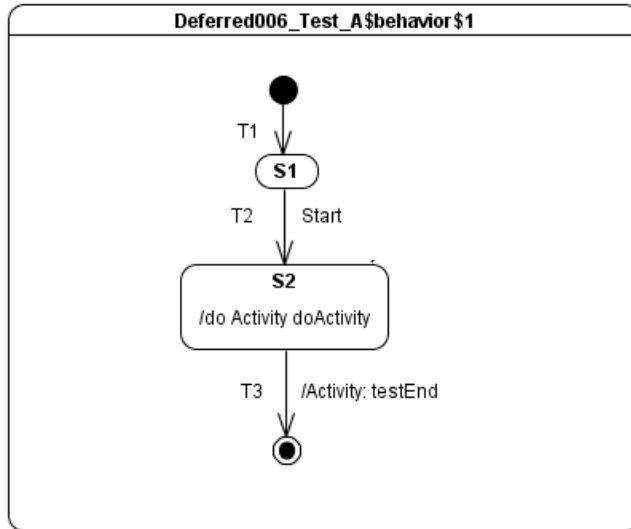
```
/*Test call event 003 - B */
ce003b = new 'CallEvent003-B_SemanticTest'();
ce003b.name = "CallEvent 003 - B";
ce003b.expectedTraces->add("S1.1(entry)[in=true][in=true][out=true][out=true]::S2.1.1(entry)[in=true][in=true][out=false][out=false]::[out=false][out=false]");
ce003b.expectedTraces->add("S2.1.1(entry)[in=true][in=true][out=false][out=false]::S1.1(entry)[in=true][in=true][out=true][out=true]::[out=true][out=true]");
suite.tests->add(ce003b);
```

Second execution trace:
CE(S2.1.1) is dispatched first

DO ACTIVITY SEMANTICS

Problem

- Ensure that a *doActivity* invoked from a state is able to consume an event occurrence sent from an external object.



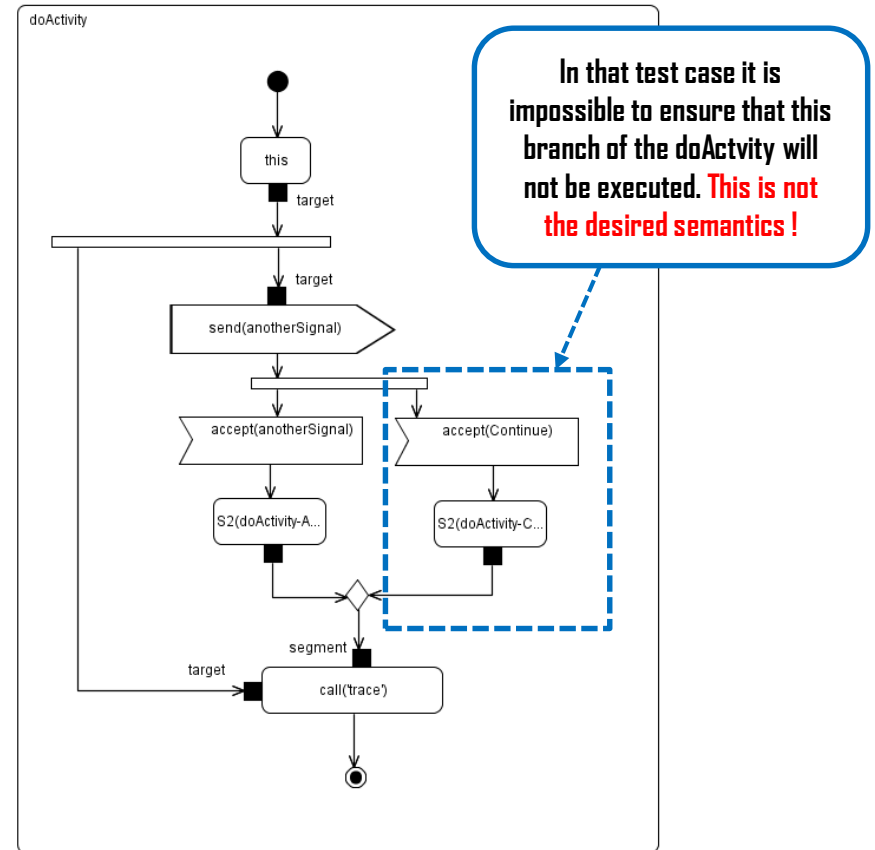
```

private import Util::Protocol::Messages::Start;
private import Util::Protocol::Messages::Continue;
private import Util::Architecture::A_testable_tester;

activity 'Behavior006_Test_A$behavior$1'() {
    accept(Start);
    this.testable.Continue();
}
    
```

```

/*Deferred006 A */
d006 = new 'Deferred006_SemanticTest_A'();
d006.name = "Deferred 006 A";
d006.expectedTraces->add("S2(doActivity-AnotherSignal)");
suite.tests->add(d006);
    
```



	Event pool	Deferred events	Configuration	Transitions
1	[]	[]	[] – Initial step	[T1]
2	[Start, CE(S1)]	[]	[S1]	[]
3	[Start]	[]	[S1]	[T2]
4	[AnotherSignal]	[]	[S2]	[]
5	[Continue]	[]	[S2]	[]

	Event pool	Wait points	Executed nodes
1	[]	[] – Initial step	[Initial, this, fork, send(AnotherSignal) – Fork – accept(AnotherSignal) – accept(Continue)]
2	[Continue]	[accept(AnotherSignal) – accept(Continue)]	S1(doActivityContinue) – MergeNode – call('trace') - FinalNode

- **Case 1:**
 - *AnotherSignal* is lost. *Continue* triggers *accept(Continue)*.
- **Case 2:**
 - *AnotherSignal* is accepted, it triggers *accept(AnotherSignal)*.
- **Case 3:**
 - Both *AnotherSignal* and *Continue* are lost. The doActivity waits forever.

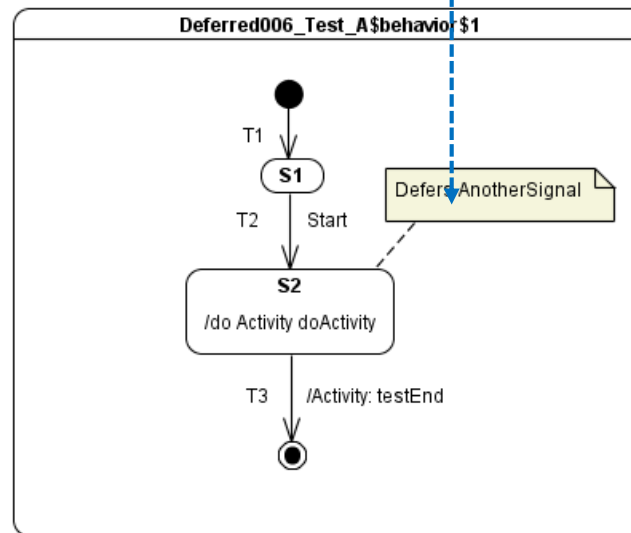
Resolution

- Rule 1:
 - To avoid a state-machine to consume an event in a certain state then this state must have a deferred trigger for that event type.
- Rule 2:
 - A state-machine is not allowed to defer an event (even if specified) if this event can be accepted by an acceptor registered by a *doActivity*.
- Rule 3:
 - A doActivity is allowed to accept an event deferred by the state-machine.

Impact on the semantic model

- StateMachineEventAcceptor
 - Rule 2 - `isDeferred(in Eventoccurrence) : Boolean`
- DoActivityContextObject
 - Rule 3 – `register(in EventAcceptor)`. The event pool is checked, if not matching deferred event could be found then the acceptor is register in the context object activation. Otherwise, a new RTC step is scheduled for the doActivity.

As specified in **Rule 1**, the AnotherSignal is specified as being deferred in S2 (is the state on which the signal might be lost if not deferred).



	Event pool	Deferred events	Configuration	Transitions
1	[]	[]	[] – Initial step	[T1]
2	[Start, CE(S1)]	[]	[S1]	[]
3	[Start]	[]	[S1]	[T2]
4	[AnotherSignal]	[]	[S2]	[]
5	[Continue]	[AnotherSignal]	[S2]	[]

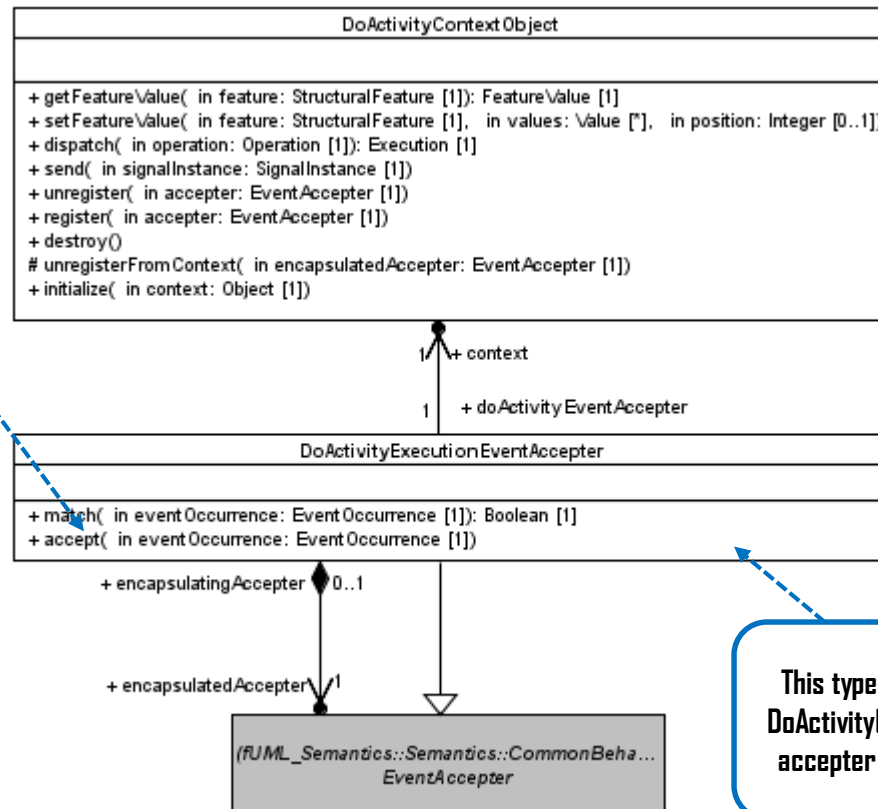
Accepted from the
deferred event pool

doActivity is invoked
from RTC step N°4

	Event pool	Wait points	Executed nodes
1	[]	[] – Initial step	[Initial this, fork, send(AnotherSignal) – Fork – accept(AnotherSignal) – accept(Continue)]
2	[AnotherSignal]	[accept(AnotherSignal) – accept(Continue)]	S1(doActivityAnotherSignal) – MergeNode – call('trace') - FinalNode

- **Case 1:**
 - *AnotherSignal* is accepted from the deferred event pool.
- **Case 2:**
 - *AnotherSignal* is accepted.

Refine the acceptance of an event occurrence from a DoActivityExecutionEventAcceptor.



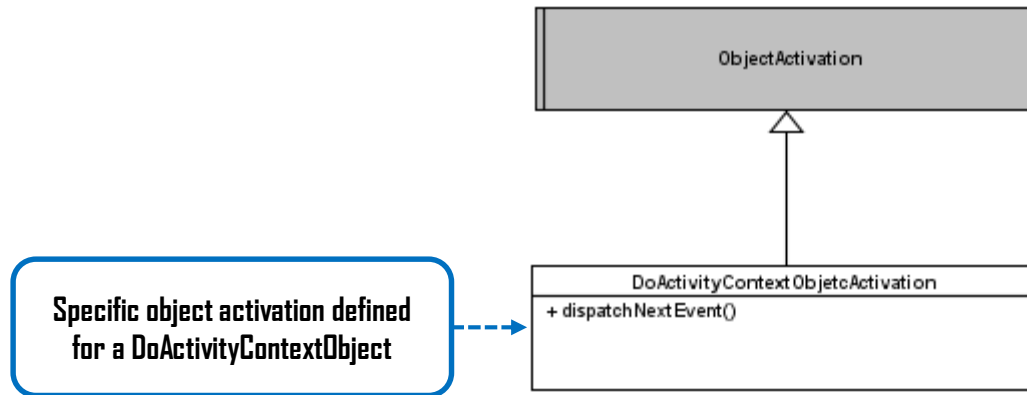
This type of acceptor is registered by the DoActivityContextObject in the waiting event acceptor list of the state-machine context

– V1 :

- The acceptance was directly delegated to the wrapped event acceptor. The side effect is that the RTC step is still realized in the execution thread of the state-machine.

– V2:


- When accepting the event occurrence the DoActivityExecutionEventAcceptor only triggers a RTC step in the doActivity. This is realized by sending the accepted event occurrence to the doActivity object activation.

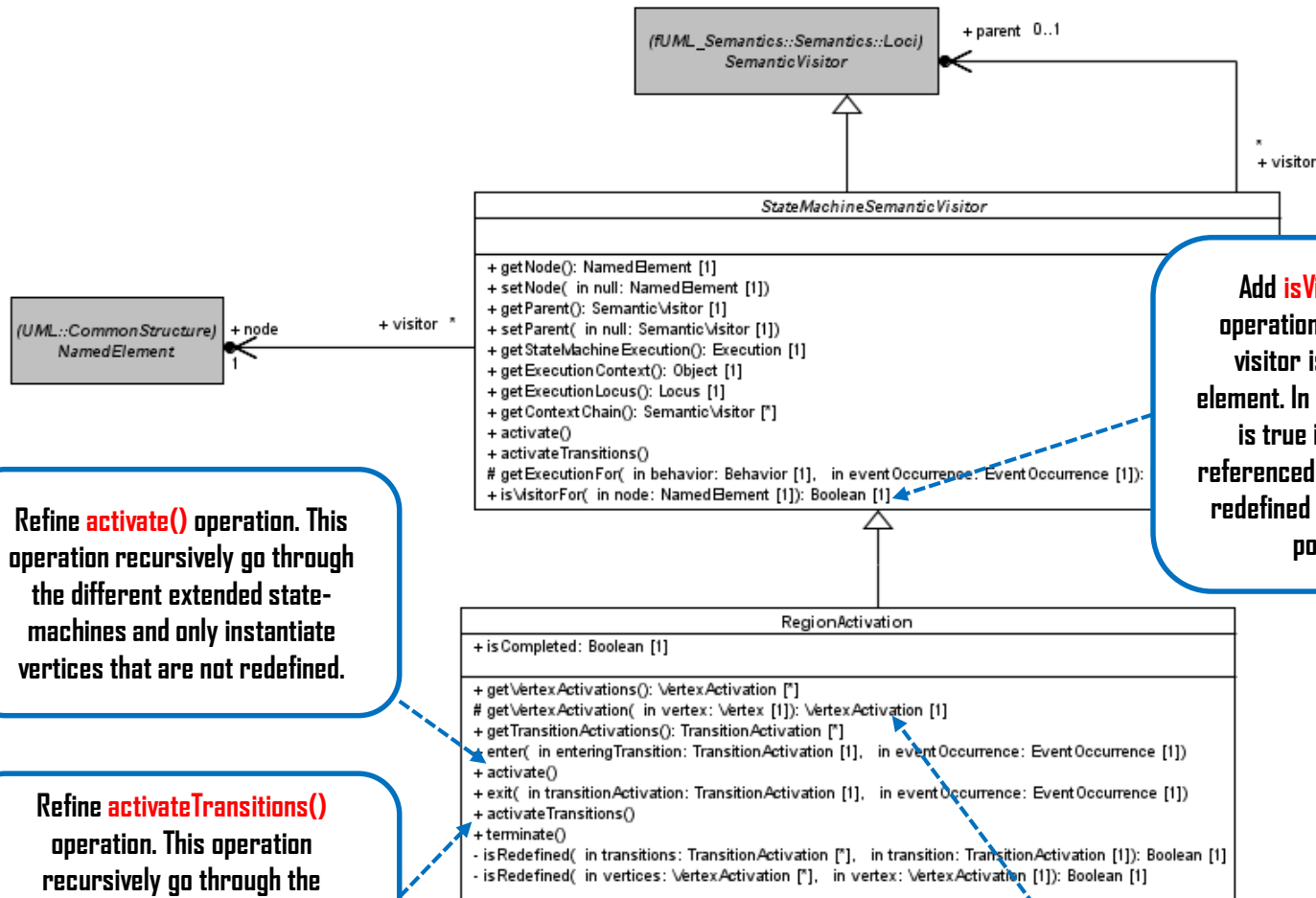


- `dispatchNextEvent()`
 - Preserve fUML semantics. Implements the dispatch.
 - Add the possibility to notify the state which invoked the doActivity that this latter has completed its execution.
 - Check for execution completion is base on the analysis of the presence of registered acceptor at the end of each RTC step.

STATE-MACHINE REDEFINITION SEMANTICS

Precise semantics

- Proposals may provide precise semantics for state machine redefinition, as represented by the following meta-associations: 
 - A_extendedRegion_region
 - A_extendedStateMachine_stateMachine
 - A_redefinedState_state
 - A_redefinedTransition_transition
 - A_redefinitionContext_region
 - A_redefinitionContext_state
 - A_redefinitionContext_transition
- Agenda: June 2016

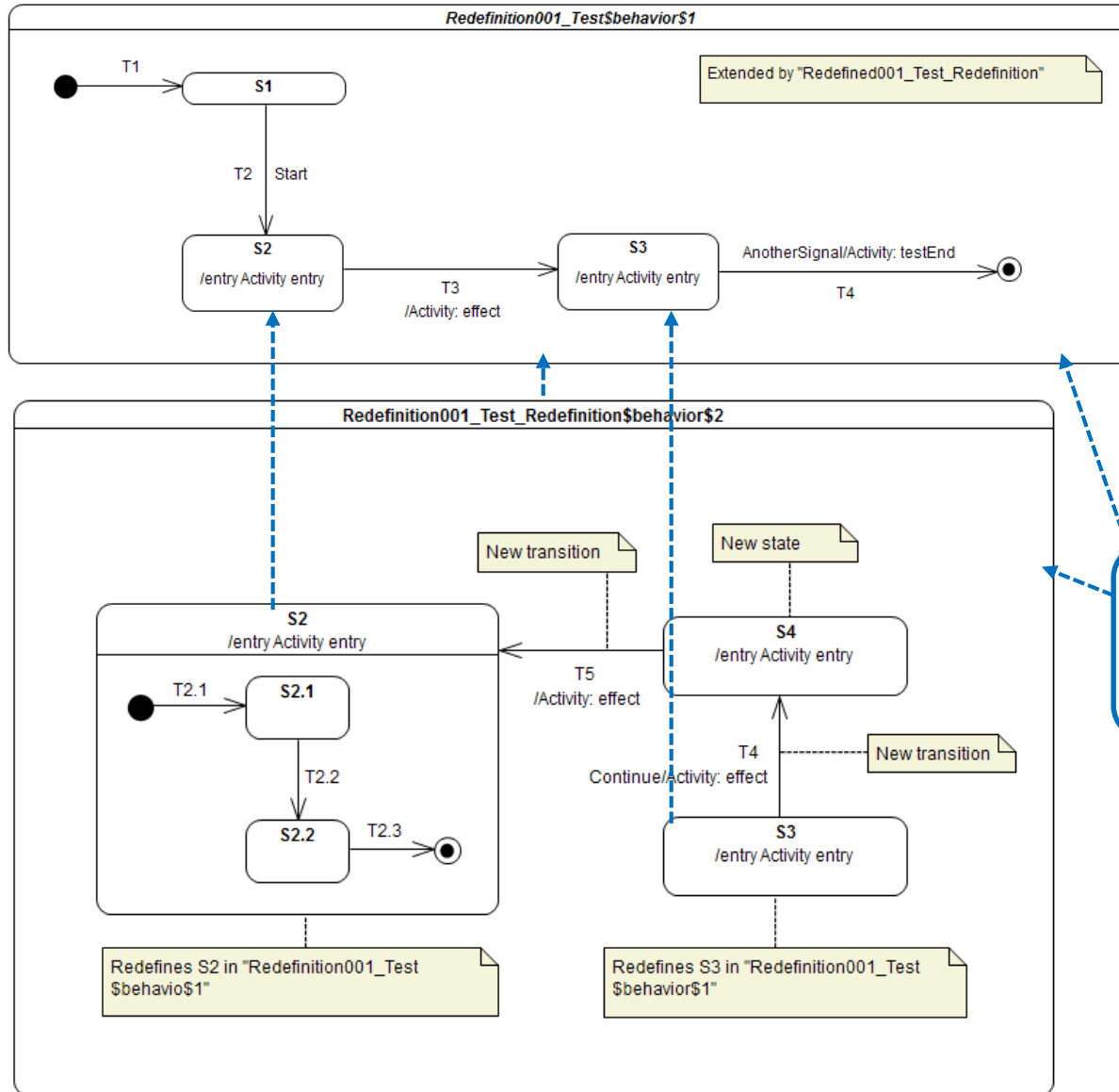


Refine **activate()** operation. This operation recursively go through the different extended state-machines and only instantiate vertices that are not redefined.

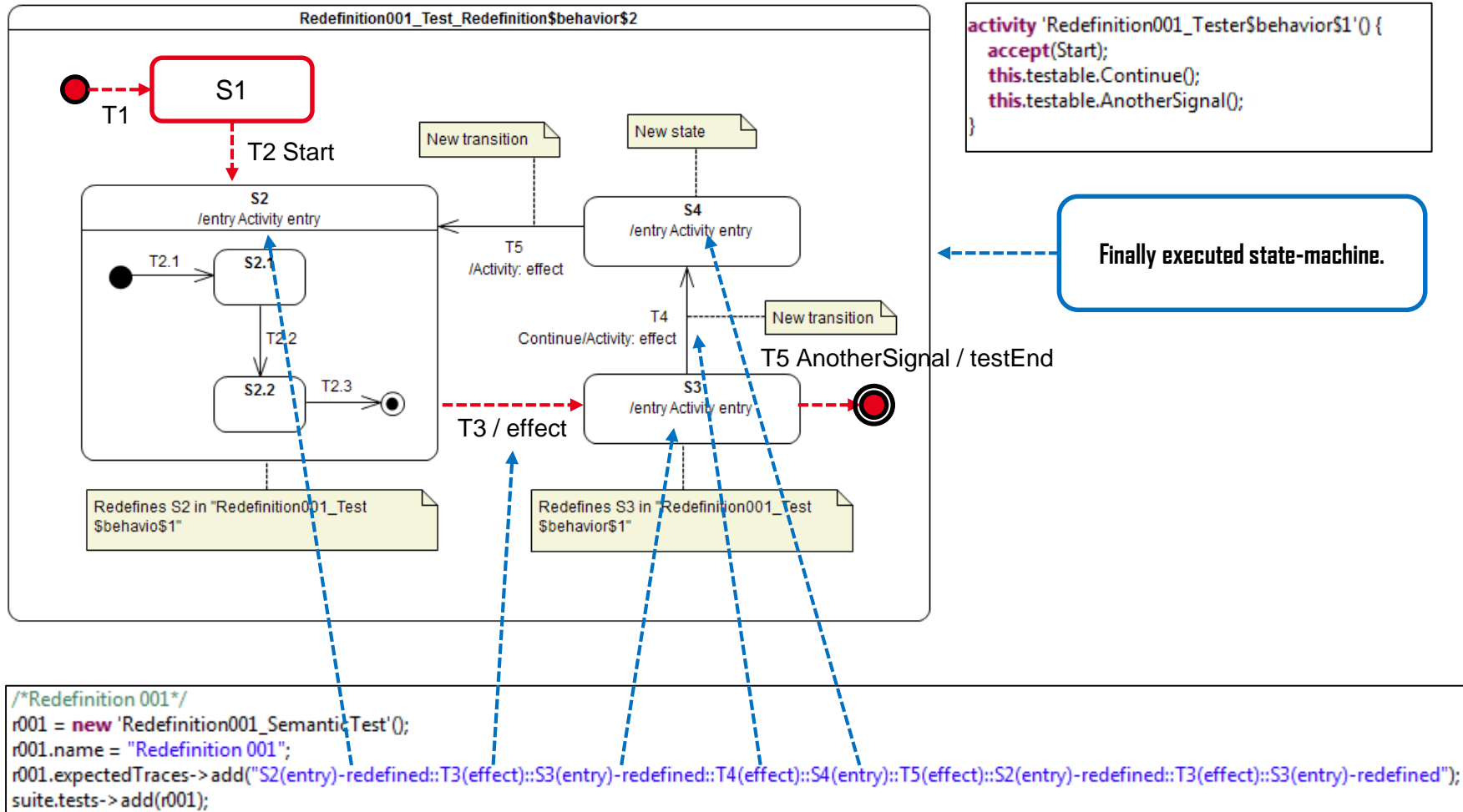
Refine **activateTransitions()** operation. This operation recursively go through the different extended state-machines and only instantiate transitions that are not redefined.

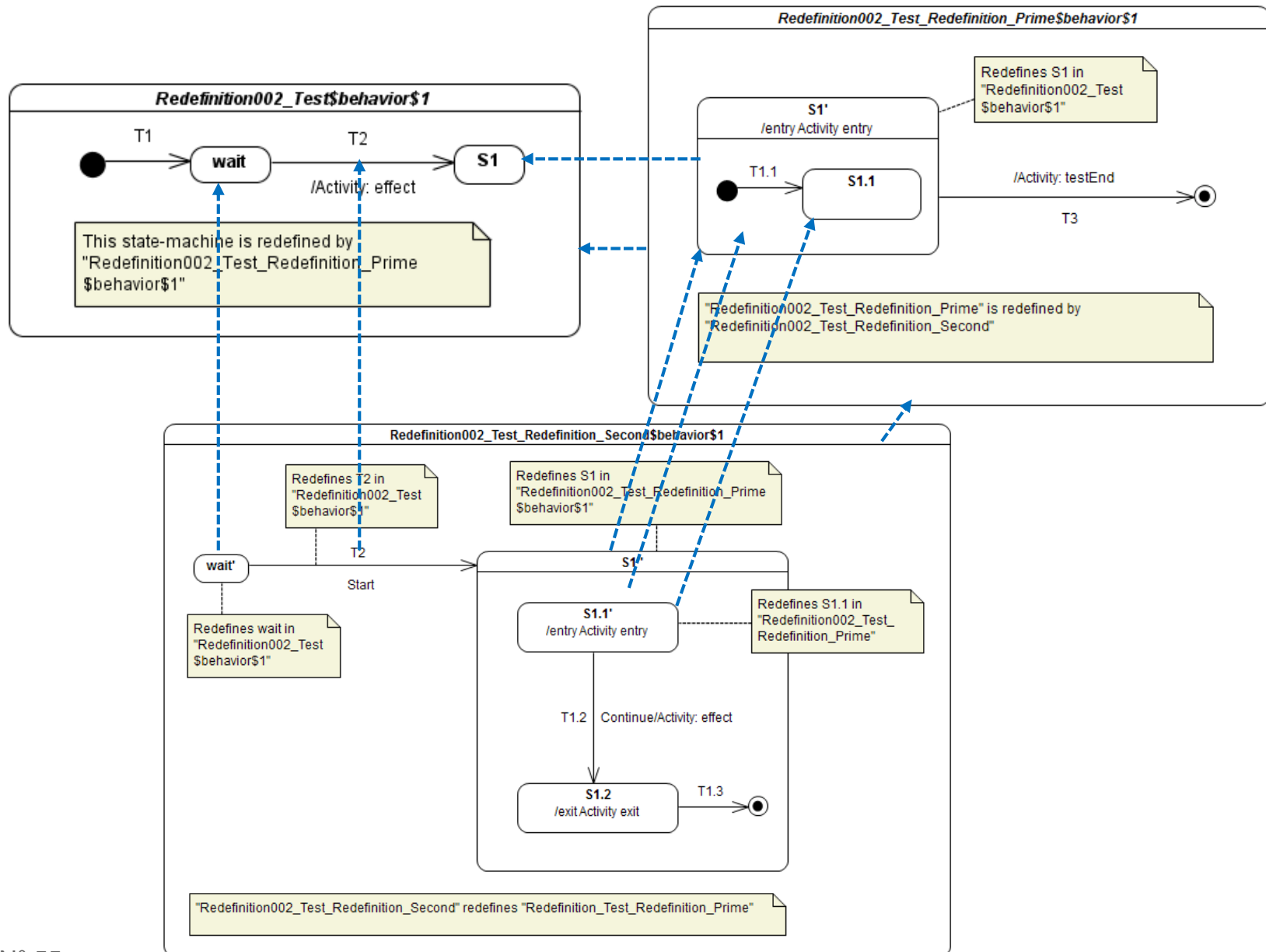
Add **isVisitorFor(...)** operation. This operation assesses if a given semantic visitor is an interpreter for a model element. In the basic version this assertion is true if the given node is the node referenced by the visitor. This operation is redefined in StateActivation to cope with possibly redefined state.

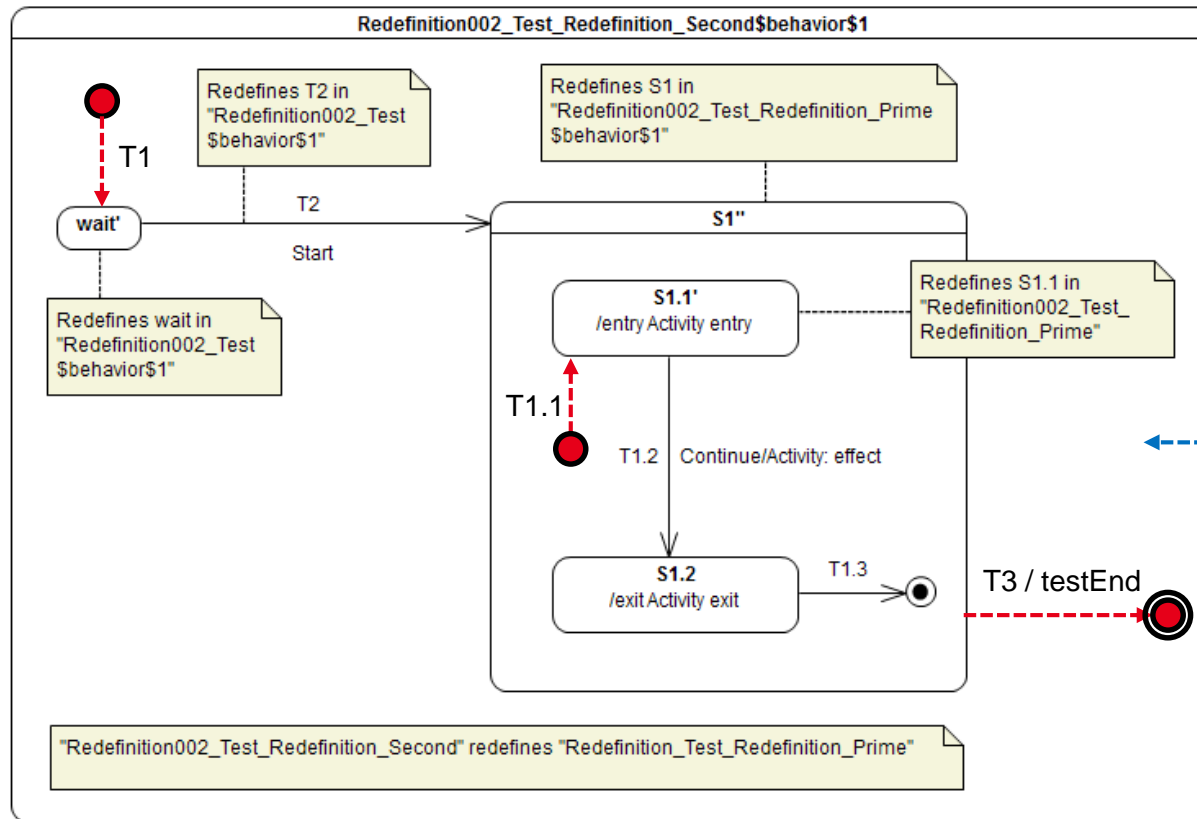
Refine **getVertexActivation (...)** operation. This operation now relies on **isVisitorFor(...)** during the search phase to figure out what is the corresponding visitor in the hierarchy



This example is exactly the one discussed in clause 8.5.3 in PSSM initial submission







```

activity 'Redefinition002_Tester$behavior$1'() {
    accept(Start);
    this.testable.Continue();
}
  
```

Finally executed state-machine.

```

/*Redefinition 002*/
r002 = new 'Redefinition002_SemanticTest'();
r002.name = "Redefinition 002";
r002.expectedTraces->add("S1.1(entry)-redefined-second::T1.2(effect)::S1.2(exit)");
suite.tests->add(r002);
  
```

OUR CURRENT STATUS

Deferred events semantics completion 

State machine configuration analysis 

Test suite refactoring 

Call event semantics 

Event data passing 

- Fix: doActivity is not allowed to return values
- Fix: data are for the moment not passed to guards (UML 2.6 RTF)

DoActivity 

State machine redefinition 

- Needs more intensive testing

Standalone state-machines 

- Needs more intensive testing

Implementation conformance to bUML 

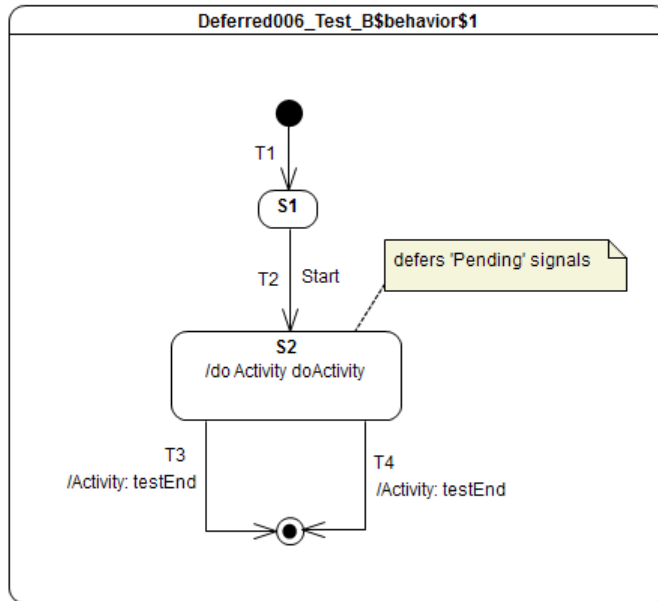
- We have the list of changes to apply

Pseudo states 

- History (deep and shallow)
- Junction



BACKUP



```

private import Util::Architecture::A_testable_tester;

activity 'Deferred006_Test_B$behavior$1'() {
    accept(Start);
    this.testable.Pending();
    this.testable.AnotherSignal();
}

```

```

/*Deferred006 B */
d006b = new 'Deferred006_SemanticTest_B'();
d006b.name = "Deferred 006 B";
d006b.expectedTraces->add("");
d006b.expectedTraces->add("S2(doActivityPartI)::S2(doActivityPartII)");
suite.tests->add(d006b);

```

