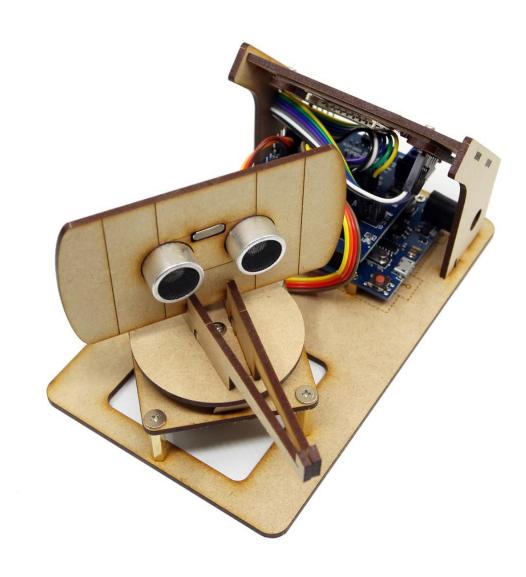
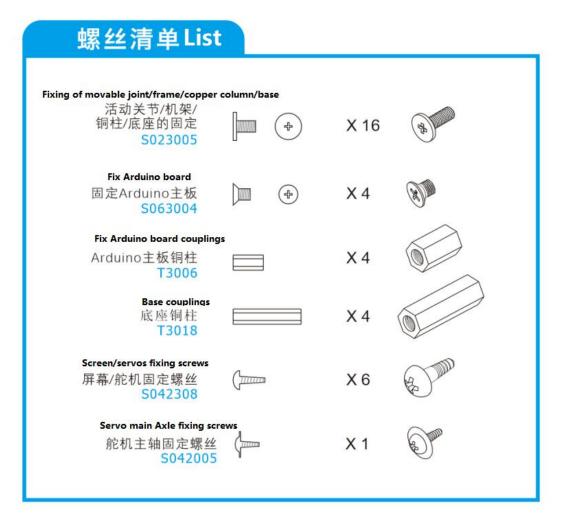
Mini Radar Ultrasonic Radar Installation and debugging instructions

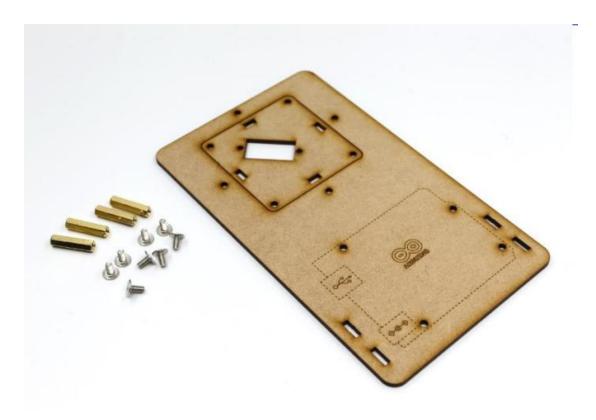


1. Installation

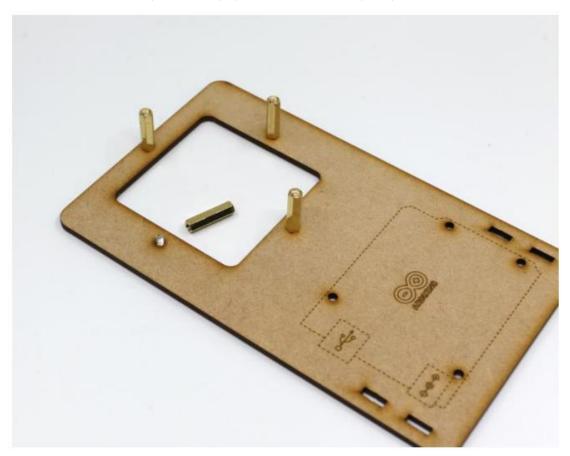


There are many types of screws in the accessory bag, please make sure to distinguish clearly before starting construction.

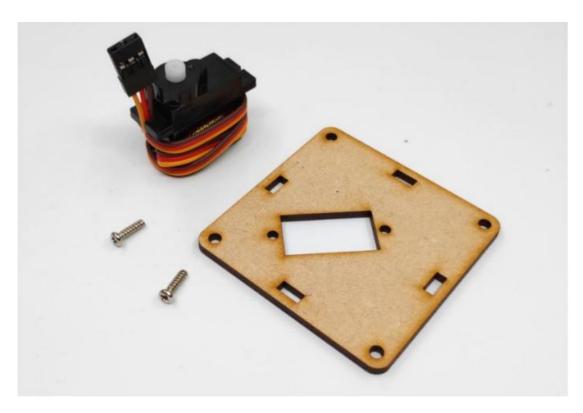
There are several kinds of screws that are very similar, do not mix them.



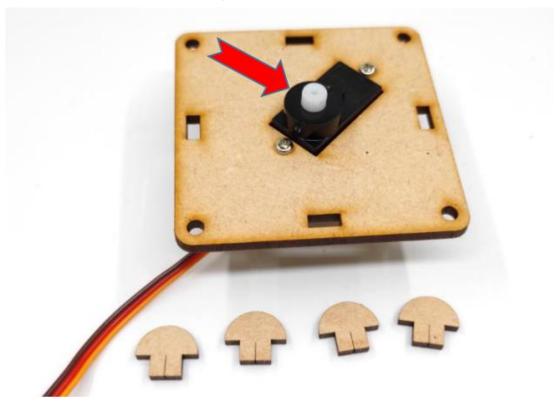
Just follow the reference picture and pay attention to the text prompt.



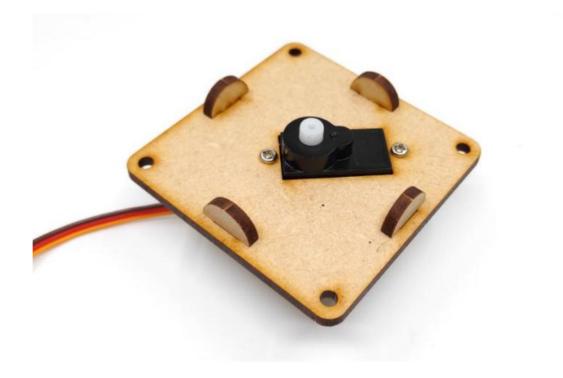
Fix the copper pillar from the bottom with screws

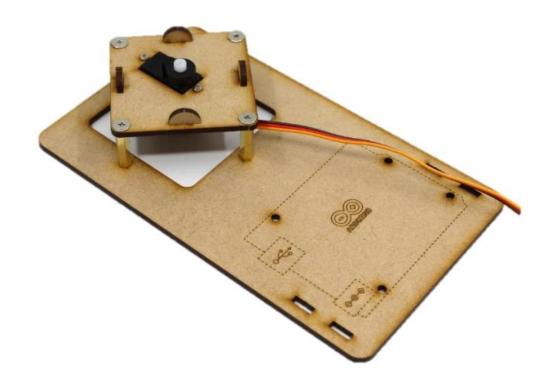


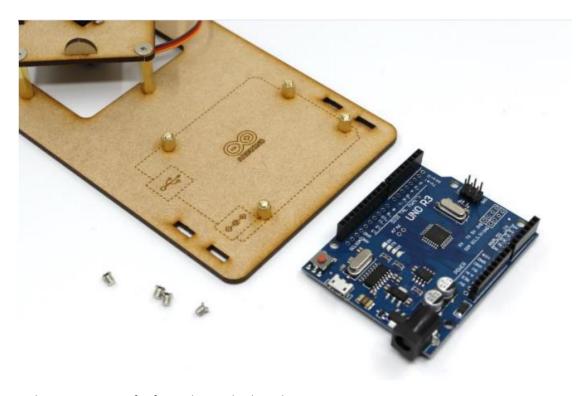
The screws to fix the servo are small cap screws.



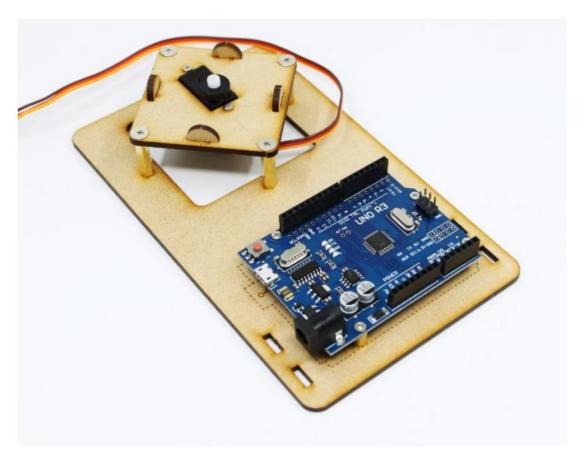
Note: The steering gear is facing, the main shaft is in the center of the base.



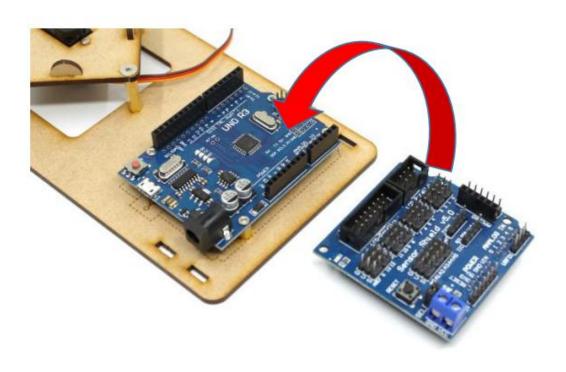


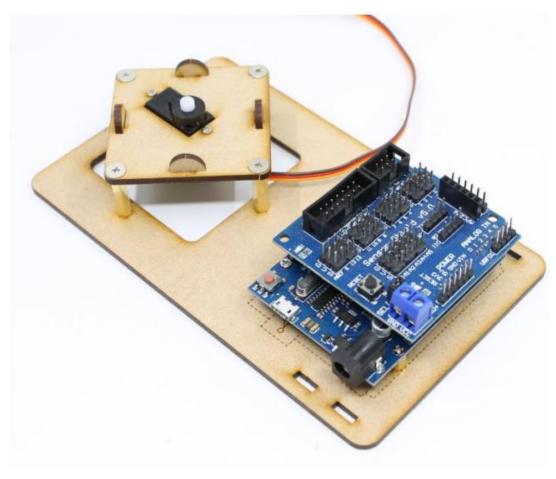


A short copper post for fixing the motherboard



Install Arduino UNO

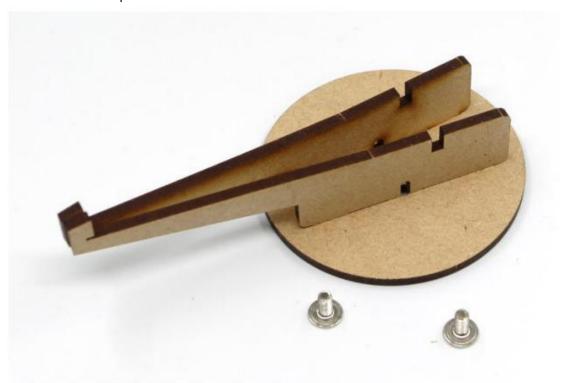


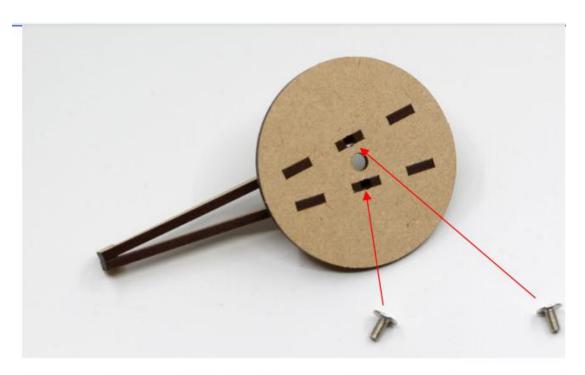


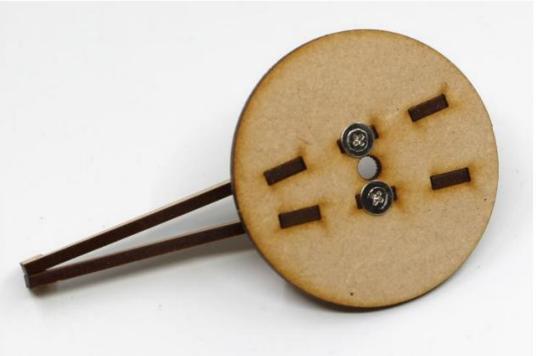
The base part is complete



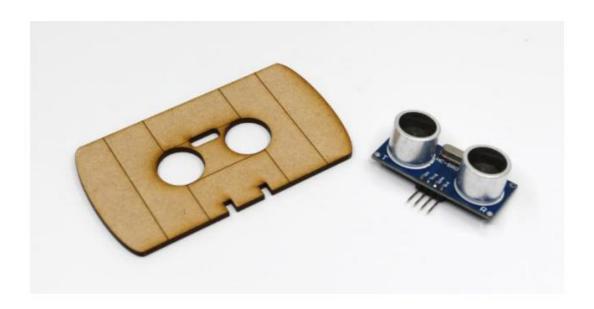
Assemble the radar part



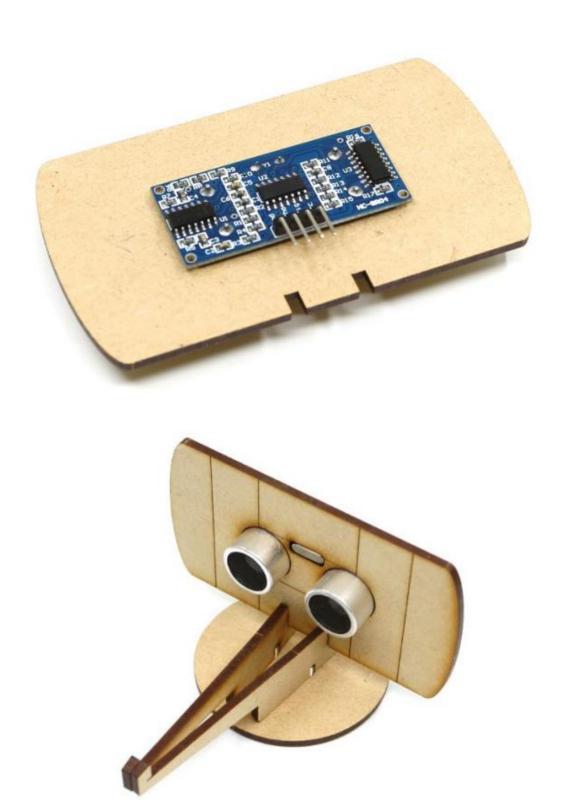


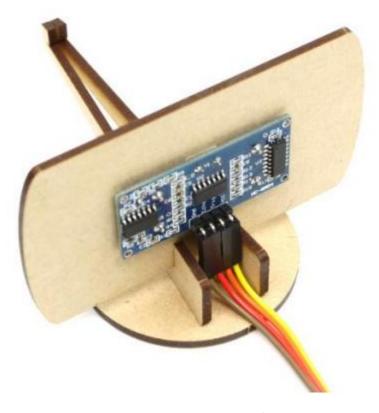


Don't over tighten the screws

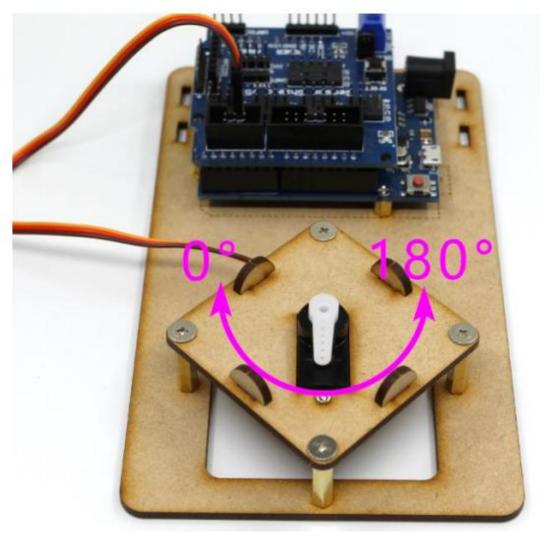




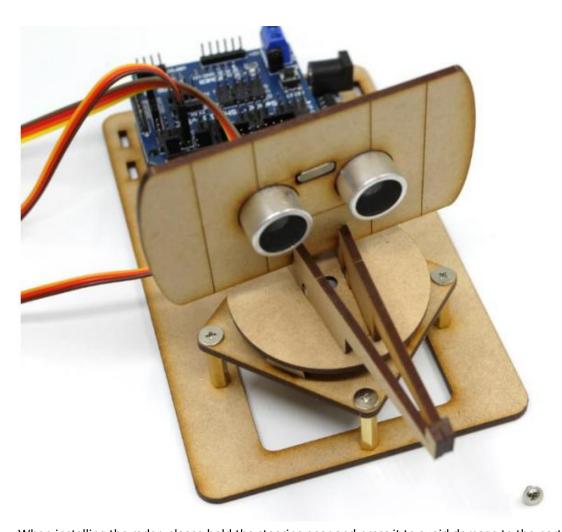




At this time, the Dupont line module can be terminated first



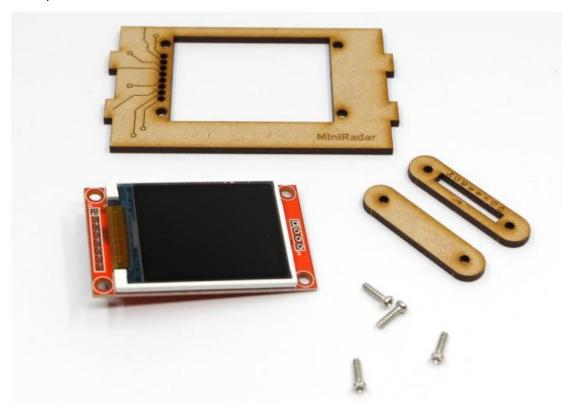
First determine the range of motion of the steering gear, set the main shaft of the steering gear at 90 degrees, and install the radar



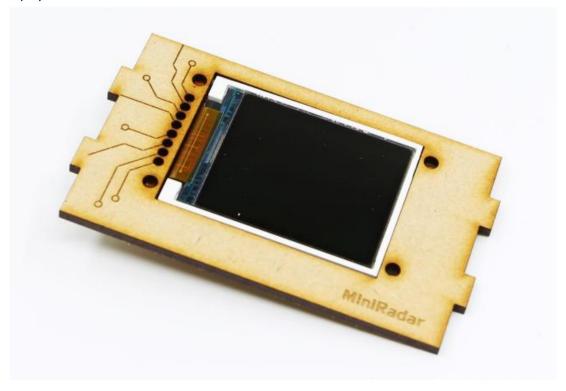
When installing the radar, please hold the steering gear and press it to avoid damage to the parts.

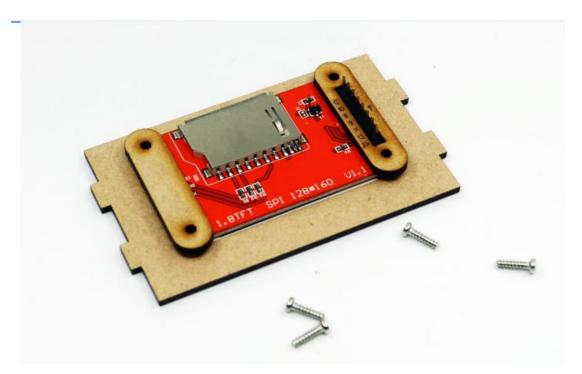


Use cap screws to lock the main shaft of the servo.

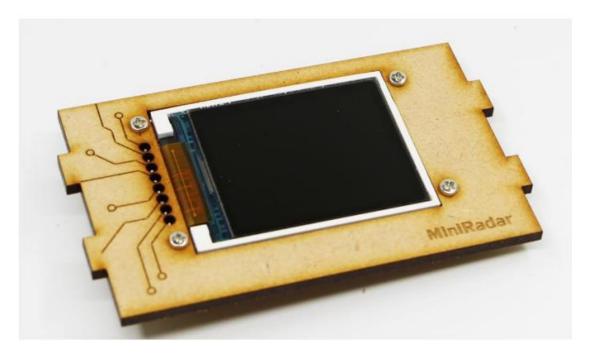


Display stand



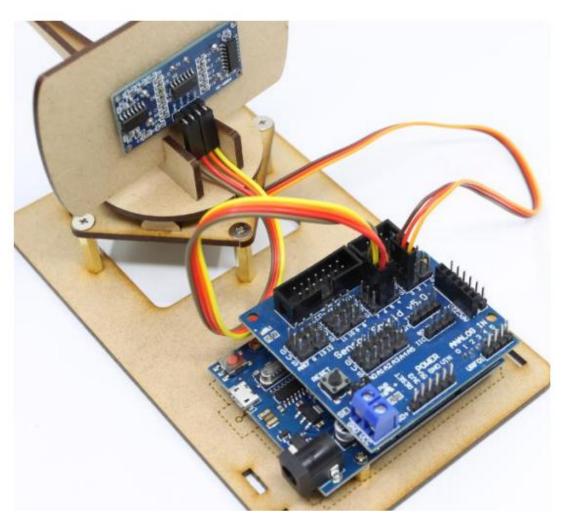


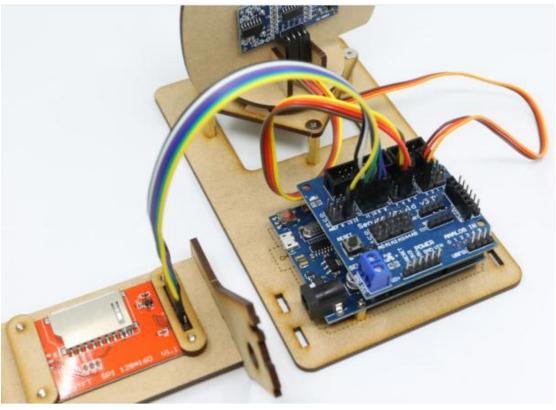
There is a wiring sequence on the spacer on the side of the pin, pay attention to the arrow pointing upwards. In principle, the first pin is not wired



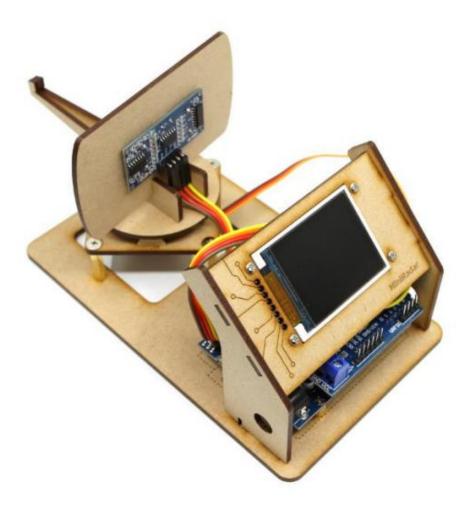
Use screws to lock from the front, do not over tighten





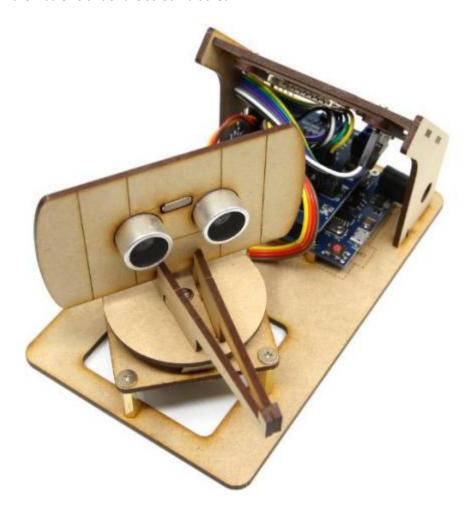


After the wiring test program, the screen bracket is assembled (for detailed wiring operation, please refer to the following instructions)





Fix the 2 screws under the screen bracket



Finished