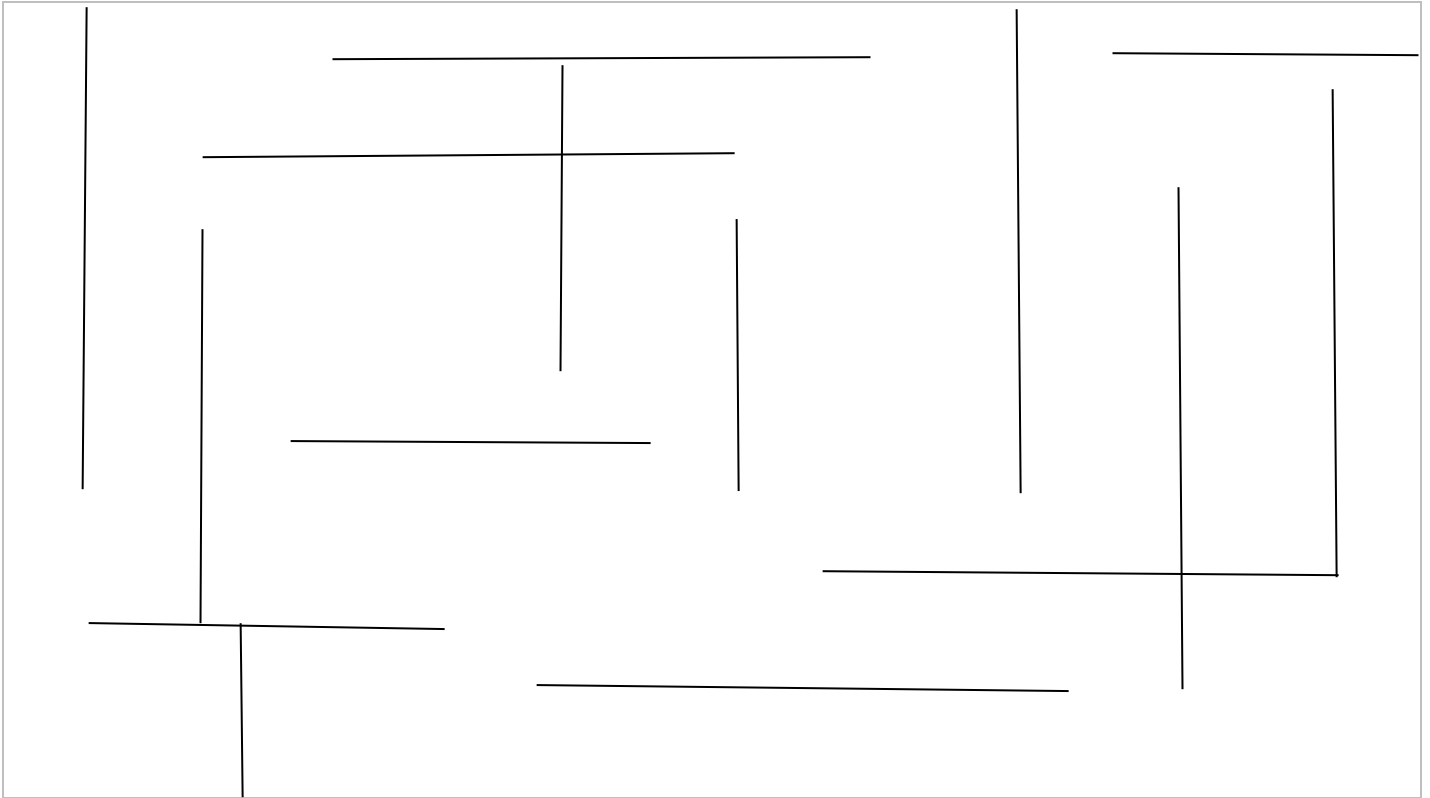


Problem formulation



Initial state: Move the ball between the walls to reach the goal

Successor function: left, right, up, down

Goal test: Reaching the end point

Path cost: 1 pre move