AVR-ATMEGA32A GPIO DRIVER DOCUMENTATION
DRIVER #1

Written on ATMEL STUDIO 7.0
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0.1 File List

Here is a list of all documented files with brief descriptions:

1 File Documentation

1.1 LSTD_BITMATH.h File Reference

This is a standard library layer file that contains bitmath macros that can come in handy while coding.

Macros

- #define **setBit**(REG, POS) (REG |= (1 << POS))
- #define **clearBit**(REG, POS) (REG &= ~(1 << POS))
- #define **toggleBit**(REG, POS) (REG ^= (1 << POS))
- #define **getBit**(REG, POS) ((REG >> POS) & 1)

1.1.1 Detailed Description

This is a standard library layer file that contains bitmath macros that can come in handy while coding.

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Version

1.0

Date

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1.2 LSTD_TYPES.h File Reference

This is a standard library layer file that is used to make aliases for the standard data types inorder to make the code more portable and to avoid changes in data type sizes when using different compilers. giving our standard data types new aliases: unsigned char and signed char -> u8_t and s8_t. unsigned short int and signed short int -> u16_t and s16_t. unsigned long int and signed long int -> u32_t and s32_t. float -> f32_t. double -> f64_t.

Typedefs

- typedef unsigned char **u8_t**
- typedef signed char **s8_t**
- typedef unsigned short int **u16_t**
- typedef signed short int **s16_t**
- typedef unsigned long int **u32_t**
- typedef signed long int **s32_t**
- typedef float **f32_t**
- typedef double **f64_t**

1.2.1 Detailed Description

This is a standard library layer file that is used to make aliases for the standard data types inorder to make the code more portable and to avoid changes in data type sizes when using different compilers. giving our standard data types new aliases: unsigned char and signed char -> u8_t and s8_t. unsigned short int and signed short int -> u16_t and s16_t. unsigned long int and signed long int -> u32_t and s32_t. float -> f32_t. double -> f64_t.

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1.3 main.c File Reference

This is the main file for the AVR-ATMEGA32A GPIO DRIVER.

```
#include "LSTD_BITMATH.h"
#include "LSTD_TYPES.h"
#include "MCAL_GPIO_interface.h"
```

Macros

- #define **LED0** (PIN2) /∗Port C∗/
- #define **LED1** (PIN7) /∗Port C∗/
- #define **LED2** (PIN3) /∗Port D∗/
- #define **PUSHB0** (PIN0) /∗Port B∗/
- #define **PUSHB1** (PIN4) /∗Port B∗/
- #define **PUSHB2** (PIN2) /∗Port D∗/

Functions

- int main (void)

  This main functions tests the GPIO DRIVER driver functions MCAL_GPIO_PinMode and MCAL_GPIO_PinState.

1.3.1 Detailed Description

This is the main file for the AVR-ATMEGA32A GPIO DRIVER.

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1.3.2 Function Documentation

1.3.2.1 main() `int main ( void )`

This main functions tests the GPIO DRIVER driver functions MCAL_GPIO_PinMode and MCAL_GPIO_PinState.

Returns

returns 0 on successful and -1 if an error occurs

1.4 MCAL_GPIO_interface.h File Reference

This .h file contains the interfacing macros, declarations and function prototypes for the GPIO Driver.

Macros

- #define **PORTA** (0)
- #define **PORTB** (1)
- #define **PORTC** (2)
- #define **PORTD** (3)
- #define PIN0 (0b00000001)

  creating macros for the PIN registers, we will be writing them in binary, so that we can do bit operations on them for ease of use.
- #define **PIN1** (0b00000010)
- #define **PIN2** (0b00000100)
- #define **PIN3** (0b00001000)
- #define **PIN4** (0b00010000)
- #define **PIN5** (0b00100000)
- #define **PIN6** (0b01000000)
- #define **PIN7** (0b10000000)
- #define INPUT_FLOAT (0)

  creating a macro for the data direction types.
- #define **INPUT_PULLUP** (1)
- #define **OUTPUT** (2)
- #define LOW (0)

  creating a macro for the possible states.
- #define **HIGH** (1)

Functions

- void MCAL_GPIO_PinMode (u8_t au8_port, u8_t au8_pin, u8_t au8_type)

  MCAL_GPIO_PinMode is used to change the Mode of a pin/pins from any given port.
- void MCAL_GPIO_PinState (u8_t au8_port, u8_t au8_pin, u8_t au8_state)

  MCAL_GPIO_PinState is used to change the State of a pin/pins from any given port to HIGH or LOW.
- void MCAL_GPIO_TogglePin (u8_t au8_port, u8_t au8_pin)

  MCAL_GPIO_TogglePin is used to toggel the State of a pin given a port.
- u8_t MCAL_GPIO_GetPinState (u8_t au8_port, u8_t au8_pin)

  MCAL_GPIO_GetPinState is a function that gets the state of a gien PORT and PIN combination.

1.4.1 Detailed Description

This .h file contains the interfacing macros, declarations and function prototypes for the GPIO Driver.

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1.4.2 Function Documentation

1.4.2.1 MCAL_GPIO_GetPinState()

```
u8_t MCAL_GPIO_GetPinState (
        u8_t au8_port,
        u8_t au8_pin )
```

MCAL_GPIO_GetPinState is a function that gets the state of a gien PORT and PIN combination.

Parameters

au8_port	the given PORT from our macros list.
au8_pin	the given PIN from our macros list.

Returns

u8_t returns true if the state is HIGH and false if the state is LOW.

1.4.2.2 MCAL_GPIO_PinMode()

```
void MCAL_GPIO_PinMode (
        u8_t au8_port,
        u8_t au8_pin,
        u8_t au8_type )
```

MCAL_GPIO_PinMode is used to change the Mode of a pin/pins from any given port.

Parameters

au8_port	is the port to be selected from our macro list PORTA, PORTB, PORTC or PORTD.
au8_pin	is the port to be selected from our macro list PIN1 ... PIN7.
au8_type	is the mode selected from our macro list INPUT_FLOAT, INPUT_PULLUP or OUTPUT.

We will switch over the au_8port given and once we find it, we will switch over the au8_type and then we set up our mode.

The registers used in order to alter the I/P or O/P modes. MCAL_DDRx, MCAL_PORTx.

1.4.2.3 MCAL_GPIO_PinState()

```
void MCAL_GPIO_PinState (
        u8_t au8_port,
        u8_t au8_pin,
        u8_t au8_state )
```

MCAL_GPIO_PinState is used to change the State of a pin/pins from any given port to HIGH or LOW.

Parameters

au8_port	is the port to be selected from our macro list PORTA, PORTB, PORTC or PORTD.
au8_pin	is the port to be selected from our macro list PIN1 ... PIN7.
au8_state	is the mode selected from our macro list HIGH or LOW.

We will switch over the au_8port given and once we find it, we will switch over the au8_type and then we set up our state.

The registers used in order to alter the I/P or O/P states. MCAL_PORTx.

1.4.2.4 MCAL_GPIO_TogglePin()

```
void MCAL_GPIO_TogglePin (
        u8_t au8_port,
        u8_t au8_pin )
```

MCAL_GPIO_TogglePin is used to toggel the State of a pin given a port.

Parameters

au8_port	The PORT used in the toggling operation.
au8_pin	The PIN to be toggled.

1.5 MCAL_GPIO_private.h File Reference

This .h file contains the private macros and declarations for the GPIO Driver.

Macros

- #define MCAL_PORTA (∗(volatile u8_t∗)(0x3B))

  Header guard for the .h file.
- #define **MCAL_DDRA** (∗(volatile u8_t∗)(0x3A))
- #define **MCAL_PINA** (∗(volatile u8_t∗)(0x39))
- #define MCAL_PORTB (∗(volatile u8_t∗)(0x38))

  defining the memory mapped addresses for the PORTB, DDRB, PINB Registers.
- #define **MCAL_DDRB** (∗(volatile u8_t∗)(0x37))
- #define **MCAL_PINB** (∗(volatile u8_t∗)(0x36))
- #define MCAL_PORTC (∗(volatile u8_t∗)(0x35))

  defining the memory mapped addresses for the PORTC, DDRC, PINC Registers.
- #define **MCAL_DDRC** (∗(volatile u8_t∗)(0x34))
- #define **MCAL_PINC** (∗(volatile u8_t∗)(0x33))
- #define MCAL_PORTD (∗(volatile u8_t∗)(0x32))

  defining the memory mapped addresses for the PORTD, DDRD, PIND Registers.
- #define **MCAL_DDRD** (∗(volatile u8_t∗)(0x31))
- #define **MCAL_PIND** (∗(volatile u8_t∗)(0x30))

1.5.1 Detailed Description

This .h file contains the private macros and declarations for the GPIO Driver.

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1.5.2 Macro Definition Documentation

1.5.2.1 MCAL_PORTA `#define MCAL_PORTA (*(volatile u8_t*)(0x3B))`

Header guard for the .h file.

defining the memory mapped addresses for the PORTA, DDRA, PINA Registers.

1.6 MCAL_GPIO_program.c File Reference

This c file contains the implementation for the function prototypes used in MCAL_GPIO_interface.h.

```
#include "LSTD_BITMATH.h"
#include "LSTD_TYPES.h"
#include "MCAL_GPIO_private.h"
#include "MCAL_GPIO_interface.h"
```

Functions

- void MCAL_GPIO_PinMode (u8_t au8_port, u8_t au8_pin, u8_t au8_type)
  MCAL_GPIO_PinMode is used to change the Mode of a pin/pins from any given port.
- void MCAL_GPIO_PinState (u8_t au8_port, u8_t au8_pin, u8_t au8_state)
  MCAL_GPIO_PinState is used to change the State of a pin/pins from any given port to HIGH or LOW.
- void MCAL_GPIO_TogglePin (u8_t au8_port, u8_t au8_pin)
  MCAL_GPIO_TogglePin is used to toggel the State of a pin given a port.
- u8_t MCAL_GPIO_GetPinState (u8_t au8_port, u8_t au8_pin)
  MCAL_GPIO_GetPinState is a function that gets the state of a gien PORT and PIN combination.

1.6.1 Detailed Description

This c file contains the implementation for the function prototypes used in MCAL_GPIO_interface.h.

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1.6.2 Function Documentation

1.6.2.1 MCAL_GPIO_GetPinState() `u8_t MCAL_GPIO_GetPinState (`

```
u8_t au8_port,
u8_t au8_pin )
```

MCAL_GPIO_GetPinState is a function that gets the state of a gien PORT and PIN combination.

Parameters

au8_port	the given PORT from our macros list.
au8_pin	the given PIN from our macros list.

Returns

u8_t returns true if the state is HIGH and false if the state is LOW.

1.6.2.2 MCAL_GPIO_PinMode()

```
void MCAL_GPIO_PinMode (
        u8_t au8_port,
        u8_t au8_pin,
        u8_t au8_type )
```

MCAL_GPIO_PinMode is used to change the Mode of a pin/pins from any given port.

Parameters

au8_port	is the port to be selected from our macro list PORTA, PORTB, PORTC or PORTD.
au8_pin	is the port to be selected from our macro list PIN1 ... PIN7.
au8_type	is the mode selected from our macro list INPUT_FLOAT, INPUT_PULLUP or OUTPUT.

We will switch over the au_8port given and once we find it, we will switch over the au8_type and then we set up our mode.

The registers used in order to alter the I/P or O/P modes. MCAL_DDRx, MCAL_PORTx.

1.6.2.3 MCAL_GPIO_PinState()

```
void MCAL_GPIO_PinState (
        u8_t au8_port,
        u8_t au8_pin,
        u8_t au8_state )
```

MCAL_GPIO_PinState is used to change the State of a pin/pins from any given port to HIGH or LOW.

Parameters

au8_port	is the port to be selected from our macro list PORTA, PORTB, PORTC or PORTD.
au8_pin	is the port to be selected from our macro list PIN1 ... PIN7.
au8_state	is the mode selected from our macro list HIGH or LOW.

We will switch over the au_8port given and once we find it, we will switch over the au8_type and then we set up our state.

The registers used in order to alter the I/P or O/P states. MCAL_PORTx.

1.6.2.4 MCAL_GPIO_TogglePin()

```
void MCAL_GPIO_TogglePin (
        u8_t au8_port,
        u8_t au8_pin )
```

MCAL_GPIO_TogglePin is used to toggel the State of a pin given a port.

Parameters

au8_port	The PORT used in the toggling operation.
au8_pin	The PIN to be toggled.

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