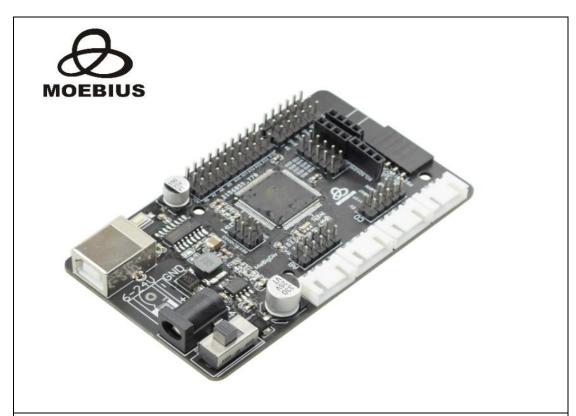
MeBigDiv, DWS300 驱动模块使用说明 MeBigDiv, DWS300 driver module instructions

深圳墨比斯科技有限公司 SHENZHEN MOEBIUS TECHNOLOGY LTD.,CO



MeBigDiv 控制器参数:

控制器: ATmega2560

工作电压: 5V

输入电压(推荐): 7-12V

输入电压(限制): 6-28V

数字 I/0 口: 26 (含 10 路 PWM 输出)

模拟输入口: 12

IIC 接口:1

串口: 3(含 usb 输入口)

SPI:

每个 I/0 口直流电流: 40 mA

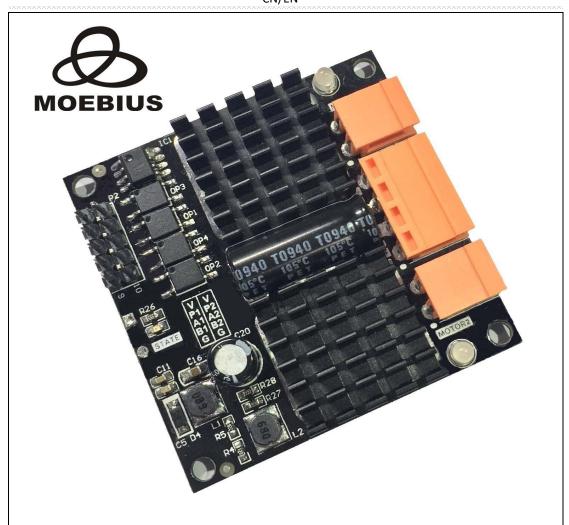
5vUSB 口直流电流: 1000 mA

闪存(Flash Memory): 256 KB(其中 8 KB 用作 bootloader)

静态存储器(SRAM): 8 KB

EEPROM: 4 KB

时钟: 16 MHz



DWS300 双通道电机驱动模块参数:

电机通道:2个

输入电压: 6.5-28VDC

控制信号输入电压:兼容 3-5V

控制信号输入电流: 15mA(5V 控制信号电压输入下)

PWM 输入频率: 18-60KHz

PWM 最小脉宽: 2us

峰值电流:70A(最多持续100ms),随着温度的升高,电流将受到限制

连续电流:每通道可持续输出 12A 电流

工作温度: -25℃~85℃ 过热温度: 85℃~95℃

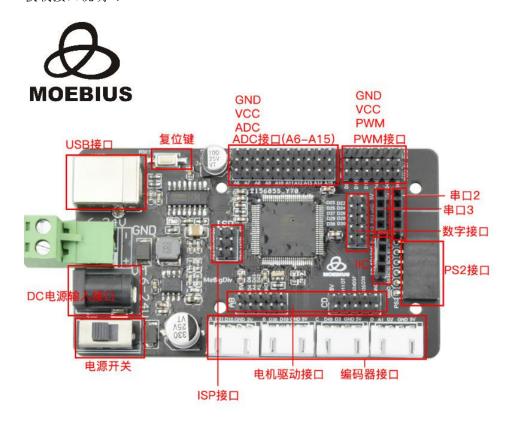
尺寸: 50mm*50mm*12.5mm

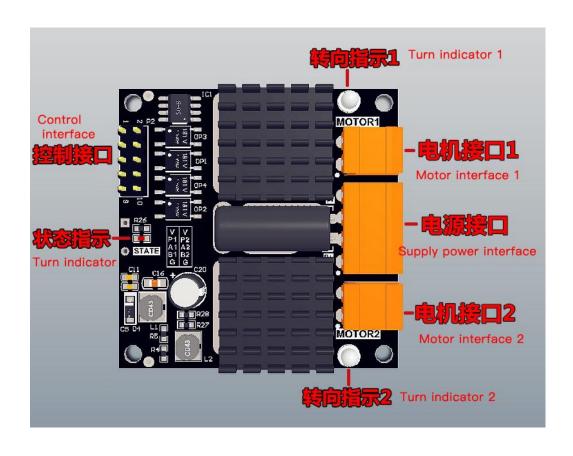
过电压: 28V

欠电压: 6.3V

内置过电压、欠电压、过热保护电路,通过 STATE 指示灯闪烁表示

板载接口说明:





驱动使用自制电机驱动模块输入电压 9V-28V,可以采用带保护板锂离子电池供电,可以驱动 9V-24V 有刷减速电机

电机驱动模块推荐使用电压 9-25.2V,单通道持续输出电流 Imc 12A (在开放环境温度 20 $^{\circ}$, 24V 条件下测试得出 Tested under the open environment temperature of 20 $^{\circ}$, 24V)

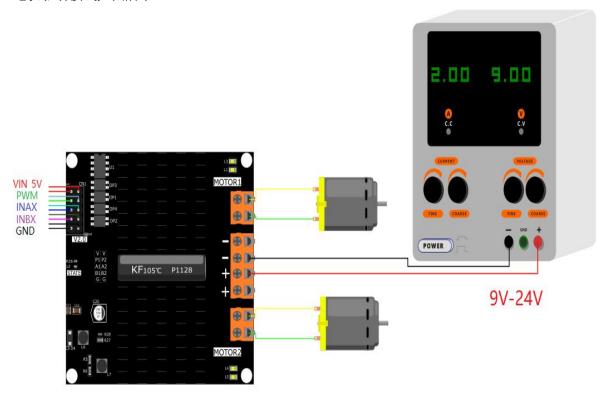
VIN 隔离正电源输入,兼容 3.3V、5V 电源

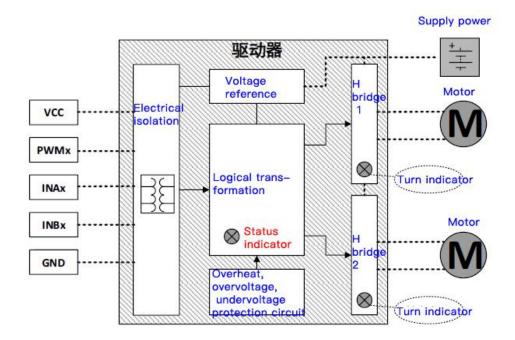
PWM 占空比调制输入,高速隔离,带宽 50MHz PWM 输入频率 推荐 18khz

INAX 通道控制逻辑输入 A INBX 通道控制逻辑输入 B

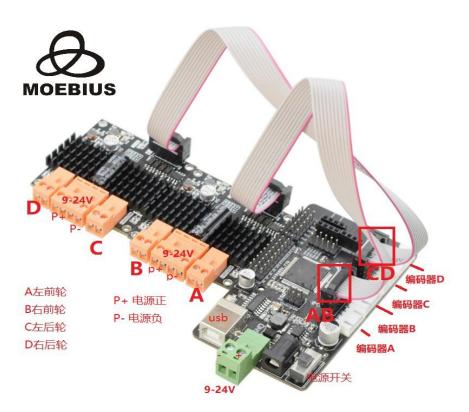
GND 隔离电源地输入

电机驱动接线如图所示





MeBigDiv 控制器与电机驱动模块接线图 (请以红色红线为基准接线,保证接线无误)



蓝牙模块接线图



蓝牙模块使用说明

插上蓝牙,使用安卓手机打开蓝牙找到 HC-06 进行配对,密码 1234.





配对完成之后打开 MOEBIU.app(需要先安装 MOEBIUS.APK)找到右上角设置点击进去点击 HC-06 进行连接,连接好会自动调到控制界面



点击 HC-06 进行蓝牙连接



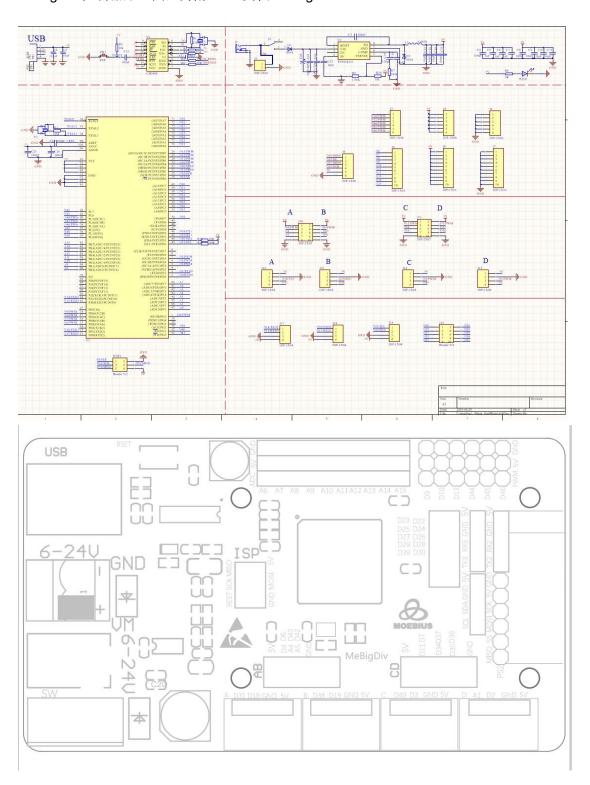
连接上完成会自动到这个界面 同时蓝牙模块上 LED 灯为常亮状态 通过左边这个滑动按钮控制电机运动

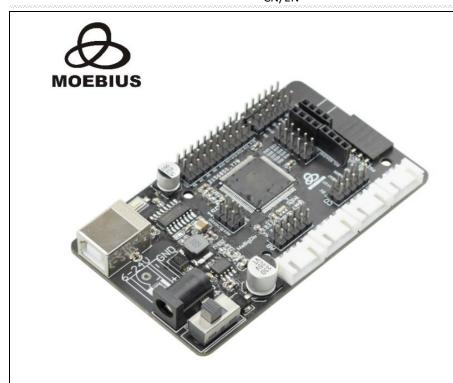
代码名称: BlueTooth_2560

MCU 控制芯片管脚对应代码如下

```
Diac | 0001_2000
//主控芯片MEGA2560芯片
//Main control chip MEGA2560 chip download chip CH340 needs to install CH340 driver
//MeBigDiv黑色控制器和DWS300黑色电机驱动蓝牙程序
//MeBigDiv black controller and DWS300 black motor driver Bluetooth program
//电机引脚
//Motor pin
#define PWMA 4
                  //A电机转速 A Motor speed
#define DIRA1 A4 //26
#define DIRA2 A5 //27 //A电机方向 A Motor direction
#define PWMB 6 //B电机转速 B Motor speed
#define DIRB1 43
#define DIRB2 42 //B电机方向 Motor direction
#define PWMC 11 //C电机转速 C Motor speed
#define DIRC1 34
#define DIRC2 35 //C电机方向 C Motor direction
#define PWMD 7 //D电机转速 D Motor speed
#define DIRD1 37
#define DIRD2 36 //D电机方向 D Motor direction
```

MeBigDiv 控制器原理图,另附 PDF 文档 MeBigDiv—SCH.PDF





MeBigDiv controller parameters:

Controller: ATmega2560

Working voltage: 5V

Input voltage (recommended): 7-12V

Input voltage (limit): 6-28V

Digital I / 0 port: 26 (including 10 PWM outputs)

Analog input port: 12

IIC interface: 1

Serial port: 3 (including USB input port)

SPI: 1 DC current per

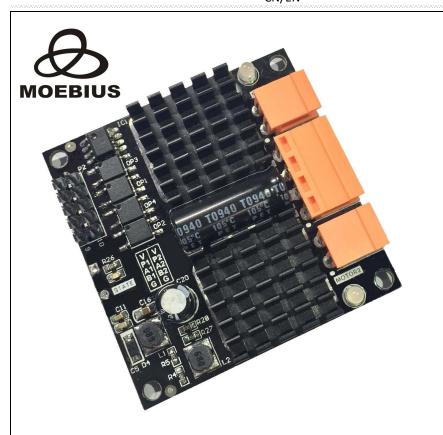
I / 0 port: 40 mA

5vUSB port DC current: 1000 mA

Flash Memory: 256 KB (of which 8 KB is used as bootloader)

Static memory (SRAM): 8 KB

EEPROM: 4 KB Clock: 16 MHz



DWS300 Motor channels: 2

Input voltage: 6.5-28VDC

Control signal input voltage: compatible with 3-5V

Control signal input current: 15mA (with 5V control signal voltage input)

PWM input frequency: 18-60KHz

PWM minimum pulse width: 2us

Peak current: 70A (up to 100ms), as the temperature increases, the current will be limited

Continuous current: 12A continuous output current per channel

Working temperature: -25 ℃ ~ 85 ℃

Overheating temperature: 85 °C ~ 95 °C

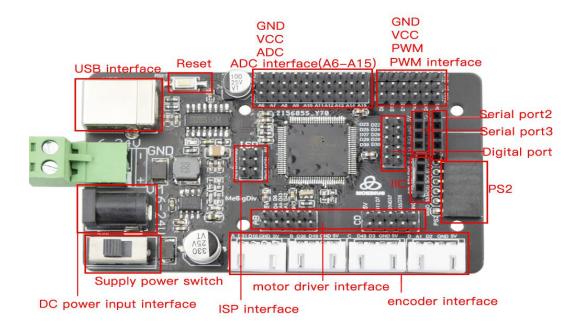
Size: 50mm * 50mm * 12.5mm

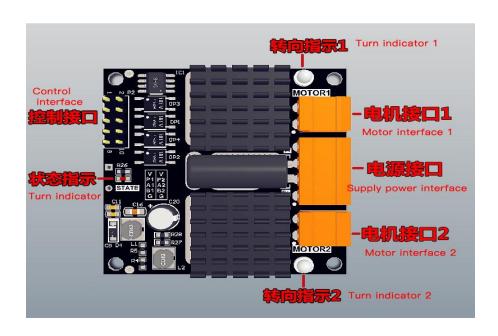
Overvoltage: 28.5V

Under voltage: 6.3V

Built-in over-voltage, under-voltage, and over-temperature protection circuits, indicated by blinking STATE indicator

On-board interface description:





Drive using self-made motor drive module input voltage 9V-28V, can be powered by lithium ion battery with protection board, can drive 9V-24V brushed geared motor

The recommended voltage for the motor drive module is 9-25.2V, and the single-channel continuous output current Imc 12A

(Tested under the open environment temperature of 20°C, 24V)

VIN Isolated positive power input, compatible with 3.3V, 5V power supply

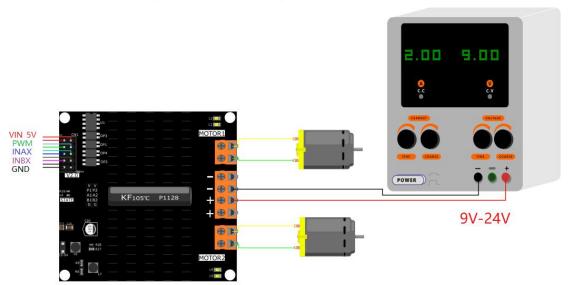
PWM Duty cycle modulation input, high-speed isolation, bandwidth 50MHz PWM input frequency 18khz recommended

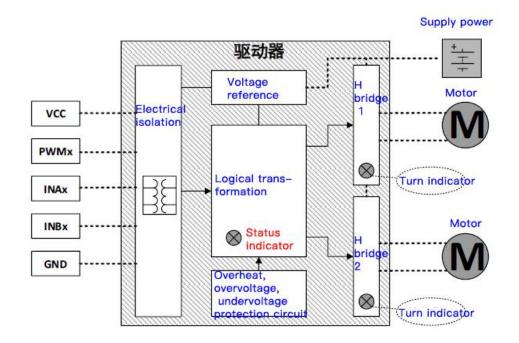
INAX Channel control logic input A

INBX Channel control logic input B

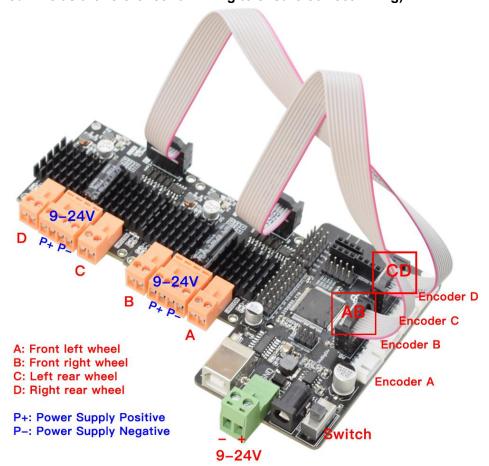
GND Isolated power ground input

The motor drive wiring is shown in the figure

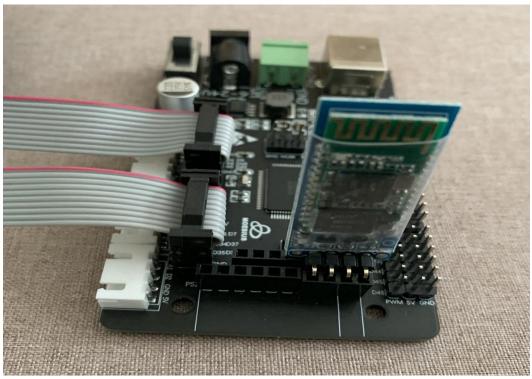




Wiring diagram of MeBigDiv controller and motor drive module(Please use the red red wire as the reference for wiring to ensure correct wiring)



Bluetooth module wiring diagram



Bluetooth module instructions

Plug in the Bluetooth, use your Android phone to turn on the Bluetooth to find HC-06 for pairing, the password is 1234.

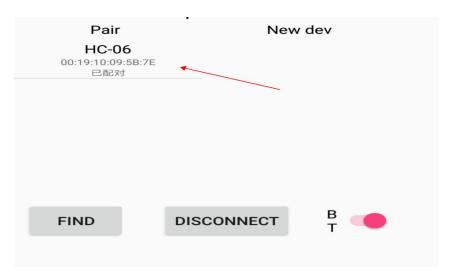




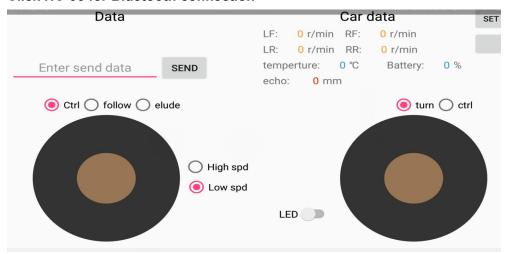
After the pairing is complete, open MOEBIU.app (you need to install MOEBIUS.APK first), find the settings in the upper right corner, click in, and click HC-06 to connect.

After the connection is completed, it will automatically be transferred to the control interface.





Click HC-06 for Bluetooth connection



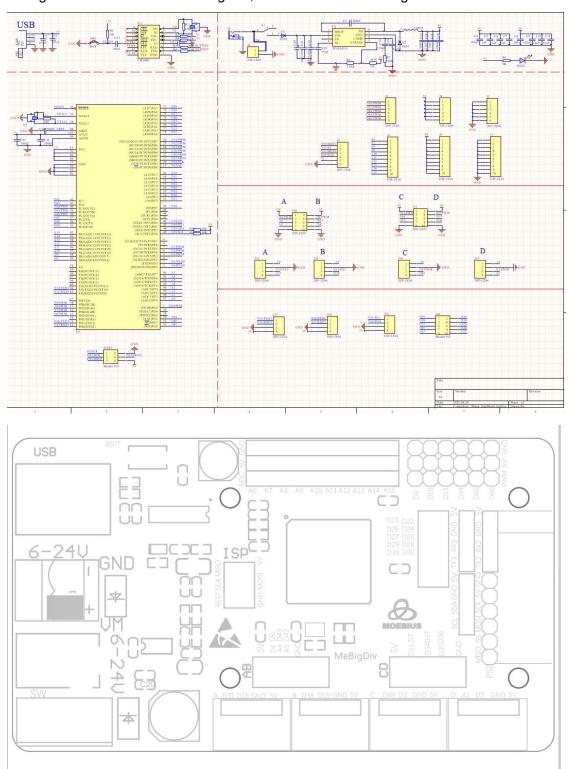
After the connection is completed, it will automatically go to this interface At the same time, the LED light on the Bluetooth module is always on Control the motor movement through the sliding button on the left

Code name: BlueTooth 2560

The corresponding codes of MCU control chip pins are as follows

```
Didc | 0001_2000
//主控芯片MEGA2560芯片
//Main control chip MEGA2560 chip download chip CH340 needs to install CH340 driver
//MeBigDiv黑色控制器和DWS300黑色电机驱动蓝牙程序
//MeBigDiv black controller and DWS300 black motor driver Bluetooth program
//电机引脚
//Motor pin
                  //A电机转速 A Motor speed
#define PWMA 4
#define DIRA1 A4 //26
#define DIRA2 A5 //27
                         //A电机方向 A Motor direction
                  //B电机转速
#define PWMB 6
                              B Motor speed
#define DIRB1 43
#define DIRB2 42 //B电机方向 Motor direction
#define PWMC 11 //C电机转速 C Motor speed
                   //C电机转速 C Motor speed
#define DIRC1 34
#define DIRC2 35 //C电机方向 C Motor direction
#define PWMD 7 //D电机转速 D Motor speed
#define DIRD1 37
#define DIRD2 36 //D电机方向 D Motor direction
```

MeBigDiv controller schematic diagram, attached PDF file MeBigDiv—SCH.PDF



https://github.com/MoebiusTech/MeBigDiv