AVR-ATMEGA32A LCD16x2 DRIVER DOCUMENTATION DRIVER #2

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Chapter 1

File Index

1.1 File List

Here is a list of all documented files with brief descriptions:

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Chapter 2

File Documentation

2.1 HAL LCD interface.h File Reference

This is the h file that is used for our macros, function prototypes and declaration used in our LCD16x2 Driver. !PLEASE DON'T FORGET TO USE DELAYS!

Macros

- #define HAL_LCD_ROW00 (0x80)
- #define HAL_LCD_ROW01 (0xC0)
- #define HAL_LCD_COL00 (0)
- #define HAL_LCD_COL01 (1)
- #define HAL LCD COL02 (2)
- #define HAL_LCD_COL03 (3)
- #define HAL LCD COL04 (4)
- #define HAL_LCD_COL05 (5)
- #define HAL_LCD_COL06 (6)
- #define **HAL_LCD_COL07** (7)
- #define HAL_LCD_COL08 (8)
- #define **HAL_LCD_COL09** (9)
- #define HAL_LCD_COL10 (10)
- #define HAL_LCD_COL11 (11)
- #define HAL_LCD_COL12 (12)
- #define HAL_LCD_COL13 (13)
- #define HAL_LCD_COL14 (14)
- #define HAL_LCD_COL15 (15)

Functions

void HAL_LCD_init (void)

HAL_LCD_init is the LCD16x2 Initializing function.

• void HAL_LCD_displayCharacter (u8_t au8_charData)

HAL_LCD_displayCharacter is a function that displays the character passed as a parameter on the LCD16x2.

void HAL_LCD_displayString (u8_t *pu8_srtData)

HAL_LCD_displayString is a function that displays a given string on the LCD16x2 screen (!Be careful of character overflows!)

void HAL_LCD_putAtLoc (u8_t au8_row, u8_t au8_col)

HAL LCD putAtLoc is a function that moves the cursor of the LCD16x2 to the DDRAM address passed.

void HAL LCD clearDisplay (void)

HAL_LCD_clearDisplay is a function that clears the display of the LCD16x2.

2.1.1 Detailed Description

This is the h file that is used for our macros, function prototypes and declaration used in our LCD16x2 Driver. !PLEASE DON'T FORGET TO USE DELAYS!

Author

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Mohamed El Barbary ( mohmbarbary@gmail.com)
```

Version

1.0

Date

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2.1.2 Function Documentation

2.1.2.1 HAL_LCD_displayCharacter()

```
void HAL_LCD_displayCharacter (  {\tt u8\_t} \  \, {\it au8\_charData} \  \, )
```

HAL_LCD_displayCharacter is a function that displays the character passed as a parameter on the LCD16x2.

Parameters

```
au8_charData is the data that will be passed to the LCD16x2.
```

2.1.2.2 HAL_LCD_displayString()

HAL_LCD_displayString is a function that displays a given string on the LCD16x2 screen (!Be careful of character overflows!)

Parameters

pu8 srtData	is a pointer to the 8 bits of dat that will be displayed.

2.1.2.3 HAL_LCD_putAtLoc()

HAL LCD putAtLoc is a function that moves the cursor of the LCD16x2 to the DDRAM address passed.

Parameters

au8_row	is the variable containing the row where we want to move (!DO NOT FORGET TO USE THE MACROS!)
au8_col	is the variable containing the column where we want to move (!DO NOT FORGET TO USE THE MACROS!)

2.2 HAL_LCD_private.h File Reference

This is the h file that is used to store the private variables and declarations of our LCD16x2 Driver. !PLEASE DON'T FORGET TO USE DELAYS!

Macros

- #define HAL_LCD_CTRL_PORT (PORTB)
- #define HAL_LCD_RS_PIN (PIN1)
- #define HAL_LCD_RW_PIN (PIN2)
- #define HAL_LCD_EN_PIN (PIN3)
- #define HAL_LCD_DATA_PORT (PORTA)
- #define HAL_LCD_D0_PIN (PIN0)
- #define HAL_LCD_D1_PIN (PIN1)
- #define HAL_LCD_D2_PIN (PIN2)
- #define **HAL_LCD_D3_PIN** (PIN3)
- #define HAL_LCD_D4_PIN (PIN4)
- #define HAL_LCD_D5_PIN (PIN5)
- #define HAL_LCD_D6_PIN (PIN6)
- #define HAL_LCD_D7_PIN (PIN7)

2.2.1 Detailed Description

This is the h file that is used to store the private variables and declarations of our LCD16x2 Driver. !PLEASE DON'T FORGET TO USE DELAYS!

```
Author
```

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Mohamed El Barbary ( mohmbarbary@gmail.com)
```

Version

1.0

Date

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Copyright

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2.3 HAL_LCD_program.c File Reference

HAL_LCD_program.c is the file that contains the implementation for the function prototypes found in the HAL LCD interface.h file.

```
#include "LSTD_BITMATH.h"
#include "LSTD_TYPES.h"
#include "MCAL_GPIO_interface.h"
#include "HAL_LCD_private.h"
#include "HAL_LCD_interface.h"
```

Functions

• void HAL_LCD_init (void)

HAL_LCD_init is the LCD16x2 Initializing function.

• void HAL_LCD_displayCharacter (u8_t au8_charData)

HAL_LCD_displayCharacter is a function that displays the character passed as a parameter on the LCD16x2.

void HAL_LCD_displayString (u8_t *pu8_srtData)

HAL_LCD_displayString is a function that displays a given string on the LCD16x2 screen (!Be careful of character overflows!)

void HAL_LCD_putAtLoc (u8_t au8_row, u8_t au8_col)

HAL_LCD_putAtLoc is a function that moves the cursor of the LCD16x2 to the DDRAM address passed.

void HAL LCD clearDisplay (void)

HAL_LCD_clearDisplay is a function that clears the display of the LCD16x2.

2.3.1 Detailed Description

HAL_LCD_program.c is the file that contains the implementation for the function prototypes found in the HAL_LCD_interface.h file.

Author

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Mohamed El Barbary ( mohmbarbary@gmail.com)
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Version

1.0

Date

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2.3.2 Function Documentation

2.3.2.1 HAL_LCD_displayCharacter()

HAL_LCD_displayCharacter is a function that displays the character passed as a parameter on the LCD16x2.

Parameters

```
au8_charData is the data that will be passed to the LCD16x2.
```

2.3.2.2 HAL_LCD_displayString()

HAL_LCD_displayString is a function that displays a given string on the LCD16x2 screen (!Be careful of character overflows!)

Parameters

2.3.2.3 HAL_LCD_putAtLoc()

```
void HAL_LCD_putAtLoc (
     u8_t au8_row,
     u8_t au8_col )
```

HAL LCD putAtLoc is a function that moves the cursor of the LCD16x2 to the DDRAM address passed.

Parameters

au8_row	is the variable containing the row where we want to move (!DO NOT FORGET TO USE THE MACROS!)
au8_col	is the variable containing the column where we want to move (!DO NOT FORGET TO USE THE MACROS!)

2.4 LSTD_BITMATH.h File Reference

This is a standard library layer file that contains bitmath macros that can come in handy while coding.

Macros

- #define **setBit**(REG, POS) (REG |= (1 << POS))
- #define clearBit(REG, POS) (REG &= ~(1 << POS))
- #define toggleBit(REG, POS) (REG ^= (1 << POS))
- #define getBit(REG, POS) ((REG >> POS) & 1)

2.4.1 Detailed Description

This is a standard library layer file that contains bitmath macros that can come in handy while coding.

Author

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Mohamed El Barbary ( Mohmbarbary@gmail.com)
```

Version

1.0

Date

2021-01-29 10:19:20 PM

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2.5 LSTD TYPES.h File Reference

This is a standard library layer file that is used to make aliases for the standard data types inorder to make the code more portable and to avoid changes in data type sizes when using different compilers. giving our standard data types new aliases: unsigned char and signed char -> u8_t and s8_t. unsigned short int and signed short int -> u16_t and s16_t. unsigned long int and signed long int -> u32_t and s32_t. float -> f32_t. double -> f64_t.

Typedefs

- typedef unsigned char u8_t
- typedef signed char s8_t
- typedef unsigned short int u16_t
- typedef signed short int s16_t
- typedef unsigned long int u32_t
- · typedef signed long int s32_t
- typedef float f32_t
- · typedef double f64_t

2.5.1 Detailed Description

This is a standard library layer file that is used to make aliases for the standard data types inorder to make the code more portable and to avoid changes in data type sizes when using different compilers. giving our standard data types new aliases: unsigned char and signed char -> u8_t and s8_t. unsigned short int and signed short int -> u16_t and s16_t. unsigned long int and signed long int -> u32_t and s32_t. float -> f32_t. double -> f64_t.

```
Author
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Mohamed El Barbary ( Mohmbarbary@gmail.com)
```

Version

1.0

Date

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2.6 main.c File Reference

This is the main function that is used to test the functionality of our LCD16x2 Driver. !PLEASE DON'T FORGET TO USE DELAYS!

```
#include "LSTD_TYPES.h"
#include "LSTD_BITMATH.h"
#include "HAL_LCD_interface.h"
```

Macros

- #define F CPU 16000000UL
- #define PUSHB0 PIN0
- #define PUSHB1 PIN4
- #define PUSHB2 PIN2

Functions

• int main (void)

2.6.1 Detailed Description

This is the main function that is used to test the functionality of our LCD16x2 Driver. !PLEASE DON'T FORGET TO USE DELAYS!

Author

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Mohamed El Barbary ( mohmbarbary@gmail.com)
```

Version

1.0

Date

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2.7 MCAL GPIO interface.h File Reference

This .h file contains the interfacing macros, declarations and function prototypes for the GPIO Driver.

Macros

- #define PORTA (0)
- #define PORTB (1)
- #define PORTC (2)
- #define PORTD (3)
- #define PIN0 (0b0000001)

creating macros for the PIN registers, we will be writing them in binary, so that we can do bit operations on them for ease of use.

- #define PIN1 (0b0000010)
- #define PIN2 (0b00000100)
- #define **PIN3** (0b00001000)
- #define PIN4 (0b00010000)
- #define PIN5 (0b00100000)
- #define PIN6 (0b01000000)
- #define **PIN7** (0b10000000)
- #define INPUT_FLOAT (0)

creating a macro for the data direction types.

- #define INPUT_PULLUP (1)
- #define OUTPUT (2)
- #define LOW (0)

creating a macro for the possible states.

• #define HIGH (1)

Functions

```
• void MCAL_GPIO_PinMode (u8_t au8_port, u8_t au8_pin, u8_t au8_type)
```

MCAL_GPIO_PinMode is used to change the Mode of a pin/pins from any given port.

void MCAL_GPIO_PinState (u8_t au8_port, u8_t au8_pin, u8_t au8_state)

MCAL_GPIO_PinState is used to change the State of a pin/pins from any given port to HIGH or LOW.

• void MCAL_GPIO_TogglePin (u8_t au8_port, u8_t au8_pin)

MCAL_GPIO_TogglePin is used to toggel the State of a pin given a port.

• u8_t MCAL_GPIO_GetPinState (u8_t au8_port, u8_t au8_pin)

MCAL_GPIO_GetPinState is a function that gets the state of a gien PORT and PIN combination.

2.7.1 Detailed Description

This .h file contains the interfacing macros, declarations and function prototypes for the GPIO Driver.

Author

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```

Version

1.0

Date

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2.7.2 Function Documentation

2.7.2.1 MCAL_GPIO_GetPinState()

MCAL GPIO GetPinState is a function that gets the state of a gien PORT and PIN combination.

Parameters

au8_port	the given PORT from our macros list.
au8_pin	the given PIN from our macros list.

Returns

u8_t returns true if the state is HIGH and false if the state is LOW.

2.7.2.2 MCAL_GPIO_PinMode()

MCAL_GPIO_PinMode is used to change the Mode of a pin/pins from any given port.

Parameters

au8_port	is the port to be selected from our macro list PORTA, PORTB, PORTC or PORTD.
au8_pin	is the port to be selected from our macro list PIN1 PIN7.
au8_type	is the mode selected from our macro list INPUT_FLOAT, INPUT_PULLUP or OUTPUT.

We will switch over the au_8port given and once we find it, we will switch over the au8_type and then we set up our mode.

The registers used in order to alter the I/P or O/P modes. MCAL_DDRx, MCAL_PORTx.

2.7.2.3 MCAL GPIO PinState()

MCAL_GPIO_PinState is used to change the State of a pin/pins from any given port to HIGH or LOW.

Parameters

au8_port	is the port to be selected from our macro list PORTA, PORTB, PORTC or PORTD.
au8_pin	is the port to be selected from our macro list PIN1 PIN7.
au8_state	is the mode selected from our macro list HIGH or LOW.

We will switch over the au_8port given and once we find it, we will switch over the au8_type and then we set up our state.

The registers used in order to alter the I/P or O/P states. MCAL_PORTx.

2.7.2.4 MCAL GPIO TogglePin()

MCAL_GPIO_TogglePin is used to toggel the State of a pin given a port.

Parameters

au8_port	The PORT used in the toggling operation.
au8_pin	The PIN to be toggled.

2.8 MCAL_GPIO_private.h File Reference

This .h file contains the private macros and declarations for the GPIO Driver.

Macros

- #define MCAL_PORTA (*(volatile u8_t*)(0x3B))
 - Header guard for the .h file.
- #define MCAL_DDRA (*(volatile u8_t*)(0x3A))
- #define MCAL_PINA (*(volatile u8_t*)(0x39))
- #define MCAL_PORTB (*(volatile u8_t*)(0x38))

defining the memory mapped addresses for the PORTB, DDRB, PINB Registers.

- #define MCAL_DDRB (*(volatile u8_t*)(0x37))
- #define MCAL_PINB (*(volatile u8_t*)(0x36))
- #define MCAL_PORTC (*(volatile u8_t*)(0x35))

defining the memory mapped addresses for the PORTC, DDRC, PINC Registers.

- #define MCAL_DDRC (*(volatile u8_t*)(0x34))
- #define MCAL_PINC (*(volatile u8_t*)(0x33))
- #define MCAL_PORTD (*(volatile u8_t*)(0x32))

defining the memory mapped addresses for the PORTD, DDRD, PIND Registers.

- #define MCAL_DDRD (*(volatile u8_t*)(0x31))
- #define MCAL_PIND (*(volatile u8_t*)(0x30))

2.8.1 Detailed Description

This .h file contains the private macros and declarations for the GPIO Driver.

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Version

1.0

Date

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2.8.2 Macro Definition Documentation

2.8.2.1 MCAL_PORTA

```
#define MCAL_PORTA (*(volatile u8_t*)(0x3B))
```

Header guard for the .h file.

defining the memory mapped addresses for the PORTA, DDRA, PINA Registers.

2.9 MCAL_GPIO_program.c File Reference

This c file contains the implementation for the function prototypes used in MCAL_GPIO_interface.h.

```
#include "LSTD_BITMATH.h"
#include "LSTD_TYPES.h"
#include "MCAL_GPIO_private.h"
#include "MCAL_GPIO_interface.h"
```

Functions

```
    void MCAL_GPIO_PinMode (u8_t au8_port, u8_t au8_pin, u8_t au8_type)
```

MCAL_GPIO_PinMode is used to change the Mode of a pin/pins from any given port.

• void MCAL_GPIO_PinState (u8_t au8_port, u8_t au8_pin, u8_t au8_state)

MCAL_GPIO_PinState is used to change the State of a pin/pins from any given port to HIGH or LOW.

• void MCAL_GPIO_TogglePin (u8_t au8_port, u8_t au8_pin)

MCAL_GPIO_TogglePin is used to toggel the State of a pin given a port.

• u8_t MCAL_GPIO_GetPinState (u8_t au8_port, u8_t au8_pin)

MCAL_GPIO_GetPinState is a function that gets the state of a gien PORT and PIN combination.

2.9.1 Detailed Description

This c file contains the implementation for the function prototypes used in MCAL_GPIO_interface.h.

Author

```
Mohamed El Barbary ( Mohmbarbary@gmail.com)
```

Version

1.0

Date

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2.9.2 Function Documentation

2.9.2.1 MCAL_GPIO_GetPinState()

MCAL_GPIO_GetPinState is a function that gets the state of a gien PORT and PIN combination.

Parameters

au8_port	the given PORT from our macros list.
au8_pin	the given PIN from our macros list.

Returns

u8_t returns true if the state is HIGH and false if the state is LOW.

2.9.2.2 MCAL_GPIO_PinMode()

MCAL_GPIO_PinMode is used to change the Mode of a pin/pins from any given port.

Parameters

au8_port	is the port to be selected from our macro list PORTA, PORTB, PORTC or PORTD.
au8_pin	is the port to be selected from our macro list PIN1 PIN7.
au8_type	is the mode selected from our macro list INPUT_FLOAT, INPUT_PULLUP or OUTPUT.

We will switch over the au_8port given and once we find it, we will switch over the au8_type and then we set up our mode.

The registers used in order to alter the I/P or O/P modes. MCAL_DDRx, MCAL_PORTx.

2.9.2.3 MCAL_GPIO_PinState()

```
void MCAL_GPIO_PinState (
          u8_t au8_port,
```

```
u8_t au8_pin,
u8_t au8_state )
```

MCAL_GPIO_PinState is used to change the State of a pin/pins from any given port to HIGH or LOW.

Parameters

au8_port	is the port to be selected from our macro list PORTA, PORTB, PORTC or PORTD.
au8_pin	is the port to be selected from our macro list PIN1 PIN7.
au8_state	is the mode selected from our macro list HIGH or LOW.

We will switch over the au_8port given and once we find it, we will switch over the au8_type and then we set up our state.

The registers used in order to alter the I/P or O/P states. MCAL_PORTx.

2.9.2.4 MCAL_GPIO_TogglePin()

MCAL_GPIO_TogglePin is used to toggel the State of a pin given a port.

Parameters

au8_port	The PORT used in the toggling operation.
au8_pin	The PIN to be toggled.

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