

# HEP Infrastructure in Julia: `UnROOT.jl`

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# Technical tasks in HEP (analysis)

In the order of data-flow:

1. Read physics data from `.root` files. ([UnROOT.jl](#))
2. Process the data, usually a reduction into histograms. ([FHist.jl](#))
3. Tinker with the script/program you wrote, usually for optimization or physics reason, repeat many times. ([Revise.jl](#))
4. \* Run on accelerator computing resource. ([CUDA.jl](#))

(Then, add “fast” and “in parallel”(built-in “[green](#)” threads) to all of the above.)

This set of slides focus on the work done in the UnROOT.jl. The main authors at this moment in time are:

- ▶ [Nick Amin](#)<sup>1</sup>
- ▶ [Tamas Gal](#) (creator)
- ▶ [Jerry Ling](#)

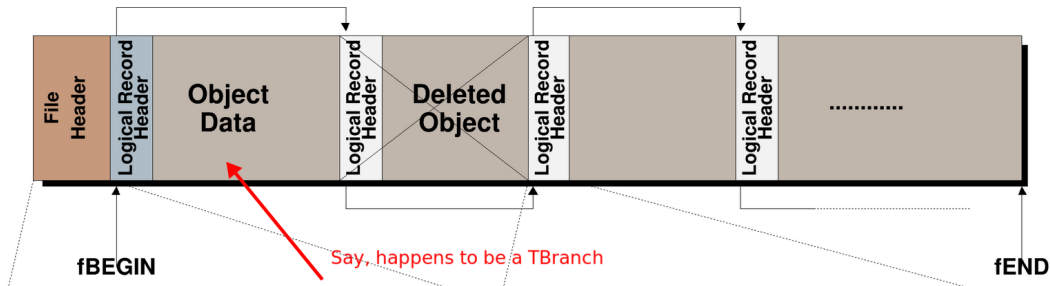
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<sup>1</sup>Thanks Nick for the visualizations.

## State of the UnROOT.jl

- ▶ Reading most used objects and data from root file:
  - ▶ TTree, TBranch, TDirectory, TNtuple, TH1/2D
  - ▶ Flat, Jagged, Doubly jagged
  - ▶ TLorentzVector and more custom structure
  - ▶ As a reference, we can read all branches of CMS's [NanoAOD](#).
- ▶ Unified user-level interface and it is **Fast**.
- ▶ Less is more
  - ▶ Doesn't require 4 different chunking functions or 3 different ways of looping.
  - ▶ Users simply do everything they already knew, by treating the TTree as a table (they are tables.), including Query-ing and multi-threading.

## 1000 Feet View of `.root`



The data almost always live inside a “branch”, the purpose of most of the logical metadata stuff: File Header, Streamer etc. are there just so we can find the data’s `TKey`, which tells us where and how data are stored inside the file.

## 100 Feet View of TBranch

The element type of a branch is fixed, meaning every event in a branch has to have the same type. But they can be custom structure (e.g. `TLorentzVector`) and/or “jagged”. This information lives in the `TBranch` streamer object in a non-trivial way.

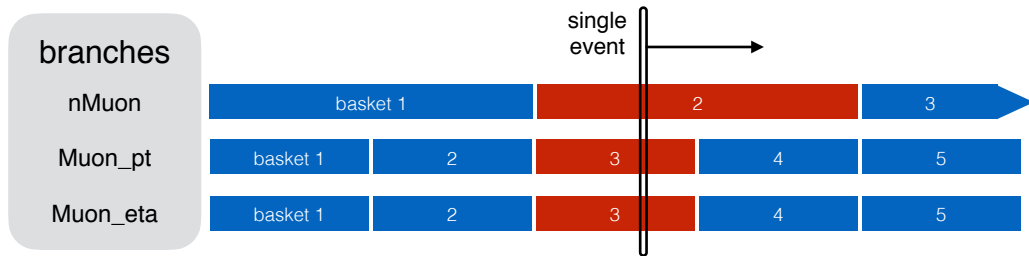
A branch is further divided into many “baskets”. These baskets are not arranged one next to another in the file. The `TBranch` objects contains the following:

- ▶ `fBasketSeek`: [248, 34865, 65932, 95550, 125071,...]

`fBasketSeek` tells us where (in terms of bytes offsets from the beginning of the file) is each basket located, in this particular example first basket starts at 248th byte.

# LazyTree

When you bundle many branches together, you get a tree. Most of the time users are not randomly accessing indices, they **iterate** over the `TTree`.



The underlying baskets of different branches are not aligned in general. We simply cache the last-used basket for each branch in RAM (a.k.a basket cache), such that new basket are read/decompressed as needed.

## Lazy to the Last Second

The interface is simple enough:

```
for evt in mytree
  if evt.nMuon != 4
    continue
  end
  # access more branches
end
```

`mytree` can have many many branches, and which branches need “access” can dynamically depend on the event content. `LazyTree` is designed such that `evt` in the above example is still lazy, no data is read until `evt.nMuon` line.

The `evt` merely keeps track of which `TTree` it comes from and which event number it is, when `evt.nMuon` happens, it effectively does `nMuonBranch[evt_idx]`.

## Compostable Multi-Threading

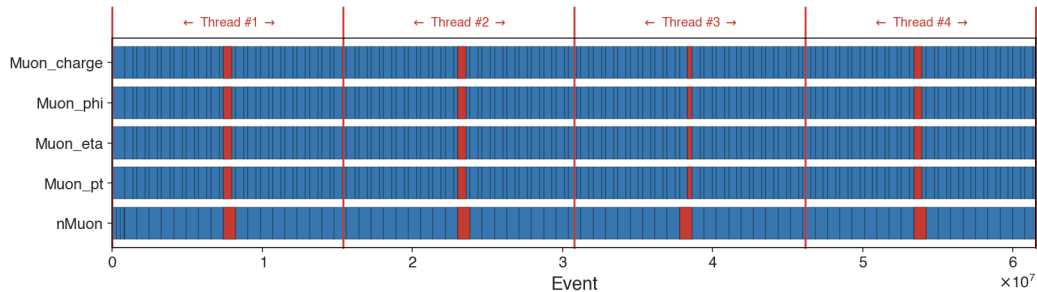
To enable parallel access of a tree/branch, we only need to make sure the basket cache is thread-local and everything else is already thread-friendly:

```
# from Polyester.jl
@batch for evt in mytree
    evt.nMuon < 4 && continue
    # more stuff
end
```



# Compostable Multi-Threading

During parallel access, threads work on disjoint ranges, roughly speaking if we have 100 events and 4 threads, the 1st thread will work on 1:25, the last thread will work on 76:100, avoiding the race-condition in basket access.



## Conclusion and Future Work

- ▶ UnROOT.jl is ready for production around the “analysis” step
  - ▶ “around”, because could do analysis on lower level data, if needed.
  - ▶ fast and integrate seamlessly with Julia ecosystem for tabular processing and multi-threading.
- ▶ The ability to write to `.root` files has not been a priority so far:
  - ▶ almost never performance critical
  - ▶ not many ecosystem advantages (e.g. no need for AutoDiff to know you’re writing to disk)
  - ▶ already can do it via [PyCall.jl](#) + uproot
- ▶ Low-hanging fruit:
  - ▶ Better `Tables.partitions`, helps writing. (github [issue](#))
  - ▶ Optimize slicing (github [issue](#))
- ▶ Plan to support `xrootd` via [Go-HEP/xrootd](#) since Go compiles to `ccall()`-able libraries nicely.

## Backup

## Mini Benchmarking

To understand if we're doing anything "very stupid" in our naive implementation, Nick made some [benchmark](#) comparing the performance of looping lazily, for different compression algorithm. (We suspect the `zlib` library in `stdlib` may not be optimal.) Here's the summary:

Table 1: Time measured in seconds. "compiled" means `g++ -O2`.

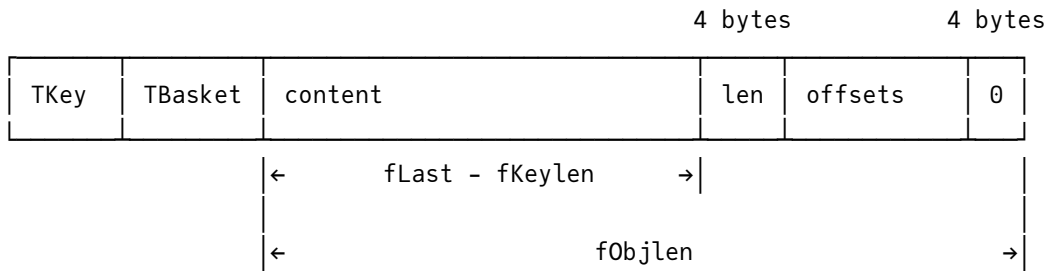
		TTreeReader	TTreeReader	SetAddress	RDataFrame
	Julia	interpreted	compiled	compiled	compiled
none	2.084	11.200	7.260	3.500	9.150
zlib	7.075	15.560	11.730	8.110	13.640
lz4	3.056	11.300	7.620	3.740	9.498
lzma	44.718	52.660	49.550	45.520	51.655

Conclusion: we're probably not doing something super wrong.

## Getting hands on the data

Despite the overall complexity of `.root` file format, after the metadata extraction, dumping data from one event to the next is relatively straightforward.

Here's a schematic of a single basket, the `TBasket` contains the information regarding compression algorithm etc. All of the data we actually care about are inside `content` and `offsets` (in the case where data is jagged).



Reference discussion

## Getting hands on the data

Due to this design, the smallest unit of reading `.root` file is a basket – you need to read and decompress one basket even if you just want one event (because in general partial decompression is impossible, also offsets may be needed). Usually the size of basket is ~ few MB, so it's not an issue to keep the last-used one in RAM (basket cache).

Thus, the logical steps for reading data are:

1. Find which basket the event number belongs to by using `fBasketEntry`.
2. Parse `TBasket` to find out compression algorithm and raw bytes length
3. Read and decompress the raw bytes in this basket (raw bytes = `Vector{UInt8}`)
4. Reinterpret the bytes into data (according to the metadata) and offsets (for jagged branch)

## Building Block: LazyBranch

The tricky part is making the interpreted data available to user-level while maintaining the performance. The starting point is:

```
julia> typeof(mybranch)
LazyBranch{Vector{Int32}, UnROOT.OffsetJagg, ...

julia> mybranch[54]
3-element view(::Vector{Int32}, 229:231) with eltype Int32:
 50
 51
 52
```

This would use the machinery described in the [previous slide](#). Despite Julia's native support of jagged array (very fast even), to reduce memory allocation, we use [ArraysOfArrays.jl](#) for jagged branch. In this case, the 54th event's data is at 229:231 of the basket, and we non-copy `viewed` it.

## Building Tree from Branches

The branches of a tree are totally independent, so it's not conceptually challenging to just “bundle them together” and make a `Tree`.

Due to the larger-than-RAM nature, you might think we're about to reinvent `Dask`-like lazy dataframe.

Fortunately, we don't need to. In fact the `julia` counterpart of `pandas`, `DataFrames.jl` already supports lazy column. More precisely, it “doesn't care” what your columns are as long as they have defined length and indexing interface.

But we use `TypedTables.jl` (which supports lazy column for the same reason) instead due to one important factor: performance.



# Type Stability of LazyBranch and LazyTree

julia includes powerful [inspection tools](#) you can look at LLVM or assembly. We just want `@code_warntype` and see for ourselves that there's no boxing or instability:

```
julia> @code_warntype mybranch[12]
MethodInstance for getindex(::LazyBranch{Vector{Int32}, UnROOT.OffsetJagg, ArraysOfArrays.VectorOfVectors{Int32, Vector{Int32}, Vector{Int32}, Vector{Tuple{}}}}, ::Int64)
  from getindex(ba::LazyBranch{T, J, B}, idx::Integer) where {T, J, B} in UnROOT at /home/akako/.julia/dev/UnROOT/src/iteration.jl:163
Static Parameters
  T = Vector{Int32}
  J = UnROOT.OffsetJagg
  B = ArraysOfArrays.VectorOfVectors{Int32, Vector{Int32}, Vector{Int32}, Vector{Tuple{}}}
Arguments
  #self#::Core.Const{getindex}
  ba::LazyBranch{Vector{Int32}, UnROOT.OffsetJagg, ArraysOfArrays.VectorOfVectors{Int32, Vector{Int32}, Vector{Int32}, Vector{Tuple{}}}}
  idx::Int64
Locals
  val@_4::SubArray{Int32, 1, Vector{Int32}, Tuple{UnitRange{Int64}}, true}
  val@_5::UnitRange{Int64}
  localidx::Int64
  br::UnitRange{Int64}
  tid::Int64
  @_9::Int64
Body::SubArray{Int32, 1, Vector{Int32}, Tuple{UnitRange{Int64}}, true}
1 - Core.NewvarNode{:(val@_4)}
  Core.NewvarNode{:(localidx)}
  %3 = Base.Threads.threadid::Core.Const{Base.Threads.threadid}
    (tid = (%3)())
    $(Expr{inbounds, true})
  %6 = Base.getproperty(ba, :buffer_range)::Vector{UnitRange{Int64}}
    (val@_5 = Base.getindex(%6, tid))
    $(Expr{inbounds, :pop})
    (br = val@_5)
  %10 = (idx < br)::Bool
    goto #3 if not %10
    (@_9 = UnROOT._localindex_newbasket!(ba, idx, tid))
    goto #4
2 -
  %14 = Base.getproperty(br, :start)::Int64
  %15 = (idx - %14)::Int64
    (@_9 = %15 + 1)
    (localidx = @_9)
3 - $(Expr{inbounds, true})
  %19 = Base.getproperty(ba, :buffer)::Vector{ArraysOfArrays.VectorOfVectors{Int32, Vector{Int32}, Vector{Int32}, Vector{Tuple{}}}}
  %20 = Base.getindex(%19, tid)::ArraysOfArrays.VectorOfVectors{Int32, Vector{Int32}, Vector{Int32}, Vector{Tuple{}}}
    (val@_4 = Base.getindex(%20, localidx))
    $(Expr{inbounds, :pop})
  return val@_4::Core.PartialStruct{SubArray{Int32, 1, Vector{Int32}, Tuple{UnitRange{Int64}}, true}, Any{Vector{Int32}, Tuple{UnitRange{Int64}}}, Int64, Core.Const{1}}
```

## Interlude: Type Stability

Two kinds of type stability:

1. Can the return type be inferred from just the **types** of the inputs?
2. Can the types of all variables in the function bodied be inferred?

The second point manifests in any user function, consider an analysis function contains the following:

```
for evt in mytree
    compute(evt.Muon_pt)
    # more stuff
end
```

## Interlude: Type Stability

```
for evt in mytree
    compute(evt.Muon_pt)
    # more stuff
end
```

If the type of `evt.Muon_pt` is unclear to compiler, then `julia` has no choice but to dynamically dispatch (call) the function `compute()`, which results a slow down.

Type instability can also cause slow down via what's called “boxing/unboxing” which is essentially handling variable of unknown type in a “box” until used, this causes allocation  $\Rightarrow$  slow down.

This leads us to `TypedTable.jl`, which is a thin wrapper around the built-in `NamedTuple`. It retains the type stability of accessing each branch when we put branches together into a tree.