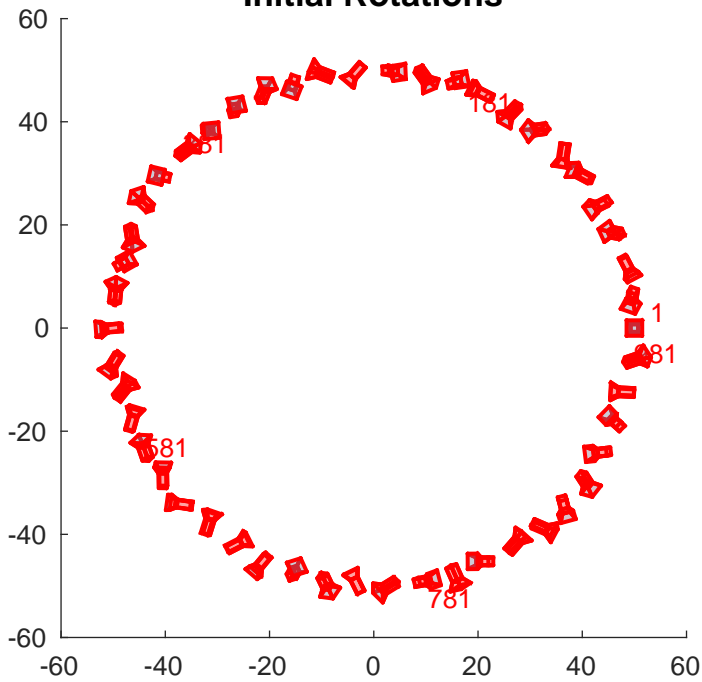


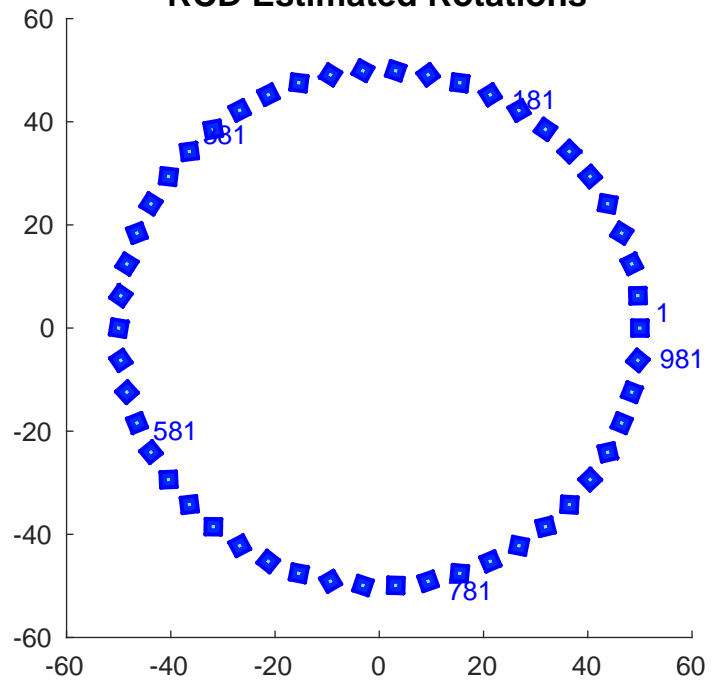
Number of cameras: 1000

Note : The cameras have been subsampled to 50 for a better visualisation.

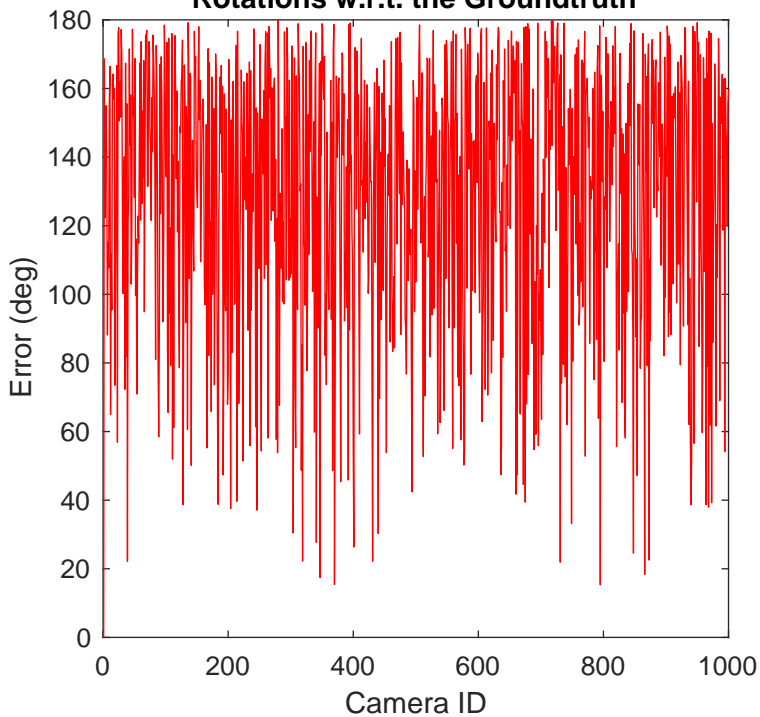
Initial Rotations



RCD Estimated Rotations



Angular Error of Initial Rotations w.r.t. the Groundtruth



Angular Error of RCD Estimated Rotations w.r.t. the Groundtruth

