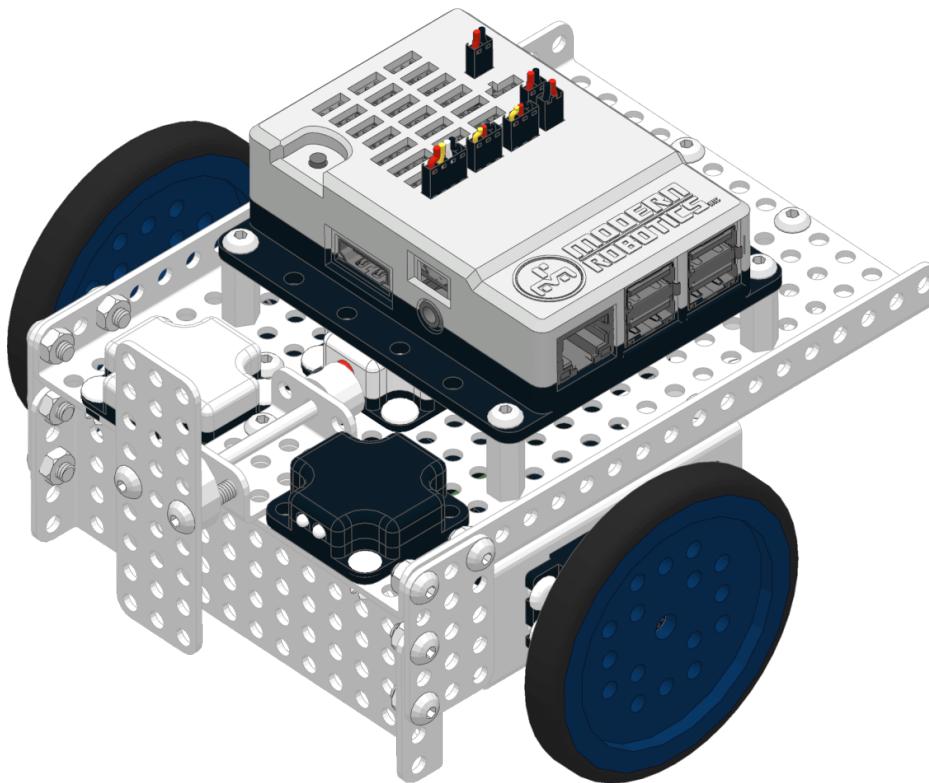
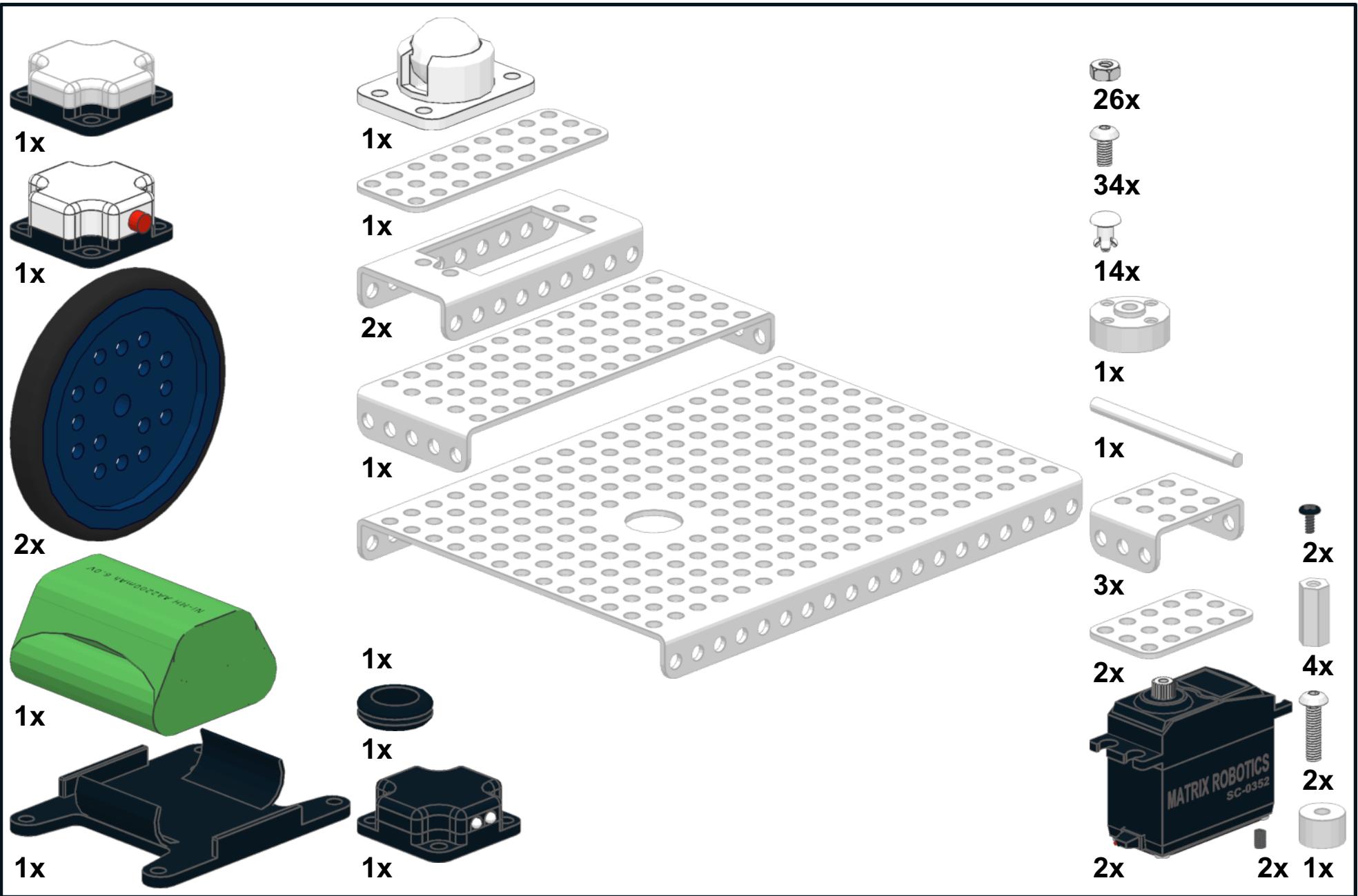
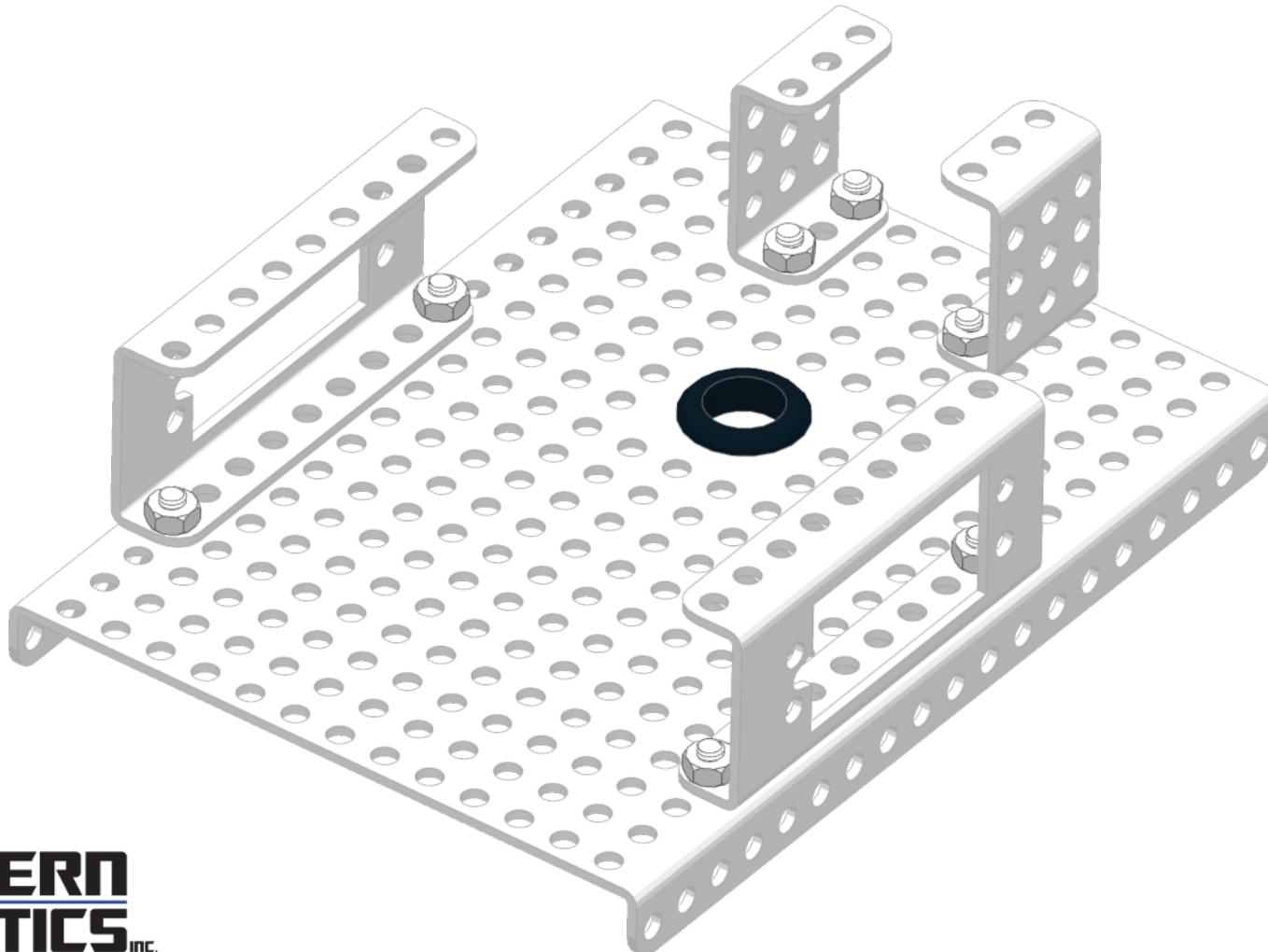
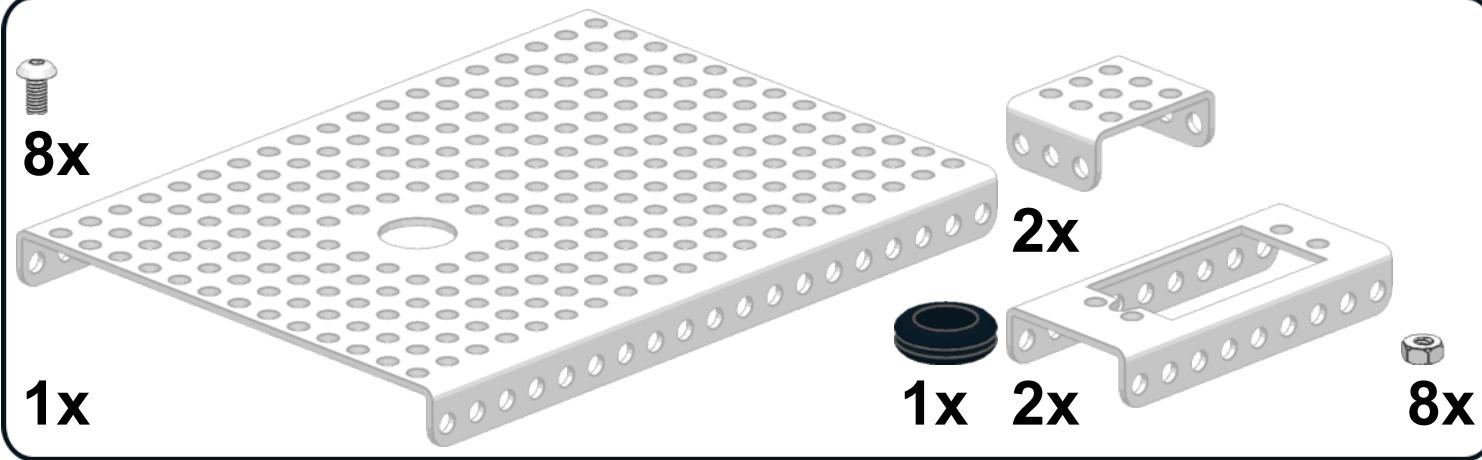


FUSION™ Base Robot Building Instructions



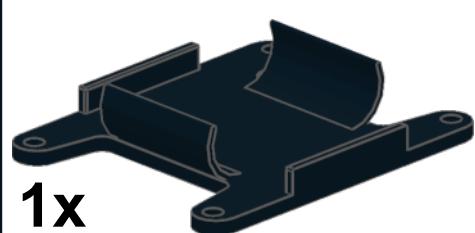


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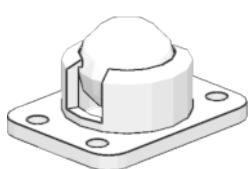
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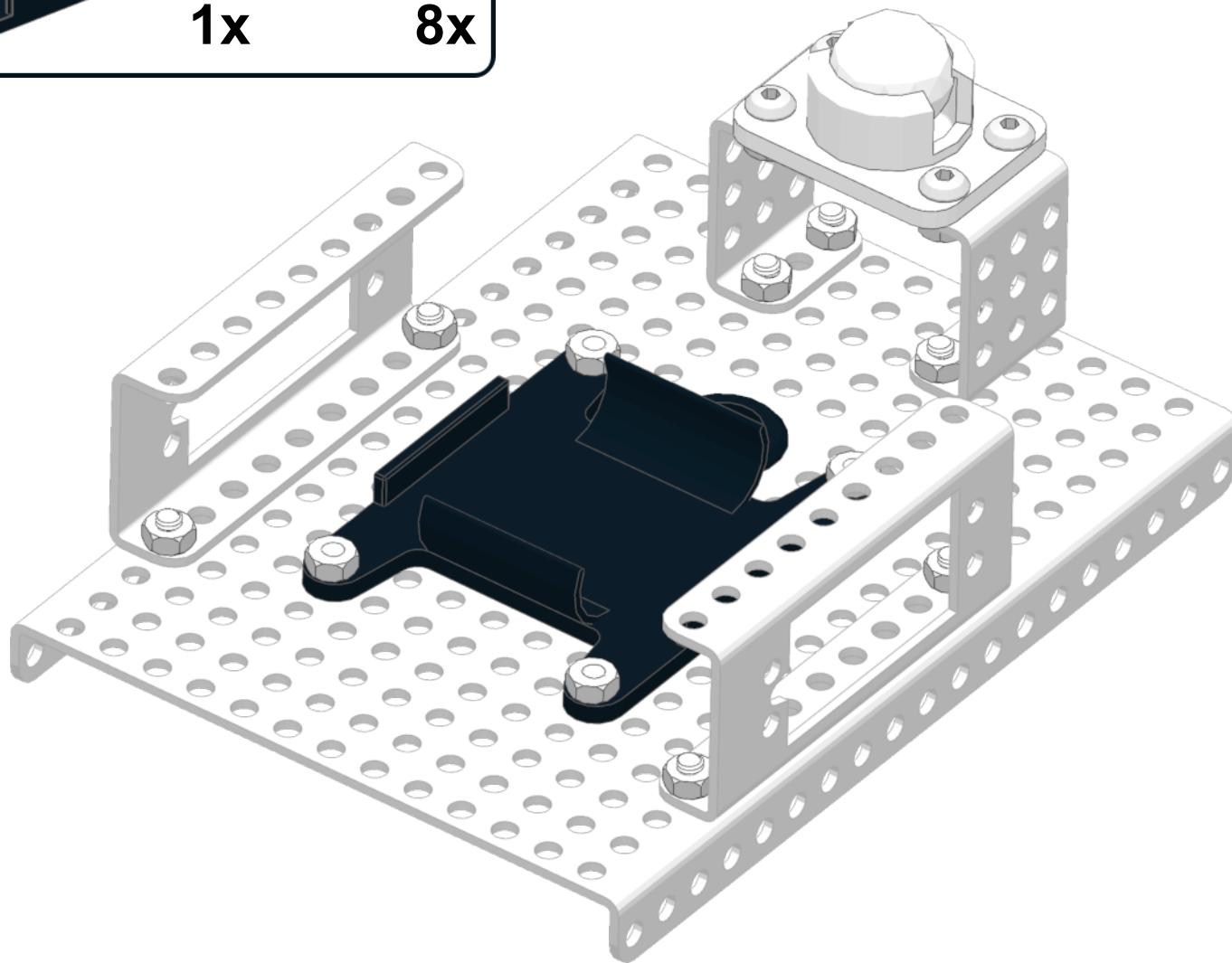
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1x



8x

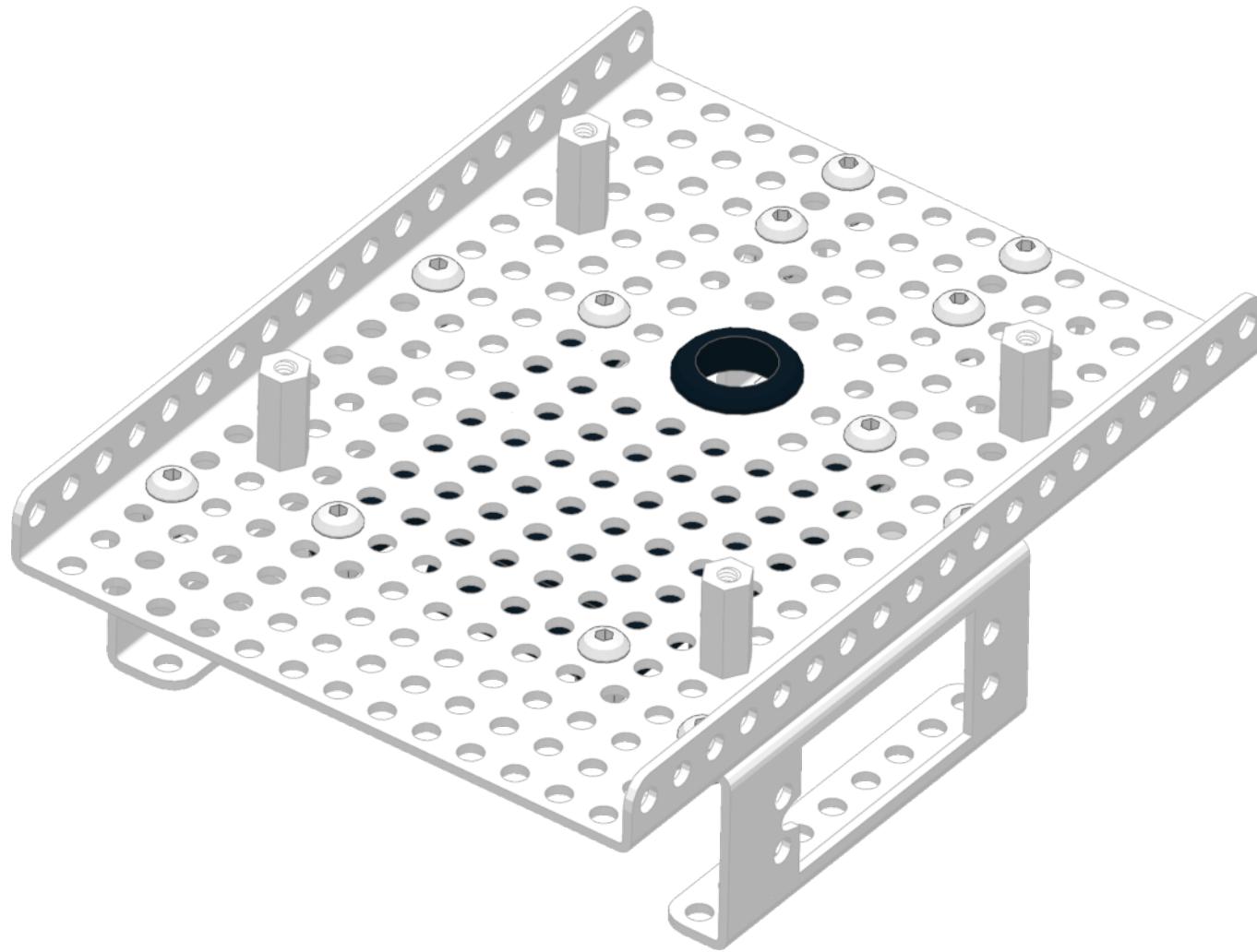
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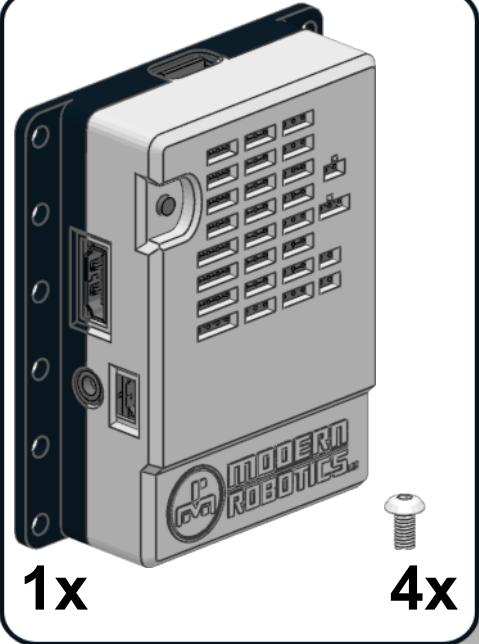
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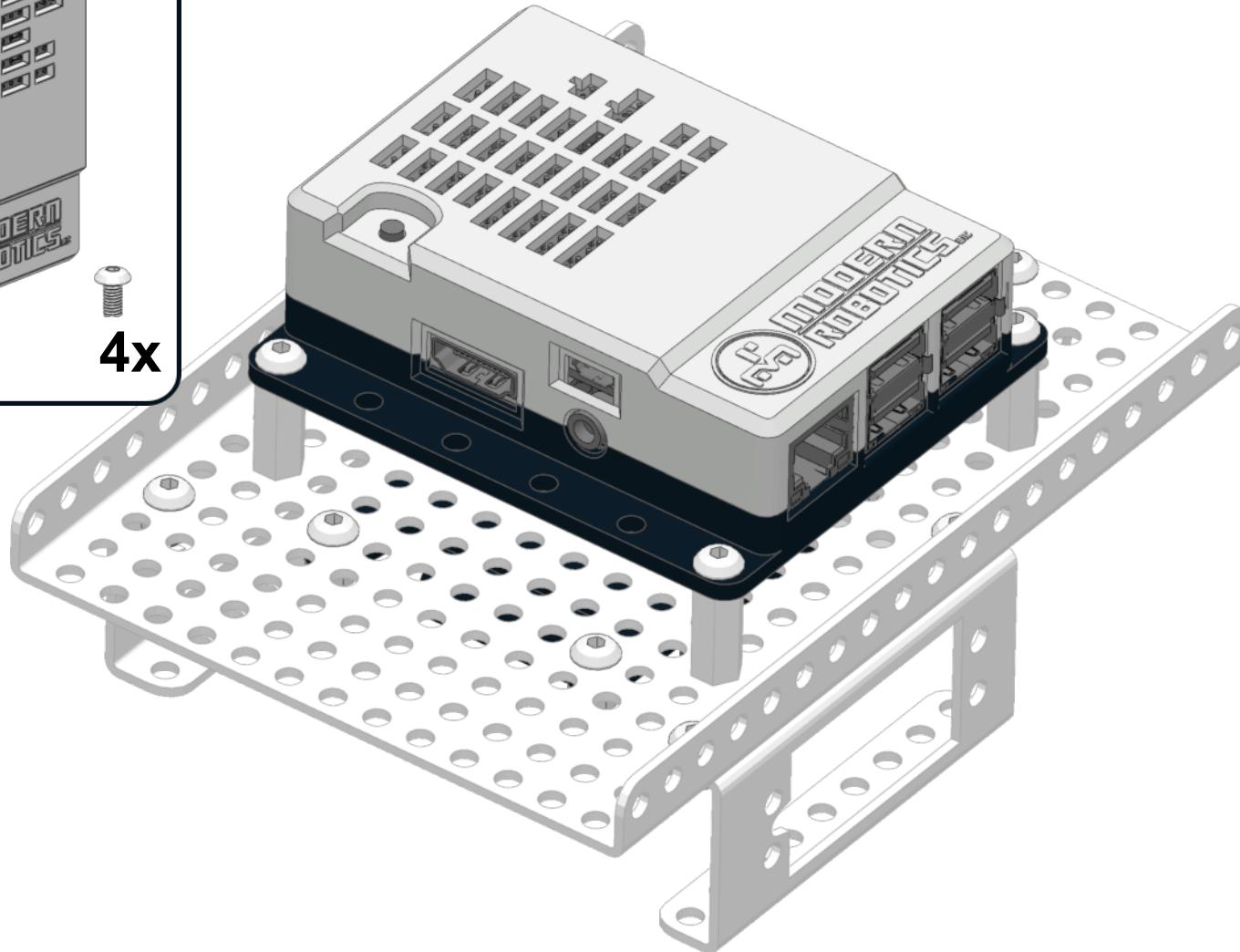
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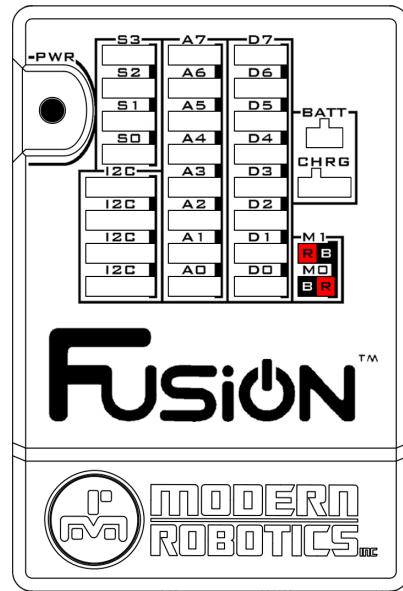
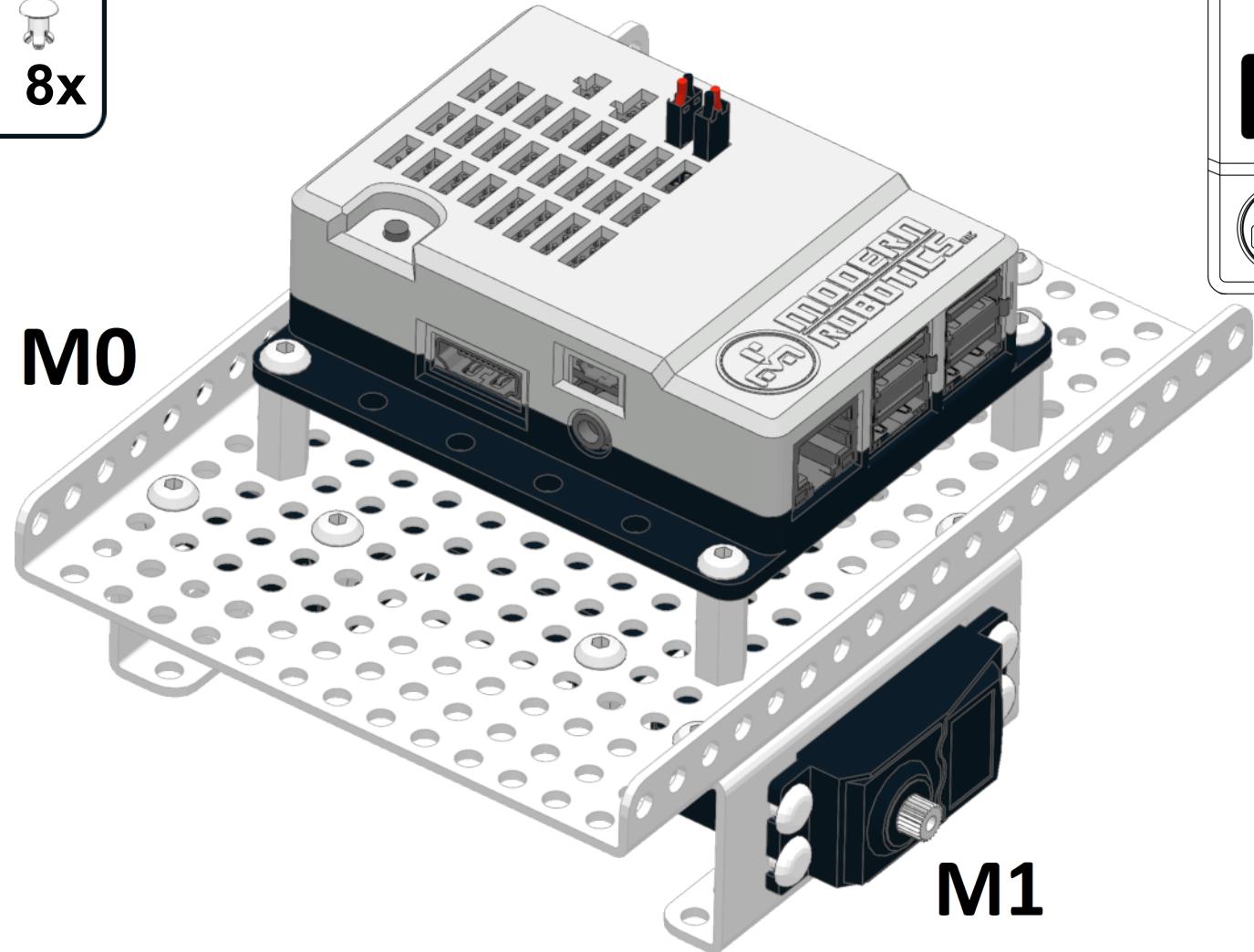
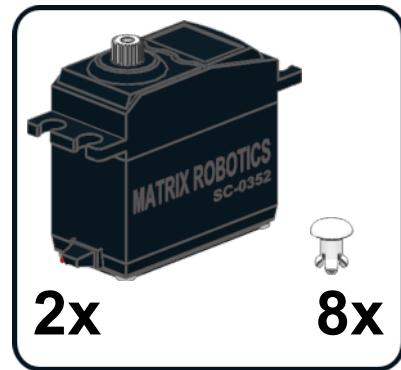
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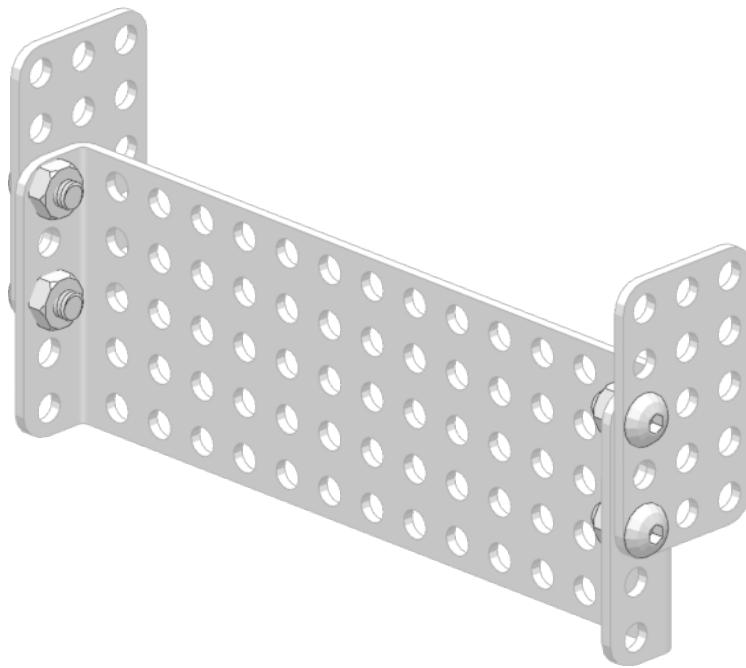
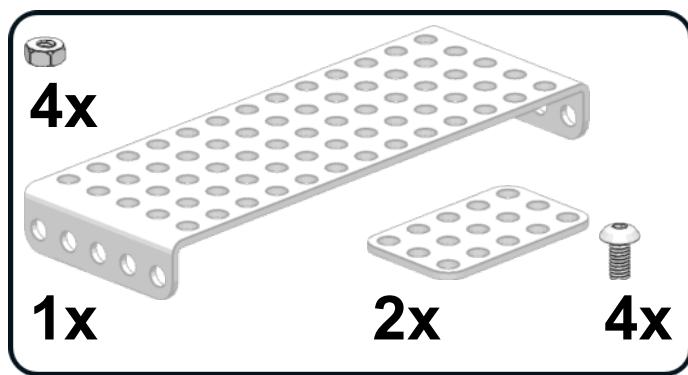


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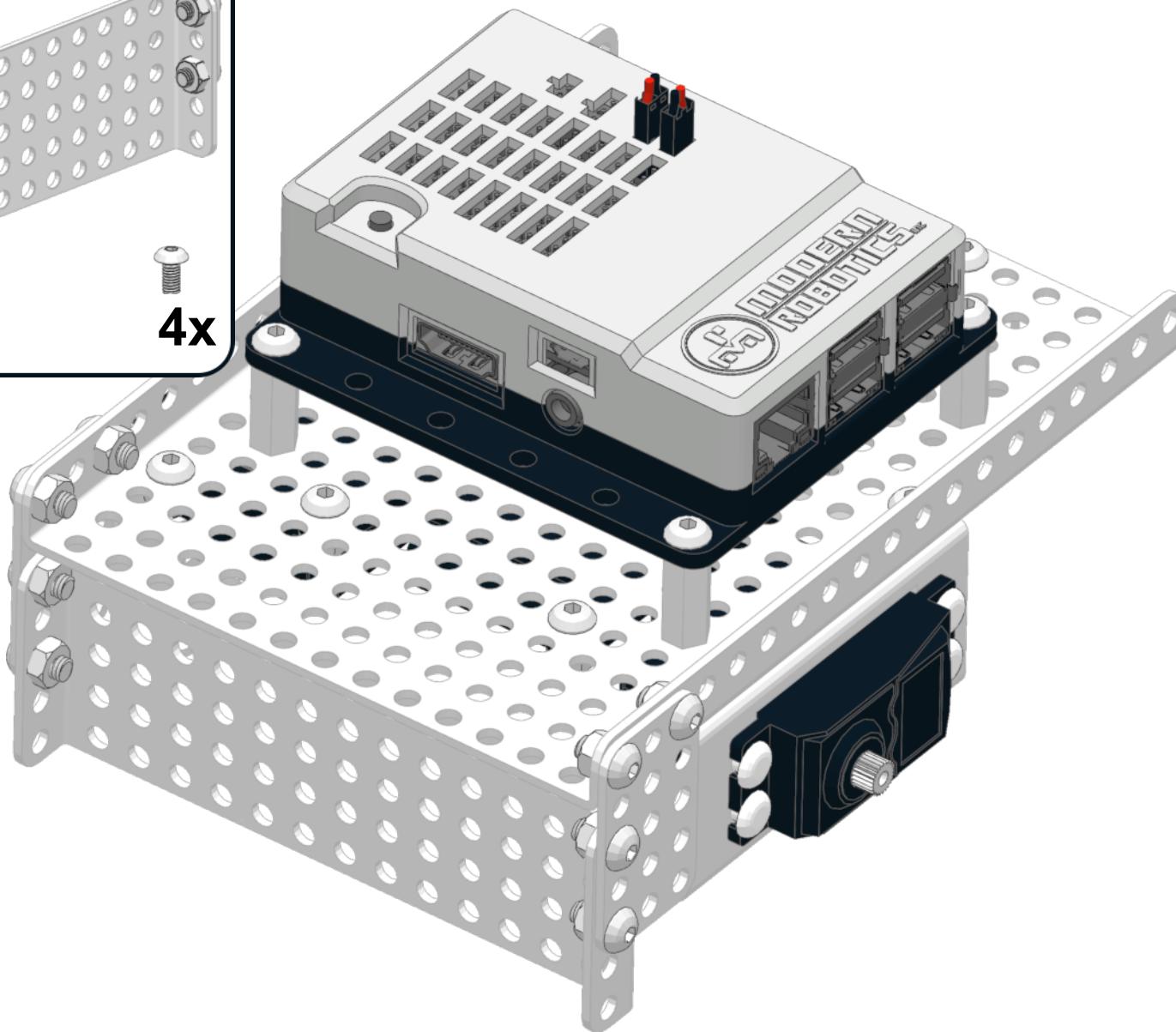
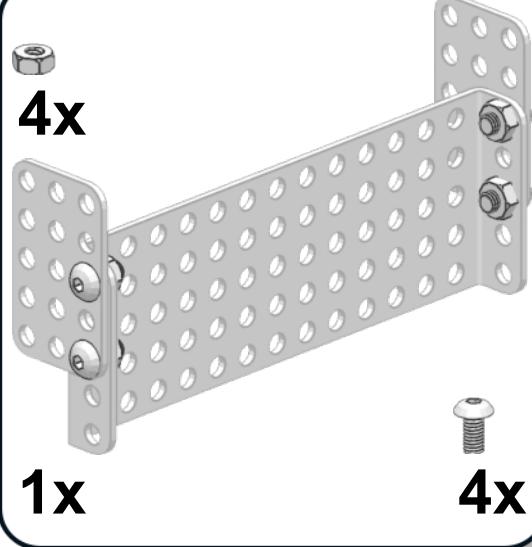


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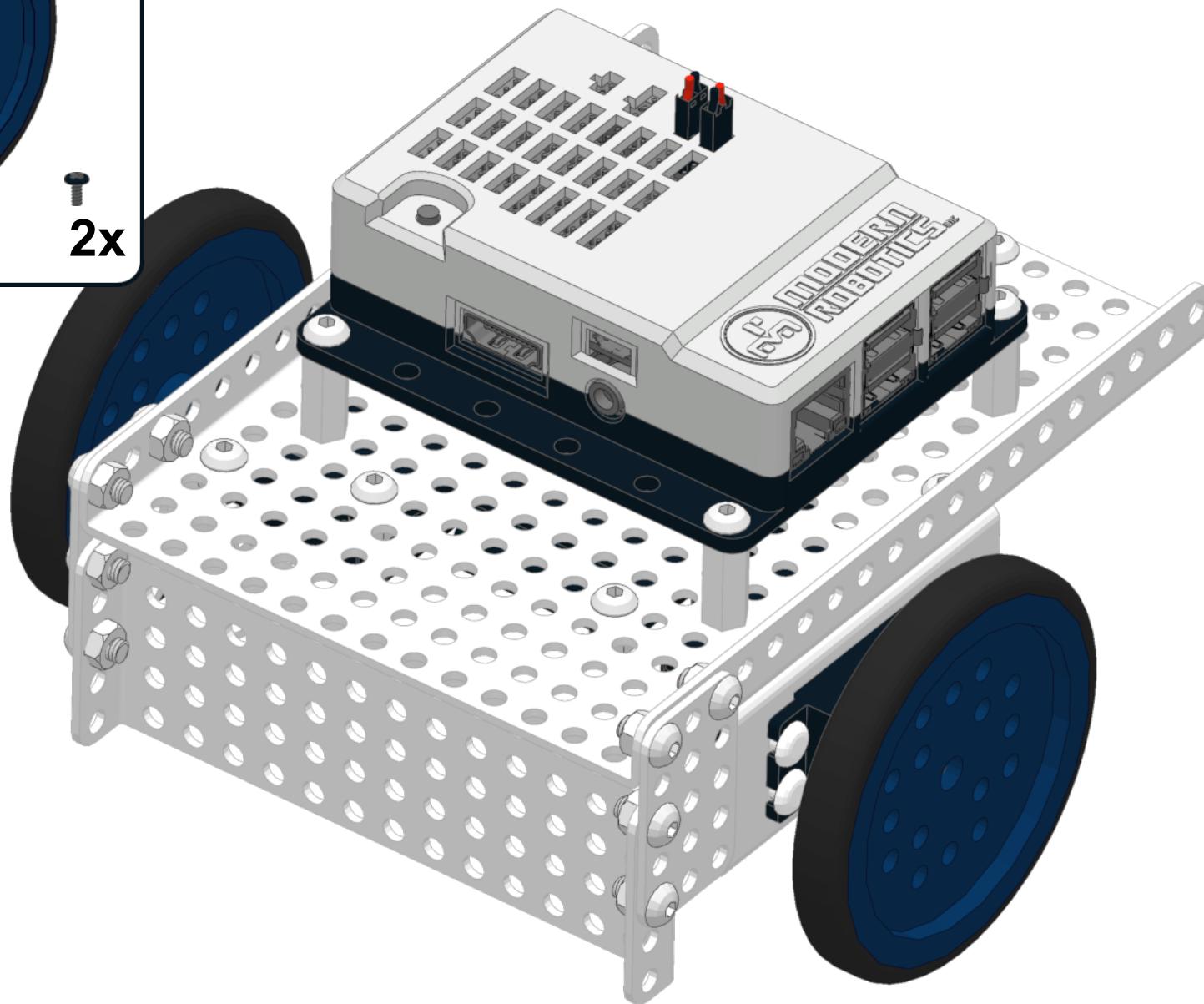
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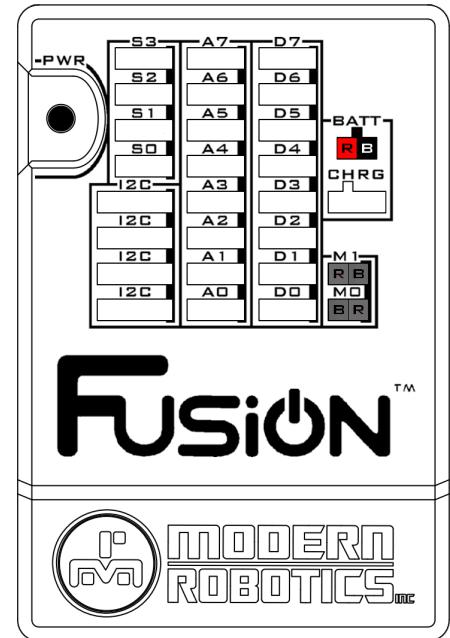
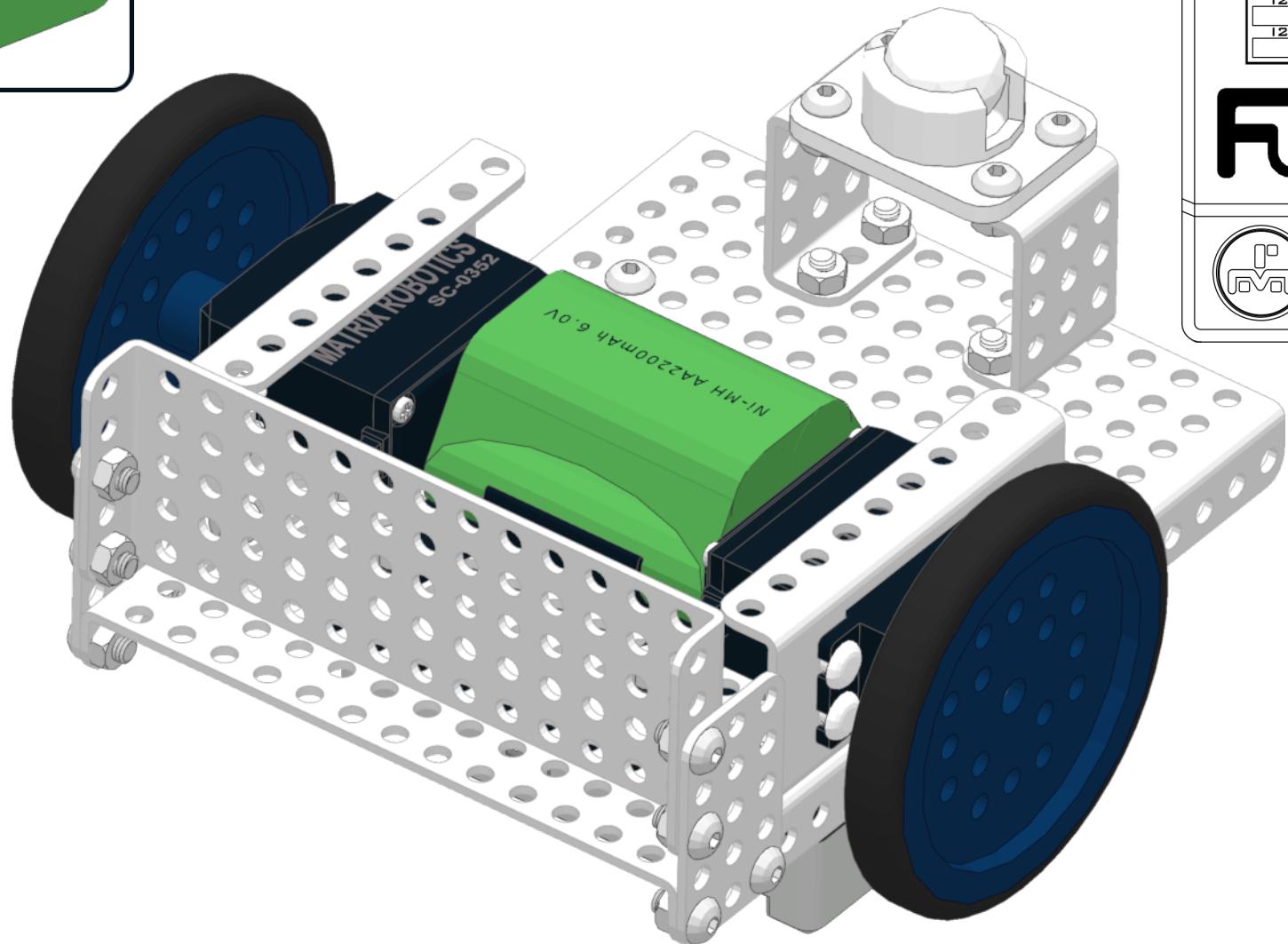
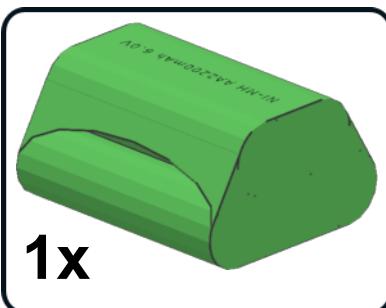
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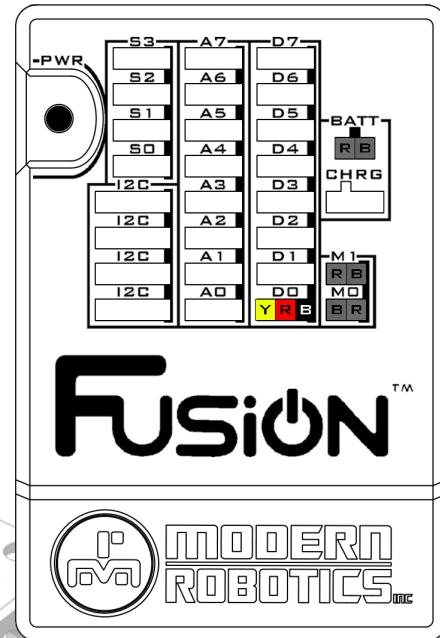
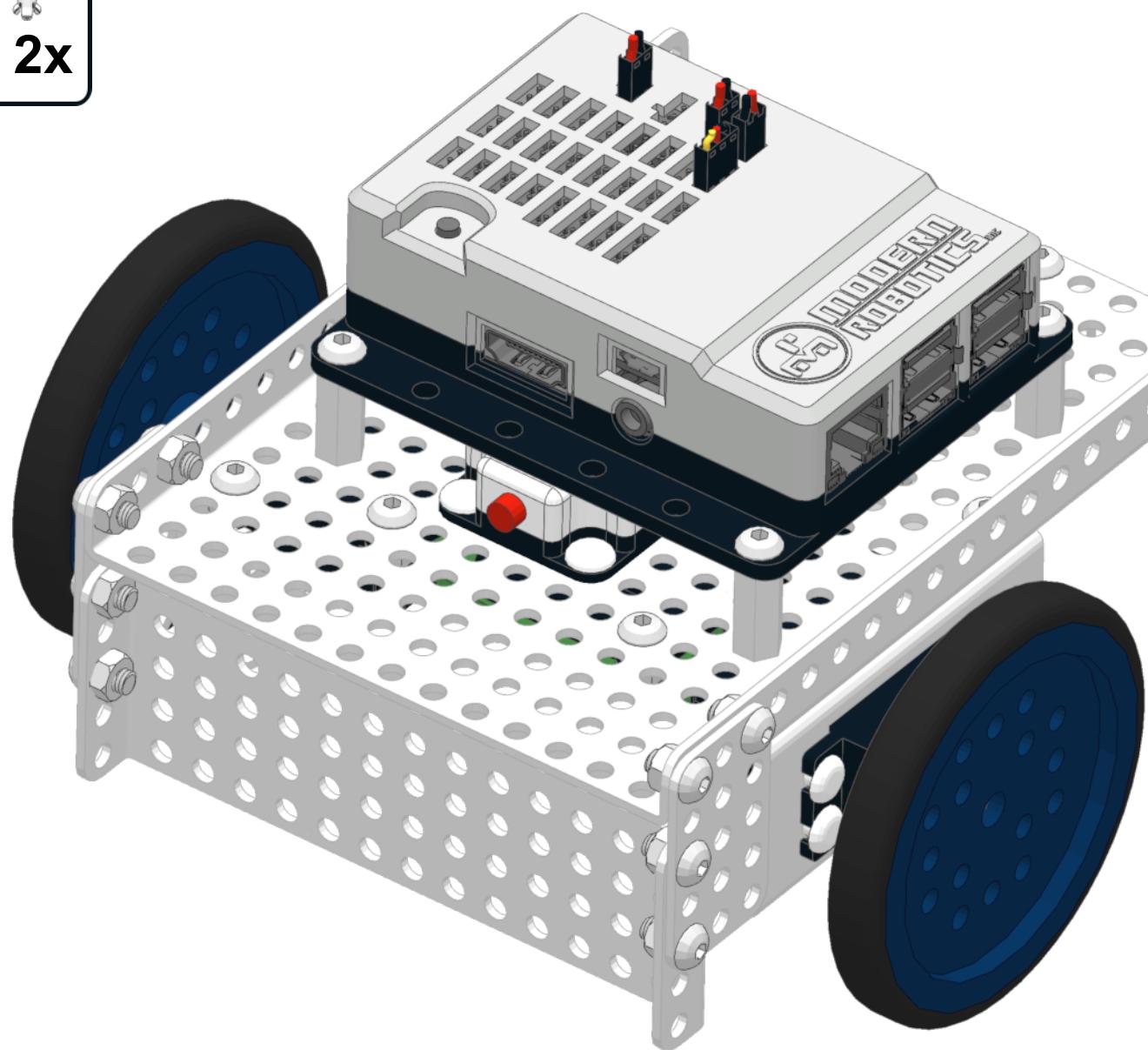
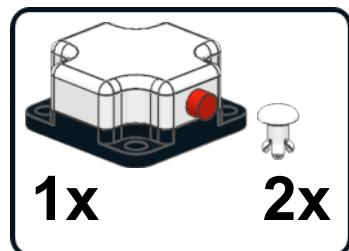
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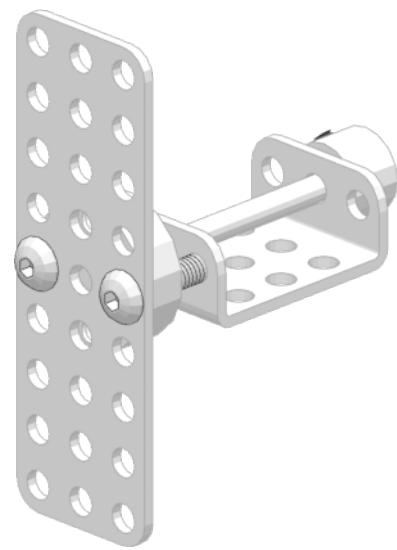
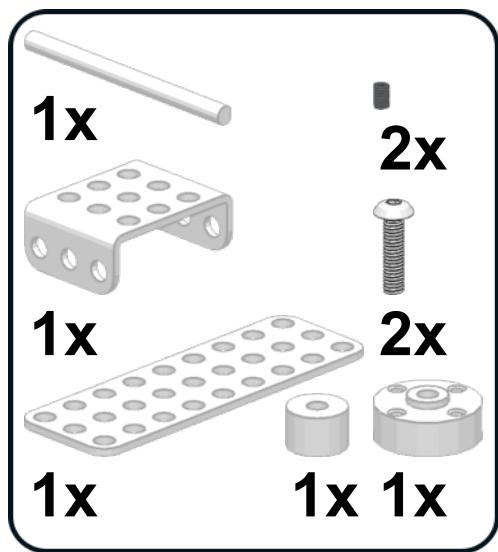


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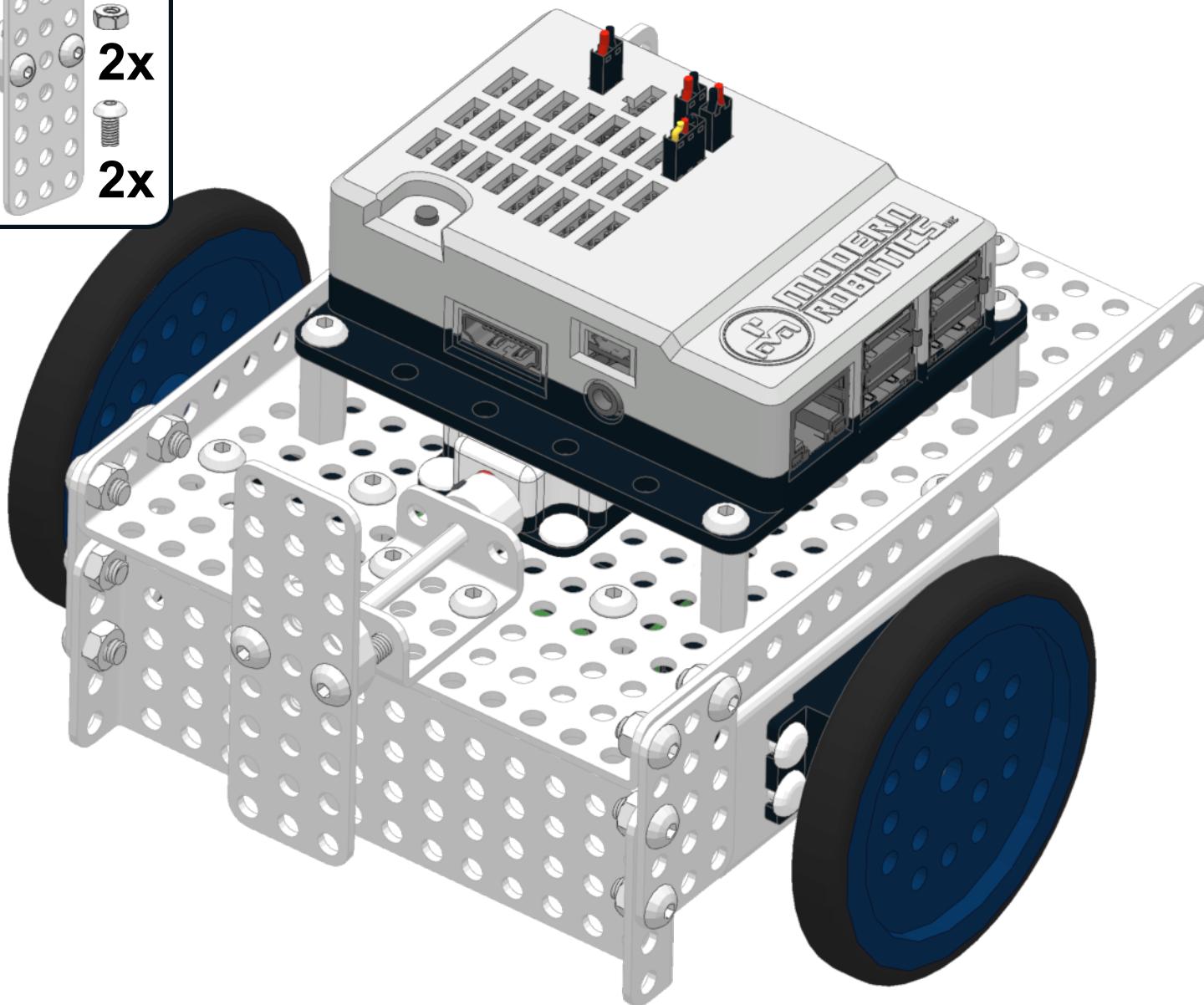
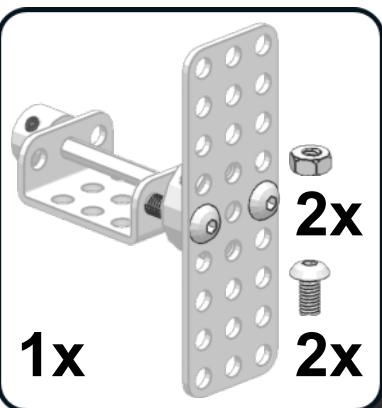


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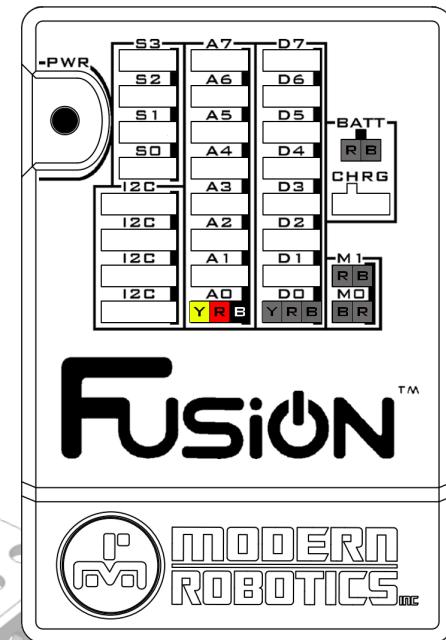
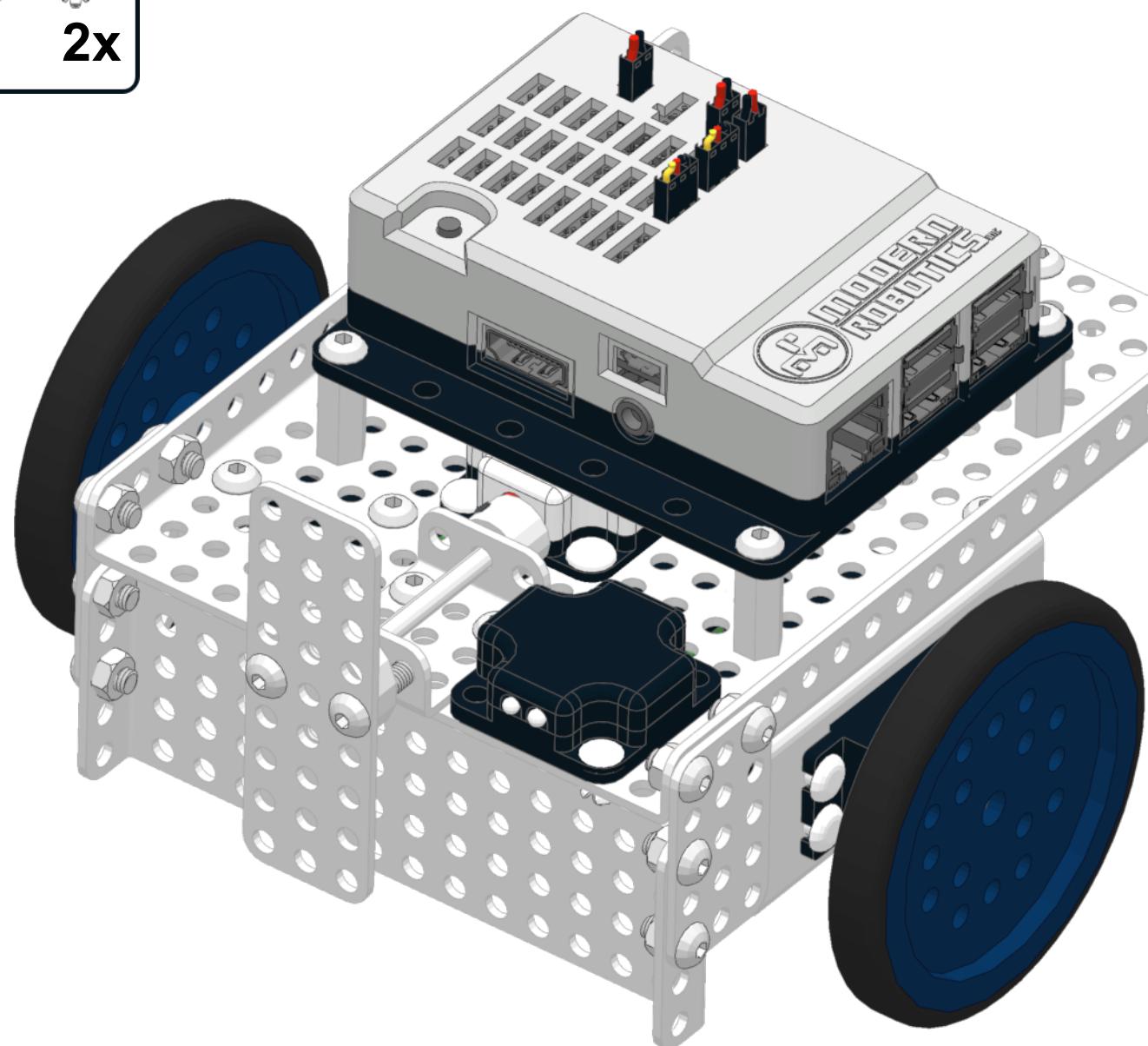
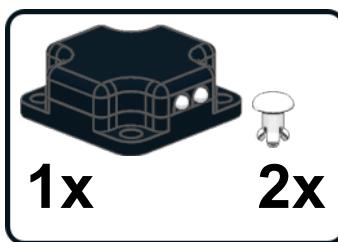
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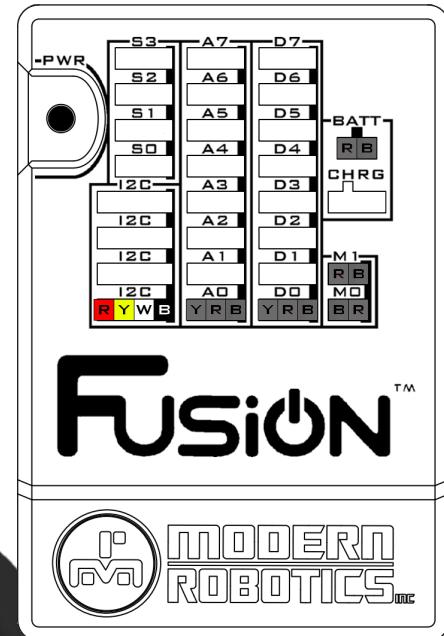
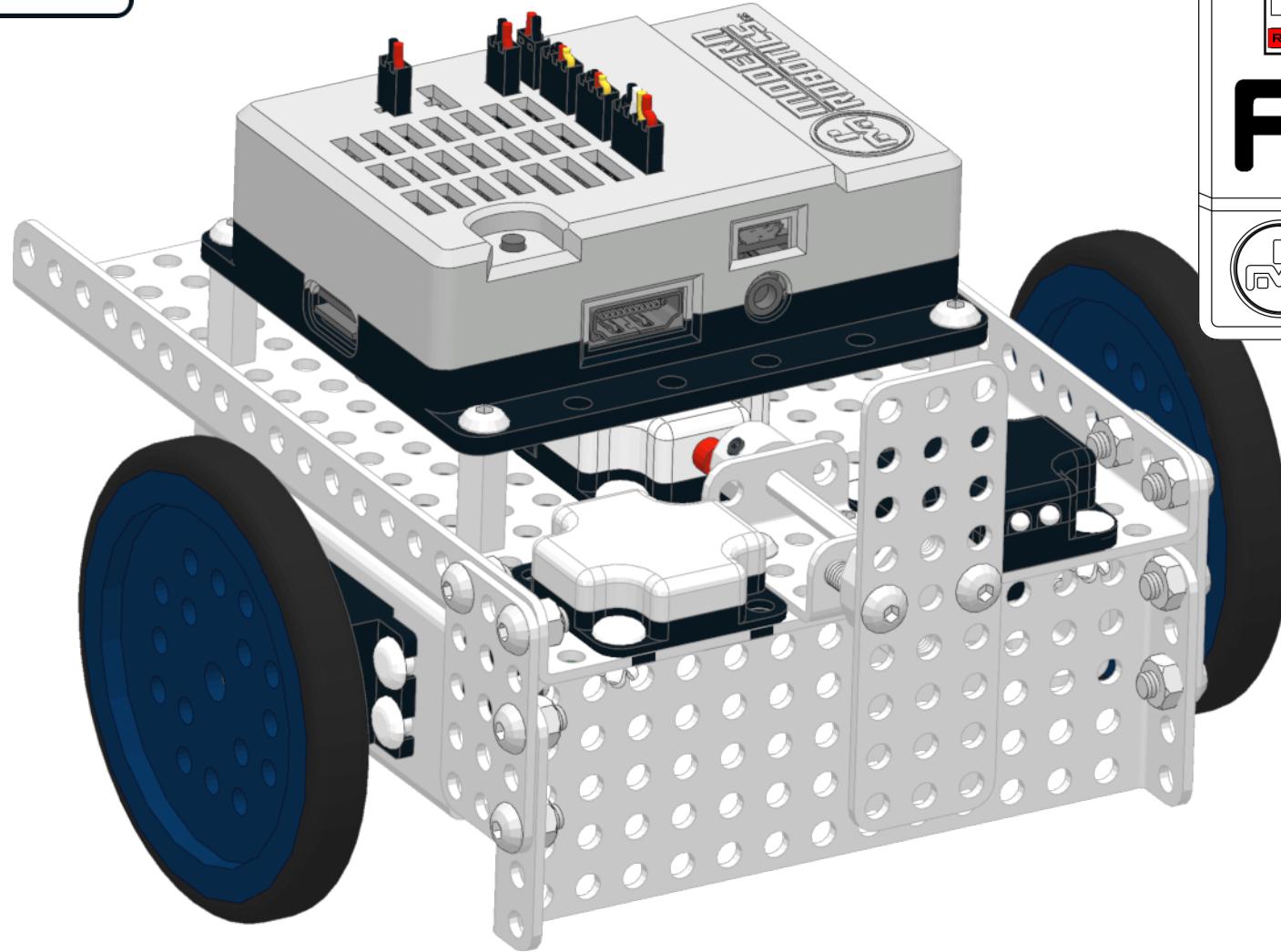
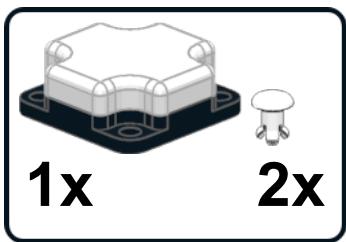
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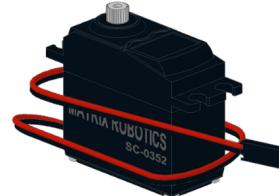
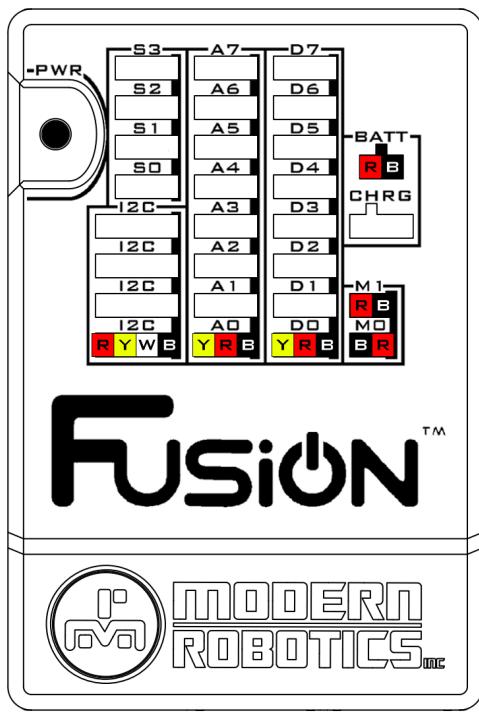
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11

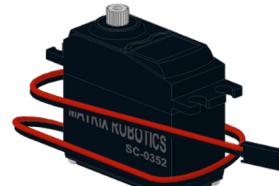


12





MO - Right Motor



MI - Left Motor



BATT - Battery (Keyed)



I₂C - Integrating Gyro



AO - Optical Distance Sensor



DO - Touch Sensor



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