

Statemachines... ...for embedded

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Generate Code from behaviour Models

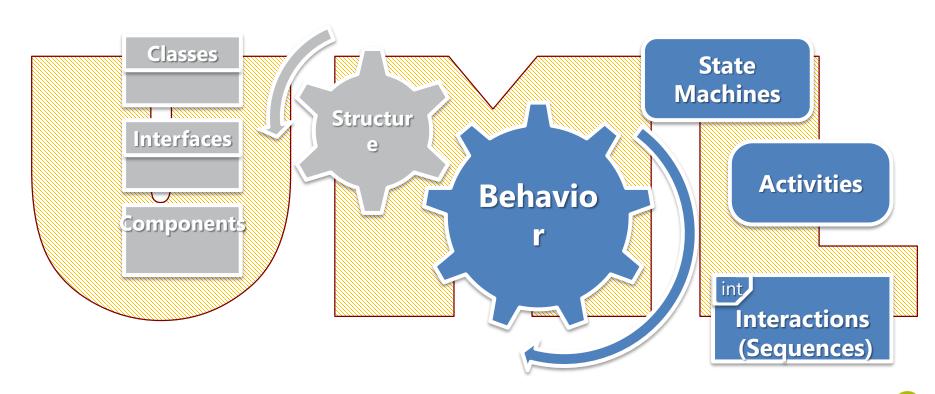
Lot's of new and old challenges ahead!

- Functional Safety (ISO 26262,...)
- UI complexity
- Multi and many core hardware
- Traceability
- Documentation requirements





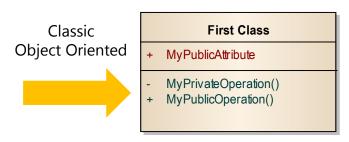
Use full power of UML





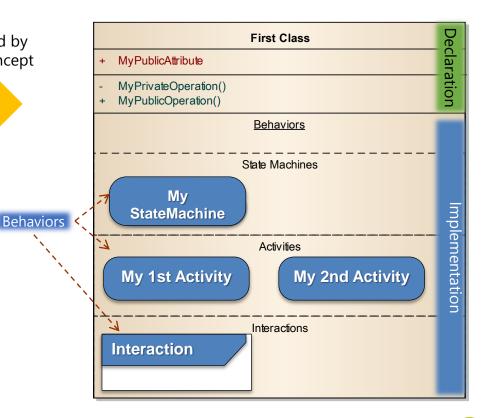


What it is about – UML Behavior?



OO extended by Behavior concept

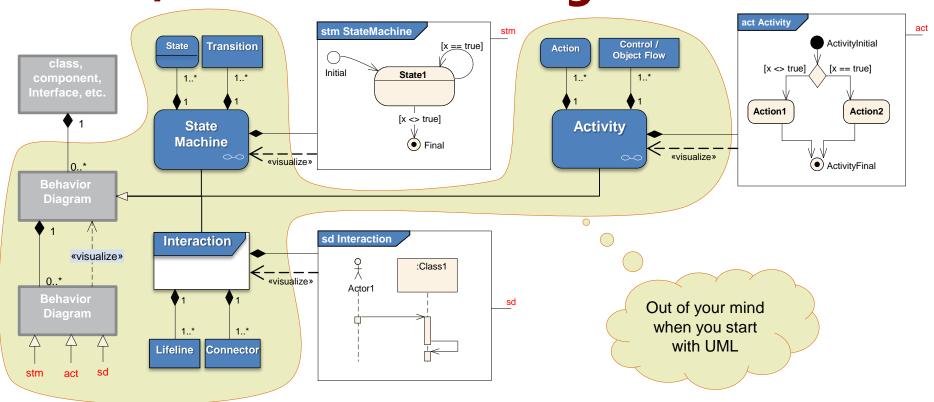
- Attributes and Operations are declaration only
 - ⇒ Same as HEADER files in C or C++
- And now how to implement using UML??
- UML introduced behaviors to extend classic object oriented concept
- Behavior is UML concept for "implementation"
 - ⇒ Same as SOURCE files in C or C++







Class, Behavior and Diagrams







Generate Code from behaviour Models

Inspiration:

- Higher level of abstraction than the generated code especially State Charts are very powerful
- Render requirement and hazard information into the code automatically!
- Documentation = Product





```
Requirement1
⊢class InterfaceTest
                                                                                             tags
                                                                                   Object Identifier = REQ-1
  public:
                                                      «interface»
                                                                                             notes
                                                     InterfaceTest
                                                                                   This is the description of
                                                                                   requirement REQ-1
      /// auto generated virtual des
                                                   doA(uint8): bool
      virtual ~InterfaceTest() {}
                                                 + doC()
                                                        notes
                                                 This is the description of
      /// This is the description of
                                                   maceTest
      /// @param param1: this is the
                                             Traceability from Requirement to Code
      /// @covers REQ-1
      virtual bool doA(uint8 param1) = 0;
      /// this is the description of method doC()
      virtual void doC() = 0;
 };
```





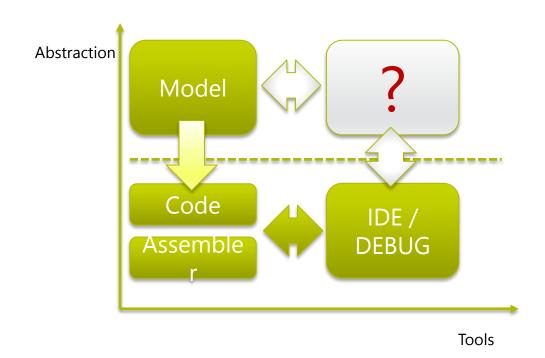
Generate Code from behaviour Models

- Full (Behavior) round trip is a myth
- 2015 forward only
- Reverse for legacy
- Optional: synchronization of method/function content





The missing Link – Debugging for Models







The missing Link – Debugging for Models

- Engineers need feedback Feedback means debugging
- We need them to debug with the model
- Ability to understand and fix issues in the model/generator and not in the "code".
- Pure UML "Simulation" is not the best solution for embedded



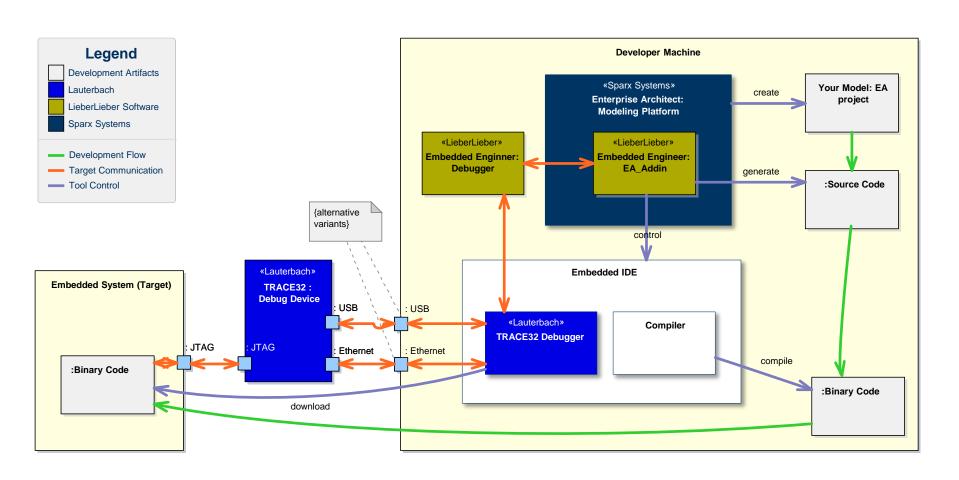


Our Approach/Demo

- Enterprise Architect from Sparx Systems to build the models
- Programmed and debug able code generator (C#)
- C or C++ source code
- Compile and ceploy done with Code Composer
- LieberLieber UML Debugger linked to TRACE32 from Lauterbach

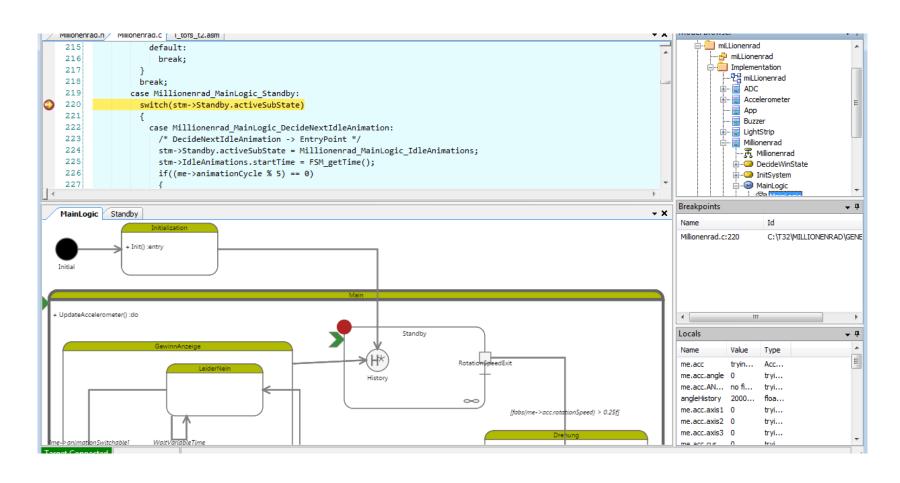
















```
Millionenrad.h Millionenrad.c
      bool Millionenrad_MainLogic(Millionenrad* const me, Millionenrad_MainLogic_STM* stm, Signals msg)
  58
  59
        bool evConsumed = 0;
  60
        switch(stm->mainState.activeSubState)
  61
  62
          case Millionenrad_MainLogic_Initialization:
  63
             evConsumed = 1;
  64
            /* Initialization -> History */
             stm->mainState.activeSubState = Millionenrad_MainLogic_Main;
  66
            Millionenrad_MainLogic_EnterDeepHistory(me, stm, &(stm->Standby));
  67
  68
           case Millionenrad MainLogic Main:
             /* do action for state Main */
  69
  70
             Accelerom
                           QdateAxis(&me->acc, &me->adc);
            /* end
  71
                            ns for state Main */
             switch(st
                           n.activeSubState)
  73
MainLogic
                                  Selected state also visualized in C
                  Init() :entry
 + UpdateAccelerometer() :do
                                                                            Standby
```

Conclusion



Can you afford and "survive" not to generate Code?

Start TODAY!





THANK YOU

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