# **Project Writeup Template**

## 1. Project overview:

In this project we used Waymo dataset and download the data as a **tfrecord** extention.

In addition, we utilized a tensorflow object detection api to localize the objects (vehcles, bedestrains and cyclist) where the object detection is necessary to perception of the enlivenments during the driving besides of other sensors as lidar and radar.

#### 2. Set up:

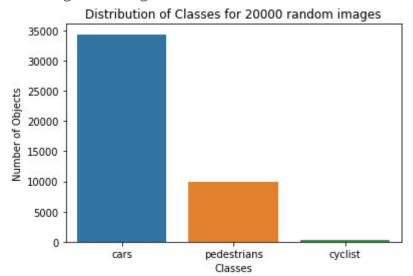
Firstly, we download TensorFlow object detection API and download the Waymo dataset.

We used Utilize.py to read the tfrecord files and put the boxes in the objects of the photos.

In addition, we analyze the data by using bar diagrams.

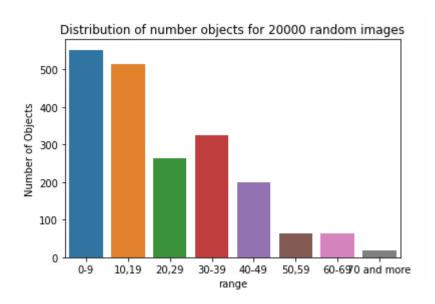
#### 3. Dataset:

According to the diagram below:



We used 20000 images and we find out that the most of objects are cars whereas pedestrians and cyclists are fewer which means we need more data about pedestrians and cyclists to increase their accuracy.

In other sides, the diagram below:



We count the number of objects in each photo where we used 2000 images.

We see that most images have less than 10 objects whereas the images with more than 70 objects are less than 100 images, we can deduce that the images with congestion flow are a little.

Where we need more images with congestion flow if we need more accuracy for congestion problems.

### **Training:**

In the training we used ssd training where we detect the algorithm, matrices and threshold in the pipeline\_new.config file.

We that iou to calucate the loss function.

We coule see in the the photo at the below which it descibs the loss function that the loss is decreasing and we got more accuracy.

We could test other algorithms to get more accuracy as yolo and use yolo loss function instead of IOU.

