Communication.Messages.Base
Message

+ time_stamp

+ BaseMessage()

Communication.Messages.Car
StateMessage

+ speed_actual
+ yaw_rate

Communication.Messages.Control
ResultMessage

+ speed_target
+ steering_angle_target
+ brake_hydr_target
+ motor_moment_target
+ lap_counter
+ cones_count_actual
+ cones_count_all

Communication.Messages.Perceived
ConesMessage

+ cones