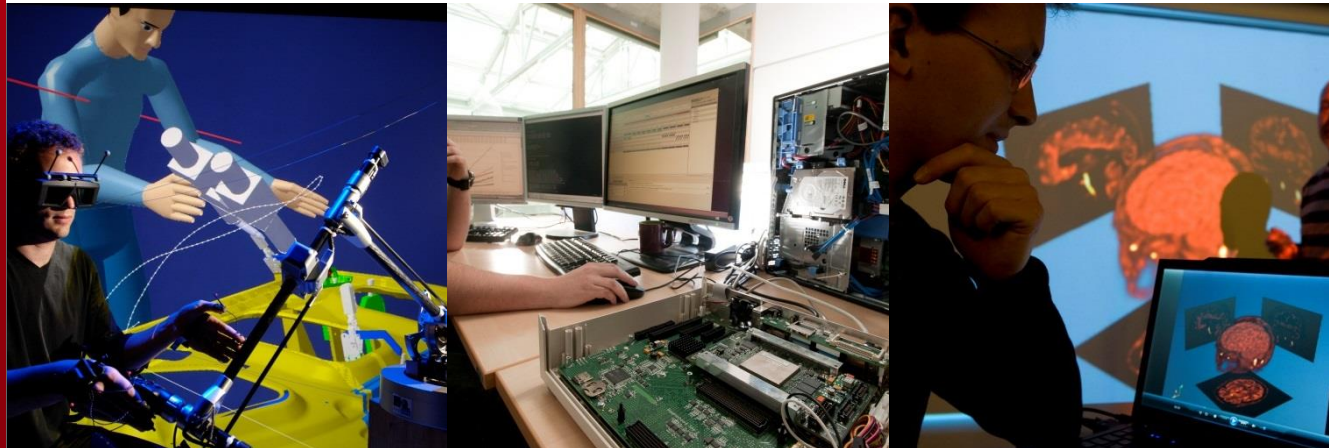


[PSSM] – SAN DIEGO MEETING DECEMBER 10TH

Jérémie TATIBOUET (CEA LIST)

Arnaud CUCCURU (CEA LIST)

list



A. Semantic model

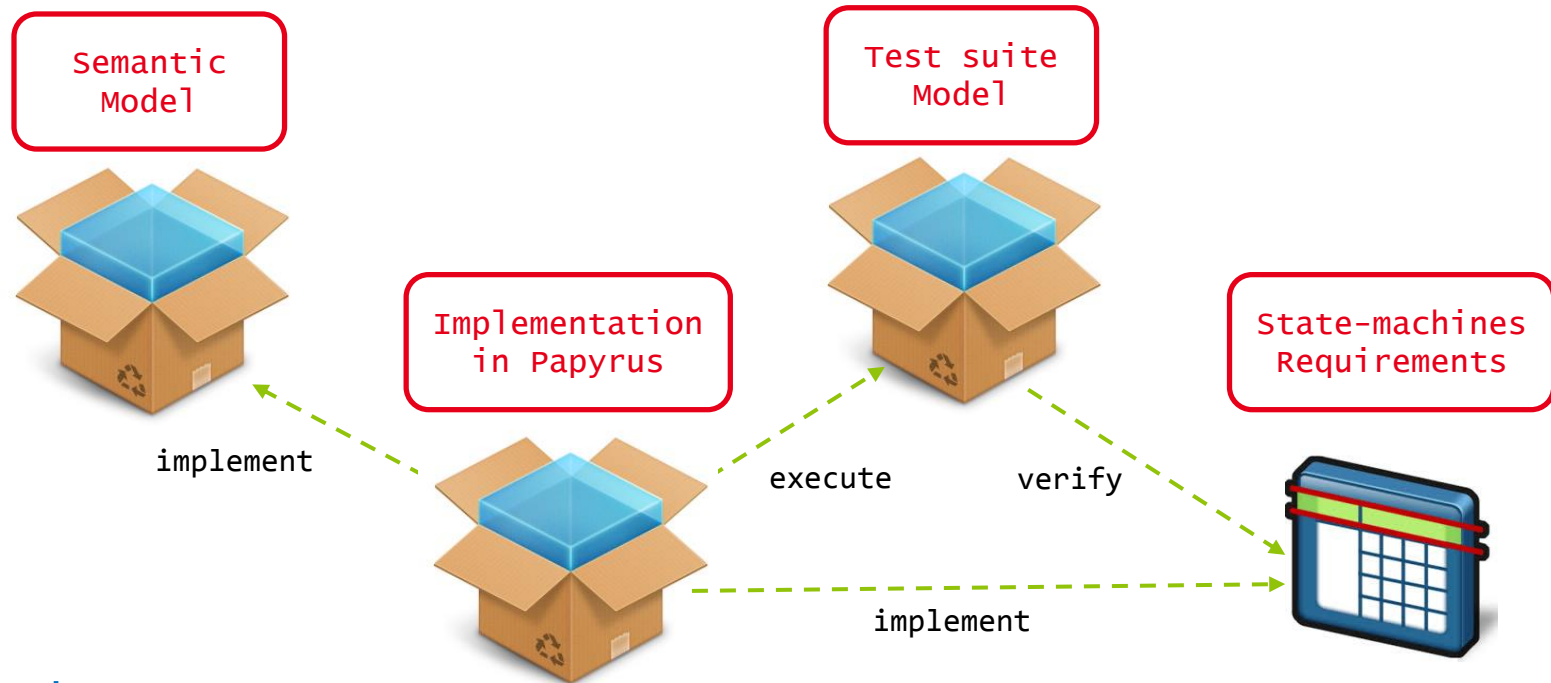
- Model architecture
- Core
 - Base semantic visitors
 - State-machine execution
 - State-machine configuration
- State
 - Simple, composites and Final
- Communication
 - Event accepter and completion events
- Selection
 - Transition selection
- Pseudo states
 - Entry point / Exit point / Choice

B. Test suite

- Reminder on the structure
- Requirements verification review

C. Assessment

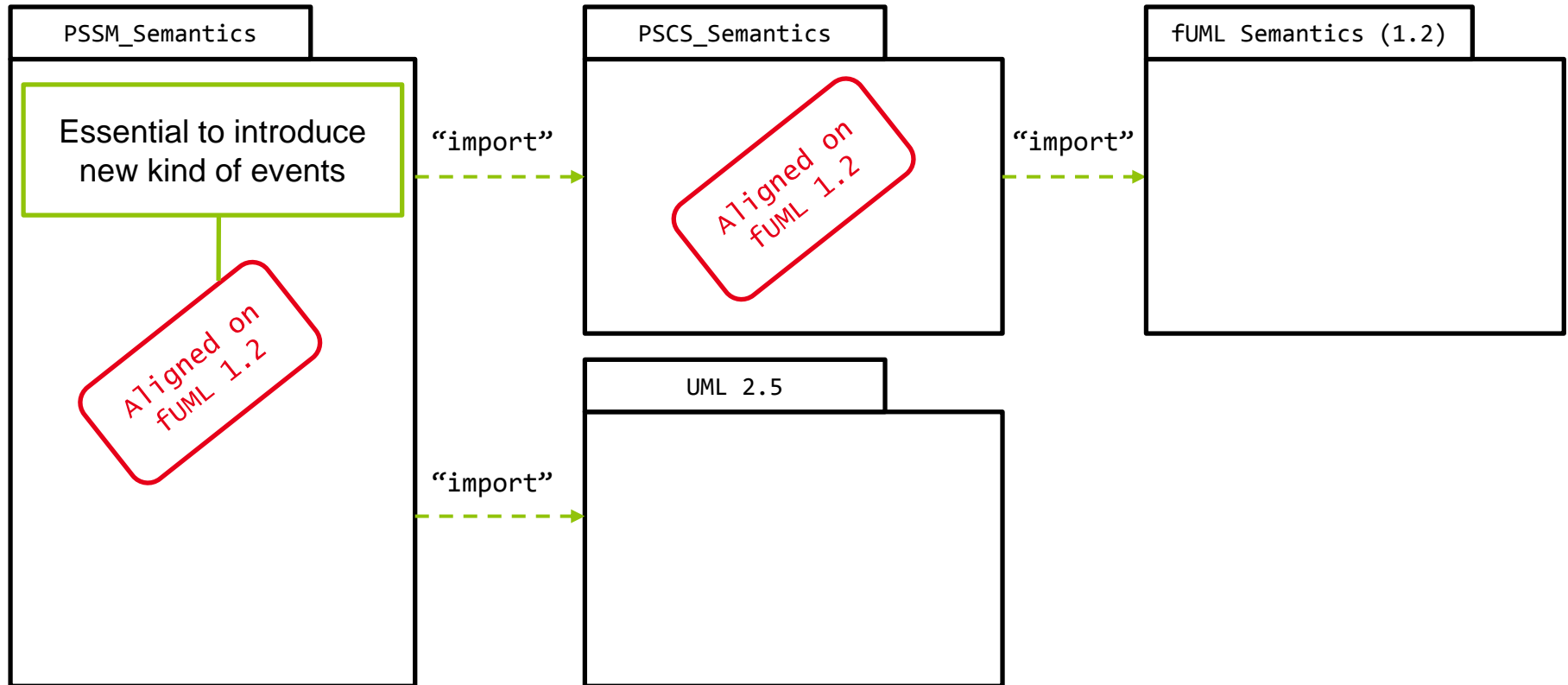
- Progress compare to last meeting
- What is not supported



Big picture

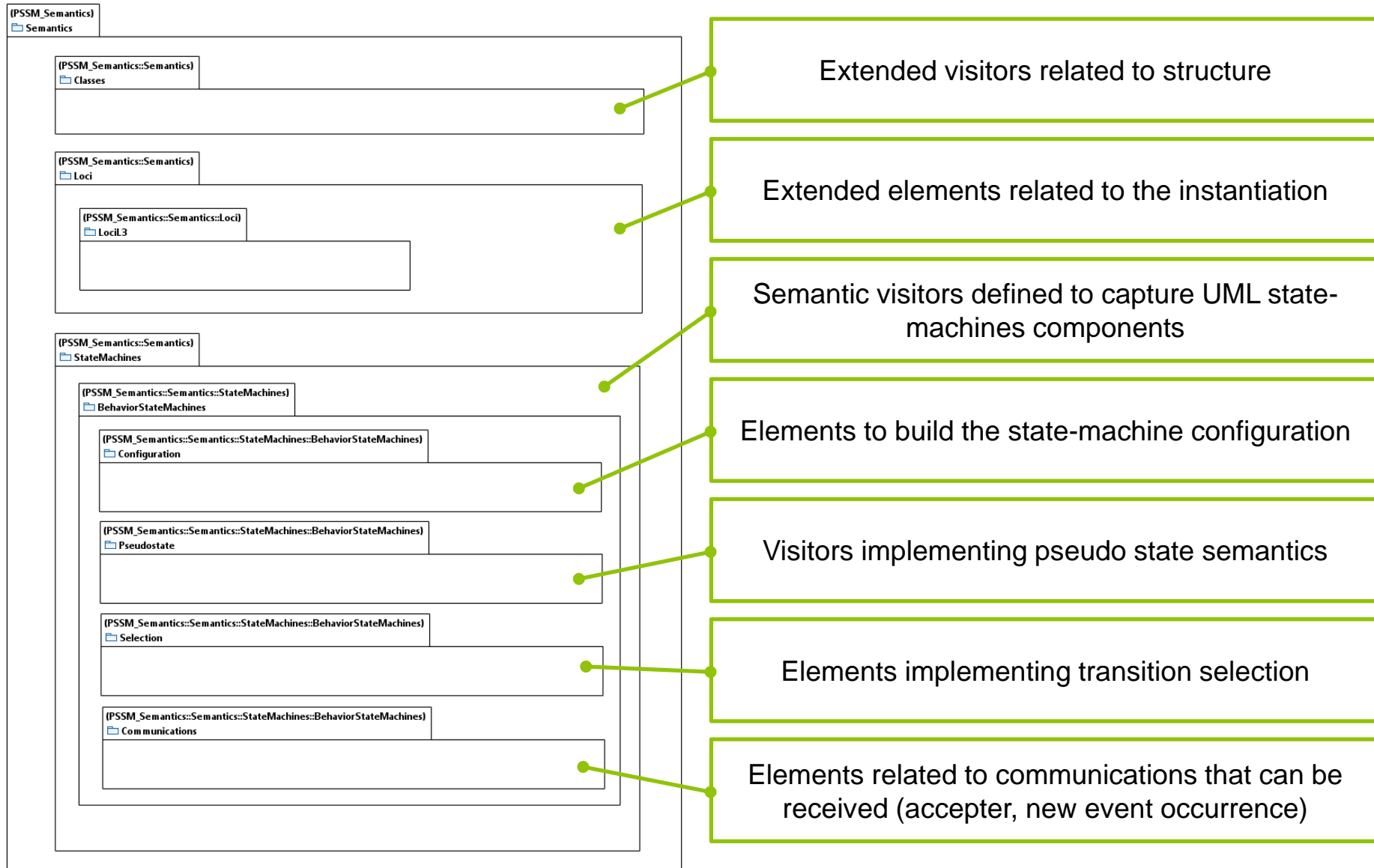
- **Prototype implementation**
 - An implementation of the semantic model
 - Capture the requirements for UML state-machines
 - Capable of executing the test suite
- **Test suite**
 - Define a set of executable state-machines
 - Each test enables the verification of one requirement
 - The “verified” status is calculated based on trace comparison

SEMANTIC MODEL ARCHITECTURE

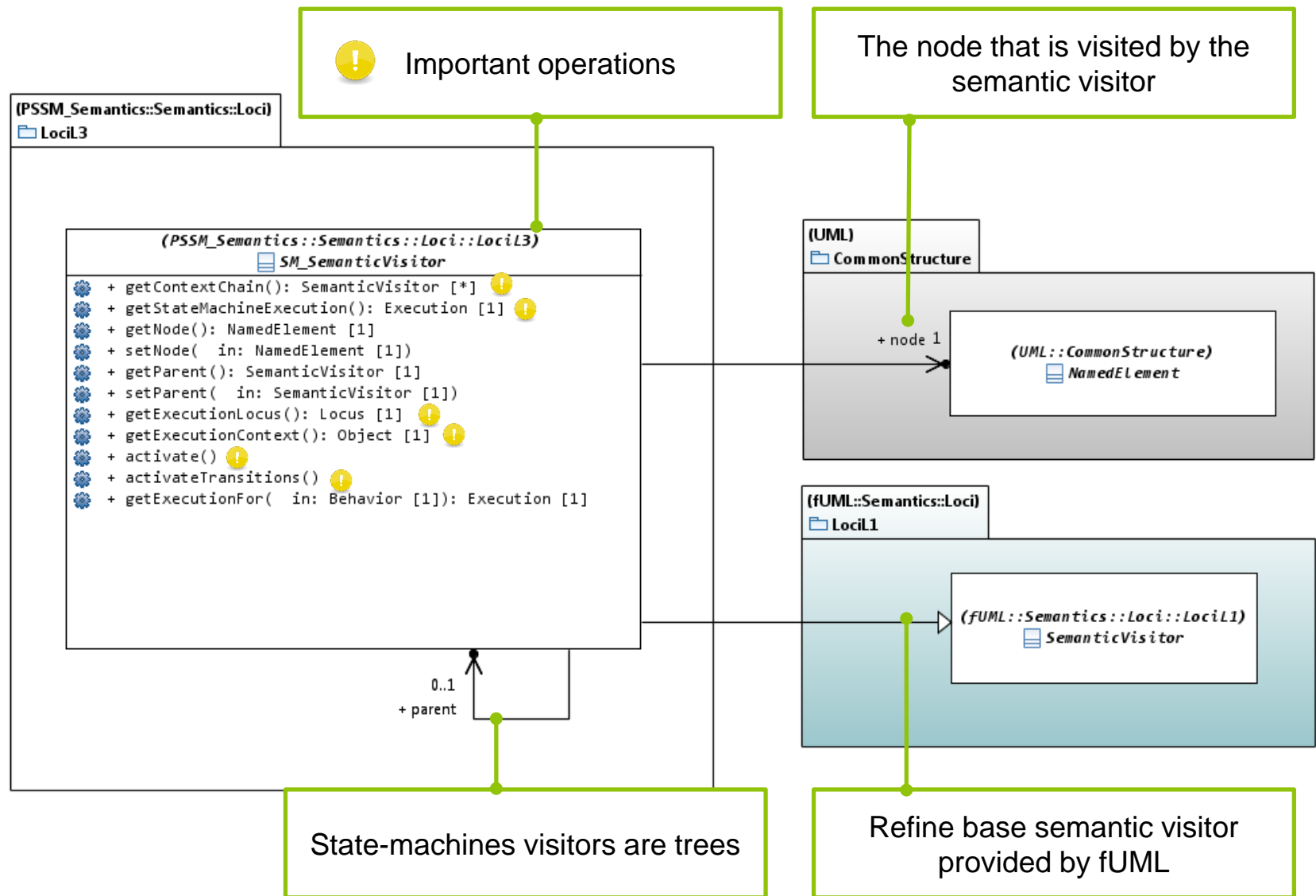


Dependencies

- UML 2.5
- PSCS semantics
 - In Papyrus, Moka (model execution tool) is aligned on fUML 1.2. As PSCS is built on top of fUML it is aligned with fUML 1.2. **Note: fUML 1.2 has no impact on PSCS.**

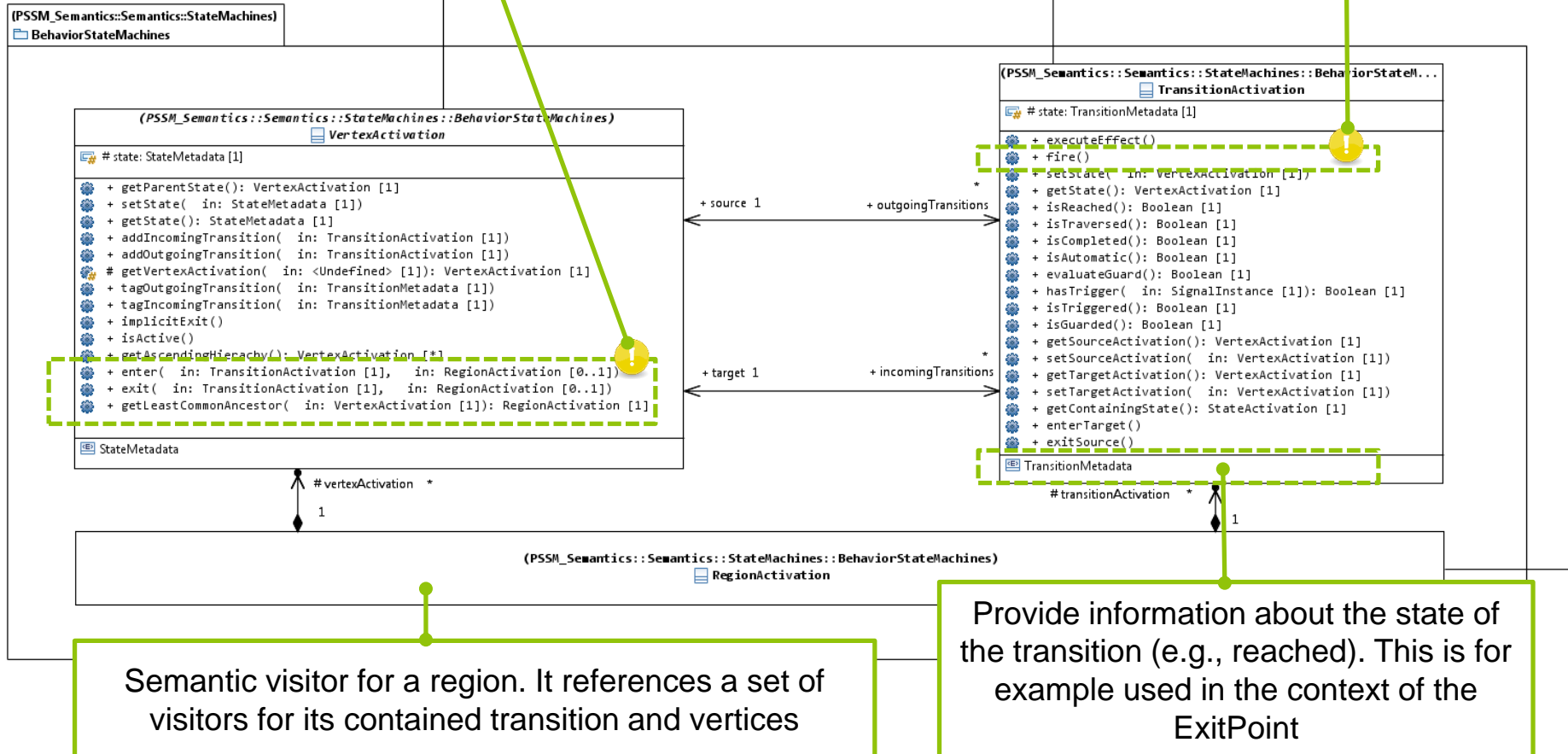


CORE OF PSSM



Any vertex is always entered and left using “enter” and “exit” operations

The transition is responsible for entering and leaving a state. It semantics is mainly encapsulated in the “fire” operation



Propagation of the execution

```
protected void enterTarget(){
    Transition node = (Transition) this.getNode();
    RegionActivation leastCommonAncestor = null;
    // A target state is always entered except when the transition reaching this latter
    // has the internal kind
    if(node.getKind()!=TransitionKind.INTERNAL_LITERAL){
        if(this.vertexSourceActivation.getParentState()!=this.vertexTargetActivation.getParentState()){
            leastCommonAncestor = this.vertexSourceActivation.getLeastCommonAncestor(this.vertexTargetActivation);
        }
        this.vertexTargetActivation.enter(this, leastCommonAncestor);
    }
}
```

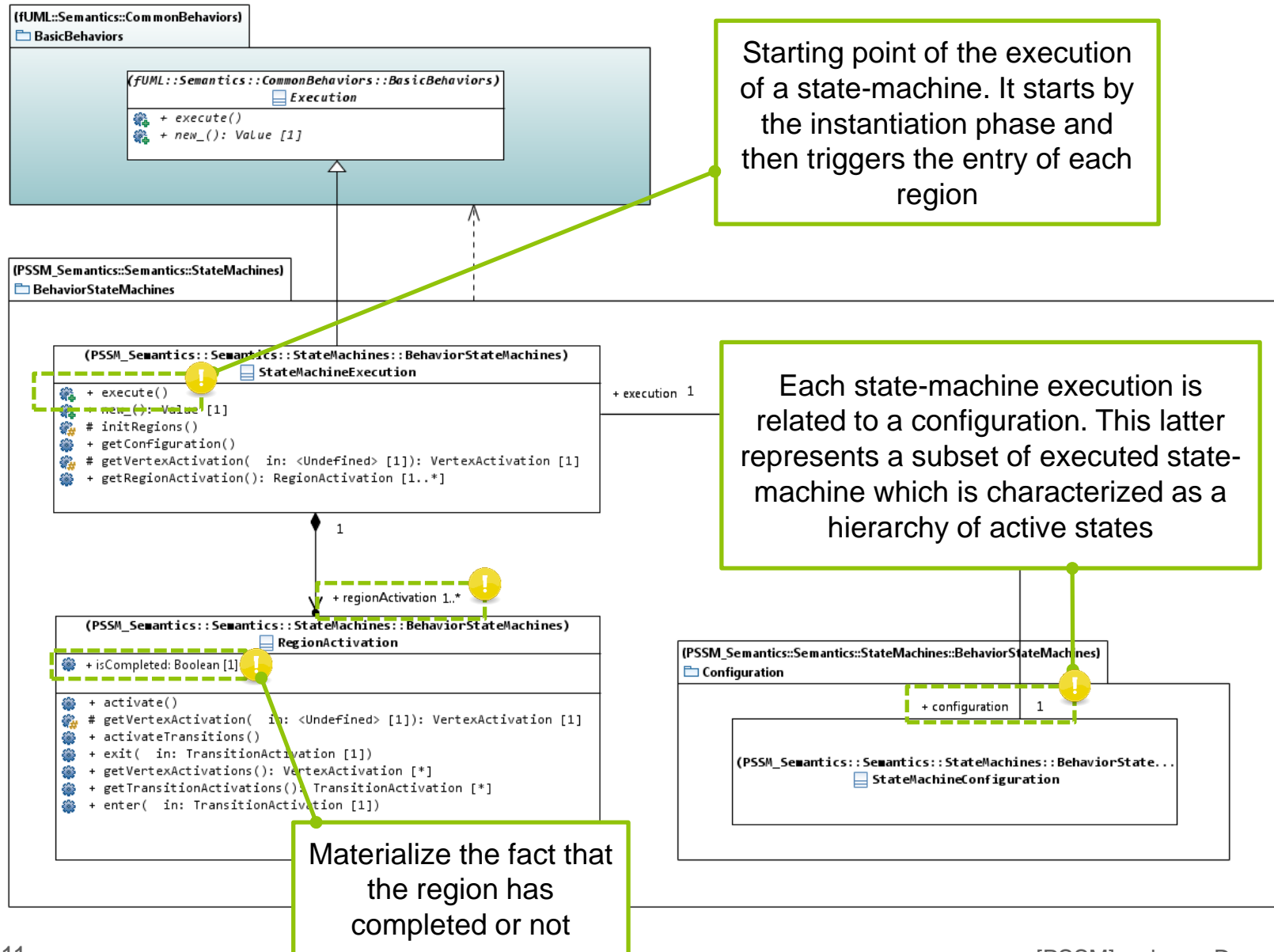
1

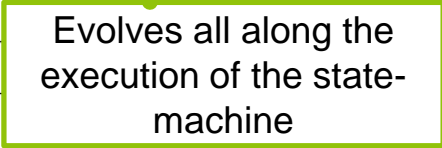
```
public void executeEffect(){
    // Execute the effect that is on the transition if it exists one
    Transition transition = (Transition) this.getNode();
    Execution execution = this.getExecutionFor(transition.getEffect());
    if(execution!=null){
        execution.execute();
    }
}
```

2

```
protected void exitSource(){
    // A source state is exited when the transition fires under the following conditions:
    // 1 - The transition leaving the source state is external
    // 2 - The transition leaving the source state is local but the source state is not the
    // state which contains the transition
    Transition node = (Transition) this.getNode();
    boolean exitSourceState = false;
    RegionActivation leastCommonAncestor = null;
    if(node.getKind()==TransitionKind.EXTERNAL_LITERAL){
        exitSourceState = true;
    }else if(node.getKind()==TransitionKind.LOCAL_LITERAL){
        StateActivation stateActivation = this.getContainingState();
        exitSourceState = stateActivation!=null && node.getSource()!=stateActivation.getNode();
    }
    if(exitSourceState){
        if(this.vertexSourceActivation.getParentState()!=this.vertexTargetActivation.getParentState()){
            leastCommonAncestor = this.vertexSourceActivation.getLeastCommonAncestor(this.vertexTargetActivation);
        }
        this.vertexSourceActivation.exit(this, leastCommonAncestor);
    }
}
```

Propagation of the execution



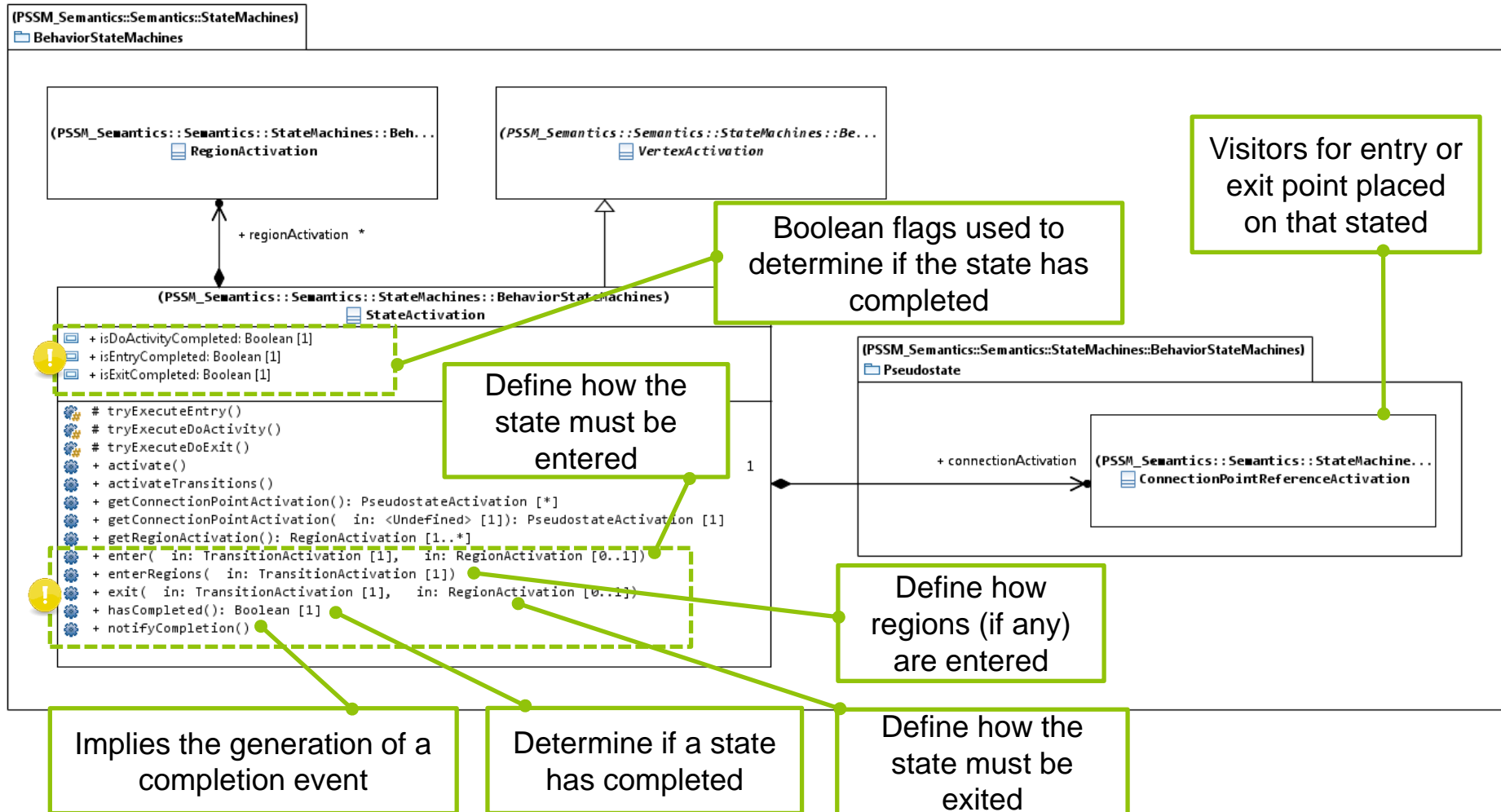


Role

- # Principles

- Each state that is entered registers within the configuration
- Each state that is exited leaves the configuration

STATES: SIMPLE, COMPOSITE AND FINAL



Note

- Simple and composite state semantics is defined in a single visitor

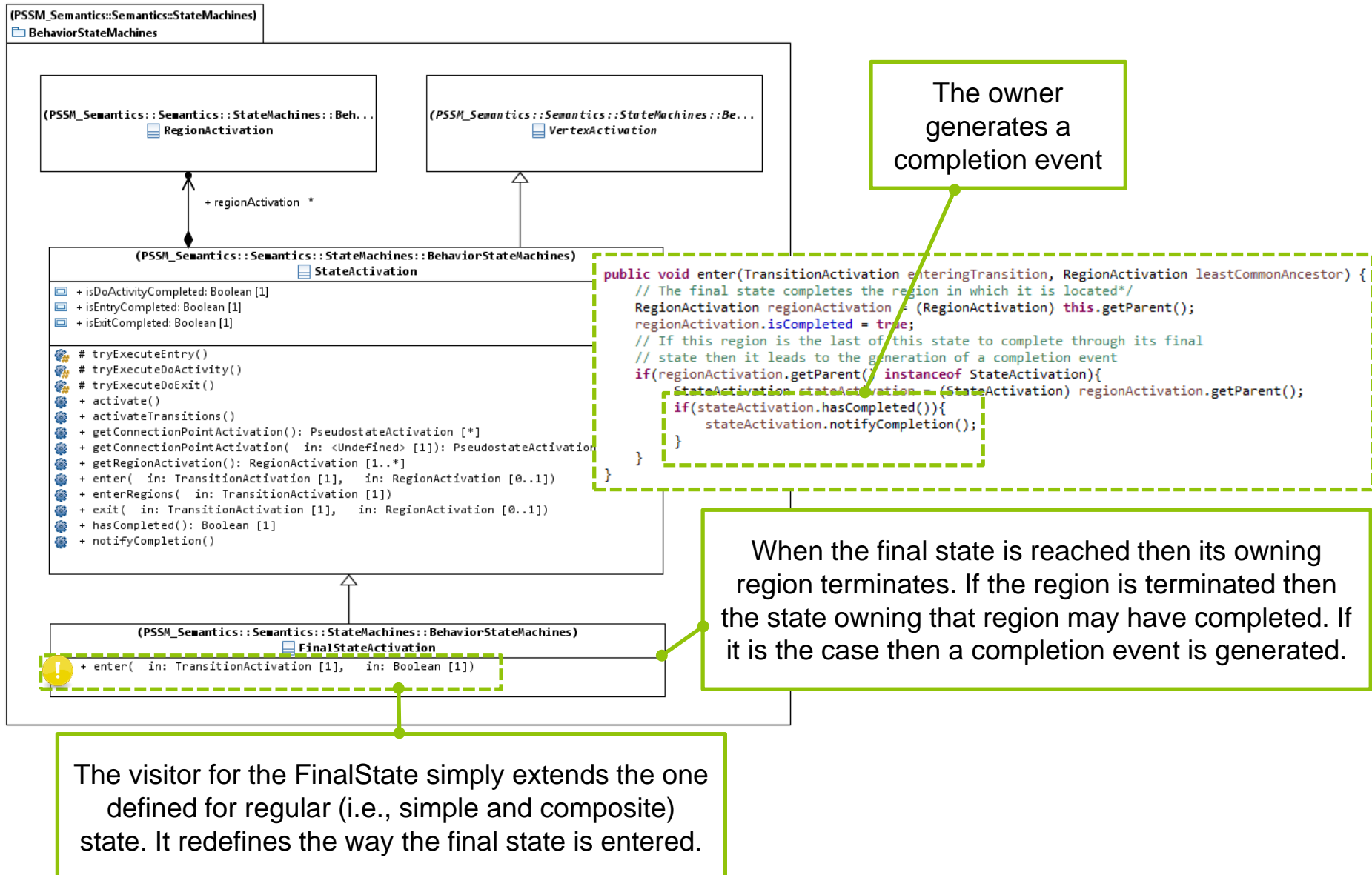
If parent need to
be entered first

Calculate initial
completion status

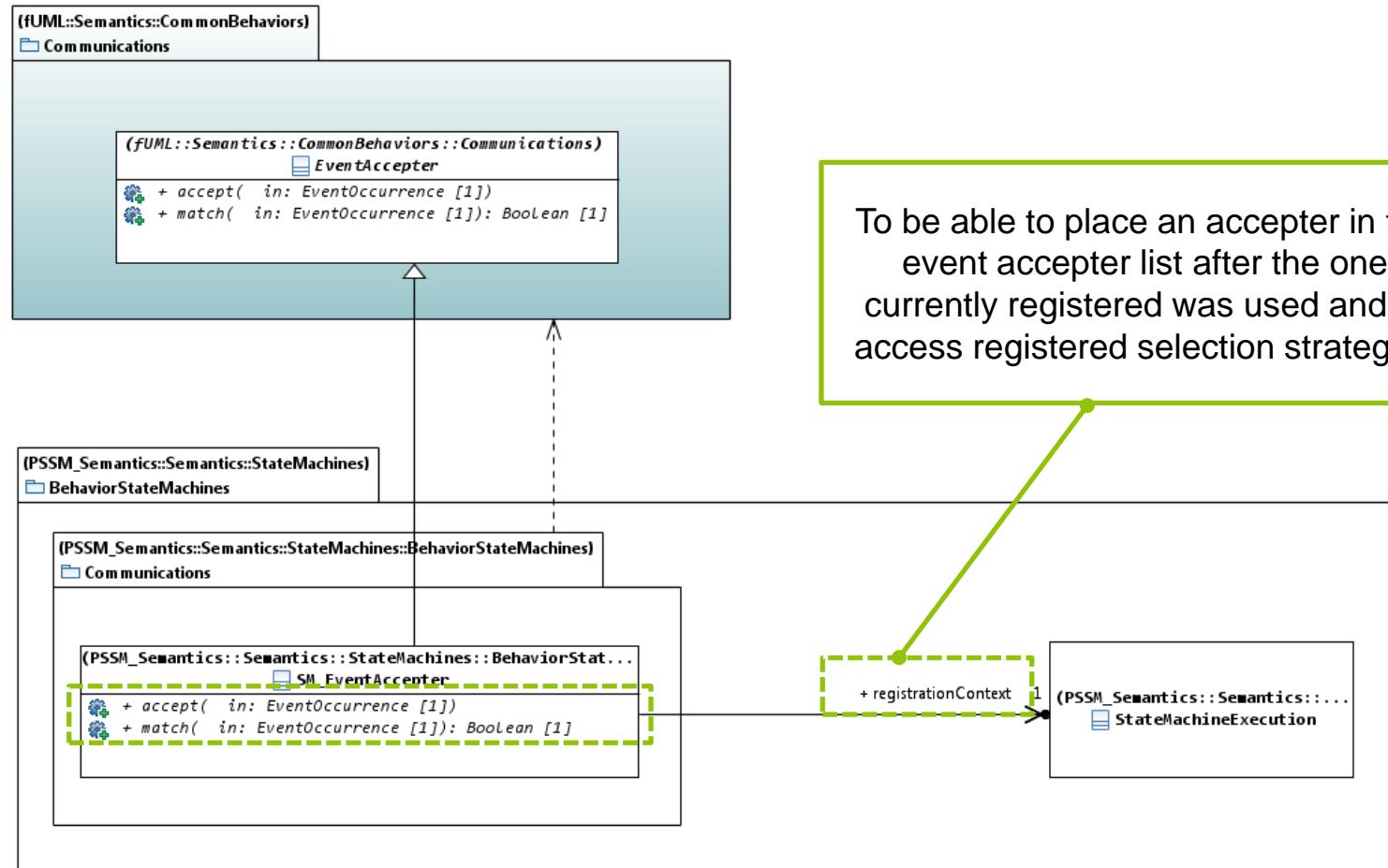
Complete if this is
allowed

Execute entry,
then enter
region(s), finally
execute doActivity

```
public void enter(TransitionActivation enteringTransition, RegionActivation leastCommonAncestor) {
    if(this.state.equals(StateMetadata.IDLE)){
        // The state is entered via an explicit transition
        // The impact on the execution is that the parent state
        // of the current state is not active then it must be entered
        // the rule applies recursively
        if(leastCommonAncestor!=null){
            RegionActivation parentRegionActivation = (RegionActivation) this.getParent();
            if(leastCommonAncestor!=parentRegionActivation){
                StateActivation stateActivation = (StateActivation) parentRegionActivation.getParent();
                if(stateActivation!=null){
                    stateActivation.enter(enteringTransition, leastCommonAncestor);
                }
            }
        }
        // Initialization
        State state = (State) this.getNode();
        super.enter(enteringTransition, leastCommonAncestor);
        this.isEntryCompleted = state.getEntry()==null;
        this.isDoActivityCompleted = state.getDoActivity()==null;
        this.isExitCompleted = state.getExit()==null;
        // When the state is entered it is registered in the current
        // state-machine configuration
        StateMachineExecution smExecution = (StateMachineExecution)this.getStateMachineExecution();
        smExecution.getConfiguration().register(this);
        // If state has completed then generate a completion event*/
        if(this.hasCompleted()){
            this.notifyCompletion();
        }else{
            // Execute the entry behavior if any
            this.tryExecuteEntry();
            // If the state is not completed, then try to start its owned regions.
            // A region is entered implicitly since the is not the
            this.enterRegions(enteringTransition);
            // Execute the doActivity if any
            this.tryExecuteDoActivity();
        }
    }
}
```

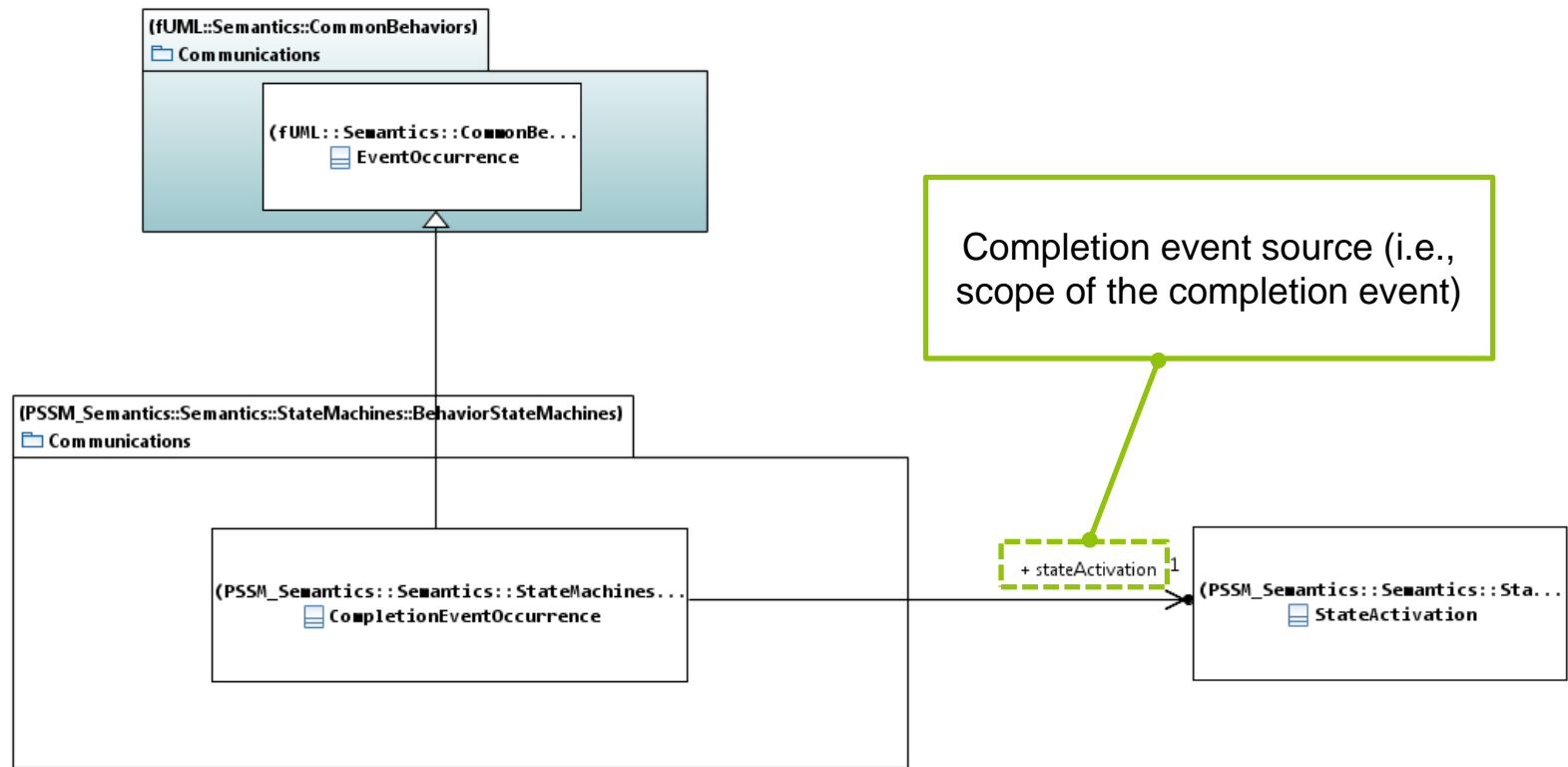


COMMUNICATIONS: ACCEPTER AND COMPLETION EVENTS



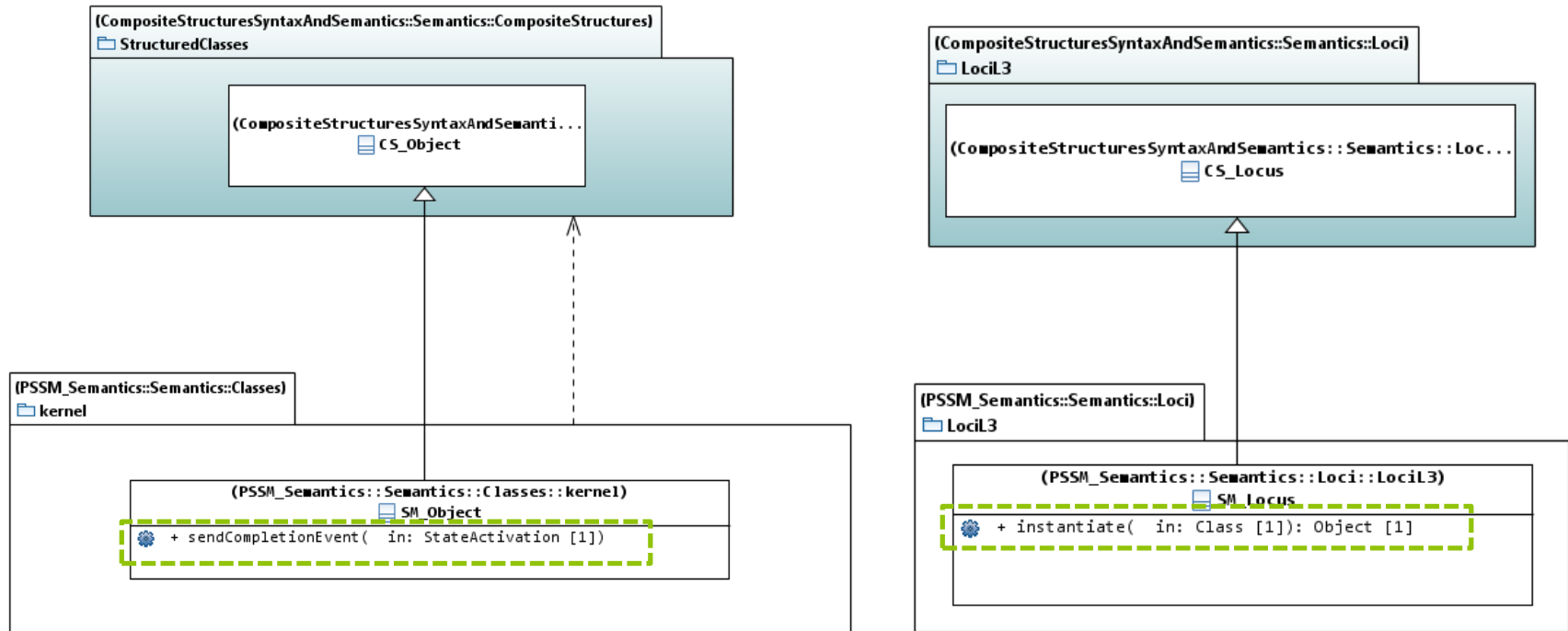
Principle

- A single acceptor is registered for the executed state-machine
- The match delegates to the transition selection process



Completion event

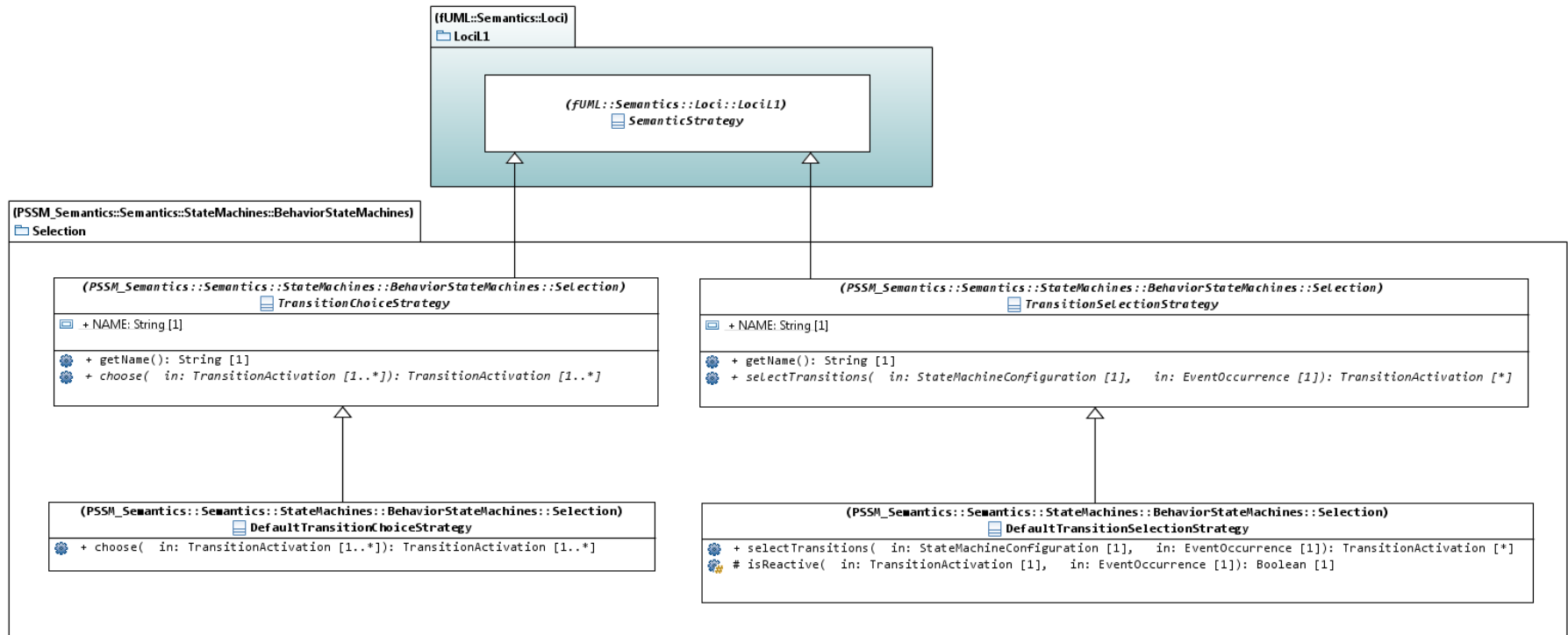
- Have priorities over events that are not completion event
- Dispatched in the order in which are they are placed in the pool
- Scope of the completion event is the event that generated it



Implied extensions

- “*SM_Object*” has the possibility to place completion events in its pool
- “*SM_Locus*” has its “instantiate” operation overridden to make sure that any class that is instantiated by PSSM leads to get an “*SM_Object*”

TRANSITIONS SELECTION



A. Transition selection

- Select a set of transitions that can be triggered by an event occurrence
- Selection is made based on the current stable configuration

B. Transition choice

- Reduce the set of transitions that can be fired
- A single transition or a set of transitions located in orthogonal regions

```
public List<TransitionActivation> selectTransitions(StateMachineConfiguration configuration, EventOccurrence eventOccurrence) {
    // Find for the given configuration the set of transition that can fire.
    // The search starts from the deepest level. If no transition enabled are found at this level
    // then the search continue in the upper level. The search stops when at given level a not empty
    // set of enabled transition is calculated. Transition returned are only those that are not triggered by an event
    // (i.e. Transitions that are automatic or only guarded).
    List<TransitionActivation> fireableTransition = new ArrayList<TransitionActivation>();
    Map<Integer, List<VertexActivation>> cartography = configuration.getCartography();
    int i = cartography.size();
    boolean nextLevel = true;
    while(i >= 1 && nextLevel){
        for(VertexActivation vertexActivation : cartography.get(i)){
            for(TransitionActivation transitionActivation : vertexActivation.getOutgoingTransitions()){
                if(this.isReactive(transitionActivation, eventOccurrence)){
                    fireableTransition.add(transitionActivation);
                }
            }
        }
        if(!fireableTransition.isEmpty()){
            nextLevel = false;
        }else{
            i--;
        }
    }
    return fireableTransition;
}
```

Principle

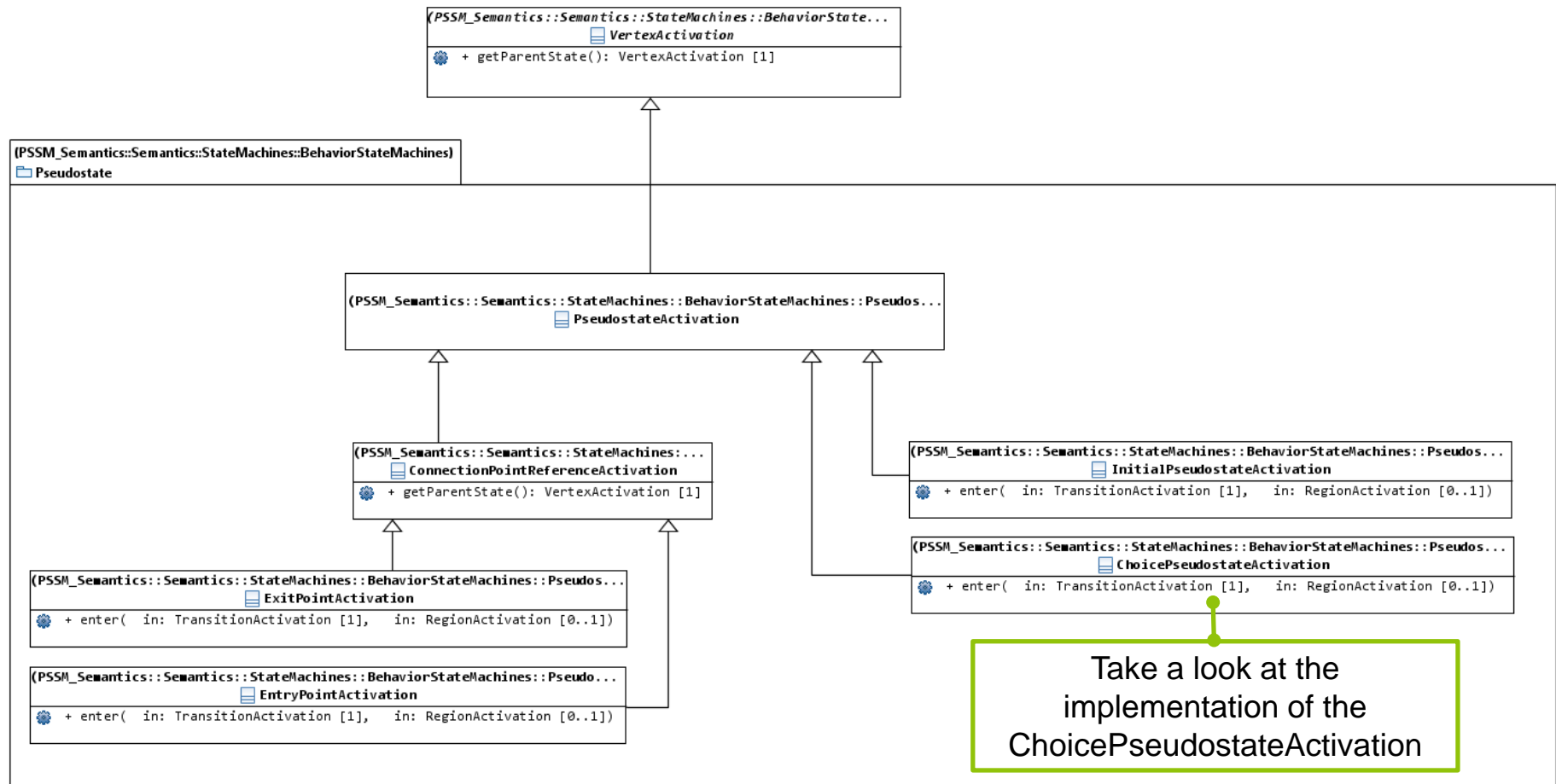
- Analysis starts from the lowest level of the hierarchy
- Collect all fireable transitions located at this level
- If no fireable transition then move one level up
- Otherwise stop and returns the list of fireable transitions

```
@Override
public List<TransitionActivation> choose(List<TransitionActivation> transitionActivations) {
    // The purpose here is to choose among a set of transition that a subset that will
    // effectively be fired. This subset can contain in the most trivial case a single
    // transition. In the case of orthogonal region it can contain several transitions
    // that will be fired using the same event occurrence
    if(transitionActivations.isEmpty()){
        return new ArrayList<TransitionActivation>();
    }else{
        List<List<TransitionActivation>> chosenTransitions = new ArrayList<List<TransitionActivation>>();
        int i = 0;
        while(i < transitionActivations.size()){
            TransitionActivation transition = transitionActivations.get(i);
            List<TransitionActivation> targetSet = this.getTargetSet(transitionActivations.get(i), chosenTransitions);
            if(targetSet==null){
                targetSet = new ArrayList<TransitionActivation>();
                targetSet.add(transition);
                chosenTransitions.add(targetSet);
            }else{
                targetSet.add(transition);
            }
            i++;
        }
        ChoiceStrategy choiceStrategy = new FirstChoiceStrategy();
        int choice = choiceStrategy.choose(chosenTransitions.size() - 1);
        return chosenTransitions.get(choice);
    }
}
```

Principle

- Based on the selection, find out which transitions will actually be fired
- Transitions in different orthogonal regions are grouped in the same set.
- The final choice is delegated to ChoiceStrategy provided by fUML

PSEUDO STATES: ENTRY / EXIT / CHOICE

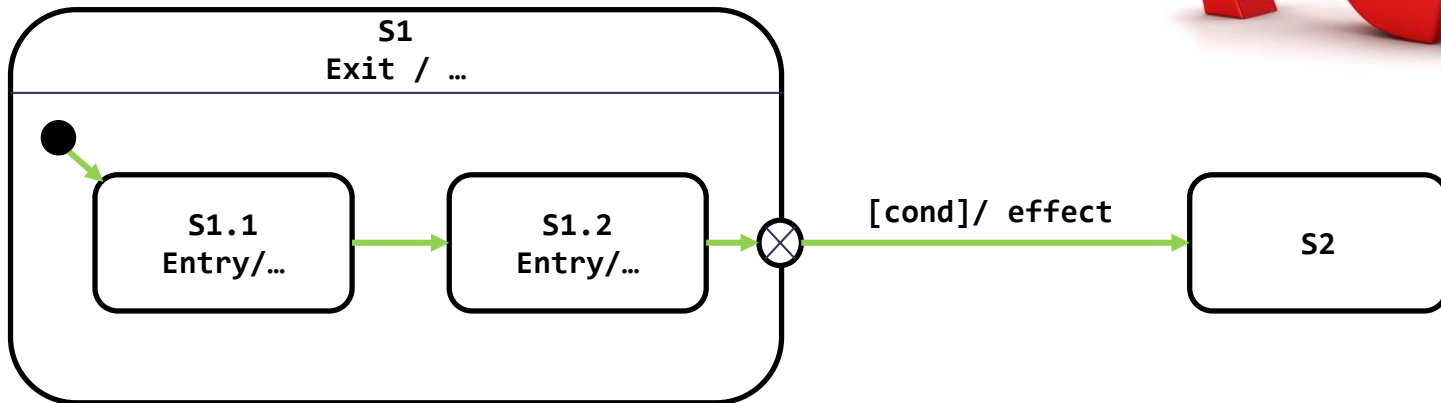


Note

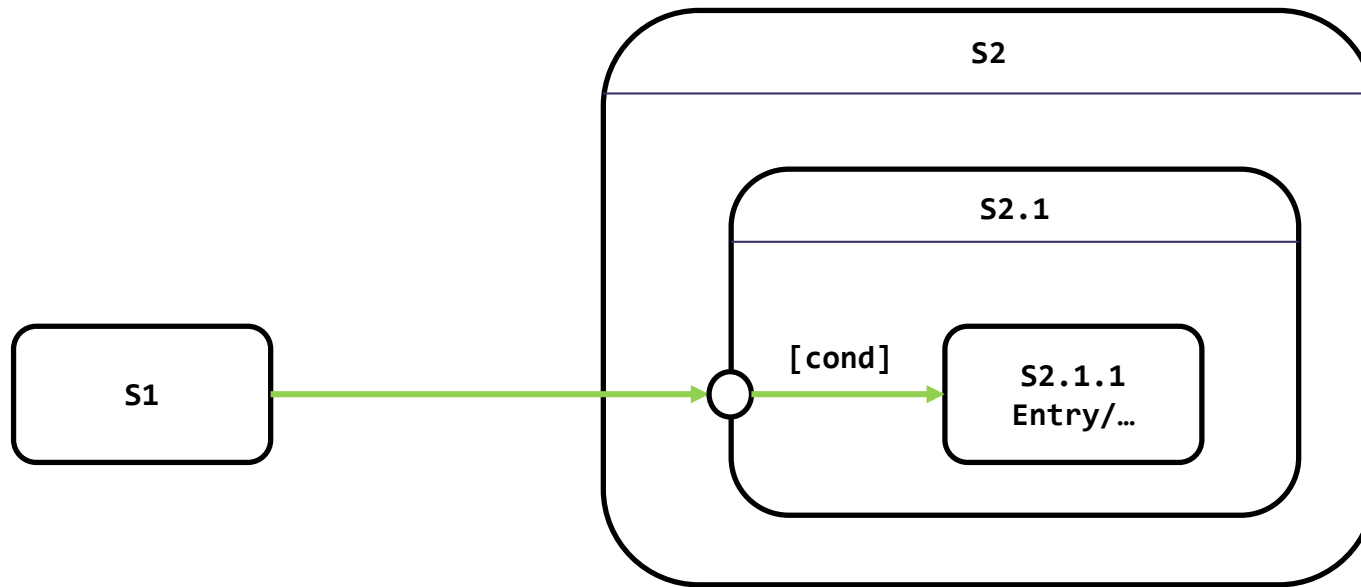
- Recurrent pattern to define a visitor for a pseudo-state
- Each pseudo-state visitor must override the “enter” operation

Transitions originating from entry and exit points

- Can have guards
- Can have an effect



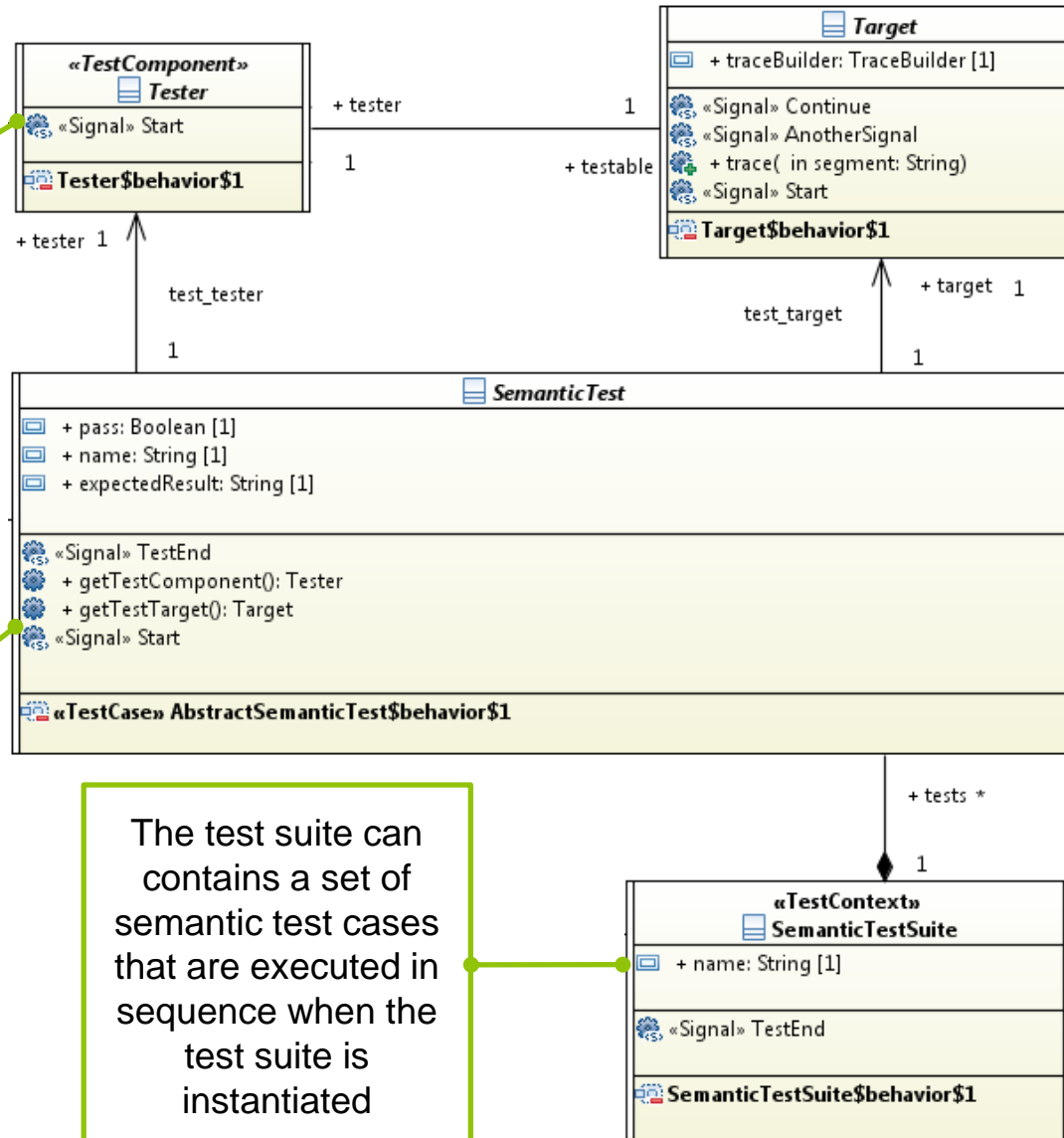
- What should occur in the situation where “cond” is false ?
 - S1 remains the in the configuration
 - The propagation of the execution stops
- Do we need to add modeling constraints ?
 - At least one of the of the guard of the outgoing transitions must be true. If it is not then the model should be considered as being ill-formed.



- What should occur in the situation in which “cond” is false ?
 - S2 is entered
 - S2.1 is entered
 - S2.1 is treated a simple state



TEST SUITE

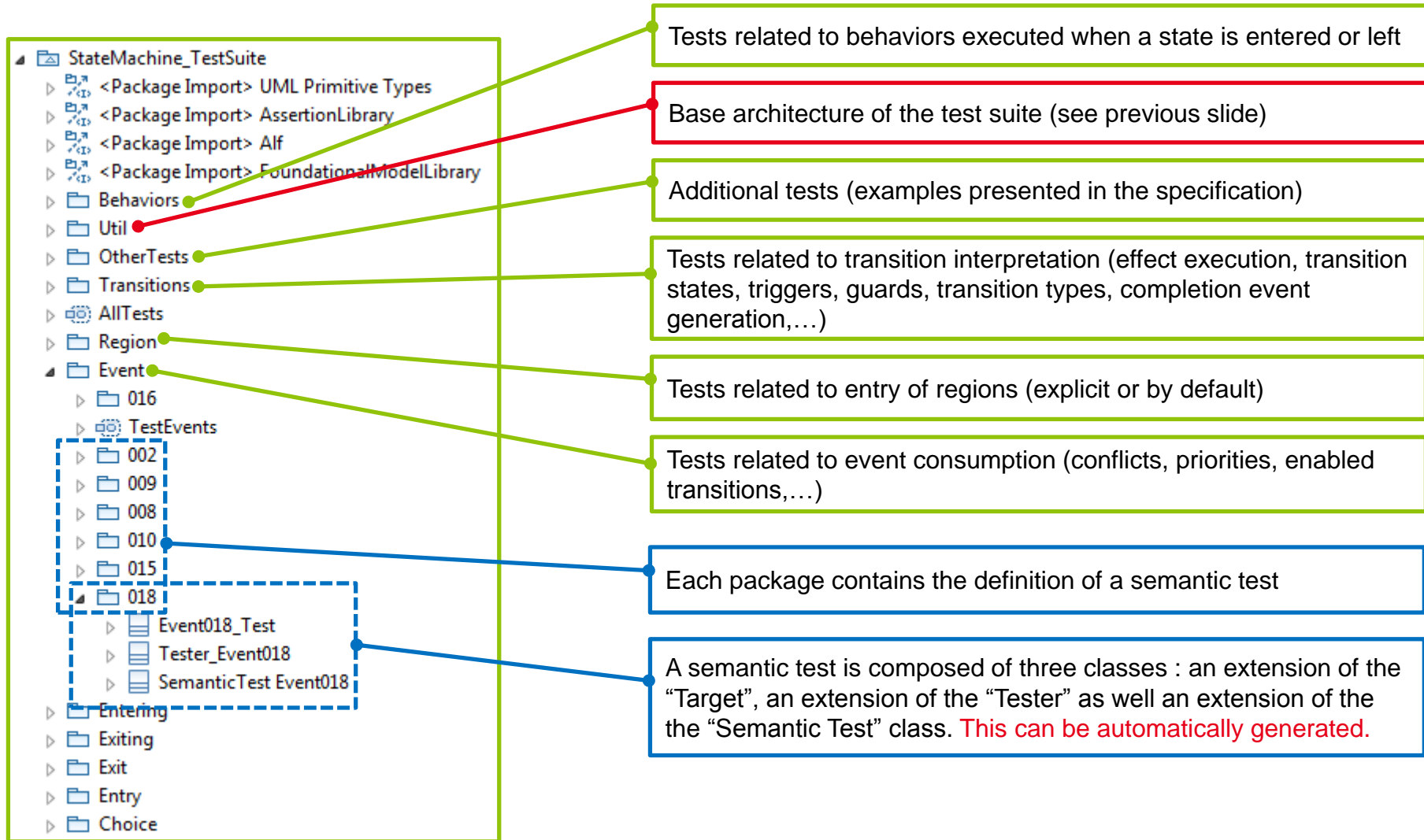


The test component formalizes the stimulation sequence that is received by the test target

Formalizes the test case that controls both the test component and the test target. It also computes the test verdict using trace comparison

The test suite can contains a set of semantic test cases that are executed in sequence when the test suite is instantiated

The test target. This part contains the state-machine that is actually executed to validate part of the semantics



Main entry point

namespace StateMachine_TestSuite;

```
activity AllTests() {
  Behaviors::Behaviors();
  Transitions::Transitions();
  OtherTests::OtherTests();
  Event::TestEvents();
  Entering::TestsEntering();
  Exiting::TestsExiting();
  Exit::TestsExit();
  Entry::TestsEntry();
  Choice::TestsChoice();
}
```

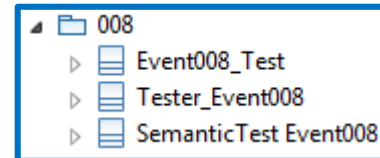
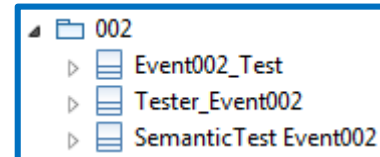
namespace StateMachine_TestSuite::Event;

```
private import StateMachine_TestSuite::Util::Architecture::SemanticTestSuite;
private import StateMachine_TestSuite::Util::Architecture::SemanticTest;
```

```
private import '002'::'SemanticTest Event002';
private import '008'::'SemanticTest Event008';
```

```
activity TestEvents() {
  let name : String = "Events";
  let tests : SemanticTest = new SemanticTest[]{};
  /*Event002*/
  e002 = new 'SemanticTest Event002'();
  e002.name = "Event002";
  e002.expectedResult = "S1(entry)::S1.1(entry)::S1(exit)";
  tests->add(e002);
  /*Event008*/
  e008 = new 'SemanticTest Event008'();
  e008.name = "Event008";
  e008.expectedResult = "T2(effect)::T3(effect)";
  tests->add(e008);
  /*Test suite*/
  suite = new SemanticTestSuite(tests, name);
}
```

“expectedResult” defines the trace that is expected as result of the test. **Note:** in the future it will be changed to be a set defining possible traces.

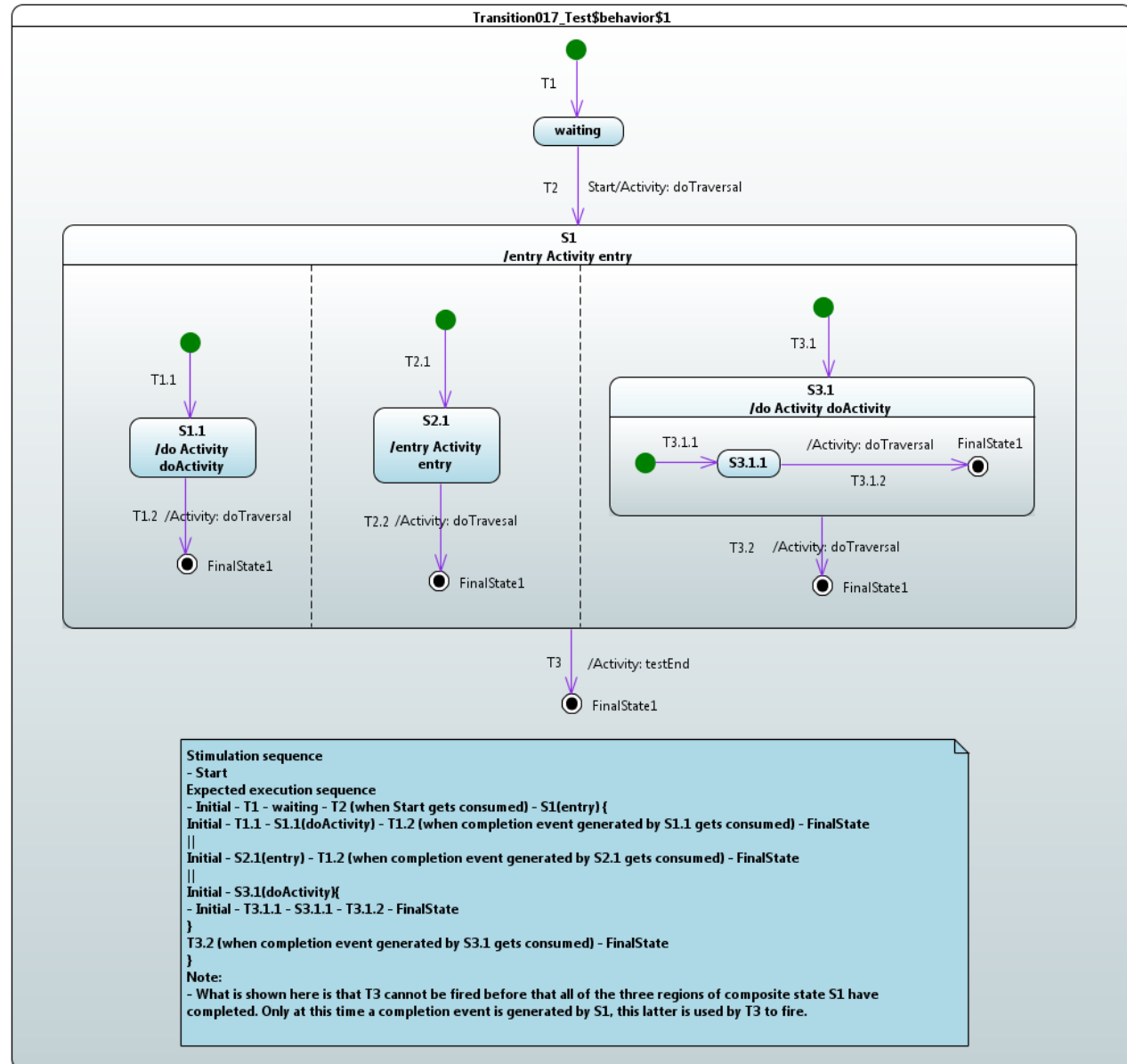


TESTS REVIEW

ONE TEST PER CATEGORY - ILLUSTRATE HOW IT WORKS

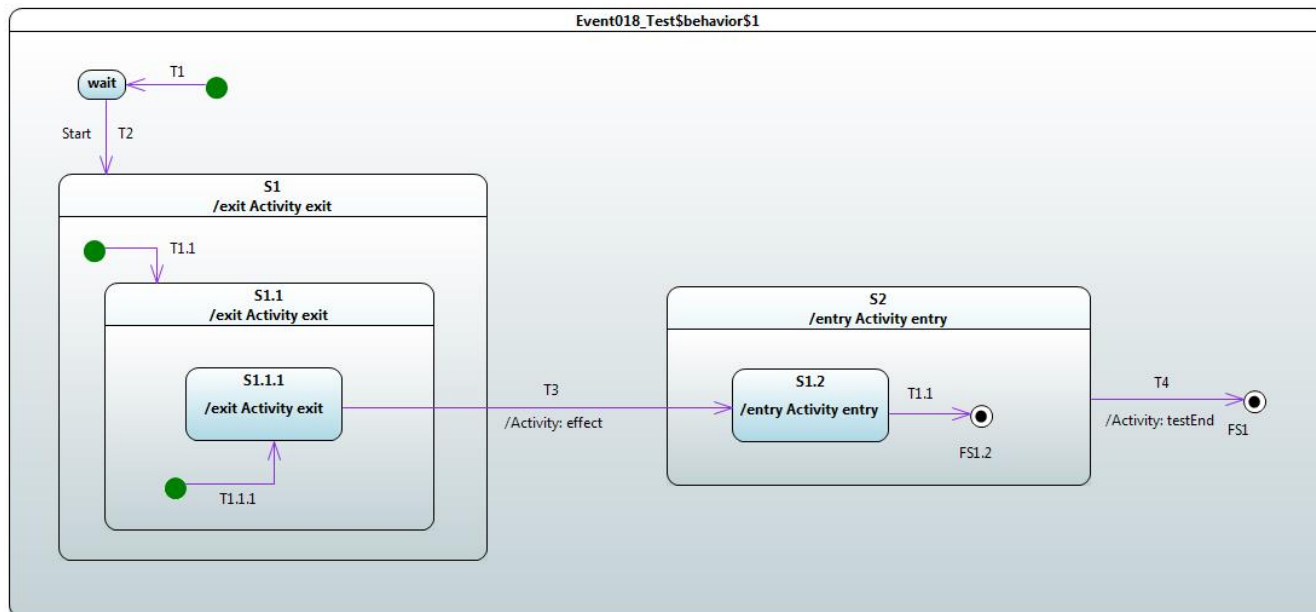
Requirement

For composite States, a completion event is generated under the following circumstances: All internal activities (e.g., entry and doActivity Behaviors) have completed execution, and all its orthogonal Regions have reached a FinalState. (p.328 - 329)



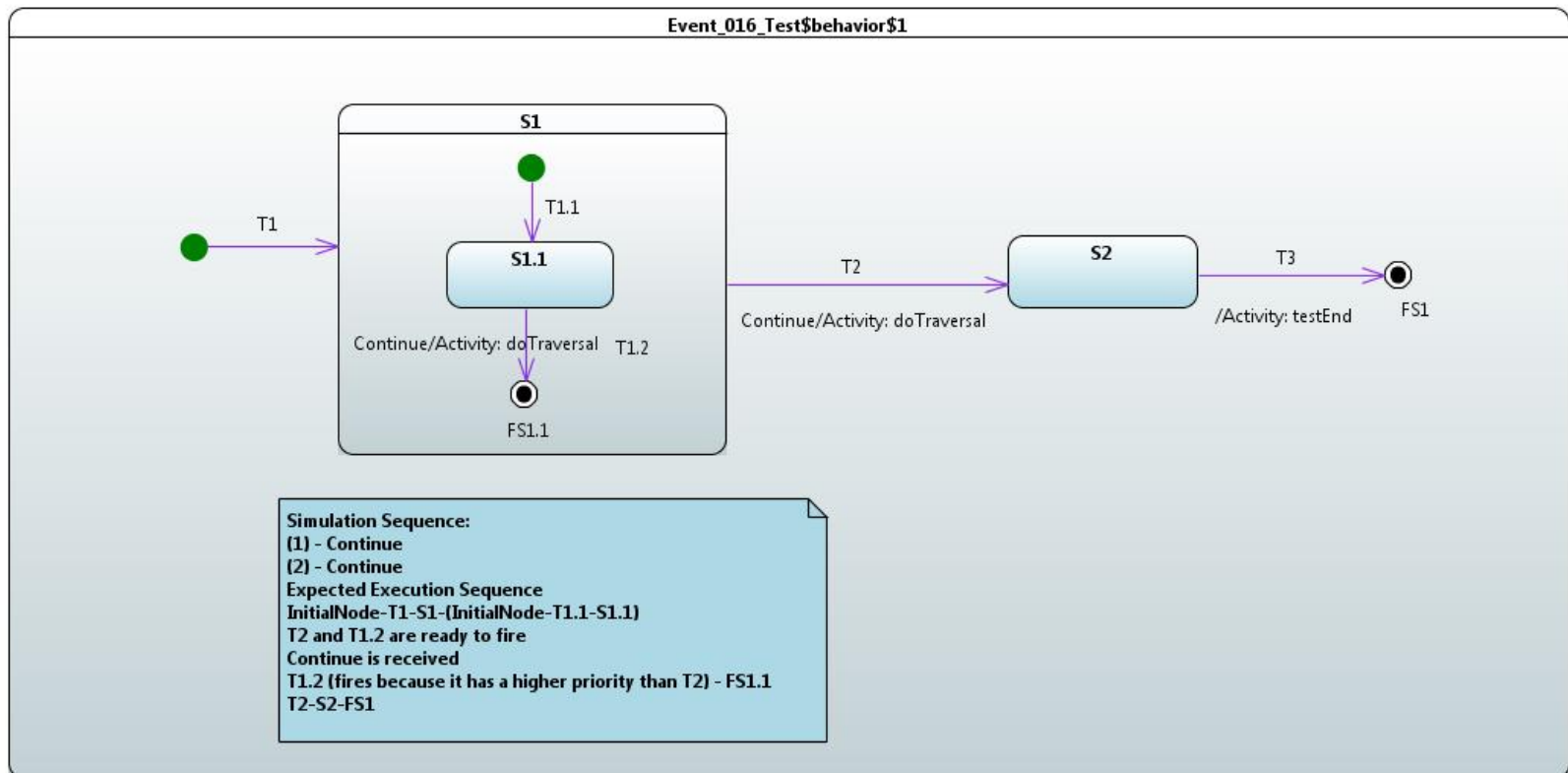
Requirement

Once a Transition is enabled and is selected to fire, the following steps are carried out in order: 1. Starting with the main source State, the States that contain the main source State are exited according to the rules of State exit (or, composite State exit if the main source State is nested) as described earlier. 2. The series of State exits continues until the first Region that contains, directly or indirectly, both the main source and main target states is reached. The Region that contains both the main source and main target states is called their least common ancestor. At that point, the effect Behavior of the Transition that connects the sub-configuration of source States to the sub-configuration of target States is executed. (A “sub-configuration” here refers to that subset of a full state configuration contained within the least common ancestor Region.) 3. The configuration of States containing the main target State is entered, starting with the outermost State in the least common ancestor Region that contains the main target State. The execution of Behaviors follows the rules of State entry (or composite State entry) described earlier. (p.331)



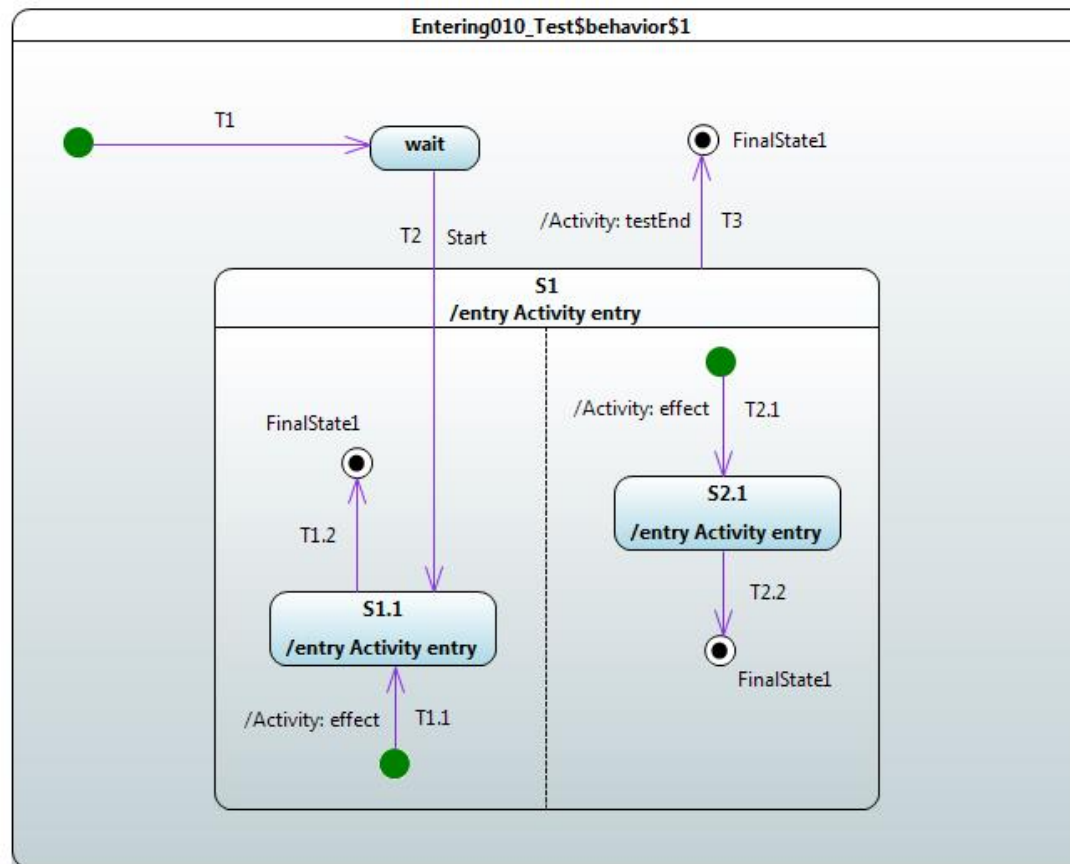
Requirement

In situations where there are conflicting Transitions, the selection of which Transitions will fire is based in part on an implicit priority. These priorities resolve some but not all Transition conflicts, as they only define a partial ordering. The priorities of conflicting Transitions are based on their relative position in the state hierarchy. By definition, a Transition originating from a substate has higher priority than a conflicting Transition originating from any of its containing States. The priority of a Transition is defined based on its source State. (p.331)



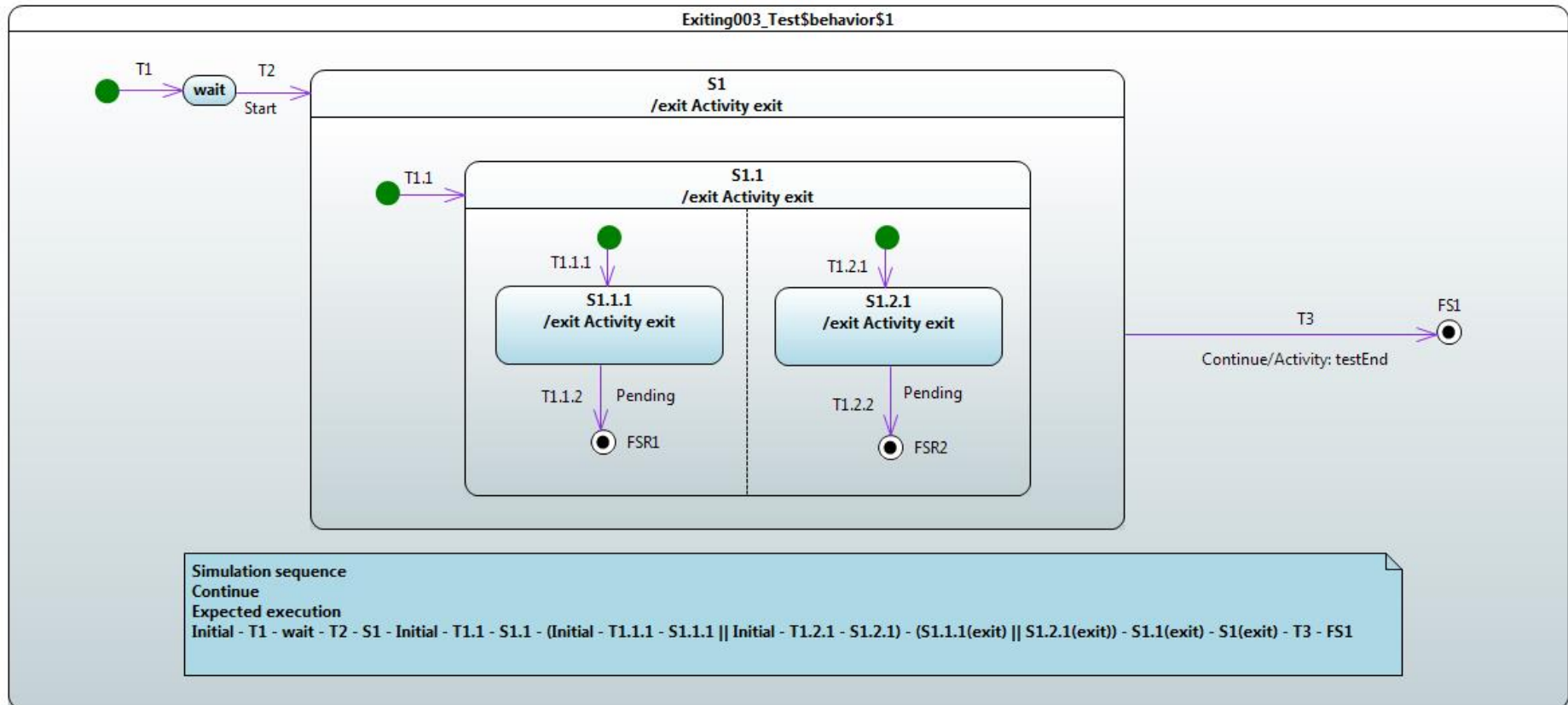
Requirement

If the composite State is also an orthogonal State with multiple Regions, each of its Regions is also entered, either by default or explicitly. (p.324)



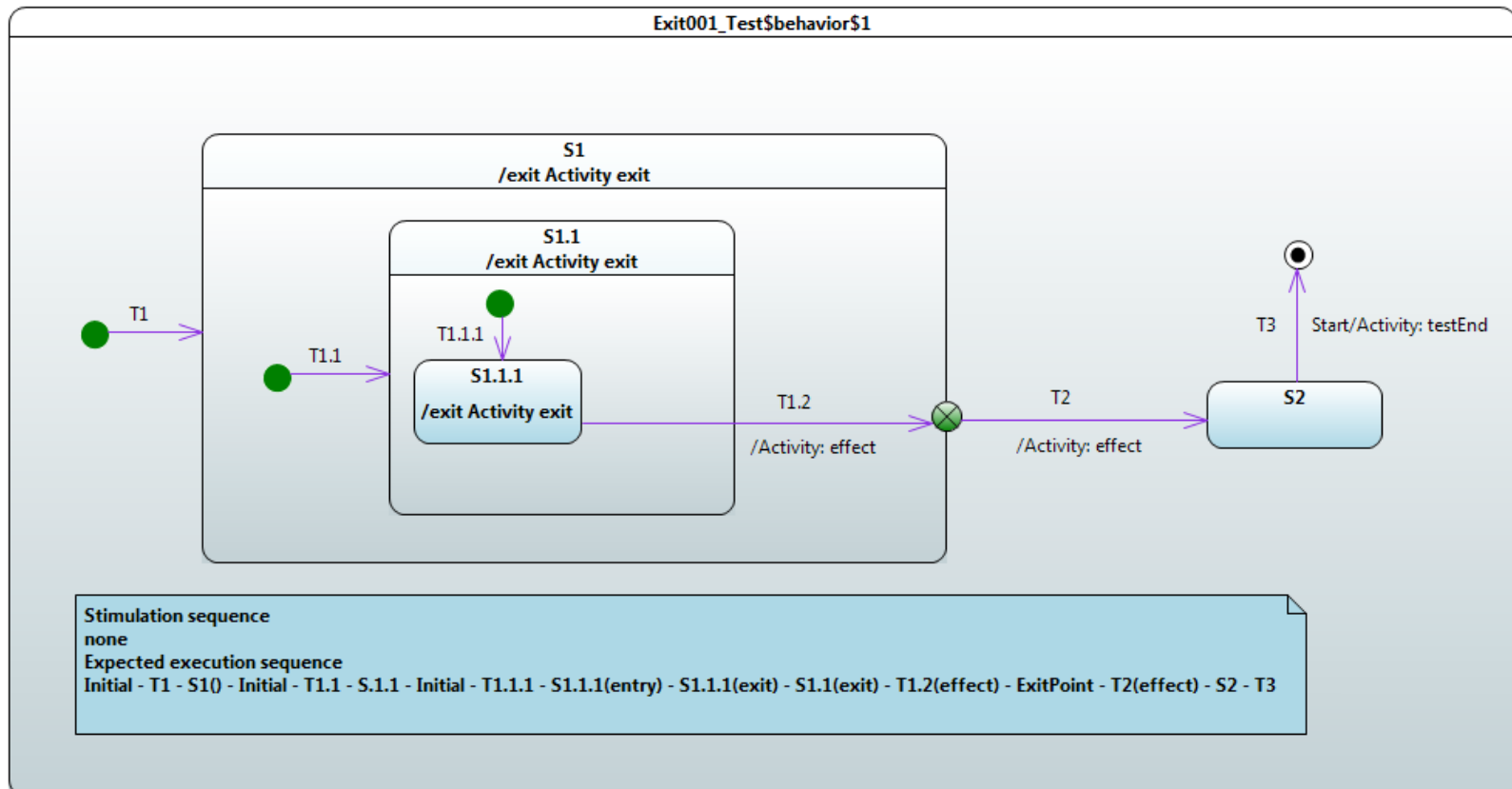
Requirement

When exiting from a composite State, exit commences with the innermost State in the active state configuration. This means that exit Behaviors are executed in sequence starting with the innermost active State. (p.324)



Requirement

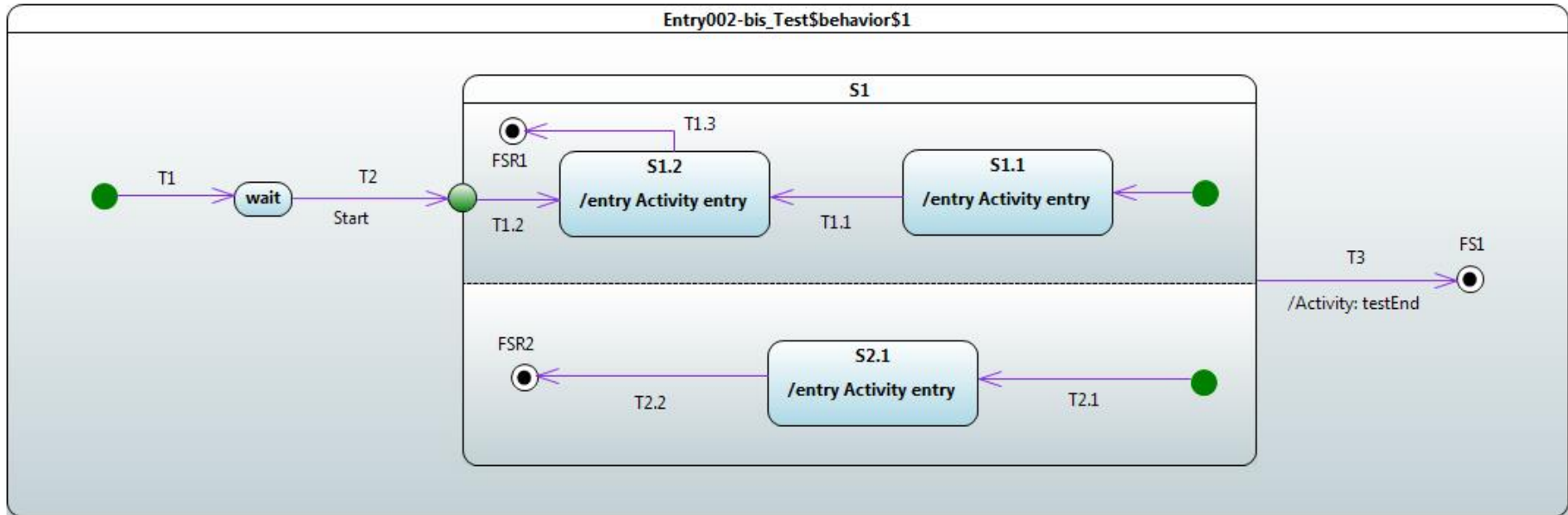
Transitions terminating on an exit point within any Region of the composite State implies exiting of this composite (with execution of its associated exit Behavior).
(p.327)



Requirement

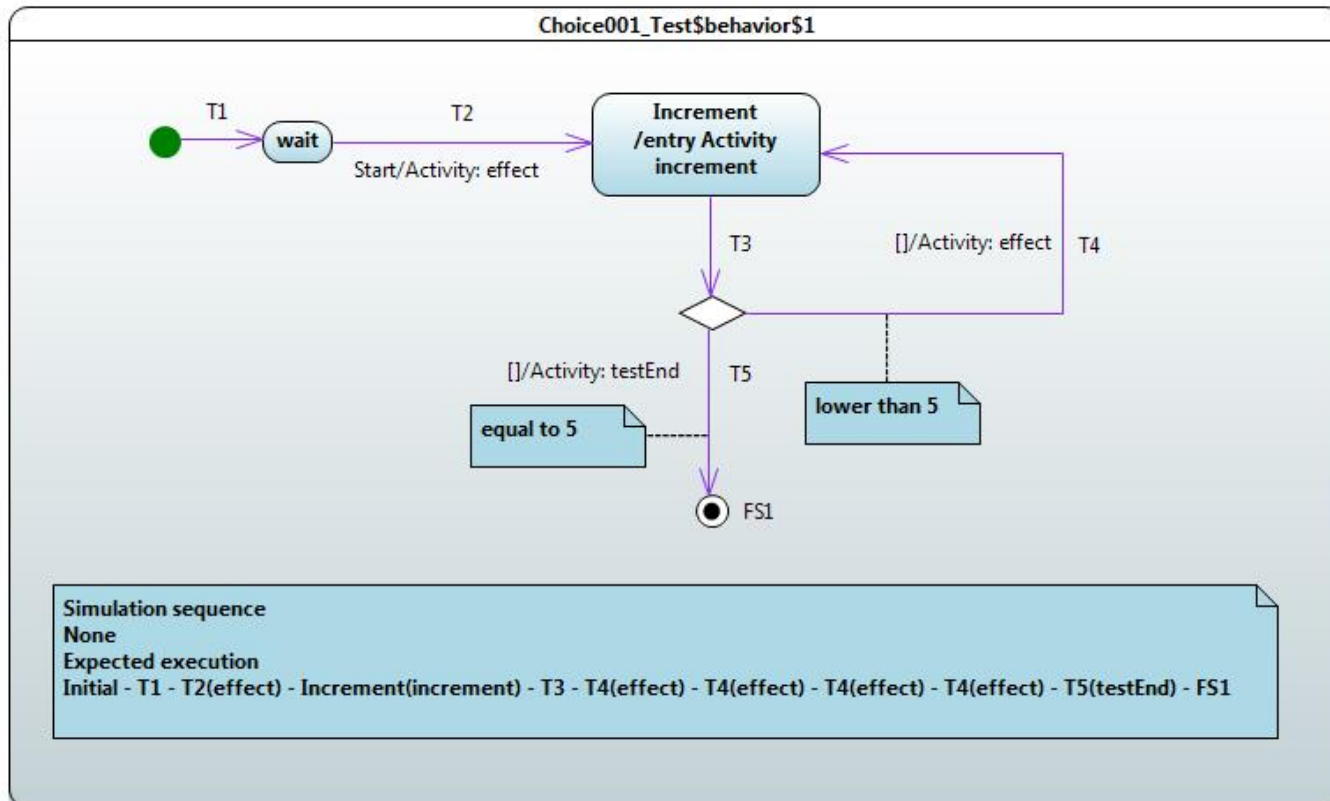
If the owning State has an associated entry Behavior, this Behavior is executed before any behavior associated with the outgoing Transition.

If multiple Regions are involved, the entry point acts as a fork Pseudostate



Requirement

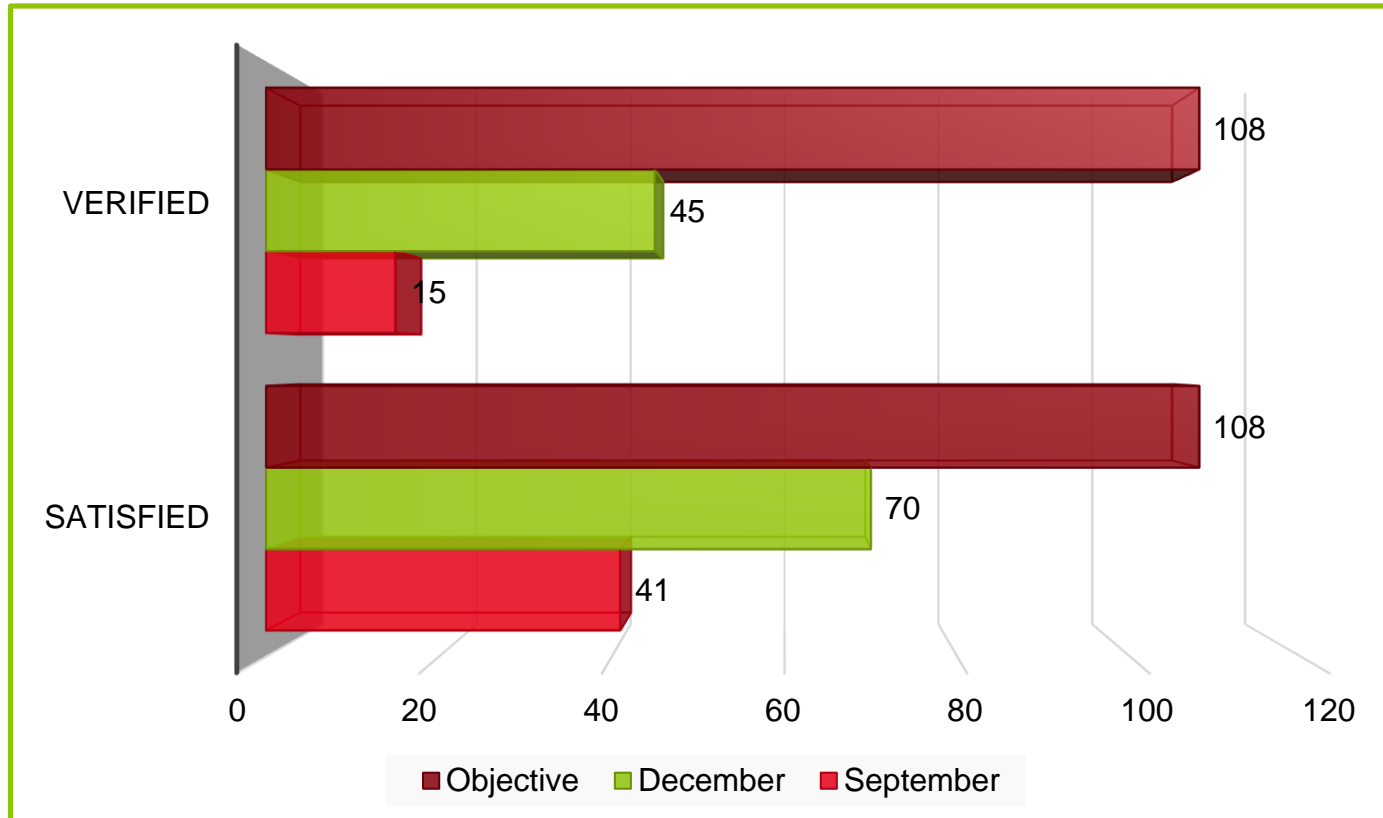
The guard Constraints on all outgoing Transitions are evaluated dynamically, when the compound transition traversal reaches this Pseudostate (p.327)



DEMO

GENERAL ASSESSEMENT

PROGRESS EVALUATION FROM LAST MEETING & OBJECTIVES FOR SUBMISSION



Notes

- Tested requirements: +30
 - Effort to consolidate existing prototype
- Satisfied requirements: + 29
- Some time allocated to move from fUML 1.1 to fUML 1.2

A. From mandatory requirements point of view

- Local transitions
- Deferred events
- History (shallow and deep)
 - Require a significant effort
- Fork
- Join
- Terminate
- Junction
 - Require a significant effort

Scope – Initial submission deadline



B. From the extra requirements point of view

- Call events
- Sub-machines

After initial submission

C. From the test suite point of view

- Test suite can be execute using an asynchronous implementation
 - Test results must be a set of possible traces
 - Require a significant effort to refactor

After initial submission

