

# Exercises<sup>1</sup>

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<sup>1</sup>HMS, 2021, v1.1

## Exercise 1: Find the bug in this model

Find the bugs in this model

```
import tellurium as te

r = te.loada ('''
    $Xo -> S1;  k1*$Xo;
    S2 -> S3;  k2*S1;
    S3 -> $X1; k3*S2;

    Xo = 10; k1 = 0.4; k2 = 0.23; k3 = 0.13;
''')

m = r.simulate (0, 60, 100)
r.plot()
```

1. Run a simulation from 0 to 60
2. What do you observe? Do you think the simulation is correct?
3. If not, where is the bug(s) in the model?

## Exercise 2: Basic Concepts

Consider the following model and answer the questions.

```
import tellurium as te

r = te.loada ('''
    $Xo -> S1;  k1*Xo;
    S1 -> S2;  k2*S1;
    S2 -> $X1; k3*S2;

    Xo = 10; k1 = 0.4; k2 = 0.23; k3 = 0.13;
''')
```

1. Identify the boundary species
2. Identify the floating species
3. Run a simulation from 0 to 60 time units

## Exercise 3: Steady State

Setting and getting values:

```
import tellurium as te

r = te.loada('''
    $Xo -> S1; k1*Xo;
    S1 -> S2; k2*S1;
    S2 -> $X1; k3*S2;

    Xo = 10; k1 = 0.4; k2 = 0.23; k3 = 0.13;
''')
```

1. Run a simulation from 0 to 60 using 100 points
2. What is happening towards the end of the simulation to S1 and S2?
3. Type `r.getRatesOfChange()` at the **console**, what do you see?
4. Type `r.getFloatingSpeciesIds()` at the **console**, the order of the names correspond to the order in the `getRatesOfChange` array.
5. Type `r.steadyState()` to compute the steady state directly.

## Exercise 4: Set, get and reset values

Setting and getting values:

```
import tellurium as te

r = te.loada('''
    $Xo -> S1;  k1*Xo;
    S1 -> S2;  k2*S1;
    S2 -> $X1; k3*S2;

    Xo = 10; k1 = 0.4; k2 = 0.23; k3 = 0.13;
''')
```

1. Type the following at the console: `r.Xo = r.Xo * 4`?
2. Enter `m = r.simulate (0, 60, 100)` at the **console**
3. Enter `r.plot()` at the **console**
4. What do you observe?
5. Type `r.S3` at the **console**

## Exercise 4: Set, get and reset values

How to reset a simulation

```
import tellurium as te
```

```
r = te.loada (''  
    $Xo -> S1;  k1*Xo;  
    S1 -> S2;  k2*S1;  
    S2 -> $X1; k3*S2;  
  
    Xo = 10; k1 = 0.4; k2 = 0.23; k3 = 0.13;  
    ''')
```

```
m = r.simulate (0, 60, 100)  
r.plot()  
# This resets all the floating species to their original values  
r.reset()
```

```
r.Xo = r.Xo * 5;  
m = r.simulate (0, 60, 100)  
r.plot()
```

## Exercise 5: Events

Applying Perturbations to a Model: Using the at syntax.

```
import tellurium as te

r = te.loada('''
    $Xo -> S1;  k1*Xo;
    S1 -> S2;  k2*S1;
    S2 -> $X1; k3*S2;

    Xo = 10; k1 = 0.4; k2 = 0.23; k3 = 0.13;
''')
```

1. Modify the model to also plot Xo as well as: time, S1 and S2
2. Add the statement: at (time > 20): Xo = 4\*Xo to the model
3. Run a simulation again from 0 to 60 time units

## Exercise 5: Events

Answer:

```
import tellurium as te

r = te.loada ('''
    $Xo -> S1; k1*Xo;
    S1 -> S2; k2*S1;
    S2 -> $X1; k3*S2;

    at (time > 20): Xo = 4*Xo

    Xo = 10; k1 = 0.4; k2 = 0.23; k3 = 0.13;
''')
m = r.simulate (0, 40, 100, ['time', 'S1', 'S2', 'Xo'])
r.plot()
```

Statements like `at()`: etc are called **events**



## Exercise 5: Events

1. Add another event: at (time > 30):  $X_o = X_o / 4$
2. Rerun the simulation

## Exercise 6: Tricks with Events

```
import tellurium as te

r = te.loada ('''

    Xo := sin ((time-10)*1.5*flag)

    $Xo -> S1; k1*Xo;
    S1 -> S2; k2*S1;
    S2 -> $X1; k3*S2;

    flag = 0
    at (time > 10): flag = 1

    k1 = 0.4; k2 = 0.23; k3 = 0.13;
''')
m = r.simulate (0, 40, 200, ['time', 'S1', 'S2', 'Xo'])
r.plot()
```

The syntax `Xo :=` etc means that this equation is **part of the model**

1. Run this model, explain what it is doing
2. Add this line to the model: `at (time > 20): flag = 0`

## Exercise 7: Tricks with Events: Delayed Ramp

```
import tellurium as te

r = te.loada ('''

    Xo := (time-10)*k*flag

    $Xo -> S1; k1*Xo;
    S1 -> S2; k2*S1;
    S2 -> $X1; k3*S2;

    flag = 0
    at (time > 10): flag = 1

    k = 0.5; k1 = 0.4; k2 = 0.23; k3 = 0.13;
''')
m = r.simulate (0, 40, 200, ['time', 'S1', 'S2', 'Xo'])
r.plot()
```

1. Run this model, explain what it is doing

## Exercise 8: Tricks with Events: Different Signals

```
import tellurium as te

r = te.loada('''
    # All waves have the following amplitude and period
    amplitude = 1
    period = 10

    # These events set the 'UpDown' variable to 1 or 0 according to the period.
    UpDown=0
    at sin(2*pi*time/period) > 0, t0=false: UpDown = 1
    at sin(2*pi*time/period) <= 0, t0=false: UpDown = 0

    # Simple Sine wave with y displaced by 3
    SineWave := amplitude/2*sin(2*pi*time/period) + 3

    # Square wave with y displaced by 1.5
    SquareWave := amplitude*UpDown + 1.5

    # Triangle waveform with given period and y displaced by 1
    TriangleWave = 1
    TriangleWave' = amplitude*2*(UpDown - 0.5)/period

    # Saw tooth wave form with given period
    SawTooth = amplitude/2
    SawTooth' = amplitude/period
    at UpDown==0: SawTooth = 0

    # Simple ramp
    Ramp := 0.03*time
''')
result = r.simulate(0, 90, 500)
r.plot()
```

### 1. Run this model